HAO WANG

haowang@chalmers.se https://hwang7308.github.io

Division of Production Systems, Department of Industrial and Materials Science Chalmers University of Technology

EDUCATION

Chalmers University of Technology

Ph.D. student in Product and Production Development

The University of Edinburgh

MSc with Distinction in Informatics

University of Skövde

Exchange Student in Informatics

Beijing University of Posts and Telecommunications

B.Eng. in Telecommunication Engineering

2021 - Present

Gothenburg, Sweden

2010 201

 $2018-2019 \\ Edinburgh,~UK$

C---+ 2016 I--- 201

Sept. 2016 - Jan. 2017

Skövde, Sweden

2014 - 2018

Beijing, China

PUBLICATION

- Journal —
- 2. Wang, H., Salunkhe, O., Quadrini, W., Lämkull, D., Ore, F., Despeisse, M., Fumagalli, L., Stahre, J., & Johansson, B. (2024). A systematic literature review of computer vision applications in robotized wire harness assembly. Advanced Engineering Informatics, 62, 102596. doi:10.1016/j.aei.2024.102596
- 1. Zhu, X., Yu, C., Huang, D., Lei, Z., Wang, H., & Li, S. Z. (2023). Beyond 3dmm: Learning to capture high-fidelity 3d face shape. *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 45(2), 1442-1457. doi:10.1109/TPAMI.2022.3164131
- Conference —
- 6. Wang, H., Salunkhe, O., Quadrini, W., Lämkull, D., Ore, F., Johansson, B., & Stahre, J. (2023). Overview of computer vision techniques in robotized wire harness assembly: Current state and future opportunities. *Procedia CIRP*, 120, 1071-1076. doi:10.1016/j.procir.2023.09.127
- 5. Salunkhe, O., Quadrini, W., Wang, H., Stahre, J., Romero, D., Fumagalli, L., & Lämkull, D. (2023). Review of current status and future directions for collaborative and semi-automated automotive wire harnesses assembly. *Procedia CIRP*, 120, 696-701. doi:10.1016/j.procir.2023.09.061
- 4. Wang, H., & Johansson, B. (2023). Deep learning-based connector detection for robotized assembly of automotive wire harnesses. 2023 IEEE 19th International Conference on Automation Science and Engineering (CASE), 1-8. doi:10.1109/CASE56687.2023.10260619
- Despeisse, M., Johansson, B., Bokrantz, J., Braun, G., Chari, A., Chen, X., Fang, Q., González Chávez, C. A., Skoogh, A., Stahre, J., Theradapuzha Mathew, N., Turanoglu Bekar, E., Wang, H., & Örtengren, R. (2023). Battery production systems: State of the art and future developments. Advances in Production Management Systems. Production Management Systems for Responsible Manufacturing, Service, and Logistics Futures, 521-535. doi:10.1007/978-3-031-43688-8_36
- 2. Zhu, X., Wang, H., Fei, H., Lei, Z., & Li, S. Z. (2021). Face forgery detection by 3d decomposition. 2021 IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2928-2938. doi:10.1109/CVPR46437.2021.00295
- 1. Zhu, X., Yang, F., Huang, D., Yu, C., Wang, H., Guo, J., Lei, Z., & Li, S. Z. (2020). Beyond 3dmm space: Towards fine-grained 3d face reconstruction. Computer Vision ECCV 2020, 343-358. doi:10.1007/978-3-030-58598-3_21
- Report —
- 1. 2023 World Manufacturing Report: New Business Models for the Manufacturing of the Future
- Thesis —
- 1. Wang, H. (2024). Toward enabling robotic visual perception for assembly tasks [Licentiate thesis]

RESEARCH PROJECTS

Empowering Human Workers for Assembly of Wire Harnesses (EWASS) SIP Produktion2030, VINNOVA

2022-2025

- · To assist the industry in ensuring a sustainable work-life by empowering human workers during assembly of wire harnesses
- To improve productivity, quality, and ergonomics of assembly installation of wire harnesses and high voltage cables using collaborative robots, thereby boosting the manufacturing of electrified vehicles

PLENary multi-User develop Ment arena for future industrial workspaces (PLENUM) $\ensuremath{VINNOVA}$

2022-2025

- · To provide industry with methods and design tools to create sustainable factories/workplaces/manual operations in a multi-user development environment
- To develop and demonstrate an easy-to-use (low threshold) cost-effective interactive multi-user 3D environment for development, workplace design, upskilling and ergonomic analysis that includes thousands of users and reduces environmental impact

To strengthen the links between research, innovation and standardisations ensuring that standardisation is an integral part of the European research and innovation landscape

DIGITAL work InStructions for cognitive work (DIGITALIS) SIP Produktion2030, VINNOVA

2022-2024

To demonstrate how systematic development of cognitive support and information design can increase quality and flexibility in future production

A Pan-European Network of Robotics DIHs for Agile Production (DIH 2) EU

2019-2023

- · To spark incremental and disruptive innovations in over 300,000 Manufacturing SMEs and Mid-Caps
- · Project webpage

OTHER PROJECTS

Gender Identification from 3D Facial Surface Model

Feb. 2019 - Aug. 2019

Dissertation for Master's degree

- · Proposed a novel method on 3D facial gender identification with machine learning & conformal mapping
- · Evaluated the proposed method and obtained competitive performance (accuracy over 88%)

Action Recognition Model with First-Person Videos

Jan. 2019 - Mar. 2019

- · Evaluated third-person action recognition methods with first-person datasets
- · Compared the differences between the third and first-person methods
- · Proposed and studied a new model combining MobileNet and Two-stream Pyramid

Image Super-Resolution with Convolutional Neural Network

Dec. 2017 - June 2018

Dissertation for Bachelor's degree

- · Realized the subpixel-based image super-resolution method with pixel shuffle
- · Tested the model on both image and video datasets

RESEARCH EXPERIENCE

National Laboratory of Pattern Recognition, CASIA

 $Oct.\,2019\text{-}June\,2021$

Research Intern

Beijing, China

· Projects: Fine-grained 3D face reconstruction; Face forgery detection; Face anti-spoofing

Next Generation Internet Research Center, BUPT Undergraduate Research Assistant

May 2017 - Oct. 2017
Beijing, China

· Projects: Optimization on DASH-based video service in high-speed railway networks with stochastic methods; Network flow variation detection with mobile crowd sensing

TEACHING EXPERIENCE

MPR213 Robotics and Manufacturing Automation Chalmers

· Apr. - May 2024: Lecturer (Robotics, AI, and computer vision)

LMT108 Automation Technique

Chalmers

· Jan. - Mar. 2024: Lecturer (Robotics, AI, and computer vision)

IMS020 Simulation and Visualisation of Production Systems Chalmers

- · Sept. Oct. 2021: Lab assistant
- · Sept. Oct. 2022: Course coordinator, lecturer, and lab assistant; Course evaluation: 4.2/5.0
- · Sept. Oct. 2023: Course coordinator, lecturer, and lab assistant; Course evaluation: 3.75/5.0

PPU055 Virtual production

Chalmers

- · Oct. Dec. 2021: Lecturer and lab assistant
- · Oct. Dec. 2022: Lecturer and lab assistant

IMS085 Simulation and optimization of sustainable production systems Chalmers

- Jan. May 2022: Lab assistant
- · Jan. May 2023: Lab assistant
- · Jan. May 2024: Lab assistant

PPU161 Production systems

Chalmers

· Oct. - Dec. 2022: Project tutor

PPU215 Research methodology in production projects

Chalmers

· Jan. - Mar. 2022: Project tutor

PPU156 Computer Aided Design (CAD)

Chalmers

· Oct. - Dec. 2021: Lecturer (3D scanning)

ACADEMIC SERVICE

Reviewer: IEEE International Conference on Multimedia and Expo

SKILLS

Programming Languages: Python, MATLAB, C, C++, Java, Go, VHDL, Verilog, Assembly Language Tools: PyTorch, Tensorflow, OpenCV, Dlib, Plant Simulation, Visual Components, RobotStudio Others: Linux, Git, SQL, LATEX, FPGA, Arduino, Raspberry Pi, NVIDIA Jetson Nano, PolyScope