

HW 1112

$$Q_1 \quad f_{u_1}(u_1) = \begin{cases} 1 & 0 \leq u_1 \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

$$f_{u_2}(u_2) = \begin{cases} 1 & 0 \leq u_2 \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

$$f_{u_1, u_2}(u_1, u_2) = f_{u_1}(u_1) f_{u_2}(u_2) = 1$$

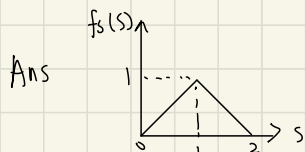
$$\text{for } 0 \leq u_1 \leq 1, 0 \leq u_2 \leq 1$$

$$f_S(s) = \int_{-\infty}^{\infty} f_{u_1}(u_1) f_{u_2}(s-u_1) du_1$$

$$f_S(s) = \int_0^s 1 du_1 = s \quad \text{for } 0 \leq s \leq 1$$

$$f_S(s) = \int_{s-1}^1 1 du_1 = 1 - (s-1) = 2-s \quad \text{for } 1 \leq s \leq 2$$

$$f_S(s) = 0 \quad \text{for } s < 0, s > 2$$



Q2

$$P(N=k) = \frac{\lambda^k e^{-\lambda}}{k!}$$

$$N = N_1 + N_2$$

$$M_X(t) = E[e^{tx}]$$

$$M_N(t) = E[e^{tN}] = e^{\lambda(e^t-1)}$$

$$\text{MGF of } N_1 : e^{\lambda_1(e^t-1)}$$

$$\text{MGF of } N_2 : e^{\lambda_2(e^t-1)}$$

$$\begin{aligned} \text{MGF of } N = N_1 + N_2 : & e^{\lambda_1(e^t-1)} e^{\lambda_2(e^t-1)} \\ & = e^{(\lambda_1 + \lambda_2)(e^t-1)} \end{aligned}$$

Since $N = N_1 + N_2$, N is poisson $(\lambda_1 + \lambda_2)$

Q 3

$$p(Z=z) = \begin{cases} \frac{1}{9} & z=0 \\ \frac{2}{9} & z=1 \\ \frac{1}{3} & z=2 \\ \frac{2}{9} & z=3 \\ \frac{1}{9} & z=4 \end{cases}$$

Q 4

$$Z = XY \Rightarrow X = \frac{Z}{Y}$$

$$\text{Jacobian determinant: } \left| \frac{\partial(X,Y)}{\partial(Z,Y)} \right| = \frac{1}{|Y|}$$

$$\text{pdf of } Z: f_Z(z) = \int_{-\infty}^{\infty} f\left(y, \frac{z}{y}\right) \frac{1}{|y|} dy$$

Q 5

$$f_{X,Y}(x,y) = f_X(x) f_Y(y) = 1 \quad \text{for } 0 \leq x \leq 1, 0 \leq y \leq 1$$

CDF of Z

$$F_Z(z) = P\left(\frac{X}{Y} \leq z\right) = P(X \leq zY)$$

$$= \int_0^1 \int_0^{\min(zY, 1)} 1 \, dx \, dy$$

$$F_Z(z) = \begin{cases} \frac{z}{2} & \text{for } 0 \leq z \leq 1 \\ 1 - \frac{1}{2z^2} & \text{for } z > 1 \end{cases}$$

$$f_Z(z) = \frac{d}{dz} F_Z(z)$$

$$\Rightarrow f_Z(z) = \begin{cases} \frac{1}{2} & \text{for } 0 \leq z \leq 1 \\ \frac{1}{z^2} & \text{for } z > 1 \end{cases}$$

Q 6

$$f_{x,y,z}(x,y,z) = \frac{1}{(2\pi b^2)^{\frac{3}{2}}} e^{-\frac{x^2+y^2+z^2}{2b^2}}$$

$$dx dy dz = r^2 \sin \phi dr d\phi d\theta$$

$$f_{r,\phi,\theta}(r,\phi,\theta) = \frac{1}{(2\pi b^2)^{\frac{3}{2}}} e^{-\frac{r^2}{2b^2}} r^2 \sin \phi$$

$$f_R(r) = \int_0^{2\pi} \int_0^\pi f_{r,\phi,\theta}(r,\phi,\theta) \sin \phi d\phi d\theta$$

$$= \frac{2r^2}{(2\pi b^2)^{\frac{3}{2}}} e^{-\frac{r^2}{2b^2}}$$

$$f_\phi(\phi) = \int_0^\infty \int_0^{2\pi} f_{r,\phi,\theta}(r,\phi,\theta) d\theta dr$$

$$= \frac{1}{(2\pi b^2)^{\frac{3}{2}}} 2\pi \sin \phi \frac{\sqrt{\pi}}{2} b^3 = \frac{1}{2} \sin \phi$$

$$f_R(r) = \frac{2r^2}{(2\pi b^2)^{\frac{3}{2}}} e^{-\frac{r^2}{2b^2}}$$

$$f_\theta(\theta) = \frac{1}{2\pi} \quad 0 \leq \theta \leq 2\pi$$

$$f_\phi(\phi) = \frac{1}{2} \sin \phi \quad 0 \leq \phi \leq \pi$$