# SAVE, LOAD AND USE MODEL

# 一、内容

本部分将涉及如何保存和加载模型,包括三种方法:1、只保存和加载参数;2、保存和加载整个模型;3、在训练过程中保存和加载。

# 二、代码

## 1、只保存和加载参数

这样只需保存必要参数, 使得模型大小减小, 利于保存。

### 保存

```
torch.save(model.state_dict(), 'model_weights.pth')
```

这里保存上一部分内容中训练的模型。

#### 加载

```
model = NeuralNetwork()
model.load_state_dict(torch.load('model_weights.pth'))
print(model)
```

```
NeuralNetwork(
  (flatten): Flatten(start_dim=1, end_dim=-1)
  (linear_relu_stack): Sequential(
     (0): Linear(in_features=784, out_features=512, bias=True)
     (1): ReLU()
     (2): Linear(in_features=512, out_features=512, bias=True)
     (3): ReLU()
     (4): Linear(in_features=512, out_features=10, bias=True)
    )
)
```

# 2、保存和加载整个模型

#### 保存

```
torch. save (mode1, 'mode1.pth')
```

#### 加载完整模型

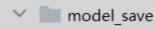
```
model = torch. load('model.pth')
print(model)
```

注意: 这里不需要model = NeuralNetwork()构建模型结构,因为保存时已经存了模型的结构。

# 3、训练中保存

#### 保存

```
}, os.path.join("model_save", str(t)))
print("Done!")
```





? 1

## 每一个epoch都会保存一次模型,并保存代化器。

```
model = NeuralNetwork()
loss_fn = nn. CrossEntropyLoss()
optimizer = torch. optim. SGD (model. parameters(), lr=0.001)

checkpoint = torch. load(os. path. join("model_save", str(0)))
model. load_state_dict(checkpoint['model_state_dict'])
optimizer. load_state_dict(checkpoint['optimizer_state_dict'])
epoch = checkpoint['epoch']
loss_last = checkpoint['loss']

# 再接着从0号模型进行训练
model. train()
train_loop(train_dataloader, model, loss_fn, optimizer)
loss_now = test_loop(test_dataloader, model, loss_fn)
print("loss_last", loss_last)
print("loss_now", loss_now)
```

```
loss: 0.796059 [ 64/60000]
loss: 0.338162 [ 6464/60000]
loss: 0.352287 [12864/60000]
loss: 0.463120 [19264/60000]
loss: 0.541893 [25664/60000]
loss: 0.507227 [32064/60000]
loss: 0.319748 [38464/60000]
loss: 0.460805 [44864/60000]
loss: 0.521575 [51264/60000]
loss: 0.641139 [57664/60000]
Test Error:
Accuracy: 87.1%, Avg loss: 0.352667
loss_last 0.48903237672439265
```

loss\_now 0.3526668991091282

接着从0号模型进行训练,这一次loss比上0号模型loss要小,说明再训练的模型性能是提高了的。