# **EVALUATE**

## 一、内容

加入模型的测试方法,包括分批处理 (batch)。

## 二、代码

#### 一、修改Loss

```
class Loss:
     # 统一通过调用calculate方法计算损失
     def calculate(self, y_pred, y_ture, *, add_regular_loss=False):
         # 对于不同的损失函数,通过继承Loss父类,并实现不同的forward方法。
         data loss = np. mean(self. forward(y pred, y ture))
         #加入了batch,所以要计算累计的损失和已训练过的样本数
          self.cumulate dataloss += data loss
         self.cumulate num += len(data loss)
         # 在加入正则代码后,可以求得正则损失
         # 注意之前版本调用regularization loss(layer)
         # 但这个版本有了self.trainable layer,可直接找到Dense层(有参数)
         regularization_loss = self.regularization_loss()
          if not add regular loss:
              # 在测试模型性能时只关心data loss
              regularization loss = 0
         #注意,这里计算得到的loss不作为类属性储存,而是直接通过return返回
          return data loss, regularization loss
     def calculate cumulate(self, *, add regularization=False):
          # 对于不同的损失函数,通过继承Loss父类,并实现不同的forward方法。
          sample loss = self. forward(y pred, y ture)
          data loss = np.mean(sample_loss)
          #加入了batch, 所以要计算累计的损失和已训练过的样本数
          self.cumulate_dataloss += np. sum(sample_loss)
          self.cumulate_num += len(sample_loss)
```

```
def clean_cumulate(self):
    self.cumulate_dataloss = 0
    self.cumulate_num = 0
```

加入了batch, 所以要计算累计的损失和已训练过的样本数,增加了self.cumulate\_dataloss和self.cumulate\_num属性,还有给清0属性的方法。

#### 二、修改Accuracy

```
class Accuracy:
     # 计算准确率
     def calculate(self, prediction, y true):
           # 获得比较结果
           comparision = self. compare(prediction, y true)
           # 计算准确率
           accuracy = np. mean (comparision)
           # 加入了累积精度属性
           self.cumulate dataloss += np. sum(comparision)
           self. cumulate num += len(comparision)
           return accuracy
     def calculate cumulate(self):
           # 平均精度
           accuracy = self.cumulate_dataloss / self.cumulate_num
           return accuracy
     def clean cumulate(self):
           self.cumulate_dataloss = 0
           self.cumulate num = 0
```

加入了batch, 所以要计算累计的损失和已训练过的样本数,增加了self.cumulate\_dataloss和self.cumulate\_num属性,还有给清0属性的方法。

### 三、修改Model

```
class Model():
    def evaluate(self, X_val, y_val, *, batch_size=None):
    # 默认只有一个batch
    validation_step = 1
    if batch_size is not None:
        validation_step = len(X_val) // batch_size
        if validation_step * batch_size < len(X_val): # 如果有余数
```

```
validation step += 1
           # 清除0
           self. loss. clean cumulate()
           {\tt self.\,accuracy.\,clean\_cumulate}\,()
           for step in range(validation_step):
                 # 没置batch
                 if not batch size:
                      X batch = X val
                      y batch = y val
                       # 这里有一个很好的性质,当(step+1)*batch_size超过X长度,则自动到
                 else:
最后为止。
                      X batch = X val[step * batch size: (step + 1) * batch size]
                      y batch = y val[step * batch size:(step + 1) * batch size]
                 # 输出层的输出
                 output = self.forward(X batch, False)
                 # 计算loss
                 data loss, regularization loss = self. loss. calculate (output, y batch)
                 loss = data loss + regularization loss
                 # 预测类别或预测值
                 prediction = self. output layer. prediction (output)
                 # 计算准确率
                 accuracy = self.accuracy.calculate(prediction, y batch)
           # 平均精度和损失
           validation accuracy = self.accuracy.calculate cumulate()
           validation data loss, validation regularizaion loss =
self.loss.calculate_cumulate()
           validation loss = validation regularization loss + validation data loss
           # 测试输出,输出的是在测试集上的平均表现
           print(f'validation, ' +
                    f'acc: {validation accuracy:.3f}, '+
                    f'loss: {validation loss:.3f}')
           # plt.plot(X val, y val)
           # plt.plot(X val, output)
           # plt. show()
     # 训练模型
     # epochs训练轮数
     # print every每多少轮输出一次
     def train(self, X, y, *, epochs=1, print_every=1, batch_size=None,
validation data=None):
           #数据集(默认)分为1个batch
           train_step = 1
           # 非默认情况
           if batch size is not None:
                 train step = len(X) // batch size
                 if train_step * batch_size < len(X): # 如果有余数
```

```
train step += 1
           # 注意: validation data需要输入一个元组,包括X、y
           for epoch in range (1, epochs+1):
                 print(f'epoch:{epoch}')
                 # 清累积
                 self. loss. clean cumulate()
                 self.accuracy.clean cumulate()
                 for step in range (train step):
                      # 没置batch
                      if not batch size:
                            X batch = X
                            y batch = y
                      else: # 这里有一个很好的性质, 当(step+1)*batch size超过X长度,则自
动到最后为止。
                            X batch = X[step*batch size: (step+1)*batch size]
                            y_batch = y[step*batch_size:(step+1)*batch_size]
                      # 前向传播
                      output = self. forward(X batch)
                      # 计算损失
                      data loss, regularization loss = self. loss. calculate (output,
y batch, add regular loss=True)
                      # 总loss
                      loss = data loss + regularization loss
                      # 计算预测值或预测类别
                      prediction = self.output_layer.prediction(output)
                      # 计算准确率
                      accuracy = self. accuracy. calculate(prediction, y_batch)
                      # 反向传播
                      self. backward (output, y batch)
                      # 优化器进行优化
                      self.optimizer.pre update param()
                      for layer in self. trainable layer:
                            self.optimizer.update_param(layer)
                      self.optimizer.post update param()
                      # step中打印的是每次的真实值
                       if not step % print_every or step == train_step - 1:
                            print(f'step: {step}, ' +
                                  f'acc: {accuracy:.3f}, ' +
                                  f'loss: {loss:.3f} ('+
                                  f'data loss: {data loss:.3f}, '+
                                  f'reg loss: {regularization loss:.3f}), '+
                                  f'lr: {self. optimizer. current learning rate}')
                 # 让epoch输出,输出每次epoch的平均值
```

#### 在Model类内加入了一个新方法evaluate, 通过调用evaluate来测试模型地性能。

```
epoch:1000
step: 0, acc: 1.000, loss: 0.226 (data_loss: 0.146, reg_loss: 0.080), lr: 0.000869678653737444
step: 100, acc: 0.900, loss: 0.348 (data_loss: 0.267, reg_loss: 0.080), lr: 0.0008696408383337683
step: 200, acc: 0.900, loss: 0.877 (data_loss: 0.797, reg_loss: 0.080), lr: 0.0008696030262185313
step: 299, acc: 1.000, loss: 0.460 (data_loss: 0.380, reg_loss: 0.080), lr: 0.0008695655954633024
training 1000, acc: 0.875, loss: 0.434 (data_loss: 0.354, reg_loss: 0.080), lr: 0.0008695655954633024
validation, acc: 0.867, loss: 0.380
validation, acc: 0.867, loss: 0.380
```