

# Seungheon (Hoon) Yang

[hoonyang00@gmail.com] | [Irvine, CA 92617] | [+1(949) 419-7812]

## EDUCATION

### University of California, Irvine

Bachelor of Science in Computer Engineering

Sep 2021 – Present

Cumulative GPA: 3.73/4.00

#### Honors & Memberships:

IEEE-Eta Kappa Nu (HKN) Honor Society – UCI Chapter

Dean's Honor List (7 of 8 quarters)

**Relevant Coursework:** Advanced C Programming, Computer Architecture, Computer Networks, Network Analysis I-II, Digital Systems and Logic, Discrete Mathematics

## PROJECTS

### MyToDo | Python, Flask, MongoDB, Jinja2, HTML/CSS

Dec 2025 – Present

- Implemented a task management web application with full CRUD operations using Flask and MongoDB
- Designed server-rendered pages using Jinja2 templates to create, update, and delete tasks

### Zotbotics | Python, Arduino C/C++, Raspberry Pi

Sep 2025 – Present

Software Subteam

- Implementing software tools for monitoring robot system status and telemetry during development and testing
- Integrated an AI chatbot pipeline using STT, TTS, and LLM-based text response APIs, enabling natural human–robot interaction

### Portfolio Website | HTML, CSS, JavaScript

Dec 2025 – Present

- Designed and developed a fully responsive personal portfolio website showcasing technical projects and experiences
- Integrated email functionality using EmailJS to enable direct contact through the website

### Drone Project | Embedded Systems, UAV Hardware, ArduPilot

Sep 2025 – Dec 2025

- Assembled and integrated UAV hardware, including flight controller, ESCs, motors, GPS, batteries, and radio systems, with extensive soldering and system validation
- Configured ArduPilot and ESP32-based telemetry to execute GPS-guided autonomous waypoint missions with real-time communication to a ground control station

## EXPERIENCE

### Undergraduate Research – AICPS Lab

Sep 2025 – Present

Research Assistant (Supervisor: Sadman Sakib, Ph.D. Student)

Irvine, CA

- Conducted a research project under Professor Mohammad Al Faruque to develop a multi-robot navigation framework using vision-language models, enabling collaborative planning, message sharing, and assisted navigation across multiple UAVs
- Developed an aerial VLN evaluation and visualization pipeline in OpenUAV, including trajectory analysis, metric extraction, and scene-level video generation
- Implemented closed-loop simulations, custom inputs, and automated scripts to streamline large-scale OpenUAV experiments
- Designing and developing a multi-agent LLM-based navigation system on a physical UAV platform

### Institute of Electrical and Electronic Engineers (IEEE)

Sep 2025 – Present

University of California, Irvine

Irvine, CA

- Engaged in the Open Project Space (OPS) program, contributing to the development of innovative engineering projects
- Developing and optimizing microcontroller-based applications using Raspberry Pi and Arduino

## CERTIFICATIONS

### DeepLearning.AI TensorFlow Developer Specialization – DeepLearning.AI via Coursera

Feb 2025 – Mar 2025

Embedded Software Development with C – EDUCBA via Coursera

Feb 2025 – Mar 2025

SQL Developer (SQLD) – Korea Data Agency

Jun 2025 – Sep 2025

## SKILLS

**Programming languages:** Python, C/C++, Java, HTML, CSS, SQL (Oracle), Arduino C/C++, JavaScript, LC-3 Assembly

**Tools & Libraries:** Linux, Flask, Jinja2, PyMongo, TensorFlow, NumPy, Pandas, Git, Xilinx Vivado

**Embedded & Hardware:** Embedded Systems, Soldering, Circuit Analysis

**Languages:** Native in Korean, Fluent in English