



## How?

## Example Game App

DB v0

(Recap <u>lectures</u>)



Q1: 1000 users/sec writing?

02: Offline?

Q3: Support v1, v1' versions?

Q7: How to model/evolve game data?

Q8: How to scale to millions of users?

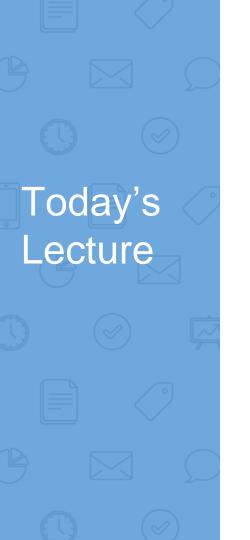
Q9: When machines die, restore game state gracefully?

Q5: Next features to build? Experiments to run?

Q4: Which user cohorts?

Q6: Predict ads demand?

Product/Biz designer App designer Systems designer



1. Indexing

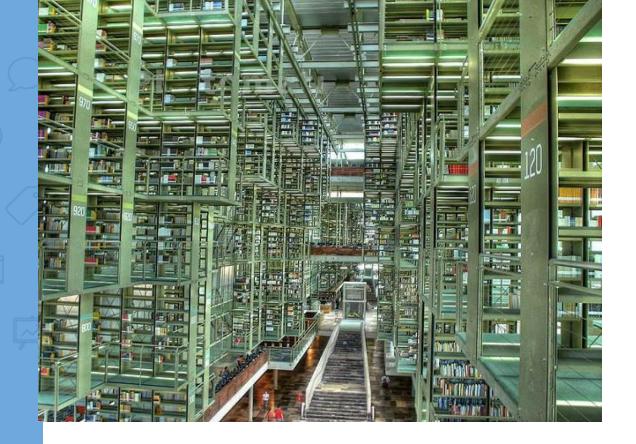
2. IO Model

3. External Merge



## 1. Indexing

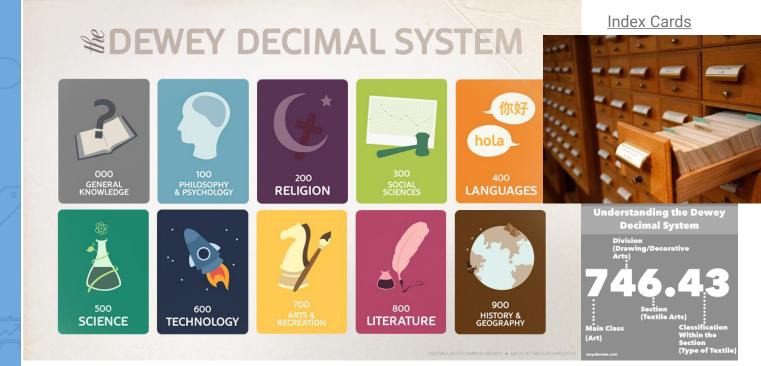
Find Book in Library



#### Design choices?

- <u>Scan</u> through each aisle
- Lookup pointer to book location, with librarian's organizing scheme

Find Book in Library With Index



#### Algorithm for book titles

- Find right category
- Lookup <u>Index</u>, find location
- Walk to aisle. <u>Scan</u> book titles. Faster if books are <u>sorted</u>

# "If you don't find it in the index, look very carefully through the entire catalog"

- Sears, Roebuck and Co., Consumers Guide, 1897



## Indexes on a table

- An <u>index</u> speeds up selections on <u>search key (s)</u>
  - Any subset of fields
- Example

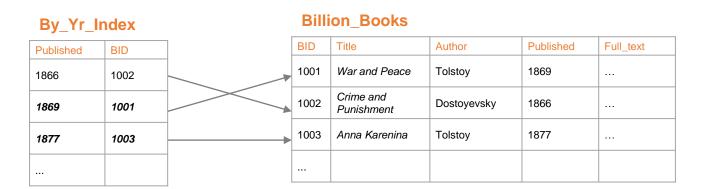
Books(BID, name, author, price, year, text)

On which attributes would you build indexes?

#### Billion\_Books

BID	Title	Author	Published	Full_text
1001	War and Peace	Tolstoy	1869	
1002	Crime and Punishment	Dostoyevsky	1866	
1003	Anna Karenina	Tolstoy	1877	

SELECT \*
FROM Billion\_Books
WHERE Published > 1867



Maintain an index for this, and search over that!

Why might just keeping the table sorted by year not be good enough?

#### By\_Yr\_Index

Published	BID	
1866	1002	_
1869	1001	_
1877	1003	_

#### Russian\_Novels

	BID	Title	Author	Published	Full_text
	1001	War and Peace	Tolstoy	1869	
>	1002	Crime and Punishment	Dostoyevsky	1866	
	1003	Anna Karenina	Tolstoy	1877	

#### By\_Author\_Title\_Index

Author	Title	BID
Dostoyevsky	Crime and Punishment	1002
Tolstoy	Anna Karenina	1003
Tolstoy	War and Peace	1001

Can have multiple indexes to support multiple search keys

Indexes shown here as tables, but in reality we will use more efficient data structures...

## **Covering Indexes**

By\_Yr\_Index

Published	BID
1866	1002
1869	1001
1877	1003

An index <u>covers</u> for a specific query if the index contains all the needed attributesmeaning the query can be answered using the index alone!

The "needed" attributes are the union of those in the SELECT and WHERE clauses...

Example:

SELECT Published, BID FROM Billion\_Books WHERE Published > 1867

## Kinds of Indexes (different data types)



<u>Index</u> for Strings, Integers

Time series, GPS traces, Genomes, Video sequences

Advanced: Equality vs Similarity, Ranges, Subsequences Composites of above



## Indexes (definition)

## An <u>index</u> is a **data structure** mapping <u>search keys</u> to <u>sets</u> of rows in table

 Provides efficient lookup & retrieval by search key value (usually much faster than scanning all rows and searching)

#### An index can store

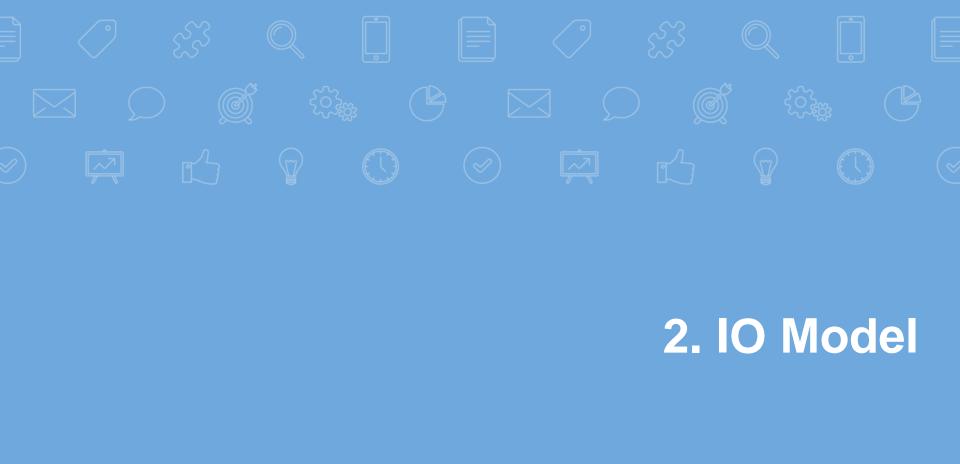
- full rows it points to (primary index), OR
- pointers to rows (secondary index) [much of our focus]



## **Operations on an Index**

- <u>Search</u>: Quickly find all records which meet some condition on the search key attributes
  - (Advanced: across rows, across tables)
- Insert / Remove entries
  - Bulk Load / Delete. Why?

Indexing is one the most important features provided by a database for performance



## Transition to Indexing Mechanisms

#### 1. So you can **understand** what the database is doing!

- Understand the CS challenges of a database and how to use it.
- Understand how to optimize a query

#### 2. Many mechanisms have become stand-alone systems

- Indexing to Key-value stores
- Embedded join processing
- SQL-like languages take some aspect of what we discuss (PIG, Hive)

What you will learn about in this section

1. RECAP: Storage and memory model

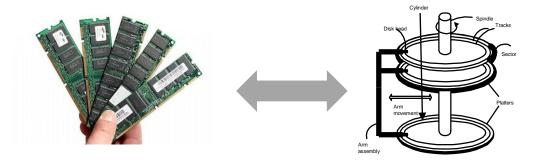
1. Buffer primer

2. Pages

3. Files



## High-level: Main Memory vs. Disk



#### Random Access Memory (RAM) or Main Memory:

- Fast: Random access, byte addressable
  - ~10x faster for sequential access
  - ~100,000x faster for random access!
- Volatile: Data can be lost if e.g. crash occurs, power goes out, etc!
- Expensive: For \$100, get 16GB of RAM vs. 2TB of disk!

#### Disk:

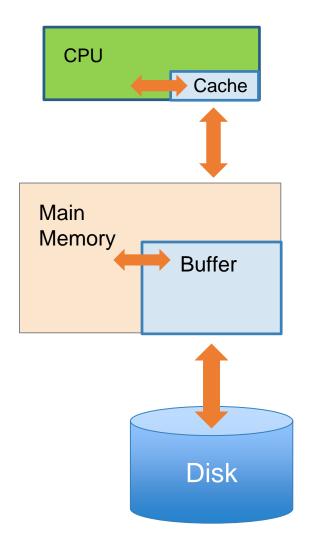
- Slow: Sequential block access
  - Read a blocks (not byte) at a time, so sequential access is cheaper than random
  - Disk read / writes are expensive!
- Durable: We will assume that once on disk, data is safe!
- Cheap



### The Buffer

- A <u>buffer</u> is a part of physical memory used to store *temporary data*
  - In this lecture: a region in main memory used to store intermediate data between processes and disk
- Why? Reading / writing to disk is slowneed to cache data!

**RECAP: Storage and memory model** 

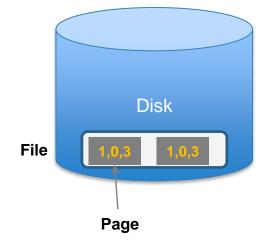




## A Simplified Filesystem Model

- For us, a <u>page</u> is *fixed-sized array* of memory
  - · Think: One or more disk blocks
  - Interface: write to an entry (called a slot) or set to "None"
  - DBMS also needs to handle variable length fields
    - Page layout is key for good hardware utilization (in cs 346)

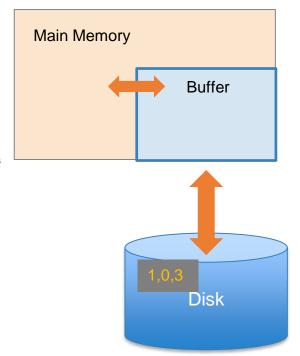
- And a file is a variable-length list of pages
  - Interface: create / open / close; next\_page(); etc.





Buffer located in **main memory** operates over **pages** and **files**:

Read(page): Read page from disk --> buffer if not already in buffer

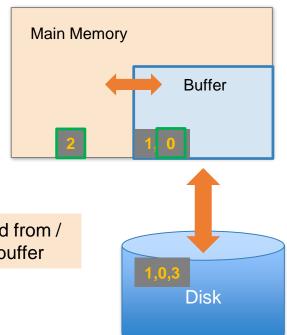




Buffer located in **main memory** operates over **pages** and **files**:

Read(page): Read page from disk --> buffer if not already in buffer

Processes can then read from / write to the page in the buffer

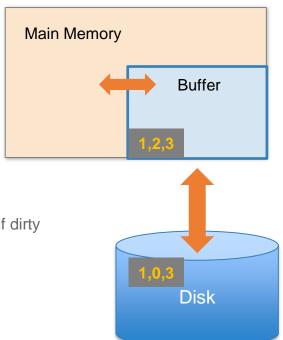




Buffer located in **main memory** operates over **pages** and **files**:

Read(page): Read page from disk --> buffer if not already in buffer

 Flush(page): Evict page from buffer & write to disk, if dirty (dirty ⇒ modified page)



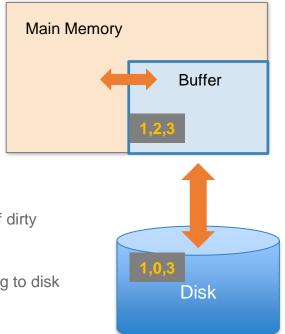


Buffer located in **main memory** operates over **pages** and **files**:

Read(page): Read page from disk --> buffer if not already in buffer

• Flush(page): Evict page from buffer & write to disk if dirty

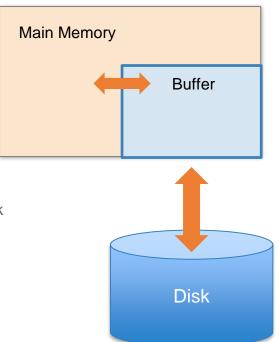
Release(page): Evict page from buffer without writing to disk





## Managing Disk: The DBMS Buffer

- Database maintains its own buffer.
  - Why? The OS already does this...
  - DB knows more about access patterns
  - Recovery and logging require ability to **flush** to disk





## The Buffer Manager

- A <u>buffer manager</u> manages operations for the buffer:
  - Primarily, handles & executes the "replacement policy"
    - i.e. finds a page in buffer to flush/release if buffer is full and a new page needs to be read in
  - DBMSs typically implement their own buffer management routines



#### Primary data structures/algorithms

Big Scaling (with Indexes)

Roadmap







Hashing

HashTables (hash<sub>i</sub>(key) --> value)



Sorting

BucketSort, QuickSort MergeSort

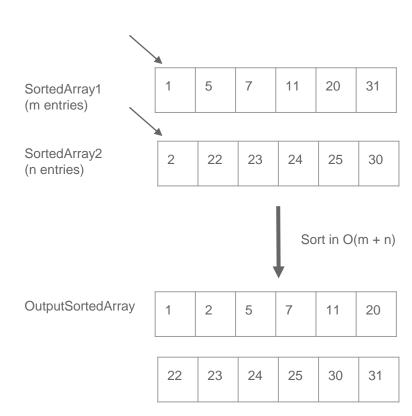
MergeSort

Counting

HashTable + Counter (hash<sub>i</sub>(key) --> <count>)

MergeSortedFiles,







## Challenge: Merging Big Files with Small Memory

How do we *efficiently* merge two sorted files when both are much larger than our main memory buffer?

**Key point:** Disk IO (R/W) dominates the algorithm cost

Our first example of an "IO aware" algorithm / cost model



Input: 2 sorted lists of length M and N

Output: 1 sorted list of length M + N

Required: At least 3 Buffer Pages

• **IOs**: 2(M+N)

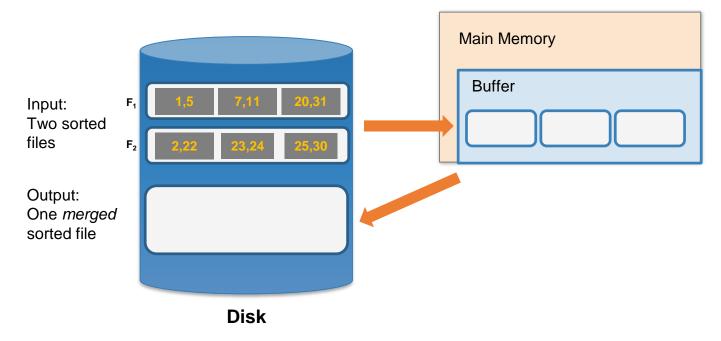


## Key (Simple) Idea

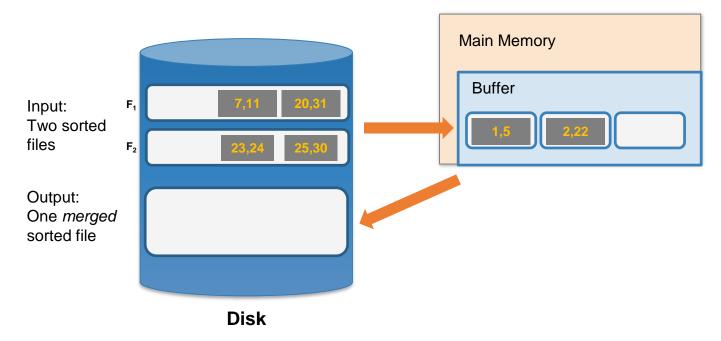
To find an element that is no larger than all elements in two lists, one only needs to compare minimum elements from each list.

If:  $A_1 \leq A_2 \leq \cdots \leq A_N \\ B_1 \leq B_2 \leq \cdots \leq B_M$  Then:  $Min(A_1, B_1) \leq A_i \\ Min(A_1, B_1) \leq B_j$  for i=1....N and j=1....M

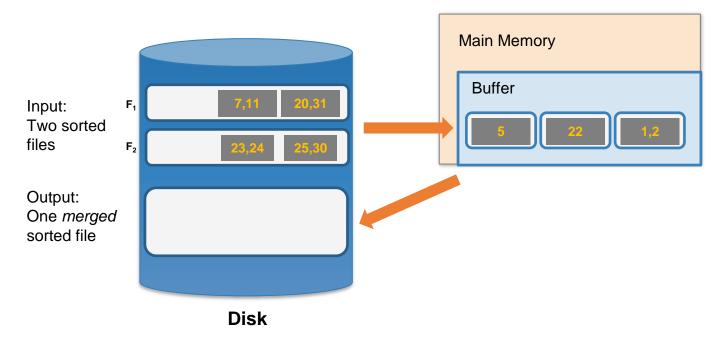




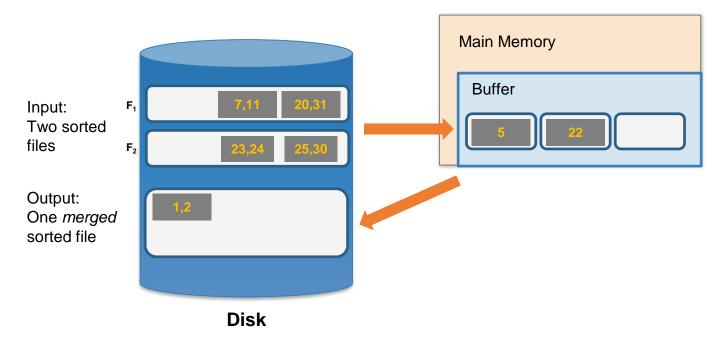




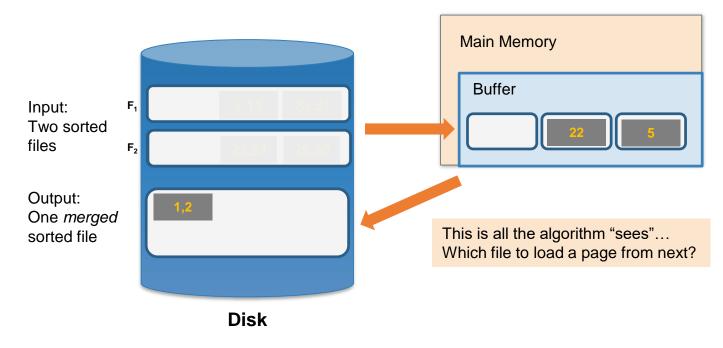




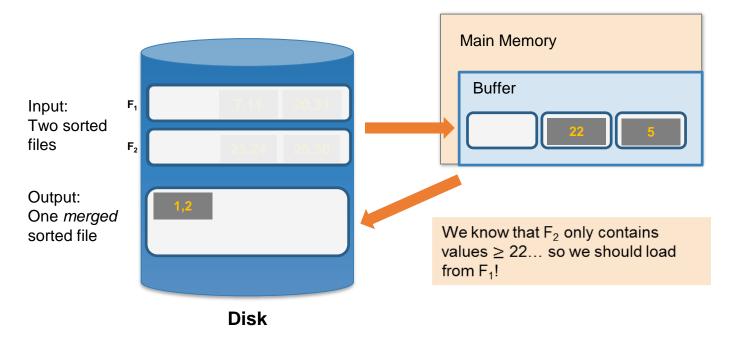




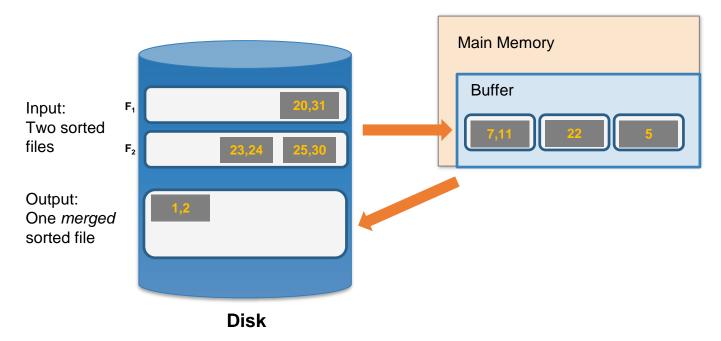




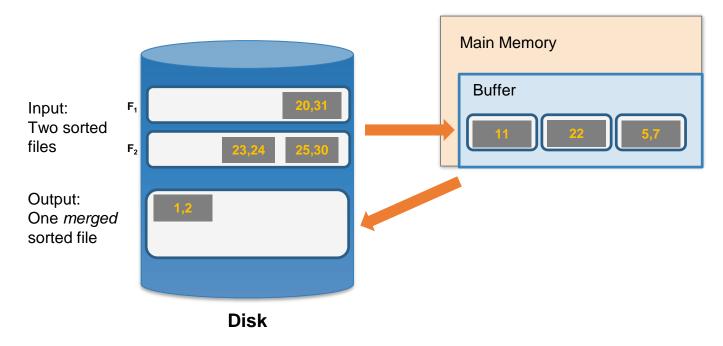




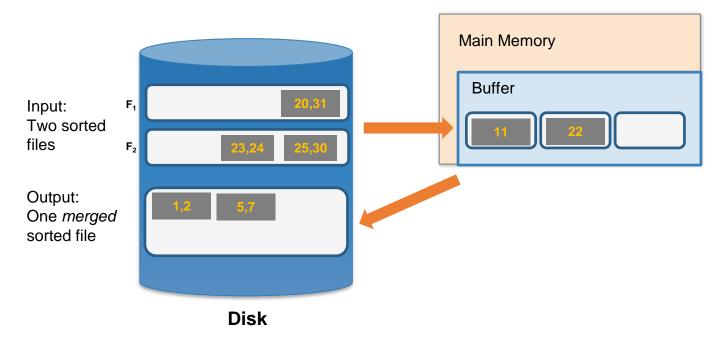




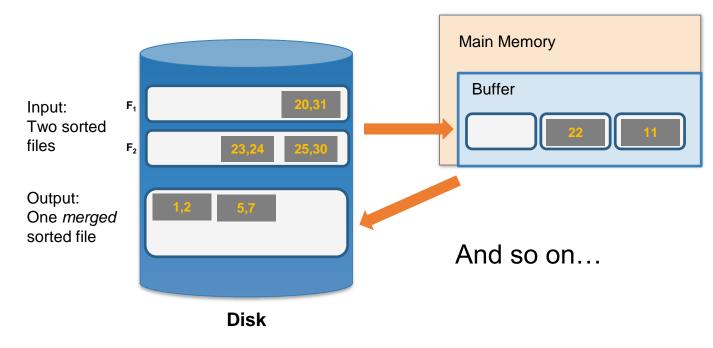














# We can merge lists of arbitrary length with only 3 buffer pages.

If lists of size M and N, then

Cost: 2(M+N) IOs

Each page is read once, written once

With B+1 buffer pages, can merge B lists. How?



#### **Recap: External Merge Algorithm**

- Suppose we want to merge two sorted files both much larger than main memory (i.e. the buffer)
- We can use the external merge algorithm to merge files of arbitrary length in 2\*(N+M) IO operations with only 3 buffer pages!

Our first example of an "IO aware" algorithm / cost model

#### Primary data structures/algorithms

Hashing

Sorting

Counting

Big Scaling (with Indexes)



HashTables (hash<sub>i</sub>(key) --> value)

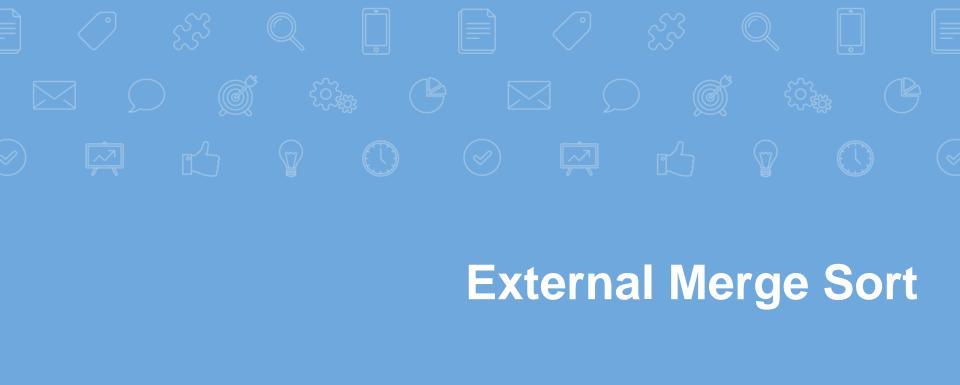
BucketSort, QuickSort MergeSort HashTable + Counter (hash<sub>i</sub>(key) --> <count>)

Roadmap



MergeSortedFiles

?????





#### Why are Sort Algorithms Important?

- Data requested from DB in sorted order is extremely common
  - e.g., find students in increasing GPA order

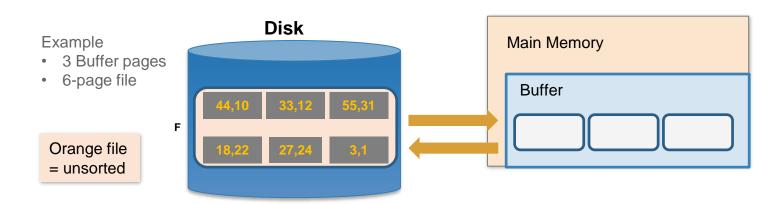
- Why not just use quicksort in main memory??
  - How to Sort 10TB of data with 1GB of RAM....

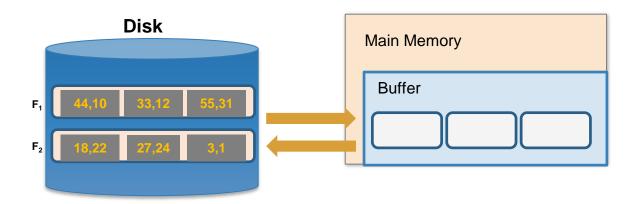
A classic problem in computer science!

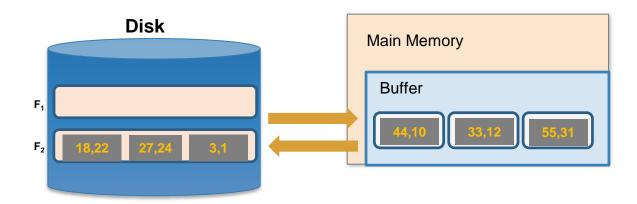


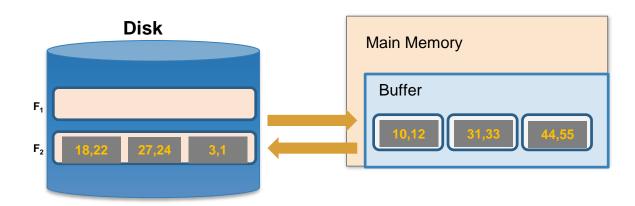
## So how do we sort big files?

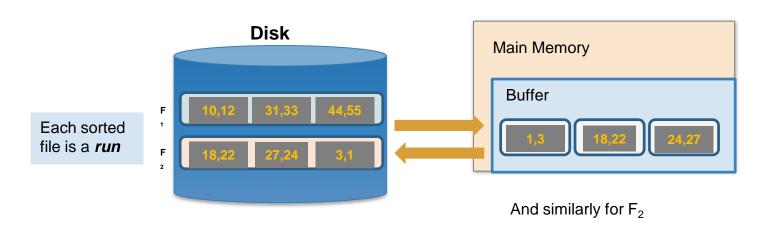
- 1. Split into chunks small enough to sort in memory ("runs")
- Merge pairs (or groups) of runs with external merge algorithm
- 1. Keep merging the resulting runs (each time = a "pass") until left with one sorted file!

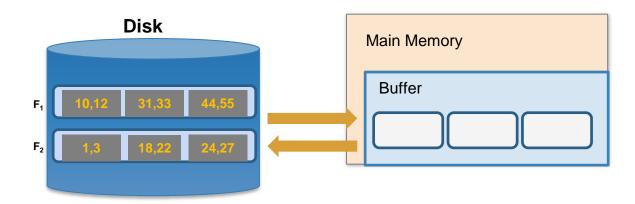












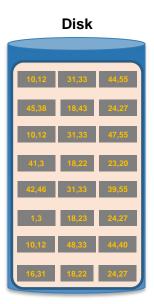
2. Now just run the **external merge** algorithm & we're done!



#### **Calculating IO Cost**

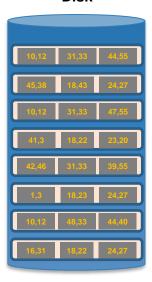
For 3 buffer pages, 6 page file:

- 1. Split into <u>two 3-page files</u> and sort in memory = 1 R + 1 W per page = 2\*(3 + 3) = 12 IO operations
- 1. Merge each pair of sorted chunks with external merge algorithm = 2\*(3 + 3) = 12 IO operations
- 1. Total cost = 24 IO



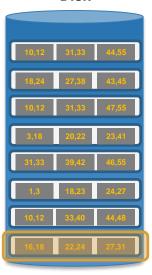
Assume we still only have 3 buffer pages (Buffer not pictured)

#### Disk



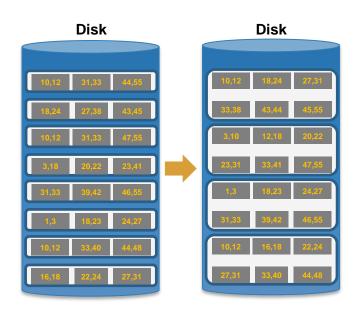
1. Split into files small enough to sort in buffer...

#### Disk

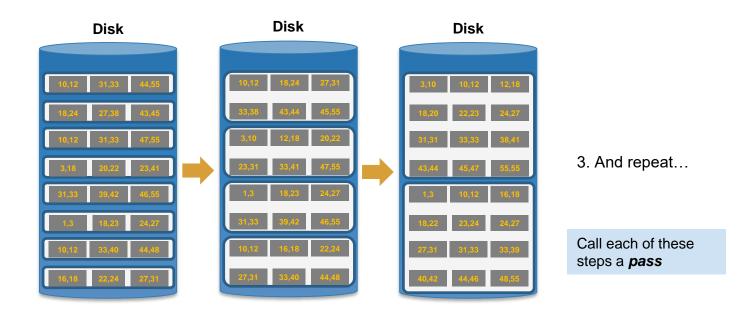


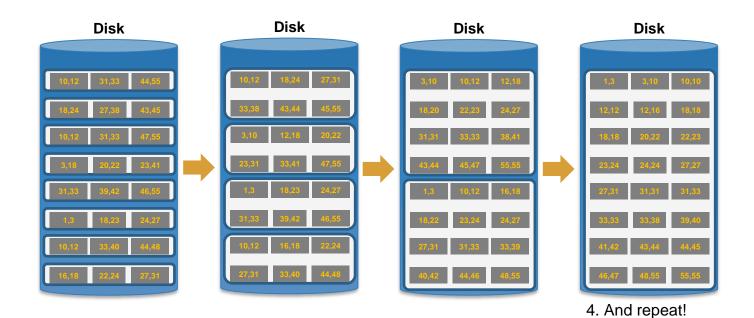
1. Split into files small enough to sort in buffer... and sort

Each sorted file is a run



2. Now merge pairs of (sorted) files... the resulting files will be sorted!



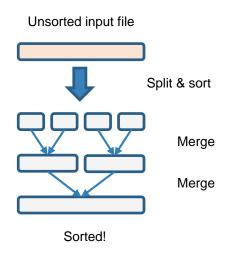




#### Simplified 3-page Buffer Version

Assume for simplicity that we split an N-page file into N single-page *runs* and sort these; then:

- First pass: Merge N/2 pairs of runs each of length 1 page
- Second pass: Merge N/4 pairs of runs each of length 2 pages
- In general, for **N** pages, we do  $[log_2 N]$  passes
  - +1 for the initial split & sort
- Each pass involves reading in & writing out all the pages = 2N IO



 $\rightarrow$  2N\*([log<sub>2</sub>N]+1) total IO cost!



## **External Merge Sort: Optimizations**

Now assume we have **B+1 buffer pages**; three optimizations:

- 1. Increase the length of initial runs
- 2. B-way merges
- 3. Repacking



# Using B+1 buffer pages to reduce # of passes

Suppose we have B+1 buffer pages now; we can:

1. Increase length of initial runs. Sort B+1 at a time!
At the beginning, we can split the N pages into runs of length B+1 and sort these in memory

#### IO Cost:

$$2N(\lceil \log_2 N \rceil + 1) \longrightarrow 2N(\left\lceil \log_2 \frac{N}{B+1} \right\rceil + 1)$$

Starting with runs of length 1

Starting with runs of length **B+1** 



# Using B+1 buffer pages to reduce # of passes

Suppose we have B+1 buffer pages now; we can:

#### 2. Perform a B-way merge.

On each pass, we can merge groups of **B** runs at a time (vs. merging pairs of runs)!

#### IO Cost:

$$2N(\lceil \log_2 N \rceil + 1) \longrightarrow 2N(\left\lceil \log_2 \frac{N}{B+1} \right\rceil + 1) \longrightarrow 2N(\left\lceil \log_B \frac{N}{B+1} \right\rceil + 1)$$

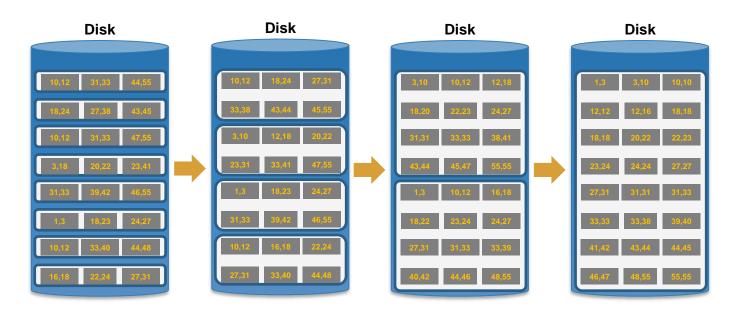
Starting with runs of length 1

Starting with runs of length **B+1** 

Performing **B-**way merges

Pretty fast IO aware sort !!

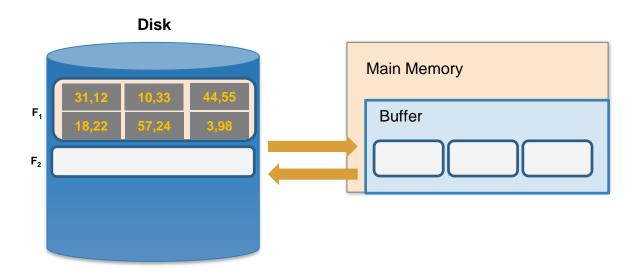
# Repacking for longer runs (Optimization)



Idea: What if it's already 'partly' sorted?

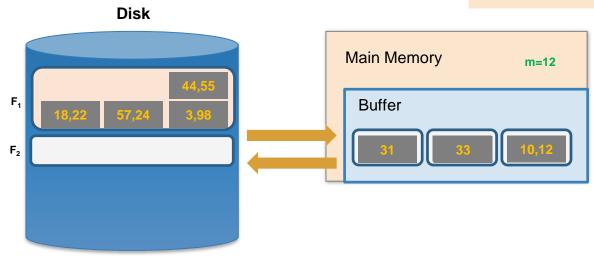
Can we be smarter with buffer?

Start with unsorted single input file, and load 2 pages

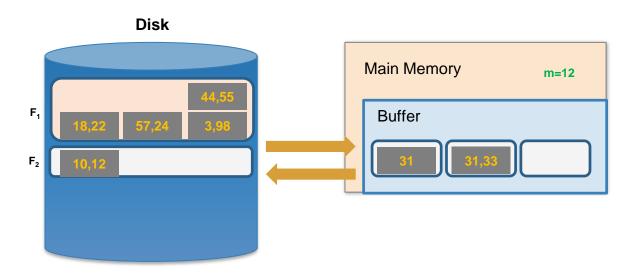


Take the minimum two values, and put in output page

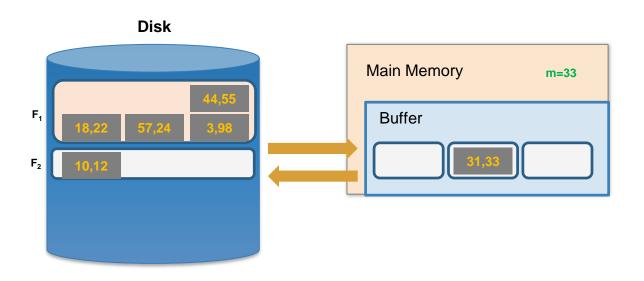
Also keep track of max (last) value in current run...

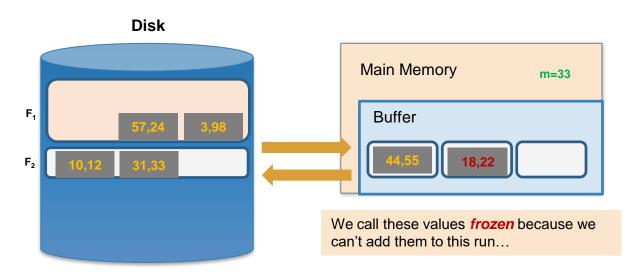


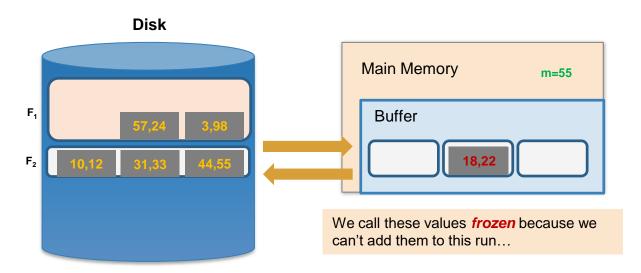
Next, repack

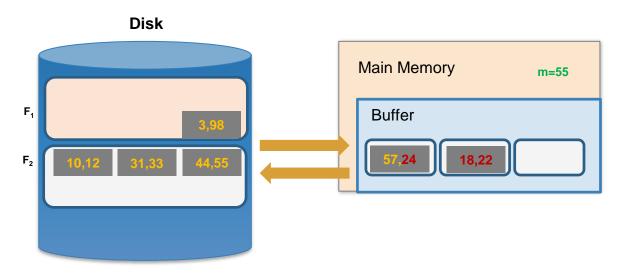


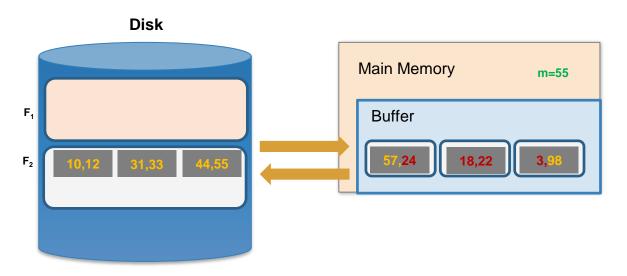
Next, repack, then load another page and continue!

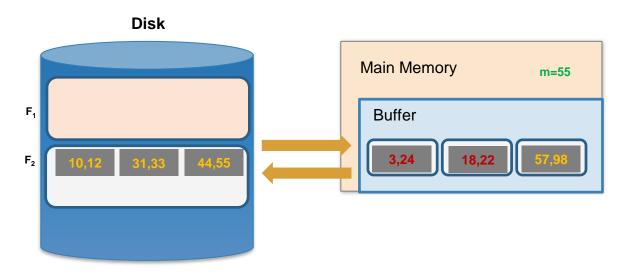




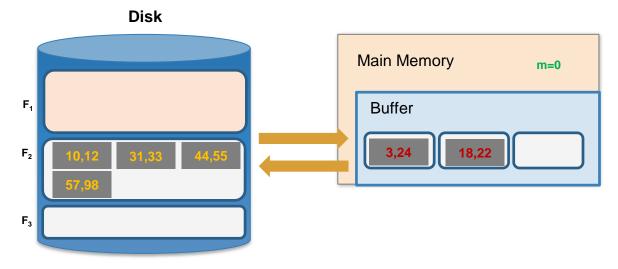




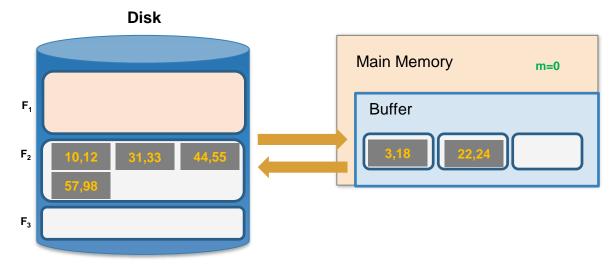




 Once all buffer pages have a frozen value, or input file is empty, start new run with the frozen values



 Once all buffer pages have a frozen value, or input file is empty, start new run with the frozen values





#### Repacking

- Note that, for buffer with B+1 pages:
  - Best case: If input file is sorted → nothing is frozen → we get a single run!
  - Worst case: If input file is reverse sorted → everything is frozen → we get runs of length B+1

- In general, with repacking we do **no worse** than without it!
- Engineer's approximation: runs will have ~2(B+1) length

$$\sim 2N(\left[\log_B \frac{N}{2(B+1)}\right] + 1)$$



## Sorting, with insertions?

What if we want to insert a new person, but keep list sorted?



- We would have to potentially shift **N** records, requiring up to ~ **2\*N/P** IO operations (where P = # of records per page)!
  - We could leave some "slack" in the pages...

Could we get faster insertions? (next section)

#### Primary data structures/algorithms

Big Scaling (with Indexes)



HashTables (hash;(key) --> value)

**Hashing** 

Sorting

Counting

BucketSort, QuickSort MergeSort HashTable + Counter (hash<sub>i</sub>(key) --> <count>)

Roadmap

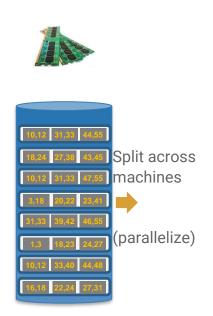


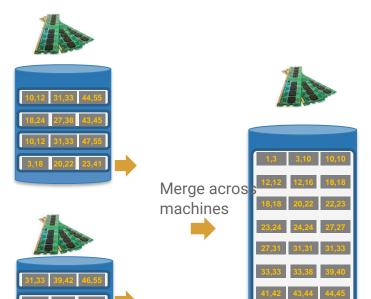


MergeSortedFiles SortFiles

?????

# Scaling, Speeding Sort (in Cluster)







MergeSort locally in each machine (in parallel)

#### Notes

- Use N machines (N >= 2)
- Could reuse machines
- Speedup at cost of network bandwidth (especially with current data centers)

Example: AWS/GCP offer machine instances (e.g., ec2.r5 offers 1-3GBps network bandwidth, 2CPU/16GB RAM to 96 CPU/768GB RAM for \$-\$\$\$ in Nov'18)



#### **Summary**

Basics of IO and buffer management.

- We introduced the IO cost model using sorting.
  - Saw how to do merges with few IOs,
  - Works better than main-memory sort algorithms
- Described a few optimizations for sorting