## Matrix determinant, inverse solving of system of equations

## Matrix Determinant

```
In [ ]: import numpy as np
        from numpy import*
In [ ]: # Creating a matrix
        A = np.matrix('1 4 6; 2 56 54; 2 0 4')
Out[]: matrix([[1, 4, 6],
                [ 2, 56, 54],
                [ 2, 0, 4]])
In [ ]: # Calculating the determinant
        det = np.linalg.det(A)
Out[]: -47.9999999999999
In [ ]: # Creatubg a matrix
        C = np.matrix('1 2 5; 2 3 4; 5 6 8')
        C
Out[]: matrix([[1, 2, 5],
                [2, 3, 4],
                [5, 6, 8]])
In [ ]: # Finding the inverse of the matrix
        Inv = np.linalg.inv(C)
Out[]: matrix([[ 1.77635684e-16, -2.00000000e+00, 1.00000000e+00],
                [-5.71428571e-01, 2.42857143e+00, -8.57142857e-01],
                [ 4.28571429e-01, -5.71428571e-01, 1.42857143e-01]])
```

## Solving Linear Systems

```
In [ ]: # Ax = B
    a = np.matrix('3 -1 1;2 1 0; 1 2 -1') #Co-efficients of x variable
    b = np.matrix('2;1;3') #R.H.S value - B

#x = Inverse of A * B
    x = np.linalg.inv(a) * b
    print(x)

[[ 2.]
    [-3.]
    [-7.]]
```

```
x_1=2, x_2=-3, x_3=-7
```