

$$G_f = k_f \frac{\tau_1 s + 1}{\tau_2 s + 1}$$

2-Tustin's metode) $s = \frac{2(z-1)}{T(z+1)}$

$$\rightarrow G_f = k_f \frac{2\tau_1(z-1) + T(z+1)}{2\tau_2(z-1) + T(z+1)}, \theta_f = \frac{y}{x}$$

$$Y(z) [2\tau_2 z - 2\tau_2 + Tz + T] = k_f [2\tau_1 z - 2\tau_1 + Tz + T] X(z)$$

$$Y(z) [(2\tau_2 + T)z + T - 2\tau_2] = k_f [(2\tau_1 + T)z + T - 2\tau_1] X(z)$$

$$Y(z) [(2\tau_2 + T) + z^{-1}(T - 2\tau_2)] = k_f [(2\tau_1 + T) + z^{-1}(T - 2\tau_1)] X(z)$$

$$\Rightarrow (2\tau_2 + T)y[n] + (T - 2\tau_2)y[n-1] =$$

$$k_f (2\tau_1 + T)x[n] + k_f (T - 2\tau_1)x[n-1]$$

$$\rightarrow y[n] = \frac{1}{2\tau_2 + T} \left[(2\tau_2 - T)y[n-1] + k_f (2\tau_1 + T)x[n] + k_f (T - 2\tau_1)x[n-1] \right]$$
