# CS 229 Homework

Tyler Neylon

345.2016

These are solutions to the most recent problems posted for Stanford's CS 229 course, as of June 2016. I'm not sure if this course re-uses old problems, but please don't copy the answers if so. This document is also available as a pdf.

## 1 Problem set 1

## 1.1 Logistic regression

#### 1.1.1 Part (a)

The problem is to compute the Hessian matrix H for the function

$$J(\theta) = -\frac{1}{m} \sum_{i=1}^{m} \log(g(y^{(i)}x^{(i)})),$$

where g(z) is the logistic function, and to show that H is positive semi-definite; specifically, that  $z^T H z \ge 0$  for any vector z.

We'll use the fact that g'(z) = g(z)(1 - g(z)). We'll also note that since all relevant operations are linear, it will suffice to ignore the summation over i in the definition of J. I'll use the notation  $\partial_j$  for  $\frac{\partial}{\partial \theta_j}$ , and introduce t for  $y\theta^T x$ . Then

$$-\partial_{j}(mJ) = \frac{g(t)(1 - g(t))}{g(t)}x_{j}y = x_{j}y(1 - g(t)).$$

Next

$$-\partial_k \partial_j(mJ) = x_j y \big( -g(t)(1-g(t)) \big) x_k y,$$

so that

$$\partial_{jk}(mJ) = x_j x_k y^2 \alpha,$$

where  $\alpha = g(t)(1 - g(t)) > 0$ .

Thus we can use repeated-index summation notation to arrive at

$$z^T H z = z_i h_{ij} z_j = (\alpha y^2)(z_i x_i x_j z_j) = (\alpha y^2)(x^T z)^2 \ge 0.$$

This completes this part of the problem.

### 1.1.2 Part (b)

Here is a matlab script to solve this part of the problem:

```
% problem1_1b.m
% Run Newton's method on a given cost function for a logistic
% regression setup.
printf('Running problem1_1b.m\n');
% Be able to compute J.
function val = J(Z, theta)
  [m, _] = size(Z);
       = 1 ./ (1 + exp(Z * theta));
 val
        = -sum(log(g)) / m;
end
% Setup.
      = load('logistic_x.txt');
[m, n] = size(X);
       = [ones(m, 1) X];
       = load('logistic_y.txt');
       = diag(Y) * X;
% Initialize the parameters to learn.
old_theta = ones(n + 1, 1);
theta
         = zeros(n + 1, 1);
          = 1; % i = iteration number.
% Perform Newton's method.
while norm(old_theta - theta) > 1e-5
 printf('J = %g\n', J(Z, theta));
```

```
printf('theta:\n');
 disp(theta);
 printf('Running iteration %d\n', i);
            = 1 ./ (1 + \exp(Z * \text{theta}));
 f
            = (1 - g);
            = f .* g;
 alpha
            = diag(alpha);
 Α
            = Z' * A * Z / m;
 nabla
           = Z' * f / m;
 old_theta = theta;
           = theta - inv(H) * nabla;
 theta
 i++;
end
% Show and save output.
printf('Final theta:\n');
disp(theta);
save('theta.mat', 'theta');
Because I have copious free time, I also wrote a Python version. Also because
I'm learning numpy and would prefer to consistently use a language that I know
can produce decent-looking graphs. Here is the Python script:
#!/usr/bin/env python
import numpy as np
from numpy import linalg as la
# Define the J function.
def J(Z, theta):
 m, _ = Z.shape
      = 1 / (1 + np.exp(Z.dot(theta)))
 return -sum(np.log(g)) / m
# Load data.
     = np.loadtxt('logistic_x.txt')
m, n = X.shape
     = np.insert(X, 0, 1, axis=1) # Prefix an all-1 column.
Y
     = np.loadtxt('logistic_y.txt')
     = np.diag(Y).dot(X);
# Initialize the learning parameters.
old_theta = np.ones((n + 1,))
theta
        = np.zeros((n + 1,))
```

```
i
          = 1
# Perform Newton's method.
while np.linalg.norm(old_theta - theta) > 1e-5:
  # Print progress.
 print('J = {}'.format(J(Z, theta)))
 print('theta = {}'.format(theta))
 print('Running iteration {}'.format(i))
 # Update theta.
            = 1 / (1 + np.exp(Z.dot(theta)))
            = 1 - g
            = (f * g).flatten()
 alpha
            = (Z.T * alpha).dot(Z) / m
 Η
            = Z.T.dot(f) / m
 nabla
 old_theta = theta
          = theta - la.inv(H).dot(nabla)
 # Update i = the iteration counter.
  i += 1
# Print and save the final value.
print('Final theta = {}'.format(theta))
np.savetxt('theta.txt', theta)
The final value of \theta that I arrived at is
```

The first value  $\theta_0$  represents the constant term, so that the final model is given by

 $\theta = (2.62051, -0.76037, -1.17195).$ 

$$y = g(2.62 - 0.76x_1 - 1.17x_2).$$

#### 1.1.3 Part (c)

## 1.2 Poisson regression and the exponential family

#### 1.2.1 Part (a)

Write the Poisson distribution as an exponential family:

$$p(y; \eta) = b(y) \exp \left(\eta^T T(y) - a(\eta)\right),$$

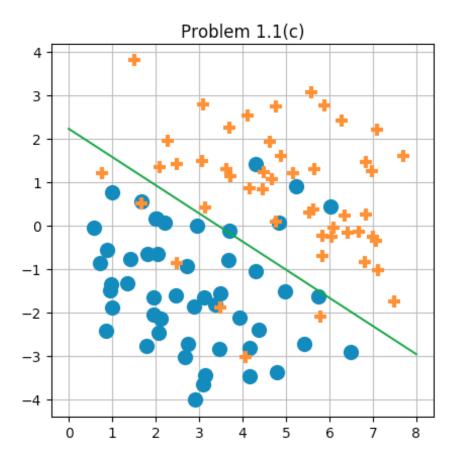


Figure 1: The data points given for problem 1.1 along with the decision boundary learned by logistic regression as executed by Newton's method.

where

$$p(y;\lambda) = \frac{e^{-\lambda}\lambda^y}{y!}.$$

This can be done via

$$\begin{array}{rcl} \eta & = & \log(\lambda), \\ a(\eta) & = & e^{\eta} = \lambda, \\ b(y) & = & 1/y!, \text{ and} \\ T(y) & = & y. \end{array}$$