LED:

CODE SEGMENT

ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE

PPIC_C EQU 1FH PPIC EQU 1DH PPIB EQU 1BH PPIA EQU 19H **ORG 1000H** MOV AL,10000000B OUT PPIC_C,AL L1: MOV AL,00000101B OUT PPIB,AL CALL DELAY MOV AL,00000000B OUT PPIB,AL CALL DELAY JMP L1 DELAY: MOV CX,1111111111111111 TIMER1: NOP NOP NOP NOP LOOP TIMER1 RET

CODE ENDS

END

LED 10 bar:

CODE SEGMENT

ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE PPIC_C EQU 1FH PPIC EQU 1DH PPIB EQU 1BH PPIA EQU 19H ORG 1000H MOV AL,10000000B OUT PPIC_C,AL mov bh,00001010B L1: MOV AL,0000001B OUT PPIB,AL CALL DELAY MOV AL,00000000B OUT PPIB,AL **CALL DELAY** dec bh cmp bh,00000000B je end JMP L1 DELAY: MOV CX,1111111111111111 TIMER1: NOP NOP NOP NOP LOOP TIMER1

RET

end:
CODE ENDS
END
7 SEGMENT:
CODE SEGMENT
ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE
PPIC_C EQU 1FH
PPIC EQU 1DH
PPIB EQU 1BH
PPIA EQU 19H
ORG 1000H
MOV AL,10000000B
OUT PPIC_C,AL
L1: MOV AL,01000000B
OUT PPIA,AL
CALL DELAY
MOV AL,11111001B
OUT PPIA,AL
CALL DELAY
JMP L1
DELAY: MOV CX,111111111111111
TIMER1: NOP
NOP
NOP
NOP

```
LOOP TIMER1
RET
CODE ENDS
END
Dot col GREEN:
CODE SEGMENT
ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE
PPIC_C EQU 1EH; control register
PPIC EQU 1CH
PPIB EQU 1AH
PPIA EQU 18H
ORG 1000H
MOV AL,10000000B
OUT PPIC_C,AL
MOV AL,11111111B
OUT PPIC,AL
MOV AL,11111111B
OUT PPIB,AL
L1: MOV AL,11111110B
L2: OUT PPIA,AL
CALL TIMER
ROL AL,1
```

TIMER: MOV CX,0FFFFH

TIMER1: NOP

JC L2

JMP L1

```
NOP
NOP
NOP
LOOP TIMER1
RET
CODE ENDS
END
Dot col GREEN(majher4 ta jolbe sudhu upore niche 2 ta kore 4 ta
row jolbe na):
CODE SEGMENT
ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE
PPIC_C EQU 1EH; control register
PPIC EQU 1CH
PPIB EQU 1AH
PPIA EQU 18H
ORG 1000H
MOV AL,10000000B
OUT PPIC_C,AL
MOV AL,00111100B
OUT PPIC,AL
MOV AL,11111111B
OUT PPIB,AL
L1: MOV AL,11111110B
L2: OUT PPIA,AL
CALL TIMER
ROL AL,1
JC L2
JMP L1
```

TIMER: MOV CX,0FFFFH TIMER1: NOP NOP NOP NOP LOOP TIMER1 RET **CODE ENDS** END **Dot row RED: CODE SEGMENT** ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE; PPIC_C EQU 1EH PPIC EQU 1CH PPIB EQU 1AH PPIA EQU 18H ORG 1000H MOV AL,10000000B OUT PPIC_C,AL MOV AL,00000000B OUT PPIB,AL MOV AL,11111111B OUT PPIA,AL L1: MOV AL,0000001B

L2: OUT PPIC,AL

CALL TIMER

ROL AL,1

JNC L2

JMP L1
TIMER: MOV CX,0FFFFH
TIMER1: NOP
NOP
NOP
NOP
LOOP TIMER1
RET

Dot row half RED-half GREEN(4 ta red,4 ta green):

CODE SEGMENT

CODE ENDS

END

ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE;

PPIC_C EQU 1EH

PPIC EQU 1CH

PPIB EQU 1AH

PPIA EQU 18H

ORG 1000H

MOV AL,10000000B

OUT PPIC_C,AL

MOV AL,11110000B

OUT PPIB,AL

MOV AL,00001111B

OUT PPIA,AL

L1: MOV AL,0000001B

L2: OUT PPIC,AL

CALL TIMER

ROL AL,1

```
JNC L2
JMP L1
TIMER: MOV CX,0FFFFH
TIMER1: NOP
NOP
NOP
NOP
LOOP TIMER1
RET
CODE ENDS
END
Dot A:
     CODE SEGMENT
ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE
PPIC_C EQU 1EH; control register
PPIC EQU 1CH; c port
PPIB EQU 1AH
PPIA EQU 18H
ORG 1000H
MOV AL,10000000B
OUT PPIC_C,AL
MOV AL,11111111B
OUT PPIA,AL
L1: MOV SI,OFFSET FONT
MOV AH,11111110B
```

```
;
L2: MOV AL, BYTE PTR CS:[SI]
OUT PPIC,AL
MOV AL,AH
OUT PPIB,AL
CALL TIMER
INC SI
CLC
ROL AH,1
JC L2
JMP L1
TIMER: MOV CX,300
TIMER1: NOP
NOP
NOP
NOP
LOOP TIMER1
RET
FONT:
DB
    00000000B
DB
    11111100B
DB
    00010010B
    00010001B
DB
DB
    00010001B
DB
    00010010B
DB
    11111100B
    0000000B
DB
```

CLC

Dot H:

```
CODE SEGMENT
ASSUME CS:CODE,DS:CODE,ES:CODE,SS:CODE
PPIC_C EQU 1EH; control register
PPIC EQU 1CH; c port
PPIB EQU 1AH
PPIA EQU 18H
ORG 1000H
MOV AL,10000000B
OUT PPIC_C,AL
MOV AL,11111111B
OUT PPIA,AL
L1: MOV SI,OFFSET FONT
MOV AH,11111110B
L2: MOV AL, BYTE PTR CS:[SI]
OUT PPIC,AL
MOV AL,AH
OUT PPIB,AL
CALL TIMER
INC SI
```

```
JC L2
JMP L1
TIMER: MOV CX,300
TIMER1: NOP
NOP
NOP
NOP
LOOP TIMER1
RET
;
FONT:
    0000000B
DB
DB
    11111111B
DB
    00011000B
DB
    00011000B
DB
    00011000B
DB
    00011000B
DB
    11111111B
DB
   0000000B
CODE ENDS
END
```

ROL AH,1