

# Hack4Kids – Drone Race



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By SECURITYMADEIN.LU



# Drone Race?

Step 1 – Team up

Step 2 – Get an iPad and a drone

Step 3 – Measure the circuit

Step 4 – Code your race

Step 5 – Run the program

Etape 1 – Créé une équipe

Etape 2 – Prend un iPad et un drone

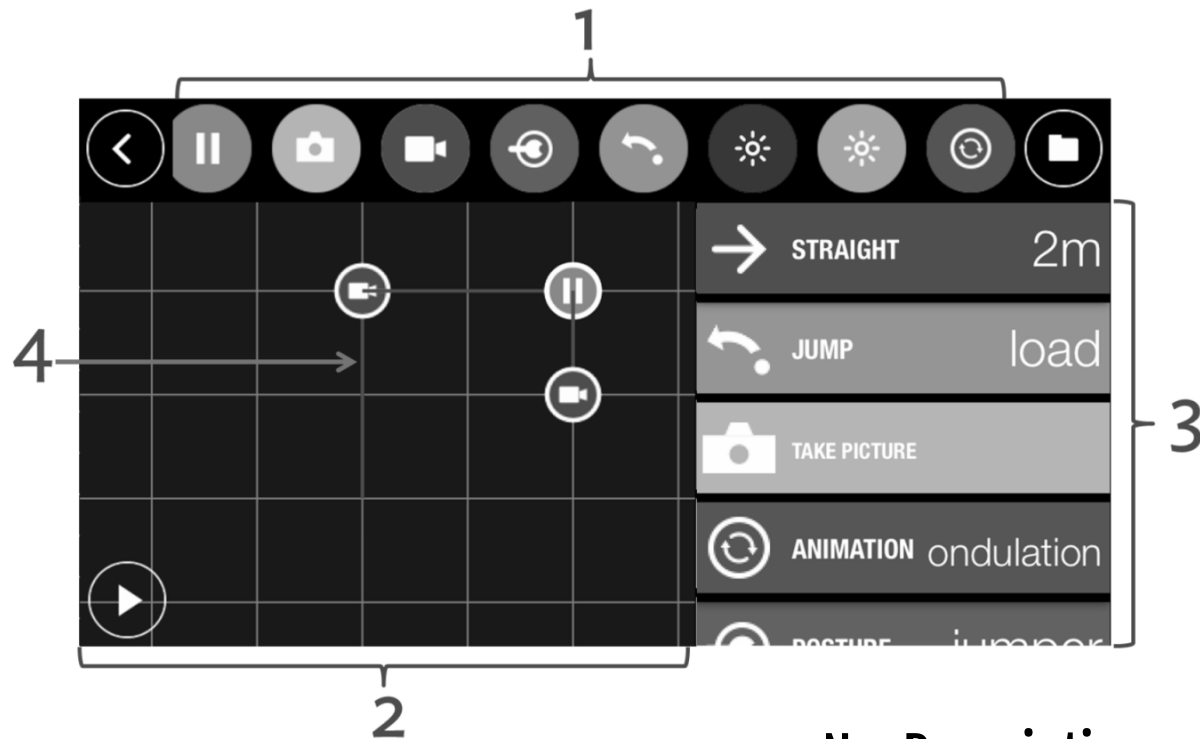
Etape 3 – Mesure le circuit

Etape 4 – Programme ta course

Etape 5 – Lance le programme



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## No. Description

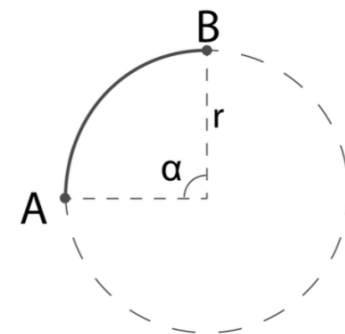
- 1 List of actions available for a road plan
- 2 Schematic representation of your road plan
- 3 Order of events within your road plan
- 4 Trajectory of the Drone



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→ Moving forward – Defining the distance to be covered

↻ Following a circular trajectory – When you define a circular trajectory, consider the circle within which it occurs. In the example opposite, to go from point A to point B: the setting Angle will need to take the value of  $\alpha$  (in degrees) the parameter Radius will need to take the value of 'r' (in meters)



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Modifying the speed – You may insert several speed-type actions with different values into the road plan.



Stopping – Define the stopping length



Taking a photo



Filming – To stop the recording insert another action Saving, and select Off



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- 👁️ **Changing the position**  
See the positions section for further information.
- ↩️ **Performing a jump, kicking an object or loading the spring**
- ☀️ **Modifying the color and luminosity of the eyes**  
Select the eyes and define the luminosity of the selected eye.  
To switch the eyes off, insert an action, defining the luminosity as 0%.

**Performing preprogrammed acrobatics**

Select the acrobatics type.



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