Theory of Random Number Generation

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Functions of RBG (Random Bit Generator)

Provides random numbers required for cryptographic systems An essential element (algorithm) for the operation of cryptographic systems and modules Required Properties: Unpredictability, Unbiasedness, Independence between bits

Ideally, the output should be akin to the results of "coin tossing." Applications of Random Bit Generator

Generation of Key and Initialization Vector (IV) used in symmetric-key cryptography (block/stream ciphers) Generation of various parameters in public-key cryptography: prime number generation, probabilistic public-key cryptography, etc. Generation of various parameters used in cryptographic protocols: nonce, salt, etc.

Chapter 2

Probability Theory

2.1 Introduction

> **Definition 2.1.**
>
> - An **experiment** is the process of observing a phenomenon that has variation in its outcomes.
>
> - The **sample space** S associated with an experiment is the collection of all possible distinct outcomes of the experiment.
>
> - An **event** A, B is the set of elementary outcomes possessing a designated feature. ($A, B \subseteq S$)

Remark 2.1.

- Union: $A \cup B$

- Complement: A^C

- Intersection: $A \cap B$ (simply, AB)

- A, B are mutually disjoint $\iff A \cap B = \emptyset$

2.2 Axioms of Probability

2.2.1 Kolmogorov's Axiom

Kolmogorov's Axiom

Axiom. The probability is a function $\Pr : 2^{\Omega} \to [0, 1] \subseteq \mathbb{R}$ satisfies

(A1) $\forall$event A, $0 \leq \Pr[A] \leq 1$.

(A2) $\Pr[\Omega] = 1$.

(A3) (Countable Additivity) $P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P[A_i]$, where $\{A_1, A_2, \dots\}$ is a countable set.

Remark 2.2. A probability is a function $\Pr : 2^{\Omega} \to [0, 1] \subseteq \mathbb{R}$.

Proposition 2.1. *Let $A, B \subseteq \Omega$.*

(1) $\Pr[A] = \Pr[AB^C] + \Pr[AB]$

(2) $\Pr[B] = \Pr[AB] + \Pr[A^C B]$

(3) $\Pr[A \cup B] = \Pr[A] + \Pr[B] - \Pr[AB]$

(4) $\Pr[A \cup B] = \Pr[AB^C] + \Pr[AB] + \Pr[A^C B]$

(5) $\Pr[A^C] = 1 - \Pr[A]$

(6) $A \subseteq B \implies \Pr[A] \leq \Pr[B]$

2.2.2   Conditional Probability and Independent

> **Conditional Probability**
>
> **Definition 2.2.** The **conditional probability** of A given B is denoted by $\Pr[A|B]$ and defined by the formula
>
> $$\Pr[A|B] = \frac{\Pr[AB]}{\Pr[B]} \quad \text{with} \quad \Pr[B] > 0.$$
>
> Equivalently, this formula can be written as **multiplication law of probability**:
>
> $$\Pr[AB] = \Pr[A|B]\Pr[B].$$

Example 2.1.

(1) Start with a *shuffled deck of cards* and distribute all 52 cards to 4 player, 13 cards to each. What is the probability that each player gets an Ace?

(2) Next, assume that you are a player and you get a single Ace. What is the probability now that each player gets an Ace?

Solution.

(1) If any ordering of cards is equally likely, then any position of the four Aces in the deck is also equally likely. There are

$$\binom{52}{4} = \frac{52!}{4!48!}$$

possibilities for the positions (slots) for the 4 aces. Out of these, the number of positions that give each player an Ace 13^4 pick the first slot among the cards that the first player gets, then the second slot among the second player's card, then the third and the fourth slot. Therefore, the answer is $\frac{13^4}{\binom{52}{4}} \approx 0.1055$.

(2) After you see that you have a single Ace, the probability goes up the previous answer need to be divided by the probability that you get a single Ace, which is

$$\frac{13 \cdot \binom{39}{3}}{\binom{52}{4}} \approx 0.4388.$$

Note that

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{P(A)}{P(B)}.$$

The answer then becomes $\frac{13^4}{13 \cdot \binom{39}{3}} \approx 0.2404$.

$\square$

> **Independence**
>
> **Definition 2.3.** Two events A and B are **independent** if
> $$\Pr[A|B] = \Pr[A]$$
> Equivalent conditions are
> $$\Pr[B|A] = \Pr[B] \quad \text{or} \quad \Pr[AB] = \Pr[A]\Pr[B]$$

Remark 2.3. $\Pr[A] = \Pr[A|B] = \dfrac{\Pr[AB]}{\Pr[B]} \implies \Pr[AB] = \Pr[A]\Pr[B].$

Example 2.2. Suppose we roll a dice once. Let the universal set is $U = \{1, 2, 3, 4, 5, 6\}$.

(1) (Independent but Not Disjoint) Let
$$A = \{1, 3, 5\} \quad \text{and} \quad B = \{3, 6\}.$$

Then $A \cap B = \{3\} \neq \emptyset$, that is, A and B are not disjoint. Note that

$$\Pr[A] = \frac{3}{6} = \frac{1}{2}, \quad \Pr[B] = \frac{2}{6} = \frac{1}{3},$$
$$\Pr[A \mid B] = \frac{\Pr[AB]}{\Pr[B]} = \frac{1/6}{1/3} = \frac{1}{2}, \quad \Pr[B \mid A] = \frac{\Pr[BA]}{\Pr[A]} = \frac{1/6}{1/2} = \frac{1}{3}.$$

Thus, $\Pr[A|B] = \Pr[A]$ and $\Pr[B|A] = \Pr[B]$. That is, A and B are mutually independent.

(2) (Not Independent but Disjoint) Let
$$A = \{1, 3, 5\} \quad \text{and} \quad B = \{2, 4, 6\}.$$

Then $A \cap B = \emptyset$, that is, A and B are disjoint. Note that

$$\Pr[A] = \frac{3}{6} = \frac{1}{2}, \quad \Pr[B] = \frac{3}{6} = \frac{1}{2},$$
$$\Pr[A \mid B] = \frac{\Pr[AB]}{\Pr[B]} = \frac{0}{1/2} = 0, \quad \Pr[B \mid A] = \frac{\Pr[BA]}{\Pr[A]} = \frac{0}{1/2} = 0.$$

Thus, $\Pr[A|B] \neq \Pr[A]$ and $\Pr[B|A] \neq \Pr[B]$. That is, A and B are not independent.

Rule of Total Probailtiy

Proposition 2.2. *Let events $A_1, \dots, A_n$ are satisfies*

(1) $\Pr[A_i] > 0$ *for* $i = 1, \dots, n$

(2) $A_i \cap A_j = \emptyset$ *for* $i \neq j$

(3) $\bigcup_{i=1}^{n} A_i = \Omega$

Then

$$
\begin{aligned}
\Pr[B] &= \sum_{i=1}^{n} \Pr[B|A_i] \Pr[A_i] \\
&= \Pr[B|A_1] \Pr[A_1] + \Pr[B|A_2] \Pr[A_2] + \cdots + \Pr[B|A_n] \Pr[A_n].
\end{aligned}
$$

Proof. $B = B \cap \Omega = B \cap \left(\bigcup_{i=1}^{n} A_i \right) = \bigcup_{i=1}^{n} (B \cap A_i)$. $\qquad\qquad\qquad\qquad\qquad\square$

2.2.3 Bayes' Theorem

Bayes' Theorem

Theorem 2.3.
$$
P(B|A) = \frac{P(A|B)P(B)}{P(A|B)P(B) + P(A|\bar{B})P(\bar{B})}
$$
The posterior probability of $\bar{B}$ is then $P(\bar{B}|A) = 1 - P(B|A)$.

Remark 2.4.

$$
\Pr[B \mid A] = \frac{\Pr[A|B] \cdot \Pr[B]}{\Pr[A]} \quad \Longleftrightarrow \quad \text{Posterior} = \frac{\text{Likelihood} \cdot \text{Prior}}{\text{Evidence}}.
$$

2.3 Random Variables

> **Random Variable**
>
> **Definition 2.4.** A **random variable** X is real-valued function on Ω the space of outcomes:
> $$X : \Omega \to \mathbb{R}.$$
> In other words, a random variable is a number whose value depends upon the outcome of a random experiment.

Remark 2.5. Sometimes, when convenient, we also allow X to have the value ∞ or, more rarely, $-\infty$.

2.3.1 Discrete Random Variables

> **Discrete Random Variable**
>
> **Definition 2.5.** A **discrete random variable** X has finitely or countably many values
> $$x_i \quad \text{for} \quad i = 1, 2, \cdots$$
> and
> $$p(x_i) = P(X = x_i)$$
> with $i = 1, 2, \cdots$, is called the **probability mass function of** X.

Remark 2.6. A probability mass function p has the following properties:

(1) $x = x_i, i \in I \implies p(x) = \Pr[X = x_i]$

(2) $0 \le p(x) \le 1, \sum_{x \in X} p(x) = 1$.

(3) $\Pr[a < X \le b] = \sum_{a < x \le b} p(x)$.

> **Discrete Probability Distribution**
>
> **Definition 2.6.** The **probability distribution** of a discrete of a random variable X is described as the function
> $$f(x_i) = P(X = x_i)$$
> which gives the probability for each value and satisfies:
>
> 1. $0 \le f(x_i) \le 1$ for each value x_i of X
>
> 2. $\displaystyle\sum_{i=1}^{k} f(x_i) = 1$

> ### Expectation(Mean) and Standard Deviation of a Probability Distribution
>
> **Definition 2.7.**
>
> - The **mean** of X or **population mean**
>
> $$E[X] = \mu$$
> $$= \sum(\text{Value} \times \text{Probability}) = \sum x_i f(x_i)$$
>
> Here the sum extends over all the distinct values x_i of X.
>
> - The **Variance and Standard Deviation of X** is given by
>
> $$\sigma^2 = \text{Var}[X] = \sum (x_i - \mu)^2 f(x_i)$$
> $$\sigma = \text{sd}[X] = +\sqrt{\text{Var}[X]}$$
>
> - **Alternative Formula for Hand calculation:**
>
> $$\sigma^2 = \sum x_i^2 f(x_i) - \mu^2$$

Example 2.3 (Calculating a Population Variance and Standard Deviation). Calculate the variance and the standard deviation of the distribution of X that appears in the left two columns of below table.

x	$f(x)$	$xf(x)$	$(x-\mu)$	$(x-\mu)^2$	$(x-\mu)^2 f(x)$	$x^2 f(x)$
0	.1	0	-2	4	.4	0
1	.2	.2	-1	1	.2	0.2
2	.4	.8	0	0	.0	1.6
3	.2	.6	1	1	.2	1.8
4	.1	.4	2	4	.4	1.6
Total	1.0	$2.0 = \mu$			$1.2 = \sigma^2$	$5.2 = \sum x^2 f(x)$

$$\text{Var}(X) = \sigma^2 = 1.2 \qquad\qquad \sigma^2 = 5.2 - (2.0)^2 = 1.2$$
$$\text{sd}(X) = \sigma = \sqrt{1.2} = 1.095 \qquad\qquad \sigma = \sqrt{1.2} = 1.095$$

2.3.2 Bernoulli

Note.

- The sample space $S = \{$ S, F $\}$.

- The probability of success $p = P(S)$, the probability of failure $q = P(F)$.

- $0 \leq p \leq 1$, $q = 1 - p$.

Binomial Distribution

Definition 2.8. The **binomial distribution** with n trails and success probability p is described by the function

$$f(x) = P[X = x] = \binom{n}{x} p^x (1 - p)^{n-x}$$

for the possible values $x = 0, 1, \cdots, n$.

Example 2.4 (An Example of the Binomial Distribution). The elementary outcomes of 4 samples, the associated probabilities, and the value of X are listed as follows.

FFFF	SFFF	SSFF	SSSF	SSSS
	FSFF	SFSF	SSFS	
	FFSF	SFFS	SFSS	
	FFFS	FSSF	FSSS	
		FSFS		
		FFSS		

Value of X	0	1	2	3	4
Probability of each outcome	q^4	pq^3	$p^2 q^2$	$p^3 q$	p^4
Number of outcomes	$1 = \binom{4}{0}$	$4 = \binom{4}{1}$	$6 = \binom{4}{2}$	$4 = \binom{4}{1}$	$1 = \binom{4}{4}$

Value x	0	1	2	3	4
Probability $f(x)$	$\binom{4}{0} p^0 q^4$	$\binom{4}{1} p^1 q^3$	$\binom{4}{2} p^2 q^2$	$\binom{4}{1} p^3 q^1$	$\binom{4}{4} p^4 q^0$

Mean and Standard Deviation of the Binomial Distribution

Definition 2.9.

$$X = X_1 + X_2 + \cdots + X_n \sim B(n, p)$$

- $E[X] = E[X_1] + \cdots + E[X_n] = np$

- $\text{Var}[X] = \text{Var}[X_1] + \cdots + \text{Var}[X_n] = npq$

The binomial distribution with n trials and success probability p has

$$\text{Mean} = np$$
$$\text{Variance} = npq = np(1 - p)$$
$$\text{sd} = \sqrt{npq}$$

Covariance and Correlation Coefficient of Two Random Variables

Definition 2.10. Let X, Y be a random variables. Then

1. The covariance of them:

$$Cov(X, Y) = E[(X - \mu_1)(Y - \mu_2)]$$

2. The correlation coefficient of them:

$$Corr(X, Y) = E\left[\left(\frac{X - \mu_1}{\sigma_1}\right)\left(\frac{Y - \mu_2}{\sigma_2}\right)\right] = \frac{Cov(X, Y)}{\text{sd}(X)\text{sd}(Y)}$$

Remark 2.7. Note that $-1 \leq Corr(X, Y) \leq 1$ and

$$\begin{aligned}
Cov(X, Y) &= E[(X - \mu_1)(Y - \mu_2)] \\
&= E[XY - \mu_2 X - \mu_1 Y + \mu_1 \mu_2] \\
&= E[XY] - \mu_2 E[X] - \mu_1 E[Y] + \mu_1 \mu_2 \\
&= E[XY] - \mu_1 \mu_2.
\end{aligned}$$

That is, $Cov(X, Y) = E[XY] - \mu_1 \mu_2$.

Proposition 2.4.

(1) $Cov(aX + b, cY + d) = ac \cdot Cov(X, Y)$

(2) $Corr(aX + b, cY + d) = \begin{cases} Corr(X, Y) & : ac > 0 \\ -Corr(X, Y) & : ac < 0 \end{cases}$

Proof. (1)

$$Cov(aX + b, cY + d) = E[(aX + b) - (a\mu_x + b) \cdot (cY + d - (c\mu_y + d))]$$
$$= E[a(X - \mu_x) \cdot c(Y - \mu_y)] = acE[(X - \mu_x)(Y - \mu_y)]$$
$$= ac \cdot Cov(X, Y).$$

(2) Note that $\sigma_{aX+b} = \sqrt{\text{Var}(aX + b)} = \sqrt{a^2\text{Var}(X)} = |a|\,\sigma_X$. Similarly $\sigma_{cY+d} = |c|\,\sigma_Y$.

$$Corr(aX + b, cY + d) = \frac{Cov(aX + b, cY + d)}{\sigma_{aX+b}\sigma_{cY+d}} = \frac{ac \cdot Cov(X, Y)}{|a|\,\sigma_X|c|\,\sigma_Y} = \frac{ac}{|ac|}Corr(X, Y).$$

Hence, $Corr(aX + b, cY + d) = \begin{cases} Corr(X, Y) & \text{if } ac > 0 \\ -Corr(X, Y) & \text{if } ac < 0 \end{cases}$

$\square$

Distribution of Sum of Two Probability Variables

Proposition 2.5.

(1) $Var(X + Y) = Var(X) + Var(Y) + 2Cov(X, Y)$

(2) $Var(X - Y) = Var(X) + Var(Y) - 2Cov(X, Y)$

Two Probability Variables are Independent

Proposition 2.6.

(1) $E[XY] = E[X] \cdot E[Y]$

(2) $Cov(X, Y) = 0, Corr(X, Y) = 0$

(3) $Var(X \pm Y) = Var(X) + Var(Y)$

Proof. (1)

$$E[XY] = \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} x_i y_j p(x_i, y_j)$$
$$= \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} x_i y_j p_1(x_i) p_2(y_j)$$
$$= \sum_{i=1}^{\infty} x_i p_1(x_i) \sum_{j=1}^{\infty} y_j p_2(y_j)$$
$$= E[X] \cdot E[Y].$$

(2) $Cov(X, Y) = E[XY] - E[X] \cdot E[Y] = 0.$

$\square$

2.3.3 Continuous Random Variables

Probability Density Function

Definition 2.11. The **probability density function** $f(x)$ describes the distribution of probability for a continuous random variable. It has the properties:

(1) The total area under the probability density curve is 1.

(2) $P[a \leq X \leq b]$ = area under the probability density curve between a and b.

(3) $f(x) \geq 0$ for all x.

Remark 2.8. With a continuous random variable, the probability that $X = x$ is **always** 0. It is only meaningful to speak about the probability that X lies in an interval.

Remark 2.9. $p(x)$ is called **probability density function** of continuous random variable X if $p(x)$ satisfies:

(i) $p(x) \geq 0, \displaystyle\int_{-\infty}^{\infty} p(x)\, dx = 1,$

(ii) $P(a \leq X \leq b) = \displaystyle\int_{a}^{b} p(x)\, dx.$

Note that

- For any constant c, $\displaystyle\int_{c}^{c} p(x)\, dx = 0.$

- $P(a \leq X \leq b) = P(a < X \leq b) = P(a \leq X < b) = P(a < X < b).$

Expectation of a Continuous Random Variable

Definition 2.12.

- Expectation(or Mean) of a Random Variable X

    - a Discrete Random variable: $E[X] = \sum_{i=1}^{\infty} x_i p(x_i)$
    - a Continuous Random variable: $E[X] = \int_{-\infty}^{\infty} x p(x)\, dx$

- Expectation and Median of a Continuous Random Variable X

    - Expectation($\mu = E[X]$): the balance point of the probability mass.
    - Median: the value of X that divides the area under the curve into halves.

2.3.4 Normal Random Variable

Normal Random Variable

Definition 2.13. A random variable is **Normal with parameter** $\mu \in \mathbb{R}$ **and** $\sigma^2 > 0$ or, in short, X **is** $N(\mu, \sigma^2)$, if its density is the function given below.

$$\text{Density}: f(x) = f_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{(x-\mu)^2}{2\sigma^2}\right],$$

where $x \in (-\infty, \infty)$.

Proposition 2.7.

(1) For $f(x) = \dfrac{1}{\sigma\sqrt{2\pi}} \exp\left[-\dfrac{(x-\mu)^2}{2\sigma^2}\right]$, $\displaystyle\int_{-\infty}^{\infty} f(x)\, dx = 1$.

(2) $EX = \mu$.

(3) $Var(X) = \sigma^2$.

2.3.5 The Normal Approximation to the Binomial

The Normal Approximation to the Binomial

Theorem 2.8. *When np and $np(1-p)$ are both large, say, greater than 15, the binomial distribution is well approximated by the normal distribution having mean $= np$ and sd $= \sqrt{np(1-p)}$. That is,*

$$Z = \frac{X - np}{\sqrt{np(1-p)}} \text{ is approximately } N(0,1).$$

Mean and Standard Deviation of $\overline{X}$

Definition 2.14. The distribution of the sample mean, based on a random sample of size n, has

$$E[\overline{X}] = \mu \qquad\qquad (= \text{Population mean})$$

$$Var[\overline{X}] = \frac{\sigma^2}{n} \qquad\qquad \left(= \frac{\text{Population variance}}{\text{Sample size}}\right)$$

$$sd[\overline{X}] = \frac{\sigma}{\sqrt{n}} \qquad\qquad \left(= \frac{\text{Population standard deviation}}{\sqrt{\text{Sample size}}}\right)$$

2.4   Central Limit Theorem

2.4.1   CLT

> **Central Limit Theorem**
>
> **Theorem 2.9.** *Assume that $X, X_1, X_2, \ldots$ are independent, identically distributed random variables, with finite $\mu = EX$ and $\sigma^2 = Var[X]$. Then,*
>
> $$\lim_{n \to \infty} \Pr\left[\frac{\sum_{i=1}^{n} X_i - \mu n}{\sigma \sqrt{n}} \le x\right] = \Pr\left[Z \le x\right],$$
>
> *where Z is standard Normal.*

2.4.2   Laws of Large Numbers

> **Weak Law of Large Numbers**
>
> **Theorem 2.10.** *Let $X_1, X_2, \ldots$ be a sequence of independent and identically distributed random variables, each having finite mean $E[X_i] = \mu$ and variance σ^2. Then, for any $\varepsilon > 0$,*
>
> $$\lim_{n \to \infty} \Pr\left[\left\|\frac{\sum_{i=1}^{n} X_i}{n} - \mu\right\| \ge \varepsilon\right] = 0.$$

> **Strong Law of Large Numbers**
>
> **Theorem 2.11.** *Let $X_1, X_2, \ldots$ be i.i.d. random variables with a finite first moment, $\mathbb{E}[X_i] = \mu$. Then*
>
> $$\frac{1}{n} \sum_{i=1}^{n} X_i \to \mu \quad \text{almost surely as} \quad n \to \infty.$$

2.5 Problem: RBG → RNG

Exercise 2.1 (Uniform Distribution). Consider an algorithm

Step 1:   Drive the RBG independently 4 times to generate a 4-bit integer value r.

Step 2:   **If** $r < 10$ **then**

        return r

    else

      go to Step 1

Prove that

$$\Pr[\text{ouput} = n] = \frac{1}{10}$$

for $n = 0, 1, 2, \ldots, 9$.

Solution. Let

- $n \leq 2^k = m$ with $n = 10, k = 4$ and $m = 16$

- Output digit $= r \in [0, 9]$.

Then

output	1st iteration	2nd iteration	$\cdots$	step iteration
0	$\Pr[0] = \frac{1}{m}$	$\Pr[0] = \frac{1}{m} \cdot \frac{m-n}{m}$	$\cdots$	$\Pr[0] = \frac{1}{m} \cdot \left(\frac{m-n}{m}\right)^{\text{step}-1}$
1	$\Pr[1] = \frac{1}{m}$	$\Pr[1] = \frac{1}{m} \cdot \frac{m-n}{m}$	$\cdots$	$\Pr[1] = \frac{1}{m} \cdot \left(\frac{m-n}{m}\right)^{\text{step}-1}$
2	$\Pr[2] = \frac{1}{m}$	$\Pr[2] = \frac{1}{m} \cdot \frac{m-n}{m}$	$\cdots$	$\Pr[2] = \frac{1}{m} \cdot \left(\frac{m-n}{m}\right)^{\text{step}-1}$
$\vdots$	$\vdots$	$\vdots$	$\cdots$	$\vdots$
$n-1$	$\Pr[n-1] = \frac{1}{m}$	$\Pr[n-1] = \frac{1}{m} \cdot \frac{m-n}{m}$	$\cdots$	$\Pr[n-1] = \frac{1}{m} \cdot \left(\frac{m-n}{m}\right)^{\text{step}-1}$

Thus,

$$
\begin{aligned}
\Pr[\text{output} = r] &= \frac{1}{m} + \frac{1}{m} \cdot \frac{m-n}{m} + \cdots + \frac{1}{m} \cdot \left(\frac{m-n}{m}\right)^s + \cdots \\
&= \frac{1}{m} \sum_{s=0}^{\infty} \left(\frac{m-n}{m}\right)^s = \frac{1}{m} \sum_{s=0}^{\infty} \left(1 - \frac{n}{m}\right)^s \\
&= \frac{1}{m} \cdot \frac{1}{1 - \left(1 - \frac{n}{m}\right)} = \frac{1}{m} \cdot \frac{m}{n} \\
&= \frac{1}{n}.
\end{aligned}
$$

$\square$

Chapter 3

Markov Chains

3.1 Introduction

> **Markov Chain**
>
> **Definition 3.1.** Let
> $$\langle X_n \rangle_{n \geq 0} := \{ X_n : n = 0, 1, 2, \cdots \}$$
> be a stochastic process over a countable set S. Let $\Pr[X]$ is the probability of the random variable X. Then $\langle X_n \rangle_{n \geq 0}$ satisfies **Markov property** if
> $$\Pr[X_{n+1} = x_{n+1} \mid X_0 = x_0, \ldots, X_n = x_n] = \Pr[X_{n+1} = x_{n+1} \mid X_n = x_n]$$
> for all $n \geq 0$ and all $x_0, \ldots, x_{n+1} \in S$. Then $\langle X_n \rangle_{n \geq 0}$ is a **Markov chain**.

Remark 3.1.

(1) The conditional probability of X_{i+1} is dependent only upon X_i, and upon no earlier values of $\langle X_n \rangle$

(2) the state of $\langle X_n \rangle$ in the future is unaffected by its history.

(3) The set S is called the **state space** of the Markov chain.

(4) The conditional probabilities $\Pr[X_{n+1} = y \mid X_n = x]$ are called the **transition probabilities**.

(5) Markov chain having **stationary transition probabilities**, i.e., $\Pr(X_{n+1} = y \mid X_n = x)$, is independent of n.

Example 3.1 (*The general two-state Markov chain*). There are two states 0 and 1 with transitions

- $0 \to 1$ with probability p

- $0 \to 0$ with probability $1 - p$

- $1 \to 0$ with probability q

- $1 \to 1$ with probability $1 - q$.

Thus we have

$$\Pr\left[X_{n+1} = 1 \mid X_n = 0\right] = p,$$
$$\Pr\left[X_{n+1} = 0 \mid X_n = 1\right] = q,$$

and $\Pr[X_0 = 0] = \pi_0(0)$. Since there are only two states, 0 and 1, it follows immediately that

$$\Pr\left[X_{n+1} = 0 \mid X_n = 0\right] = 1 - p,$$
$$\Pr\left[X_{n+1} = 1 \mid X_n = 1\right] = 1 - q,$$

and $\pi_0(1) = \Pr[X_0 = 1] = 1 - \pi_0(0)$. The transition matrix has two parameters $p, q \in [0, 1]$:

$$\begin{bmatrix} T_{00} & T_{01} \\ T_{10} & T_{11} \end{bmatrix} = \begin{bmatrix} 1 - p & p \\ q & 1 - q \end{bmatrix}.$$

Note that

- $\Pr[A] = \Pr[B \cap A] + \Pr[B^C \cap A]$

- $\Pr[A \cap B] = \Pr[A] \cdot \Pr[B \mid A]$

Then we observe that

$$
\begin{aligned}
\Pr\left[X_{n+1} = 0\right] &= \Pr\left[X_n = 0 \wedge X_{n+1} = 0\right] + \Pr\left[X_n = 1 \wedge X_{n+1} = 0\right] \\
&= \Pr[X_n = 0]\Pr[X_{n+1} = 0 \mid X_n = 0] \\
&\quad + \Pr[X_n = 1]\Pr[X_{n+1} = 0 \mid X_n = 1] \\
&= \Pr[X_n = 0] \cdot (1 - p) + \Pr[X_n = 1] \cdot q \\
&= (1 - p) \cdot \Pr[X_n = 0] + q \cdot (1 - \Pr[X_n = 0]) \\
&= (1 - p - q) \cdot \Pr[X_n = 0] + q.
\end{aligned}
$$

Now

$$
\begin{aligned}
\Pr[X_0 = 0] &= \pi_0(0), \\
\Pr[X_1 = 0] &= (1 - p - q)\pi_0(0) + q, \\
\Pr[X_2 = 0] &= (1 - p - q)\Pr[X_1 = 0] + q \\
&= (1 - p - q)^2\pi_0(0) + q\left(1 + (1 - p - q)\right), \\
\Pr[X_3 = 0] &= (1 - p - q)\Pr[X_2 = 0] + q \\
&= (1 - p - q)^3\pi_0(0) + q\left(1 + (1 - p - q) + (1 - p - q)^2\right), \\
&\vdots
\end{aligned}
$$

$$\Pr[X_n = 0] = (1 - p - q)^n\pi_0(0) + q\sum_{j=0}^{n-1}(1 - p - q)^j.$$

In the trivial case $p = q = 0$, it is clear that for all n

$$\Pr[X_n = 0] = \pi_0(0) \quad \text{and} \quad \Pr[X_n = 1] = \pi_0(1).$$

Suppose that $p + q > 0$. By the formula $\displaystyle\sum_{j=0}^{n-1} r^j = \frac{1 - r^n}{1 - r}$ for the sum of a finite geometric progression,

$$\sum_{j=0}^{n-1}(1 - p - q)^j = \frac{1 - (1 - p - q)^n}{p + q}.$$

Thus,

$$\Pr[X_n = 0] = \frac{q}{p + q} + (1 - p - q)^n \cdot \left(\pi_0(0) - \frac{q}{p + q}\right),$$

$$\Pr[X_n = 1] = \frac{p}{p + q} + (1 - p - q)^n \cdot \left(\pi_0(1) - \frac{p}{p + q}\right).$$

Suppose that $p, q \notin \{0, 1\}$. Then

$$0 < p + q < 2 \implies |1 - p - q| \le 1.$$

Then

$$\lim_{n \to \infty} \Pr[X_n = 0] = \frac{q}{p + q} \quad \text{and} \quad \lim_{n \to \infty} \Pr[X_n = 1] = \frac{p}{p + q}.$$

Suppose we want to choose $\pi_0(0)$ and $\pi_0(1)$ so that $\Pr[X_n = 0]$ and $\Pr[X_n = 1]$ are independent of n. To do this, we should choose $\pi_0(0) = q/(p + q)$ and $\pi_0(1) = p/(p + q)$. Thus if $\langle X_n \rangle_{n \ge 0}$ start with the initial distribution

$$\pi_0 = \Pr[X_n = 0] = \frac{q}{p + q} \quad \text{and} \quad \pi_0(1) = \frac{p}{p + q},$$

then for all n

$$\Pr[X_n = 0] = \frac{q}{p + q} \quad \text{and} \quad \Pr[X_n = 1] = \frac{p}{p + q}.$$

Example 3.2. Let $n = 2$ and $x_0, x_1, x_2 \in \{0, 1\}$. Then

$$\Pr[X_0 = x_0, X_1 = x_1, X_2 = x_2]$$
$$= \Pr[X_0 = x_0, X_1 = x_1] \cdot \Pr[X_2 = x_2 \mid X_0 = x_0, X_1 = x_1]$$
$$= \Pr[X_0 = x_0] \Pr[X_1 = x_1 \mid X_0 = x_0] \cdot \Pr[X_2 = x_2 \mid X_0 = x_0, X_1 = x_1].$$

If the Markov property is satisfied, then

$$\Pr[X_2 = x_2 \mid X_0 = x_0, X_1 = x_1] = \Pr[X_2 = 2 \mid X_1 = x_1],$$

which is determined by p and q. In this case

$$\Pr[X_0 = x_0, X_1 = x_1, X_2 = x_2] = \Pr[X_0 = x_0] \Pr[X_1 = x_1 \mid X_0 = x_0] \Pr[X_2 = x_2 \mid X_1 = x_1].$$

Recall that the transition matrix with $p, q \in [0, 1]$:

$$\begin{bmatrix} T_{00} & T_{01} \\ T_{10} & T_{11} \end{bmatrix} = \begin{bmatrix} 1 - p & p \\ q & 1 - q \end{bmatrix}.$$

Then

x_0	x_1	x_2	$\Pr[X_0 = x_0, X_1 = x_1, X_2 = x_2]$
0	0	0	$\pi_0(0)(1 - p)^2$
0	0	1	$\pi_0(0)(1 - p)p$
0	1	0	$\pi_0(0)pq$
0	1	1	$\pi_0(0)p(1 - q)$
1	0	0	$(1 - \pi_0(0))q(1 - p)$
1	0	1	$(1 - \pi_0(0))qp$
1	1	0	$(1 - \pi_0(0))(1 - q)q$
1	1	1	$(1 - \pi_0(0))(1 - q)^2$

Chapter 4

Examples of Markov chains

Chapter 5

Statistical Inferences

Chapter 6

Statistical Tests for Randomness

Statistical tests for random number generators (RNGs) are crucial in assessing the quality of the RNGs, which purport to produce random sequences. While it is not possible to mathematically prove that a sequence is random, these tests can reveal certain weaknesses. The tests work by evaluating sample outputs from the RNG against attributes expected from truly random sequences. The outcomes of these tests are probabilistic and not definite. If a sequence fails any of the tests, it may be rejected as non-random, or subjected to further testing. Passing all the tests allows the RNG to be accepted as random, or more precisely, not rejected, as it only provides probabilistic evidence of randomness.

6.1 Statistical tests for RNGs

Statistical tests for RNGs measure the quality of a bit generator's randomness. These tests are essential in identifying weaknesses in the generators by applying various statistical methods to the output sequences. For instance, a sequence that passes all the tests is not definitively random but is likely to exhibit characteristics of randomness, whereas a sequence that fails any test is potentially non-random and may require additional testing or rejection.

6.1.1 Golomb's randomness postulates

Golomb's randomness postulates are historical attempts to define necessary conditions for periodic pseudorandom sequences to appear random. They are not sufficient conditions for randomness but were among the first efforts to systematically address the randomness in sequences. These postulates serve as a fundamental basis for more complex tests and are critical in understanding the nature of pseudorandom sequences and their applications.

Definition 6.1. Let

$$s = s_0, s_1, s_2, \ldots$$

be an infnite sequence. The subsequence consisting of the first n terms of s is denoted by

$$s^n = s_0, s_1, \cdots, s_{n-1}.$$

Remark 6.1. s is the bit sequence if $s_i \in \{0, 1\}$.

N-Periodic

Definition 6.2. The sequence $s = s_0, s_1, s_2, \ldots$ is said to be N-**periodic** if

$$s_i = s_{i+N}$$

for all $i \geq 0$.

Remark 6.2. If s is a N-periodic sequence, then the **cycle** of s is the subsequence s^N.

Run - Gap / Block

Definition 6.3. Let s be a sequence.

- A **run** of s is a subsequence of s consisting of consecutive 0's or 1's.

- A run of 0's is called a **gap**.

- A run of 1's is called a **block**.

> **Autocorrelation Function**
>
> **Definition 6.4.** Let s be a N-periodic sequence. The **autocorrelation function** of s is the integer-value function $C(t) : \{s_i\} \rightarrow \mathbb{Z}$ defined as
>
> $$C(t) = \frac{1}{N} \sum_{i=0}^{N-1} (2s_i - 1) \cdot (2s_{i+t} - 1)$$
>
> for $0 \leq t \leq N - 1$.

Remark 6.3.

Remark 6.4. The autocorrelation function $C(t)$ measure the amount of similarity between the sequence s and a shift of s by t positions. If s is a random N-periodic sequence, then $\left| N \cdot C(t) \right|$ can be expected to be quite small for all vlaue of $t \in (0, N)$.

> **Golomb's randomness postulates**
>
> **Definition 6.5.** Let s be a N-periodic sequence. **Golomb's randomness postulates** are as follows:
>
> **R1** In the cycle s^N of s, the number of 1's differs from the number of 0's by at most 1.
>
> **R2** In the cycle s^N, at least half the runs have length 1, at least one-fourth have length 2, at least one-eighth have length 3, and so on, as long as the number of runs so indicated exceeds 1. Moreover, for each of these lengths, there are (almost) equally many gaps and blocks.
>
> **R3** The autocorrelation function $C(t)$ is two-valued. That is for some integer K,
>
> $$N \cdot C(t) = \sum_{i=0}^{N-1} (2s_i - 1) \cdot (2s_{i+t} - 1) = \begin{cases} N, & : t = 0, \\ K, & : 1 \leq t \leq N - 1. \end{cases}$$

> **Pseudo-Noise Sequence (pn-sequence)**
>
> **Definition 6.6.** A binary sequence which satisfies Golomb's randomness postulates is called a **pseudo-noise sequence** (**pn-sequence**).

Remark 6.5. Pseudo-noise sequences arise in practice as output sequences of **maximum-length linear**

The significance of Golomb's randomness postulates lies in their ability to provide a framework for the evaluation of periodic sequences. A periodic sequence with period N is assessed based on the following criteria:

Chapter 7

NIST SP 800-22

This document provides a detailed summary of the NIST Special Publication 800-22r1a. The publication is central to understanding the statistical test suite designed for evaluating random and pseudorandom number generators (RNGs) used in cryptographic applications.

7.1 Testing Strategy and Result Interpretation

The publication outlines a comprehensive strategy for statistically analyzing RNGs, which is crucial for ensuring the reliability and security of cryptographic systems.

### 7.1.1 Strategies for Statistical Analysis of an RNG

The strategy involves five key stages:

1. **Selection of a Generator:** Choosing a suitable hardware or software-based RNG.

2. **Binary Sequence Generation:** Generating a set of binary sequences using the selected RNG.

3. **Execution of the Statistical Test Suite:** Applying the NIST Statistical Test Suite to the generated sequences.

4. **Examination of P-values:** Analyzing the P-values obtained from the test suite to evaluate the quality of the sequences.

5. **Assessment: Pass/Fail Assignment:** Determining whether each sequence passes or fails the statistical tests based on P-value thresholds.

Remark 7.1.

- $H0$ (null hypothesis) : The sequence being tested is random.

- H_a (alternative hypothesis) : The sequence is not random.

- Level of significance : $\alpha = 0.01$ (α is chosen in the range $[0.001, 0.01]$.)

    - P-value $< \alpha = 0.01 \implies$ Reject H_0 (not random)

– P-value $\geq \alpha = 0.01 \implies$ Accept H_0 (random)
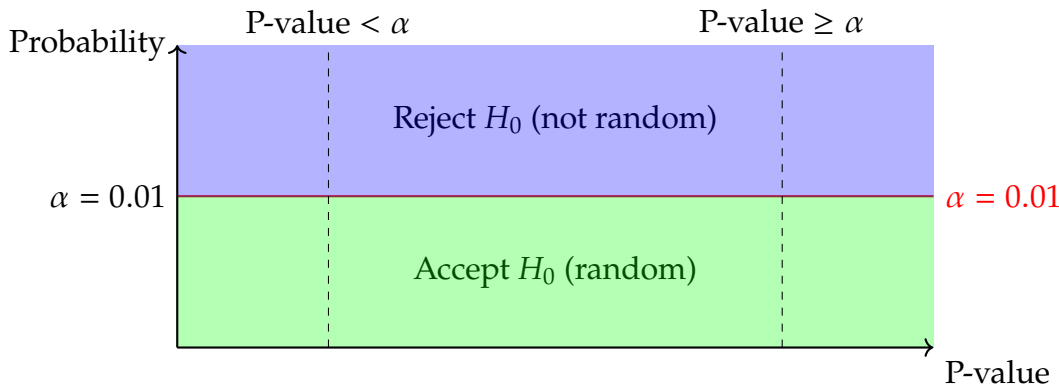
7.2 The Interpretation of Empirical Results

7.2.1 Proportion of Sequences Passing a Test

7.2.2 Uniform Distribution of P-values

7.2.3 General Recommendations and Guidelines

Key recommendations include:

- Addressing programming errors in statistical tests.

- Dealing with underdeveloped statistical tests.

- Correcting flaws in RNG implementation.

- Ensuring accuracy in data processing for tests.

- Using quality mathematical routines for computing P-values.

- Making appropriate choices for test input parameters.

7.2.4 Application of Multiple Tests

The publication highlights the importance of using multiple tests to ensure a wide-ranging assessment of RNGs. A study conducted by NIST revealed minimal redundancy among tests, confirming the suite's ability to thoroughly evaluate different aspects of randomness.

7.2.5 Conclusion

NIST SP 800-22r1a provides an essential framework for the evaluation of RNGs in cryptographic applications. Its structured approach, comprising detailed testing strategies and guidelines, is crucial for ensuring the integrity and security of cryptographic systems.

7.3 Useful Functions

- **Standard Normal (Cumulative Distribution) Function**

$$\Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{z} e^{-u^2/2} \, du.$$

- **Complementary Error Function**

$$\text{erfc}(z) = \frac{2}{\sqrt{\pi}} \int_{z}^{\infty} e^{-u^2} \, du.$$

(1) Starting Point: The given definition of $\Phi(z)$.

$$\Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{z} e^{-\frac{u^2}{2}} \, du.$$

(2) Change of Variable: To relate $\Phi(z)$ to $\text{erfc}(z)$, we make a change of variable in the integral. Let $v = u/\sqrt{2}$, which implies $u = \sqrt{2}v$ and $du = \sqrt{2}dv$.

$$\Phi(z) = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\frac{z}{\sqrt{2}}} e^{-v^2} \, dv.$$

(3) Expressing $\Phi(z)$ in terms of $\text{erfc}(z)$: he error function is defined as $\text{erfc}(z) = \frac{2}{\sqrt{\pi}} \int_{z}^{\infty} e^{-u^2} \, du.$. Hence, the complementary error function is $\text{erfc}(z) = 1 - \text{erf}(z)$.

$$\text{erfc}(z) = 1 - \frac{2}{\sqrt{\pi}} \int_{0}^{z} e^{-u^2} \, du$$

(4) Connecting $\Phi(z)$ and $\text{erfc}(z)$: We observe that $\Phi(z)$ integrates from $-\infty$ to a positive value, while $\text{erfc}(z)$ integrates from a positive value to ∞. They are complementary in nature. Therefore, we can write:

$$\Phi\left(\frac{z}{\sqrt{2}}\right) = \frac{1}{2}\text{erfc}\left(-\frac{z}{\sqrt{2}}\right)$$

(5) Final Expression for $\text{erfc}(z)$: Rearranging the last equation for $\text{erfc}(z)$, we get:

$$\text{erfc}(z) = 2\left(1 - \Phi\left(\frac{z}{\sqrt{2}}\right)\right)$$

(6) Converting Back to Integral Form: Finally, substituting the integral form of $\Phi(z)$ into the equation for $\text{erfc}(z)$, we arrive at the desired expression:

$$\text{erfc}(z) = \frac{2}{\sqrt{\pi}} \int_{z}^{\infty} e^{-u^2} \, du$$

7.4   Frequency (Monobits) Test

- The most basic test is that of the null hypothesis: in a sequence of independent identically distributed Bernoulli random variables the probability of ones is $1/2$.

- By the classic **De Moivre-Laplace theorem** (*Central Limit Theorem*), for a sufficiently large number of trials, the distribution of the binomial sum, normalized by $\sqrt{n}$, is closely approximated by a standard normal distribution.

- This test makes use of that approximation to assess the closeness of the fraction of 1's to $1/2$.

- All subsequent tests are conditioned on having passed this first basic test.

-
$$X = 2\varepsilon - 1, \quad S_n = X_1 + \cdots + X_n = 2(\varepsilon_1 + \cdots + \varepsilon_n) - n.$$

$$\mathbb{E}[S_n] = 0, \quad \mathrm{Var}(S_n) = n.$$

$$\lim_{n \to \infty} \Pr\left[\frac{S_n}{\sqrt{n}} \le z\right] = \Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{z} e^{-u^2/2}\, du, \quad \Pr\left[\frac{|S_n|}{\sqrt{n}} \le z\right] = 2\Phi(z) - 1.$$

- According to the test based on the statistic $s = |S_n|/\sqrt{n}$, evaluate the observed value $|s(\mathrm{obs})| = |X_1 + \ldots + X_n|/\sqrt{n}$, and then calculate the corresponding **P-value**, which is

$$2\left[1 - \Phi\left(|s(\mathrm{obs})|\right)\right] = \mathrm{erfc}\left(\frac{|s(\mathrm{obs})|}{\sqrt{2}}\right).$$

Here, erfc is the (complementary) error function

$$\mathrm{erfc}(z) = \frac{2}{\sqrt{\pi}} \int_{z}^{\infty} e^{-u^2}\, du.$$

Frequency Test 수행 절차

1. Conversion to ±1: The zeros and ones of the input sequence (e) are converted to values of -1 and $+1$ and are added together to produce $S_n = X_1 + X_2 + \ldots + X_n$, where $X_i = 2e_i - 1$.

   For example, if $e = 1011010101$, then $n = 10$ and $S_n = (-1) + 1 + (-1) + 1 + (-1) + 1 + (-1) + 1 + (-1) + 1 = 2$.

2. Compute the test statistic $s_{\mathrm{obs}} = \frac{|S_n|}{\sqrt{n}}$

   For the example in this section, $s_{\mathrm{obs}} = \frac{|2|}{\sqrt{10}} \approx 0.632455532$.

3. Compute P-value $= \text{erfc}\left(\frac{s_{\text{obs}}}{\sqrt{2}}\right)$, where erfc is the complementary error function as defined in Section 5.5.3.

   For the example in this section, P-value $= \text{erfc}\left(\frac{0.632455532}{\sqrt{2}}\right) \approx 0.527089$.

Example of Frequency Test

(input) $e = 11001010000011110110101010001000010101010001100001000101010011000100110001000110$

(input) $n = 100$

(processing) $S_{100} = -16$

(processing) $s_{\text{obs}} = 1.6$

(output) P-value $= 0.109599$

(conclusion) **Since P-value ≥ 0.01, accept the sequence as random.**

Frequency Test within a Block

The test seeks to detect localized deviations from the ideal 50% frequency of 1's by decomposing the test sequence into a number of overlapping subsequences and applying a chi-square test for a homogeneous match of empirical frequencies to the ideal $\frac{1}{2}$.

- Small P-values indicate large deviations from the equal proportion of ones and zeros in at least one of the substrings.

- The string of 0's and 1's (or equivalent -1's and 1's) is partitioned into a number of disjoint substrings.

- For each substring, the proportion of ones is computed.

- A chi-square statistic compares these substring proportions to the ideal $\frac{1}{2}$.

- The statistic is referred to a chi-squared distribution with the degrees of freedom equal to the number of substrings.

The parameters of this test are M and N, so that $n = MN$, i.e., the original string is partitioned into N substrings, each of length M.

- For each of these substrings, the probability of ones is estimated by the observed relative frequency of 1's, π_i, for $i = 1, \ldots, N$.

The reported P-value:

(where `igamc` is the incomplete gamma function)

The reported P-value is computed as:

$$\frac{\int_{\frac{\chi^2_{(\text{obs})}}{2}}^{\infty} e^{-u} u^{(N/2)-1} du}{\Gamma(N/2) 2^{N/2}} = \frac{\int_{\frac{\chi^2_{(\text{obs})}}{2}}^{\infty} e^{-u} u^{N/2-1} du}{\Gamma(N/2)} = \text{igamc}\left(\frac{N}{2}, \frac{\chi^2(\text{obs})}{2}\right).$$

Gamma Function

$$\Gamma(z) = \int_0^\infty t^{z-1} e^{-t} dt$$

Incomplete Gamma Function

$$P(a, x) = \frac{\gamma(a, x)}{\Gamma(a)} = \frac{1}{\Gamma(a)} \int_0^x e^{-t} t^{a-1} dt$$

where $P(a, 0) = 0$ and $P(a, \infty) = 1$.

Incomplete Gamma Function

$$Q(a, x) = 1 - P(a, x) = \frac{\Gamma(a, x)}{\Gamma(a)} = \frac{1}{\Gamma(a)} \int_x^\infty e^{-t} t^{a-1} dt$$

where $Q(a, 0) = 1$ and $Q(a, \infty) = 0$.

Frequency Test within a Block 수행 절차

1. Partition the input sequence into $N = \lceil \frac{n}{M} \rceil$ non-overlapping blocks. Discard any unused bits.

   For example, if $n = 10$, $M = 3$ and $e = 0110011010$, 3 blocks ($N = 3$) would be created, consisting of 011, 001 and 101. The final 0 would be discarded.

2. Determine the proportion π_i of ones in each M-bit block using the equation

$$\pi_i = \frac{\sum_{j=1}^M e_{(i-1)M+j}}{M}$$

   for $1 \leq i \leq N$.

   For the example in this section, $\pi_1 = \frac{2}{3}$, $\pi_2 = \frac{1}{3}$, and $\pi_3 = \frac{2}{3}$.

3. Compute the χ^2 statistic:

$$\chi^2(\text{obs}) = 4M \sum_{i=1}^N \left(\pi_i - \frac{1}{2} \right)^2.$$

   For the example in this section,

$$\chi^2(\text{obs}) = 4 \times 3 \left(\left(\frac{2}{3} - \frac{1}{2} \right)^2 + \left(\frac{1}{3} - \frac{1}{2} \right)^2 + \left(\frac{2}{3} - \frac{1}{2} \right)^2 \right) = 1.$$

Compute P-value

Compute $P\text{-value} = \texttt{igamc}\left(\frac{N}{2}, \frac{\chi^2(\text{obs})}{2}\right)$, where $\texttt{igamc}$ is the incomplete gamma function for $Q(a, x)$ as defined in Section 5.5.3.

Note: When comparing this section against the technical description in Section 3.2, note that $Q(a, x) = 1 - P(a, x)$.

For the example in this section, $P\text{-value} = \texttt{igamc}\left(\frac{3}{2}, \frac{7.2}{2}\right) = 0.801252$.

Example:

(input) $e = 11001010000011110110101010001000010101010001100001000101010011000100110001000110$

(input) $n = 100$

(input) $M = 10$

(processing) $N = 10$

(processing) $\chi^2 = 7.2$

(output) $P\text{-value} = 0.706438$

(conclusion) Since $P\text{-value} > 0.01$, accept the sequence as random.

Runs Test

This variant of a classic **nonparametric test** looks at "runs" defined as substrings of consecutive 1's and consecutive 0's, and considers whether the oscillation among such homogeneous substrings is too fast or too slow.

The specific test used here is based on the distribution of **the total number of runs**, V_n.

- For the fixed proportion $\pi = \sum_{i=1}^{n} e_i/n$; π is an estimated parameter(Not assumed from H_0),

$$\lim_{n \to \infty} P\left(\frac{V_n - 2n\pi(1 - \pi)}{\sqrt{2n\pi(1 - \pi)}} \leq z\right) = \Phi(z).$$

To evaluate V_n, define for $k = 1, \ldots, n - 1$, $r(k) = 0$ if $e_k = e_{k+1}$ and $r(k) = 1$ if $e_k \neq e_{k+1}$.

$$P\text{-value} = \text{erfc}\left(\frac{|V_n(\text{obs}) - 2n\pi(1 - \pi)|}{\sqrt{2n\pi(1 - \pi)}}\right).$$

Large values of $V_n(\text{obs})$ indicate oscillation in the string of e's which is too fast; small values indicate oscillation which is too slow.

Test Statistic and Reference Distribution

$V_n\text{obs}$: The total number of runs (i.e., the total number of zero runs + the total number of one-runs) across all n bits. The reference distribution for the test statistic is a χ^2 distribution.

Test Description

Note: The Runs test carries out a Frequency test as a prerequisite.

1. Compute the pre-test proportion π of ones in the input sequence: $\pi = \frac{\sum e_j}{n}$.

   For example, if $e = 1001101011$, then $n = 10$ and $\pi = \frac{6}{10} = \frac{3}{5}$.

2. Determine if the prerequisite Frequency test is passed: If it can be shown that $|\frac{\pi - 1/2}{\sqrt{n/4}}| < t$, then the Runs test need not be performed (i.e., the test should not have been run because of a failure to pass test 1, the Frequency (Monobit) test). If the test is not applicable, then the P-value is set to 0.0000. Note that for this test, $\frac{n}{4}$ has been pre-defined in the test code.

   For the example in this section, since $t = \frac{\pi - 1/2}{\sqrt{n/4}} = 0.63246$, then $|t - 1/2| = |3/5 - 1/2| = 0.1 < t$.

   Since the observed value π is within the selected bounds, the runs test is applicable.

3. Compute the test statistic $V_{n,\text{obs}}$:

$$V_{n,\text{obs}} = \sum_{k=1}^{n-1} r(k+1), \text{ where } r(k) = 0 \text{ if } e_k = e_{k+1}, \text{ and } r(k) = 1 \text{ otherwise.}$$

   Since $e = 001101011$, then

$$V_{10,\text{obs}} = (1 + 0 + 1 + 0 + 1 + 1 + 1 + 0 + 1) = 7.$$

4. Compute P-value $= \text{erfc}\left(\frac{|V_{n,\text{obs}} - 2n\pi(1-\pi)|}{2\sqrt{2n\pi(1-\pi)}}\right)$.

   For the example, P-value $= \text{erfc}\left(\frac{2 \cdot 10 \cdot \frac{3}{5} \cdot (1 - \frac{3}{5})}{2 \cdot \sqrt{2 \cdot 10 \cdot \frac{3}{5} \cdot (1 - \frac{3}{5})}}\right) \approx 0.147232$.

Input Size Recommendation

It is recommended that each sequence to be tested consist of a minimum of 100 bits (i.e., $n \geq 100$).

Example

(input) $e = 1100101000001111011010101000100001010101000110000100010101001100010011000100011001\text{0}$

(input) $n = 100$

(input) $\tau = 0.02$

(processing) $\pi = 0.42$

(processing) $V_{n,\text{obs}} = 52$

(output) P-value $= 0.500798$

(conclusion) Since P-value ≥ 0.01, accept the sequence as random.

7.5 Binary Matrix Rank Test

- The focus of the test is the rank of disjoint sub-matrices of the entire sequence.

- The purpose of this test is to check for linear dependence among fixed length sub-strings of the original sequence.

  - Construct matrices of successive zeroes and ones from the sequence, and check for linear dependence among the rows or columns of the constructed matrices.
  - The deviation of the rank - or rank deficiency - of the matrices from a theoretically expected value gives the statistic of interest.

- The result states that the rank R of the $M \times Q$ random binary matrix takes values $r = 0, 1, 2, \ldots, m$, where $m = \min(M, Q)$, with probabilities

$$P_r = 2^{r(Q+M-r)-MQ} \prod_{i=0}^{r-1} \frac{(1 - 2^{i-Q})(1 - 2^{i-M})}{1 - 2^{i-r}},$$

  - The probability values are fixed in the test suite code for $M = Q = 32$.
  - The number M is then a parameter of this test, so that ideally $n = M^2 N$, where N is the new "sample size".

- In practice, values for M and N are chosen so that the discarded part of the string, $n - M^2 N$, is fairly small.

Discrete Fourier Transform (Spectral) Test

- The test described here is based on the **discrete Fourier transform**.

- It is a member of a class of procedures known as **spectral methods**.

- The Fourier test detects [text redacted] that would indicate a deviation from the assumption of randomness.

Test Purpose

- The focus of this test is the peak heights in the Discrete Fourier Transform of the sequence.

- The purpose of this test is to detect periodic features (i.e., *repetitive patterns* that are near each other) in the tested sequence that would indicate a deviation from the assumption of randomness.

- The intention is to detect whether the number of peaks exceeding the 95% threshold is significantly different than 5%.

Random Excursions Test

- The focus of this test is the number of cycles having exactly *K* visits in a cumulative sum random walk.

  - The cumulative sum random walk is derived from partial sums after the (0,1) sequence is transferred to the appropriate (-1,+1) sequence.

  - A cycle of a random walk consists of a sequence of steps of unit length taken at random that begin at and return to the origin.

- The purpose of this test is to determine if the number of visits to a particular state within a cycle deviates from what one would expect for a random sequence.

  - This test is actually a series of eight tests (and conclusions), one test and conclusion for each of the states: -4, -3, -2, -1 and +1, +2, +3, +4.

- This test is based on considering successive sums of the binary bits (plus or minus simple ones) as a one dimensional random walk.

  - The test detects deviations from the distribution of the number of visits of the random walk to a certain "state," i.e., any integer value.

7.6 Testing Strategy and Result Interpretation

The publication details a five-stage strategy for the statistical analysis of RNGs, encompassing selection, generation, execution, examination, and assessment.

7.6.1 Strategies for Statistical Analysis of an RNG

- Selection of a Generator

- Binary Sequence Generation

- Execution of the Statistical Test Suite

- Examination of P-values

- Assessment: Pass/Fail Assignment

7.6.2 Interpretation of Empirical Results

Empirical results are interpreted through three scenarios: no deviation from randomness, clear deviation, or inconclusive results. The process involves examining sequence pass rates and P-value distributions.

7.6.3 General Recommendations and Guidelines

The document provides recommendations on addressing potential issues in statistical testing, such as programming errors, underdeveloped tests, RNG implementation flaws, data processing errors, poor mathematical routines, and incorrect parameter choices.

7.7 Application of Multiple Tests

A study on the interdependence of multiple tests revealed minimal redundancy, ensuring a comprehensive assessment of nonrandomness.

7.8 Conclusion

NIST SP 800-22r1a presents a comprehensive approach to evaluating RNGs for cryptographic applications, providing a structured testing strategy, methods for interpreting results, and guidelines to address common issues in statistical testing.

7.8.1   Golomb's randomness postulates

Solomon W. Golomb's randomness postulates are a cornerstone in the field of cryptography and sequence design, primarily due to their foundational role in the analysis and interpretation of sequences as random. These postulates provide a mathematical framework for evaluating the randomness of binary sequences. Specifically, they set forth criteria that a sequence must meet to be considered random.
   The postulates are as follows:

1. The number of ones and zeros in the sequence should be approximately equal, which is necessary for the sequence to have no bias.

2. The distance between consecutive ones should follow a geometric distribution. For binary sequences that are infinitely long, this implies that the probability of a 'gap' of length n between ones is $(1/2)^{n+1}$, representing the lack of structure in the sequence.

3. The sequence should be balanced, which means that for any binary substring, the number of occurrences of this substring and its complement should be approximately the same. This property is also referred to as the run property, where a 'run' is a substring of consecutive identical digits.

   Golomb's postulates are integral in the design and analysis of pseudo-random number generators (PRNGs), as they serve as a benchmark for the sequence's randomness. A sequence that fulfills these postulates is considered to be a good candidate for cryptographic applications because it exhibits the unpredictability necessary for securing communications.
   Application in Cryptography: In cryptography, the randomness of key material is paramount. Golomb's postulates are used to ensure that the generated keys do not exhibit patterns or regularities that could be exploited by adversaries. By applying these postulates to evaluate the randomness of binary sequences, cryptographers can quantify the security level of cryptographic systems.
   Mathematical Implications: The postulates form the basis of several statistical tests, such as the runs test and the autocorrelation test. These tests are applied to binary sequences to check for the presence of patterns and correlations that would indicate non-randomness. The theoretical underpinnings of Golomb's postulates also contribute to the field of combinatorics and information theory, where they have implications for the construction of codes and error correction.
   In conclusion, Golomb's randomness postulates are not only historically significant but also remain highly relevant in the modern analysis of cryptographic systems. They

7.9   Introduction

Statistical tests for randomness play a pivotal role in validating the quality and integrity of random number generators (RNGs). These tests serve as a benchmark against which RNGs are measured to ensure that their output sequences exhibit properties characteristic of true randomness. Despite the intrinsic limitations in proving randomness, these tests can effectively identify non-randomness in sequences, which is vital for applications in cryptography, simulations, and various stochastic modeling scenarios.

7.10 Statistical tests for RNGs

The purpose of statistical tests for RNGs is to analyze sequences for unpredictability, lack of patterns, and uniform distribution—traits expected from ideal random sequences. These tests range from simple frequency analysis to complex tests for serial correlation, and no single test can validate randomness conclusively. Hence, a battery of tests is typically employed, where failure of any test suggests non-randomness, prompting further scrutiny or rejection of the RNG.

7.10.1 Golomb's randomness postulates

Golomb's randomness postulates, rooted in the theory of shift register sequences, lay foundational criteria for assessing the randomness of periodic sequences. These postulates dictate:

1. **The Frequency Postulate**: The number of zeros and ones in a sequence should be approximately the same, reflecting the balance of a sequence.

2. **The Run Postulate**: A sequence should contain runs of various lengths distributed according to expected probabilities. For instance, in a binary sequence, half of the runs should be of length one, one-fourth should be of length two, and so forth.

3. **The Autocorrelation Postulate**: The autocorrelation function of the sequence should rapidly drop to zero as the shift increases, which implies that each bit should be independent of others at a certain distance.

These postulates form the basis for more sophisticated tests, and while they are not sufficient to declare a sequence as random, they are necessary conditions. In particular, they address the uniformity and independence of a sequence, which are critical aspects in cryptographic applications.

Implementing these postulates in practical statistical tests has advanced the analysis of pseudorandom number generators (PRNGs), providing a methodology to assess their suitability for various applications. The evaluation of PRNGs against these postulates often involves chi-squared tests, spectral tests, and other statistical methodologies to detect non-random behavior in generated sequences.

Chapter 8

Evaluation of Entropy

8.1 Introduction to Entropy

We introduce the concept of **entropy** is a measure of the uncertainty of a random variable.

> **Entropy**
>
> **Definition 8.1.** The **entropy** $H(X)$ of a discrete random variable X is defined by
>
> $$H : \mathbb{R}^{\Omega} \to \mathbb{R}_{\geq 0} : H(X) = -\sum_{x \in X} p(x) \log_2 p(x).$$
>
> We also write $H(p)$ for the above quantity. The log is to the base 2 and entropy is expressed in bits.

Example 8.1. For example, the entropy of a fair coin toss is 1 bit: note that

$$X : \Omega \to \mathbb{R} : \begin{cases} X(\text{"heads"}) = 1 \\ X(\text{"tails"}) = 0 \end{cases}, \quad \begin{cases} \Pr[X = 1] = p(1) = \frac{1}{2} \\ \Pr[X = 0] = p(0) = \frac{1}{2}. \end{cases}$$

Since

$$p(0) \log_2 p(0) = \frac{1}{2} \log_2 \frac{1}{2} = -\frac{1}{2} \quad \text{and} \quad p(1) \log_2 p(1) = \frac{1}{2} \log_2 \frac{1}{2} = -\frac{1}{2},$$

we have

$$H(X) = -\sum_{x \in \{0,1\}} p(x) \log_2 p(x) = 1.$$

We will use the convention that

$$p(x) = 0 \implies 0 \log 0 := 0,$$

which is easily justified by continuity since

$$\lim_{x \to 0} x \log x = 0.$$

Adding terms of zero probability does not change the entropy.

Remark 8.1. The expected value of a function $g(x)$ of a random variable $X = x$ is given by
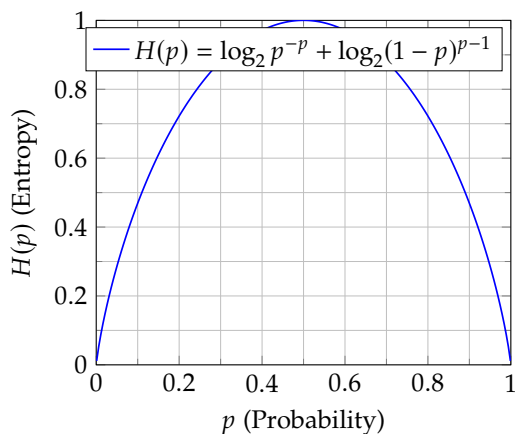
$$\mathbb{E}[g(x)] = \sum_{x \in X} p(x)g(x).$$

Let $g(x) := \log_2 \frac{1}{p(x)}$ then

$$\mathbb{E}\left[\log_2 \frac{1}{p(x)}\right] = \sum_{x \in X} p(x) \log_2 \frac{1}{p(x)} = -\sum_{x \in X} p(x) \log_2 p(x).$$

Therefore, entropy can be seen as the expected value of the information content of each outcome of a random variable. It quantifies the average amount of information (or uncertainty) inherent in the random variable's possible outcomes.

Example 8.2 (Entropy of a Binary Random Variable).

Let

$$X = \begin{cases} 1 & \text{with probability } p, \\ 0 & \text{with probability } 1 - p. \end{cases}$$

Then

$$H(X) = -\left(\log_2 p^p + \log_2(1 - p)^{1-p}\right) \overset{\text{def}}{=} H(p).$$

Example 8.3. Let

$$X = \begin{cases} a & \text{with probability } \frac{1}{2}, \\ b & \text{with probability } \frac{1}{4}, \\ c & \text{with probability } \frac{1}{8}, \\ d & \text{with probability } \frac{1}{8}. \end{cases}$$

The entropy of X is

$$H(X) = -\left(\frac{1}{2} \cdot (-1) + \frac{1}{4} \cdot (-2) + \frac{1}{8} \cdot (-3) + \frac{1}{8} \cdot (-3)\right) = \frac{4 + 4 + 3 + 3}{8} = \frac{14}{8} = \frac{7}{4} = 1.75 \text{ bits.}$$

8.2   Entropy in Cryptography

We want to look at what happens **as more and more plaintexts are encrypted using the same key**, and how likely a cryptanalyst will be able to carry out a successful **ciphertext-only attack**, given sufficient time.

The basic tool in studying this question is the idea of **entropy**, a concept from information theory introduced by Shannon in 1948. **Entropy** can be thought of as a mathematical measure of *information* or *uncertainty*, and is computed as a function of a probability distribution.

Suppose we have a discrete random variable X which takes values from a finite set according to a specified probability distribution. What is the *information* gained by the outcome of an experiment which takes place according to this probability distribution? Equivalently, if the experiment has not (yet) taken place, what is the *uncertainty* about the outcome? This quantity is called the **entropy of** X and is denoted by $H(X)$.

If $H(X)$ is high, it means there's a lot of uncertainty about the outcome of the experiment (or a lot of information to be gained by performing it). If $H(X)$ is low, it means most outcomes are quite predictable, with little new information to be gained.

In summary, the entropy $H(X)$ of a random variable X quantifies the expected amount of information gained—or equivalently, the uncertainty—about the outcome of an experiment modeled by X before the experiment is performed.

Example 8.4 (**The Length of a Bit-string in Probability Encoding**). Suppose we have a random variable X such that

$$\Pr[X = x_1] = \frac{1}{2}, \quad \Pr[X = x_2] = \frac{1}{4}, \quad \Pr[X = x_3] = \frac{1}{4}.$$

Suppose we encode the three possible outcomes as follows:

  (i) x_1 is encoded as `0`,

 (ii) x_2 is encoded as `10`, and

(iii) x_3 is encoded as `11`.

Then the **(weighted) average number of bits in this encoding of** X is

$$\frac{1}{2} \times \text{``1-bit (0)''} + \frac{1}{4} \times \text{``2-bit (10)''} + \frac{1}{4} \times \text{``2-bit (11)''} = \frac{1}{2} \cdot 1 + \frac{1}{4} \cdot 2 + \frac{1}{4} \cdot 2 = \frac{3}{2}.$$

Note (**Motivation of the Entropy**). In binary encoding, an n-bit string represents 2^n different states or outcomes. If each of these 2^n outcomes is equally likely, the probability of any specific outcome is $\frac{1}{2^n}$. For an event with a probability p, we find the number of bits required n by setting $\frac{1}{2^n} = p$.

$$\frac{1}{2^n} = p \implies \log_2 2^{-n} = \log_2 p$$
$$\implies n = -\log_2 p.$$

The length of a bit-string required to encode an event with probability p is approximately $-\log_2(p)$. This principle is central in information theory, reflecting that less probable events, which carry more information, require longer bit strings for encoding.

Given an arbitrary probability distribution taking on the values $p_1, p_2, \ldots, p_r$ for a random variable X, we consider the weighted average of $-\log_2(p_i)$:

$$H(X) = \sum_{i=1}^{r} p_i \cdot (-\log_2(p_i))$$

We could imagine that an outcome occurring with probability p might be encoded by a bit-string of length approximately $-\log_2(p)$. Given an arbitrary probability distribution, taking on the values $p_1, p_2, \ldots, p_r$ for a random variable X, we take the **weighted average of the quantities** $-\log_2(p_i)$ to be our measure of information.

Entropy of Finite Random Variable

Definition 8.2. Suppose X is a discrete random variable that takes on values from a finite set X, say, $|X| = n$. The **entropy** of the random variable X is defined to be the quantity

$$H(X) = -\sum_{i=1}^{n} p_i \log_2(p_i)$$

Expectation illustration placeholder

Definition

REMARK Observe that $\log_2(y)$ is undefined if $y = 0$. Hence, entropy is sometimes defined to be the relevant sum over all the non-zero probabilities. However, since $\lim_{y \to 0} y \log_2(y) = 0$, there is no real difficulty with allowing $Pr[X] = 0$ for some x's. Also, we note that the choice of two as the base of the logarithms is arbitrary: another base would only change the value of the entropy by a constant factor.

Note that if $|X| = n$ and $Pr[x] = 1/n$ for all $x \in X$, then $H(X) = \log n$. Also, it is easy to see that $H(X) \geq 0$ for any random variable X, and $H(X) = 0$ if and only if $Pr[x] = 1$ for some $x \in X$ and $Pr[x] = 0$ for all $x \neq x_0$.

Let us look at the entropy of the various components of a cryptosystem. We can think of the key as being a random variable K that takes on values in K, and hence we can compute the entropy $H(K)$. Similarly, we can compute entropies $H(P)$ and $H(C)$ of random variables associated with the plaintext and ciphertext, respectively.

Example Let $P = \{a, b\}$ with $Pr[a] = 1/4, Pr[b] = 3/4$. Let $K = \{K_1, K_2, K_3\}$ with $Pr[K_i] = 1/2, Pr[K_{i+1}] = Pr[K_{i+2}] = 1/4$. Let $c = \{1, 2, 3, 4\}$, and suppose the encryption functions are defined to be $e_{K_1}(a) = 1, e_{K_1}(b) = 2; e_{K_2}(a) = 2, e_{K_2}(b) = 3$; and $e_{K_3}(a) = 3, e_{K_3}(b) = 4$. This cryptosystem can be represented by the following *encryption matrix*:

Definition 8.3.

---

	a	b
K_1	1	2
K_2	2	3
K_3	3	4

First, we have to define what we mean by the entropy (per letter) of a natural language L, which we denote H_L.

- H_L should be a measure of the average information per letter in a "meaningful" string of plaintext.

- Note that a random string of alphabetic characters would have entropy (per letter) equal to $\log(26)$.

- As a "first-order" approximation to H_L, we could take $H(P)$.

- In the case where L is the English language, we get H_L by using the probability distribution of the 26 English letters.

Letter	Probability	Letter	Probability	Letter	Probability
A	.082	N	.067	T	.091
B	.015	O	.075	U	.028
C	.028	P	.019	V	.010
D	.043	Q	.001	W	.023
E	.127	R	.060	X	.001
F	.022	S	.063	Y	.020
G	.020			Z	.001

Rényi entropy

The Rényi entropy of order α, where $\alpha \geq 0$ and $\alpha \neq 1$, is defined as

$$H_\alpha(X) = \frac{1}{1 - \alpha} \log \left(\sum_{i=1}^{n} p_i^\alpha \right).$$

Here, X is a discrete random variable with possible outcomes $1, 2, \ldots, n$ and corresponding probabilities $p_i = Pr[X = i]$ for $i = 1, \ldots, n$.

Hartley or max-entropy:
$$H_0(X) = \log n = \log |X|.$$

Collision entropy:

$$H_2(X) = -\log \sum_{i=1}^{n} p_i^2 = -\log Pr[X = Y], \quad X, Y : \text{i.i.d.}$$

Min-Entropy

Entropy is defined relative to one's knowledge of an experiment's output prior to observation, and reflects the **uncertainty** associated with predicting its value – the larger the amount of entropy, the greater the uncertainty in predicting the value of an observation.

There are many possible measures for entropy; NIST uses a very *conservative measure* known as **min-entropy**, which measures the effectiveness of the strategy of guessing the most likely output of the entropy source.

The min-entropy of an independent discrete random variable X that takes values from the set $\{x_1, x_2, \ldots, x_k\}$ with probability $Pr[X = x_i] = p_i$ for $i = 1, \ldots, k$ is defined as

$$H_\infty(X) = \min(-\log_2 p_i) = -\log_2 \max p_i.$$

If X has min-entropy H, then the probability of observing any particular value for X is no greater than 2^{-H}. The maximum possible value for the min-entropy of a random variable with k distinct values is $\log_2 k$, which is attained when the random variable has a uniform probability distribution, i.e., $p_1 = p_2 = \ldots = p_k = 1/k$.

Probabilistic Analysis for the Relationship Between Min-Entropy and Guessing Attack

Min-entropy is closely related to the *optimum guessing attack cost*.

$$\mathbb{E}[S_\delta] = W_k(P)$$

Abstract. Recently NIST has published the second draft document of recommendation for the entropy sources used for random bit generation. In this document NIST has provided a practical and detailed description about the fact that the min-entropy is closely related to the optimum guessing attack cost. However the argument lacks the mathematical rigor. In this paper we provide an elaborate probabilistic analysis for the relationship between the min-entropy and cost of optimum guessing attack. Moreover we also provide some simulation results in order to investigate the practicality of optimum guessing attack.

Keywords: Entropy source · Min-Entropy · Optimum guessing attack

Appendix D–Min-Entropy and Optimum Guessing Attack Cost

Suppose that an adversary wants to determine at least one of several secret values, where each secret value is independently chosen from a set of M possibilities, with probability distribution $P = \{p_1, p_2, \ldots, p_M\}$. Assume that these probabilities are sorted so that $p_1 \geq p_2 \geq \ldots \geq p_M$. Consider a guessing strategy: and assume successfully guessing as many secret values as possible... The adversary's goal would be to minimize the expected number of guesses per successful recovery. Such a strategy would consist of guessing a maximum of k possibilities for a given secret value, moving on to a new secret value when either a guess is correct, or k incorrect guesses for the current value have been made. In general, the optimum value of k can be anywhere in the range $1 \leq k \leq M$, depending on the probability distribution P. Note that when $k = M$, the Mth guess is considered valid (though trivial) guess. Regardless of the value of k chosen, it is clear that the guesser selected for a given secret value should be the k most likely possible values, in decreasing order of probability.

The expected number of guesses $W_k(P)$ is given by:

$$W_k(P) = p_1 + 2p_2 + \ldots + (k-1)p_{k-1} + k\left(1 - \sum_{i=1}^{k-1} p_i\right)$$

Entropy Source Model

Entropy Source Validation

- Data Collection

- Determining the track: IID track vs. non–IID track

- Initial Entropy Estimate

- Restart Tests

- Entropy Estimation for Entropy Sources Using a Conditioning Component

- Additional Noise Sources

Health Tests

- Repetition Count Test

- Adaptive Proportion Test

Testing the IID Assumption

Permutation Testing

Input: $S = (s_1, \ldots, s_n)$
   Output: Decision on the IID assumption

1 For each test i

    a Assign the counters $C_{0,i}$ and $C_{1,i}$ to zero.

    b Calculate the test statistic T_i on S.

2 For j = 1 to 10,000

    1 Permute S using the Fisher-Yates shuffle algorithm.

    2 For each test i

        a Calculate the test statistic T on the permuted data.

        b If $(T > T_i)$, increment $C_{0,i}$. If $(T = T_i)$, increment $C_{1,i}$.

3 If $(C_{0,i} + C_{1,i})/10,000 > 0.9995$ for any i, reject the IID assumption; else, assume that the noise source outputs are IID.

Testing the IID Assumption

Permutation Testing

    1. Excursion Test Statistic

    2. Number of Directional Runs

    3. Length of Directional Runs

    4. Number of Increases and Decreases

    5. Number of Runs Based on the Median

    6. Length of Runs Based on Median

    7. Average Collision Test Statistic

    8. Maximum Collision Test Statistic

    9. Periodicity Test Statistic

   10. Covariance Test Statistic

   11. Compression Test Statistic

Additional Chi-square Statistical Tests

    1. Testing Independence for Non-Binary Data

    2. Testing Goodness-of-fit for Non-Binary Data

    3. Testing Independence for Binary Data

    4. Testing Goodness-of-fit for Binary Data

    5. Length of the Longest Repeated Substring Test

Estimating Min-Entropy

IID Track: Entropy Estimation for IID Data

- most common value estimate

Non-IID Track: Entropy Estimation for Non-IID Data

- The Most Common Value Estimate

- The Collision Estimate

- The Markov Estimate

- The Compression Estimate

- The t-Tuple Estimate

- The Longest Repeated Substring (LRS) Estimate

- The Multi Most Common in Window Prediction Estimate

- The Lag Prediction Estimate

- The MultiMMC Prediction Estimate

- The LZ78Y Prediction Estimate

The Most Common Value Estimate

This method first finds the proportion $\hat{p}$ of the most common value in the input dataset, and then constructs a confidence interval for this proportion. The upper bound of the confidence interval is used to estimate the min-entropy per sample of the source.

Given the input $S = (s_1, \ldots, s_L)$, where $s_i \in \{x_1, \ldots, x_k\}$,

1. Find the proportion of the most common value $\hat{p}$ in the dataset, i.e.,

$$\hat{p} = \max \frac{\#\{s_i\}}{L}.$$

2. Calculate an upper bound on the probability of the most common value p_u as

$$p_u = \min\left(1, \hat{p} + z\sqrt{\frac{\hat{p}(1-\hat{p})}{L-1}}\right),$$

where z corresponds to the $Z_{(1-\alpha/2)}$ value.

3. The estimated min-entropy is $-\log_2(p_u)$.

Example: If the dataset is $S = (0, 1, 1, 2, 0, 1, 2, 2, 0, 1, 0, 1, 0, 2, 2, 1, 0, 2, 1)$, with $L = 20$, the most common value is 1, with $\hat{p} = 0.4$. $p_u = 0.4 + 2.576 \cdot \sqrt{0.012} = 0.6895$. The min-entropy estimate is $-\log_2(0.6895) \approx 0.5363$.

The Markov Estimate

This entropy estimation method is only applied to binary inputs.

Given the input $S = (s_1, \ldots, s_L)$, where $s_i \in \{0, 1\}$,

1. Estimate the initial probabilities for each output value, P_0 and $P_1 = 1 - P_0$.

2. Let T be the 2×2 transition matrix of the form

$$\begin{bmatrix} P_{00} & P_{01} \\ P_{10} & P_{11} \end{bmatrix}$$

where the probabilities are calculated as

$$P_{00} = \frac{\#\{00 \text{ in } S\}}{\#\{0 \text{ in } S\} - 1}, \quad P_{01} = \frac{\#\{01 \text{ in } S\}}{\#\{0 \text{ in } S\}}$$

$$P_{10} = \frac{\#\{10 \text{ in } S\}}{\#\{1 \text{ in } S\}}, \quad P_{11} = \frac{\#\{11 \text{ in } S\}}{\#\{1 \text{ in } S\} - 1}$$

Find the probability of the most likely sequence of outputs of length 128, as calculated below.

Sequence	Probability
00...0	$P_0 \times P_0^{127}$
0101...01	$P_0^{64} \times P_1^{64}$
011...1	$P_0 \times P_1 \times P_1^{126}$
100...0	$P_1 \times P_0 \times P_0^{126}$
1010...10	$P_1^{64} \times P_0^{64}$
11...1	$P_1 \times P_1^{127}$

Let $p_{\max}$ be the maximum of the probabilities in the table given above. The min-entropy estimate is the negative logarithm of the probability of the most likely sequence of outputs, $p_{\max}$:

$$\text{min-entropy} = \min(-\log_2(p_{\max})/128, 1)$$

Example

For the purpose of this example[2], suppose that $L = 40$ and $S = (1, 0, 0, \ldots, 0, 1)$, with $L = 20$, the most common value is 1, with $p = 0.4$. The transition matrix is calculated as

$$\begin{bmatrix} 0 & 1 \\ P_{00} & P_{01} \\ P_{10} & P_{11} \end{bmatrix}$$

where the probabilities are calculated as

$$P_{00} = \frac{\#00 \text{ in } S}{\#0 \text{ in } S - 1}, \quad P_{01} = \frac{\#01 \text{ in } S}{\#0 \text{ in } S}$$

$$P_{10} = \frac{\#10 \text{ in } S}{\#1 \text{ in } S}, \quad P_{11} = \frac{\#11 \text{ in } S}{\#1 \text{ in } S - 1}$$

The probabilities of the possible sequences are

$$
\begin{aligned}
00...0 \quad & 3.9837 \times 10^{-3} \\
0101...01 \quad & 4.4381 \times 10^{-4} \\[6pt]
011...1 \quad & 1.4202 \times 10^{-4} \\
10...0 \quad & 6.4631 \times 10^{-3} \\
1010...10 \quad & 4.6288 \times 10^{-9} \\
11...1 \quad & 1.0121 \times 10^{-4}
\end{aligned}
$$

The resulting entropy estimate is

$$\text{min-entropy} = \min(-\log_2(4.6288 \times 10^{-9})/128, 1) = \min(0.761, 1) = 0.761.$$

Definition 8.4.

Definition 8.5.

Domain   Range

$$\boxed{\text{Probability distributions of } X} \xrightarrow{\;H(X)\;} \boxed{\text{Entropy in bits}}$$