

# **Notes on Complex Analysis and Riemann Surface Theory toward Algebraic Geometry**

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# Chapter 1

## De Rham Complex, Short Exact Sequence, and Mayer-Vietoris

### 1.1 Grad / Curl / Div

On  $M = \mathbb{R}^3$  (with its standard Euclidean metric and orientation), the exterior derivative packages the familiar vector calculus operators:

Degree	Differential Form	Exterior derivative $d$	Vector calculus
0-forms	$f \in \Omega^0(\mathbb{R}^3)$ (scalar field)	$d : \Omega^0(\mathbb{R}^3) \rightarrow \Omega^1(\mathbb{R}^3),$ $df = f_x dx + f_y dy + f_z dz$	Gradient $df \leftrightarrow \nabla f$
1-forms	$\alpha \in \Omega^1(\mathbb{R}^3),$ $\alpha = P dx + Q dy + R dz$	$d : \Omega^1(\mathbb{R}^3) \rightarrow \Omega^2(\mathbb{R}^3),$ $d\alpha = (R_y - Q_z) dy \wedge dz + (P_z - R_x) dz \wedge dx + (Q_x - P_y) dx \wedge dy$	Curl (via Hodge star) $d\alpha \leftrightarrow \nabla \times (P, Q, R)$
2-forms	$\beta \in \Omega^2(\mathbb{R}^3),$ $\beta = A dy \wedge dz + B dz \wedge dx + C dx \wedge dy$	$d : \Omega^2(\mathbb{R}^3) \rightarrow \Omega^3(\mathbb{R}^3),$ $d\beta = (A_x + B_y + C_z) dx \wedge dy \wedge dz$	Divergence $d\beta \leftrightarrow \nabla \cdot (A, B, C)$

Table 1.1: On  $\mathbb{R}^3$  (with Euclidean metric and orientation), the exterior derivative packages grad/curl/div (using the Hodge star to identify 2-forms with vector fields).

- **Functions**  $f \in \Omega^0(\mathbb{R}^3)$  correspond to scalar fields. The map

$$d : \Omega^0(\mathbb{R}^3) \rightarrow \Omega^1(\mathbb{R}^3)$$

corresponds to the **gradient**: if  $f = f(x, y, z)$  then

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz.$$

Viewing 1-forms as vector fields via the Euclidean metric,  $df$  corresponds to  $\nabla f$ .

- **1-forms**  $\alpha \in \Omega^1(\mathbb{R}^3)$  correspond (after identifying 1-forms with vector fields) to vector fields  $\mathbf{F} = (P, Q, R)$  via

$$\alpha = P dx + Q dy + R dz.$$

Then

$$d : \Omega^1(\mathbb{R}^3) \rightarrow \Omega^2(\mathbb{R}^3)$$

corresponds to **curl**. Indeed,

$$d\alpha = \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) dy \wedge dz + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) dz \wedge dx + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx \wedge dy,$$

and (using the Hodge star to identify 2-forms with vector fields) this corresponds to  $\nabla \times \mathbf{F}$ .

- **2-forms**  $\beta \in \Omega^2(\mathbb{R}^3)$  correspond (via the Hodge star) to vector fields  $\mathbf{G} = (A, B, C)$  by writing

$$\beta = A dy \wedge dz + B dz \wedge dx + C dx \wedge dy.$$

Then

$$d : \Omega^2(\mathbb{R}^3) \rightarrow \Omega^3(\mathbb{R}^3)$$

corresponds to **divergence**:

$$d\beta = \left( \frac{\partial A}{\partial x} + \frac{\partial B}{\partial y} + \frac{\partial C}{\partial z} \right) dx \wedge dy \wedge dz,$$

which corresponds to  $\nabla \cdot \mathbf{G}$ .

Operator	Differential form side	Vector field side (via $\flat, \sharp, *$ )
Gradient	For $f \in C^\infty(\mathbb{R}^3) = \Omega^0(\mathbb{R}^3)$ , $df \in \Omega^1(\mathbb{R}^3)$	Define $\nabla f \in \mathfrak{X}(\mathbb{R}^3)$ by $(\nabla f)^\flat = df, \quad \nabla f = (df)^\sharp.$
Curl	For a vector field $X \in \mathfrak{X}(\mathbb{R}^3)$ with 1-form $X^\flat \in \Omega^1(\mathbb{R}^3)$ , $d(X^\flat) \in \Omega^2(\mathbb{R}^3)$	Define $\text{curl } X \in \mathfrak{X}(\mathbb{R}^3)$ by $(\text{curl } X)^\flat = *d(X^\flat), \quad \text{curl } X = (*d(X^\flat))^\sharp.$
Divergence	For a vector field $X \in \mathfrak{X}(\mathbb{R}^3)$ , consider the 2-form $*X^\flat \in \Omega^2(\mathbb{R}^3)$ and its derivative $d(*X^\flat) \in \Omega^3(\mathbb{R}^3)$	Let $\text{vol}$ be the Euclidean volume form. Define $\text{div } X \in C^\infty(\mathbb{R}^3)$ by $d(*X^\flat) = (\text{div } X) \text{vol}, \quad \text{div } X = *d(*X^\flat).$

Table 1.2: Coordinate-free grad/curl/div on  $(\mathbb{R}^3, g)$  using musical isomorphisms  $\flat, \sharp$  and the Hodge star  $*$ .

$$\text{curl}(\nabla f) = (*d((df)^\sharp)^\flat)^\sharp = (*d(df))^\sharp = 0, \quad \text{div}(\text{curl } X) = *d(*(\text{curl } X)^\flat) = *d(*(*d(X^\flat))) = 0,$$

where we used  $d^2 = 0$  and  $*^2 = \pm 1$  on forms in dimension 3.

The cochain condition  $d^{k+1} \circ d^k = 0$  becomes, under the above identifications,

$$\nabla \times (\nabla f) = 0 \quad \text{and} \quad \nabla \cdot (\nabla \times \mathbf{F}) = 0.$$

In general, the de Rham complex is the coordinate-free framework that explains these vector calculus identities.

## Cohomology as “obstructions to being a gradient/curl”

In  $\mathbb{R}^3$ , “closed” and “exact” specialize as follows:

- A 1-form  $\alpha$  is **closed** iff  $d\alpha = 0$ , i.e.  $\nabla \times \mathbf{F} = 0$  (irrotational field). It is **exact** iff  $\alpha = df$ , i.e.  $\mathbf{F} = \nabla f$ . Thus  $H_{\text{dR}}^1$  measures irrotational fields that are not global gradients.
- A 2-form  $\beta$  is **closed** iff  $d\beta = 0$ , i.e.  $\nabla \cdot \mathbf{G} = 0$  (sourceless field). It is **exact** iff  $\beta = d\alpha$ , i.e.  $\mathbf{G} = \nabla \times \mathbf{F}$ . Thus  $H_{\text{dR}}^2$  measures divergence-free fields that are not global curls.

On contractible domains (like  $\mathbb{R}^3$ ), the Poincaré lemma implies these obstructions vanish:  $H_{\text{dR}}^k(\mathbb{R}^3) = 0$  for  $k \geq 1$ .

$$\begin{array}{ccccccc} \Omega^0(\mathbb{R}^3) & \xrightarrow{d} & \Omega^1(\mathbb{R}^3) & \xrightarrow{d} & \Omega^2(\mathbb{R}^3) & \xrightarrow{d} & \Omega^3(\mathbb{R}^3) \\ \parallel & & \uparrow \# \uparrow b & & \uparrow (*\cdot)^\# \uparrow (*\cdot)^b & & \uparrow *^{-1} = \pm * \\ C^\infty(\mathbb{R}^3) & \xrightarrow{\nabla} & \mathfrak{X}(\mathbb{R}^3) & \xrightarrow{\text{curl}} & \mathfrak{X}(\mathbb{R}^3) & \xrightarrow{\text{div}} & C^\infty(\mathbb{R}^3) \end{array}$$

Figure 1.1: Vector calculus operators as conjugates of  $d$  via  $b, \#, *$  in  $\mathbb{R}^3$ .

$$\begin{array}{ccccc} C^\infty(\mathbb{R}^3) & \xrightarrow{\nabla} & \mathfrak{X}(\mathbb{R}^3) & \xrightarrow{\text{curl}} & \mathfrak{X}(\mathbb{R}^3) \\ \parallel & & \downarrow b & & \downarrow b \\ \Omega^0(\mathbb{R}^3) & \xrightarrow{d} & \Omega^1(\mathbb{R}^3) & \xrightarrow{*d} & \Omega^1(\mathbb{R}^3) \end{array} \quad \Rightarrow \quad \text{curl}(\nabla f) = (*d(df))^\# = (*d^2f)^\# = 0.$$

$$\begin{array}{ccccc} \mathfrak{X}(\mathbb{R}^3) & \xrightarrow{\text{curl}} & \mathfrak{X}(\mathbb{R}^3) & \xrightarrow{\text{div}} & C^\infty(\mathbb{R}^3) \\ \downarrow b & & \downarrow b & & \parallel \\ \Omega^1(\mathbb{R}^3) & \xrightarrow{d} & \Omega^2(\mathbb{R}^3) & \xrightarrow{d} & \Omega^3(\mathbb{R}^3) \end{array} \quad \text{with} \quad \text{curl } X = (*d(X^b))^\#, \quad \text{div } Y = *d(*Y^b).$$

$$\Rightarrow \quad \text{div}(\text{curl } X) = *d(*(\text{curl } X)^b) = *d(*(*d(X^b))) = \pm *d(d(X^b)) = 0,$$

where the sign comes from  $*^2 = \pm 1$  on  $k$ -forms in dimension 3 (in Euclidean  $\mathbb{R}^3$ ,  $*^2 = +1$  for all  $k$ ).

## de Rham Cohomology

### Cochain Complex

Let  $M$  be a smooth manifold. A **cochain complex**  $(C^\bullet, d^\bullet)$  in  $\mathbb{R}$ -vector spaces consists of

- $\mathbb{R}$ -vector spaces  $C^k$  for each  $k \in \mathbb{Z}$ ,
- $\mathbb{R}$ -linear maps (coboundary maps)  $d^k : C^k \rightarrow C^{k+1}$ ,

such that  $d^{k+1} \circ d^k = 0$  for all  $k$ .

### de Rham cochain complex

For a smooth manifold  $M$ , the de Rham cochain complex  $(\Omega^\bullet(M), d)$  is

$$0 \rightarrow \Omega^0(M) \xrightarrow{d} \Omega^1(M) \xrightarrow{d} \Omega^2(M) \xrightarrow{d} \dots,$$

where

- $\Omega^k(M)$  is the  $\mathbb{R}$ -vector space of smooth differential  $k$ -forms on  $M$ .
- $d^k := d : \Omega^k(M) \rightarrow \Omega^{k+1}(M)$  is the exterior derivative such that

$$d^{k+1} \circ d^k = 0 \quad \text{for all } k \geq 0.$$

### The de Rham complex as a cochain complex

For a smooth manifold  $M$ , the de Rham cochain complex is

$$0 \rightarrow \Omega^0(M) \xrightarrow{d} \Omega^1(M) \xrightarrow{d} \Omega^2(M) \xrightarrow{d} \dots, \quad d \circ d = 0.$$

In  $\mathbb{R}^3$  (with a metric),  $d$  corresponds to grad/curl/div after identifying vector fields with differential forms via the Hodge star.

### De Rham cohomology

$$H_{\text{dR}}^k(M) := \frac{Z^k(M)}{B^k(M)} = \frac{\ker(d : \Omega^k(M) \rightarrow \Omega^{k+1}(M))}{\text{im}(d : \Omega^{k-1}(M) \rightarrow \Omega^k(M))}.$$

This measures global obstructions to writing a closed form as  $d$ (potential).

### Short exact sequence (SES) of complexes for a cover $M = U \cup V$

For each  $k$  define

$$\alpha^k : \Omega^k(M) \rightarrow \Omega^k(U) \oplus \Omega^k(V), \quad \alpha^k(\omega) = (\omega|_U, \omega|_V),$$

$$\beta^k : \Omega^k(U) \oplus \Omega^k(V) \rightarrow \Omega^k(U \cap V), \quad \beta^k(\eta, \theta) = \eta|_{U \cap V} - \theta|_{U \cap V}.$$

Then (for smooth manifolds) one has a short exact sequence

$$0 \rightarrow \Omega^k(M) \xrightarrow{\alpha^k} \Omega^k(U) \oplus \Omega^k(V) \xrightarrow{\beta^k} \Omega^k(U \cap V) \rightarrow 0.$$

Middle exactness  $\text{im}(\alpha^k) = \ker(\beta^k)$  is the gluing property (sheaf property); surjectivity of  $\beta^k$  uses partition of unity. Since  $d$  commutes with restriction, these assemble into an SES of cochain complexes:

$$0 \rightarrow \Omega^*(M) \xrightarrow{\alpha} \Omega^*(U) \oplus \Omega^*(V) \xrightarrow{\beta} \Omega^*(U \cap V) \rightarrow 0.$$

### Mayer–Vietoris long exact sequence

Any SES of cochain complexes yields a long exact sequence in cohomology:

$$\dots \rightarrow H^{k-1}(U \cap V) \xrightarrow{\delta} H^k(M) \rightarrow H^k(U) \oplus H^k(V) \rightarrow H^k(U \cap V) \xrightarrow{\delta} H^{k+1}(M) \rightarrow \dots$$

The connecting map  $\delta$  may be written explicitly using a partition of unity  $\rho_U + \rho_V = 1$ : for  $d\eta = 0$  on  $U \cap V$ ,

$$\delta([\eta]) = [d(\rho_V \eta)] = [d\rho_V \wedge \eta] \in H^k(M).$$

$$0 \longrightarrow \Omega^*(M) \xrightarrow{\alpha} \Omega^*(U) \oplus \Omega^*(V) \xrightarrow{\beta} \Omega^*(U \cap V) \longrightarrow 0$$



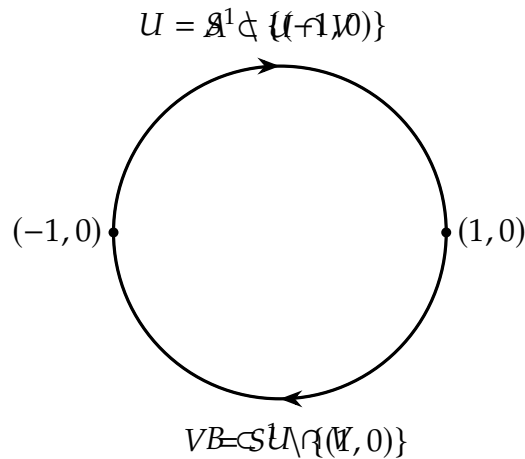
## 1.2 Example: The circle $S^1$

### 1.2.1 Cover and overlap

Let

$$U = S^1 \setminus \{(-1, 0)\}, \quad V = S^1 \setminus \{(1, 0)\}.$$

Then  $U, V$  are contractible;  $U \cap V$  has two connected components  $A$  (upper arc) and  $B$  (lower arc).



## Why stereographic charts? A detailed explanation on $S^1$

### 1. Goal: exhibit $U, V$ as coordinate domains

Let

$$S^1 = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1\}, \quad U = S^1 \setminus \{(-1, 0)\}, \quad V = S^1 \setminus \{(1, 0)\}.$$

A **(smooth) chart** on the 1-manifold  $S^1$  is a pair  $(U, \varphi)$  where

$$\varphi : U \longrightarrow \tilde{U} \subset \mathbb{R}$$

is a homeomorphism (indeed, a diffeomorphism in the smooth category) onto an open set  $\tilde{U} \subset \mathbb{R}$ .

Since removing one point from a circle “cuts it open”, we expect  $U$  and  $V$  to be diffeomorphic to  $\mathbb{R}$ . Stereographic projection gives an explicit, canonical diffeomorphism

$$U \xrightarrow{\varphi} \mathbb{R}, \quad V \xrightarrow{\psi} \mathbb{R},$$

with a very simple transition map on  $U \cap V$ .

### 2. Geometric definition of stereographic projection on $S^1$

Fix the vertical line

$$L = \{(0, t) \in \mathbb{R}^2 \mid t \in \mathbb{R}\} \cong \mathbb{R}, \quad (0, t) \leftrightarrow t.$$

- **Chart on  $U$ .** For  $p = (x, y) \in U$ , draw the straight line through the **deleted** point  $(-1, 0)$  and  $p$ , and let it intersect  $L$ . The  $t$ -coordinate of the intersection is defined to be  $\varphi(p)$ .
- **Chart on  $V$ .** For  $p = (x, y) \in V$ , draw the straight line through the **deleted** point  $(1, 0)$  and  $p$ , intersect with  $L$ , and define its  $t$ -coordinate to be  $\psi(p)$ .

This is called **stereographic projection** (here, from the missing point onto the line  $L$ ).

### 3. Derivation of the explicit formula for $\varphi$ on $U$

Take a point  $(x, y) \in S^1$  with  $(x, y) \neq (-1, 0)$ . Consider the line through  $(-1, 0)$  and  $(x, y)$ :

$$\ell(\lambda) = (-1, 0) + \lambda((x, y) - (-1, 0)) = (-1, 0) + \lambda(x + 1, y) = (-1 + \lambda(x + 1), \lambda y).$$

We find the intersection with  $L$  by imposing  $x$ -coordinate = 0:

$$-1 + \lambda(x + 1) = 0 \implies \lambda = \frac{1}{x + 1}.$$

Then the  $y$ -coordinate of the intersection point is

$$\lambda y = \frac{y}{x + 1}.$$

Identifying  $L \cong \mathbb{R}$  by  $(0, t) \leftrightarrow t$ , we obtain the chart map

$$\boxed{\varphi : U \rightarrow \mathbb{R}, \quad \varphi(x, y) = \frac{y}{1 + x}.$$

Note that  $\varphi$  is well-defined on  $U$  because  $1 + x \neq 0$  precisely when  $(x, y) \neq (-1, 0)$ .

### 4. Derivation of the explicit formula for $\psi$ on $V$

Similarly, for  $(x, y) \in V$  consider the line through  $(1, 0)$  and  $(x, y)$ :

$$\ell(\lambda) = (1, 0) + \lambda((x, y) - (1, 0)) = (1, 0) + \lambda(x - 1, y) = (1 + \lambda(x - 1), \lambda y).$$

Intersect with  $L$  by setting the  $x$ -coordinate equal to 0:

$$1 + \lambda(x - 1) = 0 \implies \lambda = -\frac{1}{x - 1} = \frac{1}{1 - x}.$$

Hence the  $y$ -coordinate of the intersection is

$$\lambda y = \frac{y}{1 - x}.$$

Thus

$$\boxed{\psi : V \rightarrow \mathbb{R}, \quad \psi(x, y) = \frac{y}{1 - x}.$$

This is well-defined on  $V$  because  $1 - x \neq 0$  precisely when  $(x, y) \neq (1, 0)$ .

### 5. Showing $\varphi$ is a diffeomorphism (by writing an inverse)

Let  $t \in \mathbb{R}$ . We solve for  $(x, y) \in S^1$  such that

$$t = \varphi(x, y) = \frac{y}{1 + x}.$$

This gives  $y = t(1 + x)$ . Impose the circle equation  $x^2 + y^2 = 1$ :

$$x^2 + t^2(1 + x)^2 = 1.$$

Expand and collect terms:

**(B) MV computation of  $H^*(S^1)$** 

Since  $U, V$  are contractible,

$$H^0(U) \cong H^0(V) \cong \mathbb{R}, \quad H^1(U) = H^1(V) = 0.$$

Since  $U \cap V = A \sqcup B$  has two components,

$$H^0(U \cap V) \cong \mathbb{R} \oplus \mathbb{R}, \quad H^1(U \cap V) = 0.$$

The relevant MV segment is

$$0 \rightarrow H^0(S^1) \rightarrow H^0(U) \oplus H^0(V) \rightarrow H^0(U \cap V) \xrightarrow{\delta} H^1(S^1) \rightarrow 0.$$

The map  $H^0(U) \oplus H^0(V) \rightarrow H^0(U \cap V)$  sends  $(a, b) \mapsto (a - b, a - b)$ , whose image is the diagonal. Hence

$$H^0(S^1) \cong \mathbb{R}, \quad H^1(S^1) \cong (\mathbb{R} \oplus \mathbb{R}) / \Delta \cong \mathbb{R}.$$

**(C) Generator and FTLI (grad) obstruction**

Choose local angle branches  $\theta_U$  on  $U$  and  $\theta_V$  on  $V$ . Then  $d\theta_U = d\theta_V$  on  $U \cap V$ , hence they glue to a global 1-form  $d\theta$  on  $S^1$ . Its period is

$$\int_{S^1} d\theta = 2\pi \neq 0,$$

so  $d\theta$  cannot be exact ( $\int_{\gamma} df = 0$  for any loop  $\gamma$  by the fundamental theorem of line integrals). Thus  $[d\theta]$  generates  $H^1(S^1) \cong \mathbb{R}$ .

$$0 \longrightarrow H^0(S^1) \longrightarrow H^0(U) \oplus H^0(V) \longrightarrow H^0(U \cap V) \xrightarrow{\delta} H^1(S^1) \longrightarrow 0$$

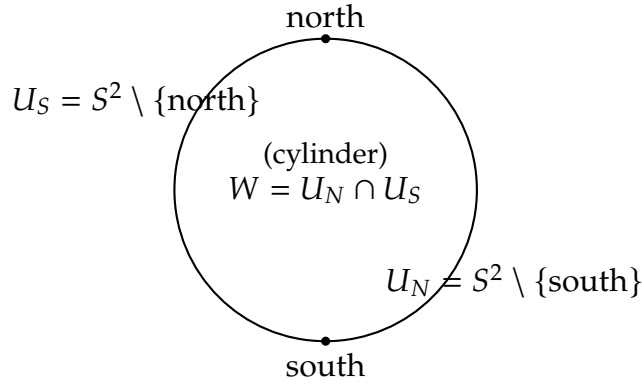
## 2. The sphere $S^2 \simeq \mathbb{CP}^1$

### (A) Cover and overlap

Let

$$U_N = S^2 \setminus \{\text{south pole}\}, \quad U_S = S^2 \setminus \{\text{north pole}\}, \quad W = U_N \cap U_S.$$

Then  $U_N \simeq \mathbb{R}^2$ ,  $U_S \simeq \mathbb{R}^2$ , and  $W \simeq S^1 \times (0, 1)$  (a cylinder).



### (B) MV computation of $H^*(S^2)$

Contractibility of  $U_N, U_S$  gives

$$H^1(U_N) = H^1(U_S) = 0, \quad H^2(U_N) = H^2(U_S) = 0.$$

Since  $W \simeq S^1 \times (0, 1)$ , we have

$$H^1(W) \cong \mathbb{R}, \quad H^2(W) = 0.$$

The key MV segment is

$$H^1(U_N) \oplus H^1(U_S) \rightarrow H^1(W) \xrightarrow{\delta} H^2(S^2) \rightarrow H^2(U_N) \oplus H^2(U_S),$$

which collapses to

$$0 \rightarrow \mathbb{R} \xrightarrow{\delta} H^2(S^2) \rightarrow 0,$$

hence

$$H^0(S^2) \cong \mathbb{R}, \quad H^1(S^2) = 0, \quad H^2(S^2) \cong \mathbb{R}.$$

### (C) Generator via area form and Stokes (div/curl-type) obstruction

In spherical coordinates  $(\vartheta, \varphi)$  on  $W$ ,

$$\Omega := \sin \vartheta \, d\vartheta \wedge d\varphi$$

is the standard area form on  $S^2$ , and

$$\int_{S^2} \Omega = 4\pi \neq 0,$$

so  $\Omega$  is not exact (if  $\Omega = dA$  globally then  $\int_{S^2} \Omega = \int_{S^2} dA = 0$  by Stokes).

Moreover, on the two charts one has explicit local potentials

$$A_N = (1 - \cos \vartheta) d\varphi \text{ on } U_N, \quad A_S = -(1 + \cos \vartheta) d\varphi \text{ on } U_S,$$

satisfying  $dA_N = dA_S = \Omega$ . On the overlap,

$$A_N - A_S = 2 d\varphi,$$

and  $[d\varphi]$  generates  $H^1(W) \cong \mathbb{R}$ . The connecting map sends

$$\delta([2 d\varphi]) = [\Omega] \in H^2(S^2).$$

$$0 \longrightarrow H^1(W) \xrightarrow[\cong]{\delta} H^2(S^2) \longrightarrow 0$$

### 3. The torus $T^2 = \mathbb{R}^2/\mathbb{Z}^2$ (complex torus)

#### (A) Global closed forms, periods, and the expected answer

The forms  $dx, dy$  descend to  $T^2$  and are closed. For the fundamental loops  $\gamma_x(t) = (t, 0)$  and  $\gamma_y(t) = (0, t) \pmod{\mathbb{Z}^2}$ ,

$$\int_{\gamma_x} dx = 1, \quad \int_{\gamma_y} dx = 0, \quad \int_{\gamma_x} dy = 0, \quad \int_{\gamma_y} dy = 1.$$

Hence  $[dx], [dy] \neq 0$  in  $H^1(T^2)$  (exact 1-forms have zero periods on loops). Also  $dx \wedge dy$  is closed and

$$\int_{T^2} dx \wedge dy = 1 \neq 0,$$

so  $[dx \wedge dy] \neq 0$  in  $H^2(T^2)$ . Thus one expects

$$H^0(T^2) \cong \mathbb{R}, \quad H^1(T^2) \cong \mathbb{R}^2 \langle [dx], [dy] \rangle, \quad H^2(T^2) \cong \mathbb{R} \langle [dx \wedge dy] \rangle.$$

#### (B) MV cover that recovers these classes

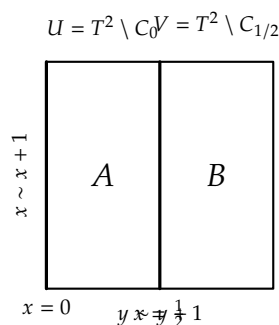
Let

$$C_0 = \{x \equiv 0 \pmod{1}\}, \quad C_{1/2} = \{x \equiv \tfrac{1}{2} \pmod{1}\},$$

and define

$$U := T^2 \setminus C_0, \quad V := T^2 \setminus C_{1/2}.$$

Then  $U \simeq S^1$ ,  $V \simeq S^1$ , and  $U \cap V$  is a disjoint union of two cylinders  $A \sqcup B$  (two vertical open strips in the fundamental square).



#### (C) MV segments (what they do)

Cohomology of pieces:

$$H^0(U) \cong H^0(V) \cong \mathbb{R}, \quad H^1(U) \cong H^1(V) \cong \mathbb{R},$$

$$H^0(U \cap V) \cong \mathbb{R} \oplus \mathbb{R}, \quad H^1(U \cap V) \cong \mathbb{R} \oplus \mathbb{R}, \quad H^2(U) = H^2(V) = H^2(U \cap V) = 0.$$

**Degree 1: producing  $[dx]$  and  $[dy]$ .** The MV segment

$$H^0(U \cap V) \xrightarrow{\delta} H^1(T^2) \rightarrow H^1(U) \oplus H^1(V) \rightarrow H^1(U \cap V)$$

shows:

- $\delta$  injects a copy of  $\mathbb{R}$  (quotient of  $H^0(U \cap V)$  by the diagonal) into  $H^1(T^2)$ ; concretely it produces  $[dx]$  from the “difference of constants” on the two components  $A, B$ .
- The kernel of  $H^1(U) \oplus H^1(V) \rightarrow H^1(U \cap V)$  contributes the second independent class, represented globally by  $[dy]$ .

Hence  $H^1(T^2) \cong \mathbb{R}^2$ .

**Degree 2: producing  $[dx \wedge dy]$ .** The MV segment

$$H^1(U \cap V) \xrightarrow{\delta} H^2(T^2) \rightarrow 0$$

shows  $H^2(T^2)$  is a quotient of  $H^1(U \cap V) \cong \mathbb{R}^2$ , killing the diagonal; the resulting 1-dimensional quotient maps onto  $H^2(T^2)$ , and the nonzero integral

$$\int_{T^2} dx \wedge dy = 1$$

identifies the generator as  $[dx \wedge dy]$  (up to sign).

$$H^0(U \cap V) \xrightarrow{\delta} H^1(T^2) \longrightarrow H^1(U) \oplus H^1(V) \longrightarrow H^1(U \cap V)$$

$$H^1(U \cap V) \xrightarrow{\delta} H^2(T^2) \longrightarrow 0$$

## Quick reference: generators and “potential” obstructions

- $S^1$ : generator  $[d\theta] \in H^1(S^1)$  detected by  $\int_{S^1} d\theta = 2\pi$  (FTLI obstruction to being a global gradient).
- $S^2$ : generator  $[\Omega] \in H^2(S^2)$  detected by  $\int_{S^2} \Omega = 4\pi$  (Stokes obstruction to being  $dA$  globally).
- $T^2$ : generators  $[dx], [dy] \in H^1(T^2)$  detected by loop periods; generator  $[dx \wedge dy] \in H^2(T^2)$  detected by  $\int_{T^2} dx \wedge dy = 1$ .

## Chapter 2

# Mayer–Vietoris Sequence and de Rham Cohomology

Choose  $\{V^k\}_{k=0}^3$  and isomorphisms  $\Phi^k : V^k \rightarrow \Omega^k(U)$  such that

$$\Phi^{k+1} \circ d^k = d \circ \Phi^k$$

where  $d^0 = \nabla$ ,  $d^1 = \nabla \times$ ,  $d^2 = \nabla \cdot$ , and  $d$  is exterior derivative.



## 2.1 Why the spaces $V^0, V^1, V^2, V^3$ are chosen as scalar and vector fields

### 2.1.1 Axiomatic goal

**Definition 2.1.1** (Design requirement: transport of the de Rham differential). Let  $U \subseteq \mathbb{R}^3$  be open and  $\mathbb{k} \in \{\mathbb{R}, \mathbb{C}\}$ . Let  $(V^\bullet, d_V)$  be a cochain complex of  $\mathbb{k}$ -vector spaces concentrated in degrees  $0, 1, 2, 3$ , i.e.  $V^n = 0$  for  $n \notin \{0, 1, 2, 3\}$ . We say that  $(V^\bullet, d_V)$  **models the de Rham complex on  $U$  via identifications** if there exist  $\mathbb{k}$ -linear isomorphisms

$$\Phi^k : V^k \xrightarrow{\cong} \Omega^k(U) \quad (k = 0, 1, 2, 3)$$

such that for all  $k \in \{0, 1, 2\}$  the following diagram commutes:

$$\begin{array}{ccc} V^k & \xrightarrow{d_V^k} & V^{k+1} \\ \Phi^k \downarrow \cong & & \Phi^{k+1} \downarrow \cong \\ \Omega^k(U) & \xrightarrow{d} & \Omega^{k+1}(U). \end{array}$$

Equivalently,

$$\Phi^{k+1} \circ d_V^k = d \circ \Phi^k \quad (k = 0, 1, 2).$$

### 2.1.2 Canonical identifications in Euclidean $\mathbb{R}^3$

**Definition 2.1.2** (Scalar fields). Define

$$V^0 := C^\infty(U; \mathbb{k}), \quad V^3 := C^\infty(U; \mathbb{k}).$$

**Remark 2.1.3.** By definition of differential forms,  $\Omega^0(U) = C^\infty(U; \mathbb{k})$ . Moreover, fixing the standard orientation with volume form

$$\text{vol} := dx_1 \wedge dx_2 \wedge dx_3,$$

every 3-form is uniquely of the form  $h \text{ vol}$  with  $h \in C^\infty(U; \mathbb{k})$ , hence

$$\Omega^3(U) \cong C^\infty(U; \mathbb{k})$$

via  $h \mapsto h \text{ vol}$ .

**Definition 2.1.4** (Vector fields and the Euclidean musical isomorphism). Define the  $\mathbb{k}$ -vector space of (smooth) vector fields

$$\mathfrak{X}(U; \mathbb{k}) := C^\infty(U; \mathbb{k}^3).$$

Endow  $U$  with the standard Euclidean metric  $g = \sum_{i=1}^3 dx_i \otimes dx_i$ . Define the  $\mathbb{k}$ -linear isomorphism

$$\flat : \mathfrak{X}(U; \mathbb{k}) \xrightarrow{\cong} \Omega^1(U)$$

by the coordinate formula

$$(P, Q, R)^\flat := P dx_1 + Q dx_2 + R dx_3.$$

Define

$$V^1 := \mathfrak{X}(U; \mathbb{k}) = C^\infty(U; \mathbb{k}^3).$$

**Definition 2.1.5** (Hodge star and the identification  $\Omega^2 \cong \mathfrak{X}$ ). With the Euclidean metric and orientation, let

$$* : \Omega^k(U) \rightarrow \Omega^{3-k}(U)$$

be the Hodge star. Define the  $\mathbb{k}$ -linear isomorphism

$$\Psi : \mathfrak{X}(U; \mathbb{k}) \xrightarrow{\cong} \Omega^2(U), \quad \Psi(G) := *(G^\flat).$$

In coordinates, for  $G = (A, B, C)$  one has

$$\Psi(A, B, C) = A dx_2 \wedge dx_3 + B dx_3 \wedge dx_1 + C dx_1 \wedge dx_2.$$

Define

$$V^2 := \mathfrak{X}(U; \mathbb{k}) = C^\infty(U; \mathbb{k}^3).$$

### 2.1.3 Compatibility with grad, curl, div

**Definition 2.1.6** (The grad–curl–div differentials). Define  $\mathbb{k}$ -linear maps

$$\nabla : V^0 \rightarrow V^1, \quad \nabla \times : V^1 \rightarrow V^2, \quad \nabla \cdot : V^2 \rightarrow V^3$$

by the standard coordinate formulas

$$\nabla f = (\partial_1 f, \partial_2 f, \partial_3 f),$$

$$\nabla \times (P, Q, R) = (\partial_2 R - \partial_3 Q, \partial_3 P - \partial_1 R, \partial_1 Q - \partial_2 P),$$

$$\nabla \cdot (A, B, C) = \partial_1 A + \partial_2 B + \partial_3 C.$$

**Proposition 2.1.7** (Commuting transport and forced shapes of  $V^k$ ). Let  $\Phi^0, \Phi^1, \Phi^2, \Phi^3$  be defined by

$$\Phi^0 = \text{id}_{C^\infty(U; \mathbb{k})}, \quad \Phi^1 = \flat, \quad \Phi^2 = \Psi, \quad \Phi^3(h) = h \text{ vol}.$$

Then

$$\Phi^1 \circ \nabla = d \circ \Phi^0, \quad \Phi^2 \circ (\nabla \times) = d \circ \Phi^1, \quad \Phi^3 \circ (\nabla \cdot) = d \circ \Phi^2.$$

Consequently, the grad–curl–div complex

$$0 \rightarrow V^0 \xrightarrow{\nabla} V^1 \xrightarrow{\nabla \times} V^2 \xrightarrow{\nabla \cdot} V^3 \rightarrow 0$$

is (via  $\Phi^\bullet$ ) a transported model of the de Rham complex

$$0 \rightarrow \Omega^0(U) \xrightarrow{d} \Omega^1(U) \xrightarrow{d} \Omega^2(U) \xrightarrow{d} \Omega^3(U) \rightarrow 0.$$

*Proof.* The equalities are verified by direct coordinate computation. Explicitly, for  $f \in C^\infty(U; \mathbb{k})$ ,

$$d(f) = \sum_{i=1}^3 \partial_i f dx_i = (\nabla f)^\flat = \Phi^1(\nabla f).$$

For  $F = (P, Q, R) \in V^1$  one computes

$$d(F^\flat) = (\partial_2 R - \partial_3 Q) dx_2 \wedge dx_3 + (\partial_3 P - \partial_1 R) dx_3 \wedge dx_1 + (\partial_1 Q - \partial_2 P) dx_1 \wedge dx_2 = \Psi(\nabla \times F) = \Phi^2(\nabla \times F),$$

and for  $G = (A, B, C) \in V^2$  one computes

$$d(\Psi(G)) = (\partial_1 A + \partial_2 B + \partial_3 C) dx_1 \wedge dx_2 \wedge dx_3 = (\nabla \cdot G) \text{ vol} = \Phi^3(\nabla \cdot G).$$

□

### 2.1.4 Uniqueness up to constant changes of basis

**Theorem 2.1.8** (Uniqueness up to  $\mathrm{GL}_3(\mathbb{k})$  in degrees 1 and 2). *Let  $\tilde{\Phi}^0, \tilde{\Phi}^1, \tilde{\Phi}^2, \tilde{\Phi}^3$  be any linear isomorphisms*

$$\tilde{\Phi}^k : V^k \xrightarrow{\cong} \Omega^k(U) \quad (k = 0, 1, 2, 3)$$

*such that*

$$\tilde{\Phi}^1 \circ \nabla = d \circ \tilde{\Phi}^0, \quad \tilde{\Phi}^2 \circ (\nabla \times) = d \circ \tilde{\Phi}^1, \quad \tilde{\Phi}^3 \circ (\nabla \cdot) = d \circ \tilde{\Phi}^2,$$

*and assume  $\tilde{\Phi}^0 = \mathrm{id}$  and  $\tilde{\Phi}^3(h) = h \, \mathrm{vol}$ . Then there exists a constant matrix  $A \in \mathrm{GL}_3(\mathbb{k})$  such that, after identifying  $V^1 = V^2 = C^\infty(U; \mathbb{k}^3)$ , one has*

$$\tilde{\Phi}^1 = \flat \circ A, \quad \tilde{\Phi}^2 = \Psi \circ A,$$

*where  $A$  acts pointwise on  $C^\infty(U; \mathbb{k}^3)$  by  $(AF)(x) = A(F(x))$ .*

*Proof.* Define linear automorphisms  $T^1 := \flat^{-1} \circ \tilde{\Phi}^1$  and  $T^2 := \Psi^{-1} \circ \tilde{\Phi}^2$  of  $C^\infty(U; \mathbb{k}^3)$ . The relations  $\tilde{\Phi}^1 \circ \nabla = d \circ \mathrm{id} = \flat \circ \nabla$  and  $\tilde{\Phi}^2 \circ (\nabla \times) = d \circ \tilde{\Phi}^1 = \Psi \circ (\nabla \times) \circ T^1$  imply

$$T^1 \circ \nabla = \nabla, \quad T^2 \circ (\nabla \times) = (\nabla \times) \circ T^1.$$

A standard linear-algebra/analysis argument shows that any  $\mathbb{k}$ -linear endomorphism of  $C^\infty(U; \mathbb{k}^3)$  commuting with all partial derivatives must be given by pointwise multiplication by a constant matrix in  $\mathrm{GL}_3(\mathbb{k})$ ; denote this matrix by  $A$ . Then  $T^1 = A$  and the second commutation forces  $T^2 = A$  as well. Hence  $\tilde{\Phi}^1 = \flat \circ A$  and  $\tilde{\Phi}^2 = \Psi \circ A$ .  $\square$

**Remark 2.1.9.** The theorem formalizes the statement that, once one fixes the canonical identifications in degrees 0 and 3, the identifications in degrees 1 and 2 are unique up to an invertible constant change of basis of  $\mathbb{k}^3$ .

## 2.2 The grad–curl–div cochain complex and its cohomology

### 2.2.1 Vector spaces and linear maps

**Definition 2.2.1** (Spaces of smooth fields). Let  $U \subseteq \mathbb{R}^3$  be an open set and fix a field  $\mathbb{k} \in \{\mathbb{R}, \mathbb{C}\}$ . Define  $\mathbb{k}$ -vector spaces

$$V^0 := C^\infty(U; \mathbb{k}), \quad V^1 := C^\infty(U; \mathbb{k}^3), \quad V^2 := C^\infty(U; \mathbb{k}^3), \quad V^3 := C^\infty(U; \mathbb{k}),$$

with pointwise addition and scalar multiplication. For all  $n \in \mathbb{Z} \setminus \{0, 1, 2, 3\}$  set  $V^n := 0$ .

**Definition 2.2.2** (Differentials:  $\nabla, \nabla \times, \nabla \cdot$ ). Write  $(x_1, x_2, x_3)$  for the standard coordinates on  $\mathbb{R}^3$  and  $\partial_i := \frac{\partial}{\partial x_i}$ . Define  $\mathbb{k}$ -linear maps

$$d^0 : V^0 \rightarrow V^1, \quad d^1 : V^1 \rightarrow V^2, \quad d^2 : V^2 \rightarrow V^3$$

by the following formulas:

$$\begin{aligned} d^0(f) &:= \nabla f := (\partial_1 f, \partial_2 f, \partial_3 f), \\ d^1(P, Q, R) &:= \nabla \times (P, Q, R) := (\partial_2 R - \partial_3 Q, \partial_3 P - \partial_1 R, \partial_1 Q - \partial_2 P), \\ d^2(A, B, C) &:= \nabla \cdot (A, B, C) := \partial_1 A + \partial_2 B + \partial_3 C. \end{aligned}$$

For all  $n \in \mathbb{Z} \setminus \{0, 1, 2\}$  define  $d^n : V^n \rightarrow V^{n+1}$  to be the zero map.

**Proposition 2.2.3** (The grad–curl–div complex). *The sequence*

$$0 \longrightarrow V^0 \xrightarrow{d^0=\nabla} V^1 \xrightarrow{d^1=\nabla \times} V^2 \xrightarrow{d^2=\nabla \cdot} V^3 \longrightarrow 0$$

is a cochain complex, i.e.  $d^1 \circ d^0 = 0$  and  $d^2 \circ d^1 = 0$ . Equivalently,

$$\nabla \times (\nabla f) = 0 \quad \forall f \in C^\infty(U; \mathbb{k}), \quad \nabla \cdot (\nabla \times F) = 0 \quad \forall F \in C^\infty(U; \mathbb{k}^3).$$

*Proof.* Let  $f \in C^\infty(U; \mathbb{k})$ . Then

$$(\nabla \times \nabla f)_1 = \partial_2(\partial_3 f) - \partial_3(\partial_2 f) = 0$$

by commutativity of mixed partials; similarly  $(\nabla \times \nabla f)_2 = (\nabla \times \nabla f)_3 = 0$ . Hence  $d^1 d^0 = 0$ .

Let  $F = (P, Q, R) \in C^\infty(U; \mathbb{k}^3)$ . Then

$$\begin{aligned} \nabla \cdot (\nabla \times F) &= \partial_1(\partial_2 R - \partial_3 Q) + \partial_2(\partial_3 P - \partial_1 R) + \partial_3(\partial_1 Q - \partial_2 P) \\ &= \partial_1 \partial_2 R - \partial_1 \partial_3 Q + \partial_2 \partial_3 P - \partial_2 \partial_1 R + \partial_3 \partial_1 Q - \partial_3 \partial_2 P \\ &= 0 \end{aligned}$$

again by commutativity of mixed partial derivatives and cancellation. Thus  $d^2 d^1 = 0$ .  $\square$

### 2.2.2 Cohomology and interpretation

**Definition 2.2.4** (Cocycles, coboundaries, cohomology). Let  $(V^\bullet, d)$  be the grad–curl–div cochain complex above. For each  $n \in \mathbb{Z}$  define

$$Z^n := \ker(d^n) \subseteq V^n, \quad B^n := \operatorname{im}(d^{n-1}) \subseteq V^n, \quad H^n(V^\bullet) := Z^n / B^n.$$

**Proposition 2.2.5** (Cohomology groups of the grad-curl-div complex). *With the conventions  $d^{-1} = 0$  and  $d^3 = 0$  one has:*

$$\begin{aligned} H^0(V^\bullet) &\cong \ker(\nabla) = \{f \in C^\infty(U; \mathbb{k}) : \nabla f = 0\}, \\ H^1(V^\bullet) &\cong \ker(\nabla \times) / \text{im}(\nabla) = \frac{\{F \in C^\infty(U; \mathbb{k}^3) : \nabla \times F = 0\}}{\{\nabla f : f \in C^\infty(U; \mathbb{k})\}}, \\ H^2(V^\bullet) &\cong \ker(\nabla \cdot) / \text{im}(\nabla \times) = \frac{\{G \in C^\infty(U; \mathbb{k}^3) : \nabla \cdot G = 0\}}{\{\nabla \times F : F \in C^\infty(U; \mathbb{k}^3)\}}, \\ H^3(V^\bullet) &\cong V^3 / \text{im}(\nabla \cdot) = \frac{C^\infty(U; \mathbb{k})}{\{\nabla \cdot G : G \in C^\infty(U; \mathbb{k}^3)\}}. \end{aligned}$$

**Remark 2.2.6** (Interpretation).  $H^1$  measures curl-free vector fields modulo gradients (obstructions to global scalar potentials).  $H^2$  measures divergence-free vector fields modulo curls (obstructions to global vector potentials).  $H^3$  measures functions modulo divergences.

### 2.2.3 Identification with the de Rham complex (formal transport)

**Definition 2.2.7** (de Rham complex). Let  $\Omega^k(U)$  denote the  $\mathbb{k}$ -vector space of smooth differential  $k$ -forms on  $U$ . The exterior derivative is a  $\mathbb{k}$ -linear map

$$d : \Omega^k(U) \rightarrow \Omega^{k+1}(U)$$

satisfying  $d \circ d = 0$ . The associated cohomology spaces are

$$H_{\text{dR}}^k(U) := \ker(d : \Omega^k(U) \rightarrow \Omega^{k+1}(U)) / \text{im}(d : \Omega^{k-1}(U) \rightarrow \Omega^k(U)).$$

**Definition 2.2.8** (Musical isomorphism and Hodge star (Euclidean)). Equip  $U \subseteq \mathbb{R}^3$  with the standard Euclidean metric and orientation. Let  $\flat : C^\infty(U; \mathbb{k}^3) \rightarrow \Omega^1(U)$  denote the metric identification (“lowering an index”). Let  $*$  :  $\Omega^k(U) \rightarrow \Omega^{3-k}(U)$  denote the Hodge star operator.

**Proposition 2.2.9** (Commuting diagram with de Rham). *Define linear isomorphisms*

$$\begin{aligned} \Phi^0 : V^0 &\xrightarrow{\cong} \Omega^0(U), & \Phi^0(f) &= f, \\ \Phi^1 : V^1 &\xrightarrow{\cong} \Omega^1(U), & \Phi^1(F) &= F^\flat, \\ \Phi^2 : V^2 &\xrightarrow{\cong} \Omega^2(U), & \Phi^2(G) &= *(G^\flat), \\ \Phi^3 : V^3 &\xrightarrow{\cong} \Omega^3(U), & \Phi^3(h) &= h \, dx_1 \wedge dx_2 \wedge dx_3. \end{aligned}$$

Then the following diagram commutes:

$$\begin{array}{ccccccccc} 0 & \longrightarrow & V^0 & \xrightarrow{\nabla} & V^1 & \xrightarrow{\nabla \times} & V^2 & \xrightarrow{\nabla \cdot} & V^3 & \longrightarrow & 0 \\ & & \Phi^0 \downarrow \cong & & \Phi^1 \downarrow \cong & & \Phi^2 \downarrow \cong & & \Phi^3 \downarrow \cong & & \\ 0 & \longrightarrow & \Omega^0(U) & \xrightarrow{d} & \Omega^1(U) & \xrightarrow{d} & \Omega^2(U) & \xrightarrow{d} & \Omega^3(U) & \longrightarrow & 0 \end{array}$$

Consequently, for each  $k \in \{0, 1, 2, 3\}$  there is an induced isomorphism

$$H^k(V^\bullet) \cong H_{\text{dR}}^k(U).$$

**Corollary 2.2.10** (Contractible case). *If  $U$  is contractible (e.g.  $U$  is star-shaped), then*

$$H^k(V^\bullet) = 0 \text{ for all } k \in \{1, 2, 3\},$$

*and if  $U$  is connected then  $H^0(V^\bullet) \cong \mathbb{k}$ .*

## 2.3 The grad–curl–div cochain complex and its identification with the de Rham complex

### 2.3.1 The grad–curl–div cochain complex

**Definition 2.3.1** (Spaces and differentials). Let  $U \subseteq \mathbb{R}^3$  be open and fix  $\mathbb{k} \in \{\mathbb{R}, \mathbb{C}\}$ . Define  $\mathbb{k}$ -vector spaces

$$V^0 := C^\infty(U; \mathbb{k}), \quad V^1 := C^\infty(U; \mathbb{k}^3), \quad V^2 := C^\infty(U; \mathbb{k}^3), \quad V^3 := C^\infty(U; \mathbb{k}).$$

Write  $(x_1, x_2, x_3)$  for the standard coordinates and  $\partial_i := \frac{\partial}{\partial x_i}$ . Define  $\mathbb{k}$ -linear maps

$$d^0 : V^0 \rightarrow V^1, \quad d^1 : V^1 \rightarrow V^2, \quad d^2 : V^2 \rightarrow V^3$$

by

$$\begin{aligned} d^0(f) &:= \nabla f := (\partial_1 f, \partial_2 f, \partial_3 f), \\ d^1(P, Q, R) &:= \nabla \times (P, Q, R) := (\partial_2 R - \partial_3 Q, \partial_3 P - \partial_1 R, \partial_1 Q - \partial_2 P), \\ d^2(A, B, C) &:= \nabla \cdot (A, B, C) := \partial_1 A + \partial_2 B + \partial_3 C. \end{aligned}$$

**Proposition 2.3.2** (Cochain complex condition). *One has  $d^1 \circ d^0 = 0$  and  $d^2 \circ d^1 = 0$ . Hence*

$$0 \longrightarrow V^0 \xrightarrow{\nabla} V^1 \xrightarrow{\nabla \times} V^2 \xrightarrow{\nabla \cdot} V^3 \longrightarrow 0$$

*is a cochain complex.*

*Proof.* This follows immediately from the computations

$$\nabla \times (\nabla f) = 0, \quad \nabla \cdot (\nabla \times F) = 0,$$

which are verified componentwise using commutativity of mixed partial derivatives.  $\square$

### 2.3.2 Cohomology of the grad–curl–div complex

**Definition 2.3.3** (Cohomology). For each  $n \in \{0, 1, 2, 3\}$  define

$$Z^n := \text{Ker}(d^n) \subseteq V^n, \quad B^n := \text{im}(d^{n-1}) \subseteq V^n, \quad H^n(V^\bullet) := Z^n / B^n,$$

with the conventions  $d^{-1} = 0$  and  $d^3 = 0$ .

**Proposition 2.3.4** (Concrete description). *One has canonical identifications*

$$\begin{aligned} H^0(V^\bullet) &\cong \text{Ker}(\nabla), \\ H^1(V^\bullet) &\cong \text{Ker}(\nabla \times) / \text{im}(\nabla), \\ H^2(V^\bullet) &\cong \text{Ker}(\nabla \cdot) / \text{im}(\nabla \times), \\ H^3(V^\bullet) &\cong V^3 / \text{im}(\nabla \cdot). \end{aligned}$$

### 2.3.3 Differential forms on $U \subseteq \mathbb{R}^3$

**Definition 2.3.5** (de Rham complex). Let  $\Omega^k(U)$  be the  $\mathbb{k}$ -vector space of smooth  $k$ -forms on  $U$ . The exterior derivative is the  $\mathbb{k}$ -linear map

$$d : \Omega^k(U) \rightarrow \Omega^{k+1}(U)$$

characterized in coordinates by the usual rules (graded Leibniz rule and  $d(dx_i) = 0$ ), and satisfies  $d \circ d = 0$ . The  $k$ -th de Rham cohomology is

$$H_{\text{dR}}^k(U) := \text{Ker}(d : \Omega^k(U) \rightarrow \Omega^{k+1}(U)) / \text{im}(d : \Omega^{k-1}(U) \rightarrow \Omega^k(U)).$$

### 2.3.4 Explicit formulas for $\flat$ and $\sharp$

**Definition 2.3.6** (Euclidean musical isomorphisms). Endow  $U \subseteq \mathbb{R}^3$  with the standard Euclidean metric  $g = \sum_{i=1}^3 dx_i \otimes dx_i$ . Define the  $\mathbb{k}$ -linear map (“lowering an index”)

$$\flat : C^\infty(U; \mathbb{k}^3) \rightarrow \Omega^1(U)$$

by the coordinate formula

$$(P, Q, R)^\flat := P dx_1 + Q dx_2 + R dx_3.$$

Its inverse  $\sharp : \Omega^1(U) \rightarrow C^\infty(U; \mathbb{k}^3)$  is given by

$$(a_1 dx_1 + a_2 dx_2 + a_3 dx_3)^\sharp := (a_1, a_2, a_3).$$

**Definition 2.3.7** (Hodge star in  $\mathbb{R}^3$ ). Fix the standard orientation, with volume form

$$\text{vol} := dx_1 \wedge dx_2 \wedge dx_3 \in \Omega^3(U).$$

Define the Hodge star operator  $*$  :  $\Omega^k(U) \rightarrow \Omega^{3-k}(U)$  by specifying its values on the standard basis:

$$\begin{aligned} *1 &= \text{vol}, \\ *dx_1 &= dx_2 \wedge dx_3, \quad *dx_2 = dx_3 \wedge dx_1, \quad *dx_3 = dx_1 \wedge dx_2, \\ *(dx_2 \wedge dx_3) &= dx_1, \quad *(dx_3 \wedge dx_1) = dx_2, \quad *(dx_1 \wedge dx_2) = dx_3, \\ *\text{vol} &= 1, \end{aligned}$$

and extending  $\mathbb{k}$ -linearly.

### 2.3.5 Transport of the de Rham differential to grad–curl–div

**Definition 2.3.8** (The comparison isomorphisms  $\Phi^k$ ). Define  $\mathbb{k}$ -linear isomorphisms

$$\begin{aligned} \Phi^0 : V^0 &\xrightarrow{\cong} \Omega^0(U), \quad \Phi^0(f) := f, \\ \Phi^1 : V^1 &\xrightarrow{\cong} \Omega^1(U), \quad \Phi^1(F) := F^\flat, \\ \Phi^2 : V^2 &\xrightarrow{\cong} \Omega^2(U), \quad \Phi^2(G) := *(G^\flat), \\ \Phi^3 : V^3 &\xrightarrow{\cong} \Omega^3(U), \quad \Phi^3(h) := h \text{ vol}. \end{aligned}$$



**Proposition 2.3.9** (Commutativity of the comparison diagram). *For all  $f \in V^0$ ,  $F \in V^1$ ,  $G \in V^2$ , one has*

$$\Phi^1(\nabla f) = d(\Phi^0(f)), \quad \Phi^2(\nabla \times F) = d(\Phi^1(F)), \quad \Phi^3(\nabla \cdot G) = d(\Phi^2(G)).$$

*Equivalently, the diagram of cochain complexes commutes:*

$$\begin{array}{ccccccccc} 0 & \longrightarrow & V^0 & \xrightarrow{\nabla} & V^1 & \xrightarrow{\nabla \times} & V^2 & \xrightarrow{\nabla \cdot} & V^3 & \longrightarrow & 0 \\ & & \Phi^0 \downarrow \cong & & \Phi^1 \downarrow \cong & & \Phi^2 \downarrow \cong & & \Phi^3 \downarrow \cong & & \\ 0 & \longrightarrow & \Omega^0(U) & \xrightarrow{d} & \Omega^1(U) & \xrightarrow{d} & \Omega^2(U) & \xrightarrow{d} & \Omega^3(U) & \longrightarrow & 0. \end{array}$$

*Proof.* **Step 1: grad.** Let  $f \in V^0 = C^\infty(U; \mathbb{K})$ . Then

$$d(\Phi^0(f)) = d(f) = \partial_1 f dx_1 + \partial_2 f dx_2 + \partial_3 f dx_3 = (\nabla f)^b = \Phi^1(\nabla f).$$

**Step 2: curl.** Let  $F = (P, Q, R) \in V^1$ . Then  $\Phi^1(F) = F^b = P dx_1 + Q dx_2 + R dx_3$ , hence

$$\begin{aligned} d(\Phi^1(F)) &= d(P) \wedge dx_1 + d(Q) \wedge dx_2 + d(R) \wedge dx_3 \\ &= (\partial_1 P dx_1 + \partial_2 P dx_2 + \partial_3 P dx_3) \wedge dx_1 \\ &\quad + (\partial_1 Q dx_1 + \partial_2 Q dx_2 + \partial_3 Q dx_3) \wedge dx_2 \\ &\quad + (\partial_1 R dx_1 + \partial_2 R dx_2 + \partial_3 R dx_3) \wedge dx_3. \end{aligned}$$

Using  $dx_i \wedge dx_i = 0$  and  $dx_j \wedge dx_i = -dx_i \wedge dx_j$ , this simplifies to

$$\begin{aligned} d(\Phi^1(F)) &= (\partial_2 P) dx_2 \wedge dx_1 + (\partial_3 P) dx_3 \wedge dx_1 \\ &\quad + (\partial_1 Q) dx_1 \wedge dx_2 + (\partial_3 Q) dx_3 \wedge dx_2 \\ &\quad + (\partial_1 R) dx_1 \wedge dx_3 + (\partial_2 R) dx_2 \wedge dx_3 \\ &= (\partial_2 R - \partial_3 Q) dx_2 \wedge dx_3 + (\partial_3 P - \partial_1 R) dx_3 \wedge dx_1 + (\partial_1 Q - \partial_2 P) dx_1 \wedge dx_2. \end{aligned}$$

On the other hand,

$$\nabla \times F = (\partial_2 R - \partial_3 Q, \partial_3 P - \partial_1 R, \partial_1 Q - \partial_2 P),$$

so

$$\begin{aligned} \Phi^2(\nabla \times F) &= *((\nabla \times F)^b) \\ &= *((\partial_2 R - \partial_3 Q) dx_1 + (\partial_3 P - \partial_1 R) dx_2 + (\partial_1 Q - \partial_2 P) dx_3) \\ &= (\partial_2 R - \partial_3 Q) dx_2 \wedge dx_3 + (\partial_3 P - \partial_1 R) dx_3 \wedge dx_1 + (\partial_1 Q - \partial_2 P) dx_1 \wedge dx_2. \end{aligned}$$

Comparing,  $d(\Phi^1(F)) = \Phi^2(\nabla \times F)$ .

**Step 3: div.** Let  $G = (A, B, C) \in V^2$ . Then

$$\Phi^2(G) = *(G^b) = *(A dx_1 + B dx_2 + C dx_3) = A dx_2 \wedge dx_3 + B dx_3 \wedge dx_1 + C dx_1 \wedge dx_2.$$

Therefore

$$\begin{aligned} d(\Phi^2(G)) &= d(A) \wedge dx_2 \wedge dx_3 + d(B) \wedge dx_3 \wedge dx_1 + d(C) \wedge dx_1 \wedge dx_2 \\ &= (\partial_1 A dx_1 + \partial_2 A dx_2 + \partial_3 A dx_3) \wedge dx_2 \wedge dx_3 \\ &\quad + (\partial_1 B dx_1 + \partial_2 B dx_2 + \partial_3 B dx_3) \wedge dx_3 \wedge dx_1 \\ &\quad + (\partial_1 C dx_1 + \partial_2 C dx_2 + \partial_3 C dx_3) \wedge dx_1 \wedge dx_2 \\ &= (\partial_1 A) dx_1 \wedge dx_2 \wedge dx_3 + (\partial_2 B) dx_2 \wedge dx_3 \wedge dx_1 + (\partial_3 C) dx_3 \wedge dx_1 \wedge dx_2 \\ &= (\partial_1 A + \partial_2 B + \partial_3 C) dx_1 \wedge dx_2 \wedge dx_3 \\ &= (\nabla \cdot G) \text{vol} = \Phi^3(\nabla \cdot G). \end{aligned}$$

This completes the proof. □

**Corollary 2.3.10** (Cohomology identification). *The maps  $\Phi^k$  induce isomorphisms on cohomology:*

$$H^k(V^\bullet) \cong H_{\text{dR}}^k(U) \quad (k = 0, 1, 2, 3).$$

**Remark 2.3.11** (Topology and “potential” obstructions). Under the identification above,  $H^1(V^\bullet)$  measures curl-free fields modulo gradients, and  $H^2(V^\bullet)$  measures divergence-free fields modulo curls. If  $U$  is contractible (e.g. star-shaped), then  $H_{\text{dR}}^k(U) = 0$  for  $k \geq 1$ , hence  $H^1(V^\bullet) = H^2(V^\bullet) = H^3(V^\bullet) = 0$ .

## 2.4 Cochain complexes and grad–curl–div as de Rham cohomology in $\mathbb{R}^3$

### 2.4.1 Formal construction of differential forms on an open set of $\mathbb{R}^3$

**Definition 2.4.1** (Coordinate ring of smooth functions). Let  $U \subseteq \mathbb{R}^3$  be open. For a field  $\mathbb{k} \in \{\mathbb{R}, \mathbb{C}\}$  define

$$\Omega^0(U) := C^\infty(U; \mathbb{k}),$$

viewed as a commutative unital  $\mathbb{k}$ -algebra under pointwise operations.

**Definition 2.4.2** (The  $\mathbb{k}$ -vector spaces  $\Omega^1(U), \Omega^2(U), \Omega^3(U)$ ). Let  $(x_1, x_2, x_3)$  be the standard coordinate functions on  $U$ . Define  $\Omega^1(U)$  to be the free  $\Omega^0(U)$ -module with basis  $\{dx_1, dx_2, dx_3\}$ , i.e.

$$\Omega^1(U) := \Omega^0(U) dx_1 \oplus \Omega^0(U) dx_2 \oplus \Omega^0(U) dx_3.$$

Define  $\Omega^2(U)$  to be the free  $\Omega^0(U)$ -module with basis  $\{dx_1 \wedge dx_2, dx_2 \wedge dx_3, dx_3 \wedge dx_1\}$ , i.e.

$$\Omega^2(U) := \Omega^0(U) (dx_1 \wedge dx_2) \oplus \Omega^0(U) (dx_2 \wedge dx_3) \oplus \Omega^0(U) (dx_3 \wedge dx_1).$$

Define  $\Omega^3(U)$  to be the free  $\Omega^0(U)$ -module of rank 1 with basis

$$\text{vol} := dx_1 \wedge dx_2 \wedge dx_3, \quad \Omega^3(U) := \Omega^0(U) \text{vol}.$$

**Definition 2.4.3** (Wedge product on coordinate forms). Define a  $\mathbb{k}$ -bilinear map

$$\wedge : \Omega^p(U) \times \Omega^q(U) \rightarrow \Omega^{p+q}(U)$$

by imposing the following axioms:

1.  $\wedge$  is  $\Omega^0(U)$ -bilinear in the sense that for  $f \in \Omega^0(U)$  and forms  $\alpha, \beta$

$$(f\alpha) \wedge \beta = f(\alpha \wedge \beta), \quad \alpha \wedge (f\beta) = f(\alpha \wedge \beta);$$

2.  $\wedge$  is associative;

3. on basis elements it is alternating:

$$dx_i \wedge dx_i = 0, \quad dx_i \wedge dx_j = -dx_j \wedge dx_i \quad (i \neq j);$$

4.  $1 \in \Omega^0(U)$  acts as a unit:  $1 \wedge \alpha = \alpha = \alpha \wedge 1$  for all  $\alpha$ .

**Remark 2.4.4** (Coordinate expansions). Every  $\alpha \in \Omega^1(U)$  has a unique expression

$$\alpha = a_1 dx_1 + a_2 dx_2 + a_3 dx_3 \quad (a_i \in \Omega^0(U)),$$

every  $\beta \in \Omega^2(U)$  has a unique expression

$$\beta = b_{12} dx_1 \wedge dx_2 + b_{23} dx_2 \wedge dx_3 + b_{31} dx_3 \wedge dx_1 \quad (b_{ij} \in \Omega^0(U)),$$

and every  $\gamma \in \Omega^3(U)$  has a unique expression  $\gamma = c \text{vol}$  with  $c \in \Omega^0(U)$ .

### 2.4.2 Formal definition of the exterior derivative

**Definition 2.4.5** (Exterior derivative in coordinates). Define  $\mathbb{k}$ -linear maps

$$d : \Omega^k(U) \rightarrow \Omega^{k+1}(U) \quad (k = 0, 1, 2)$$

by the following coordinate rules.

1. If  $f \in \Omega^0(U)$ , define

$$df := \partial_1 f dx_1 + \partial_2 f dx_2 + \partial_3 f dx_3 \in \Omega^1(U).$$

2. If  $\alpha = a_1 dx_1 + a_2 dx_2 + a_3 dx_3 \in \Omega^1(U)$ , define

$$\begin{aligned} d\alpha &:= da_1 \wedge dx_1 + da_2 \wedge dx_2 + da_3 \wedge dx_3 \\ &= (\partial_2 a_1 - \partial_1 a_2) dx_1 \wedge dx_2 + (\partial_3 a_2 - \partial_2 a_3) dx_2 \wedge dx_3 + (\partial_1 a_3 - \partial_3 a_1) dx_3 \wedge dx_1 \in \Omega^2(U). \end{aligned}$$

3. If  $\beta = b_{12} dx_1 \wedge dx_2 + b_{23} dx_2 \wedge dx_3 + b_{31} dx_3 \wedge dx_1 \in \Omega^2(U)$ , define

$$\begin{aligned} d\beta &:= db_{12} \wedge dx_1 \wedge dx_2 + db_{23} \wedge dx_2 \wedge dx_3 + db_{31} \wedge dx_3 \wedge dx_1 \\ &= (\partial_3 b_{12} + \partial_1 b_{23} + \partial_2 b_{31}) dx_1 \wedge dx_2 \wedge dx_3 \in \Omega^3(U). \end{aligned}$$

Finally define  $d : \Omega^3(U) \rightarrow 0$  to be the zero map.

**Proposition 2.4.6** (Graded Leibniz rule). *For all  $p, q \geq 0$  with  $p + q \leq 3$ , and all  $\alpha \in \Omega^p(U)$ ,  $\beta \in \Omega^q(U)$ , one has*

$$d(\alpha \wedge \beta) = d\alpha \wedge \beta + (-1)^p \alpha \wedge d\beta.$$

**Proposition 2.4.7** ( $d^2 = 0$ ). *The maps  $d : \Omega^k(U) \rightarrow \Omega^{k+1}(U)$  satisfy  $d \circ d = 0$ , i.e.*

$$d^2 = 0 : \Omega^k(U) \rightarrow \Omega^{k+2}(U) \quad \text{for } k = 0, 1, 2.$$

*Proof.* It suffices to check  $d(df) = 0$  for  $f \in \Omega^0(U)$  and  $d(d\alpha) = 0$  for  $\alpha \in \Omega^1(U)$ . The coordinate formulas show each coefficient is a sum of mixed second derivatives which cancel by  $\partial_i \partial_j = \partial_j \partial_i$ .  $\square$

**Definition 2.4.8** (de Rham cochain complex and cohomology). The sequence

$$0 \rightarrow \Omega^0(U) \xrightarrow{d} \Omega^1(U) \xrightarrow{d} \Omega^2(U) \xrightarrow{d} \Omega^3(U) \rightarrow 0$$

is a cochain complex. Its cohomology vector spaces are

$$H_{\text{dR}}^k(U) := \text{Ker}(d : \Omega^k(U) \rightarrow \Omega^{k+1}(U)) / \text{im}(d : \Omega^{k-1}(U) \rightarrow \Omega^k(U)).$$

### 2.4.3 grad, curl, div as transported differentials

**Definition 2.4.9** (Vector-field spaces and vector-calculus differentials). Let  $V^0 := C^\infty(U; \mathbb{k})$ ,  $V^1 := C^\infty(U; \mathbb{k}^3)$ ,  $V^2 := C^\infty(U; \mathbb{k}^3)$ ,  $V^3 := C^\infty(U; \mathbb{k})$ . Define

$$\nabla : V^0 \rightarrow V^1, \quad \nabla \times : V^1 \rightarrow V^2, \quad \nabla \cdot : V^2 \rightarrow V^3$$

by

$$\begin{aligned} \nabla f &:= (\partial_1 f, \partial_2 f, \partial_3 f), \\ \nabla \times (P, Q, R) &:= (\partial_2 R - \partial_3 Q, \partial_3 P - \partial_1 R, \partial_1 Q - \partial_2 P), \\ \nabla \cdot (A, B, C) &:= \partial_1 A + \partial_2 B + \partial_3 C. \end{aligned}$$

**Definition 2.4.10** (Explicit identifications  $\Phi^k$ ). Equip  $U$  with the Euclidean metric and standard orientation. Define linear isomorphisms

$$\Phi^0 : V^0 \xrightarrow{\cong} \Omega^0(U), \quad \Phi^0(f) = f,$$

$$\Phi^1 : V^1 \xrightarrow{\cong} \Omega^1(U), \quad \Phi^1(P, Q, R) = P dx_1 + Q dx_2 + R dx_3,$$

$$\Phi^2 : V^2 \xrightarrow{\cong} \Omega^2(U), \quad \Phi^2(A, B, C) = A dx_2 \wedge dx_3 + B dx_3 \wedge dx_1 + C dx_1 \wedge dx_2,$$

$$\Phi^3 : V^3 \xrightarrow{\cong} \Omega^3(U), \quad \Phi^3(h) = h dx_1 \wedge dx_2 \wedge dx_3.$$

**Proposition 2.4.11** (Diagram commutativity: explicit proof). For all  $f \in V^0, F \in V^1, G \in V^2$ ,

$$\Phi^1(\nabla f) = d(\Phi^0(f)), \quad \Phi^2(\nabla \times F) = d(\Phi^1(F)), \quad \Phi^3(\nabla \cdot G) = d(\Phi^2(G)).$$

Equivalently, the following diagram commutes:

$$\begin{array}{ccccccccc} 0 & \longrightarrow & V^0 & \xrightarrow{\nabla} & V^1 & \xrightarrow{\nabla \times} & V^2 & \xrightarrow{\nabla \cdot} & V^3 & \longrightarrow & 0 \\ & & \Phi^0 \downarrow \cong & & \Phi^1 \downarrow \cong & & \Phi^2 \downarrow \cong & & \Phi^3 \downarrow \cong & & \\ 0 & \longrightarrow & \Omega^0(U) & \xrightarrow{d} & \Omega^1(U) & \xrightarrow{d} & \Omega^2(U) & \xrightarrow{d} & \Omega^3(U) & \longrightarrow & 0. \end{array}$$

*Proof.* (i) **grad.** For  $f \in V^0$ ,

$$d(\Phi^0(f)) = df = \partial_1 f dx_1 + \partial_2 f dx_2 + \partial_3 f dx_3 = \Phi^1(\nabla f).$$

(ii) **curl.** Let  $F = (P, Q, R) \in V^1$ . Then  $\Phi^1(F) = P dx_1 + Q dx_2 + R dx_3$ . Hence

$$\begin{aligned} d(\Phi^1(F)) &= d(P) \wedge dx_1 + d(Q) \wedge dx_2 + d(R) \wedge dx_3 \\ &= (\partial_2 R - \partial_3 Q) dx_2 \wedge dx_3 + (\partial_3 P - \partial_1 R) dx_3 \wedge dx_1 + (\partial_1 Q - \partial_2 P) dx_1 \wedge dx_2. \end{aligned}$$

By definition,

$$\nabla \times F = (\partial_2 R - \partial_3 Q, \partial_3 P - \partial_1 R, \partial_1 Q - \partial_2 P),$$

so

$$\Phi^2(\nabla \times F) = (\partial_2 R - \partial_3 Q) dx_2 \wedge dx_3 + (\partial_3 P - \partial_1 R) dx_3 \wedge dx_1 + (\partial_1 Q - \partial_2 P) dx_1 \wedge dx_2.$$

Thus  $d(\Phi^1(F)) = \Phi^2(\nabla \times F)$ .

(iii) **div.** Let  $G = (A, B, C) \in V^2$ . Then

$$\Phi^2(G) = A dx_2 \wedge dx_3 + B dx_3 \wedge dx_1 + C dx_1 \wedge dx_2.$$

Hence

$$\begin{aligned} d(\Phi^2(G)) &= d(A) \wedge dx_2 \wedge dx_3 + d(B) \wedge dx_3 \wedge dx_1 + d(C) \wedge dx_1 \wedge dx_2 \\ &= (\partial_1 A + \partial_2 B + \partial_3 C) dx_1 \wedge dx_2 \wedge dx_3 = \Phi^3(\nabla \cdot G). \end{aligned}$$

□

### 2.4.4 Cohomology on the vector-calculus side

**Definition 2.4.12** (Cohomology of grad–curl–div). Define  $d^0 := \nabla$ ,  $d^1 := \nabla \times$ ,  $d^2 := \nabla \cdot$ , and extend by  $d^{-1} = 0$ ,  $d^3 = 0$ . Define

$$Z^n := \text{Ker}(d^n), \quad B^n := \text{im}(d^{n-1}), \quad H^n(V^\bullet) := Z^n / B^n \quad (n = 0, 1, 2, 3).$$

Equivalently,

$$\begin{aligned} H^0(V^\bullet) &= \text{Ker}(\nabla), \\ H^1(V^\bullet) &= \text{Ker}(\nabla \times) / \text{im}(\nabla), \\ H^2(V^\bullet) &= \text{Ker}(\nabla \cdot) / \text{im}(\nabla \times), \\ H^3(V^\bullet) &= C^\infty(U; \mathbb{k}) / \text{im}(\nabla \cdot). \end{aligned}$$

**Corollary 2.4.13** (Identification with de Rham cohomology). *For each  $k \in \{0, 1, 2, 3\}$ , the isomorphisms  $\Phi^k$  induce canonical isomorphisms*

$$H^k(V^\bullet) \cong H_{\text{dR}}^k(U).$$

**Remark 2.4.14** (Contractible domains). If  $U$  is contractible, then  $H_{\text{dR}}^k(U) = 0$  for  $k \geq 1$  and (if  $U$  is connected)  $H_{\text{dR}}^0(U) \cong \mathbb{k}$ . Consequently  $H^1(V^\bullet) = H^2(V^\bullet) = H^3(V^\bullet) = 0$  and  $H^0(V^\bullet) \cong \mathbb{k}$ .

## 2.5 Cochain complexes of vector spaces

**Definition 2.5.1** (Graded vector space). Fix a field  $\mathbb{k}$ . A  $\mathbb{Z}$ -graded  $\mathbb{k}$ -vector space is a family  $V^\bullet = \{V^n\}_{n \in \mathbb{Z}}$  of  $\mathbb{k}$ -vector spaces.

**Definition 2.5.2** (Cochain complex). A **cochain complex of  $\mathbb{k}$ -vector spaces** is a pair  $(V^\bullet, d)$  where

1.  $V^\bullet = \{V^n\}_{n \in \mathbb{Z}}$  is a  $\mathbb{Z}$ -graded  $\mathbb{k}$ -vector space;
2.  $d = \{d^n\}_{n \in \mathbb{Z}}$  is a family of  $\mathbb{k}$ -linear maps

$$d^n : V^n \longrightarrow V^{n+1} \quad (n \in \mathbb{Z})$$

such that

$$d^{n+1} \circ d^n = 0 \quad \text{for all } n \in \mathbb{Z}.$$

In diagrammatic form, one writes

$$\cdots \xrightarrow{d^{n-2}} V^{n-1} \xrightarrow{d^{n-1}} V^n \xrightarrow{d^n} V^{n+1} \xrightarrow{d^{n+1}} \cdots, \quad d^n d^{n-1} = 0.$$

**Remark 2.5.3** (The condition  $d^{n+1}d^n = 0$ ). For each  $n \in \mathbb{Z}$  the equality  $d^{n+1} \circ d^n = 0$  is an equality of  $\mathbb{k}$ -linear maps  $V^n \rightarrow V^{n+2}$ . Equivalently,

$$\forall v \in V^n, \quad d^{n+1}(d^n(v)) = 0.$$

## 2.6 Cocycles, coboundaries, and cohomology

**Definition 2.6.1** (Cocycles and coboundaries). Let  $(V^\bullet, d)$  be a cochain complex. For each  $n \in \mathbb{Z}$  define the subspaces

$$Z^n(V^\bullet) := \ker(d^n) \subseteq V^n, \quad B^n(V^\bullet) := \operatorname{im}(d^{n-1}) \subseteq V^n.$$

Elements of  $Z^n(V^\bullet)$  are called  $n$ -**cocycles**, and elements of  $B^n(V^\bullet)$  are called  $n$ -**coboundaries**.

**Lemma 2.6.2** (Coboundaries are cocycles). *For every  $n \in \mathbb{Z}$  one has  $B^n(V^\bullet) \subseteq Z^n(V^\bullet)$ .*

*Proof.* Let  $x \in B^n(V^\bullet)$ . By definition,  $\exists y \in V^{n-1}$  such that  $x = d^{n-1}(y)$ . Then

$$d^n(x) = d^n(d^{n-1}(y)) = (d^n \circ d^{n-1})(y) = 0,$$

hence  $x \in \ker(d^n) = Z^n(V^\bullet)$ . □

**Definition 2.6.3** (Cohomology). Let  $(V^\bullet, d)$  be a cochain complex. For each  $n \in \mathbb{Z}$  the  $n$ -**th cohomology vector space** is the quotient

$$H^n(V^\bullet) := Z^n(V^\bullet) / B^n(V^\bullet) = \ker(d^n) / \operatorname{im}(d^{n-1}).$$

**Remark 2.6.4** (Cohomology classes and equivalence relation). Fix  $n \in \mathbb{Z}$ . Define a binary relation  $\sim$  on  $Z^n(V^\bullet)$  by

$$z \sim z' \iff z - z' \in B^n(V^\bullet).$$

Then  $\sim$  is an equivalence relation on  $Z^n(V^\bullet)$  (reflexive, symmetric, transitive), and the quotient set  $Z^n(V^\bullet)/\sim$  inherits a unique  $\mathbb{k}$ -vector space structure for which the canonical projection  $Z^n(V^\bullet) \rightarrow Z^n(V^\bullet)/\sim$  is  $\mathbb{k}$ -linear. Under this identification one has

$$Z^n(V^\bullet)/\sim \cong Z^n(V^\bullet) / B^n(V^\bullet) = H^n(V^\bullet).$$

## 2.7 Functoriality

**Definition 2.7.1** (Morphism of cochain complexes). Let  $(V^\bullet, d_V)$  and  $(W^\bullet, d_W)$  be cochain complexes of  $\mathbb{k}$ -vector spaces. A **morphism of cochain complexes** (or **cochain map**)  $f : (V^\bullet, d_V) \rightarrow (W^\bullet, d_W)$  is a family of  $\mathbb{k}$ -linear maps

$$f^n : V^n \rightarrow W^n \quad (n \in \mathbb{Z})$$

such that

$$d_W^n \circ f^n = f^{n+1} \circ d_V^n \quad \text{for all } n \in \mathbb{Z}.$$

**Proposition 2.7.2** (Induced map on cohomology). Let  $f : (V^\bullet, d_V) \rightarrow (W^\bullet, d_W)$  be a cochain map. For each  $n \in \mathbb{Z}$  there exists a unique  $\mathbb{k}$ -linear map

$$H^n(f) : H^n(V^\bullet) \rightarrow H^n(W^\bullet)$$

such that for every  $z \in Z^n(V^\bullet)$  one has

$$H^n(f)([z]) = [f^n(z)].$$

*Proof.* First, if  $z \in Z^n(V^\bullet)$  then

$$d_W^n(f^n(z)) = (d_W^n \circ f^n)(z) = (f^{n+1} \circ d_V^n)(z) = f^{n+1}(0) = 0,$$

so  $f^n(z) \in Z^n(W^\bullet)$  and  $[f^n(z)]$  is defined.

To check well-definedness on cohomology classes: if  $[z] = [z']$  in  $H^n(V^\bullet)$  then  $z - z' \in B^n(V^\bullet)$ , so  $\exists y \in V^{n-1}$  with  $z - z' = d_V^{n-1}(y)$ . Hence

$$f^n(z) - f^n(z') = f^n(z - z') = f^n(d_V^{n-1}(y)) = (f^n \circ d_V^{n-1})(y) = (d_W^{n-1} \circ f^{n-1})(y) \in \text{im}(d_W^{n-1}) = B^n(W^\bullet).$$

Thus  $[f^n(z)] = [f^n(z')]$  in  $H^n(W^\bullet)$ , so the formula defines a function  $H^n(f)$ .

Linearity follows because the quotient map  $Z^n(V^\bullet) \rightarrow H^n(V^\bullet)$  is linear and  $f^n$  is linear. Uniqueness holds because every class in  $H^n(V^\bullet)$  has a cocycle representative.  $\square$

## 2.8 Finite-dimensional dimension formula

**Proposition 2.8.1** (Dimension identity). Assume each  $V^n$  is finite-dimensional. Then for all  $n \in \mathbb{Z}$ ,

$$\dim_{\mathbb{k}} H^n(V^\bullet) = \dim_{\mathbb{k}} \ker(d^n) - \dim_{\mathbb{k}} \text{im}(d^{n-1}) = \text{nullity}(d^n) - \text{rank}(d^{n-1}).$$

*Proof.* Since  $B^n(V^\bullet) \subseteq Z^n(V^\bullet)$ , the quotient  $H^n(V^\bullet) = Z^n/B^n$  is a vector space and

$$\dim_{\mathbb{k}} H^n(V^\bullet) = \dim_{\mathbb{k}} Z^n(V^\bullet) - \dim_{\mathbb{k}} B^n(V^\bullet).$$

By definition  $Z^n = \ker(d^n)$  and  $B^n = \text{im}(d^{n-1})$ , giving the stated formula.  $\square$

**Example 2.8.2** (Two-step complex). Let  $V^0, V^1, V^2$  be  $\mathbb{k}$ -vector spaces and let  $d^0 : V^0 \rightarrow V^1$ ,  $d^1 : V^1 \rightarrow V^2$  be linear maps satisfying  $d^1 d^0 = 0$ . Extend by  $V^n = 0$  for  $n \notin \{0, 1, 2\}$  and  $d^n = 0$  otherwise. Then

$$H^0 \cong \ker(d^0), \quad H^1 \cong \ker(d^1)/\text{im}(d^0), \quad H^2 \cong V^2/\text{im}(d^1),$$

and  $H^n = 0$  for  $n \notin \{0, 1, 2\}$ .



**Definition 2.8.3** (Graded object). Let  $\mathcal{A}$  be an abelian category. A  $\mathbb{Z}$ -**graded object** of  $\mathcal{A}$  is a family  $A^\bullet = \{A^k\}_{k \in \mathbb{Z}}$  of objects of  $\mathcal{A}$ .

**Definition 2.8.4** (Cochain complex). A **cochain complex** in  $\mathcal{A}$  is a pair  $(A^\bullet, d)$  consisting of a  $\mathbb{Z}$ -graded object  $A^\bullet$  and morphisms

$$d^k : A^k \longrightarrow A^{k+1} \quad (k \in \mathbb{Z})$$

such that

$$d^{k+1} \circ d^k = 0 \quad \text{for all } k \in \mathbb{Z}.$$

We write the complex as

$$\cdots \xrightarrow{d^{k-2}} A^{k-1} \xrightarrow{d^{k-1}} A^k \xrightarrow{d^k} A^{k+1} \xrightarrow{d^{k+1}} \cdots.$$

**Definition 2.8.5** (Morphisms of cochain complexes). Let  $(A^\bullet, d_A)$  and  $(B^\bullet, d_B)$  be cochain complexes in  $\mathcal{A}$ . A **morphism of complexes** (or **cochain map**)  $f : (A^\bullet, d_A) \rightarrow (B^\bullet, d_B)$  is a family of morphisms

$$f^k : A^k \rightarrow B^k \quad (k \in \mathbb{Z})$$

such that

$$d_B^k \circ f^k = f^{k+1} \circ d_A^k \quad \text{for all } k \in \mathbb{Z}.$$

## 2.9 Cocycles, coboundaries, and cohomology

**Definition 2.9.1** (Cocycles and coboundaries). Let  $(A^\bullet, d)$  be a cochain complex in an abelian category  $\mathcal{A}$ . Define

$$Z^k(A^\bullet) := \ker(d^k) \subseteq A^k, \quad B^k(A^\bullet) := \operatorname{im}(d^{k-1}) \subseteq A^k.$$

**Lemma 2.9.2** (Boundaries are cycles). *For every  $k \in \mathbb{Z}$  one has  $B^k(A^\bullet) \subseteq Z^k(A^\bullet)$ .*

*Proof.* Let  $x \in B^k(A^\bullet)$ . Then  $x = d^{k-1}(y)$  for some  $y \in A^{k-1}$ , hence

$$d^k(x) = d^k(d^{k-1}(y)) = (d^k \circ d^{k-1})(y) = 0$$

by the defining condition  $d^k \circ d^{k-1} = 0$ . Therefore  $x \in \ker(d^k) = Z^k(A^\bullet)$ .  $\square$

**Definition 2.9.3** (Cohomology). The  $k$ -th **cohomology object** of  $(A^\bullet, d)$  is

$$H^k(A^\bullet) := Z^k(A^\bullet) / B^k(A^\bullet) = \ker(d^k) / \operatorname{im}(d^{k-1}).$$

**Remark 2.9.4** (Cohomology classes). If  $\mathcal{A} = \mathbf{Ab}$  (or  $R\text{-Mod}$ ), elements of  $H^k(A^\bullet)$  are classes  $[\alpha]$  with  $\alpha \in Z^k(A^\bullet)$ , and  $[\alpha] = [\alpha']$  iff  $\alpha - \alpha' \in B^k(A^\bullet)$ , i.e. iff  $\alpha - \alpha' = d^{k-1}\beta$  for some  $\beta \in A^{k-1}$ .

## 2.10 Exactness

**Definition 2.10.1** (Exactness). A cochain complex  $(A^\bullet, d)$  is **exact at  $A^k$**  if

$$\operatorname{im}(d^{k-1}) = \ker(d^k).$$

It is **exact** if it is exact at every degree.

**Proposition 2.10.2** (Exactness and vanishing cohomology). *A cochain complex  $(A^\bullet, d)$  is exact if and only if  $H^k(A^\bullet) = 0$  for all  $k \in \mathbb{Z}$ .*

*Proof.* By definition,

$$H^k(A^\bullet) = 0 \iff \ker(d^k) = \operatorname{im}(d^{k-1}).$$

Thus vanishing of all cohomology objects is equivalent to exactness in every degree.  $\square$

## 2.11 Homotopy of cochain maps

**Definition 2.11.1** (Cochain homotopy). Let  $f, g : (A^\bullet, d_A) \rightarrow (B^\bullet, d_B)$  be cochain maps. A **cochain homotopy** from  $f$  to  $g$  is a family of morphisms

$$h^k : A^k \rightarrow B^{k-1} \quad (k \in \mathbb{Z})$$

such that

$$f^k - g^k = d_B^{k-1} \circ h^k + h^{k+1} \circ d_A^k \quad \text{for all } k \in \mathbb{Z}.$$

We write  $f \simeq g$  if there exists such a homotopy.

**Proposition 2.11.2** (Homotopic maps induce the same map on cohomology). *If  $f \simeq g$ , then  $H^k(f) = H^k(g)$  for all  $k \in \mathbb{Z}$ .*

*Proof.* Let  $\alpha \in Z^k(A^\bullet)$ , so  $d_A^k(\alpha) = 0$ . Then

$$(f^k - g^k)(\alpha) = d_B^{k-1}(h^k(\alpha)) + h^{k+1}(d_A^k(\alpha)) = d_B^{k-1}(h^k(\alpha)),$$

so  $f^k(\alpha) - g^k(\alpha) \in \text{im}(d_B^{k-1}) = B^k(B^\bullet)$ . Hence  $[f^k(\alpha)] = [g^k(\alpha)]$  in  $H^k(B^\bullet)$ .  $\square$

## 2.12 Mapping cone and long exact sequence

**Definition 2.12.1** (Shift). Given a complex  $(A^\bullet, d_A)$ , its **shift**  $A[1]^\bullet$  is defined by

$$A[1]^k := A^{k+1}, \quad d_{A[1]}^k := -d_A^{k+1}.$$

**Definition 2.12.2** (Mapping cone). Let  $f : (A^\bullet, d_A) \rightarrow (B^\bullet, d_B)$  be a cochain map. The **mapping cone**  $\text{Cone}(f)$  is the complex with

$$\text{Cone}(f)^k := B^k \oplus A^{k+1}$$

and differential

$$d_{\text{Cone}(f)}^k(b, a) := (d_B^k(b) + f^{k+1}(a), -d_A^{k+1}(a)).$$

**Lemma 2.12.3.**  $\text{Cone}(f)$  is a cochain complex, i.e.  $d_{\text{Cone}(f)}^{k+1} \circ d_{\text{Cone}(f)}^k = 0$ .

*Proof.* A direct computation using  $d_B \circ d_B = 0$ ,  $d_A \circ d_A = 0$ , and  $d_B \circ f = f \circ d_A$ .  $\square$

**Proposition 2.12.4** (Short exact sequence of complexes). *There is a natural short exact sequence of complexes*

$$0 \longrightarrow B^\bullet \xrightarrow{i} \text{Cone}(f)^\bullet \xrightarrow{p} A[1]^\bullet \longrightarrow 0,$$

where  $i(b) = (b, 0)$  and  $p(b, a) = a$  in each degree.

**Theorem 2.12.5** (Long exact sequence in cohomology). *Let  $0 \rightarrow X^\bullet \rightarrow Y^\bullet \rightarrow Z^\bullet \rightarrow 0$  be a short exact sequence of cochain complexes in an abelian category. Then there exist connecting morphisms  $\delta^k : H^k(Z^\bullet) \rightarrow H^{k+1}(X^\bullet)$  such that*

$$\cdots \rightarrow H^k(X^\bullet) \rightarrow H^k(Y^\bullet) \rightarrow H^k(Z^\bullet) \xrightarrow{\delta^k} H^{k+1}(X^\bullet) \rightarrow H^{k+1}(Y^\bullet) \rightarrow \cdots$$

is exact.

**Remark 2.12.6** (Explicit connecting morphism in  $\text{Ab}$  or  $R\text{-Mod}$ ). Suppose  $0 \rightarrow X^\bullet \xrightarrow{u} Y^\bullet \xrightarrow{v} Z^\bullet \rightarrow 0$  is degreewise exact. Given  $[z] \in H^k(Z^\bullet)$  with  $z \in Z^k(Z^\bullet)$ , choose  $y \in Y^k$  with  $v(y) = z$ . Then  $v(d_Y^k y) = d_Z^k(v(y)) = d_Z^k(z) = 0$ , hence  $d_Y^k y \in \ker(v) = \text{im}(u)$ . Choose  $x \in X^{k+1}$  with  $u(x) = d_Y^k y$  and set  $\delta^k([z]) := [x] \in H^{k+1}(X^\bullet)$ . One checks  $\delta^k$  is well-defined and yields exactness.

## 2.13 Examples

**Example 2.13.1** (de Rham complex). For a smooth manifold  $M$ , the graded  $\mathbb{R}$ -vector space  $\Omega^\bullet(M)$  with exterior derivative  $d : \Omega^k(M) \rightarrow \Omega^{k+1}(M)$  satisfies  $d \circ d = 0$ , hence forms a cochain complex. Its cohomology is

$$H_{\text{dR}}^k(M) := \ker(d : \Omega^k(M) \rightarrow \Omega^{k+1}(M)) / \operatorname{im}(d : \Omega^{k-1}(M) \rightarrow \Omega^k(M)).$$

**Example 2.13.2** (Singular cochains). Let  $X$  be a topological space and  $G \in \mathbf{Ab}$ . Let  $C_k(X)$  be the singular chain group and define  $C^k(X; G) := \operatorname{Hom}(C_k(X), G)$ . The coboundary  $\delta : C^k(X; G) \rightarrow C^{k+1}(X; G)$  satisfies  $\delta^2 = 0$ . The cohomology  $H^k(C^\bullet(X; G))$  is the singular cohomology  $H^k(X; G)$ .

## **Chapter 3**

# **Elliptic Curve and Torus**

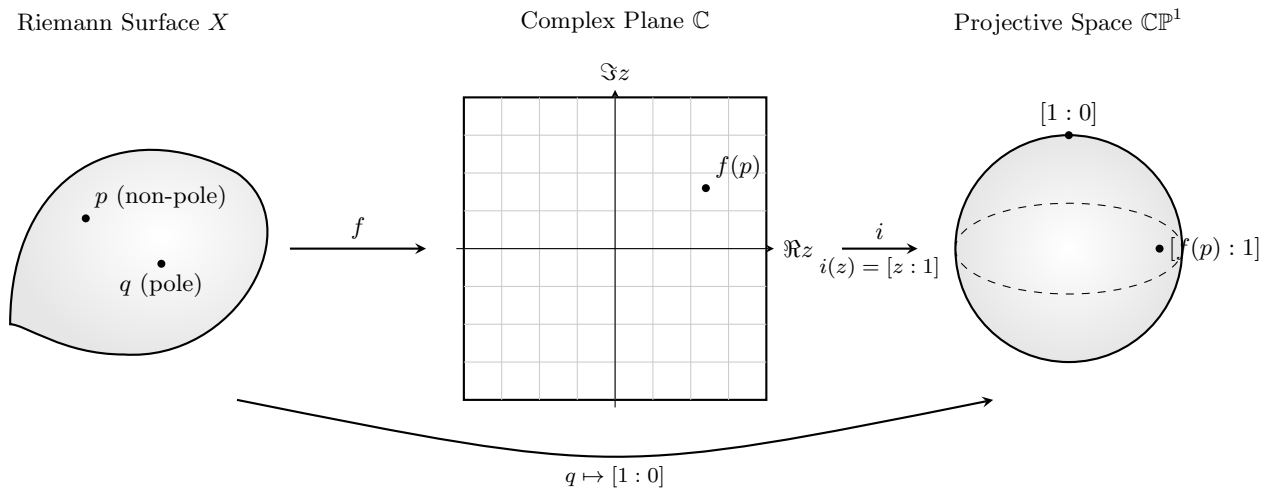
### **3.1 Note 1: Meromorphic Function and Order**

### 3.2 Note 2: Meromorphic $f \in \mathbb{C}^X$ and Holomorphic $F \in (\mathbb{CP}^1)^X$

Given a meromorphic  $f : X \rightarrow \mathbb{C}$  on a Riemann surface  $X$ , we define

$$F : X \longrightarrow \mathbb{C} \cup \{\infty\} (\simeq \mathbb{CP}^1)$$

$$p \longmapsto F(p) = \begin{cases} [1 : f(p)] & \text{if } p \text{ is not a pole} \\ [0 : 1] & \text{if } p \text{ is a pole} \end{cases}$$



In other word,

$$X \xrightarrow{f} \mathbb{C} \xrightarrow{i} \mathbb{CP}^1$$

$$p_{\text{non-pole}} \longmapsto f(p) \longmapsto [z_0 : z_1] = [1 : z_1/z_0] = [1 : f(p)]$$

$$q_{\text{pole}} \longmapsto [0 : 1] = \infty$$

### 3.2.1 Example 1: $X = \mathbb{CP}^1$ (Riemann sphere)

We view  $\mathbb{CP}^1$  as the Riemann sphere. On the affine chart

$$U_1 = \{[z_0 : z_1] \in \mathbb{CP}^1 \mid z_1 \neq 0\},$$

we use the coordinate  $z = z_0/z_1$ . The point at infinity is  $\infty = [1 : 0]$ .

On  $\mathbb{CP}^1$ , a meromorphic function is the same as a rational function. Take for instance

$$f(z) = \frac{z^2 - 1}{z - 2}.$$

This is meromorphic on  $\mathbb{CP}^1$ , with a simple pole at  $z = 2$ , and (possibly) a pole at  $\infty$ .

Define

$$F : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1, \quad F(p) = \begin{cases} [f(p) : 1], & p \text{ not a pole of } f, \\ [1 : 0], & p \text{ a pole of } f. \end{cases}$$

Concretely, for  $p = [z : 1]$  with  $z \neq 2$ ,

$$F([z : 1]) = [f(z) : 1] = \left[ \frac{z^2 - 1}{z - 2} : 1 \right],$$

and at the pole  $p = [2 : 1]$ ,

$$F([2 : 1]) = [1 : 0].$$

Similarly one checks the value at  $\infty = [1 : 0]$  using the behavior of  $f(z)$  as  $|z| \rightarrow \infty$ .

To see that  $F$  is holomorphic, we use the usual charts on  $\mathbb{CP}^1$ :

- **At a non-pole point  $p$ .** Suppose  $p$  is not a pole of  $f$ . Then  $f$  is holomorphic near  $p$  and finite there, so  $F(p) = [f(p) : 1] \in U_1$ . Let

$$w = \frac{z_0}{z_1} : U_1 \rightarrow \mathbb{C}$$

be the affine coordinate on  $U_1$ . In this chart,

$$(w \circ F)(q) = \frac{z_0}{z_1} \Big|_{F(q)} = f(q),$$

which is holomorphic in any local coordinate around  $p$ . Hence  $F$  is holomorphic at non-poles.

- **At a pole  $p$ .** Let  $p$  be a pole of order  $m > 0$ . Choose a local coordinate  $z$  on  $\mathbb{CP}^1$  with  $z(p) = 0$ . Then

$$f(z) = z^{-m} g(z), \quad g \text{ holomorphic, } g(0) \neq 0.$$

Here  $F(p) = [1 : 0]$ . Use the chart

$$U_0 = \{[z_0 : z_1] \in \mathbb{CP}^1 \mid z_0 \neq 0\},$$

with coordinate

$$u = \frac{z_1}{z_0} : U_0 \rightarrow \mathbb{C}.$$

For  $z \neq 0$  near  $p$ ,

$$F(z) = [f(z) : 1] = [z^{-m}g(z) : 1].$$

Multiplying homogeneous coordinates by  $z^m$  (which does not change the point in projective space), we get

$$[z^{-m}g(z) : 1] = [g(z) : z^m].$$

Thus, in the chart  $U_0$ ,

$$(u \circ F)(z) = \frac{z^m}{g(z)}.$$

Since  $g(z)$  is holomorphic with  $g(0) \neq 0$ , the function  $\frac{1}{g(z)}$  is holomorphic near 0, and hence

$$\frac{z^m}{g(z)}$$

is holomorphic near 0 (and vanishes to order  $m$ ). Therefore  $F$  is holomorphic at the pole  $p$ .

Since we have holomorphicity in local charts at every point of  $\mathbb{CP}^1$ ,  $F : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1$  is a holomorphic map.

### 3.2.2 Example 2: $X = \mathbb{C}/\Lambda$ (complex torus)

Let  $\Lambda \subset \mathbb{C}$  be a lattice and consider the complex torus

$$X = \mathbb{C}/\Lambda.$$

The quotient map is

$$\pi : \mathbb{C} \rightarrow X, \quad \pi(z) = [z].$$

A meromorphic function  $f : X \rightarrow \mathbb{C}$  corresponds to a  $\Lambda$ -periodic meromorphic function  $\tilde{f} : \mathbb{C} \rightarrow \mathbb{C}$  satisfying

$$\tilde{f}(z + \lambda) = \tilde{f}(z), \quad \forall \lambda \in \Lambda,$$

and

$$f([z]) = \tilde{f}(z).$$

A standard example is the Weierstrass  $\wp$ -function  $\wp : \mathbb{C} \rightarrow \mathbb{C}$ , which is  $\Lambda$ -periodic and meromorphic with double poles at lattice points. Thus it descends to a meromorphic

$$f : X \rightarrow \mathbb{C}, \quad f([z]) = \wp(z).$$

We define

$$F : X \rightarrow \mathbb{CP}^1, \quad F(p) = \begin{cases} [f(p) : 1], & p \text{ not a pole of } f, \\ [1 : 0], & p \text{ a pole of } f. \end{cases}$$

For our example  $f([z]) = \wp(z)$ :

- $\wp(z)$  has poles precisely at lattice points  $z \in \Lambda$ , which all represent the same point on the torus, usually denoted  $[0]$ .
- For  $[z] \neq [0]$ , we set  $F([z]) = [\wp(z) : 1]$ .
- At  $[0]$ , we set  $F([0]) = [1 : 0]$ .

### Local coordinate on the torus near a pole

To get a local coordinate near  $[0] \in X$ , choose a small disc  $D \subset \mathbb{C}$  around 0 such that  $\pi|_D : D \rightarrow \pi(D)$  is a biholomorphism. Then

$$\varphi : \pi(D) \rightarrow \mathbb{C}, \quad \varphi([z]) = z,$$

is a local coordinate on  $X$  near  $[0]$ .

The local behavior of  $\wp(z)$  at  $z = 0$  is

$$\wp(z) = \frac{1}{z^2} + \text{holomorphic terms},$$

so more precisely,

$$\wp(z) = z^{-2}g(z), \quad g(z) \text{ holomorphic, } g(0) \neq 0.$$

Thus, for the induced  $f$ ,

$$f([z]) = \wp(z) = z^{-2}g(z),$$

so  $f$  has a pole of order  $m = 2$  at  $[0]$ .

### Holomorphicity of $F$ at the pole $[0]$

As before, we use the chart around  $[1 : 0] \in \mathbb{CP}^1$ :

$$U_0 = \{[z_0 : z_1] \mid z_0 \neq 0\}, \quad u = \frac{z_1}{z_0} : U_0 \rightarrow \mathbb{C}.$$

For  $z \neq 0$  small, we have  $p = [z] \neq [0]$  and

$$F([z]) = [f([z]) : 1] = [\wp(z) : 1] = [z^{-2}g(z) : 1].$$

Multiplying the homogeneous coordinates by  $z^2$  gives

$$[z^{-2}g(z) : 1] = [g(z) : z^2].$$

So in the chart  $U_0$ ,

$$(u \circ F)([z]) = \frac{z^2}{g(z)}.$$

Since  $g(z)$  is holomorphic with  $g(0) \neq 0$ , the function  $\frac{1}{g(z)}$  is holomorphic near 0, and hence  $\frac{z^2}{g(z)}$  is holomorphic near 0 and vanishes at  $z = 0$ . In the local coordinate  $\varphi([z]) = z$  on  $X$ , the expression

$$u \circ F \circ \varphi^{-1}(z) = \frac{z^2}{g(z)}$$

is holomorphic, so  $F$  is holomorphic at the pole  $[0]$ .

At a non-pole point  $[z_0] \in X$ , the same argument as in Example 1 applies:  $f$  is holomorphic and finite, and in the affine chart

$$U_1 = \{[z_0 : z_1] \mid z_1 \neq 0\}, \quad w = \frac{z_0}{z_1},$$

we have

$$(w \circ F)([z]) = f([z]) = \wp(z),$$

which is holomorphic in the local coordinate on  $X$ .



### Conclusion

For both examples  $X = \mathbb{CP}^1$  and  $X = \mathbb{C}/\Lambda$ , the construction

$$f : X \rightarrow \mathbb{C} \text{ meromorphic} \quad \mapsto \quad F : X \rightarrow \mathbb{CP}^1, \quad F(p) = \begin{cases} [f(p) : 1], & p \text{ not a pole,} \\ [1 : 0], & p \text{ a pole,} \end{cases}$$

produces a holomorphic map  $F : X \rightarrow \mathbb{CP}^1$ . This concretely illustrates the general principle that a meromorphic function on a Riemann surface is the same as a holomorphic map to  $\mathbb{CP}^1$ .

We start with a meromorphic function

$$f : X \rightarrow \mathbb{C}$$

on a Riemann surface  $X$ , and define a map

$$F : X \rightarrow \mathbb{CP}^1$$

by

$$F(p) = \begin{cases} [f(p) : 1], & p \text{ not a pole of } f, \\ [1 : 0], & p \text{ a pole of } f. \end{cases}$$

You're asking: **why is this  $F$  holomorphic as a map of Riemann surfaces?**

## 1. Definition to remember

A map  $F : X \rightarrow Y$  between Riemann surfaces is **holomorphic** if, for every point  $p \in X$ , you can choose local coordinates

- $\varphi$ : neighborhood of  $p \rightarrow \mathbb{C}$ ,
- $\psi$ : neighborhood of  $F(p) \rightarrow \mathbb{C}$ ,

such that the coordinate expression

$$\psi \circ F \circ \varphi^{-1} : (\text{open in } \mathbb{C}) \rightarrow \mathbb{C}$$

is an ordinary holomorphic function.

So we need to check this around:

1. a point where  $f$  is holomorphic (no pole),
2. a point where  $f$  has a pole.

## 2. Case 1: $p$ is not a pole (easy)

If  $p$  is not a pole, then  $f$  is holomorphic near  $p$  and finite there.

- On  $X$ : choose any local coordinate  $z$  with  $z(p) = 0$ .
- On  $\mathbb{CP}^1$ : since  $F(p) = [f(p) : 1]$  has second coordinate  $\neq 0$ , it lies in the chart

$$U_1 = \{[z_0 : z_1] \mid z_1 \neq 0\}$$

with coordinate

$$w = \frac{z_0}{z_1} : U_1 \rightarrow \mathbb{C}.$$

Then on some neighborhood of  $p$ ,

$$(w \circ F)(q) = \frac{z_0}{z_1} \Big|_{F(q)} = \frac{f(q)}{1} = f(q),$$

which is holomorphic in  $z$ .

So  $\psi \circ F \circ \varphi^{-1} = f$  is holomorphic  $\Rightarrow F$  is holomorphic at non-pole points.

### 3. Case 2: $p$ is a pole of order $m > 0$

This is the interesting part.

Let  $p$  be a pole of  $f$  of order  $m$ . Choose a local coordinate  $z$  on  $X$  with  $z(p) = 0$ . By the definition of meromorphic:

$$f(z) = z^{-m}g(z),$$

where  $g$  is holomorphic and  $g(0) \neq 0$ .

By definition,

$$F(p) = [1 : 0] \in \mathbb{CP}^1.$$

Now we must look at a chart of  $\mathbb{CP}^1$  that contains  $[1 : 0]$ . That is:

$$U_0 = \{[z_0 : z_1] \mid z_0 \neq 0\},$$

with coordinate

$$u = \frac{z_1}{z_0} : U_0 \rightarrow \mathbb{C},$$

and in this chart  $[1 : 0]$  corresponds to  $u = 0$ .

For  $z \neq 0$  near  $p$ ,

$$F(z) = [f(z) : 1] = [z^{-m}g(z) : 1].$$

Multiply homogeneous coordinates by  $z^m$  (allowed in projective space):

$$[z^{-m}g(z) : 1] = [g(z) : z^m].$$

So in the chart  $U_0$  we have:

$$u(F(z)) = \frac{z^m}{g(z)}.$$

Now, check holomorphicity:

- $g(z)$  is holomorphic with  $g(0) \neq 0 \Rightarrow 1/g(z)$  is holomorphic near 0.
- $z^m$  is holomorphic.
- The product  $z^m \cdot \frac{1}{g(z)}$  is holomorphic near 0.

So

$$u \circ F(z) = \frac{z^m}{g(z)}$$

is an ordinary holomorphic function of  $z$  on a neighborhood of 0, and it extends to  $z = 0$  with value 0.

Thus, in local coordinates,

$$\psi \circ F \circ \varphi^{-1} = u \circ F$$

is holomorphic at  $z = 0$ . Therefore,  $F$  is **holomorphic at the pole  $p$** .

## 4. Conclusion

We have checked:

- At non-poles: in the chart  $U_1$ ,  $w \circ F = f$  is holomorphic.
- At poles: in the chart  $U_0$ ,  $u \circ F = z^m / g(z)$  is holomorphic.

So at **every** point  $p \in X$ , we can choose charts making the coordinate expression of  $F$  holomorphic. That's exactly the definition:

$$F : X \rightarrow \mathbb{CP}^1 \text{ is holomorphic.}$$

This is why we can safely say:

### 3.3 Note 3: The Isomorphism $\mathcal{M}(\mathbb{CP}^1) \simeq \mathbb{C}(x)$

We explain that the field of meromorphic functions on  $\mathbb{CP}^1$  is isomorphic to the field  $\mathbb{C}(x)$  of rational functions in one variable.

$$\mathcal{M}(X) = \left\{ \overline{i \circ f} \in (\mathbb{CP}^1)^X \mid f \text{ meromorphic on } X \right\},$$

$$\mathcal{M}(X) = \{ F : X \rightarrow \mathbb{CP}^1 \mid F \text{ holomorphic} \}.$$

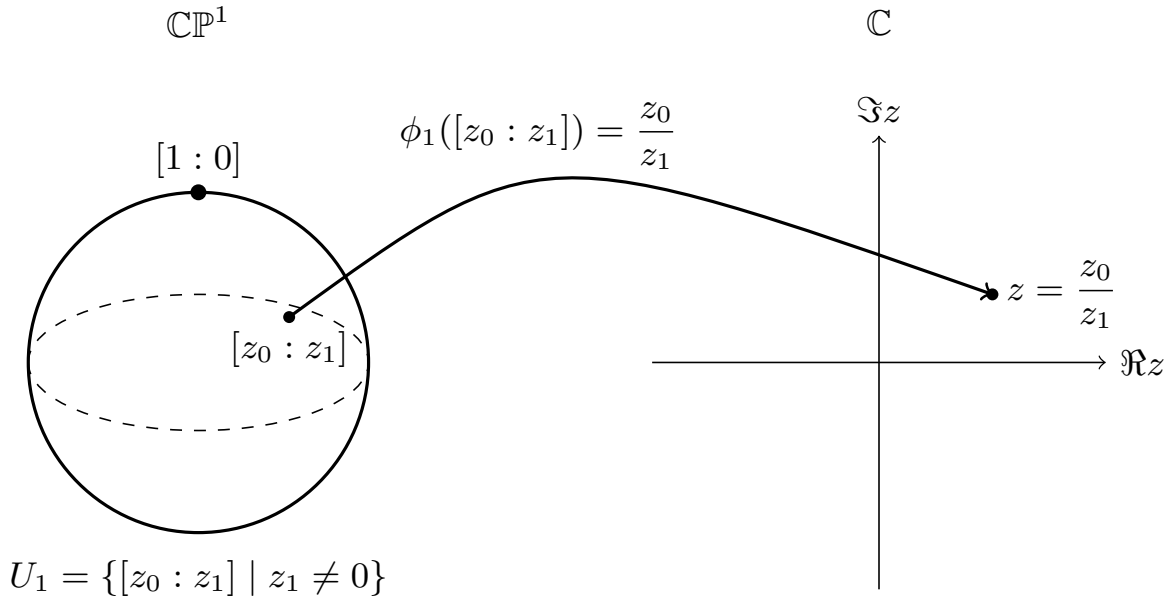
#### 3.3.1 Charts on $\mathbb{CP}^1$ and Field of Meromorphic Functions

View  $\mathbb{CP}^1$  as the Riemann sphere. Consider the standard affine chart

$$U_1 = \{ [z_0 : z_1] \in \mathbb{CP}^1 \mid z_1 \neq 0 \}$$

with coordinate map

$$\begin{aligned} \phi_1 : U_1 &\longrightarrow \mathbb{C} \\ [z_0 : z_1] &\longmapsto \frac{z_0}{z_1}. \end{aligned}$$



We write

$$x := \phi_1,$$

and think of  $x$  as the **coordinate function** on  $U_1$ . This function extends meromorphically to all of  $\mathbb{CP}^1$ , with a simple pole at  $\infty = [1 : 0]$ .

We define the field of meromorphic functions on  $\mathbb{CP}^1$  as

$$\mathcal{M}(\mathbb{CP}^1) = \{ F : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1 \mid F \text{ holomorphic} \},$$

viewing a meromorphic function as a holomorphic map into  $\mathbb{CP}^1$  (via the usual convention “finite value  $\mapsto [f(p) : 1]$ , pole  $\mapsto [1 : 0]$ ”).

On the other hand, the field  $\mathbb{C}(x)$  is

$$\mathbb{C}(x) = \left\{ \frac{p(x)}{q(x)} \mid p, q \in \mathbb{C}[x], q \neq 0 \right\} / \sim,$$

where  $\frac{p}{q} \sim \frac{p'}{q'}$  if  $p(x)q'(x) = p'(x)q(x)$ .

Here  $\phi_1$  is a biholomorphism between  $U_1$  and  $\mathbb{C}$ , its inverse is

$$\begin{aligned} \phi_1^{-1} : \mathbb{C} &\longrightarrow U_1 \\ z &\longmapsto [z : 1] \end{aligned} .$$

We'll write

$$x := \phi_1$$

and think of  $x$  as the **coordinate function** on  $U_1$ . It extends meromorphically to all of  $\mathbb{CP}^1$  with a simple pole at  $[1 : 0]$  (the point at infinity).

## 1. Describe both sides with $\phi_1$

### Side 1: $\mathcal{M}(\mathbb{CP}^1)$

We use the “holomorphic map to  $\mathbb{CP}^1$ ” definition:

$$\mathcal{M}(\mathbb{CP}^1) = \left\{ F : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1 \mid F \text{ holomorphic} \right\} .$$

We want to use  $\phi_1$ , so whenever the image of  $F$  lies in  $U_1$ , we can look at

$$\phi_1 \circ F : (\text{some open set}) \rightarrow \mathbb{C} .$$

That's just the “affine coordinate” of the value of  $F$ .

### Side 2: $\mathbb{C}(x)$

$$\mathbb{C}(x) = \left\{ \frac{p(x)}{q(x)} \mid p(x), q(x) \in \mathbb{C}[x], q(x) \neq 0 \right\} / \sim ,$$

where  $\frac{p}{q} \sim \frac{p'}{q'}$  iff  $p(x)q'(x) = p'(x)q(x)$ .

Here the symbol  $x$  is exactly your coordinate function

$$x = \phi_1 : U_1 \rightarrow \mathbb{C} .$$

## 2. Map $\mathbb{C}(x) \rightarrow \mathcal{M}(\mathbb{CP}^1)$ using $\phi_1$

Take a rational function

$$R(x) = \frac{p(x)}{q(x)} \in \mathbb{C}(x) .$$

**On the affine chart  $U_1$ :**

Given a point  $[z_0 : z_1] \in U_1$ , write

$$x([z_0 : z_1]) = \phi_1([z_0 : z_1]) = z_0/z_1 =: z .$$

We **define** a map  $F_R : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1$  by saying on  $U_1$ ,

$$\phi_1(F_R([z_0 : z_1])) = R(\phi_1([z_0 : z_1])) = R(z) .$$

In other words,

$$F_R|_{U_1} = \phi_1^{-1} \circ R \circ \phi_1.$$

Concretely:

$$F_R([z_0 : z_1]) = [R(z_0/z_1) : 1] \quad (\text{for } z_1 \neq 0, R(z) \neq \infty).$$

At points where  $R(z) = \infty$  (i.e.  $q(z) = 0$ ), we set

$$F_R([z_0 : z_1]) = [1 : 0].$$

This defines  $F_R$  on  $U_1 \cup \{\infty\}$ , but one must check it is **holomorphic at  $\infty$** . Using homogeneous polynomials is a cleaner way:

- Let  $\deg p \leq m$ ,  $\deg q \leq m$ . Define

$$P(z_0, z_1) = z_1^m p(z_0/z_1), \quad Q(z_0, z_1) = z_1^m q(z_0/z_1),$$

homogeneous of degree  $m$ .

- Then set

$$F_R([z_0 : z_1]) = \begin{cases} [P(z_0, z_1) : Q(z_0, z_1)], & Q(z_0, z_1) \neq 0, \\ [1 : 0], & Q(z_0, z_1) = 0. \end{cases}$$

This is well-defined and holomorphic on all of  $\mathbb{CP}^1$ . In the chart  $U_1$ , this is exactly  $\phi_1^{-1} \circ R \circ \phi_1$ . So we get a map

$$\Phi : \mathbb{C}(x) \rightarrow \mathcal{M}(\mathbb{CP}^1), \quad R \mapsto F_R.$$

### 3. Use $\phi_1$ to go backwards: from $F$ to $R(x)$

Now take any

$$F \in \mathcal{M}(\mathbb{CP}^1), \quad F : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1 \text{ holomorphic.}$$

We want to show: **there exists a unique rational function  $R(x) \in \mathbb{C}(x)$  such that**

$$F = F_R.$$

Using  $\phi_1$ :

1. Consider the open set where the image of  $F$  stays inside  $U_1$ :

$$V := F^{-1}(U_1) \subset \mathbb{CP}^1.$$

2. On  $V$ , define

$$f := \phi_1 \circ F : V \rightarrow \mathbb{C}.$$

In local coordinates,  $f$  is holomorphic. So  $f$  is a holomorphic function on the Riemann surface  $V$ .

3. The complement  $\mathbb{CP}^1 \setminus V = F^{-1}(\infty)$  is a **finite set** (preimages of the point  $[1 : 0]$  under a holomorphic map from a compact Riemann surface). At those points, we'll see  $f$  has poles. So in the chart  $\phi_1$ ,  $f$  is a **meromorphic function on  $\mathbb{C}$**  with finitely many poles.



Now, via  $\phi_1$ , we can identify  $\mathbb{CP}^1 \setminus \{\infty\}$  with  $\mathbb{C}$ . Under this,  $F$  becomes a meromorphic function

$$\tilde{f} : \mathbb{C} \rightarrow \mathbb{C} \cup \{\infty\},$$

which has only finitely many poles (coming from  $F^{-1}(\infty)$ ) and maybe a pole at  $\infty$ .

From standard complex analysis:

A meromorphic function on  $\mathbb{CP}^1$  (i.e. on  $\mathbb{C} \cup \{\infty\}$ ) is **rational**.

Concretely, we do the principal-part argument **in the coordinate**  $\phi_1$ :

- In the  $x$ -coordinate (i.e. using  $\phi_1$  as your chart),  $f(x)$  has Laurent expansions at each finite pole  $x = a_j$ .
- You build a rational function  $R(x)$  whose principal parts match those of  $f$  at all finite poles and at  $\infty$ .
- Then  $f(x) - R(x)$  is entire and holomorphic at  $\infty$ , so it's constant. So  $f(x) = R(x) + C$ , still rational.

Thus there exists some  $R(x) \in \mathbb{C}(x)$  such that

$$f(x) = R(x) \quad \text{as meromorphic functions on } \mathbb{C} \cup \{\infty\}.$$

But  $f = \phi_1 \circ F$  and  $R \circ \phi_1$  have the same values on  $U_1$ , so

$$\phi_1 \circ F = R \circ \phi_1 \quad \text{on } U_1,$$

hence

$$F|_{U_1} = \phi_1^{-1} \circ R \circ \phi_1 = F_R|_{U_1}.$$

Both  $F$  and  $F_R$  are holomorphic maps  $\mathbb{CP}^1 \rightarrow \mathbb{CP}^1$  that agree on the nonempty open set  $U_1$ , so by the identity theorem they agree everywhere:

$$F = F_R.$$

So every  $F \in \mathcal{M}(\mathbb{CP}^1)$  comes from a unique  $R \in \mathbb{C}(x)$ . That's surjectivity and injectivity of  $\Phi$ .

## 4. Summary in your language

Using your chart

$$\phi_1 : U_1 \rightarrow \mathbb{C}, \quad [z_0 : z_1] \mapsto z_0/z_1,$$

we have:

- Define  $x := \phi_1$ . This is a meromorphic function on  $\mathbb{CP}^1$  with one pole at  $[1 : 0]$ .
- Given  $R(x) \in \mathbb{C}(x)$ , we define a holomorphic map  $F_R : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1$  by

$$F_R = \phi_1^{-1} \circ R \circ \phi_1 \quad \text{on } U_1,$$

extended holomorphically to  $\infty$ .

- Given a holomorphic  $F : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1$ , its coordinate expression

$$f = \phi_1 \circ F \circ \phi_1^{-1} : \mathbb{C} \cup \{\infty\} \rightarrow \mathbb{C} \cup \{\infty\}$$

is a meromorphic function on the sphere, hence a rational function  $R(x)$ . Then  $F = F_R$ .

So precisely:

$$\boxed{\mathcal{M}(\mathbb{CP}^1) = \{F : \mathbb{CP}^1 \rightarrow \mathbb{CP}^1 \text{ holomorphic}\} \cong \{R(x) \in \mathbb{C}(x)\}}$$

and the chart  $\phi_1$  is the bridge that makes this identification explicit.