

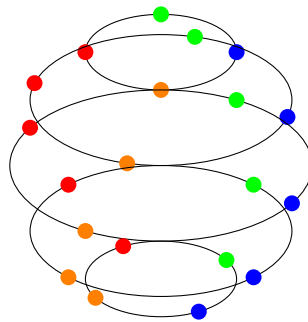
Abstract Algebra II

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We cover the following topics in this note.

- Group Action
- Cayley Theorem
- Normal Subgroups
- Normality of the Kernel



Group Action

Definition. Let $(G, *)$ be a group and let $X \neq \emptyset$. A **(left) group action** of G on X is a function

$$\cdot : G \times X \rightarrow X, \quad (g, x) \mapsto g \cdot x$$

satisfying the followings: for all $g, h \in G$ and all $x \in X$,

- (i) (Identity) $e \cdot x = x$, where $e \in G$ is the identity element of G ;
- (ii) (Compatibility) $(g * h) \cdot x = g \cdot (h \cdot x)$.

The pair (X, \cdot) (or simply X) is then called a G -set.

Note (Notation). If a group G acts on a set X , one commonly writes: $G \curvearrowright X$.

Remark. A right group action of G on X is a function $\cdot : X \times G \rightarrow X, \quad (x, g) \mapsto x \cdot g$ satisfying:

- (i) $x \cdot e = x$ for all $x \in X$;
- (ii) $(x \cdot g) \cdot h = x \cdot (gh)$ for all $g, h \in G, x \in X$.

Example (Scalar Multiplication on a Vector Space). Let \mathbb{F} be a field, and let $X = \mathbb{F}^n$ be the n -dimensional vector space over \mathbb{F} . Consider the multiplicative group of nonzero scalars in \mathbb{F} :

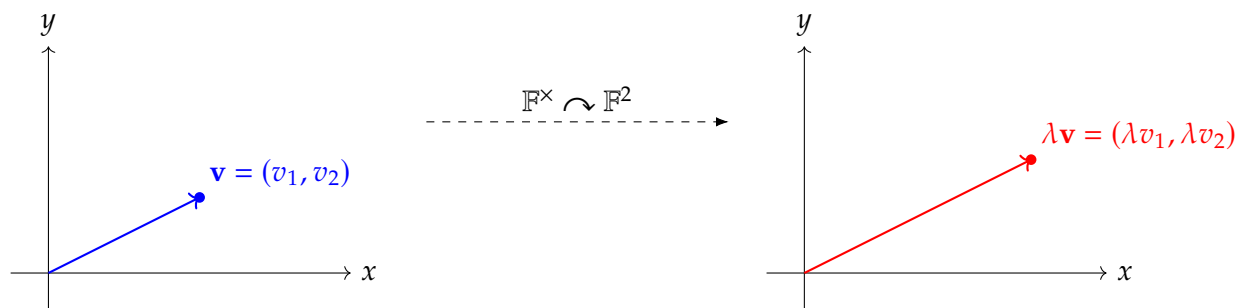
$$G = (\mathbb{F}^\times, \times), \quad \text{where } \mathbb{F}^\times = \mathbb{F} \setminus \{0\}.$$

We define an action $G \curvearrowright X$ by scalar multiplication:

$$\begin{aligned} \cdot &: \mathbb{F}^\times \times \mathbb{F}^n \longrightarrow \mathbb{F}^n \\ (\lambda, \mathbf{v}) &\longmapsto \lambda \cdot \mathbf{v} \end{aligned}$$

where the product $\lambda \cdot \mathbf{v}$ is defined componentwise. Then

- (i) $1 \cdot \mathbf{v} = \mathbf{v}$ for all $\mathbf{v} \in \mathbb{F}^n$.
- (ii) $(\lambda\mu) \cdot \mathbf{v} = \lambda \cdot (\mu \cdot \mathbf{v})$ for all $\lambda, \mu \in \mathbb{F}^\times, \mathbf{v} \in \mathbb{F}^n$.



Example (Conjugation Action on the Group Itself). Let G be any group, and consider $X = G$. Define an action of G on itself by conjugation:

$$G \curvearrowright G, \quad (g, x) \mapsto g \cdot x := g * x * g^{-1}.$$

Then

- (i) $e \cdot x = e * x * e^{-1} = x$ for all $x \in G$.
- (ii) Note that

$$\begin{aligned} (g * h) \cdot x &= (g * h) * x * (g * h)^{-1} \\ &= (g * h) * x * (h^{-1} * g^{-1}) \\ &= g * (h * x * h^{-1}) * g^{-1} \\ &= g * (h \cdot x) * g^{-1} \\ &= g \cdot (h \cdot x). \end{aligned}$$

Thus, this is a left group action.

Example (Trivial G -Set). Let G be any group and define the set $X = \{x\}$, a singleton. Define the action

$$G \curvearrowright X, \quad (g, x) \mapsto g \cdot x := x \quad \text{for all } g \in G.$$

This is the **trivial action**, where every group element acts as the identity on X :

- (i) $e \cdot x = x$.
- (ii) $(g * h) \cdot x = x = g \cdot (h \cdot x)$.

Example (Action on Coset Space G/H). Let $(G, *)$ be a group, and let $H \leq G$. Let $X = G/H$ be the set of left cosets of H in G , i.e.,

$$X = G/H = \{gH \mid g \in G\}.$$

Define an action

$$G \curvearrowright G/H, \quad (g, aH) \mapsto (ga)H.$$

This is well-defined because if $a_1H = a_2H$, then $a_1^{-1}a_2 \in H$, so: $ga_1H = ga_2H$. Since

- (i) $e \cdot aH = aH$;
- (ii) $(gh) \cdot aH = g \cdot (h \cdot aH)$.

Group Elements Act as Permutations

Proposition. Let G be a group action on a set X via a left action $G \curvearrowright X$, given by $(g, x) \mapsto g \cdot x$. Then for each $g \in G$, the map

$$\sigma_g : X \rightarrow X, \quad x \mapsto g \cdot x$$

is one-to-one and onto. That is, $\sigma_g \in \text{Sym}(X)$, the group of all permutations of X .

Proof. TBA

□

Group Actions Induce Permutation Representations

Theorem. Let G be a group action on a set X via a left group action $G \curvearrowright X$, $(g, x) \mapsto g \cdot x$. For each $g \in G$, define the bijection $\sigma_g : X \rightarrow X$ by $\sigma_g(x) := g \cdot x$. Then the map

$$\phi : G \rightarrow \text{Sym}(X), \quad g \mapsto \sigma_g,$$

is a **group homomorphism** from G to the symmetric group $\text{Sym}(X)$. In other words, for all $g, h \in G$,

$$\phi(g * h) = \sigma_{g * h} = \sigma_g \circ \sigma_h = \phi(g) \circ \phi(h).$$

Remark. A group action $G \curvearrowright X$ is equivalent to a group homomorphism $G \rightarrow \text{Sym}(X)$, i.e., a **permutation representation** of G .

Proof. TBA

□

Cayley Theorem

Theorem. Let G be a group. Consider the action of G on itself by left multiplication. For each $g \in G$, define

$$\sigma_g : G \longrightarrow G, \quad x \mapsto g \cdot x.$$

Then the map

$$\phi : G \longrightarrow \text{Sym}(G), \quad g \mapsto \sigma_g$$

is an **injective group homomorphism** (group monomorphism). In particular,

$$\phi(G) \simeq G \quad \text{and} \quad \phi(G) \leq \text{Sym}(G).$$

Proof. TBA

□

Normal Subgroups

Observation. Consider $4\mathbb{Z} \leq \mathbb{Z}$. Then

$$\mathbb{Z}/4\mathbb{Z} = \{0 + 4\mathbb{Z}, 1 + 4\mathbb{Z}, 2 + 4\mathbb{Z}, 3 + 4\mathbb{Z}\} = \{[0], [1], [2], [3]\}.$$

- $[0] + [1] = (0 + 4\mathbb{Z}) + (1 + 4\mathbb{Z}) \stackrel{\text{def.}}{=} (0 + 1) + 4\mathbb{Z} = 1 + 4\mathbb{Z} = [1].$
- $[1] + [2] = (1 + 4\mathbb{Z}) + (2 + 4\mathbb{Z}) \stackrel{\text{def.}}{=} (1 + 2) + 4\mathbb{Z} = 3 + 4\mathbb{Z} = [3].$
- $[1] + [3] = (1 + 4\mathbb{Z}) + (3 + 4\mathbb{Z}) \stackrel{\text{def.}}{=} (1 + 3) + 4\mathbb{Z} = 4 + 4\mathbb{Z} = 0 + 4\mathbb{Z} = [0].$

Existence of the Quotient Group

Proposition. Let $(G, *)$ be a group and let $H \leq G$ be a subgroup. Define a binary operation \boxtimes on the set of left cosets G/H by

$$(g * H) \boxtimes (g' * H) = (g * g') * H$$

where $g, g' \in G$. Then this operation is well-defined if and only if

$$g * h * g^{-1} \in H.$$

for all $g \in G, h \in H$.

Proof. TBA

□

Normal Subgroup

Definition. Let $(G, *)$ be a group and let $H \leq G$. We say that H is **normal** in G , written

$$H \trianglelefteq G,$$

if $g * h * g^{-1} \in H$ for any $g \in G$ and $h \in H$.

Remark. The set of (left) cosets G/H be a well-defined group structure via

$$(g * H) \boxtimes (k * H) = (g * k) * H,$$

making G/H the quotient group of G by H .

Equivalent Definitions of Normal Subgroup

Proposition. Let $(G, *)$ be a group and let $H \leq G$. The Following Are Equivalent:

- (1)^a H is normal in G , i.e., $H \trianglelefteq G$;
- (2)^b $g * h * g^{-1} \in H$ for all $g \in G, h \in H$;
- (3)^c $g * H * g^{-1} = H$ for all $g \in G$;
- (4)^d $g * H = H * g$ for all $g \in G$.

^aTerminology and Notation

^b(Elementwise Conjugation)

^c(Conjugation Invariance)

^d(Coset Equality)

Proof. ((2) \Rightarrow (3)) TBA

((3) \Rightarrow (4)) TBA

((4) \Rightarrow (2)) TBA

□

Normality of Kernel

Theorem. Let $\phi : (G, *) \longrightarrow (H, *')$ be a group homomorphism, and define its kernel by

$$\ker \phi = \{ g \in G : \phi(g) = e_H \} .$$

Then $\ker \phi$ is a normal subgroup of G ; that is, $\ker \phi \trianglelefteq G$.

Proof. Since ϕ is a homomorphism, for every $g \in G$ and every $k \in \ker \phi$ we have

$$\phi(g * k * g^{-1}) = \phi(g) *' \phi(k) *' \phi(g)^{-1} = \phi(g) *' e_H *' \phi(g)^{-1} = e_H,$$

so $g * k * g^{-1} \in \ker \phi$. Thus,

$$g * (\ker \phi) * g^{-1} = \ker \phi \quad \forall g \in G,$$

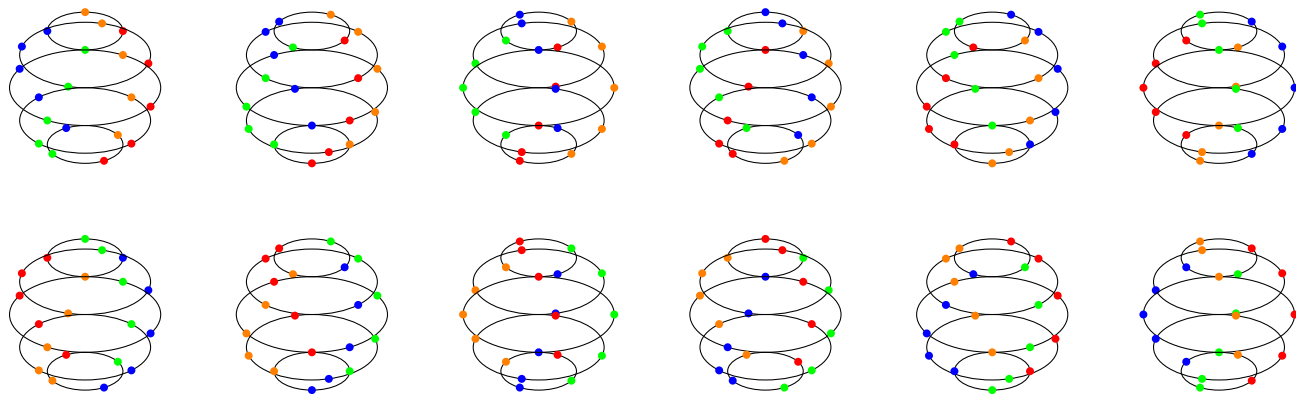
i.e. $\ker \phi$ is invariant under conjugation and hence normal in G . □

References

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- [2] 수학의 즐거움, Enjoying Math. “수학 공부, 기초부터 대학원 수학까지, 24. 추상대수학 (e) 정규부분군의 정의 def of normal subgroups” YouTube Video, 23:00. Published October 25, 2019. URL: <https://www.youtube.com/watch?v=3UJILZr4CNo>.

A Appendices

A.1 The Rotation Action of \mathbb{S}^1 on \mathbb{S}^2



Consider

$$\mathbb{S}^1 = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\} = \{e^{i\theta} : \theta \in \mathbb{R}\},$$

$$\mathbb{S}^2 = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 = 1\}.$$

Define the map

$$\Phi: \mathbb{S}^1 \times \mathbb{S}^2 \longrightarrow \mathbb{S}^2, \quad (e^{i\theta}, P) \mapsto \text{Rot}_\theta(P),$$

where, for each $e^{i\theta} \in \mathbb{S}^1$, define the rotation

$$\text{Rot}_\theta: \mathbb{S}^2 \longrightarrow \mathbb{S}^2, \quad \text{Rot}_\theta(x, y, z) = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \cos \theta + y \sin \theta \\ -x \sin \theta + y \cos \theta \\ z \end{pmatrix}.$$

Here, $\Phi(e^{i\theta}, P) = \text{Rot}_\theta(P)$. Then

(i) (Identity) The identity in \mathbb{S}^1 is $1 = e^{i \cdot 0}$. Since $\cos 0 = 1$, $\sin 0 = 0$, we have

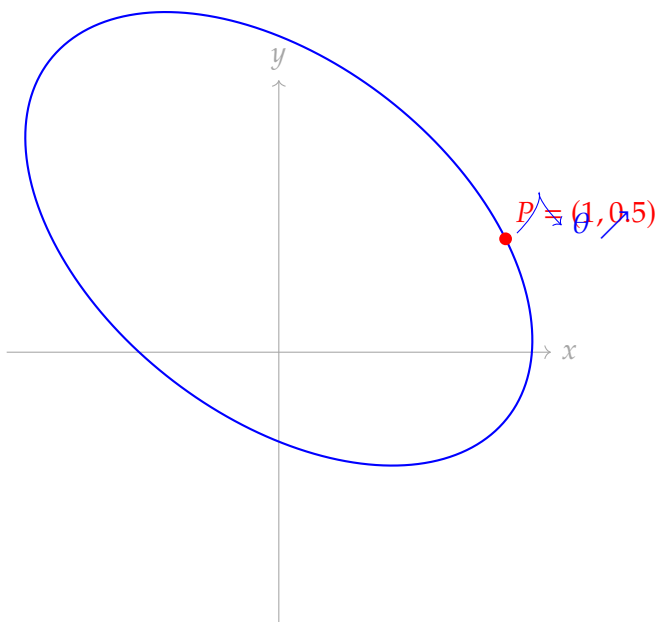
$$\Phi(1, P) = \text{Rot}_0(P) = (x, y, z) = P,$$

for every $P \in \mathbb{S}^2$.

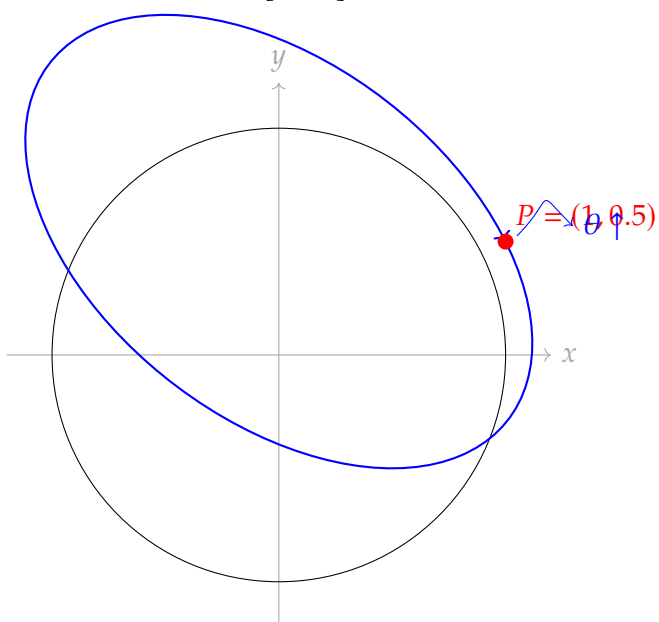
(ii) (Compatibility) For any $e^{i\theta}, e^{i\phi} \in \mathbb{S}^1$ and $P \in \mathbb{S}^2$,

$$\Phi(e^{i\theta} e^{i\phi}, P) = \Phi(e^{i(\theta+\phi)}, P) = \text{Rot}_{\theta+\phi}(P) = \text{Rot}_\theta(\text{Rot}_\phi(P)) = \Phi(e^{i\theta}, \Phi(e^{i\phi}, P)).$$

Hence Φ be a left group action. To be continue \dots .



$\theta \in [0, 2\pi]$



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| P | $\text{Rot}_0(P)$ | $\text{Rot}_{\frac{\pi}{4}}(P)$ | $\text{Rot}_{\frac{\pi}{2}}(P)$ | $\text{Rot}_{\frac{3\pi}{4}}(P)$ | $\text{Rot}_{\pi}(P)$ | $\text{Rot}_{\frac{5\pi}{4}}(P)$ | $\text{Rot}_{\frac{3\pi}{2}}(P)$ | $\text{Rot}_{\frac{7\pi}{4}}(P)$ |
|---|---|---|---|--|--|---|---|--|
| $(1, 0, 0)$ | $(1, 0, 0)$ | $(\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2}, 0)$ | $(0, -1, 0)$ | $(-\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2}, 0)$ | $(-1, 0, 0)$ | $(-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ | $(0, 1, 0)$ | $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ |
| $(0, 1, 0)$ | $(0, 1, 0)$ | $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ | $(1, 0, 0)$ | $(\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2}, 0)$ | $(0, -1, 0)$ | $(-\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2}, 0)$ | $(-1, 0, 0)$ | $(-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ |
| $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ | $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ | $(0, -1, 0)$ | $(-\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2}, 0)$ | $(-1, 0, 0)$ | $(-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ | $(0, 1, 0)$ | $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ | $(1, 0, 0)$ |
| $(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}})$ | $(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}})$ | $(\frac{1}{2}, -\frac{1}{2}, \frac{1}{\sqrt{2}})$ | $(0, -\frac{\sqrt{2}}{2}, \frac{1}{\sqrt{2}})$ | $(-\frac{1}{2}, -\frac{1}{2}, \frac{1}{\sqrt{2}})$ | $(-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}})$ | $(-\frac{1}{2}, \frac{1}{2}, \frac{1}{\sqrt{2}})$ | $(0, \frac{\sqrt{2}}{2}, \frac{1}{\sqrt{2}})$ | $(\frac{1}{2}, \frac{1}{2}, \frac{1}{\sqrt{2}})$ |
| $(0, 0, 1)$ | $(0, 0, 1)$ | $(0, 0, 1)$ | $(0, 0, 1)$ | $(0, 0, 1)$ | $(0, 0, 1)$ | $(0, 0, 1)$ | $(0, 0, 1)$ | $(0, 0, 1)$ |

| P | θ | $\text{Rot}_\theta(P)$ | Comment |
|---|--------------------------------|--|---|
| $(1, 0, 0)$ | $\pi/2$ | $(0, -1, 0)$ | “East” \rightarrow “South” on equator |
| $(1, 0, 0)$ | π | $(-1, 0, 0)$ | “East” \rightarrow “West” |
| $(1, 0, 0)$ | $2\pi/3$ | $(-\frac{1}{2}, -\frac{\sqrt{3}}{2}, 0)$ | 120° around equator |
| $(0, 1, 0)$ | $\pi/2$ | $(1, 0, 0)$ | “North” \rightarrow “East” on equator |
| $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0)$ | $\pi/4$ | $(1, 0, 0)$ | 45° NE equator \rightarrow East |
| $(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}})$ | $\pi/2$ | $(0, -\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$ | 45° above equator (height fixed) |
| $(1, 0, 0)$ | rotate by $\pi/4$ then $\pi/4$ | $(0, -1, 0)$ | composition = $\text{Rot}_{\pi/2}(1, 0, 0)$ |

Table 1: Computations of the rotation Rot_θ on \mathbb{S}^2 .

| θ | $\cos \theta$ | $\sin \theta$ | $\text{Rot}_\theta(x, y, z)$ | Interpretation |
|-----------------|----------------------|----------------------|--|--------------------|
| 0 | 1 | 0 | (x, y, z) | identity |
| $\frac{\pi}{6}$ | $\frac{\sqrt{3}}{2}$ | $\frac{1}{2}$ | $(\frac{\sqrt{3}}{2}x + \frac{1}{2}y, -\frac{1}{2}x + \frac{\sqrt{3}}{2}y, z)$ | 30° rotation |
| $\frac{\pi}{4}$ | $\frac{\sqrt{2}}{2}$ | $\frac{\sqrt{2}}{2}$ | $(\frac{x+y}{\sqrt{2}}, -\frac{x-y}{\sqrt{2}}, z)$ | 45° rotation |
| $\frac{\pi}{3}$ | $\frac{1}{2}$ | $\frac{\sqrt{3}}{2}$ | $(\frac{1}{2}x + \frac{\sqrt{3}}{2}y, -\frac{\sqrt{3}}{2}x + \frac{1}{2}y, z)$ | 60° rotation |
| $\frac{\pi}{2}$ | 0 | 1 | $(y, -x, z)$ | 90° rotation |
| π | -1 | 0 | $(-x, -y, z)$ | 180° rotation |
| 2π | 1 | 0 | (x, y, z) | full 360° rotation |

Table 2: Trigonometric values and the induced rotations on \mathbb{S}^2 for key angles θ .

