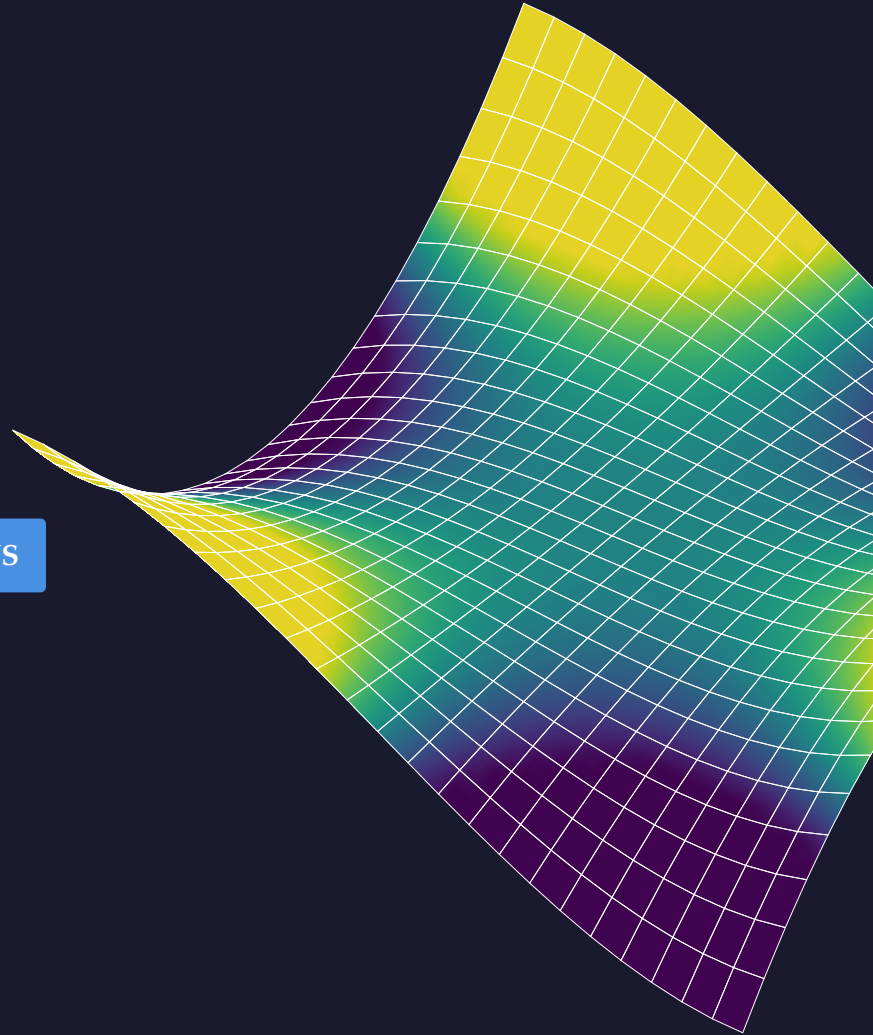


# Riemann Surfaces and Algebraic Curves

A framework for understanding Elliptic Curves

Ji, Yonghyeon

PART I — MULTIVARIABLE CALCULUS



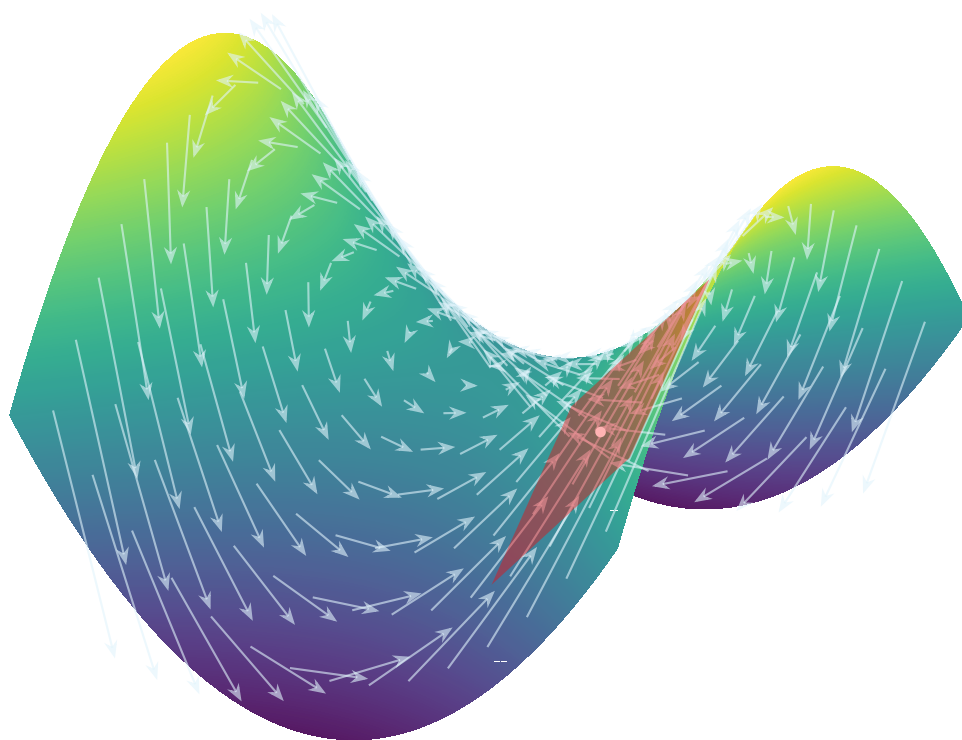
# Riemann Surfaces and Algebraic Curves

*A Framework for Understanding Elliptic Curves*

## Part I — Multivariable Calculus

Ji, Yonghyeon

January 28, 2026



WINTER 2026

## The FTC hierarchy

Name	Formula
FTC I (Accumulation)	$\frac{d}{dx} \left( \int_a^x f(t) dt \right) = f(x).$
FTC II (Evaluation)	$\int_a^b f'(x) dx = f(b) - f(a).$
Fundamental Theorem of Line Integrals	$\int_C \nabla \phi \cdot d\mathbf{r} = \phi(B) - \phi(A).$
Green's Theorem	$\oint_{\partial R} P dx + Q dy = \iint_R \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA.$
Stokes' Theorem (3D)	$\oint_{\partial S} \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} dS.$
Divergence Theorem	$\iint_{\partial V} \mathbf{F} \cdot \mathbf{n} dS = \iiint_V (\nabla \cdot \mathbf{F}) dV.$
Generalized Stokes	$\int_{\partial \Omega} \omega = \int_{\Omega} d\omega.$

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## Changelog

v1.0 2025-12-29 Initial release.

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# 1 Fundamental Theorem of Calculus

## Fundamental Theorem for Gradient Fields

If  $\mathbf{F} = \nabla f$  is a conservative vector field and  $C$  is a smooth curve from  $A$  to  $B$ , then

$$\int_C \mathbf{F} \cdot d\mathbf{r} = f(B) - f(A).$$

## Green's Theorem

For a positively oriented, simple closed curve  $C$  bounding a region  $R$  in the plane,

$$\oint_C P \, dx + Q \, dy = \iint_R \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA.$$

## Divergence Theorem

Let  $\mathbf{F}$  be a vector field defined on a region  $E$  with closed boundary surface  $S$  (outward-oriented). Then

$$\iiint_E \nabla \cdot \mathbf{F} \, dV = \iint_S \mathbf{F} \cdot \mathbf{n} \, dS.$$

## Stokes' Theorem

Let  $S$  be an oriented surface with boundary curve  $C$ , and let  $\mathbf{F}$  be a vector field. Then

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} \, dS.$$

## Triple Integral

To integrate a scalar function  $f(x, y, z)$  over a region  $E$  in  $\mathbb{R}^3$ ,

$$\iiint_E f(x, y, z) \, dV.$$

## 1.1 Gradient Vector Fields

### Scalar field

**Definition 1.1.** Let  $U \subseteq \mathbb{R}^n$  be an open set. A scalar field on  $U$  is a function

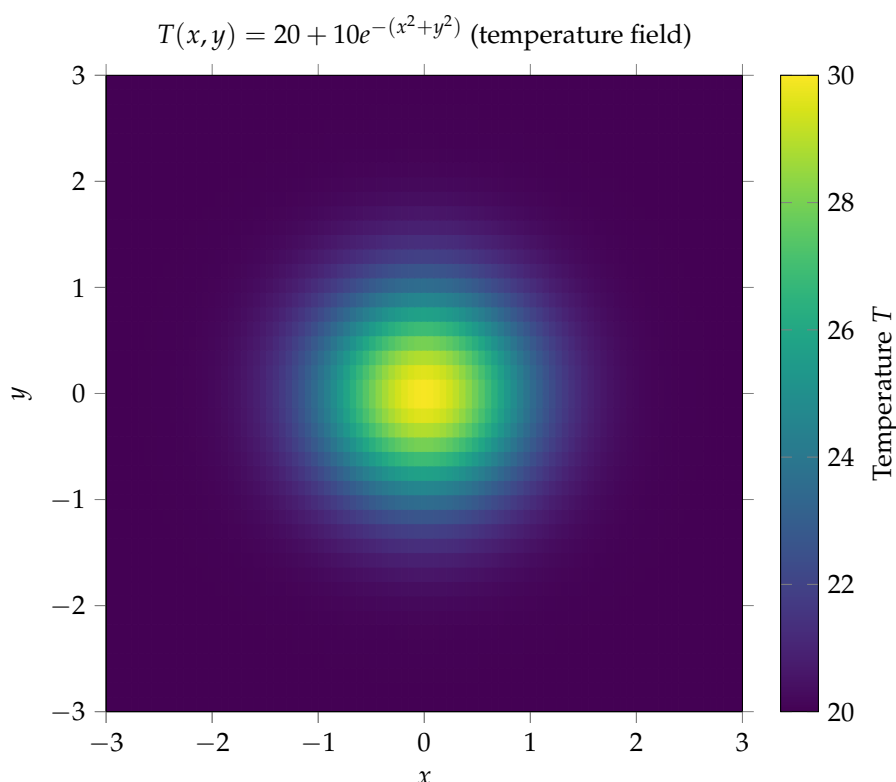
$$\begin{aligned} f &: U \longrightarrow \mathbb{R} \\ \mathbf{x} &\longmapsto f(\mathbf{x}) . \end{aligned}$$

Equivalently, to each point  $\mathbf{x} \in U$  the scalar field assigns a real number  $f(\mathbf{x})$ .

**Example 1** (Temperature distribution). Let  $U = \mathbb{R}^2$ . Define

$$T(x, y) = 20 + 10e^{-(x^2+y^2)}.$$

Then  $T : U \rightarrow \mathbb{R}$  is a scalar field. One may interpret  $T(x, y)$  as the temperature (in degrees) at the point  $(x, y)$ . Notice that  $T(0, 0) = 30$  and  $T(x, y) \rightarrow 20$  as  $x^2 + y^2 \rightarrow \infty$ , so the temperature is highest at the origin and decays outward.



## Vector field

**Definition 1.2.** Let  $U \subseteq \mathbb{R}^n$  be an open set. A vector field on  $U$  is a function

$$\begin{aligned} \mathbf{F} &: U \longrightarrow \mathbb{R}^n \\ \mathbf{x} &\longmapsto \mathbf{F}(\mathbf{x}) . \end{aligned}$$

Equivalently, to each point  $\mathbf{x} \in U$  the vector field assigns a vector  $\mathbf{F}(\mathbf{x}) \in \mathbb{R}^n$ . In coordinates, one often writes

$$\mathbf{F}(\mathbf{x}) = \langle F_1(\mathbf{x}), F_2(\mathbf{x}), \dots, F_n(\mathbf{x}) \rangle ,$$

where each component function  $F_i : U \rightarrow \mathbb{R}$  is a scalar field on  $U$ .

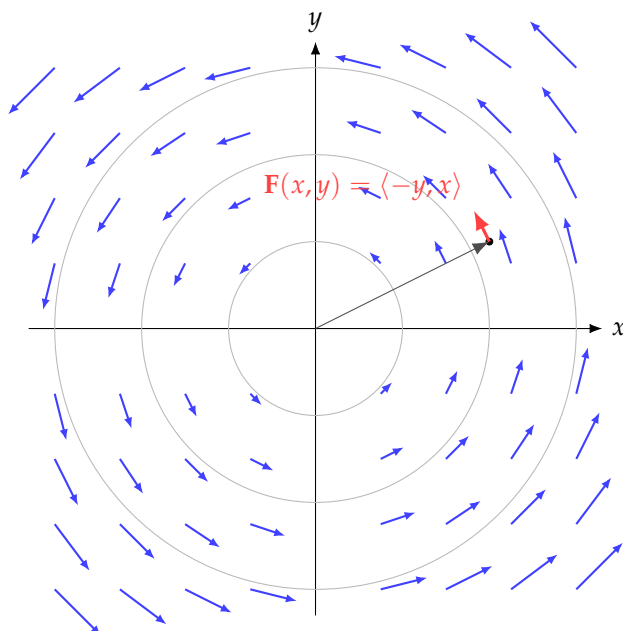
**Example 2** (Rotation field). Let  $U = \mathbb{R}^2$ . Define

$$\mathbf{F}(x, y) = \langle -y, x \rangle .$$

Then  $\mathbf{F} : U \rightarrow \mathbb{R}^2$  is a vector field. At each point  $(x, y)$  it assigns the vector  $(-y, x)$ , which is perpendicular to  $\langle x, y \rangle$  and tangent to the circle  $x^2 + y^2 = \text{constant}$ . Moreover,

$$\|\mathbf{F}(x, y)\| = \sqrt{x^2 + y^2} ,$$

so the magnitude increases linearly with the distance from the origin. This field models a rigid counterclockwise rotational flow about the origin.



*Remark.*

**Definition 1.3** (Conservative vector field). Let  $U \subseteq \mathbb{R}^n$  be an open set and let  $\mathbf{F} : U \rightarrow \mathbb{R}^n$  be a vector field. We say that  $\mathbf{F}$  is conservative on  $U$  if there exists a scalar field  $f : U \rightarrow \mathbb{R}$  of class  $C^1$  such that

$$\mathbf{F} = \nabla f \quad \text{on } U.$$

In this case,  $f$  is called a potential function for  $\mathbf{F}$ .

**Remark** (Equivalent characterization). A vector field  $\mathbf{F}$  on  $U$  is conservative if and only if for every piecewise  $C^1$  curve  $C$  in  $U$  with endpoints  $\mathbf{A}, \mathbf{B}$ , the line integral  $\int_C \mathbf{F} \cdot d\mathbf{r}$  depends only on  $\mathbf{A}$  and  $\mathbf{B}$  (path independence). Equivalently,

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$$

for every piecewise  $C^1$  closed curve  $C$  in  $U$ .

**Definition 1.4** (Gradient operator). Let  $U \subseteq \mathbb{R}^n$  be open. The gradient operator (or nabla operator) is the map

$$\nabla : C^1(U) \longrightarrow C^0(U, \mathbb{R}^n)$$

defined by

$$(\nabla f)(\mathbf{x}) = \begin{pmatrix} \frac{\partial f}{\partial x_1}(\mathbf{x}) \\ \frac{\partial f}{\partial x_2}(\mathbf{x}) \\ \vdots \\ \frac{\partial f}{\partial x_n}(\mathbf{x}) \end{pmatrix}, \quad \mathbf{x} = (x_1, \dots, x_n) \in U.$$

**Remark** (Directional derivative characterization). For  $f \in C^1(U)$  and  $\mathbf{x} \in U$ , the vector  $\nabla f(\mathbf{x}) \in \mathbb{R}^n$  is uniquely characterized by the property that

$$D_{\mathbf{v}}f(\mathbf{x}) = \nabla f(\mathbf{x}) \cdot \mathbf{v} \quad \text{for all } \mathbf{v} \in \mathbb{R}^n,$$

where  $D_{\mathbf{v}}f(\mathbf{x})$  denotes the directional derivative of  $f$  at  $\mathbf{x}$  in the direction  $\mathbf{v}$ .

[Linearity of  $\nabla$ ] Let  $f, g \in C^1(U)$  and  $a, b \in \mathbb{R}$ . Then

$$\nabla(af + bg) = a \nabla f + b \nabla g.$$

**Remark** (Jacobian/transpose viewpoint). For  $f \in C^1(U)$ , the total derivative at  $\mathbf{x} \in U$  is the linear map

$$Df(\mathbf{x}) : \mathbb{R}^n \rightarrow \mathbb{R}, \quad Df(\mathbf{x}) \mathbf{v} = D_{\mathbf{v}}f(\mathbf{x}).$$

In coordinates,  $Df(\mathbf{x})$  is represented by the  $1 \times n$  Jacobian row matrix

$$Df(\mathbf{x}) = \left( \frac{\partial f}{\partial x_1}(\mathbf{x}) \quad \cdots \quad \frac{\partial f}{\partial x_n}(\mathbf{x}) \right),$$



and the gradient is its transpose:

$$\nabla f(\mathbf{x}) = \left( Df(\mathbf{x}) \right)^{\top}.$$

Consequently, for any  $\mathbf{v} \in \mathbb{R}^n$ ,

$$D_{\mathbf{v}}f(\mathbf{x}) = Df(\mathbf{x}) \mathbf{v} = \left( \nabla f(\mathbf{x}) \right)^{\top} \mathbf{v} = \nabla f(\mathbf{x}) \cdot \mathbf{v}.$$

### Fundamental Theorem for Gradient Fields

**Theorem 1.5.** *Let  $U \subset \mathbb{R}^n$  be an open set and let  $f : U \rightarrow \mathbb{R}$  be continuously differentiable ( $f \in C^1(U)$ ). Let  $C$  be a piecewise  $C^1$  curve in  $U$  with a piecewise  $C^1$  parametrization*

$$\mathbf{r} : [a, b] \rightarrow U.$$

*If  $\mathbf{r}(a) = \mathbf{A}$  and  $\mathbf{r}(b) = \mathbf{B}$ , then*

$$\int_C \nabla f \cdot d\mathbf{r} = f(\mathbf{B}) - f(\mathbf{A}).$$

*In particular, the line integral of a gradient field depends only on the endpoints of the curve.*

*Proof.* By definition of the line integral of a vector field along a parametrized curve,

$$\int_C \nabla f \cdot d\mathbf{r} = \int_a^b \nabla f(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt.$$

Define a scalar-valued function  $g : [a, b] \rightarrow \mathbb{R}$  by  $g(t) = f(\mathbf{r}(t))$ . Since  $f \in C^1(U)$  and  $\mathbf{r}$  is piecewise  $C^1$ , the composition  $g$  is piecewise  $C^1$ . On any subinterval where  $\mathbf{r}$  is  $C^1$ , the multivariable chain rule gives

$$g'(t) = \nabla f(\mathbf{r}(t)) \cdot \mathbf{r}'(t).$$

Hence on each such subinterval we have  $\nabla f(\mathbf{r}(t)) \cdot \mathbf{r}'(t) = g'(t)$ , and summing over the finitely many smooth pieces yields

$$\int_a^b \nabla f(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_a^b g'(t) dt.$$

By the (single-variable) Fundamental Theorem of Calculus,

$$\int_a^b g'(t) dt = g(b) - g(a).$$

Substituting back  $g(t) = f(\mathbf{r}(t))$  gives

$$g(b) - g(a) = f(\mathbf{r}(b)) - f(\mathbf{r}(a)) = f(\mathbf{B}) - f(\mathbf{A}).$$

Therefore,

$$\int_C \nabla f \cdot d\mathbf{r} = f(\mathbf{B}) - f(\mathbf{A}),$$

as claimed. □

Consider a small rectangle centered at  $(x_0, y_0)$  with side lengths  $\Delta x, \Delta y$ .

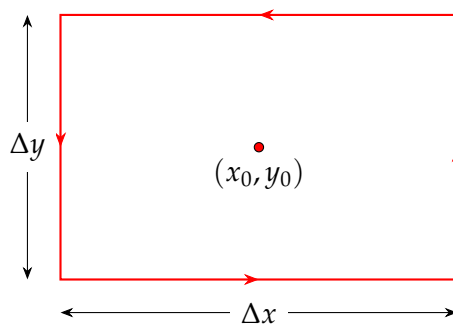


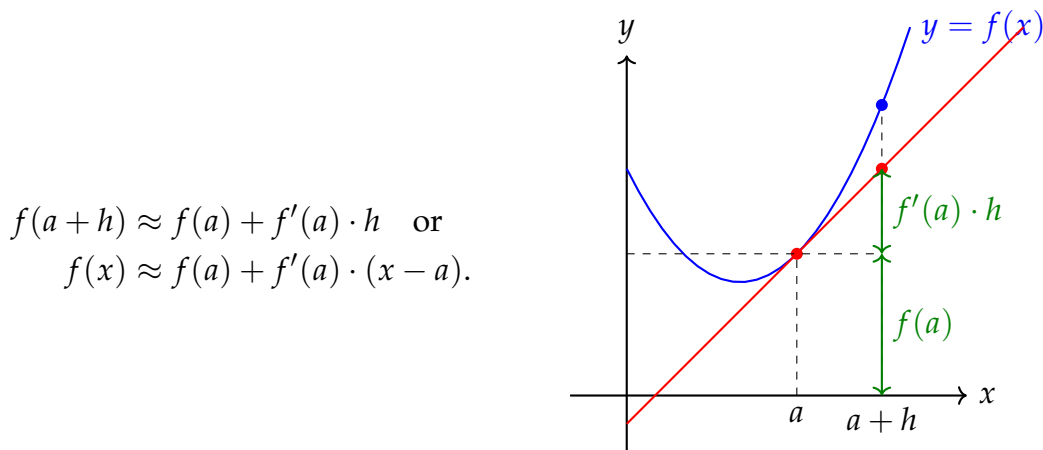
Figure 1: Circulation around an infinitesimal rectangle.

The total counterclockwise circulation is the sum of the line integrals along the four edges:

$$\oint_{\partial R} \mathbf{F} \cdot d\mathbf{r} = \int_{\text{bottom}} P dx + \int_{\text{right}} Q dy + \int_{\text{top}} P dx + \int_{\text{left}} Q dy.$$

We will approximate the value of  $P$  or  $Q$  along each edge as being constant, equal to its value at the midpoint of that edge. We find this value using a first-order Taylor expansion from the center point  $(x_0, y_0)$ .

For a simple function of one variable,  $f(x)$ , if we know its value at a point  $a$ , then we can estimate its value at a nearby point  $a + h$  using the tangent line at  $a$ :



In words, “New Value  $\approx$  Old Value + (Rate of Change)  $\times$  (Small Step)”.

For a function of two variables like  $P(x, y)$ , the idea is identical, but the “rate of change” now has two components (one for each direction), and the “tangent line” becomes a “tangent plane”. The general first-order Taylor expansion for  $P(x, y)$  around a center point  $(x_0, y_0)$  is

$$P(x_0 + a, y_0 + b) \approx P(x_0, y_0) + \frac{\partial P}{\partial x}(x_0, y_0) \cdot a + \frac{\partial P}{\partial y}(x_0, y_0) \cdot b$$

Here,  $a$  is the small step in the  $x$ -direction, and  $b$  is the small step in the  $y$ -direction.

**1. The Horizontal Paths** These integrals involve the horizontal component of  $P(x, y)$ .

• **Bottom Path ( $\rightarrow$ ):**

$$\begin{aligned} P\left(x, y_0 - \frac{\Delta y}{2}\right) &\approx P(x_0, y_0) - \frac{\partial P}{\partial y}(x_0, y_0) \frac{\Delta y}{2} \\ \Rightarrow \int_{\text{bottom}} P \, dx &\approx \int_{-\Delta x/2}^{\Delta x/2} \left(P_0 + P_x s - P_y \frac{\Delta y}{2}\right) ds \quad (x = x_0 + s, \, dx = ds) \\ \Rightarrow \int_{\text{bottom}} P \, dx &\approx \left(P(x_0, y_0) - \frac{\partial P}{\partial y}(x_0, y_0) \frac{\Delta y}{2}\right) (\Delta x) \end{aligned}$$

Note that

$$\int_{-\Delta x/2}^{\Delta x/2} P_x s \, ds = P_x \left[ \frac{s^2}{2} \right]_{-\Delta x/2}^{\Delta x/2} = P_x \left( \frac{(\Delta x/2)^2}{2} - \frac{(\Delta x/2)^2}{2} \right) = 0.$$

• **Top Path ( $\leftarrow$ ):**

$$P\left(x, y_0 + \frac{\Delta y}{2}\right) \approx P(x_0, y_0) + \frac{\partial P}{\partial y} \frac{\Delta y}{2} \Rightarrow \int_{\text{top}} P \, dx \approx - \left(P(x_0, y_0) + \frac{\partial P}{\partial y} \frac{\Delta y}{2}\right) (\Delta x)$$

Here, we are left with only the parts that describe the *change* in  $P$  with respect to  $y$ .

$$\int_{\text{bottom}} P \, dx + \int_{\text{top}} P \, dx \approx \left(-\frac{\partial P}{\partial y} \frac{\Delta y}{2}\right) \Delta x - \left(\frac{\partial P}{\partial y} \frac{\Delta y}{2}\right) \Delta x = -\frac{\partial P}{\partial y} \Delta x \Delta y$$

**2. The Vertical Paths** These integrals involve the vertical component of  $Q(x, y)$ .

• **Right Path ( $\uparrow$ ):**

$$Q\left(x_0 + \frac{\Delta x}{2}, y\right) \approx Q(x_0, y_0) + \frac{\partial Q}{\partial x} \frac{\Delta x}{2} \Rightarrow \int_{\text{right}} Q \, dy \approx \left(Q(x_0, y_0) + \frac{\partial Q}{\partial x} \frac{\Delta x}{2}\right) (\Delta y)$$

• **Left Path ( $\downarrow$ ):**

$$Q\left(x_0 - \frac{\Delta x}{2}, y\right) \approx Q(x_0, y_0) - \frac{\partial Q}{\partial x} \frac{\Delta x}{2} \Rightarrow \int_{\text{left}} Q \, dy \approx - \left(Q(x_0, y_0) - \frac{\partial Q}{\partial x} \frac{\Delta x}{2}\right) (\Delta y)$$

Here, we are left with only the parts that describe the *change* in  $Q$  with respect to  $x$ .

$$\int_{\text{right}} Q \, dy + \int_{\text{left}} Q \, dy \approx \left( \frac{\partial Q}{\partial x} \frac{\Delta x}{2} \right) \Delta y + \left( \frac{\partial Q}{\partial x} \frac{\Delta x}{2} \right) \Delta y = \frac{\partial Q}{\partial x} \Delta x \Delta y$$

Now we sum the results from the horizontal and vertical pairs:

$$\begin{aligned} \oint_{\partial R} \mathbf{F} \cdot d\mathbf{r} &\approx \left( -\frac{\partial P}{\partial y} \Delta x \Delta y \right) + \left( \frac{\partial Q}{\partial x} \Delta x \Delta y \right) \\ &= \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \Delta x \Delta y \end{aligned}$$

This shows that the total circulation around the tiny loop is approximately the quantity  $\left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right)$  multiplied by the area of the loop ( $\Delta A = \Delta x \Delta y$ ).

To get the property *at the point*  $(x_0, y_0)$ , we find the circulation **density**. We divide by the area and take the limit as the rectangle shrinks to zero.

$$\lim_{\Delta A \rightarrow 0} \frac{1}{\Delta A} \oint_{\partial R} \mathbf{F} \cdot d\mathbf{r} = \frac{\partial Q}{\partial x}(x_0, y_0) - \frac{\partial P}{\partial y}(x_0, y_0)$$

This is why we call the scalar quantity  $\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}$  the **curl**: it is the circulation per unit area at a point, which measures the local rotational tendency of the field.

If  $C = \partial D$  is a positively oriented simple closed curve enclosing a region  $D$ , Green's theorem states

$$\underbrace{\oint_C \mathbf{F} \cdot d\mathbf{r}}_{\substack{\text{Line Integral} \\ \text{(Total Circulation)}}} = \underbrace{\iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA}_{\substack{\text{Double Integral} \\ \text{(Sum of Local Curls)}}$$

1. Let  $\mathbf{F} = \langle 2x, 2y \rangle$ . Show that  $\mathbf{F}$  is conservative and compute

$$\int_C \mathbf{F} \cdot d\mathbf{r}$$

where  $C$  is any path from  $(0,0)$  to  $(1,1)$ .

**Sol.** Let  $\mathbf{F} = \langle P, Q \rangle = \langle 2x, 2y \rangle$ . Since

$$\frac{\partial P}{\partial y} = \frac{\partial}{\partial y}(2x) = 0 \quad \text{and} \quad \frac{\partial Q}{\partial x} = \frac{\partial}{\partial x}(2y) = 0,$$

we have  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  everywhere in  $\mathbb{R}^2$ , a simply connected domain. Therefore  $\mathbf{F}$  is conservative.

To find a potential function  $f$  with  $\nabla f = \mathbf{F}$ , we solve

$$f_x = 2x \quad \Rightarrow \quad f(x, y) = \int 2x \, dx = x^2 + g(y),$$

for some function  $g(y)$ . Then

$$f_y = g'(y) = 2y \quad \Rightarrow \quad g(y) = y^2 + C.$$

Hence a potential function is

$$f(x, y) = x^2 + y^2 \quad (\text{constant irrelevant}).$$

By the Fundamental Theorem for Line Integrals, for any path  $C$  from  $(0,0)$  to  $(1,1)$ ,

$$\int_C \mathbf{F} \cdot d\mathbf{r} = f(1,1) - f(0,0) = (1^2 + 1^2) - (0^2 + 0^2) = 2.$$

□

2. Determine whether the vector field  $\mathbf{F} = \langle y, x \rangle$  is conservative. If so, find a potential function.

**Sol.** Let  $\mathbf{F} = \langle P, Q \rangle = \langle y, x \rangle$ . Compute the mixed partials:

$$\frac{\partial P}{\partial y} = \frac{\partial}{\partial y}(y) = 1, \quad \frac{\partial Q}{\partial x} = \frac{\partial}{\partial x}(x) = 1.$$

Since  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  everywhere in  $\mathbb{R}^2$  (a simply connected domain),  $\mathbf{F}$  is conservative.

To find a potential function  $f$  such that  $\nabla f = \mathbf{F}$ , we solve

$$f_x = P = y.$$

Integrating with respect to  $x$  gives

$$f(x, y) = \int y \, dx = xy + g(y),$$

where  $g$  is a function of  $y$  only. Differentiate with respect to  $y$ :

$$f_y = x + g'(y).$$

But  $f_y$  must equal  $Q = x$ , so  $g'(y) = 0$ , hence  $g(y) = C$ .

Therefore, a potential function is

$$f(x, y) = xy \quad (\text{up to an additive constant}).$$

Let  $\mathbf{F} = \langle P, Q \rangle = \langle y, x \rangle$  on an open set  $U \subseteq \mathbb{R}^2$ . Since  $P, Q \in C^1(U)$ ,  $\mathbf{F}$  is conservative on  $U$  if  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  on  $U$ .

Compute:

$$\frac{\partial P}{\partial y} = \frac{\partial}{\partial y}(y) = 1, \quad \frac{\partial Q}{\partial x} = \frac{\partial}{\partial x}(x) = 1.$$

Thus  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  everywhere on  $U$ , so  $\mathbf{F}$  is conservative.

To find a potential function  $f$  with  $\nabla f = \mathbf{F}$ , we require

$$f_x = y, \quad f_y = x.$$

Integrate  $f_x = y$  with respect to  $x$ :

$$f(x, y) = xy + g(y),$$

for some function  $g$  of  $y$  alone. Differentiate with respect to  $y$ :

$$f_y(x, y) = x + g'(y).$$

Set this equal to  $x$  (since  $f_y = x$ ):

$$x + g'(y) = x \Rightarrow g'(y) = 0 \Rightarrow g(y) = C.$$

Therefore a potential function is

$$f(x, y) = xy + C.$$

(Any two potential functions differ by an additive constant.)

□



**Theorem 1.6** (Curl test for conservativeness in  $\mathbb{R}^2$ ). *Let  $U \subseteq \mathbb{R}^2$  be an open and simply connected set, and let*

$$\mathbf{F} = \langle P, Q \rangle : U \rightarrow \mathbb{R}^2$$

*be a  $C^1$  vector field. Then the following are equivalent:*

- (a)  $\mathbf{F}$  is conservative on  $U$ , i.e. there exists a  $C^1$  function  $f : U \rightarrow \mathbb{R}$  such that  $\nabla f = \mathbf{F}$ .
- (b)  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  everywhere on  $U$ .

*Proof. (1)  $\Rightarrow$  (2).* Assume  $\mathbf{F}$  is conservative, so  $\mathbf{F} = \nabla f$  for some  $f \in C^1(U)$ . In coordinates,

$$P = f_x, \quad Q = f_y.$$

If moreover  $f \in C^2(U)$  (which holds, for instance, if  $P, Q \in C^1$  and  $f$  is constructed as in the converse direction), then

$$\frac{\partial P}{\partial y} = \frac{\partial}{\partial y}(f_x) = f_{xy}, \quad \frac{\partial Q}{\partial x} = \frac{\partial}{\partial x}(f_y) = f_{yx}.$$

By Clairaut's theorem (equality of mixed partials for  $C^2$  functions),  $f_{xy} = f_{yx}$ , hence

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} \quad \text{on } U.$$

*(2)  $\Rightarrow$  (1).* Assume  $P_y = Q_x$  on  $U$ . Let  $C$  be any positively oriented, piecewise  $C^1$ , simple closed curve in  $U$  bounding a region  $D \subseteq U$ . By Green's Theorem,

$$\oint_C P dx + Q dy = \iint_D (Q_x - P_y) dA.$$

Since  $Q_x - P_y = 0$  on  $U$ , it follows that

$$\oint_C P dx + Q dy = 0$$

for every such curve  $C$ .

*Path independence.* Fix two piecewise  $C^1$  curves  $C_1$  and  $C_2$  in  $U$  with the same endpoints  $A$  and  $B$ . Consider the closed curve  $C = C_1 \cup (-C_2)$  obtained by traversing  $C_1$  from  $A$  to  $B$  and then  $C_2$  from  $B$  back to  $A$ . Because  $U$  is simply connected, this closed curve can be decomposed into finitely many simple closed curves each bounding a region contained in  $U$ . Since the integral around each such simple closed curve is 0, additivity of line integrals yields

$$\oint_C P dx + Q dy = 0.$$

Therefore,

$$\int_{C_1} P dx + Q dy = \int_{C_2} P dx + Q dy,$$

so the line integral depends only on endpoints (path independence).

*Construction of a potential.* Fix a base point  $A_0 \in U$ . Define  $f : U \rightarrow \mathbb{R}$  by

$$f(x, y) = \int_{C_{A_0 \rightarrow (x, y)}} P dx + Q dy,$$

where  $C_{A_0 \rightarrow (x, y)}$  is any piecewise  $C^1$  curve in  $U$  from  $A_0$  to  $(x, y)$ . By path independence,  $f$  is well-defined.

*Verification that  $\nabla f = \mathbf{F}$ .* Let  $(x, y) \in U$  and choose  $h$  small so that the horizontal segment from  $(x, y)$  to  $(x + h, y)$  lies in  $U$ . Using the definition of  $f$  and path independence,

$$f(x + h, y) - f(x, y) = \int_x^{x+h} P(s, y) ds.$$

Divide by  $h$  and let  $h \rightarrow 0$  to obtain

$$f_x(x, y) = P(x, y).$$

Similarly, using a vertical segment,

$$f(x, y + h) - f(x, y) = \int_y^{y+h} Q(x, t) dt,$$

so

$$f_y(x, y) = Q(x, y).$$

Hence  $\nabla f = \langle f_x, f_y \rangle = \langle P, Q \rangle = \mathbf{F}$ , and  $\mathbf{F}$  is conservative on  $U$ . □

3. Let  $f(x, y, z) = xyz$ . Compute  $\nabla f$  and evaluate the line integral of  $\nabla f$  over the path from  $(1, 0, 0)$  to  $(1, 2, 3)$ .

**Sol.** Given  $f(x, y, z) = xyz$ , its gradient is

$$\nabla f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle = \langle yz, xz, xy \rangle.$$

To evaluate the line integral of  $\nabla f$  over any path  $C$  from  $(1, 0, 0)$  to  $(1, 2, 3)$ , use the Fundamental Theorem for Line Integrals:

$$\int_C \nabla f \cdot d\mathbf{r} = f(1, 2, 3) - f(1, 0, 0).$$

Compute the endpoint values:

$$f(1, 2, 3) = (1)(2)(3) = 6, \quad f(1, 0, 0) = (1)(0)(0) = 0.$$

Hence,

$$\int_C \nabla f \cdot d\mathbf{r} = 6 - 0 = 6.$$

□

4. Let  $\mathbf{F} = \nabla f$  for  $f(x, y) = x^2 + y^2$ . Compute the line integral over a circular path from  $(1, 0)$  to  $(0, 1)$  and explain the result.

**Sol.** Given  $f(x, y) = x^2 + y^2$ , we have

$$\mathbf{F} = \nabla f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right\rangle = \langle 2x, 2y \rangle.$$

Since  $\mathbf{F}$  is a gradient field, it is conservative. Therefore, by the Fundamental Theorem for Line Integrals, for any smooth path  $C$  from  $(1, 0)$  to  $(0, 1)$  (including a circular arc),

$$\int_C \mathbf{F} \cdot d\mathbf{r} = f(0, 1) - f(1, 0).$$

Compute:

$$f(0, 1) = 0^2 + 1^2 = 1, \quad f(1, 0) = 1^2 + 0^2 = 1.$$

Hence,

$$\int_C \mathbf{F} \cdot d\mathbf{r} = 1 - 1 = 0.$$

**Explanation.** The line integral depends only on the endpoints because  $\mathbf{F} = \nabla f$  is conservative. Here both endpoints lie on the same level curve of  $f$  (indeed, on the circle  $x^2 + y^2 = 1$ ), so  $f$  has the same value at  $(1, 0)$  and  $(0, 1)$ ; thus the net change in potential is zero, and the work done by  $\mathbf{F}$  along the circular path is 0.  $\square$

## 1.2 Green's Theorem

1. Use Green's Theorem to evaluate

$$\oint_C x \, dy - y \, dx$$

where  $C$  is the unit circle oriented counterclockwise.

**Sol.** Write the integral in Green's Theorem form:

$$\oint_C P \, dx + Q \, dy,$$

where here  $P(x, y) = -y$  and  $Q(x, y) = x$ , since

$$x \, dy - y \, dx = (-y) \, dx + x \, dy.$$

By Green's Theorem (with  $C$  positively oriented),

$$\oint_C P \, dx + Q \, dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA,$$

where  $D$  is the unit disk. Compute:

$$\frac{\partial Q}{\partial x} = \frac{\partial}{\partial x}(x) = 1, \quad \frac{\partial P}{\partial y} = \frac{\partial}{\partial y}(-y) = -1.$$

Thus

$$\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = 1 - (-1) = 2.$$

Therefore,

$$\oint_C x \, dy - y \, dx = \iint_D 2 \, dA = 2 \cdot \text{Area}(D) = 2 \cdot \pi(1)^2 = 2\pi.$$

□

2. Let  $\mathbf{F} = \langle y^2, 2xy \rangle$ . Use Green's Theorem to evaluate the line integral around the boundary of the square  $[0, 1] \times [0, 1]$ .

**Sol.** Let  $\mathbf{F} = \langle P, Q \rangle = \langle y^2, 2xy \rangle$ , and let  $C$  be the positively oriented (counterclockwise) boundary of the square

$$D = [0, 1] \times [0, 1].$$

By Green's Theorem,

$$\oint_C P dx + Q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA.$$

Compute the partial derivatives:

$$\frac{\partial Q}{\partial x} = \frac{\partial}{\partial x}(2xy) = 2y, \quad \frac{\partial P}{\partial y} = \frac{\partial}{\partial y}(y^2) = 2y.$$

Hence,

$$\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = 2y - 2y = 0.$$

Therefore,

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \oint_C P dx + Q dy = \iint_D 0 dA = 0.$$

□

3. Evaluate

$$\oint_C (x + y)dx + (x - y)dy$$

where  $C$  is the triangle with vertices  $(0, 0)$ ,  $(1, 0)$ ,  $(1, 1)$  oriented counterclockwise.

**Sol.** Write the line integral as  $\oint_C P dx + Q dy$  with

$$P(x, y) = x + y, \quad Q(x, y) = x - y.$$

Since  $C$  is positively oriented (counterclockwise), Green's Theorem gives

$$\oint_C P dx + Q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA,$$

where  $D$  is the triangular region with vertices  $(0, 0)$ ,  $(1, 0)$ ,  $(1, 1)$ .

Compute the partial derivatives:

$$\frac{\partial Q}{\partial x} = \frac{\partial}{\partial x}(x - y) = 1, \quad \frac{\partial P}{\partial y} = \frac{\partial}{\partial y}(x + y) = 1.$$

Thus,

$$\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = 1 - 1 = 0.$$

Therefore,

$$\oint_C (x + y) dx + (x - y) dy = \iint_D 0 dA = 0.$$

□

4. Determine if

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$$

for  $\mathbf{F} = \langle y, -x \rangle$  around a circle of radius  $r$  centered at the origin.

**Sol.** Let  $\mathbf{F} = \langle P, Q \rangle = \langle y, -x \rangle$ . Then

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \oint_C P dx + Q dy = \oint_C y dx - x dy,$$

where  $C$  is the circle of radius  $r$  centered at the origin, oriented counterclockwise.

Using Green's Theorem,

$$\oint_C P dx + Q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA,$$

where  $D$  is the disk of radius  $r$ . Compute

$$\frac{\partial Q}{\partial x} = \frac{\partial}{\partial x}(-x) = -1, \quad \frac{\partial P}{\partial y} = \frac{\partial}{\partial y}(y) = 1.$$

Hence

$$\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = -1 - 1 = -2.$$

Therefore,

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_D (-2) dA = -2 \text{Area}(D) = -2 \cdot \pi r^2 = -2\pi r^2.$$

So the integral is *not* zero (except in the degenerate case  $r = 0$ ). For clockwise orientation, the value would be  $+2\pi r^2$ .  $\square$



### 1.3 Divergence Theorem

1. Let  $\mathbf{F} = \langle x, y, z \rangle$ . Use the Divergence Theorem to compute the flux across the surface of the unit sphere.

**Sol.** content...

□

2. Let  $\mathbf{F} = \langle x^2, y^2, z^2 \rangle$ . Compute both the divergence and the surface integral over the unit cube  $[0, 1]^3$ .

**Sol.** content...



3. Use the Divergence Theorem to find the outward flux of  $\mathbf{F} = \langle yz, xz, xy \rangle$  through the unit cube.

**Sol.** content...



4. Let  $\mathbf{F} = \langle x, -y, z \rangle$ . Verify the Divergence Theorem on the upper hemisphere of radius 1 centered at the origin.

**Sol.** content...



## 1.4 Stokes' Theorem

1. Let  $\mathbf{F} = \langle -y, x, 0 \rangle$ . Use Stokes' Theorem to compute the circulation around the boundary of the disk  $x^2 + y^2 \leq 1$  in the  $xy$ -plane.

**Sol.** content...

□

2. Let  $\mathbf{F} = \langle z, 0, x \rangle$ . Use Stokes' Theorem on the triangular surface with vertices at  $(0, 0, 0)$ ,  $(1, 0, 0)$ ,  $(0, 1, 0)$ .

**Sol.** content...



3. Compute both sides of Stokes' Theorem for  $\mathbf{F} = \langle y, z, x \rangle$  on the surface  $z = 0$  bounded by the unit circle.

**Sol.** content...



4. Use Stokes' Theorem to show that

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$$

if  $\mathbf{F}$  is the gradient of some scalar field  $f$ .

**Sol.** content...

□



## 2 Differential Forms

TBA

### 3 Winding Numbers and Complexification

TBA