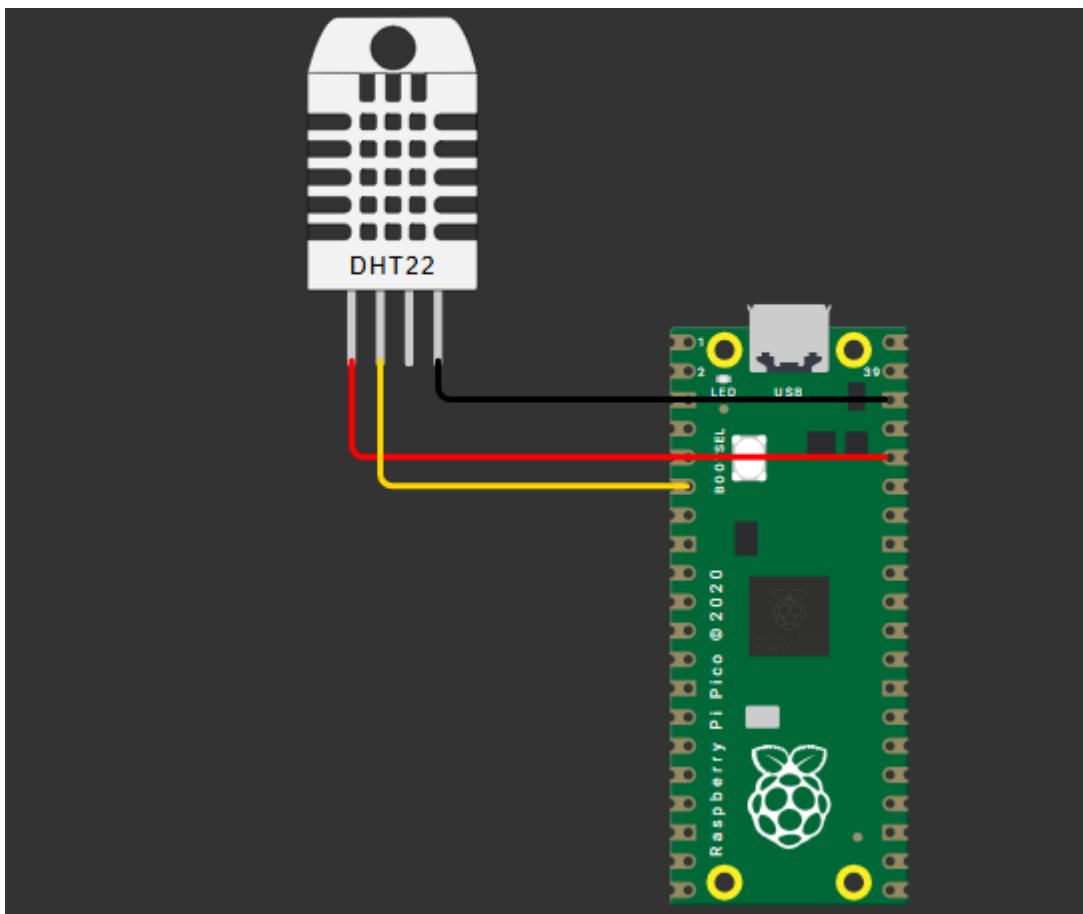


## PRACTICAL 2:

Understanding the connectivity of Raspberry-Pi /Beagle board circuit with temperature sensor. Write an application to read the environment temperature. If temperature crosses a threshold value, generate alerts using LEDs.



## PROGRAM:

```
# Paste this code into main.py and run it
import time
from machine import Pin
import dht

dht_pin = Pin(4, Pin.IN, Pin.PULL_UP)
dht_device = dht.DHT22(dht_pin)
```

```

print("DHT22 Isolation Test")
print("-----")
print("Waiting 2 seconds...")

time.sleep(2)
print("Attempting a single sensor reading...")

try:
    dht_device.measure()
    time.sleep(0.5)
    temp = dht_device.temperature()
    hum = dht_device.humidity()
    print(f"SUCCESS! Temperature: {temp}°C, Humidity: {hum}%")
except Exception as e:
    print(f"FAILURE! The sensor is not responding. Error: {e}")

print("-----")
print("Test finished.")

```

## OUTPUT:



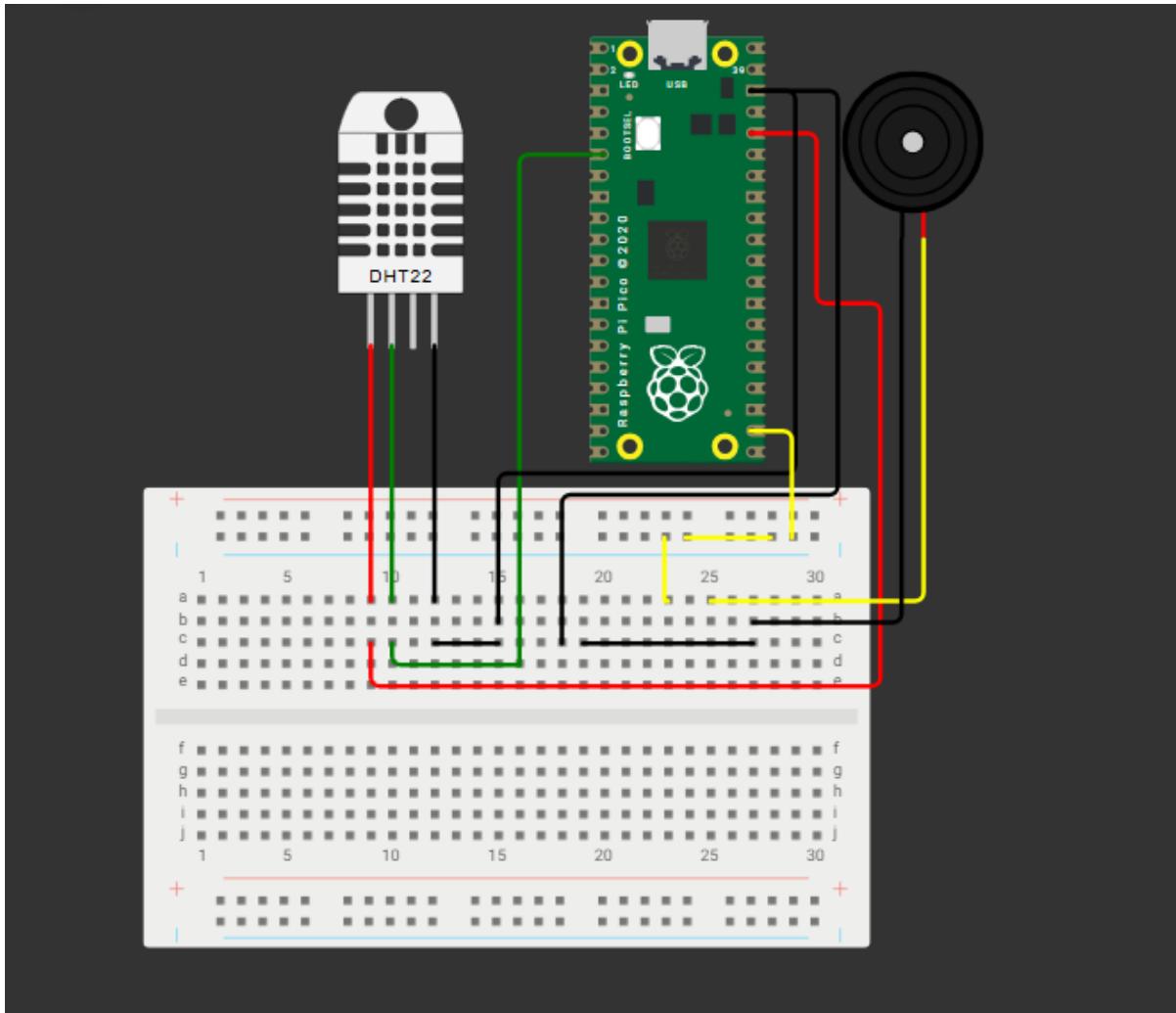
```

DHT22 Isolation Test
-----
Waiting 2 seconds...
Attempting a single sensor reading...
SUCCESS! Temperature: 31.0°C, Humidity: 40.0%
-----
Test finished.
MicroPython v1.24.1 on 2024-11-29; Raspberry Pi Pico with RP2040
Type "help()" for more information.
>>>

```

## ASSIGNMENT 2

Create a circuit using Raspberry Pi, DHT11 and Buzzer. Write a program when the temperature goes beyond 35 degrees, the buzzer will start ringing.



### PROGRAM:

```
import time  
from machine import Pin  
import dht  
  
# --- CONFIGURATION ---  
# The GPIO pin the DHT11 data line is connected to.
```

```
dht_pin = Pin(4, Pin.IN, Pin.PULL_UP)

# The GPIO pin the buzzer is connected to.
buzzer_pin = Pin(17, Pin.OUT)

# The temperature threshold in Celsius.
THRESHOLD_TEMP = 35.0

# --- HARDWARE INITIALIZATION ---
# Initialize the DHT11 sensor.
dht_device = dht.DHT11(dht_pin)

# Give the sensor a moment to settle.
print("Waiting for sensor to initialize...")
time.sleep(1)

# --- MAIN APPLICATION LOGIC ---
print("Temperature Alert System Started for Pico. Press CTRL+C to exit.")

while True:
    try:
        # In MicroPython, you must call measure() first.
        dht_device.measure()

        # Then you can read the temperature.
        temperature_c = dht_device.temperature()

        print(f"Current Temperature: {temperature_c:.1f}°C")

    # --- THRESHOLD CHECK AND ALERT ---

```

```

if temperature_c > THRESHOLD_TEMP:
    # Temperature is above the threshold, turn the buzzer ON.
    buzzer_pin.value(1) # 1 is ON
    print(f"ALERT! Temperature ({temperature_c:.1f}°C) is above
{THRESHOLD_TEMP}°C. BUZZER ON.")

else:
    # Temperature is normal, turn the buzzer OFF.
    buzzer_pin.value(0) # 0 is OFF
    print("Temperature is normal. Buzzer is OFF.")

```

except Exception as error:

```
# Errors happen fairly often with DHT sensors.
```

```
print(f"Failed to read sensor: {error}")
```

```
# Wait 2 seconds before the next reading.
```

```
time.sleep(2.0)
```

## OUTPUT:

