

```
function atrous_convolution()
{
    /*Works by increasing the
    size of the filter by app
    ending zeroes to fill the g
    ap between the parameters*/
    [Atrous Convolution](http
    s://nanonets.com/blog/conte
    nt/images/2020/08/main-qimg
    -d9025e88d7d792e26f4040b767
    b25819.png);
    Increase size by Dilation
    Rate;
    block{
        Dilation Rate = 1;
        3 x 3 Filter;
    }
    block{
        Dilation Rate = 2;
        5 x 5 Filter;
    }
    block{
        Dilation Rate = 3;
        7 x 7 Filter;
    }
}

/*Last pooling layer has
stride = 1 instead of 2*/
Downsample 8x only;
Series of Atrous layers a
plied to capture larger co
ntext;

/*Downsampling by 8x to c
ompare each pixel*/
Training;

/*Use Bilinear upsampling
to produce result of same
size*/
Upsampling;
Result Feature Map;
}

function spatial_pyramidal_
pooling(){
    /*Before SPP input images
    of multiple resolutions ar
    e supplied to FCN. Feature
    maps are then joined togeth
    er to extract multi-scale i
    nformation (Expensive compu
    tation and time)*/

    Problem;

    /*Capture multiscale info
    rmation from feature map us
    ing single input image*/
    [Spatial Pyramidal Poolin
    g](https://nanonets.com/blo
    g/content/images/2020/08/sp
    pnet.jpg);
    /*Input image of any size
    can be provided*/
    Advantage;

    /Single Input Image/;
    CNN Layers;
    Feature Maps;
    Spatial Pyramidal Pool;
    branch(a1){
        1x1;
    }
    branch(b1){
        2x2;
    }
    branch(c1){
        4x4;
    }
    }
    join(a1,b1,c1);
    /*Concatenated by convert
    ing to 1D vector, Gets mult
    i-scale information*/
    concatenation;
}

function atrous_spp(){
    [Atrous Spatial Pyramidal
    Pooling](https://nanonets.
    com/blog/content/images/202
    0/08/deeplab_aspp.jpg);
    call spatial_pyramidal_po
    oling();
    /*Fusing information from
    different scale and applyi
    ng to atrous convolution. I
    nputs are convolved with di
    fferent dilation rates and
    outputs are fused together*/
    /
    Concept;
    /Input Feature Map/;
    Convolve with;
    branch(a2){
        Filter Size (3x3);
        Dilation rate 6;
        Output1;
    }
    branch(b2){
        Filter Size (3x3);
        Dilation rate 12;
        Output2;
    }
    branch(c2){
        Filter Size (3x3);
        Dilation rate 18;
        Output3;
    }
    branch(d2){
        Filter Size (3x3);
        Dilation rate 24;
        Output4;
    }
    }
    join(a2,b2,c2,d2);
    /*Outputs concatenated du
    e to same size*/
    Concatenation;
    Fused Output;
    /*Stride to keep downsamp
    le 8x*/
    Convolve with 1x1 map;
    Upsampling;
    /*To keep Global Contextu
    al Information*/
    Output1;
    /*Get the required number
    of channels*/
    Pass through 1x1 Convolut
    ion;
    Improved Results;
}

}

/*Multitude techniques for
results improvement by Goog
le*/
Deeplab Neural Network;
block{
    branch(theory){
        /*Three main improvements
        */
        Theory;
        /*Problem:
        Excessive downsizing due
        to consecutive pooling. (Do
        wnsampled by 32x)*/
        Loss of Information;
        /*Upsampling 32x will cau
        se*/
        Compute and Memory expens
        ive operation ;

        /*Solution to understand
        large context using same nu
        mber of parameters*/
        [Atrous convolution](http
        s://nanonets.com/blog/conte
        nt/images/2020/08/main-qimg
        -d9025e88d7d792e26f4040b767
        b25819.png);
        call altrous_convolution(
        );

        Altrous spatial pyramidal
        pooling;

        call spatial_pyriamidal_p
        ooling;
        call atrous_spp();
    }
    ||Conditional Random Fiel
    d||;
}
}
block{
    branch(logic)
    {
        Logic;
    }
}
join(theory, logic)
```

