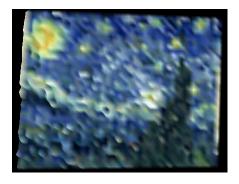
Mini project 2022

Submitted by: Noam Ariea Spiegelstein 315770453 and Hadar Lieber 208827352

In this project, we developed a software application that uses altitude interpolation to transform 2D images into 3D models using mesh generation. The program is written in C++, using the libraries OpenGL and OpenCV. The generated 3D models can be translated, scaled, and rotated in the X-axis, Y-axis, Z-axis, and Zoom-in and out.

The program enables 3D model representation in <u>two resolutions</u> (high and low); wherein the high resolution model is constructed of 4x triangles from the number of triangles in the low resolution.





LOW-RES HIGH-RES

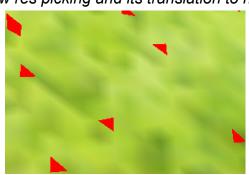
The Program represents the triangles used to draw the 3D model with the following structs:

```
typedef struct Triangle {
typedef struct TriPoint {
                                                     TriPoint p1:
        GLint x;
                                                      TriPointColor c1;
         GLint y;
                                                     TriPointColor c2;
                                                     TriPoint p3:
}TriPoint;
                                                     TriPointColor c3;
                                                     bool isPicked;
typedef struct TriPointColor {
                                                     GLfloat left r:
         GLfloat z;
                                                     GLfloat left_g;
                                                     GLfloat left_b;
         GLfloat r;
                                                     int parentId;
                                                     int vectorIndex;
         GLfloat g;
                                                     bool collision;
         GLfloat b;
                                                     int bfsParentId:
}TriPointColor;
                                               }Triangle;
```

The triangles are initially loaded once per image specification at the beginning of the program into 3 different Triangle vectors. The triangles vectors are Low-Resolution, High-Resolution and High-Resolution-Collision. Low-Res and High-Res vectors enable picking persistence throughout the program, and High-Res-Collision vector enables efficient path-finding in high resolution. Pre-loading the vectors substantially lowered the buffer time between moving from high-res to low-res.

The program enables picking of triangles - The user can choose specific triangles with the mouse. We implemented that by giving each triangle a unique ID (which is stored in its special coloring members left_r/g/b). When the user clicks the screen, the model is drawn with its color-ID for a short time. The color pointed to by the mouse is then read and translated to a triangle-id (its location in the current vector), and the triangle at the specified id is signed as picked through its member isPicked. Picked triangles are pushed into a picked-triangles map to enable efficient picking translation from high-res to low-res. The function is reversible; when the user clicks a selected triangle, it returns to its original color.

low res picking and its translation to high res picking and vice versa



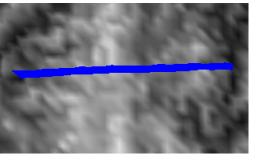


Special Operations

- 1.Shortest path implementation with BFS
- 2.flight path finding (path without collision) Implementation with BFS

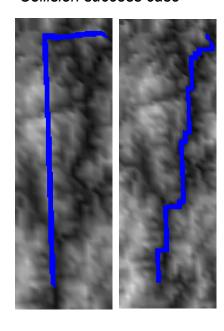
Shortest Path and collision comparison

Collision failure case



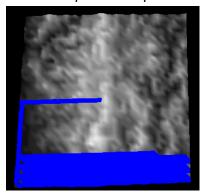


Collision success case



3.path between 2 points - implementation with DFS

DFS path example



Interaction with the Program is done via the following keyboard and mouse prompts.

UpZoom-InDownZoom-OutLeftY rotationRightY rotationZZ rotationXZ rotationMX rotationNX rotationHHigh-resolutionLLow-resolutionBBFSCNo collision pathDDFSLeft clickPick a triangle		
Left Y rotation Right Y rotation Z Z rotation X Z rotation M X rotation N X rotation H High-resolution L Low-resolution B BFS C No collision path D DFS	Up	Zoom-In
Right Y rotation Z Z rotation X Z rotation M X rotation N X rotation H High-resolution L Low-resolution B BFS C No collision path D DFS	Down	Zoom-Out
Z Z rotation X Z rotation M X rotation N X rotation H High-resolution L Low-resolution B BFS C No collision path D DFS	Left	Y rotation
X Z rotation M X rotation N X rotation H High-resolution L Low-resolution B BFS C No collision path D DFS	Right	Y rotation
M X rotation N X rotation H High-resolution L Low-resolution B BFS C No collision path D DFS	Z	Z rotation
N X rotation H High-resolution L Low-resolution B BFS C No collision path D DFS	Х	Z rotation
H High-resolution L Low-resolution B BFS C No collision path D DFS	М	X rotation
L Low-resolution B BFS C No collision path D DFS	N	X rotation
B BFS C No collision path D DFS	Н	High-resolution
C No collision path D DFS	L	Low-resolution
D DFS	В	BFS
	С	No collision path
Left click Pick a triangle	D	DFS
	Left click	Pick a triangle