Helical Gears

$$d = mN$$

$$= \frac{m_n}{\cos \psi} N$$

 $\tan \varphi_n = \tan \varphi_t \cos \psi$

$$W_a = W_t \tan \psi$$

$$W_r = W_t \tan \varphi_t$$

Spur gears:

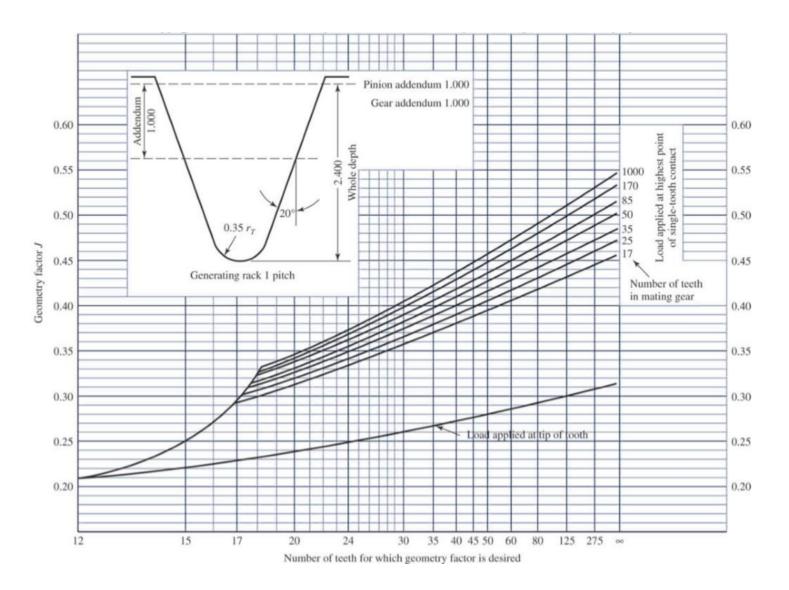
Bending Stress:

$$\sigma = \frac{W_t}{bmJ} K_v K_0 K_s K_H K_B$$

Dynamic factor K_v:

$$K_v = \left(\frac{A + \sqrt{200V}}{A}\right)^B$$
, V is the tangential velocity in m/s $A = 50 + 56(1 - B)$

$$B = 0.25(12 - Q_v)^{\frac{2}{3}}$$



Module m	Factor k _b	Module m	Factor k _b
1-2	1.000	11	0.843
2.25	0.984	12	0.836
2.5	0.974	14	0.824
2.75	0.965	16	0.813
3	0.956	18	0.804
3.5	0.942	20	0.796
4	0.930	22	0.788

 $K_s = 1 / k_b$

		Face Width, mm			
Characteristic of support	0- 50	150	22 5	400 up	
Accurate mounting, small bearing clearance, minimum deflection, precision gears	1.3	1.4	1.5	1.8	
Less rigid mountings, less accurate gears, contact across full face	1.6	1.7	1.8	2.2	
Accuracy and mounting such that less than full face contact exists		Over 2.2			

Bending Strength:

$$\sigma_{FP} = \sigma_{FP}^{\prime} (Y_N / Y_{\theta} Y_Z)$$

$$\sigma_{FP}^{\prime} = 0.703 H_B + 113 \qquad MPa$$

Reliability	Yz	
0.9999	1.5	
0.999	1.25	
0.99	1	
0.9	0.85	
0.5	0.7	

Contact Stress:

$$\sigma_c = C_p \sqrt{\frac{W_t}{bd_p I} K_v K_o K_s K_H C_f}$$

$$I = \frac{\cos\varphi\sin\varphi}{2} \frac{m_G}{m_G + 1}$$

Contact strength:

$$oldsymbol{\sigma}_{HP} = oldsymbol{\sigma}_{HP}^{\setminus} \, rac{Z_N C_H}{Y_{ heta} Y_Z}$$

$$\sigma_{HP}^{\setminus} = 2.22 \text{ H}_{B} + 200 \text{ MPa}$$

