Selection of Ball Bearings:

If both radial and axial (thrust) loads exist then an equivalent radial load should be determined:

$$F_{eq} = P = VXF_r + YF_a$$



 F_{eq} = equivalent radial load.

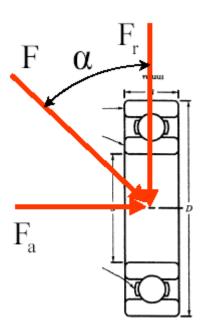
 F_r = applied radial load.

 F_a = applied thrust load.

X = radial load coefficient.

Y = axial load coefficient.

V = a rotation factor (V = 1 for rotating inner ring and 1.2 for rotating outer ring)



$$F_{eq} \equiv P = F_r$$
 when $\frac{F_a}{VF_r} \le e$

$$F_{eq} \equiv P = VXF_r + YF_a$$
 when $\frac{F_a}{VF_r} > e$

 $e \rightarrow is$ given in the bearing tables according to the value

of
$$\frac{F_a}{C_a}$$
,

Where

C_o is the static basic load rating.

Table for X, Y for deep groove ball bearings:

F _a /C _o	е	Х	Y	
0.025	0.22	0.56	2	
0.04	0.24	0.56	1.8	
0.07	0.27	0.56	1.6	
0.13	0.31	0.56	1.4	
0.25	0.25 0.37		1.2	
0.5 0.44		0.56	1	

Principal dimensions		Basic load ratings dynamic static		Limiting speeds Lubrication		Mass	Designations Bearings with		
đ	D	В	C	C ₀	grease oil	Gill		cylindrical bore	tapered bore
mm N			r/min		kg	-			
20	47 47 52 52	14 18 15 21	9 950 12 500 12 400 18 200	3 200 3 900 4 000 5 300	15 000 14 000 12 000 11 000	18 000 17 000 15 000 14 000	0,12 0,14 0,16 0,21	1204 2204 1304 2304	-
25	52 52 62 62	15 18 17 -24	12 100 12 400 17 800 24 200	4 060 4 250 6 000 7 500	13 000 11 000 9 500 9 500	16 000 14 000 12 000 12 000	0,14 0,16 0,26 0.34	1205 2205 1305 2305	1205 K 2205 K 1305 K

Example:

Select a deep groove ball bearing for the given loading conditions:

$$F_r = 3000 \text{ N}$$
 radial load

$$F_a = 1000 \text{ N}$$
 axial (thrust) load

$$n = 2000 \text{ rpm}$$
 (for inner ring – Shaft)

$$L_h = 4 \text{ kh}$$

The diameter of the shaft at the bearing is 25 mm.

Solution:

1-From the bearing catalog select bearing 2205:

$$d = 25 \text{ mm}$$
, $D = 52 \text{ mm}$, $B = 18 \text{ mm}$, $C = 12400 \text{ N}$, $C_0 = 4250 \text{ N}$

2- Calculate the ratio (F_a / C_o)

$$F_a / C_o = 1000 / 4250 = 0.235$$

From tables
$$e = 0.37$$

3- calculate the ratio (F_a / VF_r)

$$F_a / VF_r = 1000 / 3000 = 0.33333 < e$$

4- since
$$F_a / VF_r < e$$
, then $X = 1$, $Y = 0$

5- $F_{eq} = XVF_r + YF_a = 1 \times 1 \times 3000 + 0 = 3000 \text{ N}$ 6- The required dynamic loading capacity:

$$C_R = k_A F_{eq} \left[\left(\frac{L_D}{L_R} \right) \left(\frac{n_D}{n_R} \right) \right]^{1/a}$$
$$= 1 \times 3000 \left[\frac{4000}{500} \frac{2000}{\left(\frac{100}{3} \right)} \right]^{\frac{1}{3}} = 23489.2 \text{ N}$$

Which is greater than the dynamic loading capacity of the selected Bearing (C = 12400 N)

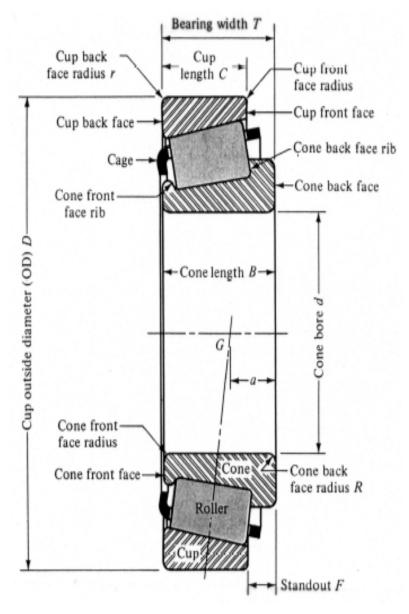
7- select another bearing; bearing 2305 d = 25 mm, d = 62 mm, B = 24 mm, C = 24200 N, C_o = 7500 N F_a / C_o = 1000 / 7500 = 0.133 then e = 0.31 Since F_a / VF_r = 0.333 > e, then X = 0.56, Y = 1.4 $F_{eq} = XVF_r + YF_a = 0.56$ x 3000 + 1.4 x 1000 = 2680 N The required dynamic loading capacity

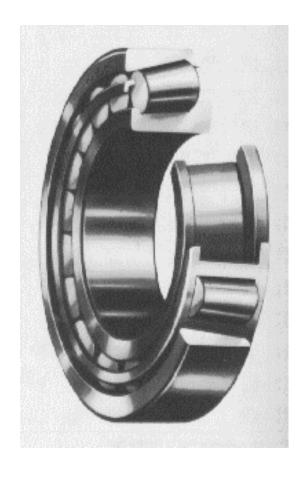
C = 20983.7 N < 24200 N of the selected bearing.

Selection of Taper Roller Bearings

The nomenclature for a taper roller bearings is shown in the figure

Below.



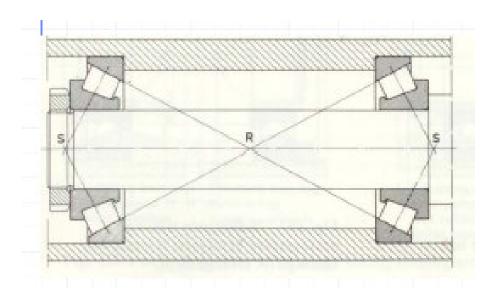


- The inner ring is called the cone, and the outer ring is called the cup.
- It can be seen that, a tapered roller bearing is separable in that the cup can be removed from the cone and roller assembly.
- This type of bearing can carry both radial and axial loads or any combinations of the two.
- However, even when an external axial load is not present, the radial load will induce a thrust (axial) reaction within the bearing because of the taper.

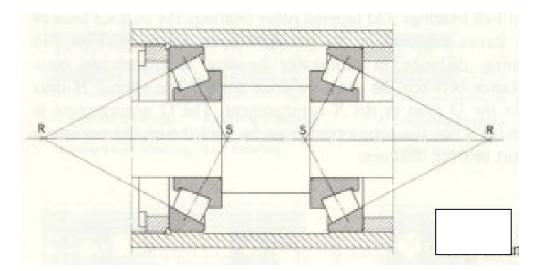
The equivalent dynamic bearing load is given by:

$$F = F_r$$
 when $F_a / F_r \le e$
 $F = 0.4 F_r + YF_a$ when $F_a / F_r > e$

- The mounting of bearings can be as follows: a- O-configuration (back-to-back).



b- X-configuration (face-to-face).



Axial loading of taper roller bearings

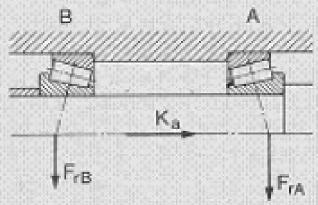
Arrangement

Load case

Axial loads

Back-to-back

Face-to-face



1a)
$$\frac{F_{rA}}{Y_A} \ge \frac{F_{rB}}{Y_B} \qquad \qquad F_{aA} = \frac{0.5 \; F_{rA}}{Y_A} \qquad F_{aB} = F_{aA} \; \pm \; K_a$$

$$K_a \ge 0$$

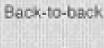
1b)
$$\frac{F_{rA}}{Y_A} < \frac{F_{rB}}{Y_B}$$

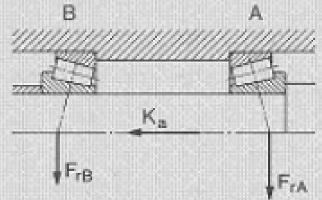
$$K_B \ge 0.5 \left(\frac{F_{rB}}{Y_B} - \frac{F_{rA}}{Y_A} \right)$$

1b)
$$\frac{F_{rA}}{Y_A} < \frac{F_{rB}}{Y_B}$$
 $F_{aA} = \frac{0.5 F_{rA}}{Y_A}$ $F_{aB} = F_{aA} + K_a$
 $K_a \ge 0.5 \left(\frac{F_{rB}}{Y_A} - \frac{F_{rA}}{Y_A}\right)$

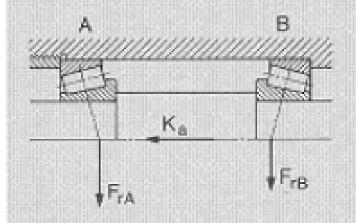
1c)
$$\begin{split} \frac{F_{rA}}{Y_A} &< \frac{F_{rB}}{Y_B} \\ K_a &< 0.5 \ \left(\frac{F_{rB}}{Y_B} - \frac{F_{rA}}{Y_A} \right) \end{split}$$

te)
$$\frac{F_{rA}}{Y_A} < \frac{F_{rB}}{Y_B}$$
 $F_{aA} = F_{aB} - K_a$ $F_{aB} = \frac{0.5 \; F_{rB}}{Y_B}$





Face-to-face



$$\begin{aligned} 2a) & & \frac{F_{rA}}{Y_A} \leq \frac{F_{rB}}{Y_B} \\ & & K_a \geq 0 \end{aligned}$$

a)
$$\frac{F_{rA}}{Y_A} \le \frac{F_{rB}}{Y_B}$$
 $F_{aA} = F_{aB} + K_a$ $F_{aB} = \frac{0.5 F_{rB}}{Y_B}$
 $K_c \ge 0$

2b)
$$\begin{split} \frac{F_{rA}}{Y_A} > & \frac{F_{rB}}{Y_B} \\ K_a \ge 0.5 & \left(\frac{F_{rA}}{Y_A} - \frac{F_{rB}}{Y_B}\right) \end{split}$$

2c)
$$\begin{split} \frac{F_{rA}}{Y_A} > & \frac{F_{rB}}{Y_B} \\ K_a < 0.5 & \left(\frac{F_{rA}}{Y_A} - \frac{F_{rB}}{Y_B}\right) \end{split} \qquad F_{aA} - K_a \end{split}$$

Designation of Bearing (bearing codes):

- Rolling element bearings re categorized by a code made up of two sections:

A- section 1:

The code for the bearing series which is further divided into:

- a type code,
- a diameter series and in many cases a width series.

B- section 2:

The code for the bore diameter.



- Type code:

The first digit, letter of the bearing code define the bearing type.

- •1 Self aligning ball
- •2 Type 1 but wider
- •3 Double row angular contact
- •4 Double row ball
- •6 Single row ball (deep groove)
- •7 Single row angular contact
- •16 Type 6 but narrower
- •22 Self aligning roller
- •23 Type 22 but wider
- •51 Thrust ball
- •M Radial ball with filling slots
- •N Cylindrical roller
- •HJ Separate thrust collar)
- •QJ Single row duplex ball

- Diameter and width series (dimension series):
- The second pair of digits define the dimension series.

series

Bore

- The first number is from the width series (0, 1, 2, 3, 4, 5 and 6)
- The second number is from the diameter series (outside diameter). (8, 9, 0, 1, 2, 3 and 4).

Width series \longrightarrow 0 1 2 3

Diameter series \bigcirc 2 \bigcirc 2 \bigcirc 3

Dimension \bigcirc 2 \bigcirc 2 \bigcirc 3 \bigcirc 2 \bigcirc 3 \bigcirc 2 \bigcirc 3 \bigcirc 3 \bigcirc 4 \bigcirc 5 \bigcirc 6 \bigcirc 6 \bigcirc 6 \bigcirc 7 \bigcirc 8 \bigcirc 9 \bigcirc 9

OD

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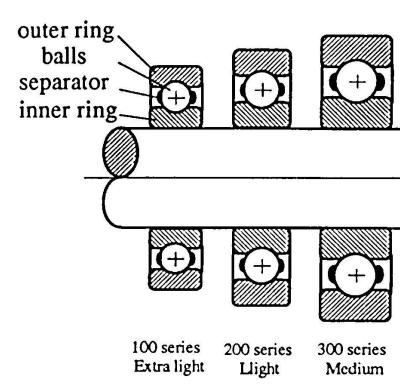
The most common sizes being defined as follows:

- 0 Extra light
- 1 Extra light thrust
- 2 Light
- 3 Medium
- 4 Heavy

Note:

For 02, 03, 04 the zero is ignored

Example: 0 2 (0 is width series, 2 is diameter series).



- Bore code: (inner diameter)

- Bores from 10-17 mm:

Bore diameter	code		
10	00		
12	01		
15	02		
17	03		
20	04		

- Bores from 20-480 mm:

Code no.= Bore diameter / five

Example: NU 2355 Type: Roller Bearing Width Series 2 Diameter Series 3 Bore Diameter 55

- Designation of Bearing:

Rolling element type

Designation Number	62 00	6201	6202	6203	6204	6205
Bore diameter	10	12	15	17	20	25

