

# Mechatronics Engineering

## I2C Communication Protocol

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## I2C History

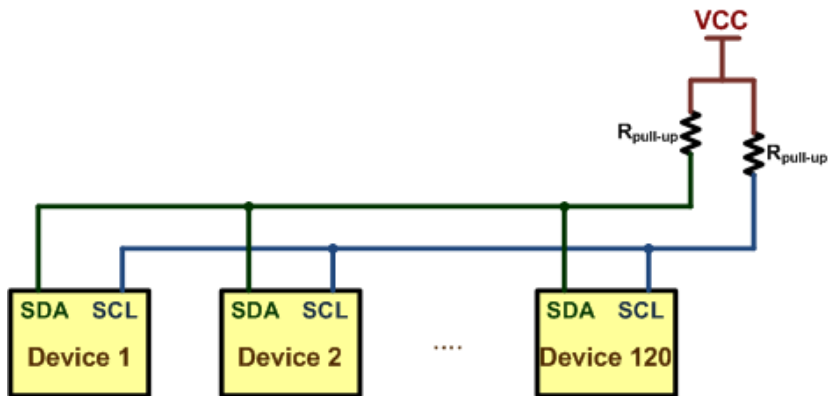
- IIC: Inter-Integrated Circuit
- Philips
- 1982
- Aim: connecting many devices (around 128 devices) to the MCU using two wires



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## Connecting devices using I2C

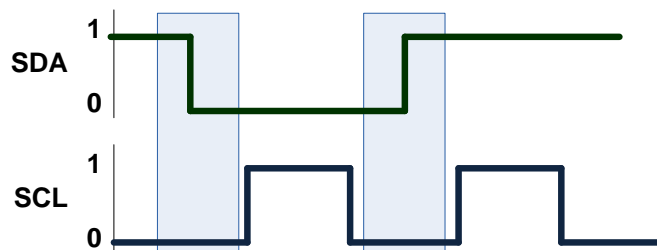
- SDA: Serial Data
- SCL: Serial Clock
- Open-collector devices (Wire AND)



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## Sending bits of data

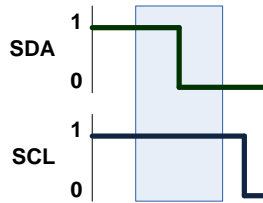
- The SDA values changes when SCL is low.
- The receiver reads SDA on the falling edge of SCL.



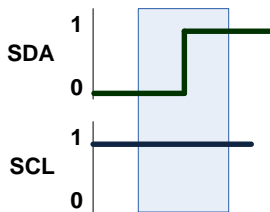
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## Start and Stop conditions

- Start



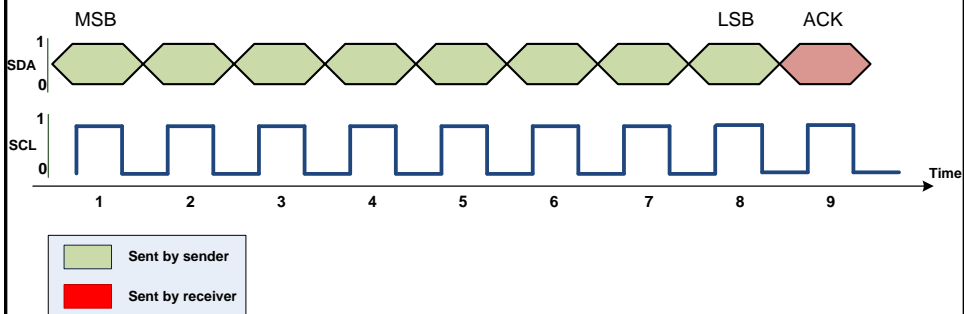
- Stop



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## Packet Format

- Each packet is 9 bits long.
- First 8 bits are put on SDA by the transmitter
- The 9th bit is an acknowledge by the receiver
  - NACK (leave high) or ACK (pull down)



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## Master vs. Slave

- Master
  - Begins the communication
  - Chooses the slave
  - Makes clock
  - Sends or receives data
- Slave
  - Responds to the master
  - Each slave has a unique 7-bit address



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## Master vs. Slave (Cont.)

- There might be more than 1 master on an I2C bus
- Each device can be both Master and Slave



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## Steps of a communication

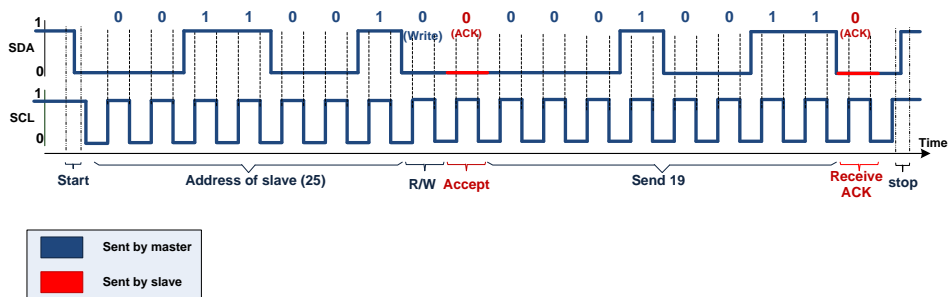
1. Start
2. Address
3. Send or Receive (Write or read)
4. Acknowledge
5. Send/receive a byte of data
6. Acknowledge
7. Stop



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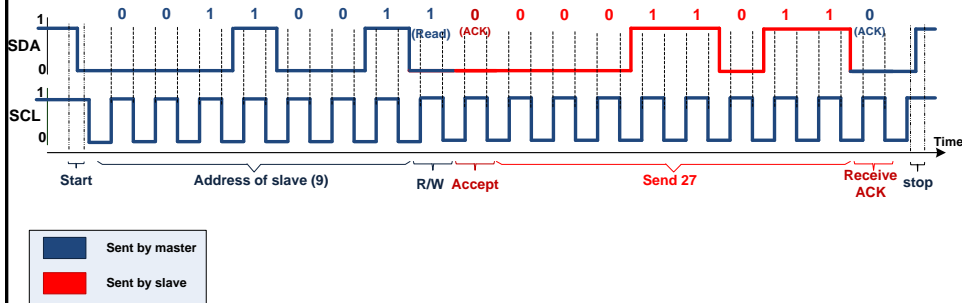
## Sending a byte

- Sending 19 to device 25.



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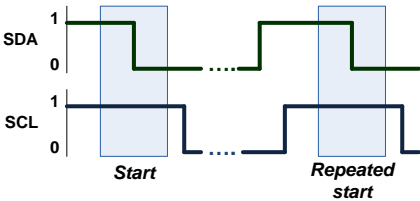
## Receiving a byte from Device 9



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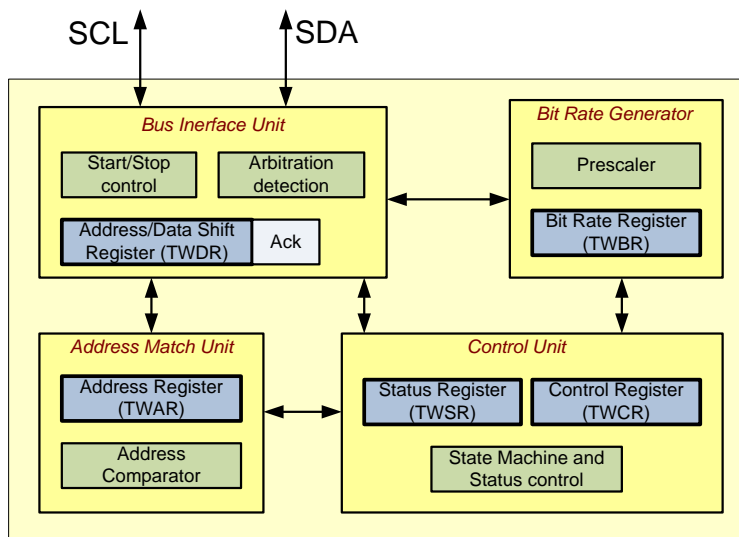
## Repeated start

- A new Start condition before the Stop condition



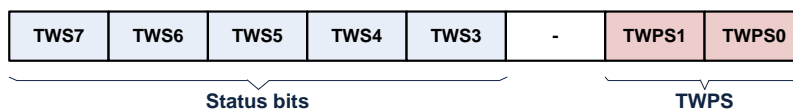
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## I2C (TWI) Unit in AVR



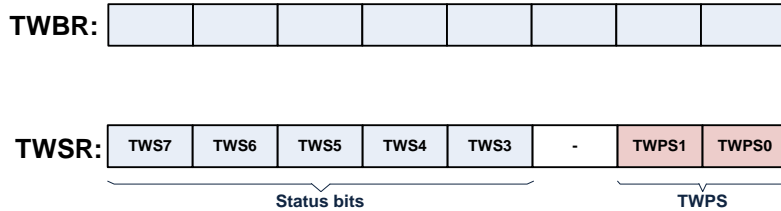
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## TWSR (TWI Status Register)



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## TWBR (TWI Bit Rate) Register

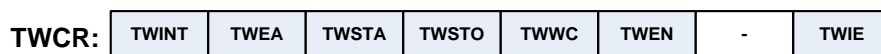


$$frequency = \frac{XTAL}{16 + 2 \times TWBR \times 4^{TWPS}}$$



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## TWCR



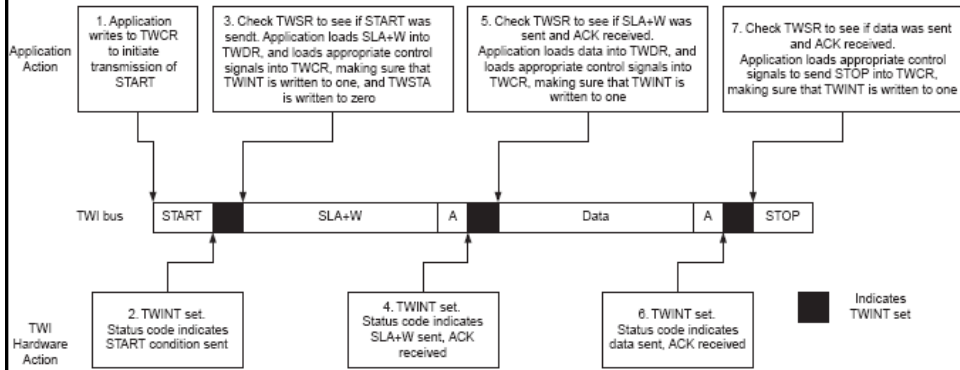
- TWINT: TWI Interrupt flag
- TWEA: TWI Enable Acknowledge bit  
    ➤ 1:ACK, 0:NACK
- TWSTA: TWI Start condition bit
- TWSTO: TWI Stop condition bit
- TWWC: TWI Write Collision flag
- TWEN: TWI Enable bit
- TWIE: TWI Interrupt Enable



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## TWI Control Register



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## TWAR (TWI Address Register)

**TWAR:**

TWA6	TWA5	TWA4	TWA3	TWA2	TWA1	TWA0	TWGCE
------	------	------	------	------	------	------	-------

- TWA6-0 (TWI slave Address)
- TWGCE (TWI General Call Recognition Enable bit)
  - 1: Answer to general call



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## TWDR (TWI Data Register)



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## TWI, Master Mode programming

- Initializing
  - Set the TWI module clock frequency by setting the values of the TWBR register and the TWPS bits in the TWSR register.
  - Set the TWEN bit in TWCR to one to enable the TWI module
- Transmit START condition
  - Set TWEN, TWSTA, and TWINT bits of TWCR to one.



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## TWI, Master Mode programming

- Send Data

- Copy the data byte to the TWDR
- Set the TWEN and TWINT bits of the TWCR to one to start sending the byte.
- Poll TWINT flag in TWCR register to see whether the byte transmitted completely

- Receive Data

- Set TWEN and TWINT bits of TWCR to one to start receiving a byte.
- Poll TWINT flag in TWCR to see whether a byte has been received completely
- read the received byte from the TWDR



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## TWI, Master Mode programming

- Transmit STOP condition

- Set TWEN, TWSTO, and TWINT bits of TWCR to one
  - Note: we cannot poll the TWINT flag after transmitting the STOP condition



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## Writing and reading a byte in master mode

```
#include <avr/io.h>

void i2c_write(unsigned char data)
{
    TWDR = data ;
    TWCR = (1<< TWINT) | (1<<TWEN);
    while ((TWCR & (1 <<TWINT)) == 0);
}

//*****
unsigned char i2c_read(unsigned char isLast)
{
    if (isLast == 0) //send ACK
        TWCR = (1<< TWINT) | (1<<TWEN) | (1<<TWEA); //send ACK
    else
        TWCR = (1<< TWINT) | (1<<TWEN); //send NACK
    while ((TWCR & (1 <<TWINT)) == 0);
    return TWDR;
}
```



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```
void i2c_start(void)
{
    TWCR = (1 << TWINT) | (1 << TWSTA) | (1 << TWEN);
    while ((TWCR & (1 << TWINT)) == 0);
}

void i2c_stop()
{
    TWCR = (1<<TWINT) | (1<<TWEN) | (1<<TWSTO);
}

void i2c_init(void)
{
    TWSR=0x00; //set prescaler bits to zero
    TWBR=152; //SCL frequency is 50K for XTAL = 16M
    TWCR=0x04; //enable the TWI module
}
```



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```

int main (void)
{
    i2c_init();

    //writing a byte
    i2c_start();           //transmit START condition
    i2c_write(0b11010000); //transmit SLA + W(0)
    i2c_write(0b11110000); //transmit data
    i2c_stop();            //transmit STOP condition

    //reading a byte
    i2c_start();           //transmit START condition
    i2c_write(0b11010001); //transmit SLA + R(1)
    PORTD =i2c_read(1);    //read one byte of data
    i2c_stop();            //transmit STOP condition
    while(1);              //stay here forever
}

```



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## TWI, Slave Mode programming

- Initializing

- Set the slave address by setting the values for the TWAR register.
  - 7 bits for address
  - 8<sup>th</sup> bit is TWGCE ( 1 = answer general calls)
- Set the TWEN bit in TWCR to one to enable the TWI module
- Set the TWEN, TWINT, and TWEA bits of TWCR to one to enable the TWI and acknowledge generation

- Listening

- poll the TWINT flag to see when the slave is addressed by a master device or use its interrupt



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## TWI, Slave Mode programming

- Send Data

- Copy the data byte to the TWDR
- Set the TWEN, TWEA, and TWINT bits of the TWCR register to one to start sending the byte.
- Poll TWINT flag in TWCR register to see whether the byte transmitted completely

- Receive Data

- Set TWEN and TWINT bits of TWCR to one to start receiving a byte.
- Poll TWINT flag in TWCR to see whether a byte has been received completely
- read the received byte from the TWDR



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