

# Deep Learning

QCon London, March 9th

# Today's Overview

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- ▶ 9:00 Introduction to Deep Learning
  - ▶ Short recap on machine learning
  - ▶ Build and train a perceptron in numpy
  - ▶ Gradient Descent
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- ▶ 16:00 End of workshop

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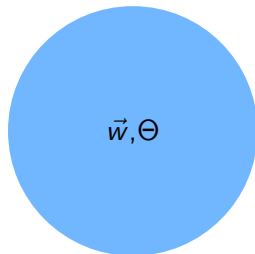
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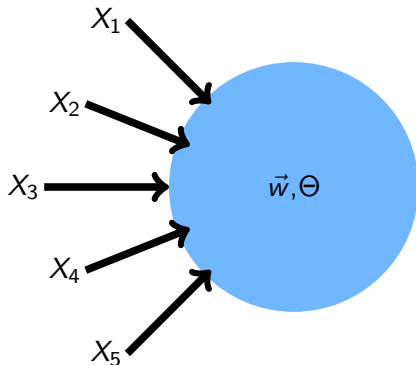
# Perceptron

- ▶ The perceptron contains a weight ( $\vec{w}$ ) for each input and a threshold ( $\Theta$ )



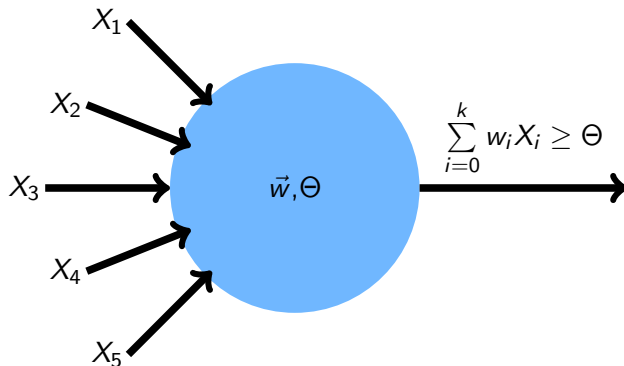
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- ▶ Its output can be calculated as  $\sum_{i=0}^k w_i X_i \geq \Theta$



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- ▶ Restart the process until the solution is found
- ▶ Let us actually implement this in the first notebook (Perceptron)

# Conclusions

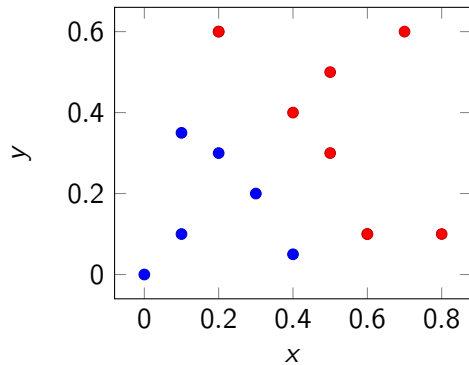
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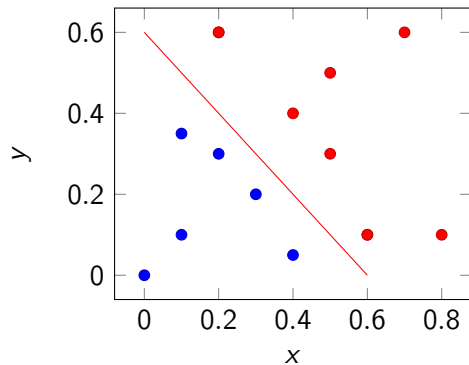
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- ▶ Congratulations on training your first perceptron! You just taught a computer to learn!
- ▶ Why didn't we wait for the final weights, but stop after one run over the dataset?

# Linear Separability

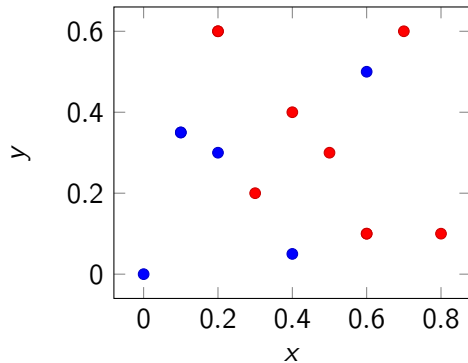
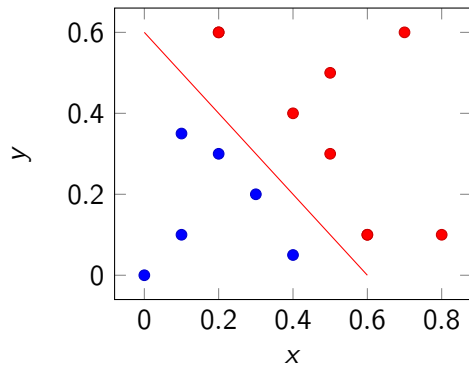


## Linear Separability



Data are linearly separable -> Can be divided by a plane

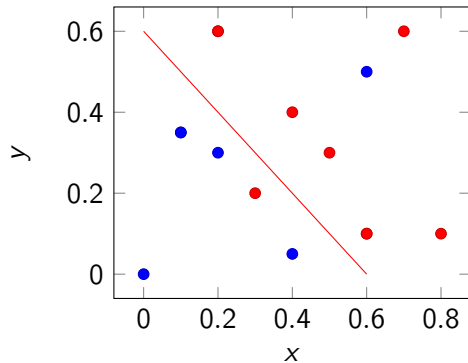
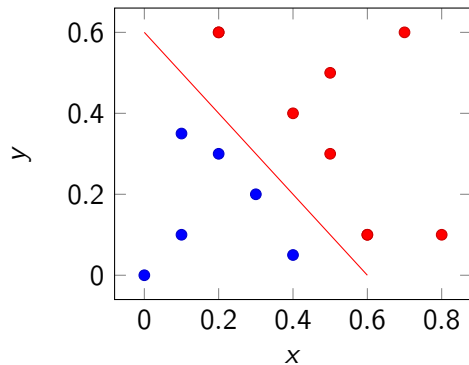
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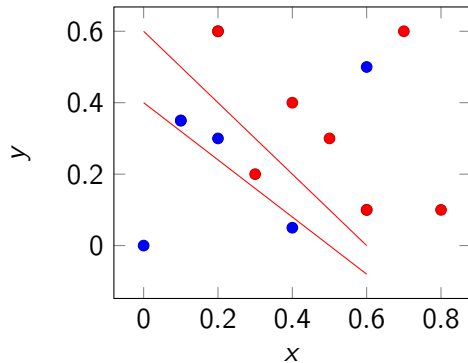
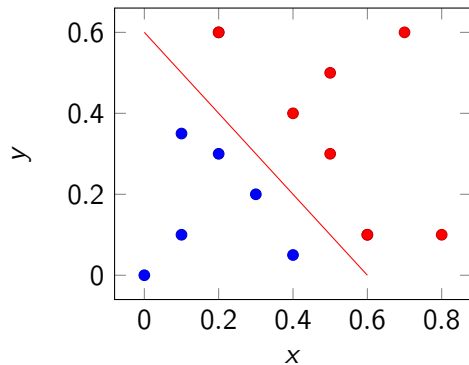


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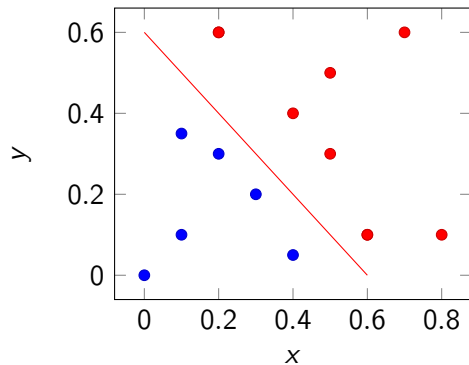
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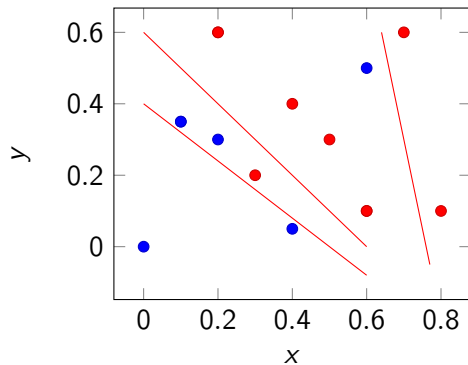


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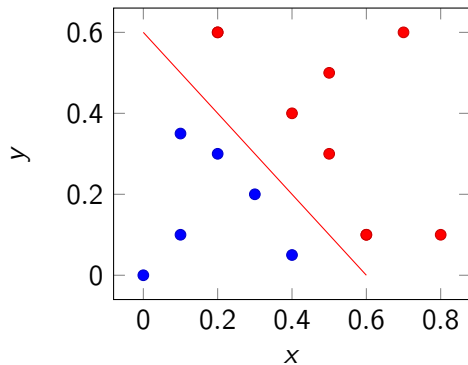


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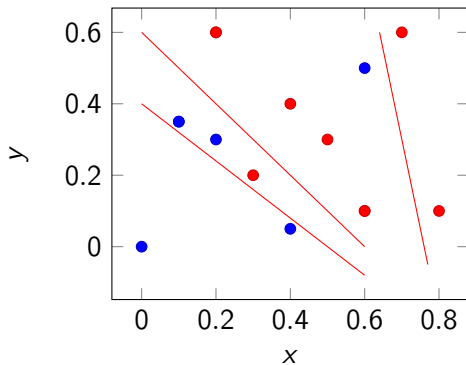


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The algorithm only converges, if the problem is linearly separable.

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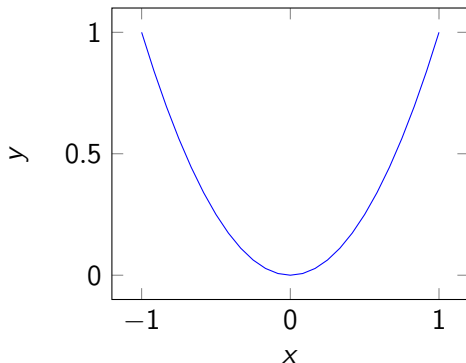
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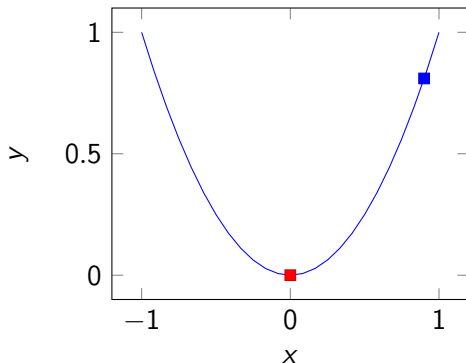
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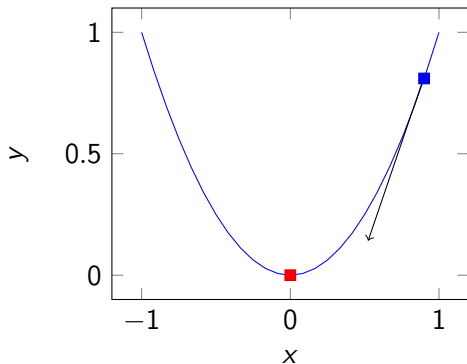
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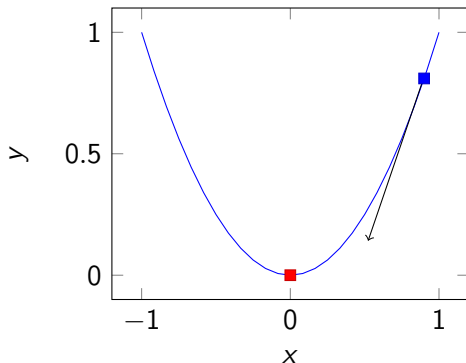
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- ▶ Every deep learning framework can calculate those weights using the chain rule and backpropagation.



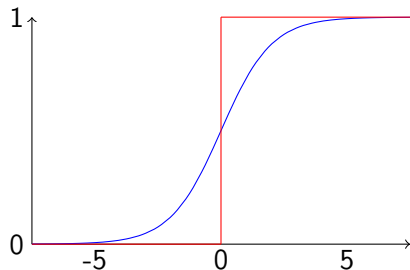
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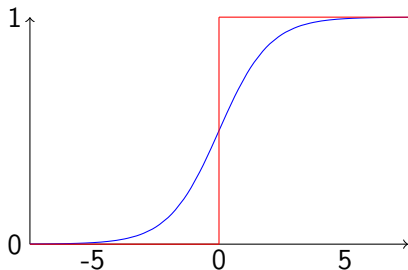
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- ▶ The sigmoid allows us to convert the strict classification into a regression over the probability for each point to belong to a certain class



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- ▶ With this we can define the general loss
- ▶ Cross-Entropy  $E = -\frac{1}{n} \sum_{i=1}^n \sum_{k=1}^m y_{i,k} \ln p_{i,k}$   
 $y_{i,k}$  1, if  $i = k$  else 0  
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# Neural Network

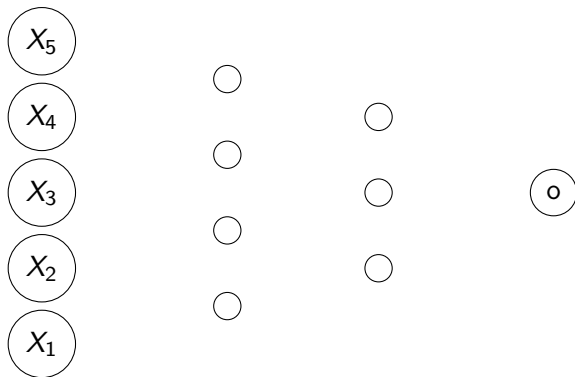
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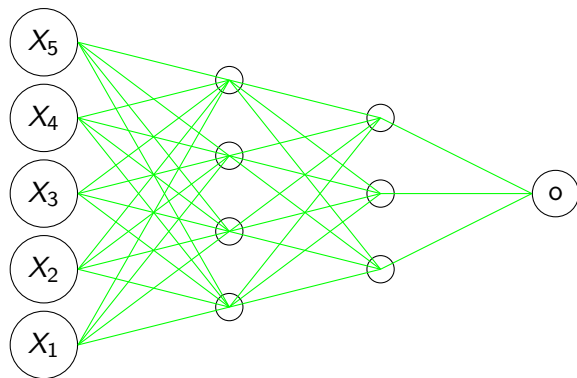
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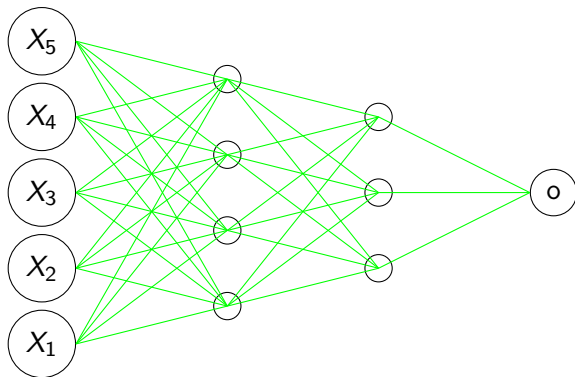
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- ▶ However, instead of going from start to end directly we now add hidden units
- ▶ For each of the units we now apply the sigmoid function
- ▶ Since every unit is differentiable, the whole network is differentiable  
→ We can use backpropagation to minimise the error as we can calculate the gradients



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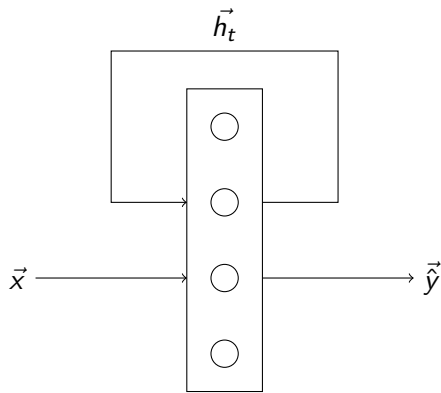
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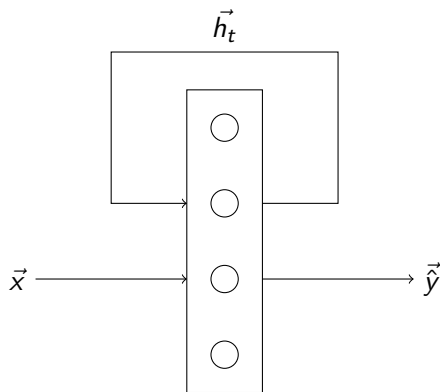
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- ▶ What do we do if we want to store information about previous examples in the network

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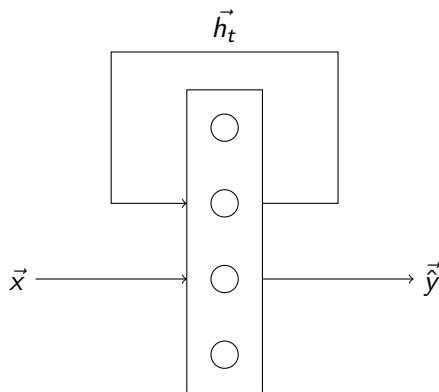
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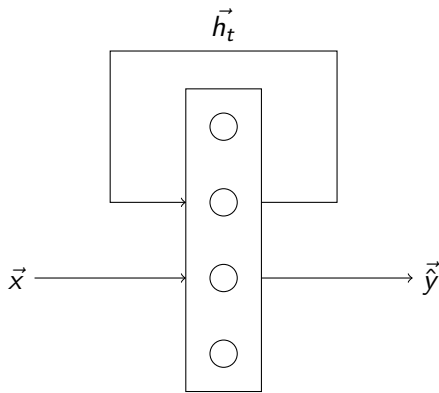
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$$\vec{h}_t = \sigma_h(W_h \vec{x}_t + U_h \vec{h}_{t-1} + b_h)$$
- ▶ From this hidden state the current output is calculated as
$$\vec{y}_t = \sigma_y(W_y \vec{h}_t + b_y)$$
- ▶ These networks cannot represent long-term dependencies as  $U_h$  is always multiplied by itself.



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# Word2Vec

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- ▶ How can we turn text into numbers?

# Chatbot

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► Let's chat