## Deep Learning

QCon London, March 9th

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  - ► Short recap on machine learning
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  - ► Gradient Descent
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- ▶ 16:00 End of workshop

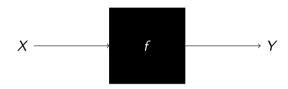


► What is machine learning?

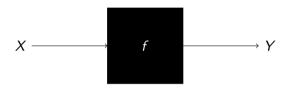
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▶ By knowing a set of data and their targets we can tune f to output what we want.

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- ▶ It can often write better computational rules than we could
- It can check more cases than we could

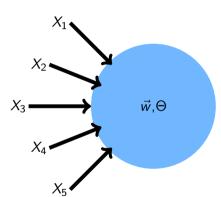
## Perceptron

The perceptron contains a weight  $(\vec{w})$  for each input and a threshold  $(\Theta)$ 



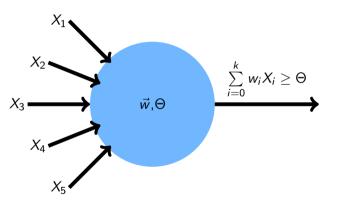
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- The perceptron contains a weight  $(\vec{w})$  for each input and a threshold  $(\Theta)$
- Its output can be calculated as  $\sum_{i=0}^{k} w_i X_i \ge \Theta$



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- Restart the process until the solution is found
- Let us actually implement this in the first notebook (Perceptron)

#### Conclusions

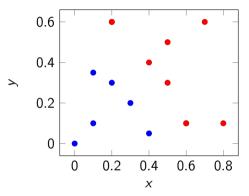
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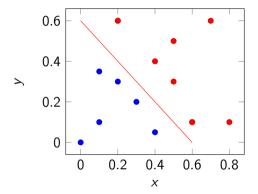
#### Conclusions

- ► Congratulations on training your first perceptron! You just taught a computer to learn!
- ▶ Why didn't we wait for the final weights, but stop after one run over the dataset?

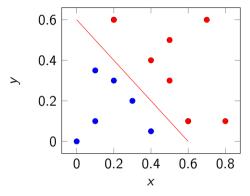
# Linear Separability



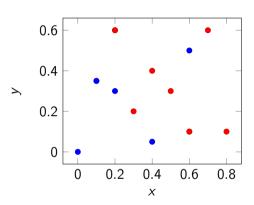
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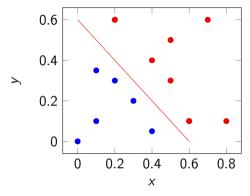


Data are linearly separable -> Can be divided by a plane

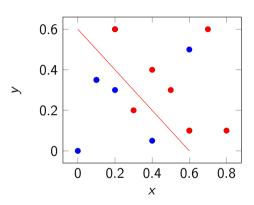


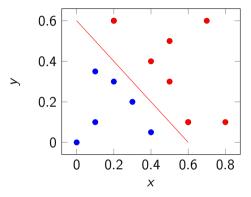
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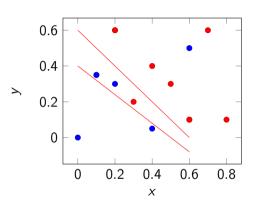


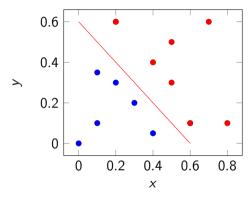
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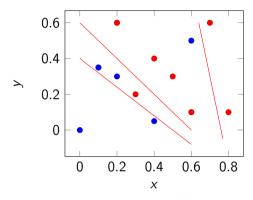


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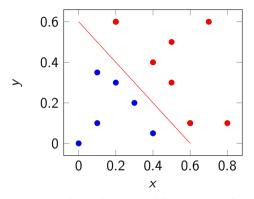




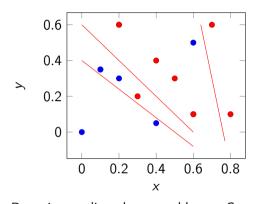
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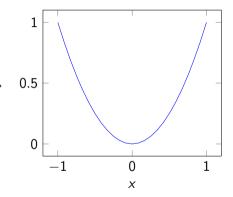
The algorithm only converges, if the problem is linearly separable.

▶ What we calculated is an activation

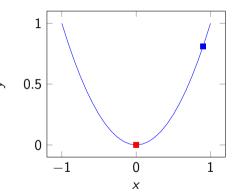
$$a = \sum_{i} w_{i} X_{i}$$

- What we calculated is an activation  $a = \sum_{i} w_i X_i$
- ► Let us ignore the threshold and try to get the activation as close to the target value as possible.

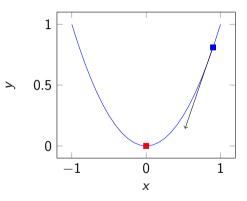
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- This brings us back to regression with an error:  $E(w) = \frac{1}{2} \sum_{(x,y) \in D} (y-a)^2$



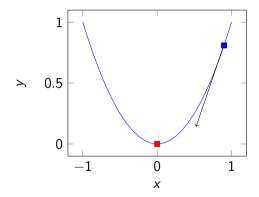
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- Every deep learning framework can calculate those weights using the chain rule and backpropagation.



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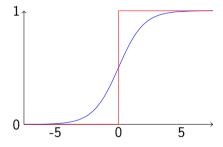
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## Sigmoid → Differentiable Threshold

Even though the perceptron is great for boolean functions it is not differentiable and has no continuous error function, consequently the gradient cannot be calculated

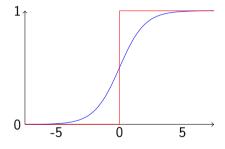
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- Even though the perceptron is great for boolean functions it is not differentiable and has no continuous error function, consequently the gradient cannot be calculated
- ➤ The sigmoid allows us to convert the strict classification into a regression over the probability for each point to belong to a certain class



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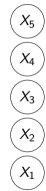
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- Cross-Entropy  $E = -\frac{1}{n} \sum_{i=1}^{n} \sum_{k=1}^{m} y_{i,k} \ln p_{i,k}$

$$y_{i,k}$$
 1, if  $i = k$  else 0

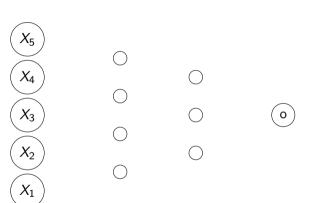
 $p_{i,k}$  probability for point i belonging to class k

➤ Similar to the perceptron we have a lot of inputs and output

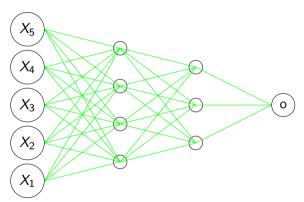


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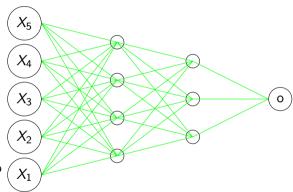
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- However, instead of going from start to end directly we now add hidden units
- ► For each of the units we now apply the sigmoid function
- Since every unit is differentiable, the whole network is differentiable
  → We can use backpropagation to minimize the error as we can calculate the gradients



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How do we make sure that we do not learn the arbitrary noise in the dataset?

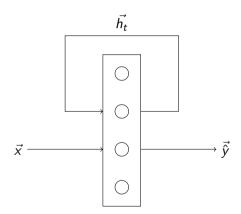
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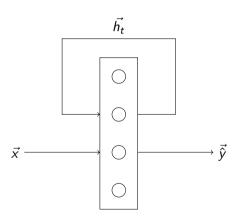
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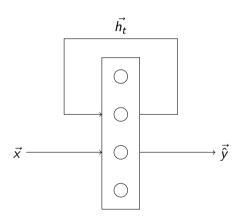
- ▶ How can we limit the representational power of the neural network?
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- ▶ All of these can be perfectly tested using a validation set



 Recurrent Neural Networks allow one to propagate states through time



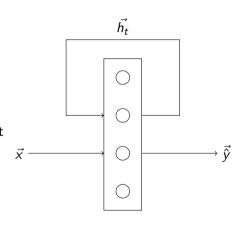
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- From this hidden state the current output is calculated as  $y_t = \sigma_y(W_y h_t + b_y)$
- ► These networks cannot represent long-term dependencies as U<sub>h</sub> is always multiplied by itself.



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# Word2Vec

### Word2Vec

► How can we turn text into numbers?

# Chatbot

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► Let's chat