

# Deep Learning

QCon London, March 9th

# Machine Learning (Recap)

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- What is machine learning?

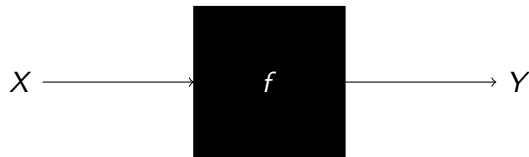
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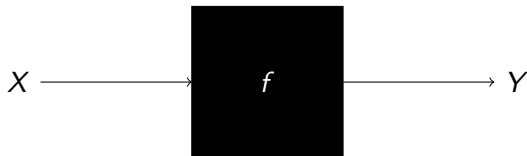
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- By knowing a set of data and their targets we can tune  $f$  to output what we want.

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- It can check more cases than we could

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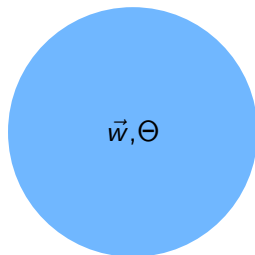
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- 16:00 End of workshop

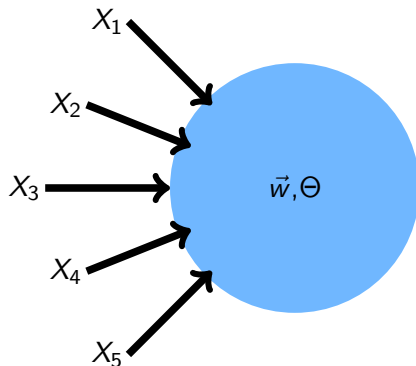
# Perceptron

- The perceptron contains a weight ( $\vec{w}$ ) for each input and a threshold ( $\Theta$ )



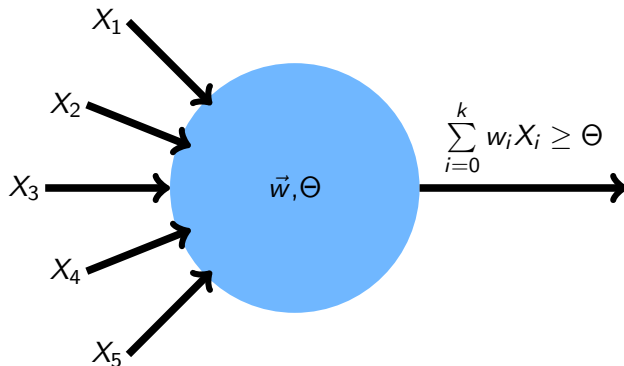
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- Its output can be calculated as  $\sum_{i=0}^k w_i X_i \geq \Theta$





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- Restart the process until the solution is found
- Let us actually implement this in the first notebook (Perceptron)

# Conclusions



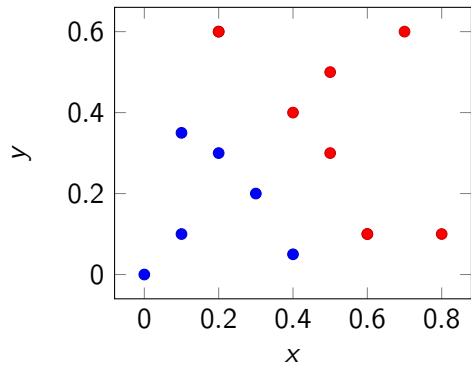
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- Congratulations on training your first perceptron! You just taught a computer to learn!

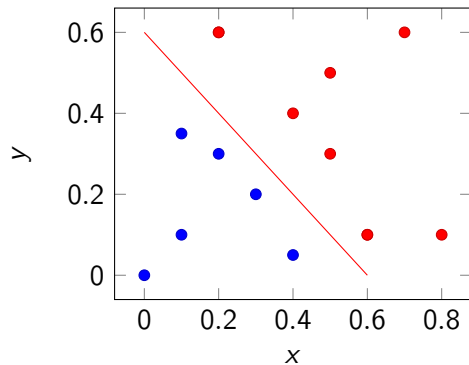
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- Congratulations on training your first perceptron! You just taught a computer to learn!
- Why didn't we wait for the final weights, but stop after one run over the dataset?

# Linear Separability

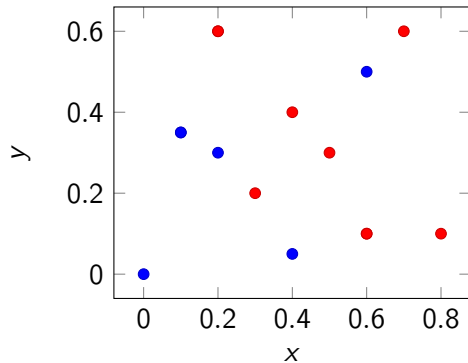
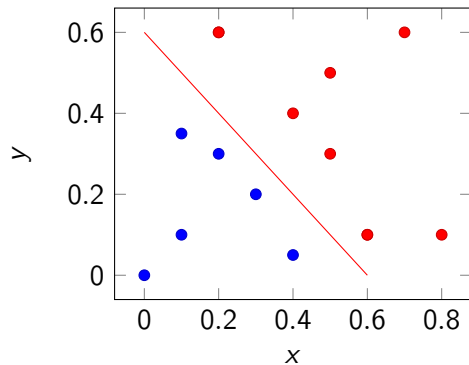


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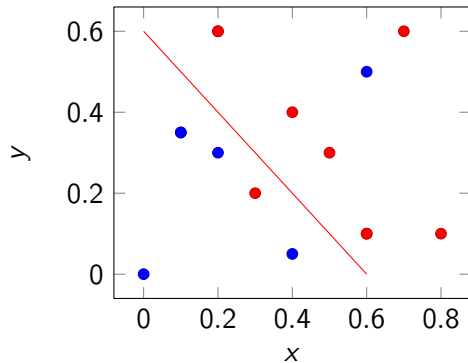
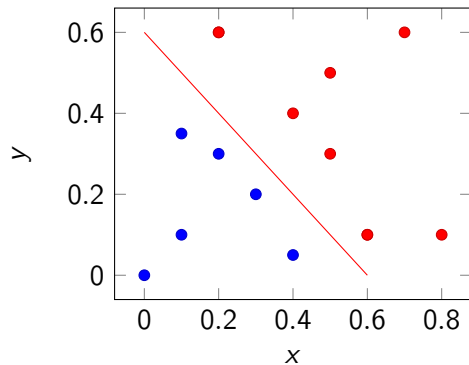
Data is linearly separable -> Can be divided by a plane

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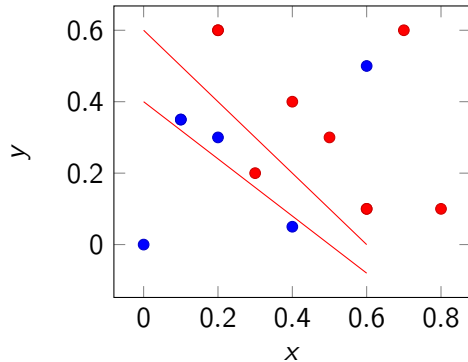
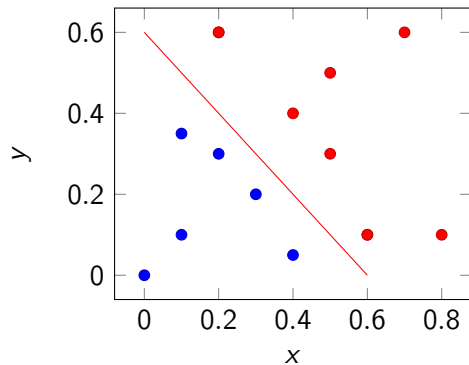
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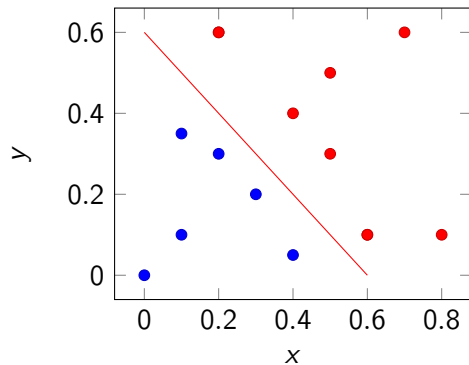
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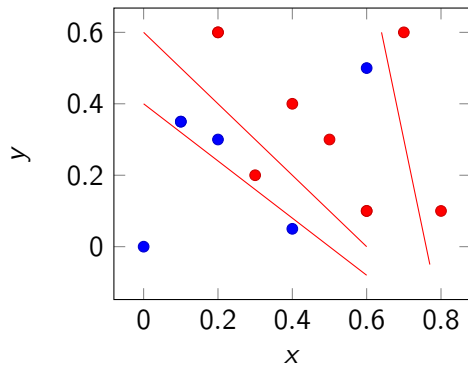


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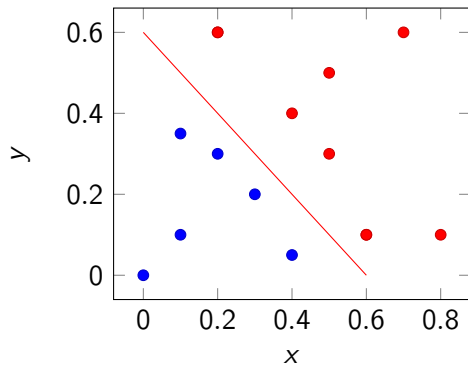
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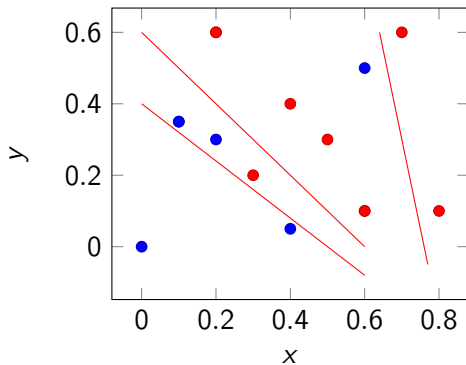
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## Linear Separability



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The algorithm only converges, if the problem is linearly separable.

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- What we calculated is an activation

$$a = \sum_i w_i X_i$$

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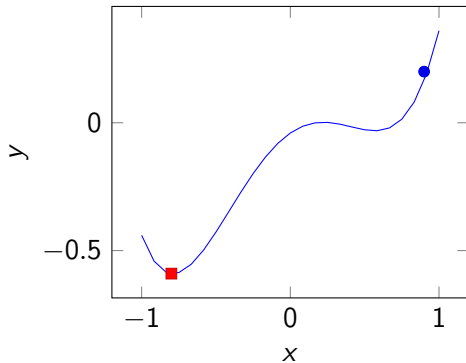
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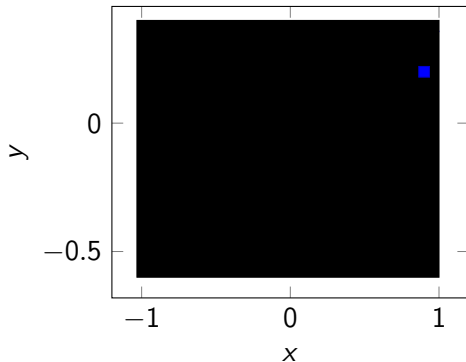


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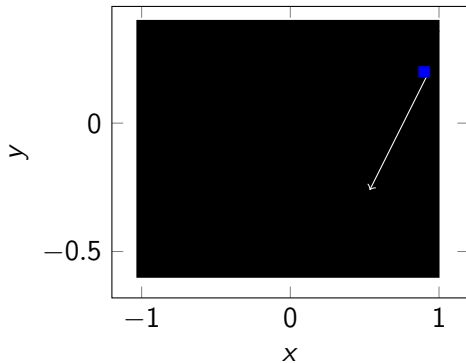
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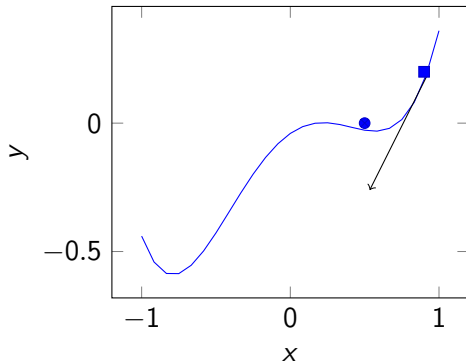
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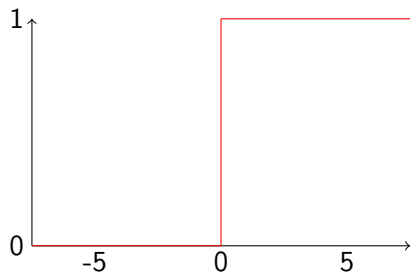
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- Every deep learning framework can calculate those gradients using the chain rule and backpropagation.



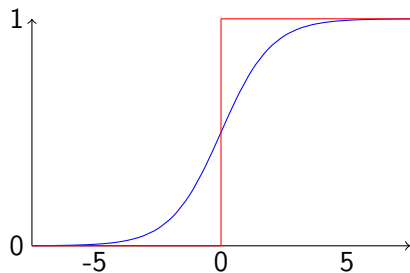


## Sigmoid $\rightarrow$ Differentiable Threshold



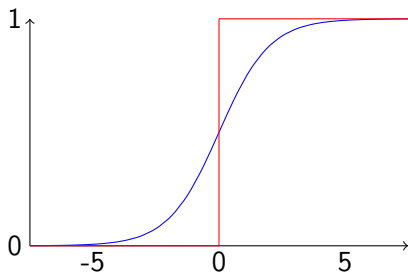
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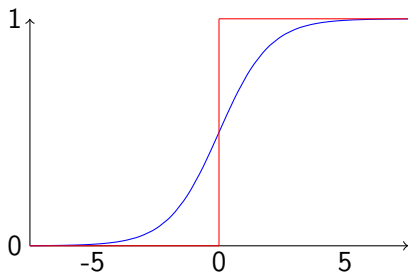
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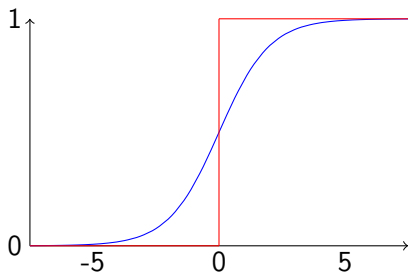
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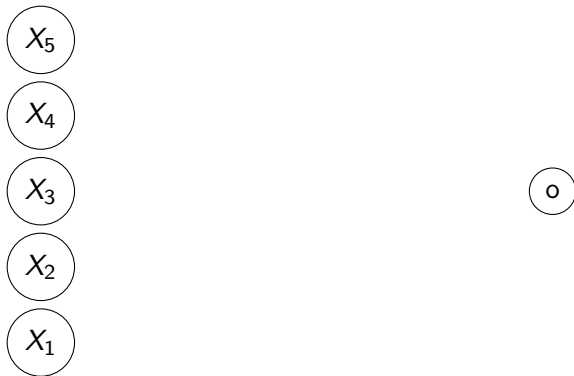
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- Let us use this new knowledge to implement gradient descent in the next notebook.



# Neural Network

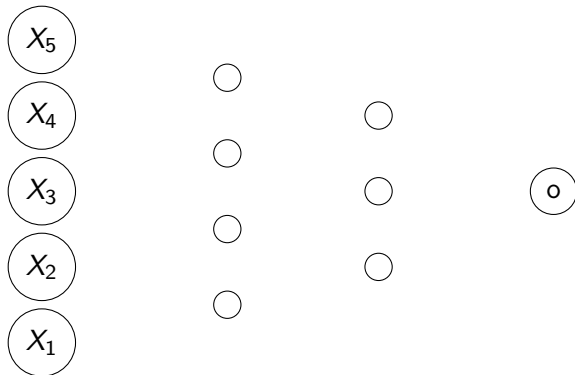
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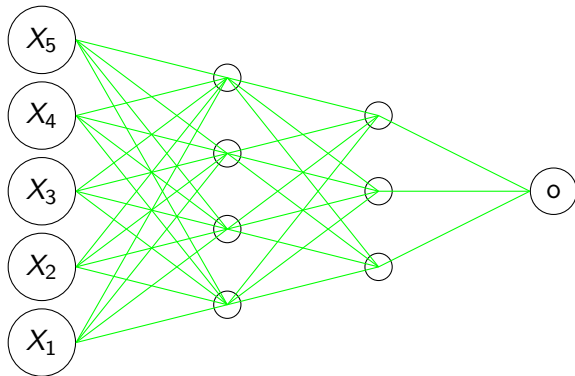
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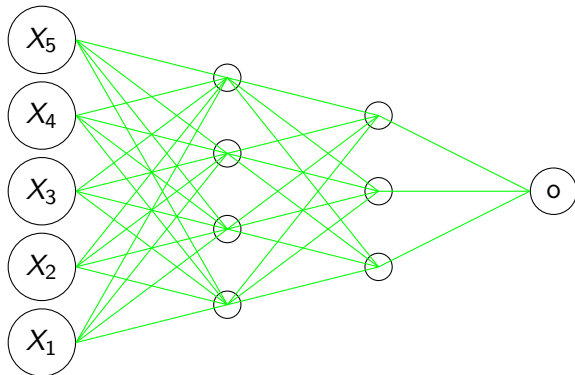
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- Hereby, every output from the previous layers is added as all inputs
- For each of the units we now apply the sigmoid function
- Since every unit is differentiable, the whole network is differentiable  
→ We can use backpropagation to minimize the error as we can calculate the gradients



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- There are multiple ways to use gradient descent.

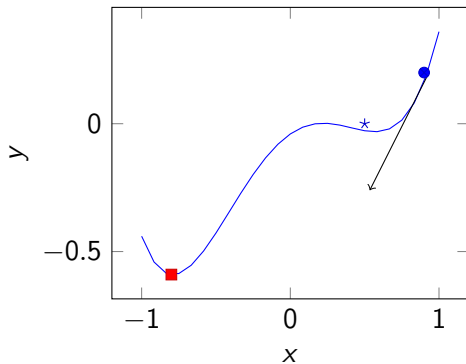
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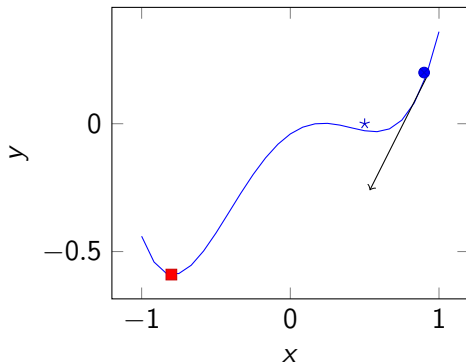
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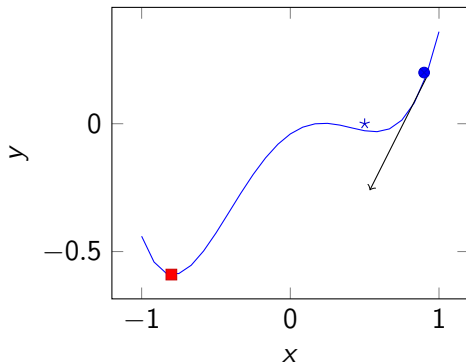
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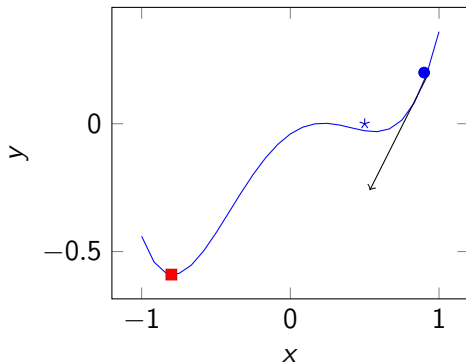
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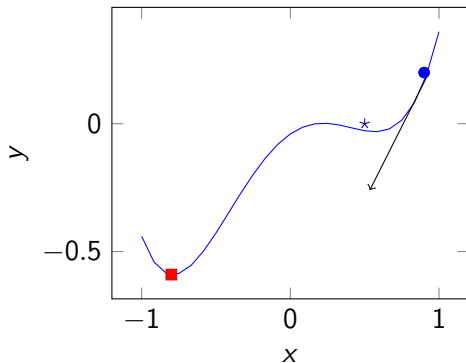
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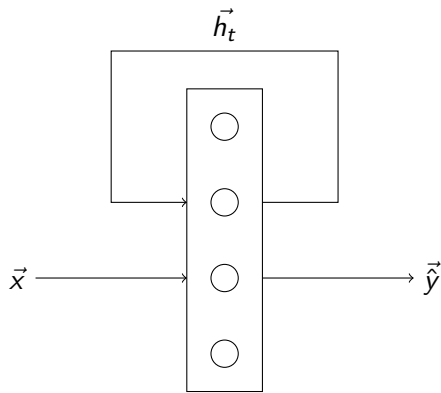


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  - Penalty for Complexity

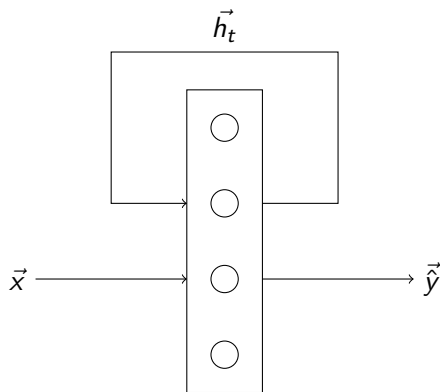


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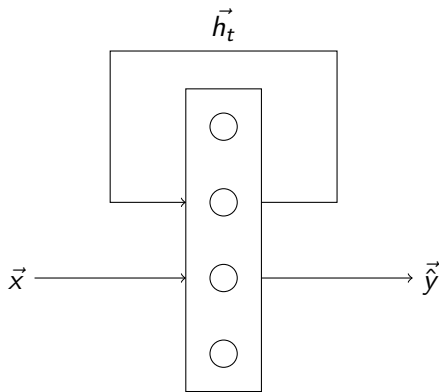
- Recurrent Neural Networks allow one to propagate states through time



# Recurrent Neural Networks

- Recurrent Neural Networks allow one to propagate states through time
- They calculate a hidden state  $\vec{h}_t$  which is kept for the next time step, as

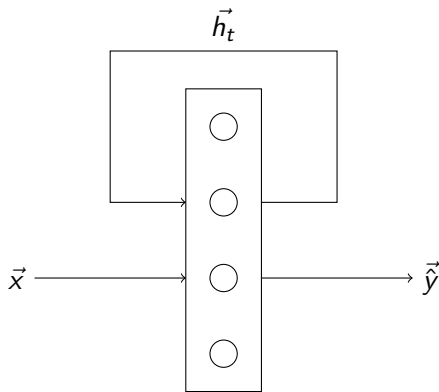
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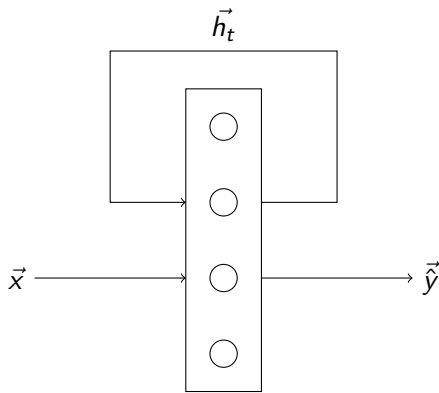
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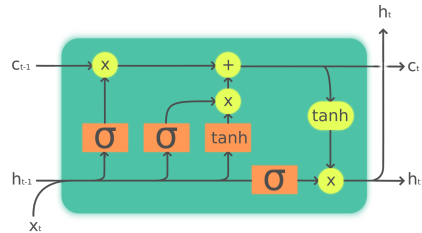
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- These networks cannot represent long-term dependencies as  $U_h$  is always multiplied by itself.



# LSTM

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Legend:

Layer



Pointwise op



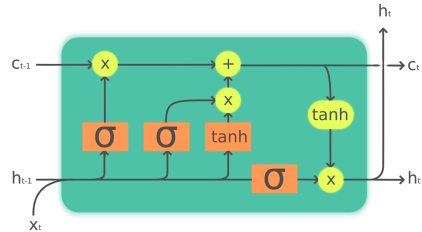
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Figure: Courtesy of wikipedia

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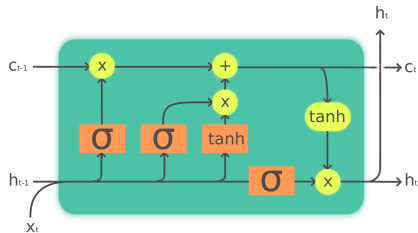
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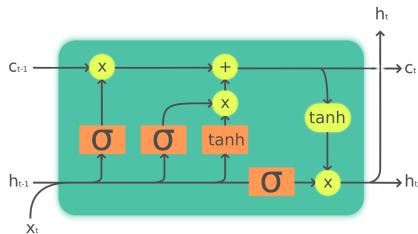
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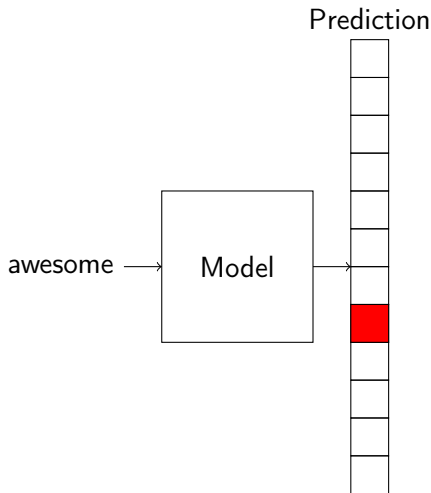
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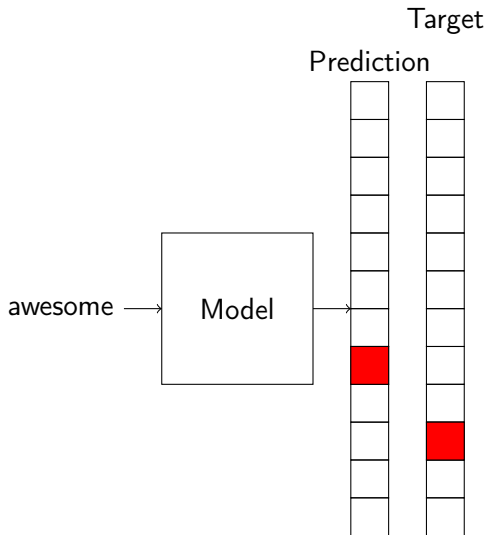
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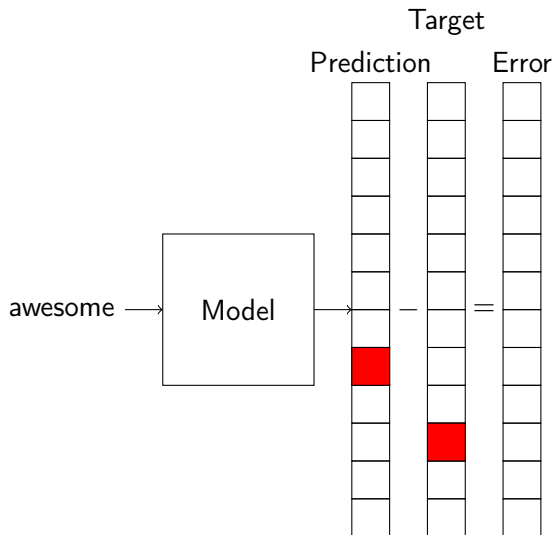
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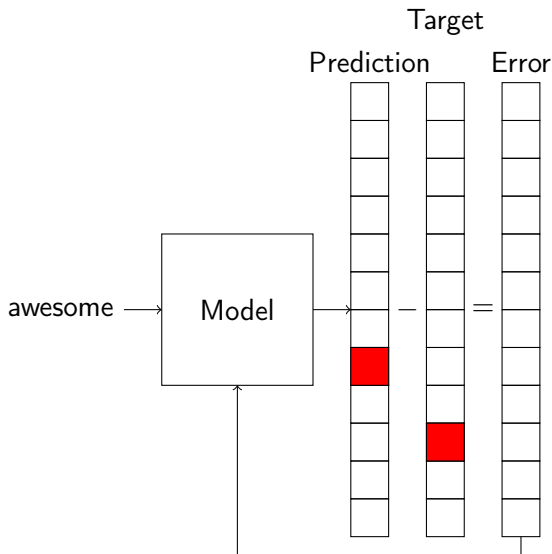
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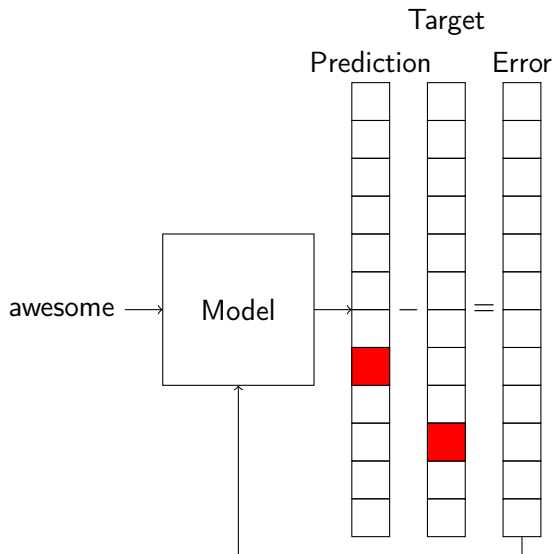
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- As classical training would update all the weights for each target example (where vocabularies can be million of words), the weights will only be updated for the right targets and a random selection of false targets



# Chatbot

# Chatbot

- Let's chat

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- The notebook we will use is inspired by the PyTorch chatbot tutorial, but it utilizes AllenNLP.

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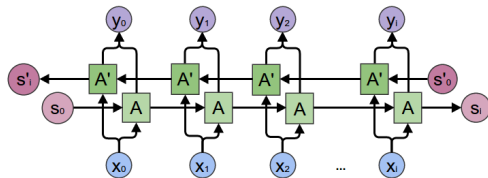


Figure: Image from <https://colah.github.io/posts/2015-09-NN-Types-FP/>



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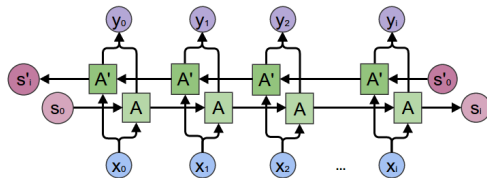


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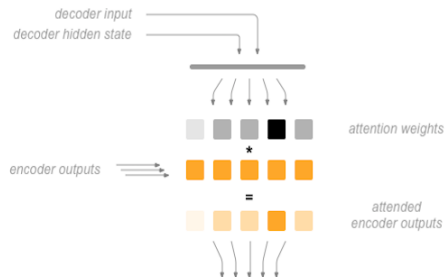


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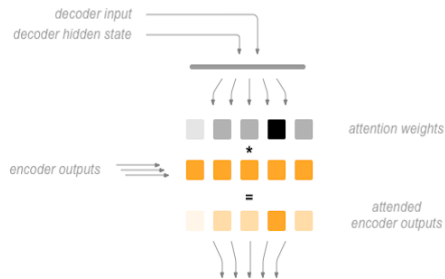


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- It will then merge the weighted encoder vectors with the current decoder output

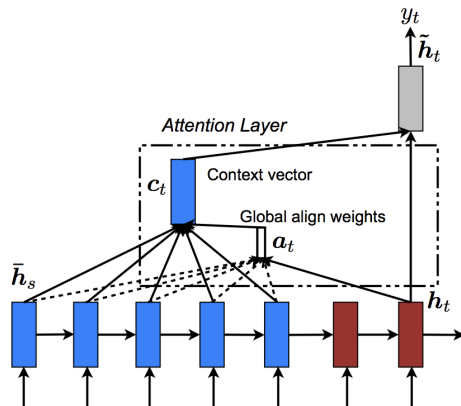


Figure: From arxiv 1508.04025