

Лекция 7

Библиотека *thrust*

- Контейнеры *host_vector* и *device_vector*.
- Алгоритмы *thrust*.
- Преобразование указателей и комбинированный код.
- Алгоритм *transform* и функторы.
- Кортежи и *zip*-итератор.

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/generate.h>
#include <cstdlib>
int main(void){
    thrust::host_vector<int> h(1 << 24);
    thrust::generate(h.begin(), h.end(), rand);
    thrust::device_vector<int> d = h;

    return 0;
}
```

Line: 7 of 11 Col: 21 LINE INS 0.cu UTF

malkov@linux-5002:~/WORKSHOP/CUDA EXERCISE/THRUST/tests> nvcc 0.cu -o 0

malkov@linux-5002:~/WORKSHOP/CUDA EXERCISE/THRUST/tests> nvprof ./0

==11098== NVPROF is profiling process 11098, command: ./0

==11098== Profiling application: ./0

==11098== Profiling result:

Time(%)	Time	Calls	Avg	Min	Max	Name
100.00%	11.104ms	1	11.104ms	11.104ms	11.104ms	[CUDA memcpy HtoD]

==11098== API calls:

Time(%)	Time	Calls	Avg	Min	Max	Name
86.14%	73.273ms	1	73.273ms	73.273ms	73.273ms	cudaMalloc
13.09%	11.137ms	1	11.137ms	11.137ms	11.137ms	cudaMemcpyAsync
0.36%	302.51us	83	3.6440us	291ns	128.30us	cuDeviceGetAttribute
0.33%	278.22us	1	278.22us	278.22us	278.22us	cudaFree
0.05%	40.411us	1	40.411us	40.411us	40.411us	cuDeviceTotalMem
0.04%	32.067us	1	32.067us	32.067us	32.067us	cuDeviceGetName
0.00%	1.8530us	2	926ns	441ns	1.4120us	cuDeviceGetCount
0.00%	891ns	2	445ns	285ns	606ns	cuDeviceGet

malkov@linux-5002:~/WORKSHOP/CUDA EXERCISE/THRUST/tests> █

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/generate.h>
#include <thrust/sort.h>
#include <thrust/copy.h>
#include <cstdlib>

int main(void){
    thrust::host_vector<int> h(1 << 8);
    thrust::generate(h.begin(), h.end(), rand);

    thrust::device_vector<int> d = h;

    thrust::sort(d.begin(), d.end());

    thrust::copy(d.begin(), d.end(), h.begin()); //h=d;

    for(int i=0;i<(1<<8);i++)
        printf("%d\n",h[i]);

    return 0;
}
```

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/fill.h>
#include <thrust/copy.h>
#include <cstdio>
```

```
__global__ void gTest(float* d){
    int idx=threadIdx.x+blockDim.x*blockIdx.x;
    d[idx]+=(float)idx;
}
```

```
int main(void){
    float *raw_ptr;

    thrust::host_vector<float> h(1 << 8);
    thrust::fill(h.begin(), h.end(), 3.1415f);
    thrust::device_vector<float> d = h;
    raw_ptr = thrust::raw_pointer_cast(&d[0]); //d.data());

    gTest<<<4,64>>>(raw_ptr);
    cudaDeviceSynchronize();

    thrust::copy(d.begin(), d.end(), h.begin());
    for(int i=0;i<(1<<8);i++)
        printf("%g\n",h[i]);

    return 0;
}
```

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
// #include <thrust/fill.h>
#include <thrust/transform.h>
#include <thrust/sequence.h>
// #include <thrust/generate.h>
#include <thrust/execution_policy.h>
#include <cstdio>
// #include <thrust/for_each.h>
#include <cmath>
```

```
struct range_functor
{
    float h;
    range_functor(float _h):h(_h){}
    __host__ __device__
    float operator()(float x){
        return h*x;
    }
};

struct sin_functor
{
    __host__ __device__
    float operator()(float x){
        return sin(x);
    }
};
```

```
int main(){
    range_functor rfunc(0.02);
    sin_functor sfunc;

    thrust::host_vector<float> h1(1 << 8);
    thrust::host_vector<float> h2(1 << 8);
    thrust::device_vector<float> d1(1 << 8); // = h1;
    thrust::device_vector<float> d2(1 << 8); // = h2;
    thrust::sequence(thrust::device, d1.begin(), d1.end());
    thrust::transform(d1.begin(), d1.end(), d1.begin(), rfunc);
    thrust::transform(d1.begin(), d1.end(), d2.begin(), sfunc);

    //thrust::for_each(thrust::device, d2.begin(), d2.end(), printf_functor());
    h2=d2;
    h1=d1;

    for(int i=0;i<(1<<8);i++){
        printf("%g\t%g\n",h1[i], h2[i]);
    }

    return 0;
}
```

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tests

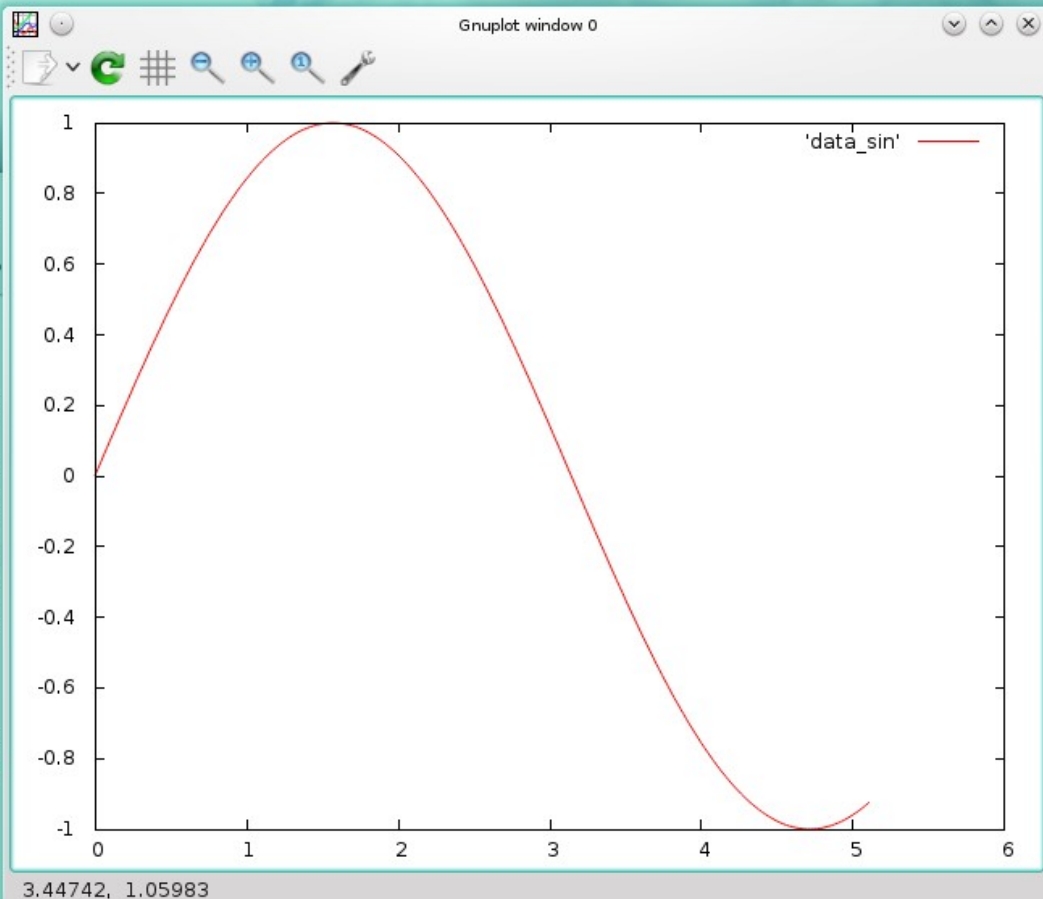
- 1-1prod.cu
- 1-2prod.cu
- 1.cu
- 1prod.cu
- 2.cu
- funct1.cu
- funct2.cu
- funct3.cu

```
//
int main(){
    range_func rfunc;
    sin_func sfunc;

    thrust::host_vector<float> d1;
    thrust::host_vector<float> d2;
    thrust::device_vector<float> d1d;
    thrust::device_vector<float> d2d;
    thrust::sequence(d1, d1+1000000);
    thrust::transform(d1.begin(), d1.end(), d1d.begin(), d1d.end(), thrust::identity<float>());
    thrust::transform(d2.begin(), d2.end(), d2d.begin(), d2d.end(), thrust::identity<float>());
    //thrust::fill(d2d.begin(), d2d.end(), 0.0);

    h2=d2;
    h1=d1;
    //thrust::for_each(h1.begin(), h1.end(), h2.begin(), h2.end(), thrust::identity<float>());
    for(int i=0; i<1000000; i++)
        printf("%g\t%g\n", h1[i], h2[i]);

    return 0;
}
```



Line: 63 of 79 Col: 57 LINE INS

funct3.cu UTF-8

```
malkov@linux-5002:~/WORKSHOP/CUDA_EXERCISE/THRUST/tests> nvcc funct3.cu -o funct3
malkov@linux-5002:~/WORKSHOP/CUDA_EXERCISE/THRUST/tests> ./funct3 > data_sin
malkov@linux-5002:~/WORKSHOP/CUDA_EXERCISE/THRUST/tests> gnuplot
```

```
GNUPLOT
Version 4.6 patchlevel 5    last modified February 2014
Build System: Linux x86_64

Copyright (C) 1986-1993, 1998, 2004, 2007-2014
Thomas Williams, Colin Kelley and many others

gnuplot home:    http://www.gnuplot.info
faq, bugs, etc:  type "help FAQ"
immediate help:  type "help" (plot window: hit 'h')
```

```
Terminal type set to 'qt'
gnuplot> plot 'data_sin' w l
gnuplot>
```

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```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/fill.h>
#include <thrust/transform.h>
#include <thrust/sequence.h>
#include <cstdio>
```

```
struct saxpy_functor
{
    const float a;
    saxpy_functor(float _a) : a(_a) {}
    __host__ __device__
    float operator()(float x, float y){
        return a*x+y;
    }
};
```

```
void saxpy(float a,
           thrust::device_vector<float>& x,
           thrust::device_vector<float>& y){
    saxpy_functor func(a);
    // call transform
    thrust::transform(x.begin(), x.end(), y.begin(), y.begin(), func);
}
```



```
int main(){
    thrust::host_vector<float> h1(1 << 24);
    thrust::host_vector<float> h2(1 << 24);
    thrust::sequence(h1.begin(), h1.end());
    thrust::fill(h2.begin(), h2.end(), 2.0);

    thrust::device_vector<float> d1 = h1;
    thrust::device_vector<float> d2 = h2;

    saxpy(3.0, d1, d2);

    h2=d2;

    for(int i=0;i<(1<<8);i++){
        printf("%g\n",h2[i]);
    }
    return 0;
}
```

КОРТЕЖИ

```
#include <thrust/tuple.h>
#include <cstdio>

int main(){
    thrust::tuple<int, float, const char *> test_tuple(23, 4.5, "thrust");
    printf("%d\t%f\t%s\n", thrust::get<0>(test_tuple),
          thrust::get<1>(test_tuple),
          thrust::get<2>(test_tuple));

    return 0;
}
```

```
malkov@linux-5002:~/WORKSHOP/CUDA EXERCISE/THRUST/tests> ./tuple1
23    4.5    thrust
```

```

#include <thrust/tuple.h>
#include <thrust/device_vector.h>
#include <thrust/host_vector.h>
#include <thrust/transform.h>
#include <thrust/fill.h>
#include <thrust/iterator/zip_iterator.h>
#include <cstdio>
#define N 32

struct rotate_tuple{
    __host__ __device__
    thrust::tuple<float,float,float> operator()(thrust::tuple<float&,float&,float&>& t){
        float x = thrust::get<0>(t);
        float y = thrust::get<1>(t);
        float z = thrust::get<2>(t);

        float rx=0.36*x+0.48*y-0.80*z;
        float ry=-0.80f*x+0.60*y+0.00f*z;
        float rz=0.48f*x+0.64f*y+0.60f*z;

        return thrust::make_tuple(rx,ry,rz);
    }
};

```

```
int main(){
    thrust::device_vector<float> x(N), y(N), z(N);

    thrust::fill(x.begin(), x.end(), 2.0);
    thrust::fill(y.begin(), y.end(), 3.0);
    thrust::fill(z.begin(), z.end(), 5.0);


    thrust::transform( thrust::make_zip_iterator( thrust::make_tuple(x.begin(), y.begin(),
z.begin() )),
        thrust::make_zip_iterator( thrust::make_tuple(x.end(), y.end(), z.end() )),
        thrust::make_zip_iterator( thrust::make_tuple(x.begin(), y.begin(), z.begin() )),
        rotate_tuple() );


    thrust::host_vector<float> hx(N), hy(N), hz(N);
    hx=x; hy=y; hz=z;
    for(int i=0;i<N;i++)
        printf("%g\t%g\t%g\n",hx[i], hy[i], hz[i]);

    return 0;
}
```