

Solving stiff PDEs on the sphere

Numerical Analysis Group, Mathematical Institute

Hadrien Montanelli and Yuji Nakatsukasa

November 23, 2016



■ Problem: Stiff PDEs of the form

$$u_t = \mathcal{L}u + \mathcal{N}(u), \quad u(t=0,x,y,z) = u_0(x,y,z)$$

u(t,x,y,z) is a function of time t and (x,y,z) with $x^2+y^2+z^2=1$ $\mathcal L$ is a linear differential operator, e.g., $\mathcal L=\alpha\Delta$ with $\alpha\in\mathbf R$ or $\alpha\in i\mathbf R$ $\mathcal N$ is a nonlinear operator, e.g., $\mathcal N(u)=u|u|^2$

■ Problem: Stiff PDEs of the form

$$u_t = \mathcal{L}u + \mathcal{N}(u), \quad u(t=0,x,y,z) = u_0(x,y,z)$$

u(t,x,y,z) is a function of time t and (x,y,z) with $x^2+y^2+z^2=1$ $\mathcal L$ is a linear differential operator, e.g., $\mathcal L=\alpha\Delta$ with $\alpha\in\mathbf R$ or $\alpha\in i\mathbf R$ $\mathcal N$ is a nonlinear operator, e.g., $\mathcal N(u)=u|u|^2$

■ Aim: Spectral accuracy in space and fourth-order time-stepping

■ Problem: Stiff PDEs of the form

$$u_t = \mathcal{L}u + \mathcal{N}(u), \quad u(t=0,x,y,z) = u_0(x,y,z)$$

u(t,x,y,z) is a function of time t and (x,y,z) with $x^2+y^2+z^2=1$ $\mathcal L$ is a linear differential operator, e.g., $\mathcal L=\alpha\Delta$ with $\alpha\in\mathbf R$ or $\alpha\in i\mathbf R$ $\mathcal N$ is a nonlinear operator, e.g., $\mathcal N(u)=u|u|^2$

- Aim: Spectral accuracy in space and fourth-order time-stepping
- Method: Double Fourier Sphere (DFS) method in space with mn points,

$$u(t,\lambda,\theta) \approx \sum_{i=-m/2}^{m/2-1} \sum_{k=-n/2}^{n/2-1} \hat{u}_{jk}(t) e^{ij\theta} e^{ik\lambda}$$

This leads to a system of mn ODEs for $\hat{u}(t) = \{\hat{u}_{jk}(t)\}$,

$$\hat{u}'(t) = \mathbf{L}\hat{u} + \mathbf{N}(\hat{u}), \quad \hat{u}(0) = \hat{u}(0)$$



■ Problem: Stiff PDEs of the form

$$u_t = \mathcal{L}u + \mathcal{N}(u), \quad u(t=0,x,y,z) = u_0(x,y,z)$$

u(t,x,y,z) is a function of time t and (x,y,z) with $x^2+y^2+z^2=1$ $\mathcal L$ is a linear differential operator, e.g., $\mathcal L=\alpha\Delta$ with $\alpha\in\mathbf R$ or $\alpha\in i\mathbf R$ $\mathcal N$ is a nonlinear operator, e.g., $\mathcal N(u)=u|u|^2$

- Aim: Spectral accuracy in space and fourth-order time-stepping
- Method: Double Fourier Sphere (DFS) method in space with mn points,

$$u(t,\lambda,\theta) \approx \sum_{i=-m/2}^{m/2-1} \sum_{k=-n/2}^{n/2-1} \hat{u}_{jk}(t) e^{ij\theta} e^{ik\lambda}$$

This leads to a system of mn ODEs for $\hat{u}(t) = \{\hat{u}_{jk}(t)\},\$

$$\hat{u}'(t) = \mathbf{L}\hat{u} + \mathbf{N}(\hat{u}), \quad \hat{u}(0) = \hat{u}(0)$$

Observations:

Multiplication matrices in coefficient space: no pole singularity

Special structure of the discrete Laplacian: optimal $O(mn \log mn)$ complexity

Implicit-explicit schemes and exponential integrators: no severe CFL restrictions

■ The DFS method (1970s) uses the longitude-latitude coordinate transforms,

$$x=\cos\lambda\sin\theta,\ y=\sin\lambda\sin\theta,\ z=\cos\theta,$$

with
$$(\lambda, \theta) \in [-\pi, \pi] \times [0, \pi]$$

■ The DFS method (1970s) uses the longitude-latitude coordinate transforms,

$$x = \cos \lambda \sin \theta$$
, $y = \sin \lambda \sin \theta$, $z = \cos \theta$,

with
$$(\lambda, \theta) \in [-\pi, \pi] \times [0, \pi]$$

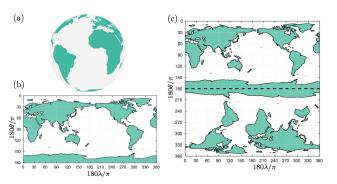
■ Functions $u(\lambda, \theta)$ on the sphere are 2π -periodic in λ but not periodic in θ

■ The DFS method (1970s) uses the longitude-latitude coordinate transforms,

$$x = \cos \lambda \sin \theta$$
, $y = \sin \lambda \sin \theta$, $z = \cos \theta$,

with $(\lambda, \theta) \in [-\pi, \pi] \times [0, \pi]$

- Functions $u(\lambda, \theta)$ on the sphere are 2π -periodic in λ but not periodic in θ
- Key idea: double up $u(\lambda, \theta)$ and flip it to make it periodic in both directions



lacktriangle We want to solve $u_t = lpha \Delta u + \mathcal{N}(u)$ with

$$\Delta u = u_{\theta\theta} + \frac{\cos\theta\sin\theta}{\sin^2\theta}u_{\theta} + \frac{1}{\sin^2\theta}u_{\lambda\lambda}$$

■ We want to solve $u_t = \alpha \Delta u + \mathcal{N}(u)$ with

$$\Delta u = u_{\theta\theta} + \frac{\cos\theta\sin\theta}{\sin^2\theta}u_{\theta} + \frac{1}{\sin^2\theta}u_{\lambda\lambda}$$

lacksquare The DFS method leads to a system of mn ODEs for $\hat{u}(t)=\{\hat{u}_{jk}(t)\},$

$$\hat{\textit{u}}'(t) = \mathsf{L}\hat{\textit{u}} + \mathsf{N}(\hat{\textit{u}}), \quad \mathsf{L} = \mathsf{I}_\textit{n} \otimes (\mathsf{D}_\textit{m}^2 + \mathsf{M}_{\mathsf{sin}^2}^{-1} \mathsf{M}_{\mathsf{cos}\,\mathsf{sin}} \mathsf{D}_\textit{m}) + \mathsf{D}_\textit{n}^2 \otimes (\mathsf{M}_{\mathsf{sin}^2}^{-1})$$

■ We want to solve $u_t = \alpha \Delta u + \mathcal{N}(u)$ with

$$\Delta u = u_{\theta\theta} + \frac{\cos\theta\sin\theta}{\sin^2\theta}u_{\theta} + \frac{1}{\sin^2\theta}u_{\lambda\lambda}$$

lacksquare The DFS method leads to a system of mn ODEs for $\hat{u}(t)=\{\hat{u}_{jk}(t)\},$

$$\hat{\textit{u}}'(\textit{t}) = \mathsf{L}\hat{\textit{u}} + \mathsf{N}(\hat{\textit{u}}), \quad \mathsf{L} = \mathsf{I}_\textit{n} \otimes (\mathsf{D}^2_\textit{m} + \mathsf{M}_{\mathsf{sin}^2}^{-1} \mathsf{M}_{\mathsf{cos}\,\mathsf{sin}} \mathsf{D}_\textit{m}) + \mathsf{D}^2_\textit{n} \otimes (\mathsf{M}_{\mathsf{sin}^2}^{-1})$$

■ In value space: $M_{\sin^2}^v$ is diagonal with three zeros at $\theta = 0, \pi, 2\pi \Rightarrow$ singular

■ We want to solve $u_t = \alpha \Delta u + \mathcal{N}(u)$ with

$$\Delta u = u_{\theta\theta} + \frac{\cos\theta\sin\theta}{\sin^2\theta}u_{\theta} + \frac{1}{\sin^2\theta}u_{\lambda\lambda}$$

lacksquare The DFS method leads to a system of mn ODEs for $\hat{u}(t)=\{\hat{u}_{jk}(t)\},$

$$\hat{u}'(t) = \mathsf{L}\hat{u} + \mathsf{N}(\hat{u}), \quad \mathsf{L} = \mathsf{I}_n \otimes (\mathsf{D}_m^2 + \mathsf{M}_{\mathsf{sin}^2}^{-1} \mathsf{M}_{\mathsf{cos}\,\mathsf{sin}} \mathsf{D}_m) + \mathsf{D}_n^2 \otimes (\mathsf{M}_{\mathsf{sin}^2}^{-1})$$

- In value space: $\mathbf{M}_{\sin^2}^{\mathbf{v}}$ is diagonal with three zeros at $\theta = 0, \pi, 2\pi \Rightarrow$ singular
- In coefficient space: $\tilde{M}_{sin^2} = FM^{v}_{sin^2}F^{-1}$ is singular too (unitary transformation)

■ We want to solve $u_t = \alpha \Delta u + \mathcal{N}(u)$ with

$$\Delta u = u_{\theta\theta} + \frac{\cos\theta\sin\theta}{\sin^2\theta}u_{\theta} + \frac{1}{\sin^2\theta}u_{\lambda\lambda}$$

lacksquare The DFS method leads to a system of mn ODEs for $\hat{u}(t)=\{\hat{u}_{jk}(t)\},$

$$\hat{\textit{u}}'(\textit{t}) = \mathsf{L}\hat{\textit{u}} + \mathsf{N}(\hat{\textit{u}}), \quad \mathsf{L} = \mathsf{I}_\textit{n} \otimes (\mathsf{D}^2_\textit{m} + \mathsf{M}_{\mathsf{sin}^2}^{-1} \mathsf{M}_{\mathsf{cos}\,\mathsf{sin}} \mathsf{D}_\textit{m}) + \mathsf{D}^2_\textit{n} \otimes (\mathsf{M}_{\mathsf{sin}^2}^{-1})$$

- In value space: $\mathbf{M}_{\sin^2}^{\nu}$ is diagonal with three zeros at $\theta = 0, \pi, 2\pi \Rightarrow \frac{1}{2}$ singular
- In coefficient space: $\tilde{M}_{sin^2} = FM^{\nu}_{sin^2}F^{-1}$ is singular too (unitary transformation)
- lacktriangle Null space of $ilde{M}_{\text{sin}2}$: spurious modes 1 and ± 1 because it doesn't handle correctly the extreme wavenumbers

■ We want to solve $u_t = \alpha \Delta u + \mathcal{N}(u)$ with

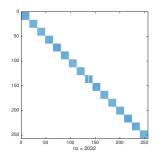
$$\Delta u = u_{\theta\theta} + \frac{\cos\theta\sin\theta}{\sin^2\theta}u_{\theta} + \frac{1}{\sin^2\theta}u_{\lambda\lambda}$$

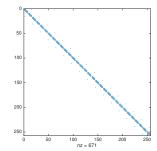
■ The DFS method leads to a system of mn ODEs for $\hat{u}(t) = \{\hat{u}_{jk}(t)\}$,

$$\hat{\textit{u}}'(\textit{t}) = \mathsf{L}\hat{\textit{u}} + \mathsf{N}(\hat{\textit{u}}), \quad \mathsf{L} = \mathsf{I}_\textit{n} \otimes (\mathsf{D}^2_\textit{m} + \mathsf{M}_{\mathsf{sin}^2}^{-1} \mathsf{M}_{\mathsf{cos}\,\mathsf{sin}} \mathsf{D}_\textit{m}) + \mathsf{D}^2_\textit{n} \otimes (\mathsf{M}_{\mathsf{sin}^2}^{-1})$$

- In value space: $\mathbf{M}_{\sin^2}^{\nu}$ is diagonal with three zeros at $\theta = 0, \pi, 2\pi \Rightarrow \frac{1}{2}$ singular
- In coefficient space: $\tilde{M}_{sin^2} = FM^{v}_{sin^2}F^{-1}$ is singular too (unitary transformation)
- lacktriangle Null space of $ilde{M}_{\text{sin}2}$: spurious modes 1 and ± 1 because it doesn't handle correctly the extreme wavenumbers
- The correct matrix, M_{sin2}, is nonsingular (row diagonally dominant and irreducible)

■ Sparsity patterns of L (left) and M_{sin²}L (right):





- Each $m \times m$ block of L: dense
- Each $m \times m$ block of $M_{sin^2}L$: "pentadiagonal plus rank two"
- Consequence:

$$(z\mathbf{I} + h\mathbf{L})x = b$$

can be solved in O(mn) operations since it is equivalent to solving

$$(zM_{\sin^2} + hM_{\sin^2}L)x = M_{\sin^2}b$$

 \blacksquare We want to use a fourth-order time-stepping algorithm for solving

$$\hat{u}'(t) = \mathbf{L}\hat{u} + \mathbf{N}(\hat{u})$$

■ We want to use a fourth-order time-stepping algorithm for solving

$$\hat{u}'(t) = \mathbf{L}\hat{u} + \mathbf{N}(\hat{u})$$

■ Large eigenvalues of L and clustering of points near the poles: force us to use very small time-steps

■ We want to use a fourth-order time-stepping algorithm for solving

$$\hat{u}'(t) = \mathbf{L}\hat{u} + \mathbf{N}(\hat{u})$$

- Large eigenvalues of L and clustering of points near the poles: force us to use very small time-steps
- Exponential integrators and implicit-explicit (IMEX) schemes: aimed at solving such systems

■ We want to use a fourth-order time-stepping algorithm for solving

$$\hat{u}'(t) = \mathbf{L}\hat{u} + \mathbf{N}(\hat{u})$$

- Large eigenvalues of L and clustering of points near the poles: force us to use very small time-steps
- Exponential integrators and implicit-explicit (IMEX) schemes: aimed at solving such systems
- Exponential integrators: L integrated exactly with matrix exponential, numerical scheme for N, e.g.,

ETDRK1
$$\hat{u}^{n+1} = e^{hL}\hat{u}^n + L^{-1}(e^{hL} - I)N(\hat{u}^n)$$

■ We want to use a fourth-order time-stepping algorithm for solving

$$\hat{u}'(t) = \mathbf{L}\hat{u} + \mathbf{N}(\hat{u})$$

- Large eigenvalues of L and clustering of points near the poles: force us to use very small time-steps
- Exponential integrators and implicit-explicit (IMEX) schemes: aimed at solving such systems
- Exponential integrators: L integrated exactly with matrix exponential, numerical scheme for N, e.g.,

ETDRK1
$$\hat{u}^{n+1} = e^{hL}\hat{u}^n + L^{-1}(e^{hL} - I)N(\hat{u}^n)$$

■ IMEX: implicit scheme for L, explicit formula for N, e.g.,

IMEX – BDF2
$$(3I - 2hL)\hat{u}^{n+1} = 4\hat{u}^n - \hat{u}^{n-1} + 4hN(\hat{u}^n) - 2hN(\hat{u}^{n-1})$$

- Dozens of exponential integration formulas of order four and higher have been proposed over the last 15 years
- Hard to do much better than the ETDRK4 scheme of Cox and Matthews

ETDRK4

```
\begin{split} \hat{a}^n &= e^{hL/2} \hat{u}^n + (h/2) \varphi_1(Lh/2) N(\hat{u}^n), \\ \hat{b}^n &= e^{hL/2} \hat{u}^n + (h/2) \varphi_1(Lh/2) N(\hat{a}^n), \\ \hat{c}^n &= e^{hL/2} \hat{a}^n + (h/2) \varphi_1(Lh/2) \big[ 2N(\hat{b}^n) - N(\hat{u}^n) \big], \\ \hat{u}^{n+1} &= e^{hL} \hat{u}^n + hf_1(hL) N(\hat{u}^n) + hf_2(hL) \big[ N(\hat{a}^n) + N(\hat{b}^n) \big] + hf_3(hL) N(\hat{c}^n) \end{split}
```

- In general: precompute e^{hL} by diagonalizing L and using contour integrals, $O(nm^3)$, then $O(nm^2)$ per time-step (dense blocks)
- Real eigenvalues: no precomputation, $e^{hL}\hat{u}^n$ products can be evaluated directly using Carathéodory-Fejér (CF) approximations, O(mn) per time-step

- We consider two IMEX schemes
- Multistep and stable for diffusive PDEs only:

IMEX – BDF4
$$(25I-12hL)\hat{u}^{n+1} = 48\hat{u}^n - 36\hat{u}^{n-1} + 6\hat{u}^{n-2} - 3\hat{u}^{n-3} + 48hN(\hat{u}^n) - 72hN(\hat{u}^{n-1}) + 48hN(\hat{u}^{n-2}) - 2hN(\hat{u}^{n-3})$$

One-step with six stages and stable for both diffusive and dispersive PDEs:

LIRK4

$$\hat{\mathbf{v}}_{1} = \hat{\mathbf{u}}^{n},
(\mathbf{I} - a_{ii} h \mathbf{L}) \hat{\mathbf{v}}^{i} = \hat{\mathbf{u}}^{n} + h \sum_{j=2}^{i-1} b_{j} \mathbf{L} \hat{\mathbf{v}}_{j} + h \sum_{j=1}^{i-1} \tilde{\mathbf{a}}_{ij} \mathbf{N}(\hat{\mathbf{v}}_{j}), \quad 2 \leq i \leq 6,
\hat{\mathbf{u}}^{n+1} = \hat{\mathbf{u}}^{n} + h \sum_{i=2}^{6} b_{i} \mathbf{L} \hat{\mathbf{v}}_{i} + h \sum_{i=1}^{6} \tilde{b}_{i} \mathbf{N}(\hat{\mathbf{v}}_{i})$$

■ Both have a O(mn) cost per time-step

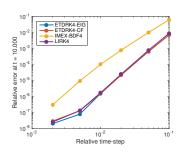
Numerical comparisons (1/3)

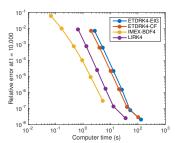
Allen-Cahn equation:

$$u_t = 10^{-2} \Delta u + u - u^3$$

with $u_0(\lambda,\theta)=Y_8^2(\lambda,\theta)$, m=n=200 and up to t=10

Diffusive PDE: we can use ETDRK4-CF, ETDRK4-EIG, IMEX-BDF4, LIRK4





IMEX-BDF4 the most efficient for diffusive PDEs

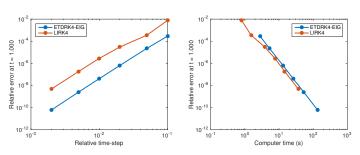
Numerical comparisons (2/3)

Nonlinear Schrödinger equation:

$$u_t = i\Delta u + iu|u|^2,$$

with $u_0(x, y, z) = \exp(-x^2 - y^2 - (z - 1)^2)$, m = n = 200 and up to t = 1

Dispersive PDE: we can only use ETDRK4-EIG and LIRK4



LIRK4 the most efficient for dispersive PDEs

Numerical comparisons (3/3)

IMEX – BDF4
$$(25I-12h\mathsf{L})\hat{u}^{n+1} = 48\hat{u}^n - 36\hat{u}^{n-1} + 6\hat{u}^{n-2} - 3\hat{u}^{n-3} \\ + 48h\mathsf{N}(\hat{u}^n) - 72h\mathsf{N}(\hat{u}^{n-1}) \\ + 48h\mathsf{N}(\hat{u}^{n-2}) - 2h\mathsf{N}(\hat{u}^{n-3})$$

ETDRK4

$$\begin{split} \hat{\mathbf{a}}^n &= e^{hL/2} \hat{u}^n + (h/2) \varphi_1(\mathbf{L}h/2) \mathbf{N}(\hat{u}^n), \\ \hat{b}^n &= e^{hL/2} \hat{u}^n + (h/2) \varphi_1(\mathbf{L}h/2) \mathbf{N}(\hat{\mathbf{a}}^n), \\ \hat{c}^n &= e^{hL/2} \hat{\mathbf{a}}^n + (h/2) \varphi_1(\mathbf{L}h/2) \big[2\mathbf{N}(\hat{b}^n) - \mathbf{N}(\hat{u}^n) \big], \\ \hat{u}^{n+1} &= e^{hL} \hat{u}^n + h f_1(h\mathbf{L}) \mathbf{N}(\hat{u}^n) + h f_2(h\mathbf{L}) \big[\mathbf{N}(\hat{a}^n) + \mathbf{N}(\hat{b}^n) \big] + h f_3(h\mathbf{L}) \mathbf{N}(\hat{c}^n) \end{split}$$

	IMEX		ETDRK4	
	BDF4	LIRK4	CF	EIG
# FFTs	2	12	8	8
$O(2mn\log mn)$				
# backslashes	1	6	90	0
O(12mn)				
# dense mat-vec ×	0	0	0	9
$O(nm^2)$				
diffusive PDEs	✓	√	√	√
dispersive PDEs	×	√	×	√



■ DFS method plus IMEX schemes: optimal $O(mn \log mn)$ algorithm for solving stiff PDEs on the sphere

- DFS method plus IMEX schemes: optimal $O(mn \log mn)$ algorithm for solving stiff PDEs on the sphere
- IMEX schemes outperform exponential integrators

- DFS method plus IMEX schemes: optimal $O(mn \log mn)$ algorithm for solving stiff PDEs on the sphere
- IMEX schemes outperform exponential integrators
- Future work includes PDFs on the disk and inside the unit ball