

# **MICROSAR Classic COM Based Transformer**

## Technical Reference

Version 4.35.0

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Status	Released

## Document Information

### Reference Documents

No.	Source	Title	Version
[1]	AUTOSAR	Specification of COM Based Transformer	R20-11
[2]	AUTOSAR	List of Basic Software Modules	R20-11
[3]	AUTOSAR	Specification of Communication	R20-11

### Scope of the Document

This technical reference describes the general use of the COM Based Transformer.



#### Caution

We have configured the programs in accordance with your specifications in the questionnaire. Whereas the programs do support other configurations than the one specified in your questionnaire, Vector's release of the programs delivered to your company is expressly restricted to the configuration you have specified in the questionnaire.

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# 1 Introduction

This document describes the functionality, API and configuration of the AUTOSAR BSW module ComXf as specified in [1].

<b>Supported Configuration Variants:</b>	pre-compile	
<b>Vendor ID:</b>	COMXF_VENDOR_ID	30 decimal (= Vector-Informatik, according to HIS)
<b>Module ID:</b>	COMXF_MODULE_ID	175 decimal (according to ref. [2])

The ComXf module provides the functionality to serialize complex data when the target bus system uses a fixed communication matrix.

## 1.1 Architecture Overview

The following figure shows where the ComXf is located in the AUTOSAR architecture.

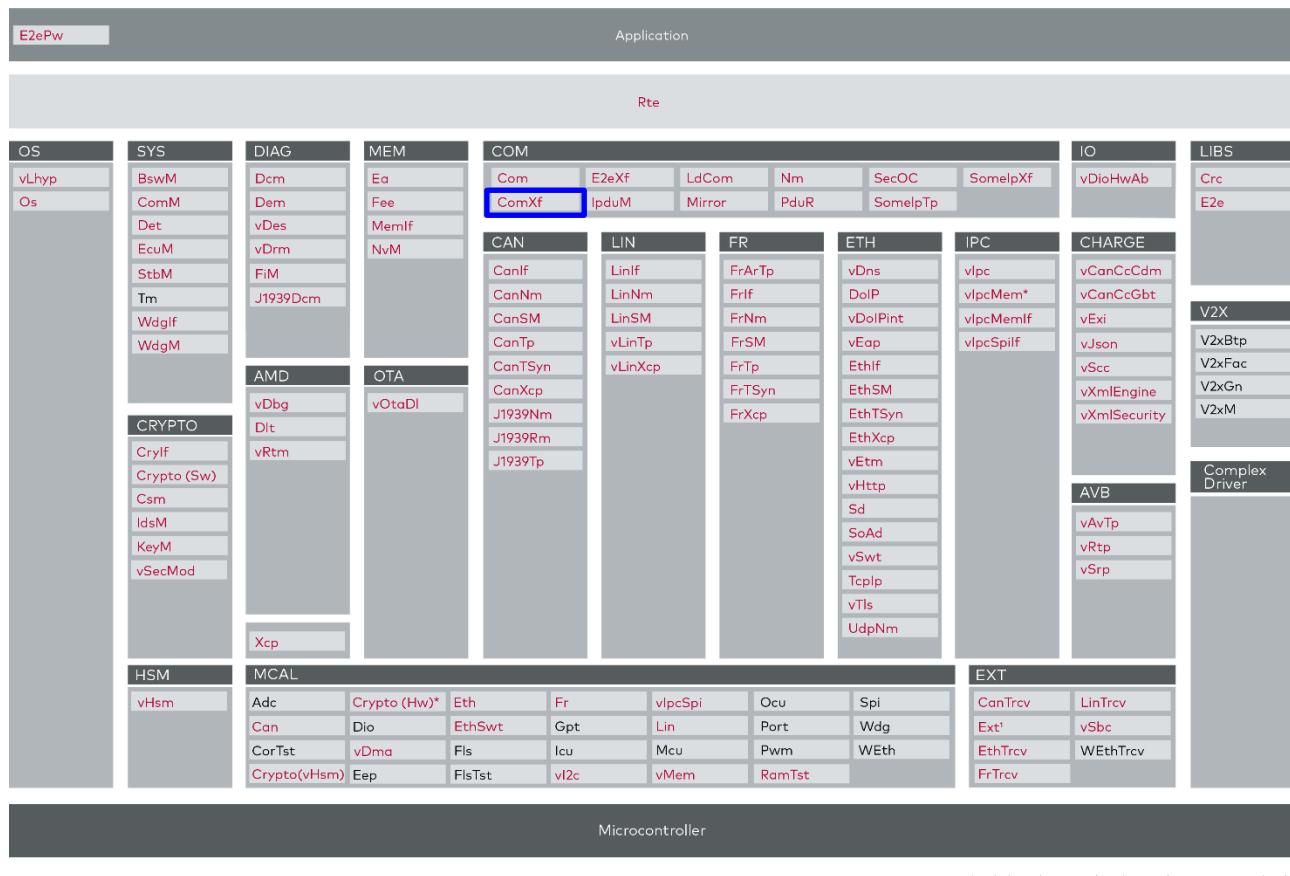


Figure 1-1 AUTOSAR Architecture Overview

## 2 Functional Description

### 2.1 Features

The features listed in the following tables cover the complete functionality specified for the ComXf.

The AUTOSAR standard functionality is specified in [1], the corresponding features are listed in the tables

- > Table 2-1 Supported AUTOSAR standard conform features
- > Table 2-2 Not supported AUTOSAR standard conform features

The following features specified in [1] are supported:

Supported AUTOSAR Standard Conform Features
Serialization / Deserialization of complex data for S/R communication.
Handling of gaps in the array representation of a signal group.

Table 2-1 Supported AUTOSAR standard conform features

#### 2.1.1 Deviations

The following features specified in [1] are not supported:

Category	Description
Functional	Development error detection.
Functional	Postbuild support.

Table 2-2 Not supported AUTOSAR standard conform features

### 2.2 Initialization

The ComXf does not have to be initialized or deinitialized. Calls to `ComXf_Init()` and `ComXf_DeInit()` can be omitted.

### 2.3 States

No internal states exist.

### 2.4 Main Functions

No main function exists because all functionality is performed within the called API.

### 2.5 Error Handling

#### 2.5.1 Development Error Reporting

No development error reporting is currently supported by the ComXf.

## 2.5.2 Production Code Error Reporting

No production errors are specified for the ComXf.

## 3 Integration

This chapter gives necessary information for the integration of the MICROSAR Classic ComXf into an application environment of an ECU.

### 3.1 Embedded Implementation

The delivery of the ComXf consists of:

File Name	Description	Integration Tasks
ComXf.c	Generated source file of the ComXf module.	-
ComXf.h	Generated main header file which shall be included by modules using the ComXf module.	-
ComXf_MemMap.h	Generated file with template areas that can be adapted by the user. It contains the ComXf specific part of the memory mapping.	Adapt the dedicated code areas within that file. See hints within that file.
ComXf_Compiler_Cfg.h	Generated file with template areas that can be adapted by the user. It contains the ComXf specific part of the compiler abstraction.	Adapt the dedicated code areas within that file. See hints within that file.

Table 3-1 Implementation files

## 4 API Description

### 4.1 Services provided by ComXf

#### 4.1.1 ComXf\_Init

Prototype	
<pre>void ComXf_Init (const ComXf_ConfigType *config)</pre>	
Parameter	
config	Pointer to the transformer's configuration data.
Return code	
void	none
Functional Description	
Initialization function.	
Particularities and Limitations	
none	
Expected Caller Context	
This function can be called in any context.	

Table 4-1 ComXf\_Init

#### 4.1.2 ComXf\_DelInit

Prototype	
<pre>void ComXf_DelInit (void)</pre>	
Parameter	
void	none
Return code	
void	none
Functional Description	
Deinitialization function.	
Particularities and Limitations	
none	
Expected Caller Context	
This function can be called in any context.	

Table 4-2 ComXf\_DelInit

### 4.1.3 ComXf\_GetVersionInfo

#### Prototype

```
void ComXf_GetVersionInfo (Std_VersionInfoType *versioninfo)
```

#### Parameter

versioninfo	Pointer to where to store the version information of this module.
-------------	---

#### Return code

void	none
------	------

#### Functional Description

This API returns version information, vendor ID and AUTOSAR module ID of the called transformer module.

#### Particularities and Limitations

This API is only available if enabled by the configuration parameter XfrmVersionInfoApi.

#### Expected Caller Context

This function can be called in any context.

Table 4-3 ComXf\_GetVersionInfo

#### 4.1.4 ComXf\_<transformerId>

##### Prototype

```
Std_ReturnType ComXf_<transformerId> (uint8 *buffer, uint32 *bufferLength, const  
<type> *dataElement)
```

##### Parameter

buffer	Buffer allocated by the RTE, where the transformed data has to be stored by the transformer.
bufferLength	Used length of the buffer.
dataElement	Data element which shall be transformed.

##### Return code

E_OK	Serialization successful.
------	---------------------------

##### Functional Description

Serialization of signal group based on the COM ECU configuration for S/R communication.

##### Particularities and Limitations

none

##### Expected Caller Context

This function can be called in any context.

Table 4-4 ComXf\_<transformerId>



##### Caution

The return code E\_SER\_GENERIC\_ERROR cannot occur and is therefore not supported.

### 4.1.5 ComXf\_Inv\_<transformerId>

#### Prototype

```
Std_ReturnType ComXf_Inv_<transformerId> (const uint8 *buffer, uint32  
bufferLength, <type> *dataElement)
```

#### Parameter

buffer	Buffer allocated by the RTE, where the serialized data is stored by the Rte.
bufferLength	Used length of the buffer.
dataElement	Data element which is the result of the transformation and contains the deserialized data element.

#### Return code

E_OK	Deserialization successful.
------	-----------------------------

#### Functional Description

Deserialization of signal group based on the COM ECU configuration for S/R communication.

#### Particularities and Limitations

none

#### Expected Caller Context

This function can be called in any context.

Table 4-5 ComXf\_Inv\_<transformerId>



#### Caution

The return code `E_SER_GENERIC_ERROR` cannot occur and is therefore not supported.



#### Caution

The MICROSAR Classic RTE never calls `ComXf_Inv_<id>` with a `NULL_PTR` or with a buffer size equal 0. Therefore, the return code `E_NO_DATA` cannot occur and is thus not supported.

## 5 Configuration

In the ComXf the attributes can be configured with the following tools:

- > Configuration in DaVinci Configurator

Currently, only the GetVersionInfo API can be enabled / disabled in the ComXf ECU configuration.

The serialization / deserialization of the signal groups is based on the ECU configuration of the COM module (for details see [3]).

### 5.1 Configuration Variants

The ComXf supports the configuration variants

- > VARIANT-PRE-COMPIL

The configuration classes of the ComXf parameters depend on the supported configuration variants. For their definitions please see the `ComXf_bswmd.arxml` file.

### 5.2 Enabling / Disabling of data transformation

If a signal shall be handled by the ComXf, the parameter “Signal Group Array Access” has to be set in the ECU configuration of the COM module (see Figure 5-1 Enable Data Transformation).

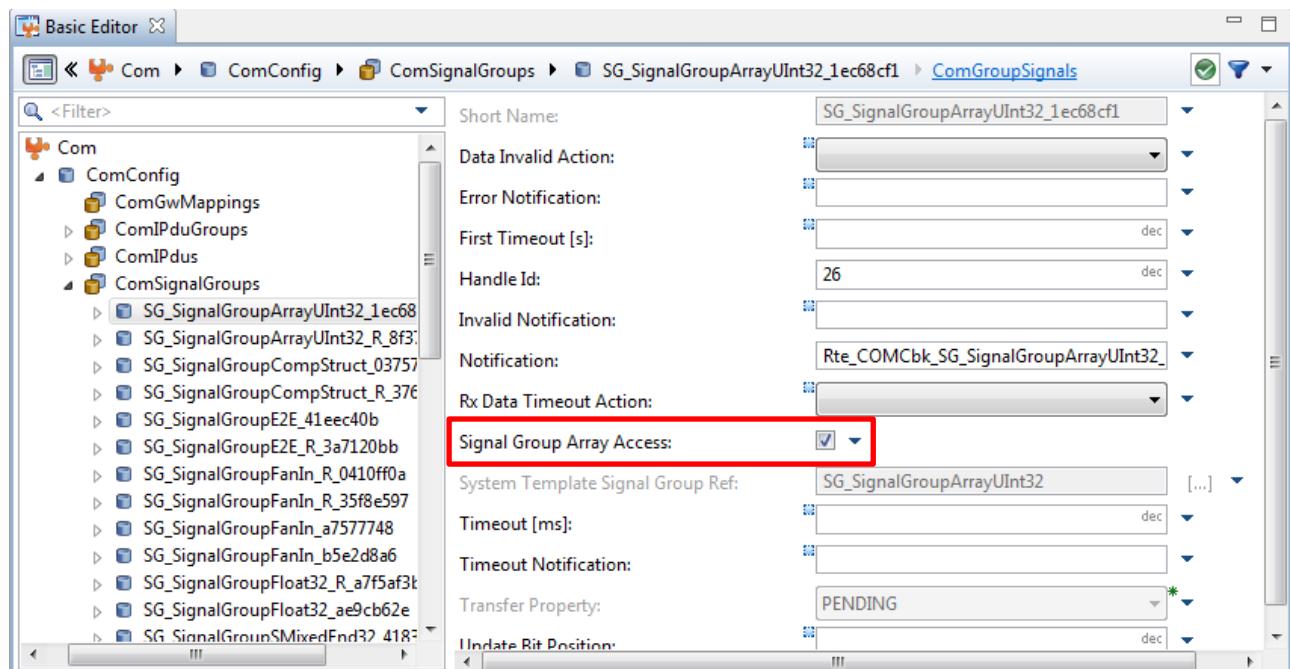


Figure 5-1 Enable Data Transformation

## 6 Glossary and Abbreviations

### 6.1 Glossary

Term	Description
DaVinci Configurator	Configuration and generation tool for MICROSAR Classic components

Table 6-1 Glossary

### 6.2 Abbreviations

Abbreviation	Description
API	Application Programming Interface
AUTOSAR	Automotive Open System Architecture
BSW	Basis Software
DEM	Diagnostic Event Manager
DET	Development Error Tracer
ECU	Electronic Control Unit
MICROSAR	Microcontroller Open System Architecture (the Vector AUTOSAR solution)
RTE	Runtime Environment
SRS	Software Requirement Specification
SWC	Software Component
SWS	Software Specification

Table 6-2 Abbreviations

## 7 Additional Copyrights

The MICROSAR Classic COMXF Generator contains *Free and Open Source Software* (FOSS). The following table lists the files which contain this software, the kind and version of the FOSS, the license under which this FOSS is distributed and a reference to a license file which contains the original text of the license terms and conditions. The referenced license files can be found in the directory of the RTE Generator.

File	FOSS	License	License Reference
MicrosarComXfGen64.exe	Perl 5.30	Artistic License	License_Artistic.txt

Table 7-1 Free and Open Source Software Licenses

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