

Exercise 1 Multilayer Perceptrons

a. Implementation Back-Propagation

- i. MultiLayerPerceptron.java, lines 206-243 and 326-391

b. XOR

- i. With the given parameters 10000 epochs was not enough to reduce the error below the constraint (< 0.01). But increasing the momentum coefficient (0.5 to 0.95) helped in learning faster.
- ii. Also we reduced the number of units in first hidden layer (20 to 2). Since 2 two units are sufficient enough to learn XOR.

```
epoch: 9993 training error: 0.0030821856118021795
epoch: 9994 training error: 0.0030820316494192257
epoch: 9995 training error: 0.0030818723001621307
epoch: 9996 training error: 0.003081714075022224
epoch: 9997 training error: 0.003081557702704213
epoch: 9998 training error: 0.0030814014871231865
epoch: 9999 training error: 0.003081242603812623
epoch: 10000 training error: 0.0030810876520673824
```

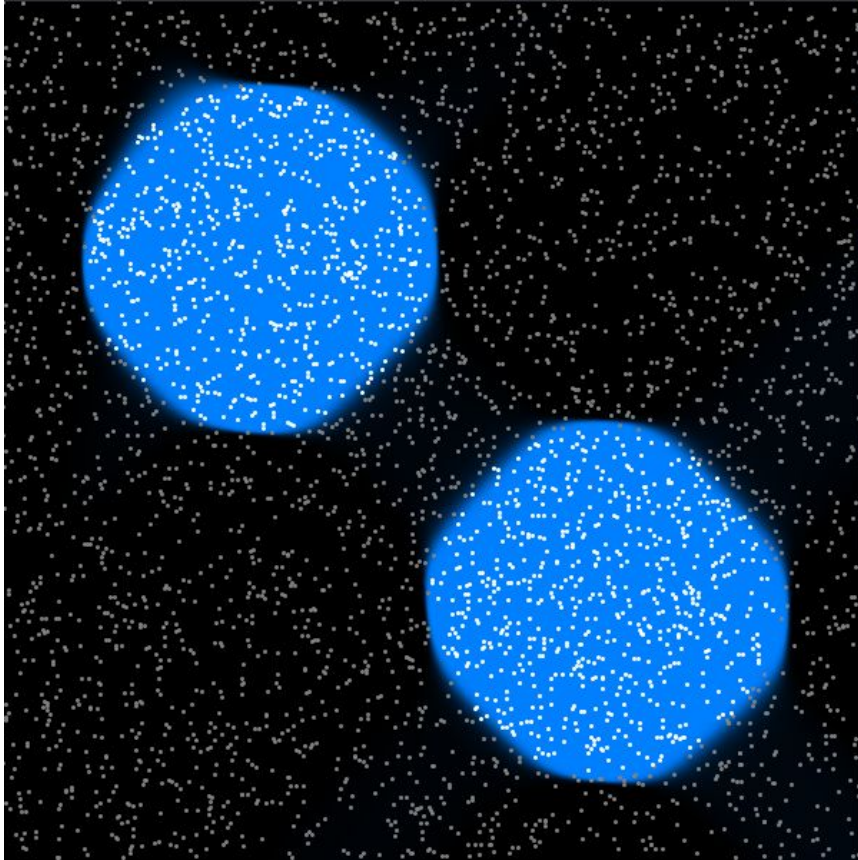
c. Geometry:

- i. No, It is not solvable by one hidden layer. (since the data is not linearly separable)
- ii. We need two hidden layers: one to learn set of linear separators and the second layer to learn to combine them to create the decision boundary.
- iii. Increasing the number of units in the first hidden layer smoothens the decision boundary with better approximation.

Screenshot of a successful training run

Parameters (learning rate: 0.01, momentum: 0.95, 20 units in hidden layer)

```
epoch: 1995 training error: 0.022602483988094214
epoch: 1996 training error: 0.02061975422544343
epoch: 1997 training error: 0.023962082012653898
epoch: 1998 training error: 0.02646158333376371
epoch: 1999 training error: 0.02514416648485564
epoch: 2000 training error: 0.02323801198981493
```



Exercise 2 Recurrent Neural Networks

a. Implementation Back-Propagation Through Time

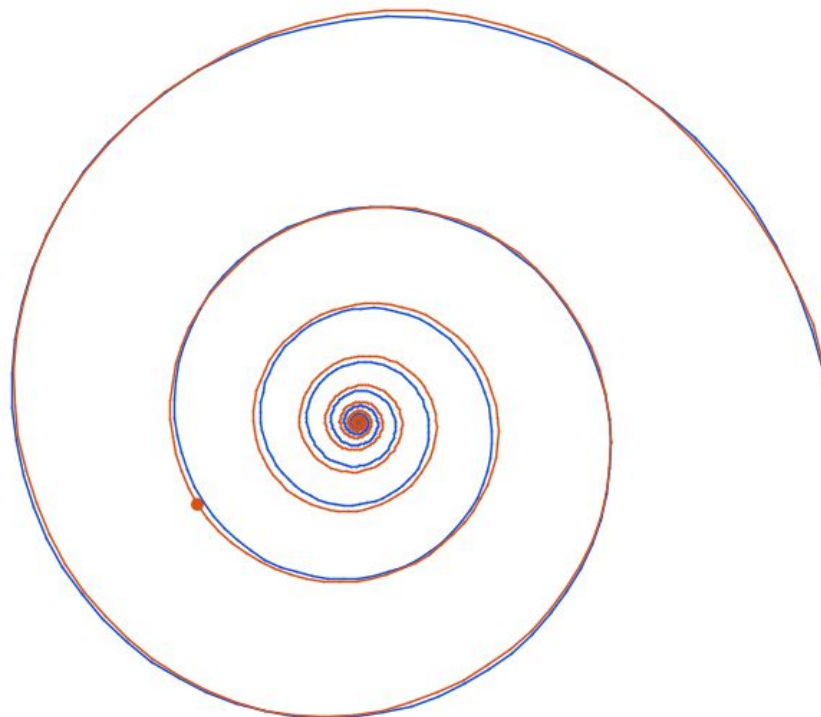
- i. RecurrentNeuralNetwork.java, lines 325-423 and 514-582

b. Trajectory Generation

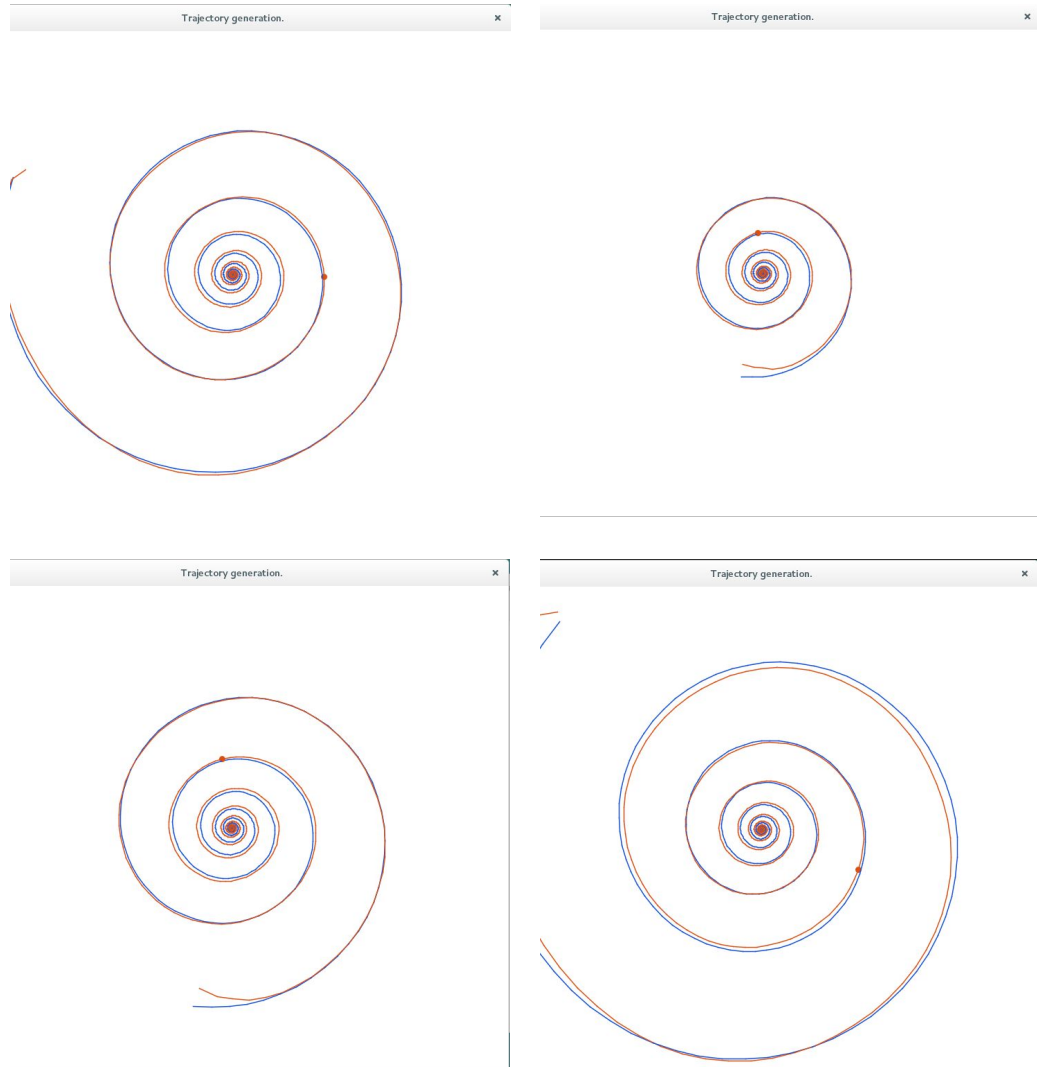
- i. We found that the initial settings (learning rate = 0.00002, momentum rate = 0.95, one hidden layer of 16 neurons) work pretty well:

```
franek@debian:java$ javac de/cogmod/anns/exercisesheet01/RNNTrajectory.java && java
epoch: 1 training error: 0.4672477719933927
epoch: 1001 training error: 0.46478949589974766
epoch: 2001 training error: 0.42308284249417766
epoch: 3001 training error: 0.46097955407332786
epoch: 4001 training error: 0.4123991598705403
epoch: 5001 training error: 0.4078908795002563
epoch: 6001 training error: 0.45531733332275587
epoch: 7001 training error: 0.0727340287844561
epoch: 8001 training error: 0.04995516531206807
epoch: 9001 training error: 0.040903661495657606
epoch: 10001 training error: 0.03546548223652344
epoch: 11001 training error: 0.031686386862729024
epoch: 12001 training error: 0.028870290149261155
epoch: 13001 training error: 0.026680946749573848
epoch: 14001 training error: 0.024925860300448372
epoch: 15001 training error: 0.023484321797008992
epoch: 16001 training error: 0.022276696987753468
epoch: 17001 training error: 0.021248494144430242
```

- ii. Below is a spiral corresponding to the above training run:



- iii. We implemented the “tricky” part, that is forcing trajectory to start from a chosen point. You can run the `RNNTrajectory.java` file and after clicking it will start the spiral from the point you clicked. We implemented it in the function `forceTrajectoryByInitialization()` in `RecurrentNeuralNetwork.java`, lines 630-661.



c. Gradient Measurement

- i. We implemented gradient measurement in GradientMeasurement.java, closely following the instructions. The result indeed shows that vanishing gradient is a problem:

```
frane@debian:~$ javac de/cogmod/anns/exercisesheet01/GradientMeasurement.java && java -ea de.cogmod.anns.exercisesheet01.GradientMeasurement
100
[[-1.0782431235968582E-117, -1.6007426315158488E-116, -2.377730299871274E-115, -3.531995457343568E-114, -5.246610105502545E-113, -7.793589395066738E-112, -1.1577005941302315E-110, -1.7197091080316978E-109, -2.554545995222909E-108, -3.794656440007762E-107, -5.636781457301306E-106, -8.373170456852046E-105, -1.2437946021250606E-103, -1.847597657598688E-102, -2.744518346141632E-101, -4.0768513216767057E-100, -6.055968517180166E-99, -8.99585287451541E-98, -1.3362911103376798E-96, -1.9849968162843038E-95, -2.94861825404431E-94, -4.380032016554155E-93, -6.506329003330914E-92, -9.664841932568473E-91, -1.435666249488968E-89, -2.1326138537001027E-88, -3.1678963342716313E-87, -4.705759163704131E-86, -6.990181170772696E-85, -1.0383581288457396E-83, -1.542431558495418E-82, -2.2912086365493716E-81, -3.4034813326299204E-80, -5.055709461276174E-79, -7.510015674769892E-78, -1.1155770691983706E-76, -1.6571366175735155E-75, -2.4615975400751836E-74, -3.656585935670678E-73, -5.431684297399903E-72, -8.06850839161512E-71, -1.1985385029966996E-69, -1.7803718772337028E-68, -2.6446576503962238E-67, -3.9285130130603445E-66, -5.835619022928074E-65, -8.668534192847513E-64, -1.28766947871903E-62, -1.912771697656388E-61, -2.8413312793551345E-60, -4.22066232417255E-59, -6.269592913760017E-58, -9.313181743809844E-57, -1.3834288028952075E-55, -2.0550176140953708E-54, -3.0526308151198174E-53, -4.5345377234253806E-52, -6.735839874027074E-51, -1.0005769402720837E-49, -1.4863094018381065E-48, -2.20784184511751E-47, -3.2796439335064128E-46, -4.8717549014535217E-45, -7.236759935235209E-44, -1.074986230210398E-42, -1.5968408590085468E-41, -2.3720310617374915E-40, -3.523539196849532E-39, -5.2340497019634E-38, -7.774931610557315E-37, -1.1549290700500509E-35, -1.7155921410748755E-34, -2.5484304368495322E-33, -3.7855720692402333E-32, -5.6232870570827764E-31, -8.353125167869567E-30, -1.2408169698932887E-28, -1.843174526699734E-27, -2.7379479958006686E-26, -4.0670913790954896E-25, -6.041470587199972E-24, -8.974316889855507E-23, -1.3330920423610431E-21, -1.9802447531301187E-20, -2.941559290500464E-19, -4.369546262325601E-18, -6.490752914708458E-17, -9.641704394582515E-16, -1.4322292783916167E-14, -2.1275083967879634E-13, -3.1603124211273525E-12, -4.694493621839854E-11, -6.973446744747324E-10, -1.0358723095414178E-8, -1.5387389922822895E-7, -2.2857235052630258E-6, -3.39533343128113E-5, -5.043606141788656E-4, -0.007492036769976366, -0.11129063884986831]]
```

- ii. And below you can find a log-scale plot of the above sequence (reversed in time):

