

Lecture \approx 13

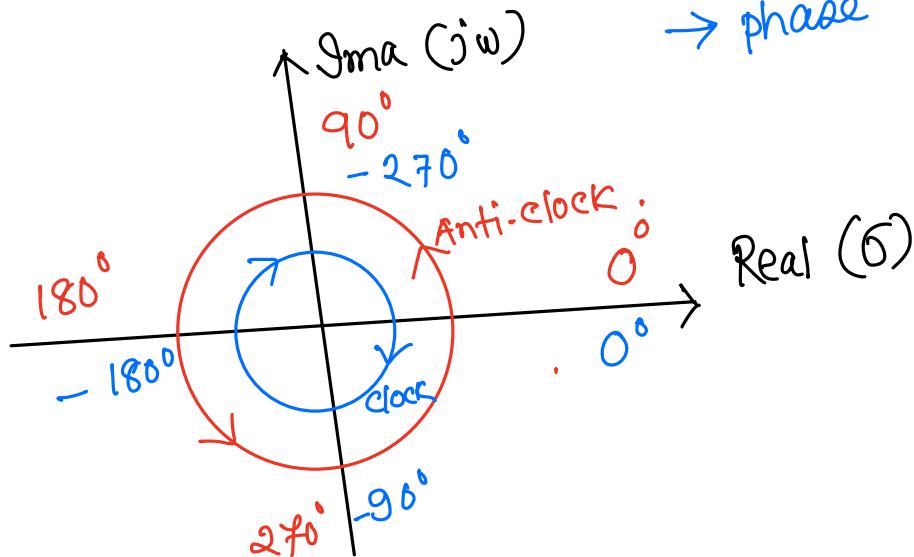
Polar Plot

Rise : 10

Polar Plot :

- used for frequency response characteristics of system
- plot of Mag. and phase by varying freq from $0 \rightarrow \infty$ plane with a circular pattern.
- plotted on a real-imaginary plane

→ Magnitude = Distance w.r.t. Center
→ phase = Angle w.r.t. Real axis.



Procedure :

- plot of Mag. and phase by varying freq from $0 \rightarrow \infty$
- plotted using Open Loop Transfer function $G(s)$

Step : 1 Determine Open loop Transfer function $G(s)$

Step : 2 Put $s = j\omega$, $G(j\omega) = |G(j\omega)| \angle G(j\omega)$.

Step : 3 find Mag $|G(j\omega)|$ and phase $\angle G(j\omega)$ at $\omega = 0$

Step 4 Separate real & imaginary part of $G(j\omega)$

$$G(j\omega) = \text{Real}[G(j\omega)] + j \text{Imag}[G(j\omega)].$$

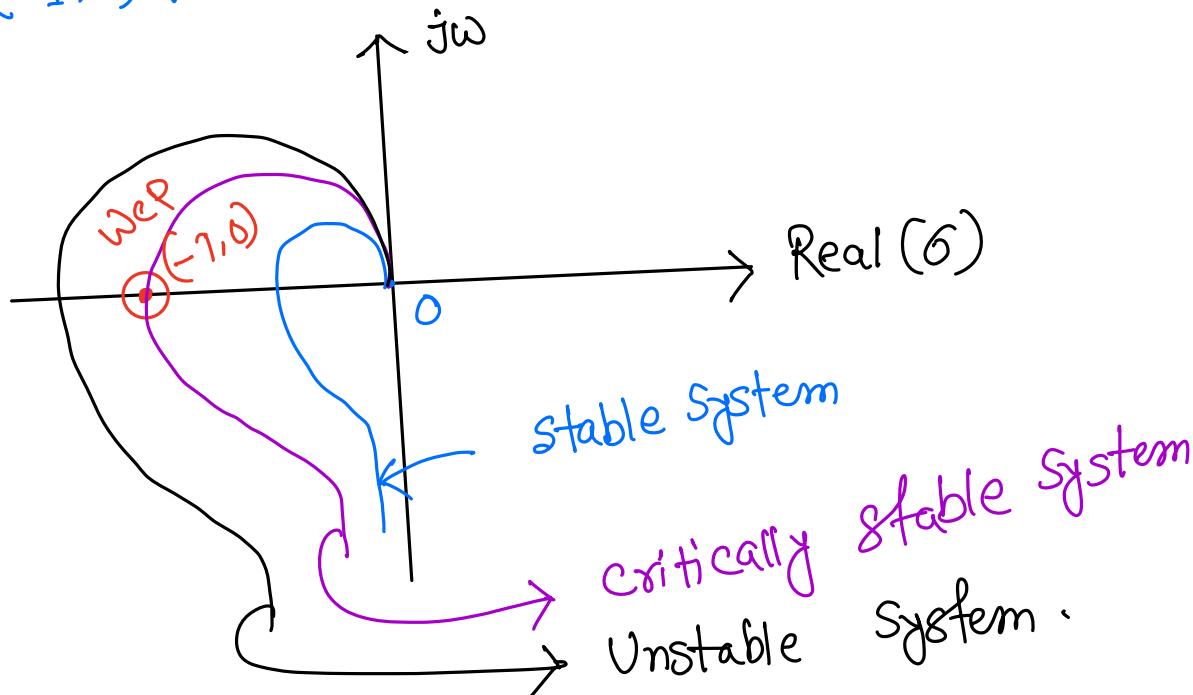
Step 5 If $\text{Real}[G(j\omega)] = 0$,
 \Rightarrow get intersection to Imaginary axis

If $\text{Imag}[G(j\omega)] = 0$,
 \Rightarrow " " " real axis

Advantages of Polar Plot

- Single Plot plots Frequency Response Characteristics {Magnitude and Phase}.
- Graphical Study of Stability is Easy with Polar Plot {Compared to Root Locus and Bode Plot}.
- Easy to determine Gain Cross Over Frequency ω_{GC} and Phase Cross Over Frequency ω_{PC} using Polar Plot.
- Polar Plot can be plotted from the Open Loop Transfer Function {Other techniques need Closed Loop Transfer Function}.

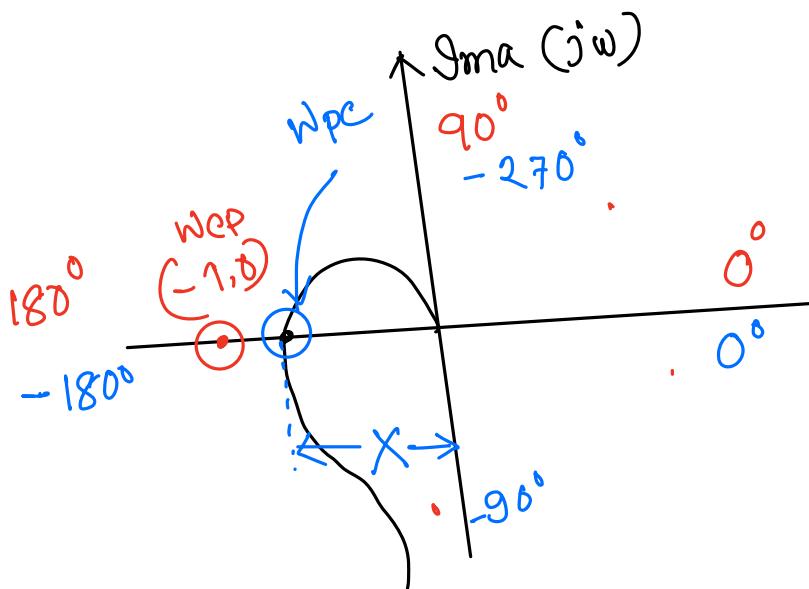
Critical Point and stability of Polar Plot
 $\rightarrow (-1,0)$ point is Critical Point in Polar Plot.



Phase Cross-over Frequency and Gain Margin:

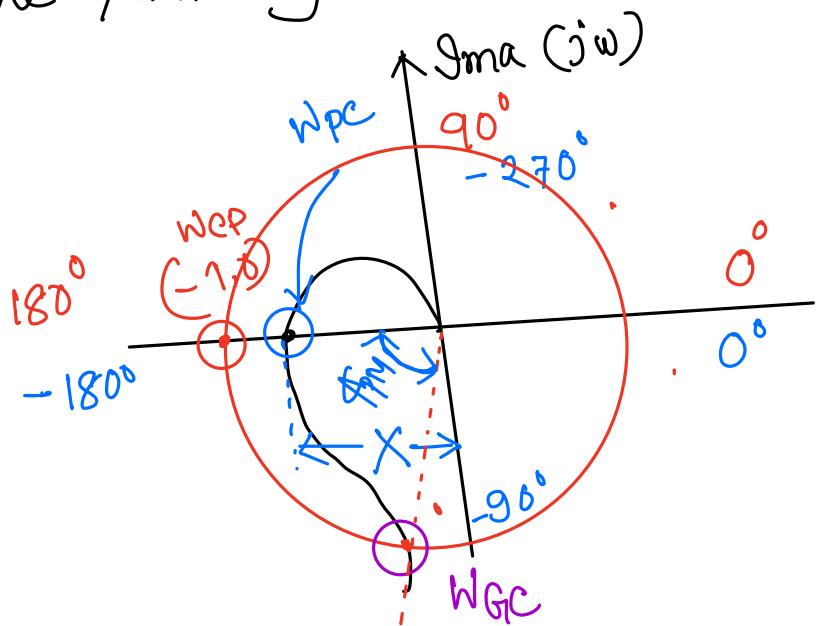
ω_{pc} : Freq, at which phase is crossing -180° Angle.
 Let's. $X = \text{Mag. at } \omega_{pc} \text{ from origin.}$

$$\text{Gain Margin} = 20 \log \left(\frac{1}{X} \right).$$



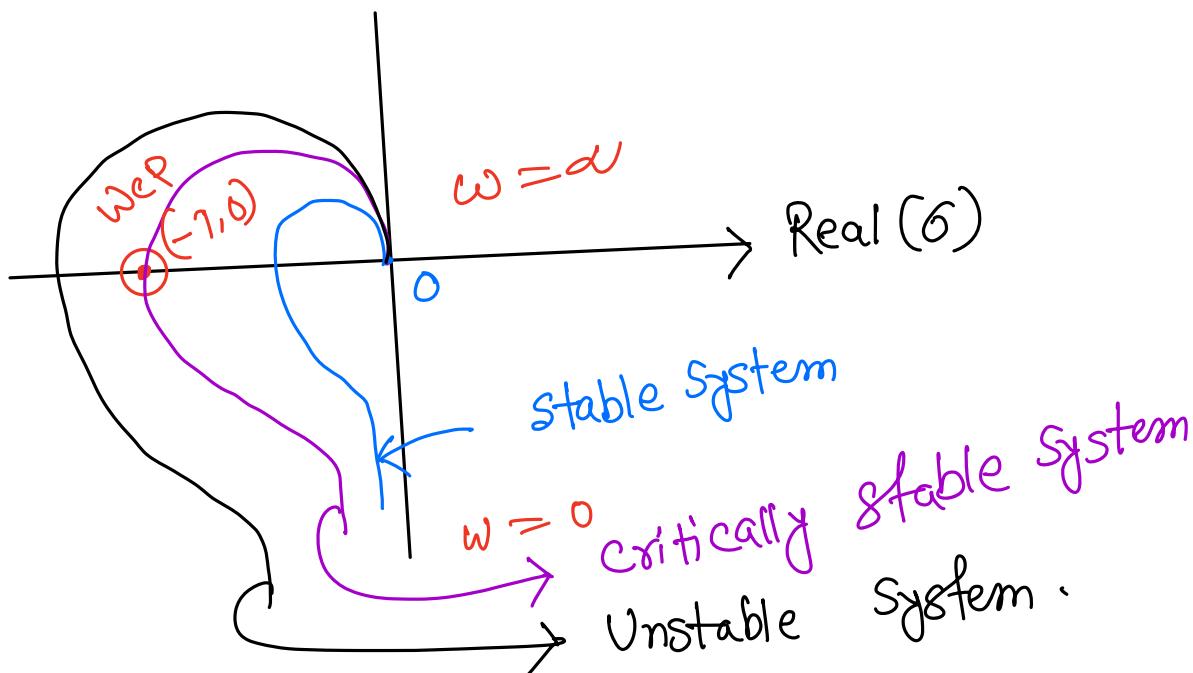
Gain Cross-over Frequency and Phase Margin:

ω_{pc} : Freq, at which gain is crossing Unit Magnitude
 Phase Margin, ϕ_{PM} = Angle measure from -180° in anticlockwise direction to the point of WGC.



Stability Analysis

→ Polar Plot can be drawn for all systems, but stability analysis is only applicable for minimum phase system.



Stable : If $(-1, 0)$ is not enclosed by polar plot
 Unstable : If $(-1, 0)$ is enclosed by polar plot
 Critically " : " is crossed by || or

$W_{PC} > W_{GC}$ & $GM = +ve \rightarrow$ stable

$W_{PC} < W_{GC}$ & $GM = -ve \rightarrow$ unstable

$W_{PC} = W_{GC}$ & $GM = 0 \rightarrow$ critically stable

Polar Plot For Type "0" System

→ Zero number of pole at origin \Rightarrow Type 0

Expo $G(s) = \frac{K}{(1+sT_1)(1+sT_2)}$

Step 1: $G(j\omega) = \frac{K}{(1+j\omega T_1)(1+j\omega T_2)}$

Step 2: Write $G(j\omega)$ in polar form

$$G(j\omega) = |G(j\omega)| \angle G(j\omega)$$

$$|G(j\omega)| = \frac{K}{\sqrt{1+\omega^2 T_1^2} \cdot \sqrt{1+\omega^2 T_2^2}}$$

$$\text{phase} = \angle G(j\omega) = -\tan^{-1}\left(\frac{\omega T_1}{1}\right) - \tan^{-1}\left(\frac{\omega T_2}{1}\right)$$

Step 3 Find Mag. & phase at $\omega=0, \omega=\infty$

→ At $\omega=0$, Mag = K , phase = 0°

→ At $\omega=\infty$ Mag = 0 " = -180°

Step 4: Separate real & imaginary part of $G(j\omega)$ by multiplying complex conjugate of denominator.

$$\Rightarrow G(j\omega) = \frac{K}{(1+j\omega T_1)(1+j\omega T_2)} \times \frac{(1-j\omega T_1)(1-j\omega T_2)}{(1-j\omega T_1)(1-j\omega T_2)}$$

$$\begin{aligned}
 &= \frac{K(1 - \tilde{\omega}^2 T_1 T_2) - Kj(\omega T_1 + \omega T_2)}{(1 + \omega^2 T_1^2)(1 + \omega^2 T_2^2)} \\
 &= \frac{K(1 - \tilde{\omega}^2 T_1 T_2)}{(1 + \omega^2 T_1^2)(1 + \omega^2 T_2^2)} + j \frac{K(\omega T_1 + \omega T_2)}{(1 + \omega^2 T_1^2)(1 + \omega^2 T_2^2)}
 \end{aligned}$$

↓ Real ↓ imv

Step 5: Intersection to Real Axis ,
 $\text{Img}[G(j\omega)] = 0$

$$\Rightarrow \omega = 0$$

Step 6: Intersection to Imag Axis ,
 $\text{Real}[G(j\omega)] = 0$

$$\begin{aligned}
 \Rightarrow 1 - \tilde{\omega}^2 T_1 T_2 &= 0 \\
 \therefore \omega &= \frac{1}{\sqrt{T_1 T_2}}
 \end{aligned}$$

$$\therefore \text{Magnitude, } |G(j\omega)| = \frac{K}{\sqrt{1 + \tilde{\omega}^2 T_1^2} \cdot \sqrt{1 + \tilde{\omega}^2 T_2^2}}$$

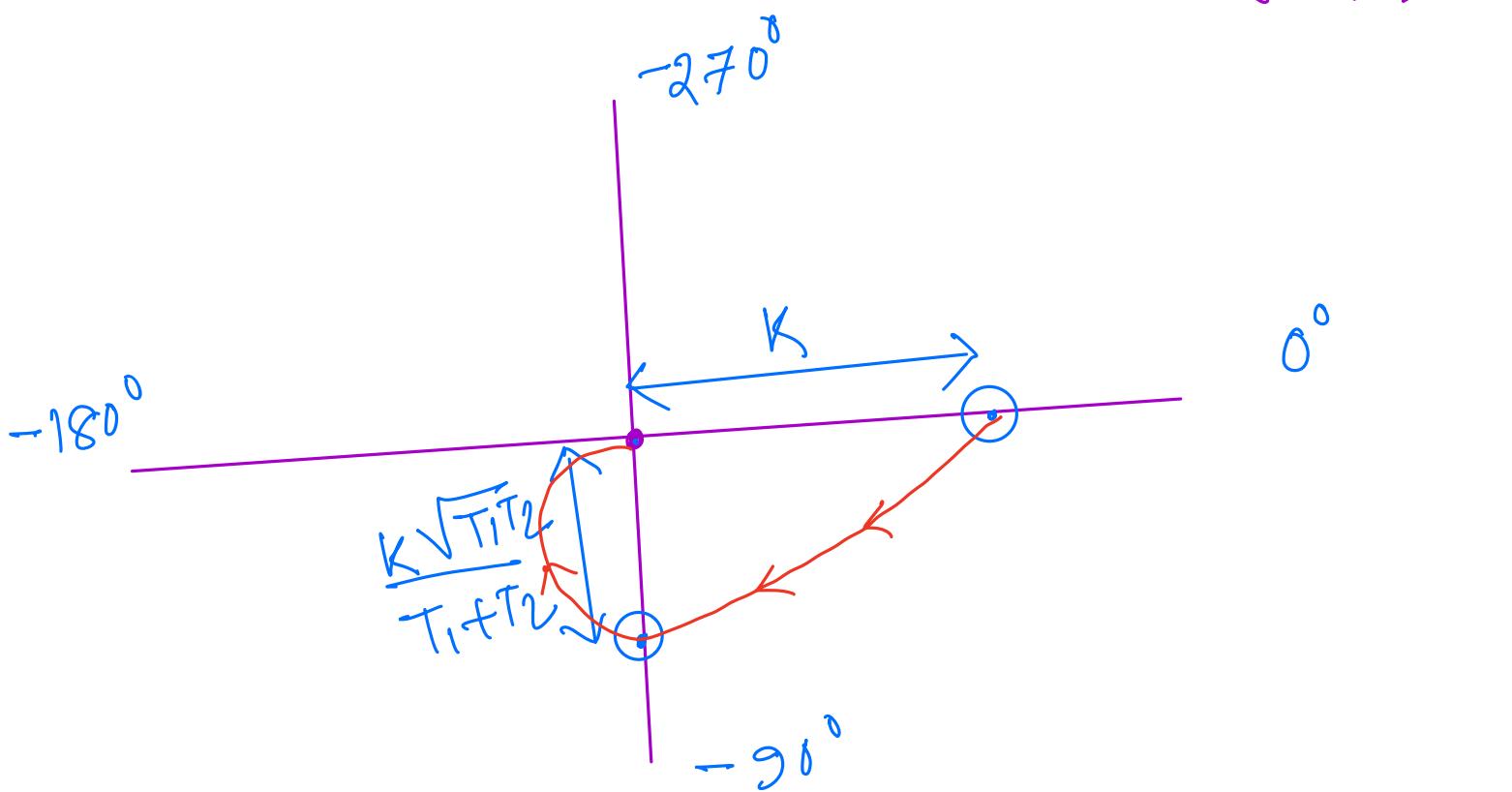
Put, value of $\tilde{\omega}$

$$= \frac{K \sqrt{T_1 T_2}}{T_1 + T_2}$$

$$\text{phase} = \angle G_1(j\omega) = -\tan^{-1}\left(\frac{\omega T_1}{1}\right) - \tan^{-1}\left(\frac{\omega T_2}{1}\right)$$

Put value of ω

$$\therefore \angle G_1(j\omega) = -\tan^{-1}(0) = -90^\circ \\ = -\tan^{-1} \tan^{-1} \left(\frac{K\sqrt{T_1 T_2}}{T_1 + T_2} \times T_1 \right)$$



Type 1 system
one pole at origin.

$$G_i(s) = \frac{K}{s(1+sT_1)(1+sT_2)}$$

Step 1: $G(j\omega) = \frac{K}{j\omega(1+j\omega T_1)(1+j\omega T_2)}$

Step 2: Write $G_i(j\omega)$ in polar form

$$G_i(j\omega) = |G_i(j\omega)| \angle G_i(j\omega)$$

$$|G_i(j\omega)| = \frac{K}{\omega \sqrt{1+\omega^2 T_1^2} \cdot \sqrt{1+\omega^2 T_2^2}}$$

$$\text{phase} = \angle G_i(j\omega) = -90^\circ - \tan^{-1}\left(\frac{\omega T_1}{1}\right) - \tan^{-1}\left(\frac{\omega T_2}{1}\right)$$

Step 3 Find Mag. & phase at $\omega=0, \omega=\infty$

$$\rightarrow \text{At } \omega=0, \text{ Mag} = \infty, \text{ phase} = -90^\circ$$

$$\rightarrow \text{At } \omega=\infty, \text{ Mag} = 0, \text{ " } = -270^\circ$$

Step 4: Separate real & imaginary part of $G_i(j\omega)$

$$\Rightarrow G_i(j\omega) = \frac{K}{j\omega(1+j\omega T_1)(1+j\omega T_2)} \times \frac{(1-j\omega T_1)(1-j\omega T_2)}{(1-j\omega T_1)(1-j\omega T_2)}$$

$$\begin{aligned}
 &= \frac{-j K(1 - \omega^2 T_1 T_2) - K j(\omega T_1 + \omega T_2)}{\omega(1 + \omega^2 T_1^2)(1 + \omega^2 T_2^2)} \\
 &= \frac{-K j(\omega T_1 + \omega T_2)}{\omega(1 + \omega^2 T_1^2)(1 + \omega^2 T_2^2)} \quad j \rightarrow \frac{K(1 - \omega^2 T_1 T_2)}{\omega(1 + \omega^2 T_1^2)(1 + \omega^2 T_2^2)} \\
 &= \frac{-K(\omega T_1 + \omega T_2)}{(1 + \omega^2 T_1^2)(1 + \omega^2 T_2^2)} \quad j \rightarrow \frac{K(1 - \omega^2 T_1 T_2)}{\omega(1 + \omega^2 T_1^2)(1 + \omega^2 T_2^2)} \\
 &\quad \text{Real} \qquad \qquad \qquad \text{Img.}
 \end{aligned}$$

Step 5: Intersection to Real Axis ,
 $\text{Img}[G(j\omega)] = 0$

$$\Rightarrow 1 - \omega^2 T_1 T_2 = 0$$

$$\therefore \omega = \frac{1}{\sqrt{T_1 T_2}}$$

$$\therefore \text{Magnitude}, |G(j\omega)| = \frac{K}{\omega \sqrt{1 + \omega^2 T_1^2} \cdot \sqrt{1 + \omega^2 T_2^2}}$$

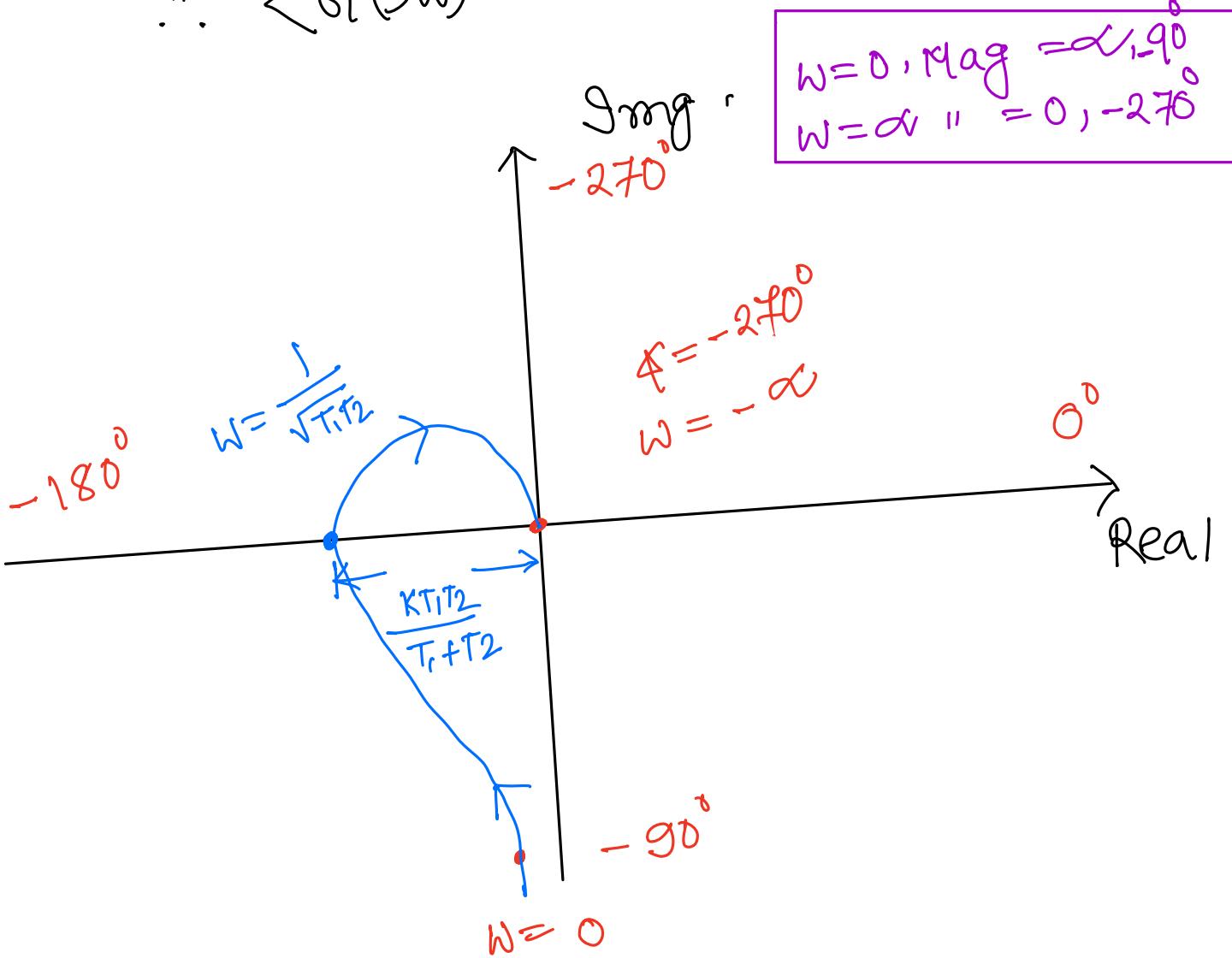
Put value of ω

$$= \frac{K T_1 T_2}{T_1 + T_2}$$

$$\text{phase} = \angle G(j\omega) = -90^\circ - \tan^{-1}(\omega T_1) - \tan^{-1}(\omega T_2)$$

Put value of ω

$$\angle G(j\omega) = -180^\circ$$



Examp^o: Sketch polar plot for given open loop T.F. $G(s) = \frac{s^3}{(s+1)(s+2)}$

Step 1^o: Put $s = j\omega$

$$G(j\omega) = \frac{(j\omega)^3}{(1+j\omega)(2+j\omega)}$$

Step 2^o: $G(j\omega) = |G(j\omega)| \angle G(j\omega)$

$$= \frac{\omega}{\sqrt{1+\omega^2} \sqrt{4+\omega^2}} \begin{cases} 270^\circ - \tan^{-1}\omega \\ -\tan^{-1}\left(\frac{\omega}{2}\right) \end{cases}$$

Step 3

$$\text{At } w = 0$$

$$\begin{aligned} |G(j\omega)| &= 0 \\ \angle G(j\omega) &= 270^\circ \end{aligned}$$

At $w = \infty$

$$|G(j\omega)| = \infty$$

$$\angle G_L(j\omega) = 270^\circ - 90^\circ - 90^\circ = 90^\circ$$

Step 4^o Separate real & imaginary.

$$G(j\omega) = \frac{(j\omega)^3}{(1+j\omega)(2+j\omega)} \times \frac{(1-j\omega)(2-j\omega)}{(1-j\omega)(2-j\omega)}$$

$$= \frac{-3\omega^4}{(1+\omega^2)(4+\omega^2)} + \frac{j\omega^3(\omega^2-2)}{(1+\omega^2)(4+\omega^2)}$$

Real Imaginary

Step 5: Intersection to real axis at $\text{img}(G(jw))$

$$w=0, \quad w=\sqrt{2}, \quad$$

$$A), w = \sqrt{2}, |G(i\omega)| = 0.66 < 180^\circ$$

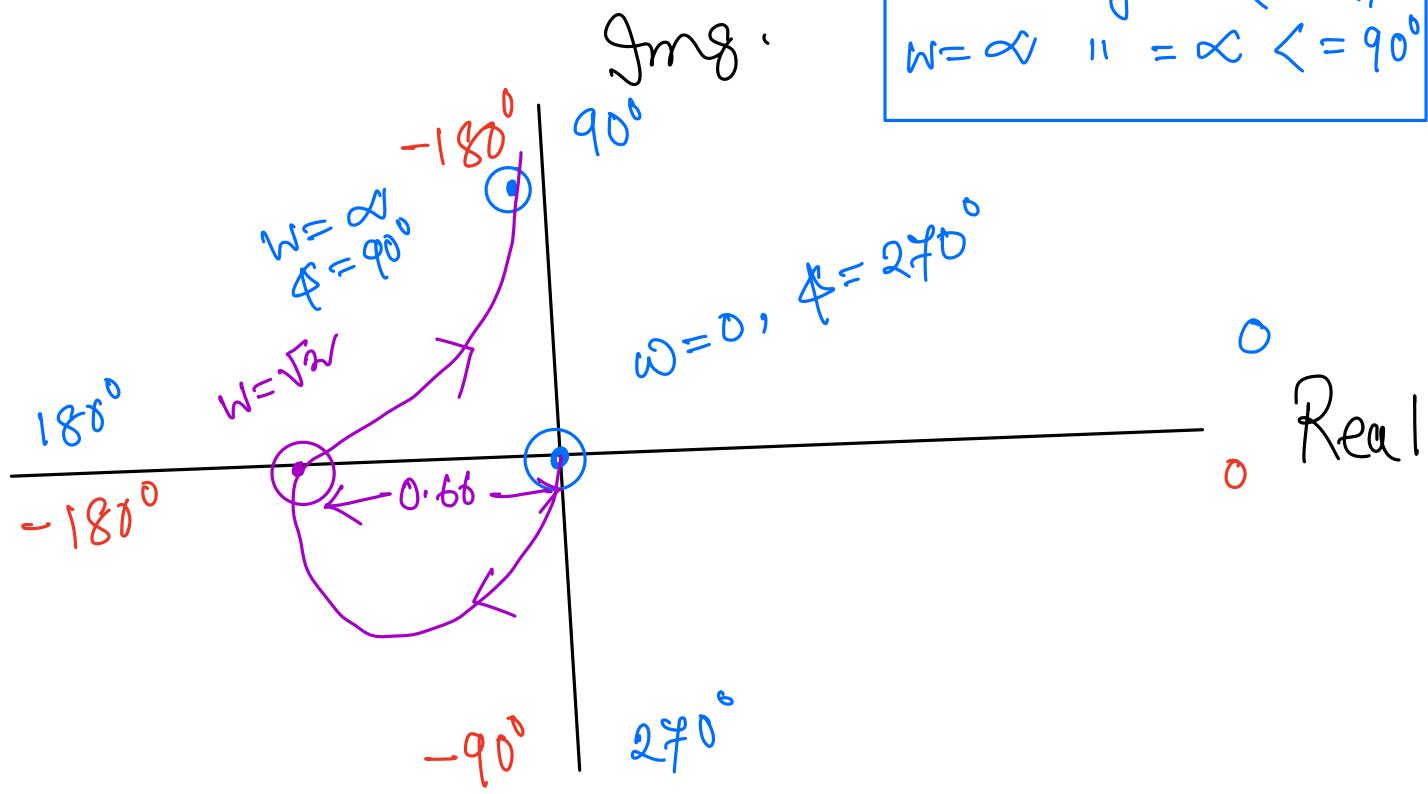
Step 6:

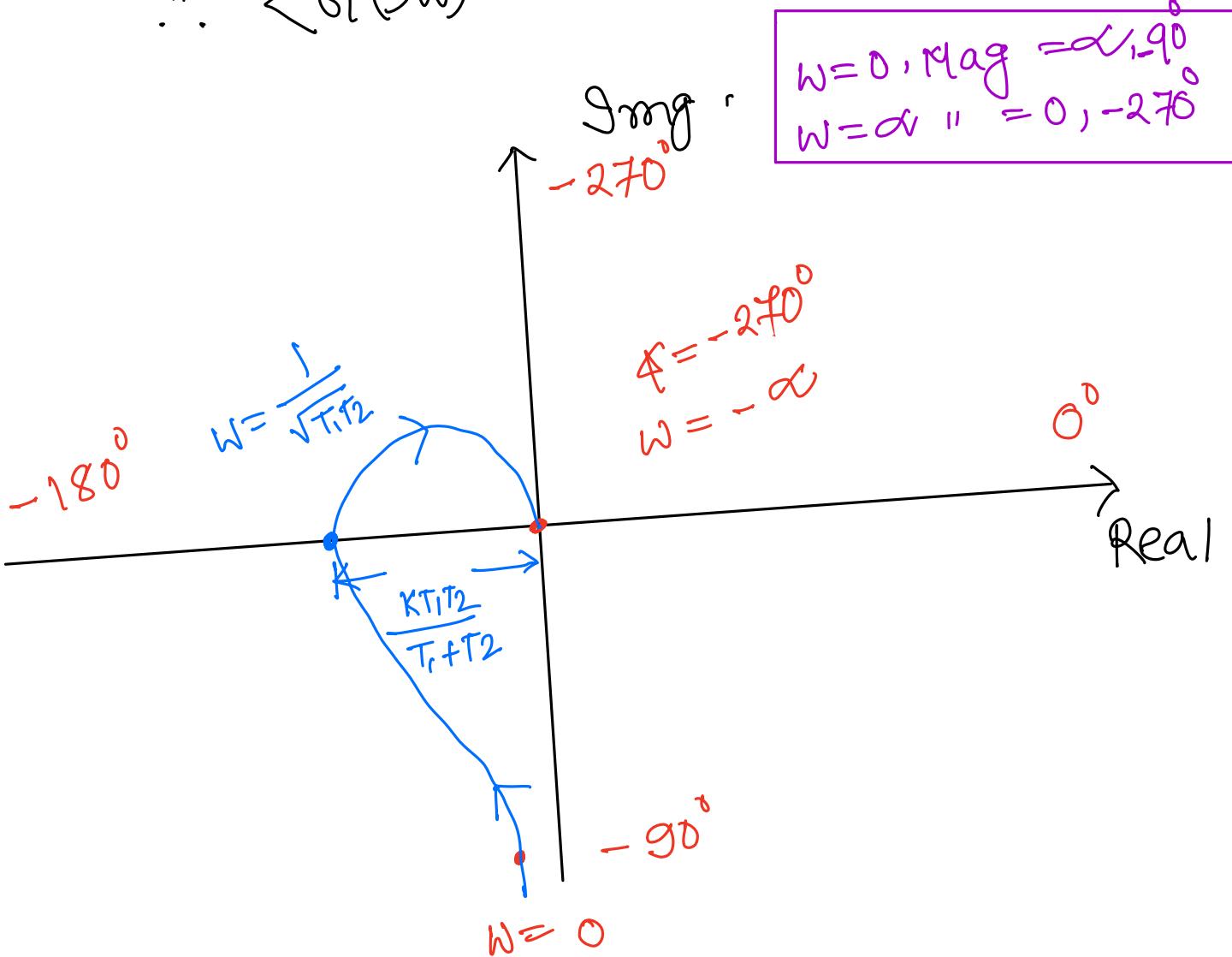
" " img

$$\Rightarrow \omega = 0,$$

$$W=0, \text{Mag}=0, \angle = 270^\circ$$

$$W=\infty \parallel = \infty \angle = 90^\circ$$





Examp: Sketch polar plot for given open loop T.F.

$$G(s) = \frac{s^3}{(s+1)(s+2)}$$

Step 1: Put $s = j\omega$

$$G(j\omega) = \frac{(j\omega)^3}{(1+j\omega)(2+j\omega)}$$

Step 2: $G(j\omega) = |G(j\omega)| \angle G(j\omega)$

$$= \frac{\omega}{\sqrt{1+\omega^2} \sqrt{4+\omega^2}} \begin{cases} 270^\circ - \tan^{-1} \omega \\ -\tan^{-1} \left(\frac{\omega}{2} \right) \end{cases}$$

Step 3

$$\text{At } w = 0$$

$$\begin{aligned} |G(j\omega)| &= 0 \\ \angle G(j\omega) &= 270^\circ \end{aligned}$$

At $w = \infty$

$$|G_1(j\omega)| = \infty$$

$$\angle G_L(j\omega) = 270^\circ - 90^\circ - 90^\circ = 90^\circ$$

Step 4^o Separate real & imaginary.

$$G(j\omega) = \frac{(j\omega)^3}{(1+j\omega)(2+j\omega)} \times \frac{(1-j\omega)(2-j\omega)}{(1-j\omega)(2-j\omega)}$$

$$= \frac{-3\omega^4}{(1+\omega^2)(4+\omega^2)} + \frac{j\omega^3(\omega^2-2)}{(1+\omega^2)(4+\omega^2)}$$

Real Imaginary

Step 5:

Intersection to real axis at $\operatorname{img}(\beta_1(jw)) = 0$

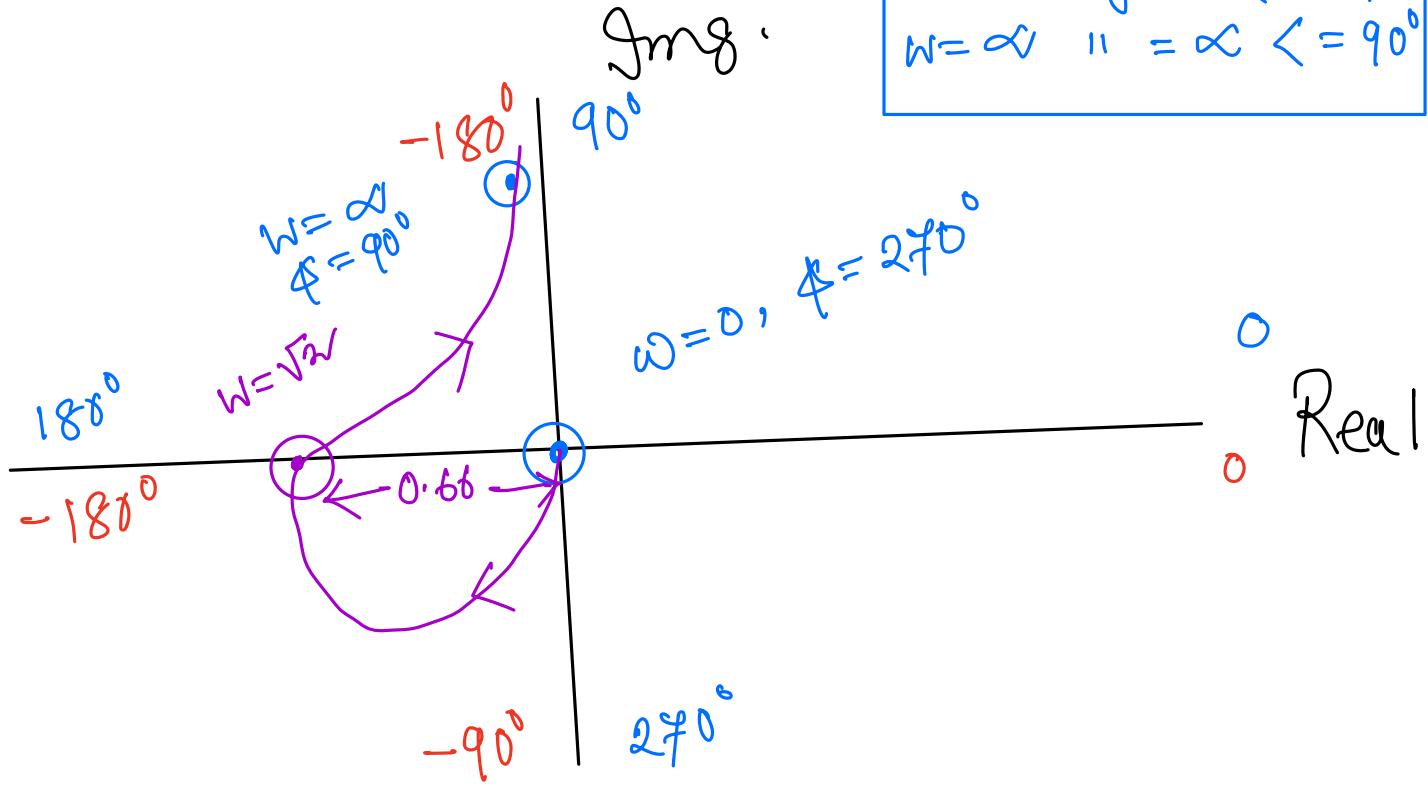
$$w=0, \quad w=\sqrt{2}, \quad$$

$$A), w = \sqrt{2}, |G(i\omega)| = 0.66 < 180^\circ$$

Step 6:

" " ing

$$\Rightarrow \omega = 0,$$



Pres

Section A

ID: 2257, 2234, 2115, 2179, 2127

1-3, 5, 9, 10-13, 15, 20, 17, 18, 21, 22, 27, 29,
31, 32, 34, 36, 68.

Section B

1815, 1995, 1880, 2292, 1135

44, 46, 47, 49, 53, 55, 56, 57, 59, 60, 62, 64,
71, 72, 73, 74, 78, 76, 77, , 82-84, 86-88,
92, '

Sec. C

2280, 1510, 1105, 1081.

93, 94, 97 ~ 99, 101~4, 108, 11, 14, 17, 18, 19,
21, 22, 23, 24, 28, 33, 36, 38