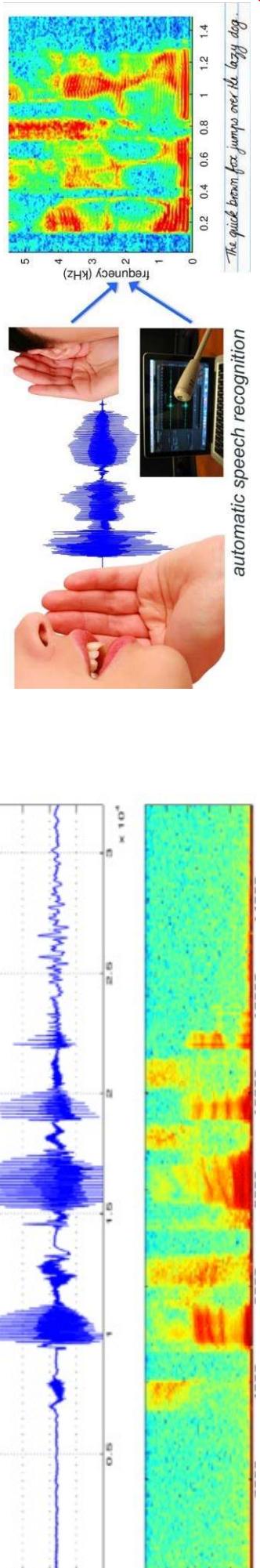


Laplace Transformation

Lecture-02

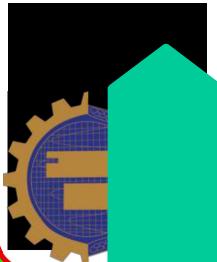
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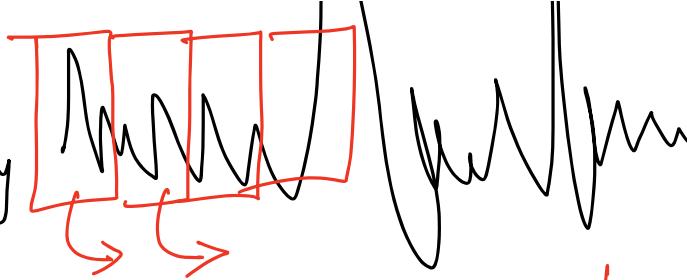
Contents

- Introduction
- Laplace Transformation
- Property
- Theorem
- Conclusion



Limitations:

1. FT is suitable only for stationary signal.
For Non-stationary Signal, STFT has been used.



Short-time Fourier transform
STFT

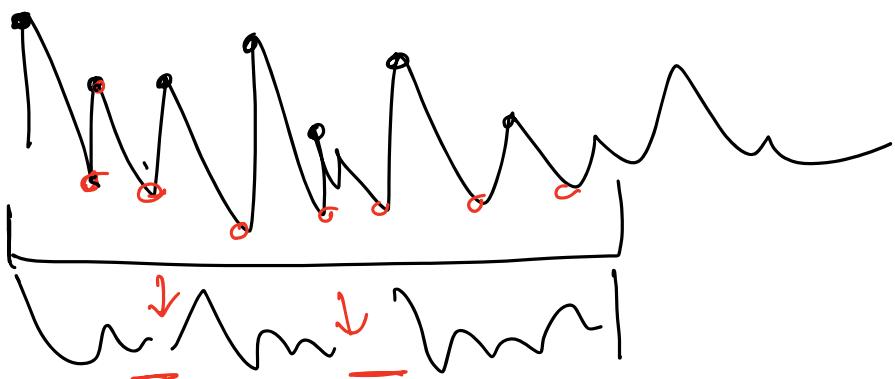
2. Loss of Time Information: FT provides freq domain representation but doesn't indicate when a particular freq occurs in time.

3. Computational complexity :-

use FFT.

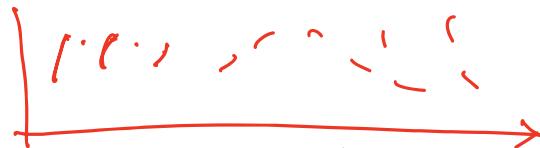
- **Not Suitable for Non-Stationary Signals:** Fourier Transform assumes the signal is infinite in duration and does not change over time. For non-stationary signals, Short-Time Fourier Transform (STFT) or Wavelet Transform is preferred.
- **Loss of Time Information:** FT provides frequency domain representation but does not indicate when a particular frequency occurs in time.
- **Computational Complexity:** The computation of Fourier Transform for large data sets can be time-consuming, though the Fast Fourier Transform (FFT) algorithm helps in reducing complexity.
- **Ideal Conditions Assumption:** In real-world scenarios, signals may not always be perfectly periodic or infinite in duration, affecting the accuracy of FT.

Condition of Fourier Transformation:



Any periodic signal $f(\theta)$ with period 2π that satisfies the Dirichlet condition, can be used to apply Fourier transformation.

Dirichlet conditions:



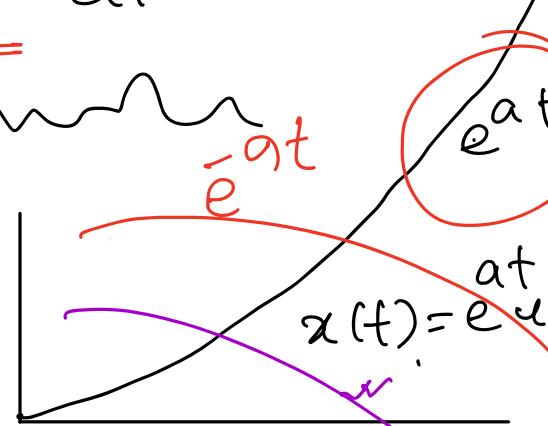
- 1) It has finite number of discontinuities in one period
- 2) It has finite number of maxima & minima in one period.
- 3) The integral $\int_{-\pi}^{\pi} |f(\theta)| d\theta$ is finite.

$$F(j\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$



$$x(t) = e^{at}$$

$$\dot{x}(t) = x(t) \cdot e^{-at}$$



$$\int_{-\infty}^{\infty} x(t) e^{-j\omega t} e^{-at} dt$$

$$\begin{aligned}
 e^{-at} x(j\omega) &= \int_0^{\infty} x(t) \cdot e^{-at} \cdot e^{-j\omega t} dt \\
 &= \int_0^{\infty} x(t) e^{-(\alpha+j\omega)t} dt \\
 &= \int_0^{\infty} \underline{x(t)} \underline{e^{-st}} dt \quad \underline{s = \alpha + j\omega} \\
 &= F(s) \\
 &= \text{Laplace transformed of } x(t)
 \end{aligned}$$

Laplace
tran

F(j\omega)

Advantages:

- 1) It simplifies function
- 2) " " operation.
- 3) It solves the problem of certain signals that can't be analyzed by FT.

$$F(s) = \mathcal{L}(f(t)) = \int_{-\infty}^{\infty} f(t) e^{-st} dt, s = \sigma + j\omega$$

Introduction

Laplace:

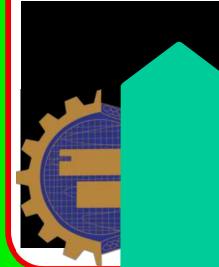
Pierre-Simon, marquis de Laplace (French; 23 March 1749 – 5

March 1827) was an influential French scholar whose work was

important to the development of mathematics, statistics, physics,
and astronomy.

Transformation:

It refers to conversion .



What is Laplace Transform?

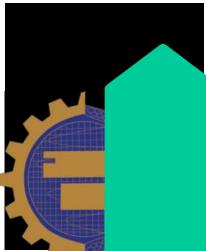
The Laplace Transform is a powerful integral transform used to convert functions of time (usually denoted as $f(t)$) into functions of a complex variable (usually denoted as s).

The Laplace transform of a function $f(t)$ is defined as:

$$L[f(t)] = F(s) = \int_0^{\infty} f(t)e^{-st} dt$$

Here:

- t is the time-domain variable.
- s is a complex number $s=\sigma+j\omega$.
- $F(s)$ is the Laplace transform of $f(t)$



Why Laplace Transform?

1. Simplifies Differential Equations:

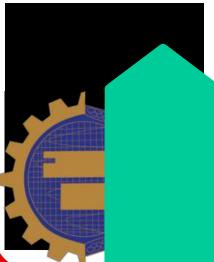
- It converts differential equations into algebraic equations, which are easier to solve.
- For example, a second-order differential equation in time becomes a simple polynomial in s .

2. System Analysis and Control Engineering:

- Widely used in electrical, control, and mechanical engineering for analyzing linear time-invariant (LTI) systems.
- Allows engineers to study the stability, frequency response, and behavior of systems in the **s-domain** (frequency domain).

3. Initial and Final Value Theorems:

- Provides tools to quickly find the initial and steady-state behavior of a system without solving the entire differential equation.



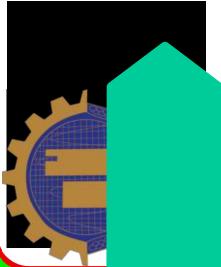
Why Laplace Transform?

4. Handling Discontinuous and Impulse Functions:

- Easily manages step functions, impulses (Dirac delta), and other non-continuous signals, which are common in real-world systems.

5. Convolution Simplification:

- Convolution in the time domain becomes multiplication in the Laplace domain, simplifying signal processing tasks.



The Laplace Transform

The Laplace Transform of a function, $f(t)$, is defined as;

$$L[f(t)] = F(s) = \int_0^{\infty} f(t)e^{-st} dt$$

The Inverse Laplace Transform is defined by

$$L^{-1}[F(s)] = f(t) = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} F(s)e^{ts} ds$$



An important point to remember:

$$f(t) \Leftrightarrow F(s)$$

The above is a statement that $f(t)$ and $F(s)$ are transform pairs. What this means is that for each $f(t)$ there is a unique $F(s)$ and for each $F(s)$ there is a unique $f(t)$.



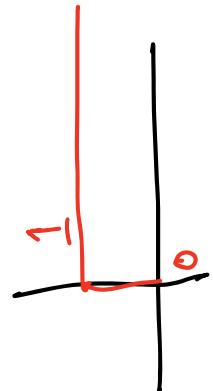
Laplace Transform of the unit step.

$$L[u(t)] = \int_0^{\infty} 1 e^{-st} dt = -\frac{1}{s} e^{-st} \Big|_0^{\infty}$$

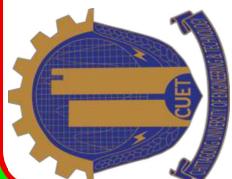
$$L[u(t)] = \frac{1}{s}$$

The Laplace Transform of a unit step is:

$$\frac{1}{s}$$

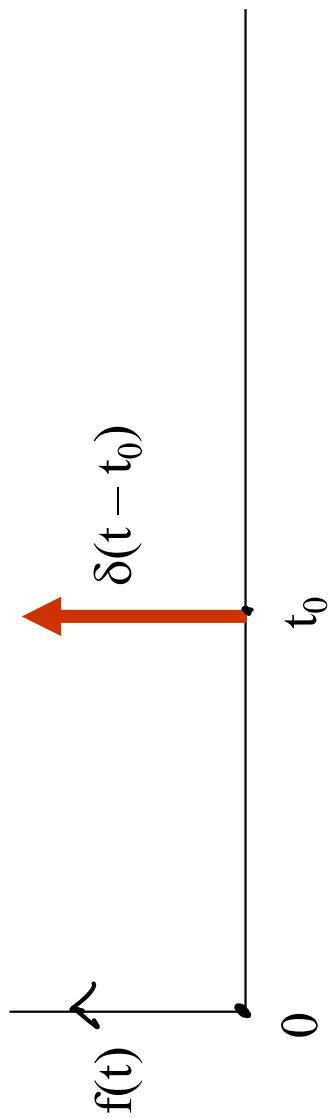


$$\begin{aligned}
 u(t) &\propto \int_{-\infty}^t u(\tau) e^{-s\tau} d\tau \\
 F(s) &= \int_{-\infty}^0 u(\tau) \frac{e^{-st}}{s} d\tau = \left[\frac{e^{-st}}{s} \right]_0^{\infty} = -\frac{1}{s} [0 - 1] \\
 &= -\frac{1}{s}
 \end{aligned}$$



The Laplace transform of a unit impulse:

Pictorially, the unit impulse appears as follows:



Mathematically:

$$\delta(t - t_0) = 0 \quad t \neq 0$$

$$\int_{t_0-\varepsilon}^{t_0+\varepsilon} \delta(t - t_0) dt = 1 \quad \varepsilon > 0$$

$$\int_{t_1}^{t_2} f(t) \delta(t - t_0) dt = \begin{cases} f(t_0) & t_1 < t_0 < t_2 \\ 0 & t_0 < t_1, t_0 > t_2 \end{cases}$$



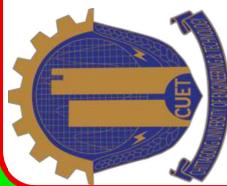
The Laplace transform of a unit impulse:

In particular, if we let $f(t) = \delta(t)$ and take the Laplace

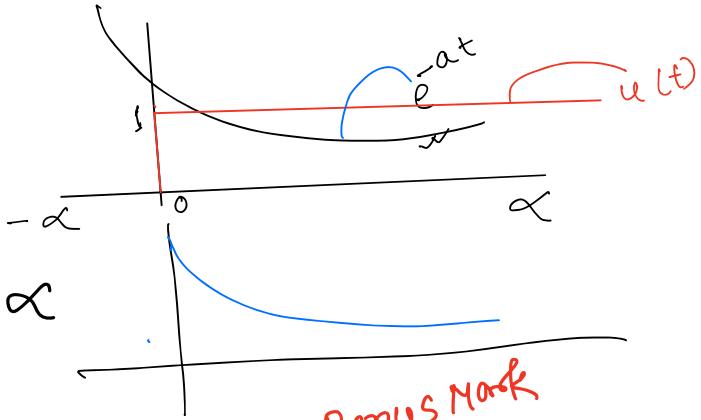
$$L[\delta(t)] = \int_0^{\infty} \delta(t) e^{-st} dt = e^{-0s} = 1$$

$$\int_0^{\infty} \delta(t) e^{-st} dt = \left[\frac{e^{-st}}{-s} \right]_0^{\infty} = \frac{0 - 1}{-s} = \frac{1}{s}$$

$$\delta(t) = \begin{cases} 1 & t=0 \\ 0 & t \neq 0 \end{cases}$$



$$\begin{aligned}
 L[e^{-at} u(t)] &= \int_{-\alpha}^{\alpha} e^{-at} u(t) e^{-st} dt \\
 &= \int_0^{\alpha} e^{-at} e^{-st} dt \\
 &= \int_0^{\alpha} e^{-(s+a)t} dt \\
 &= -\frac{1}{s+a} \left[e^{-(s+a)t} \right]_0^{\alpha} \\
 &= -\frac{1}{s+a} \left[e^{-\alpha(s+a)} - e^0 \right] \\
 &= -\frac{1}{s+a} (-1) = \frac{1}{s+a}
 \end{aligned}$$



Bonus Mark
1044 - 87 +1.

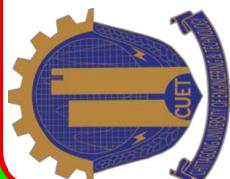
Building transform pairs:

$$L[e^{-at} u(t)] = \int_0^{\infty} e^{-at} e^{-st} dt = \int_0^{\infty} e^{-(s+a)t} dt$$

$$L[e^{-at} u(t)] = \frac{-e^{-st}}{(s+a)} \Big|_0^\infty = \frac{1}{s+a}$$

$$e^{-at} u(t) \quad \Leftrightarrow \quad \frac{1}{s+a}$$

$$\begin{aligned} & L\left(\frac{e^{-at} u(t)}{s+a}\right) = \int_0^{\infty} e^{-at} e^{-st} dt \\ & = \int_0^{\infty} e^{-at} e^{-(s+a)t} dt \\ & = \int_0^{\infty} e^{-(s+a)t} dt \end{aligned}$$



$$\boxed{\text{Def}} \quad L[f(t-a)u(t-a)] = \int_{-\infty}^{\infty} f(t-a) \cdot u(t-a) e^{-st} dt$$

$$= \int_{t=a}^{t=\infty} f(t-a) e^{-st} dt$$

$t = x+a$

$$\text{Let, } \frac{t-a}{dt} = \frac{x}{dx} \Rightarrow t = x+a$$

$$= \int_{x=0}^{x=\infty} f(x) e^{-s(x+a)} dx$$

$$\begin{aligned} t &= a, & x &= t-a = a-a = 0 \\ t &= \infty, & x &= \infty \end{aligned}$$

$$x=0 \quad \infty$$

$$= \int f(x) \cdot e^{-xs} \cdot e^{-sa} dx$$

$$= \underbrace{\int_{x=0}^{\infty} f(x) e^{-xs} dx}_{\mathcal{L}(f(x))} = F(s)$$

$$= e^{-as} \cdot F(s)$$

$$L[e^{-2t} u(t)] = \frac{1}{s+2}$$

$$L[e^{-2(t-3)} u(t-3)] = \frac{e^{-3s}}{s+2}$$

Time Shift

$$L[f(t-a)u(t-a)] = \int_a^{\infty} f(t-a)e^{-st} dt$$

Let $x = t - a$, then $dx = dt$ and $t = x + a$

As $t \rightarrow a$, $x \rightarrow 0$ and as $t \rightarrow \infty$, $x \rightarrow \infty$. So,

$$\int_0^{\infty} f(x)e^{-s(x+a)} dx = e^{-as} \int_0^{\infty} f(x)e^{-sx} dx$$

$$L[f(t-a)u(t-a)] = e^{-as} F(s)$$

$$\begin{aligned} \text{Ex op. } L[e^{-2t} u(t)] &= \frac{1}{s+2} \\ &\quad \cancel{-\frac{2}{s^2}} \\ &= \frac{e^{-2t}}{s+2} = \frac{e^{-2s}}{s+2} F(s) \end{aligned}$$

$$\begin{aligned} L[f(t-a)u(t-a)] &= \int_a^{\infty} f(t-a)u(t-a)e^{-st} dt \\ &= \int_{a-s}^{\infty} f(t-a)u(t-a)e^{-st} dt \\ &= \int_{a-s}^{\infty} f(t-a)u(t-a)e^{-s(t-a)} e^{sa} dt \\ &= \int_{a-s}^{\infty} f(t-a)u(t-a)e^{sa} dt \\ &\quad \cancel{e^{-s(t-a)}} \\ &= \int_{a-s}^{\infty} f(t-a)u(t-a)dt \\ &= \int_{a-s}^{\infty} f(x)u(x)dx \\ &= e^{-as} \int_0^{\infty} f(x)u(x)dx \\ &= e^{-as} F(s) \end{aligned}$$



Thank you!
Question?

