

Reference Book

Signals and Systems (2nd edition)

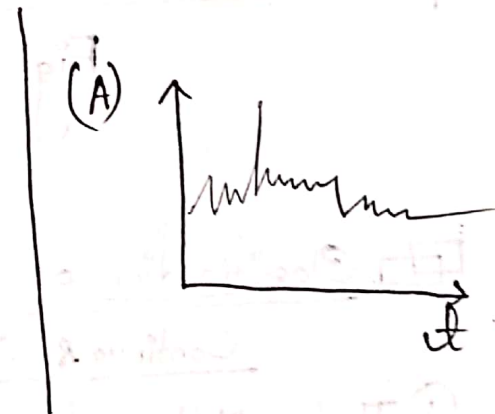
Simon Haykin

Signal:

It is defined as a function of one or more variables that conveys information on the basis of a physical phenomenon.

- Speech
- Image
- heartbeat, blood pressure, pulse.

Signal $\begin{cases} \rightarrow \text{single dimensional signal} \\ \rightarrow \text{multi dimensional signal} \end{cases}$



System:

It is an entity that manipulates one or more signals to accomplish a function and, thereby yield a new signal

- Automatic Speaker recognition.
- Communication System.
- Aircraft Landing System.

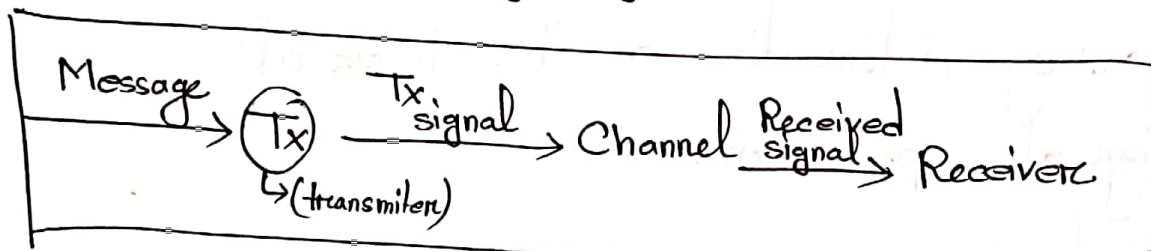
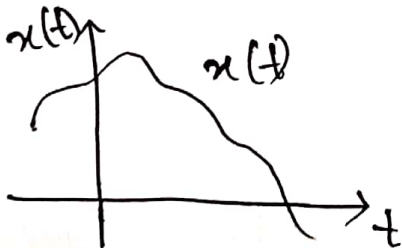


Fig: Basic Communication System

Classification of Signal:

Continuous Signal

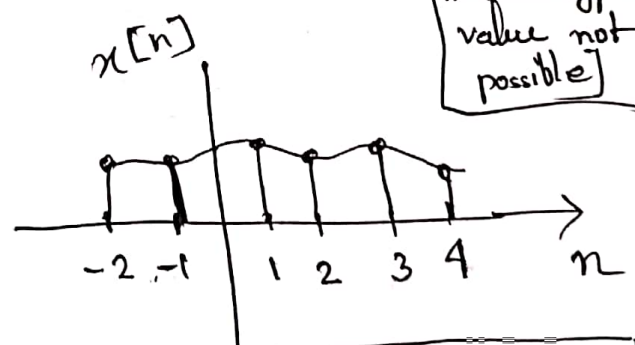
- ① Its amplitude/value varies continuously with time.



[Continuous signal (সকাল) value নিয়ে discrete signal (তড়ি) করা যায়]

Discrete signal

- ① Changes in discrete instant of time.

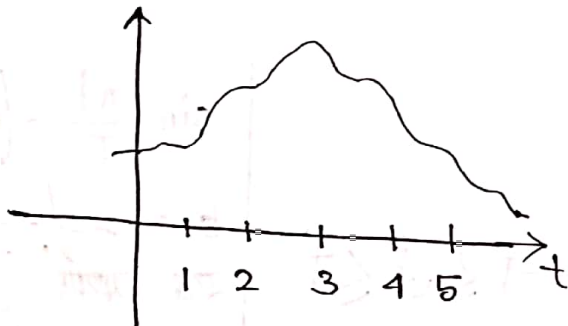


[fraction type value not possible]

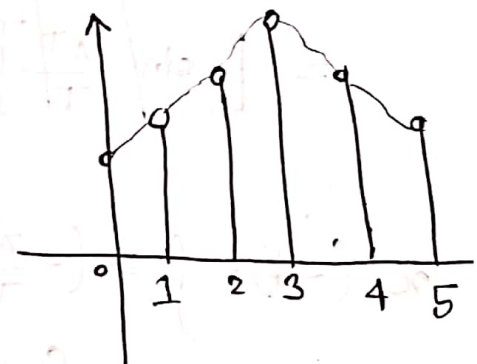
$$x[n] = x(nT_s)$$

→ $T_s = 2s$ (sampling period of time) / time interval

* T_s is the sampling of time period. যা দ্বারা time interval নির্ধারিত হয়, অর্থাৎ continuous system হোক discrete system তৈরি করার জন্য যেকোনো কত সময় পর পর value নিব তাই নির্ধারিত হয়।



$$T_s = 1s$$

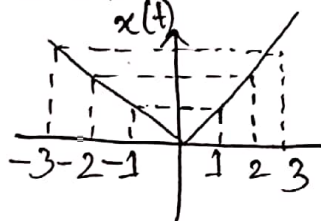


$$x[n] = x(nT_s)$$

$$n = 0, 1, 2, 3, 4$$

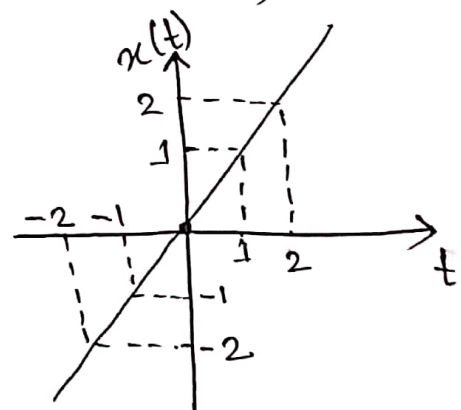
☐ Even Signal: (Symmetric signal)

$$x(t) = x(-t)$$



Odd signal (inverse signal)

$$x(-t) = -x(t)$$



FilwelTM

Gold

&

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Silver

Ex: 1.1

$$x(t) = \begin{cases} \sin\left(\frac{\pi t}{T}\right), & -T \leq t \leq T \\ 0, & \text{otherwise} \end{cases}$$

$$= \int_{-T}^T \sin\left(\frac{\pi t}{T}\right) dt$$
$$= \left[-\cos\left(\frac{\pi t}{T}\right) \right]_{-T}^T$$

is it even or odd?

$$x(-t) = \begin{cases} \sin\left(-\frac{\pi t}{T}\right), & -T \leq t \leq T \\ 0, & \text{otherwise} \end{cases}$$

$$= \begin{cases} -\sin\left(\frac{\pi t}{T}\right), & -T \leq t \leq T \\ 0, & \text{otherwise} \end{cases}$$

$$\sin\left(\frac{\pi t}{T}\right) = -\left(\sin\left(-\frac{\pi t}{T}\right)\right)$$

because $(-)- = +$
হয় অর্থাৎ
একটি একটি
inverse হবে।

it is odd.

Decomposing Signal in even and odd signals

$$x(t) = \underbrace{x_e(t)}_{\text{even}} + \underbrace{x_o(t)}_{\text{odd}}$$

$$x(-t) = x_e(-t) + x_o(-t)$$

$$= \underbrace{x_e(t)}_{\text{even}} - \underbrace{x_o(t)}_{\text{odd}}$$

Thereby,

$$x_e(t) = \frac{1}{2} [x(t) + x(-t)]$$

$$x_o(t) = \frac{1}{2} [x(t) - x(-t)]$$

even value,

$$\begin{aligned} \rightarrow 2x_e(t) &= [x(t) + x(-t)] \\ x_e(t) &= \frac{1}{2} [x(t) + x(-t)] \\ \rightarrow x_o(t) - (-x_o(t)) &= [x(t) - x(-t)] \\ \rightarrow x_o(t) &= \frac{1}{2} [x(t) - x(-t)] \end{aligned}$$

Ex: 1.2

$x(t) = e^{-2t} \cos t \rightarrow$ Find the even and odd components of this signal.

$$x(t) = e^{-2t} \cos t$$

$$\begin{aligned} x(-t) &= e^{-2(-t)} \cos(-t) \\ &= e^{2t} \cos t \end{aligned}$$

$$x_e(t) = \frac{1}{2} \{x(t) + x(-t)\}$$

$$= \frac{1}{2} \left(\frac{e^{-2t} + e^{2t}}{2} \right) \cos t$$

$$x_o(t) = \frac{1}{2} \left(\frac{e^{-2t} - e^{2t}}{2} \right) \cos t$$

07.09.2019

Saturday

Problem 1.1

$$x(t) = (1+t^3) \cos^3(10t)$$

Find the even and odd component of this signal.

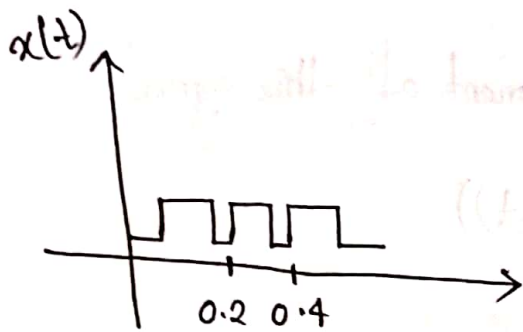
$$\Rightarrow x(-t) = (1+(-t)^3) \cos^3(10(-t))$$
$$= (1-t^3) \cos^3(10t)$$

$$\therefore x_e(t) = \frac{1}{2} \left[(1+t^3) \cos^3(10t) + (1-t^3) \cos^3(10t) \right]$$
$$= \frac{1}{2} \left[\cos^3(10t) (1+t^3 + 1-t^3) \right]$$
$$= \cos^3(10t)$$

$$\therefore x_o(t) = \frac{1}{2} \cos^3(10t) [1+t^3 - 1+t^3]$$
$$= t^3 \cos^3(10t)$$

Periodic Signals:

$$x(t) = x(t+T) \dots \dots (i)$$



(T) period पद पद repeat शक्य,

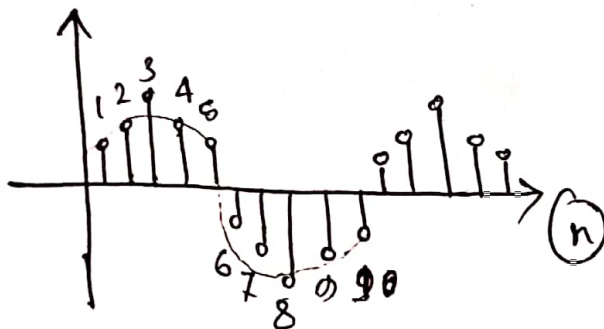
$$f = \frac{1}{T}$$

$$= \frac{1}{0.2}$$

$$= 20 \text{ Hz}$$

Periodic discrete signal condition:

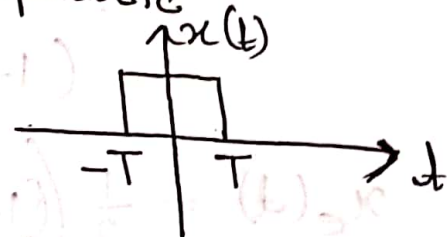
$$x[n] = x[n+N]$$



period (N) = 10

Non periodic signal

Any signal that does not satisfy (i) is non-periodic or aperiodic

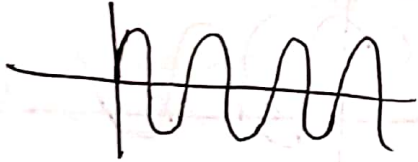


निर्दिष्ट अवधि पद
आवृत्ति value
दिह्य ना,

Plot (t, x(t))
stem (n, x(n))

Deterministic

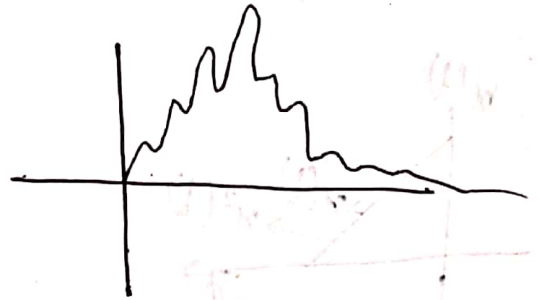
No uncertainty with respect to its value at any time.



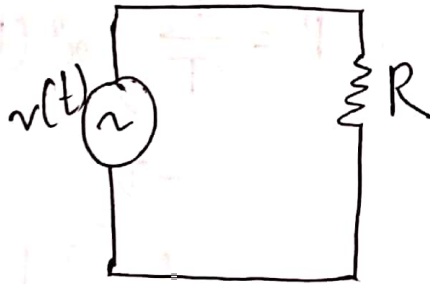
$\sin \omega t$
 $\cos \omega t$ } determined signal

Random

There is uncertainty before it occurs.



Energy Signal Vs. Power Signal:



$$P(t) = \frac{v^2(t)}{R}$$
$$= i^2(t) \cdot R$$

$$P(t) \propto x^2(t)$$

$$e(t) \propto \int p(t) dt$$

$$E = \int_{-\infty}^{\infty} x^2(t) dt$$

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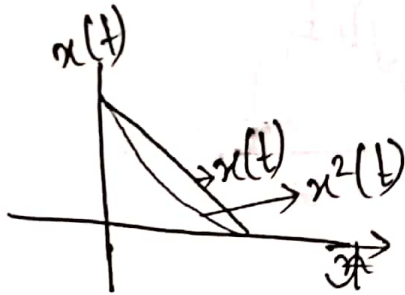
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* Condition:

Energy Signal $E(t)$

$$0 < E < \infty$$

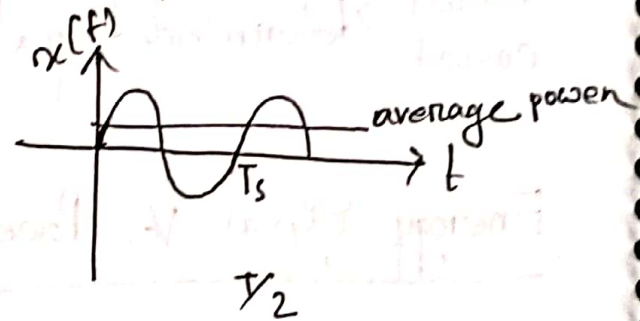
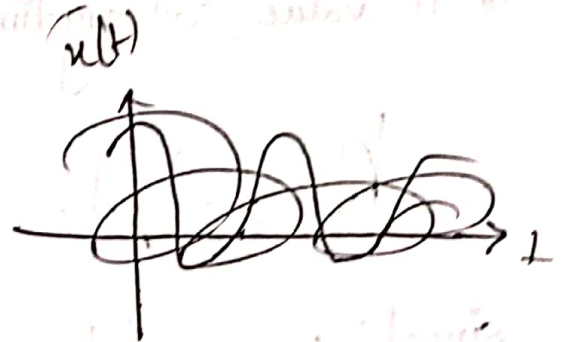


* non periodic and finite signal

$$E = \int_{-\infty}^{\infty} x^2(t) dt$$

Power Signal $P(t)$

$$0 < P < \infty$$



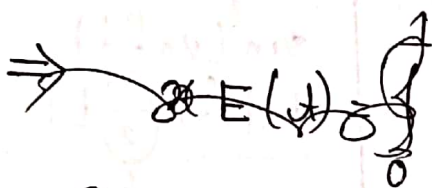
$$P = \frac{1}{T} \int_{-T/2}^{T/2} x^2(t) dt$$

* periodical signal \Rightarrow power signal

Problem 1.9%

(a) $x(t) = \begin{cases} t & ; 0 \leq t \leq 1 \\ (2-t) & ; 1 \leq t \leq 2 \\ 0, & \text{otherwise,} \end{cases}$

is it energy or power signal? Find Energy/power of this signal.



Sol^{no} As it is a non-periodical signal.

So, this signal is energy signal.

$$E = \int_{-\infty}^{\infty} x^2(t) dt$$

$$= \int_0^1 t^2 dt + \int_1^2 (2-t)^2 dt$$

$$= \left[\frac{t^3}{3} \right]_0^1 + \left[\frac{(2-t)^3}{3} \right]_1^2$$

$$= \frac{1}{3} + \frac{1}{3} = \frac{2}{3}$$

$$E = \int_1^2 (2-t)^2 dt$$

Problem 1.9

(c) $x(t) = 5 \cos(\pi t) + \sin(5\pi t)$, $-1 < t < 1$

$$P = \frac{1}{T} \int_{-T/2}^{T/2} x^2(t) dt$$

~~$$= \frac{1}{2} \int_{-1}^{+1} \cos^2(\pi t) dt$$~~

~~$$= \frac{5}{2} \int_{-1}^{+1} \cos^2(\pi t) dt + \frac{1}{2} \int_{-1/5}^{1/5} \sin^2(5\pi t) dt$$~~

~~$$= \frac{5}{2}$$~~

~~$$= \frac{5}{2} \int_{-1}^{+1} \cos^2(\pi t) dt + \frac{5}{2} \int_{-1/5}^{1/5} \sin^2(5\pi t) dt$$~~

~~$$= \frac{5}{4} \int_{-1}^{+1} 2\cos^2(\pi t) dt + \frac{5}{4} \int_{-1/5}^{1/5} 2\sin^2(5\pi t) dt$$~~

~~$$= \frac{5}{4} \left[1 + \cos(\pi t) \right]_{-1}^{+1} + \frac{5}{4} \left[1 - \cos(5\pi t) \right]_{-1/5}^{1/5}$$~~

~~$$= \frac{5}{4} [1 + \cos(\pi) - 1 - \cos(\pi)] + \frac{5}{4} [1 - \cos(5\pi \cdot \frac{1}{5}) - 1 + \cos(5\pi \cdot \frac{1}{5})]$$~~

Sinusoidal signal

$\sin(\omega t)$

$\sin(2\pi f t)$

$\sin t (2\pi \frac{1}{2} t)$

f

$T = 2$

$2\cos^2\theta = 1 + \cos(2\theta)$

$2\sin^2\theta = 1 - \cos(2\theta)$

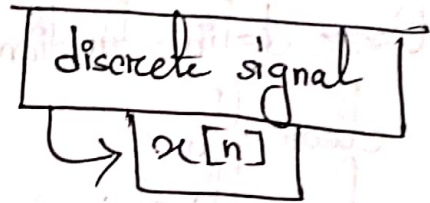
$$\begin{aligned}
 &= \frac{5}{4} [\cancel{\cos(\pi)} - \cos(\pi)] + \frac{5}{4} [\cancel{1 - \cos(\pi)} - \cancel{1 - \cos(\pi)}] \\
 &= \frac{5}{4} \times 0 + \frac{5}{4} (-2 \cos \pi) \\
 &= 0 + \left(-\frac{5}{2} \cos \pi\right) \\
 &= -\frac{5}{2} \cos(\pi)
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{2} \int_{-1}^{+1} (5 \cos \pi t)^2 dt + \frac{1}{2/5} \int_{-1/5}^{1/5} (\sin 5\pi t)^2 dt \\
 &= \frac{1}{2} \times 25 \int_{-1}^{+1} \frac{1}{2} (1 + \cos 2\pi t) dt + \frac{5}{2} \int_{-1/5}^{1/5} \frac{1}{2} (1 - \cos 10\pi t) dt \\
 &= \frac{25}{4} \left[t - \frac{\sin 2\pi t}{2\pi} \right]_{-1}^{+1} + \frac{5}{4} \left[t + \frac{\sin \frac{10\pi t}{10\pi}}{10\pi} \right]_{-1/5}^{1/5} \\
 &= \frac{25}{4} [\cancel{1 - \frac{\sin(+1)}{2\pi}} - 1 + \sin(-1)] + \frac{5}{4} \left(\frac{1}{5} + \sin\left(\frac{1}{5}\right) - \frac{1}{5} - \sin\left(-\frac{1}{5}\right) \right) \\
 &= \frac{25}{4} [1 + 1] + \frac{5}{4} \left(\frac{1}{5} + \frac{1}{5} \right) \\
 &= \frac{25}{2} + \frac{5}{2} \left(\frac{2}{5} \right) = \frac{25+1}{2} = \frac{26}{2} = 13
 \end{aligned}$$

Class no. 3

14.09.2019

Saturday



$$\textcircled{P} \quad x[n] = \begin{cases} \sin(\pi n) & ; -4 \leq n \leq 4 \\ 0 & ; \text{otherwise.} \end{cases}$$

~~$\sin \pi n$~~

$$x_p = \frac{1}{N} \sum_{n=0}^{N-1} x^2[n]$$

Solution:

$$x[n] = \begin{cases} \sin(\pi n) & ; -4 \leq n < 4 \end{cases}$$



प्रति point आनका
रुब घोग बा,

$$\text{Energy} = \sum_{-\infty}^{\infty} x^2[n]$$

$$= \sum_{n=-4}^4 x^2(\pi n)$$

$$= \sum_{n=-4}^4 \sin^2(\pi n)$$

$$= \sum_{n=-4}^4 \sin^2(\pi n)$$

$$= 0$$

$$\text{Energy} = \int_{-\infty}^{\infty} x^2(t) dt$$

∴ Zero signal का power 0 और energy 0 रहे,

* Sinusoidal Signal: → continuous time signal

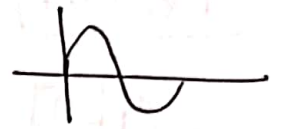
$$x(t) = A \cos(\omega t + \phi)$$

$$x[n] = A \cos(\omega n + \phi) \rightarrow \text{discrete signal \& angular formula}$$

$$= A \cos(\omega n + \omega N + \phi) \leftarrow \begin{array}{l} x[n+N] \\ n = [n+N] \end{array}$$

$$\omega N = 2\pi m$$

$$\sin(\omega t)$$



$$\sin(\omega t + 90^\circ)$$



$$\sin(\omega t - 90^\circ)$$



m is integer value

যদি $\omega N = 2\pi m$

যদি value 2π is multiple হয়,

$$m=0, \omega N = 0$$

$$m=1, \omega N = 2\pi$$

periodic signal হয়, নই, non-periodic

$$\square x[n] = 5 \sin[2n];$$

Here, $\omega = 2$

$$= 5 \sin$$

non-periodic signal

$$\omega N = 2\pi m$$

$$N = \frac{2\pi}{\omega} \times m$$

$$= \frac{2\pi}{2} \times m$$

$$= \pi \times m$$

* দ্রষ্টব্য point থাকলে non periodic.

$$x[n] = 5 \sin(5\pi n)$$

$$N = \frac{2\pi}{5\pi} \times m$$

$$= \frac{2}{5} \times m \text{ [if } m=5]$$

$$= \frac{2}{5} \times 5$$

$$= 2 \text{ [fundamental period]}$$

অথবা (যদি মোট value.)

* unit বা থাকলে sample দিচ্ছে নিশ্চয় হয়.

After 2 sample the signal repeat.

Ex: 1.7

$$x_1[n] = \sin[5\pi n]$$

$$x_2[n] = \sqrt{3} \cos[5\pi n]$$

(a) Find the common fundamental period?

Solution:

$$x_1[n] = \sin[5\pi n]$$

Here,

$$\boxed{N=2}$$

$$\begin{aligned} N &= \frac{2\pi}{\omega} = \frac{2\pi}{5\pi} \\ &= \frac{2}{5} \times \frac{1}{1} \\ &= \frac{2}{5} \end{aligned}$$

(a) The common fundamental period 2.

(b) ~~$y[n] = x_1[n] + x_2[n]$~~

$$= \sin[5\pi n] + \sqrt{3} \cos[5\pi n]$$

$$= \frac{1}{2} (\sin[5\pi n] + \sqrt{3} \cos[5\pi n])$$

$$= \frac{1}{2} \sin[5\pi n] + \frac{\sqrt{3}}{2} \cos[5\pi n]$$

$$=$$

$$A \cos(\omega t + \phi_1) + B \sin(\omega t + \phi_2)$$

$$= \sqrt{(A \cos \phi_1 + B \sin \phi_2)^2 + (A \sin \phi_1 + B \cos \phi_2)^2} \times \cos\left(\omega t + \tan^{-1} \frac{A \sin \phi_1 + B \cos \phi_2}{A \cos \phi_1 + B \sin \phi_2}\right)$$

$$= \sqrt{(A \cos \phi_1 + B \sin \phi_2)^2 + (A \sin \phi_1 + B \cos \phi_2)^2} \times \boxed{\cos\left(\omega t + \tan^{-1} \frac{A \sin \phi_1 + B \cos \phi_2}{A \cos \phi_1 + B \sin \phi_2}\right)}$$

amplitude

$$\therefore y[n] = x_1[n] + x_2[n]$$

⊕ Operation performed on dependent variable:

Signal $\rightarrow x(t)$

Addition $\rightarrow y(t) = x_1(t) + x_2(t)$

Multiplication $\rightarrow y(t) = x_1(t) \times x_2(t)$

Differentiation $\rightarrow y(t) = \frac{d}{dt} x(t)$

Integration $\rightarrow y(t) = \int_{-\infty}^t x(t) dt$

⊕ Operation performed on independent variable:

Time Scaling:

Signal $\rightarrow x(t)$

$y(t) = x(at) \rightarrow$ If $0 < a < 1 \rightarrow$ signal will be stretched
 $a > 1 \rightarrow$ signal will be compressed.

* $y(t) = x(2t)$

$\downarrow = \frac{1}{2}$

$2t = 2 \times \left(\frac{t}{2} \right)$

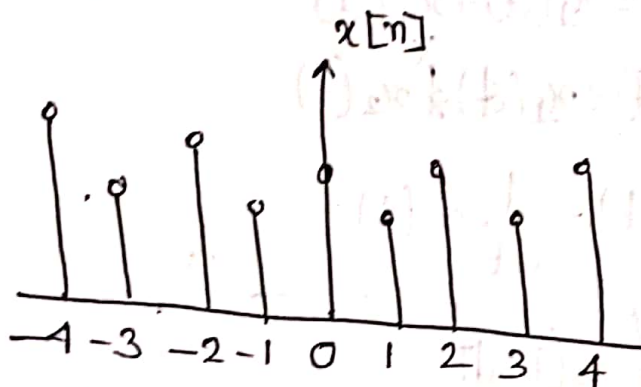
* time বাড়ে কিন্তু file size
compressed হয়ে যায়,

$$y(t) = x\left(\frac{1}{2}t\right) \rightarrow x\left(\frac{1}{2}\right) \text{ এর value 1 দিতে হবে}$$

Class no. 5

Tuesday

17.09.2019



$$y[n] = x[2n]$$

→ ১ থেকে বড় হলে ~~expand~~ হয়ে যাবে।

signal compress হয়ে যেতে পারে

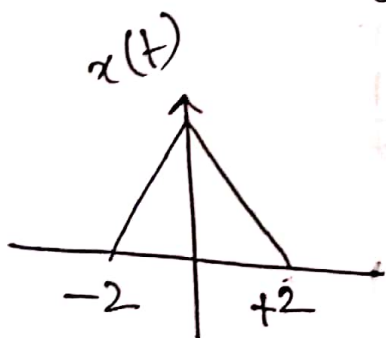
তাই time scale কে $\frac{1}{2}$ value দিয়ে
প্রকাশ করতে হবে।

$$x(2t) \rightarrow$$

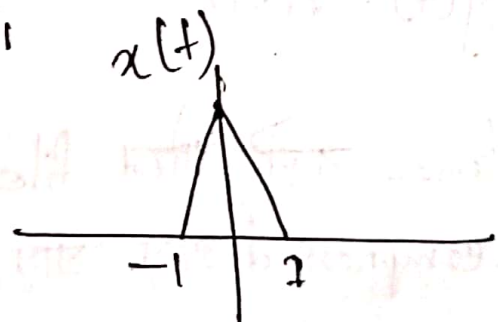
maximum

value 2. অর্থাৎ $\frac{1}{2}$ এর value 1 হবে।

→ যদি $\frac{1}{2}$ থেকে ছোট হয় তখন signal
expand হয়ে তখন time scale কে $\frac{1}{2}$ value
দিয়ে গুন করতে হবে।

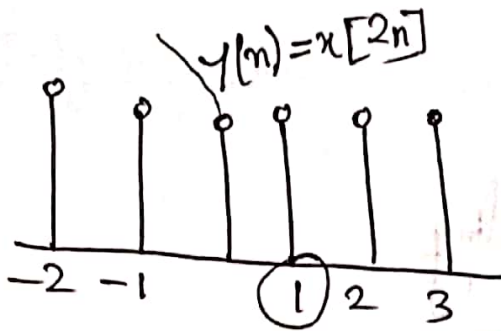


compressed



$$x[n] = x\left[\frac{1}{2}n\right]$$

$$n = \frac{1}{2}n \times 2$$



$$y[0] = x[0]$$

$$y[1] = x[2] \quad [n=1 \text{ even}]$$

$$y[2] = x[4]$$

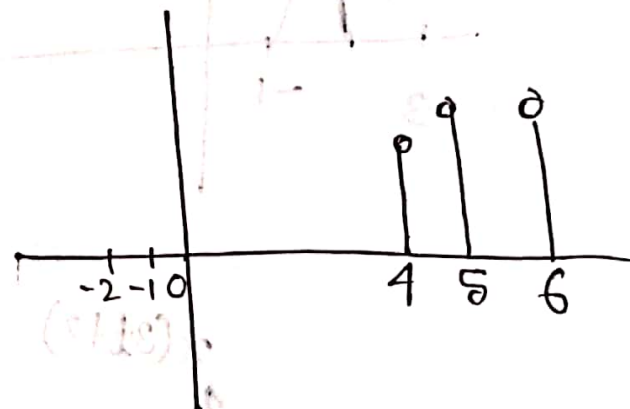
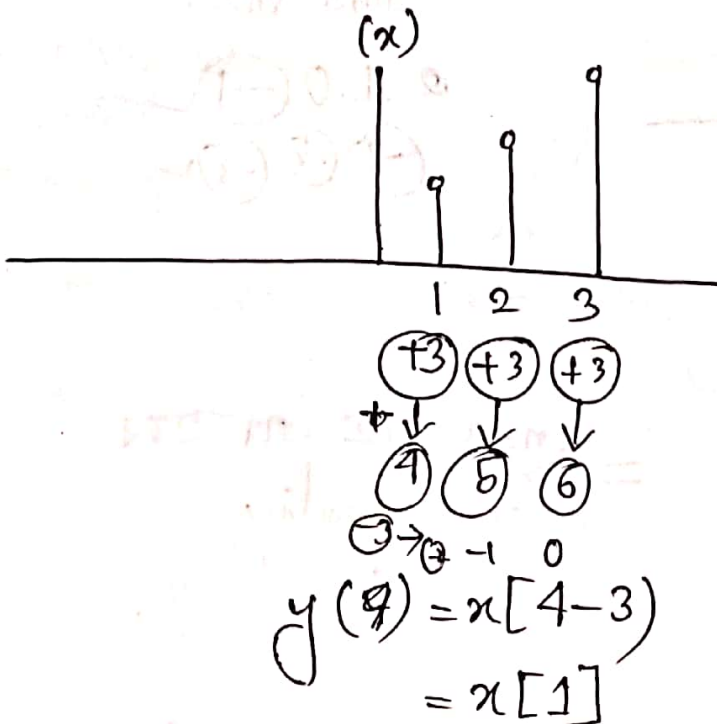
$$y[3] = x[6]$$

Time Shifting:

$$y[n] = x[n-3]$$

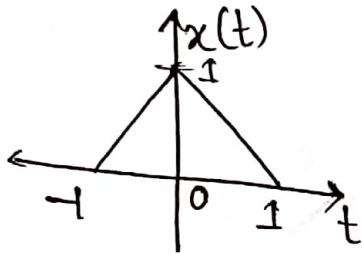
$$y[-n] = x[n+3]$$

(-) operator रहल,
time shifting रहल बा दाहिना दिशा
(+) operator रहल,
time shifting रहल बा बायाँ दिशा



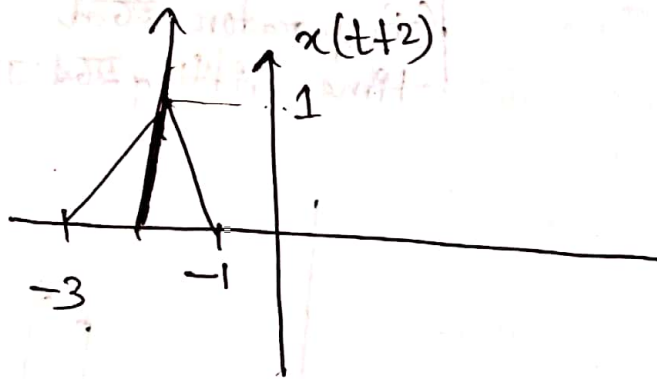
$$\boxed{\square} \quad y[n] = x[2n-3]$$

* আগে ২৬৭ time shifting তারপর হবে scaling

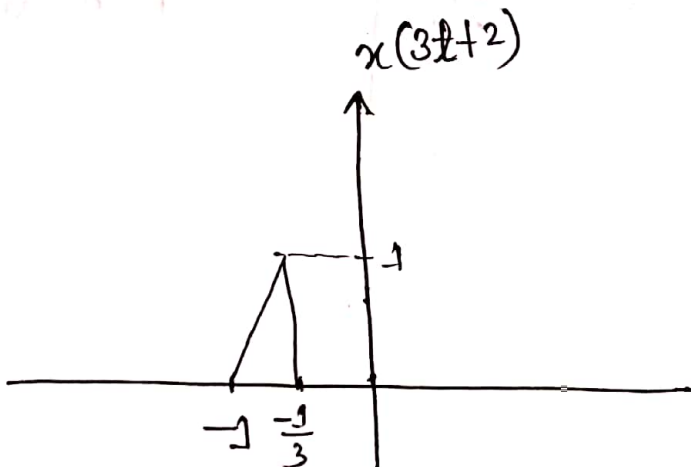


$y(t) \rightarrow$ যাকা মানে continuous
 $y[n] \rightarrow$ is a discrete

Find, $y(t) = x(3t+2)$
 $= x(t+2)$



\Rightarrow ২ ব্যব বাক্সে
 যাতে জে
 ১, ০, (-১)
 (-১) (-২) (-৩)



$\Rightarrow n=3$, জে এম ২৬৭
 time scaling
 $\frac{1}{3}, -\frac{2}{3}$
 $= -1$