

$$\boxed{\text{solution}} : z^{1/n} = r^{1/n} \left[\cos \left(\frac{\theta + 2k\pi}{n} \right) + i \sin \left(\frac{\theta + 2k\pi}{n} \right) \right]$$

where, $r = |z|$

$$= \sqrt{x^2 + y^2}, \text{ for } z = x + iy;$$

$$n = 4 \rightarrow k = 0, 1, \dots, n-1; \Rightarrow k = 0, 1, 2, 3$$

$$\theta = \text{any angle of } \arg z = \text{Arg } z = \arctan \left(\frac{y}{x} \right)$$

$$\text{Here, } z = 1 - i \rightarrow r = \sqrt{(1)^2 + (-1)^2}$$

$$= \sqrt{2}$$

$$= |z|$$

$$\theta = \arctan \left(\frac{-1}{1} \right)$$

$$= \arctan (-1)$$

$$= -\frac{\pi}{4}$$



Thus, the required roots are:

$$(i) \ k = 0 \rightarrow (1 - i)^{1/4}$$

$$= (\sqrt{2})^{1/4} \left[\cos \left(\frac{-\frac{\pi}{4} + 0}{4} \right) + i \sin \left(\frac{-\frac{\pi}{4} + 0}{4} \right) \right]$$

$$= (2^{1/2})^{1/4} \left[\cos \left(-\frac{\pi}{16} \right) + i \sin \left(-\frac{\pi}{16} \right) \right]$$

$$= 2^{1/8} \left[\cos \left(\frac{\pi}{16} \right) - i \sin \left(\frac{\pi}{16} \right) \right] \sim 1.07 - 0.213 i \quad \square$$

$$(ii) \quad k=1 \rightarrow (1-i)^{1/4} = 2^{1/8} \left[\cos \left(\frac{-\frac{\pi}{4} + 2\pi}{4} \right) + i \sin \left(\frac{-\frac{\pi}{4} + 2\pi}{4} \right) \right]$$

$$= 2^{1/8} \left[\cos \left(\frac{\frac{-\pi + 8\pi}{4}}{4} \right) + i \sin \left(\frac{\frac{-\pi + 8\pi}{4}}{4} \right) \right]$$

$$= 2^{1/8} \left[\cos \left(-\frac{\pi}{16} + \frac{\pi}{2} \right) + i \sin \left(-\frac{\pi}{16} + \frac{\pi}{2} \right) \right]$$

$$= 2^{1/8} \left[\cos \left(\frac{7\pi}{16} \right) + i \sin \left(\frac{7\pi}{16} \right) \right] \sim 0.213 + 1.07 i$$

$$(iii) \quad k=2 \rightarrow (1-i)^{1/4} = 2^{1/8} \left[\cos \left(\frac{-\frac{\pi}{4} + 4\pi}{4} \right) + i \sin \left(\frac{-\frac{\pi}{4} + 4\pi}{4} \right) \right]$$

$$= 2^{\frac{1}{8}} \left[\cos \left(\frac{-\pi + 16\pi}{4} \right) + i \sin \left(\frac{-\pi + 16\pi}{4} \right) \right]$$

$$= 2^{\frac{1}{8}} \left[\cos \left(\frac{-\pi + 16\pi}{16} \right) + i \sin \left(\frac{-\pi + 16\pi}{16} \right) \right]$$

$$= 2^{\frac{1}{8}} \left[\cos \left(\frac{15\pi}{16} \right) + i \sin \left(\frac{15\pi}{16} \right) \right] \sim 0.213 - 1.07i$$

□

$$(iv) \quad k=3 \rightarrow (1-i)^{\frac{1}{4}} = 2^{\frac{1}{8}} \left[\cos \left(\frac{-\frac{\pi}{4} + 6\pi}{4} \right) + i \sin \left(\frac{-\frac{\pi}{4} + 6\pi}{4} \right) \right]$$

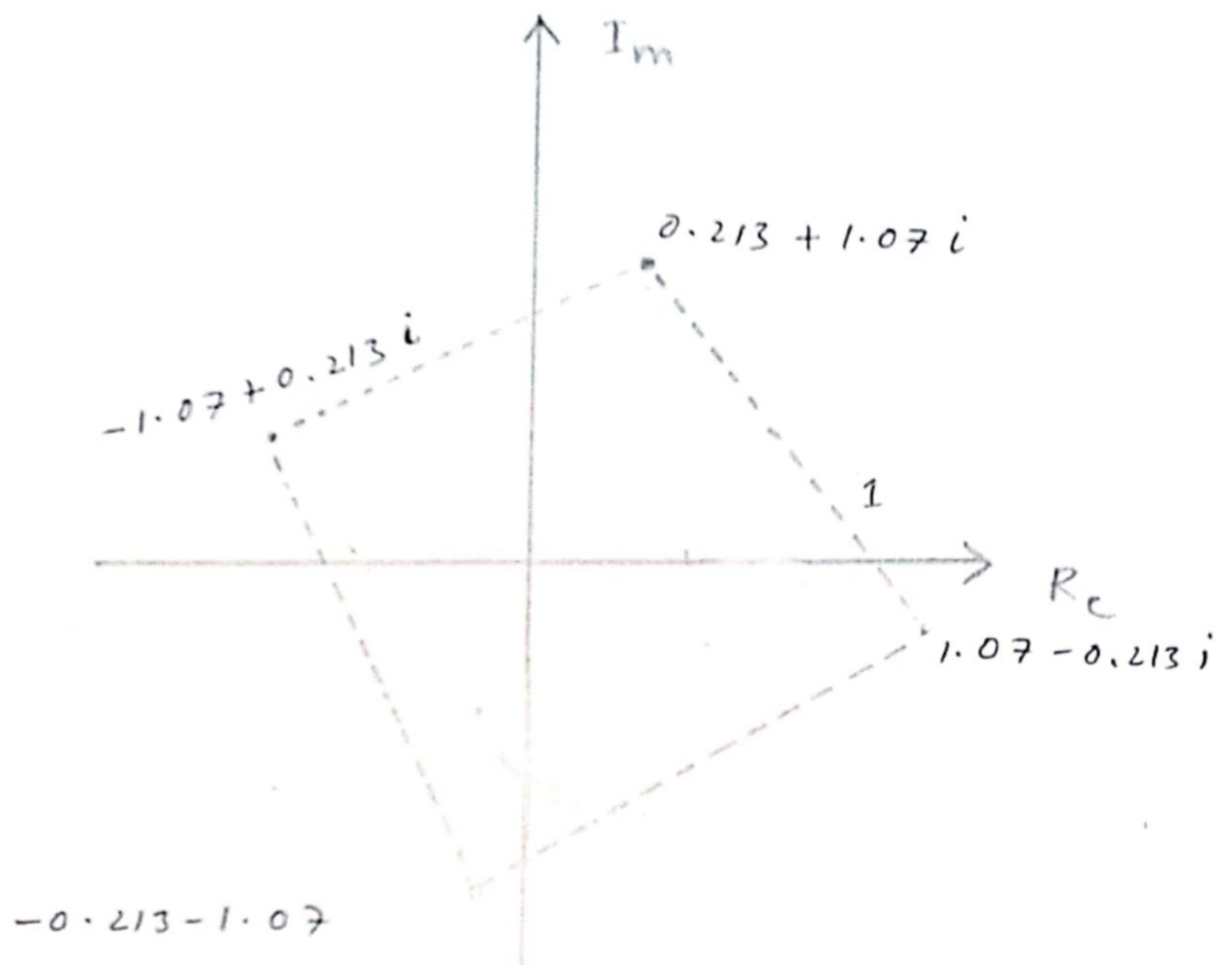
$$= 2^{\frac{1}{8}} \left[\cos \left(\frac{-\pi + 24\pi}{4} \right) + i \sin \left(\frac{-\pi + 24\pi}{4} \right) \right]$$

$$= 2^{\frac{1}{8}} \left[\cos \left(\frac{23\pi}{16} \right) + i \sin \left(\frac{23\pi}{16} \right) \right] \sim -0.213 - 1.07i$$

□

$$\sim -0.213 - 1.07i$$

□



solution : $f(z) = 1 - z$

$$\rightarrow f[z(t)] = 1 - z(t)$$

$$= 1 - x + it^2$$

$$z'(t) = 1 - 2it$$

$$\Rightarrow f(z(t)) z'(t)$$

$$= (1 - x + it^2)(1 - 2it)$$

$$= 1 - 2it - x + 2it^2 + it^2 - 2it^3$$

$$= (1 - 2it - x) + 3it^2 + 2t^3$$

$$= (1 - x + 2t^3) + (3t^2 - 2t)i$$

$$= \int_C f(z) dz = \int_0^1 f(z(t)) z'(t) dt$$

$$= \int_0^1 [1 - x + 2t^3] + i(3t^2 - 2t) dt$$

$$= \int_0^1 1 dt - \int_0^1 x dt + 2 \int_0^1 t^3 dt + 3i \int_0^1 t^2 dt - 2i \int_0^1 t dt$$

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$$= [t]_0' - \frac{1}{2} [t^2]_0' + \frac{2}{4} [t^4]_0' + \frac{3i}{3} [t^3]_0'$$

$$- \frac{2i}{i} [t^2]_0'$$

$$= 1 - \frac{1}{2} + \frac{1}{2} + i - i$$

$$= 1$$

□

solution: Here c is a simple closed path, and

the domain inside the c is simply connected.

But $0 \in D$, and $f'(z) = -\frac{1}{z^2}$ does not exist. Hence

$f(z)$ is not analytic in the entire domain D .

Thus we cannot apply Cauchy Integral Theorem.

But we can evaluate $\oint_c f(z) dz = \oint_c \frac{1}{z} dz$ as

follows: we can re-write $c = z(\theta) = x + yi =$

$r \cos \theta + i r \sin \theta$, for $0 \leq \theta \leq 2\pi = \cos \theta + i \sin \theta$,

[\therefore for unit circle $r = 1$, $0 \leq \theta \leq 2\pi$] $\Rightarrow z(\theta) = e^{i\theta}$,

$z'(\theta) = i e^{i\theta}$ and we can write $\oint_c \frac{1}{z} dz =$

$$\begin{aligned} \oint_c \frac{1}{z} dz &= \int_0^{2\pi} f(z(\theta)) z'(\theta) d\theta = \int_0^{2\pi} \frac{1}{z(\theta)} z'(\theta) d\theta \\ &= \int_0^{2\pi} \frac{1}{e^{i\theta}} i e^{i\theta} d\theta = i \int_0^{2\pi} d\theta = i [\theta]_0^{2\pi} = i [2\pi - 0] = 2\pi i \end{aligned}$$

Solution : $\therefore \theta = \arccos \left(\frac{1}{\sqrt{3}} \right) \approx 54.74^\circ$

Thus, $0 \leq \theta \leq \frac{\pi}{2}$, and we use the formula:

$$\vec{H} = \left(\frac{\vec{F} \cdot \vec{n}}{\|\vec{n}\|^2} \right) \vec{n} = \frac{\{3(1)\} + \{(-2)(1)\} + \{6(1)\}}{(\sqrt{1^2+1^2+1^2})^2} (\hat{i} + \hat{j} + \hat{k})$$

$$= \left(\frac{3-2+6}{3} \right) (\hat{i} + \hat{j} + \hat{k})$$

$$= \frac{7}{3} (\hat{i} + \hat{j} + \hat{k})$$

□

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Solution : Here, c is swept out by the vector

$$\vec{R}(t) = 2 \cos(t) \hat{i} + 2 \sin(t) \hat{j} + t \hat{k}, \quad t \in [0, 2].$$

Now, tangent to c , $\vec{R}'(t) = -2 \sin(t) \hat{i} + 2 \cos(t) \hat{j} + \hat{k}$.

We know, the length of c ;

$$L(c) = \int_a^b \|\vec{R}'(t)\| dt, \text{ here } a=0 \text{ \& } b=2.$$

$$\|\vec{R}'(t)\| = \sqrt{\{-2 \sin(t)\}^2 + \{2 \cos(t)\}^2 + (1)^2}$$

$$= \sqrt{4(\sin^2 t + \cos^2 t) + 1}$$

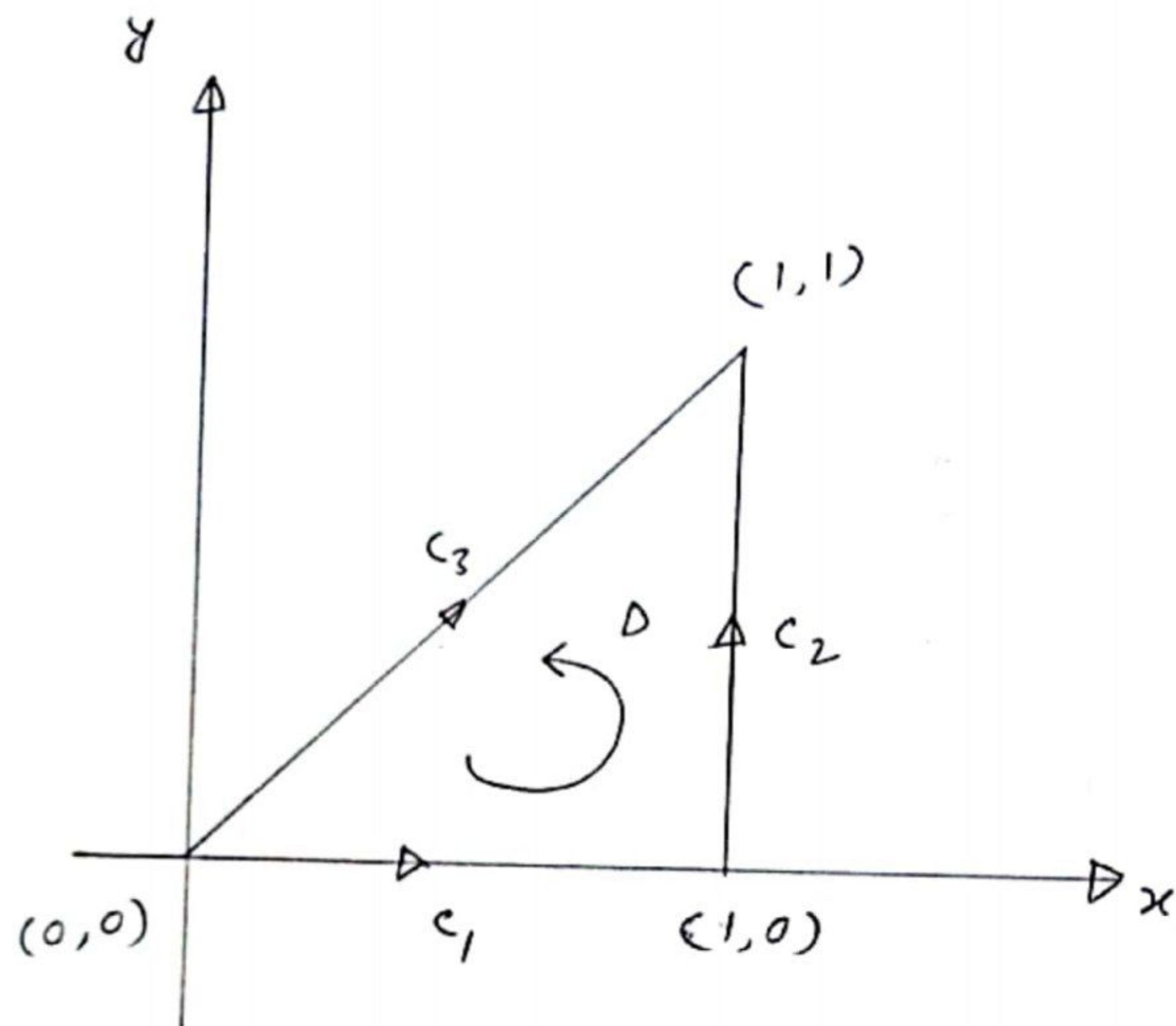
$$= \sqrt{4(1) + 1}$$

$$= \sqrt{5}.$$

$$\therefore L(c) = \int_0^2 \sqrt{5} dt = \sqrt{5} \int_0^2 dt = \sqrt{5} [t]_0^2 = 2\sqrt{5} \text{ unit.}$$

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Solution:



Here, c consists of three smooth pieces:

c_1 , c_2 & c_3 as shown: we may parametrize

these as:

$$c_1 : x = x, y = 0; x: 0 \rightarrow 1,$$

$$c_2 : x = 1, y = y; y: 0 \rightarrow 1,$$

$$c_3 : x = y; x: 1 \rightarrow 0,$$

$$\hookrightarrow \text{i.e. } x(x) = x, y(x) = x; x: 1 \rightarrow 0$$

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$$= \int [F_1 dx + F_2 dy] = \int_{C_1} (F_1 dx + F_2 dy) + \int_{C_2} (F_1 dx +$$

$$F_2 dy) + \int_{C_3} (F_1 dx + F_2 dy)$$

$$\int_{C_2} [F_1 dx + F_2 dy]; \quad x(x) = x, \quad y(x) = 0, \quad x: 0 \rightarrow 1$$

$$dx = dx, \quad dy = d(0) = 0 \quad (x \text{ is parameter})$$

$$F_1(x(x), y(x)) = y(x) = 0, \quad F_2(x(x), y(x)) = z(x)(0) = 0$$

$$\int_{C_1} F_1 dx + F_2 dy = \int_0^1 0 dx + \int_0^1 0 d(0) = 0$$

For $\int_{C_2} F_1 dx + F_2 dy$ we can use y as the parameter

For $\int_{C_2} F_1 dx + F_2 dy$ we get:

$$x \doteq x(y) = 1, \quad x(y) = y; \quad y: 0 \rightarrow 1$$

$$dx = d(1) = 0, dy = dy, F_1(x(y), y(y)) = y, \text{ and}$$

$$F_2(x(y), y(y)) = 2(1)y = 2y$$

$$\therefore \int_{C_2} F_1 dx + F_2 dy = \int_0^1 y d(1) + 2y dy = \int_0^1 (0 + 2y) dy$$

$$= 2 \int_0^1 y dy = 2 \left[\frac{y^2}{2} \right]_0^1 = [y^2]_0^1 = 1^2 - 0^2 = 1$$

Now, for $\int_C F_1 dx + F_2 dy$ we get:

$$F_1(x(x), y(x)) = x, F_2(x(x), y(x)) = 2(x)(x)$$

$$dx = dx$$

$$dy(x) = dx$$

$$x: 1 \rightarrow 0$$

$$\therefore \int_1^0 x dx + 2x^2 dx = \left[\frac{x^2}{2} \right]_1^0 + \left[\frac{2x^3}{3} \right]_1^0$$

$$= \frac{1}{2} [x^2]_1^0 + \frac{2}{3} [x^3]_1^0 = \frac{1}{2} [0^2 - 1^2] + \frac{2}{3}$$

$$[0^3 - 1^3]$$

$$= -\frac{1}{2} - \frac{2}{3} = \frac{-3-4}{6} = \frac{-7}{6} \text{ and thus, we get:}$$

$$\int_{C_1} \vec{F} + \int_{C_2} \vec{F} + \int_{C_3} \vec{F} = 0 + 1 + \left(\frac{-7}{6}\right) = \frac{6-7}{6} = -\frac{1}{6} \quad \square$$

Thus we have found that :

$$\int_C F_1 dx + F_2 dy = \int_D \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy \quad \square$$

Solution : Gauss's divergence Formula is :

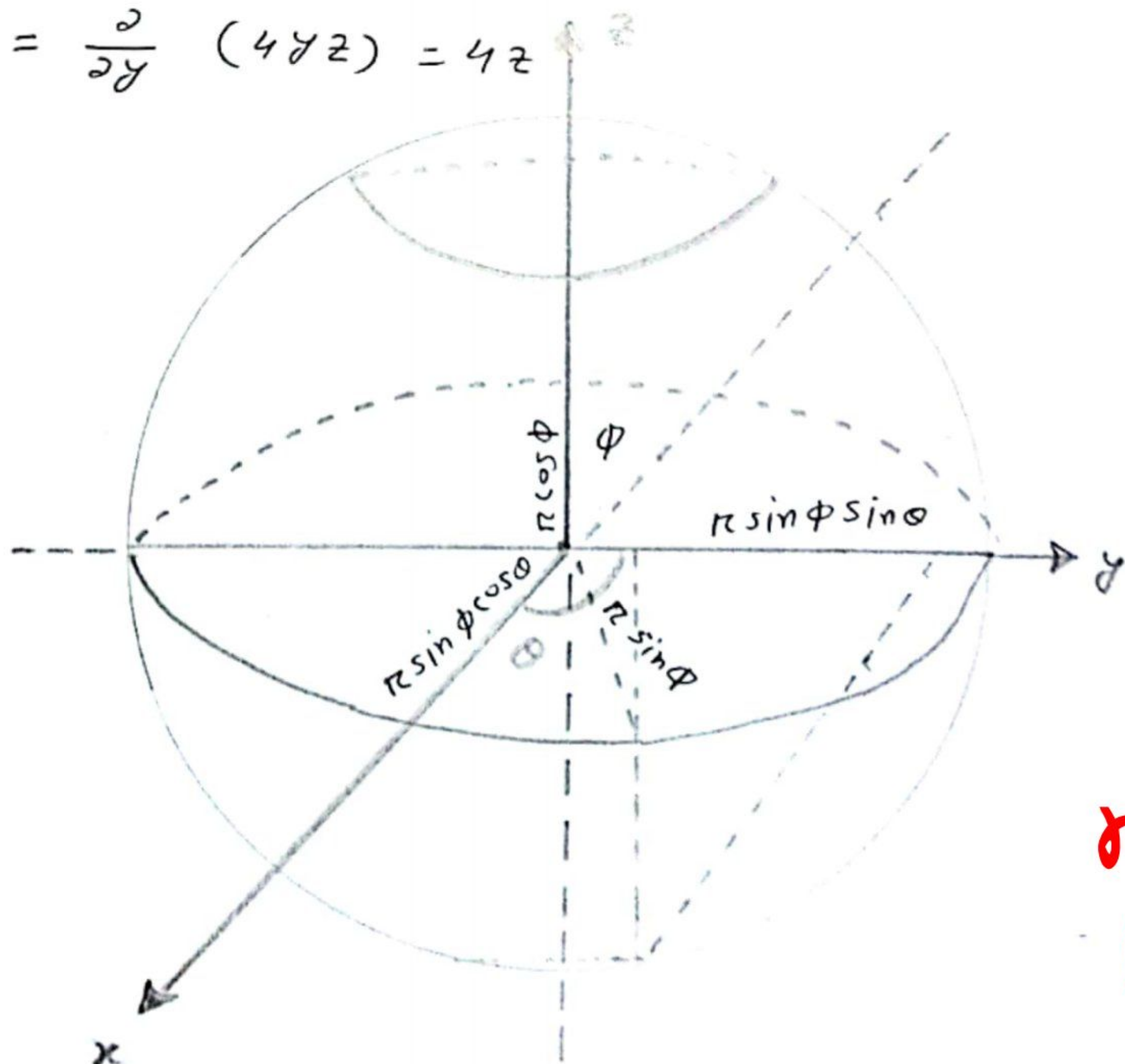
$$\iiint_S \vec{F} = \iiint_V \vec{\nabla} \cdot \vec{F} \, dV$$

First, let us compute the

R.H.S

$$\vec{\nabla} \cdot \vec{F} = \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \cdot 4yz \hat{j}$$

$$= \frac{\partial}{\partial y} (4yz) = 4z$$



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Hence in cartesian coordinates:

$$\iiint_V \vec{\nabla} \cdot \vec{F} \, dV = \iiint_V 4z \, dx \, dy \, dz$$

Since, limits are given in spherical coordinates

on S enclosing the sphere with radius R ; we

transform to spherical coordinates as: $4z = 4R \cos \phi$

$dx \, dy \, dz = R^2 \sin \phi \, dR \, d\theta \, d\phi$ with $0 \leq R \leq R$, $0 \leq \theta \leq 2\pi$,

and $0 \leq \phi \leq \pi$; and we get:

$$\iiint_V 4z \, dx \, dy \, dz = \int_0^\pi \int_0^{2\pi} \int_0^R (4R \cos \phi) R^2 \sin \phi \, dR \, d\theta \, d\phi$$

$$= \int_0^\pi \int_0^{2\pi} \cos \phi \sin \phi [R^4]_0^R \, d\theta \, d\phi = R^4 \int_0^\pi \int_0^{2\pi} \cos \phi \sin \phi \, d\theta \, d\phi$$

$$\cos \phi \sin \phi \, d\theta \, d\phi$$

$$= \pi^4 \int_0^\pi \cos \phi \sin \phi [\theta]_0^{2\pi} d\phi = 2\pi \pi^4 \int_0^\pi \cos \phi \sin \phi d\phi =$$

$$2\pi \pi^4 \int_0^\pi \frac{1}{2} \sin(2\phi) d\phi$$

$$= \pi \pi^4 \int_0^\pi \sin(2\phi) d\phi = -\pi \pi^4 \left(\frac{1}{2}\right) [\cos(2\phi)]_0^\pi =$$

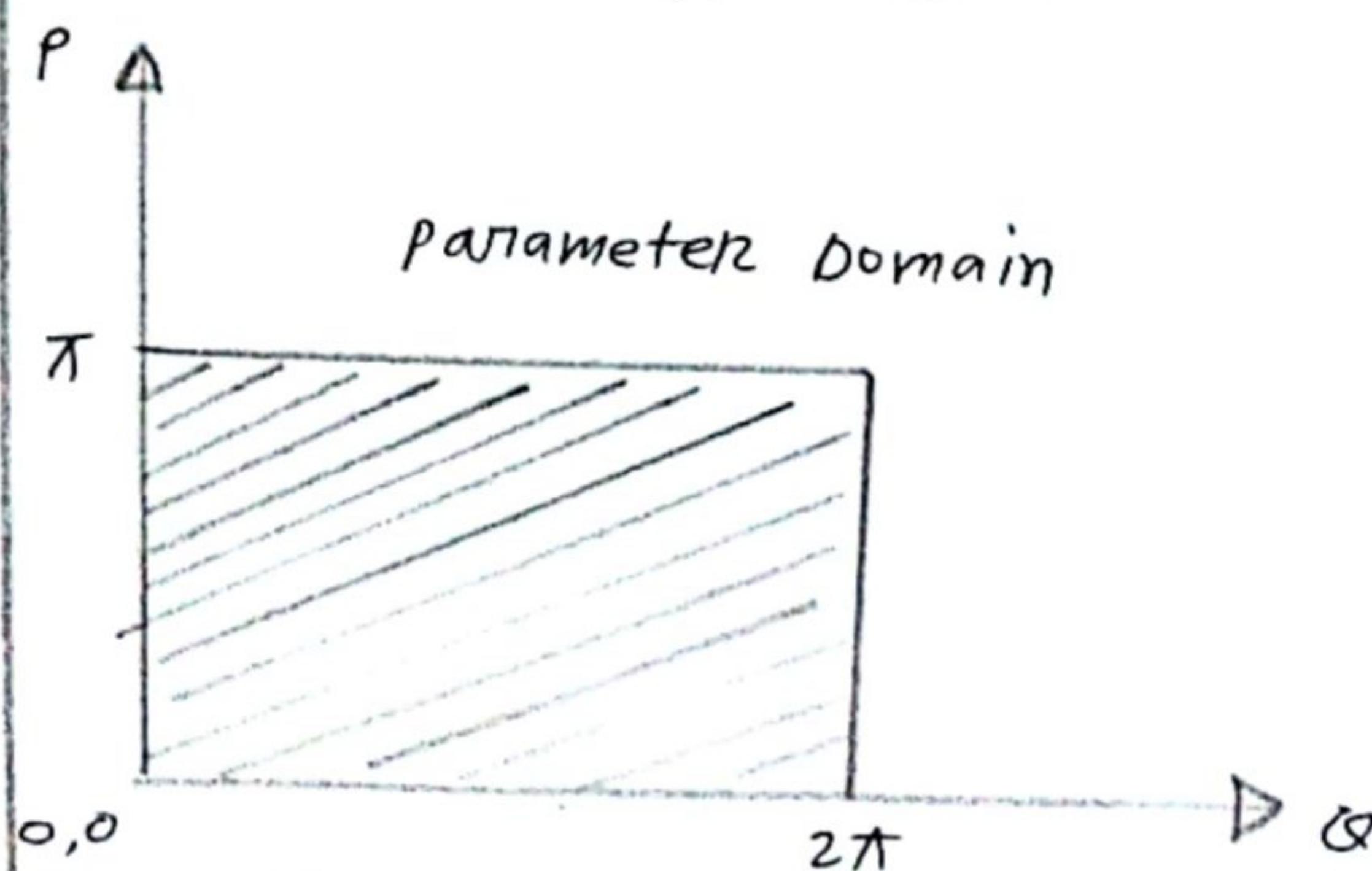
$$-\frac{\pi}{2} \pi^4 [1-1] = 0$$

Now, we compute L.H.S :

$$\iint_S \vec{F} = \iint_D [\vec{F}(x(\theta, \phi), y(\theta, \phi), z(\theta, \phi)),$$

$\vec{N}(\theta, \phi)] d\theta d\phi$ where D is the parameter

domain, $D = \{(\theta, \phi) : 0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi\}$



$$\text{Here } \vec{F}(x(\theta, \phi), y(\theta, \phi), z(\theta, \phi)) = 4yz\hat{j}$$

$$= 4r \sin \phi \sin \theta \cos \phi \hat{j} = 4r^2 \sin \theta \sin \phi \cos \phi \hat{j}$$

$$\text{Now, } \vec{N}(\theta, \phi) = \frac{\partial(y, z)}{\partial(\theta, \phi)} \hat{i} + \frac{\partial(z, x)}{\partial(\theta, \phi)} \hat{j} + \frac{\partial(x, y)}{\partial(\theta, \phi)} \hat{k}$$

[in Jacobian notation]

$$= \left(\frac{\partial y}{\partial z} \frac{\partial z}{\partial \phi} - \frac{\partial z}{\partial \theta} \frac{\partial y}{\partial \phi} \right) \hat{i} + \left(\frac{\partial z}{\partial \theta} \frac{\partial x}{\partial \phi} - \frac{\partial x}{\partial \theta} \frac{\partial z}{\partial \phi} \right) \hat{j}$$

$$+ \left(\frac{\partial x}{\partial \phi} \frac{\partial y}{\partial \phi} - \frac{\partial y}{\partial \theta} \frac{\partial x}{\partial \phi} \right) \hat{k} ; \text{ where, we get:}$$

$$\frac{\partial x}{\partial \theta} = \frac{\partial}{\partial \theta} (r \sin \phi \cos \theta) = -r \sin \phi \sin \theta, \quad \frac{\partial x}{\partial \phi} = \frac{\partial}{\partial \phi}$$

$$(r \sin \phi \cos \theta) = r \cos \phi \cos \theta$$

$$\frac{\partial y}{\partial \theta} = \frac{\partial}{\partial \theta} (r \sin \phi \sin \theta) = r \sin \phi \cos \theta ; \quad \frac{\partial y}{\partial \phi} = \frac{\partial}{\partial \phi}$$

$$(r \sin \phi \sin \theta) = r \cos \phi \sin \theta$$

$$\frac{\partial z}{\partial \theta} = \frac{\partial}{\partial \theta} (r \cos \phi) = 0, \quad \frac{\partial z}{\partial \phi} = \frac{\partial}{\partial \phi} (r \cos \phi) = -r \sin \phi$$

$$\therefore \vec{N}(\theta, \phi) = [(R \sin \phi \cos \theta)(-R \sin \phi) - 0(R \cos \phi \sin \theta)] \hat{i} + [0(R \cos \phi \sin \theta)$$

$$- (-R \sin \phi \sin \theta)(-R \sin \phi)] \hat{j} + [(-R \sin \phi \sin \theta)$$

$$(R \cos \phi \sin \theta) - R \sin \phi \cos \theta (R \cos \phi \cos \theta)] \hat{k}$$

$$= -R^2 \sin^2 \phi \cos \theta \hat{i} - R^2 \sin^2 \phi \sin \theta \hat{j} + (-R^2 \sin \phi \sin \theta - R^2 \sin \phi \cos \phi \cos \theta) \hat{k}$$

$$= -R^2 \sin^2 \phi \cos \theta \hat{i} - R^2 \sin^2 \phi \sin \theta \hat{j} - R^2 \sin \phi \cos \phi (\sin \theta + \cos \theta) \hat{k}$$

$$= -R^2 \sin \phi [\cos \theta \sin \phi \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \phi \hat{k}]$$

$$\therefore F(x(\theta, \phi), y(\theta, \phi), z(\theta, \phi))$$

$$\vec{N}(\theta, \phi) = [4R^2 \sin \theta \sin \phi \cos \phi \hat{j}].$$

$$[-R^2 \sin \phi \{\cos \theta \sin \theta \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \phi \hat{k}\}]$$

$$= (4R^2 \sin \theta \sin \phi \cos \phi)(-R^2 \sin \theta \sin^2 \phi) = -4R^4 \sin^3 \theta \sin^2 \phi$$

$$\sin^3 \theta \cos \phi$$

$$\therefore \int_S \vec{F} = \int_0^{2\pi} \int_0^\pi (-4\pi^4 \sin^2 \theta \sin^3 \phi \cos \phi)$$

$$d\phi d\theta = -4\pi^4 \int_0^{2\pi} \sin^2 \theta \left[\int_0^\pi \sin^3 \phi \cos \phi d\phi \right] d\theta$$

$$= 0$$

$$\text{Thus L.H.S} = \text{R.H.S} \quad \square$$

solution: The distribution is moderately skewed

as because its skewness = 0.3. Hence, we can

use the following formula:

$$\text{Mean} - \text{Mode} = 3 (\text{Mean} - \text{Median})$$

$$\rightarrow \text{Mean} - 50 = 3 (\text{Mean} - 55)$$

$$\rightarrow 3\text{Mean} - \text{Mean} = 3(55) - 50 \rightarrow 2\text{Mean} = 115.$$

$$\therefore \text{Mean} = \frac{115}{2} = 57.5$$

□

$$\text{Also, Given } S_k(P_1) = 0.3 = \frac{\text{Mean} - \text{Mode}}{\text{Standard Deviation}}$$

$$\Rightarrow \text{Standard deviation} = \frac{57.5 - 50}{0.3} = \frac{7.5}{0.3} = 25$$

$$S_k(P_2) = \frac{3(\text{Mean} - \text{Median})}{\text{Standard Deviation}} = \frac{3(57.5 - 55)}{25}$$

$$= \frac{3(2.5)}{25} = \frac{7.5}{25} = 0.3 \quad \square$$

Thus, for this distribution $s_k(P_1) = s_k(P_2)$. \square

[That is the degree of skewness from both formulas is 0.3 and the skewness is positive].

solution : $P(X) = \binom{N}{X} P^X q^{N-X}$;

Here , $X = 2$, $N = 6$ $P = \frac{1}{2}$, $q = 1 - P = 1 - \frac{1}{2} = \frac{1}{2}$

$$\therefore P(2) = \frac{N!}{X! (N-X)!} \left(\frac{1}{2}\right)^X \left(\frac{1}{2}\right)^{N-X}$$

$$= \frac{6!}{2! (6-2)!} \left(\frac{1}{2}\right)^2 \left(\frac{1}{2}\right)^{6-2}$$

$$= \frac{15}{64} \quad \square$$

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$$\boxed{\text{solution}} : z_1 = \frac{x_1 - \mu}{\sigma} = \frac{1 - 5}{2} = -2 \text{ \& } z_2 = \frac{x_2 - \mu}{\sigma}$$

$$= \frac{8 - 5}{2}$$

$$= 1.5$$

$$P(x_1 < x < x_2) = P(1 < x < 8)$$

$$= P(z_1 < z < z_2) =$$

$$P(-2 < z < 1.5)$$

$$= P(-\infty < z < 1.5) - P(-\infty < z < -2.0)$$

$$= \Phi(1.5) - \Phi(-2.0)$$

$$= \Phi(1.5) - [1 - \Phi(2.0)]$$

$$= 0.9332 - (1 - 0.9773)$$

$$= 0.9105.$$

□

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