MSBD 6000B Project 2

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The final model used in this project is a CNN. The model has pre-processing including using transform all image into a (50,50) smaller image with inter-area to fill the pixel. At last, all the pixels are divided by 255 to normalize the overall set.

Keras are used to train our model with the following steps

- 1. Conv2D of 128 features map with size of 3x3 and a rectifier activation function
- 2. 20% Dropout layer
- 3. Conv2D of 128 features map with size of 3x3 and a rectifier activation function
- 4. 2x2 Max Pool Layer
- 5. Conv2D of 128 features map with size of 3x3 and a rectifier activation function
- 6. 20% Dropout layer
- 7. Conv2D of 128 features map with size of 3x3 and a rectifier activation function
- 8. 2x2 Max Pool Layer
- 9. Conv2D of 128 features map with size of 3x3 and a rectifier activation function
- 10. 20% Dropout layer
- 11. Conv2D of 128 features map with size of 3x3 and a rectifier activation function
- 12. 2x2 Max Pool Layer
- 13. Flatten Layer
- 14. 20% Dropout layer
- 15. Fully Connected Layer with 2048 units and a rectifier activation function
- 16. 20% Dropout layer
- 17. Fully Connected Layer with 1024 units and a rectifier activation function
- 18. 20% Dropout layer
- 19. Fully Connected Layer with 512 units and a rectifier activation function
- 20. 20% Dropout layer
- 21. Fully Connected Layer with 5 output unit and a softmax activation function

Since the GPU memory available in the computer used for training are limited, only a small 50x50 image can be used and a large model are used to cover the limitation.