2.1、求证二阶张量的主不变量 g_1, g_2, g_3 ,(由(2.3.5)式定义)与矩 g_1^*, g_2^*, g_3^* (由(2.3.9)式定义)的关系式为

$$g_1 = g_1^*, g_2 = \frac{1}{2} [(g_2^*)^2 - g_2^*] g_3 = \frac{1}{6} (g_1^*)^3 - \frac{1}{2} g_1^* g_2^* + \frac{1}{3} g_3^*$$

以及

$$g_1^* = g_1$$
, $g_2^* = (g_1)^2 - 2g_2$, $g_3^* = (g_1)^3 - 3g_1g_2 + 3g_3$
 \Rightarrow if:

由书P56式2.3.5及2.3.8可知:

$$g_1 = T_{.1}^1 + T_{.2}^2 + T_{.3}^3$$

$$\boldsymbol{g}_{1} = \begin{bmatrix} T_{.1}^{1} & T_{.2}^{1} \\ T_{.1}^{2} & T_{.2}^{2} \end{bmatrix} + \begin{bmatrix} T_{.2}^{2} & T_{.3}^{2} \\ T_{.3}^{3} & T_{.3}^{3} \end{bmatrix} + \begin{bmatrix} T_{.3}^{3} & T_{.1}^{3} \\ T_{.3}^{1} & T_{.1}^{1} \end{bmatrix}$$

$$\mathbf{g}_3 = \begin{bmatrix} T_{.1}^1 & T_{.2}^1 & T_{.3}^1 \\ T_{.1}^2 & T_{.2}^2 & T_{.3}^2 \\ T_{.1}^3 & T_{.2}^3 & T_{.3}^3 \end{bmatrix}$$

$$g_1^* = trT = T_i^i$$

$$g_2^* = tr(T \cdot T) = T_{i}^i T_{i}^j$$

$$g_3^* = tr(T \cdot T \cdot T) = T_{i}^i T_{k}^j T_{i}^k$$

由以上可得

$$g_1^* = trT = T_i^i = T_{11} + T_{22} + T_{33} = g_1$$

$$g_{2}^{*} = tr(T \cdot T) = T_{.j}^{i} T_{.i}^{j} = T_{11} T_{11} + T_{12} T_{21} + T_{21} T_{12} + T_{22} T_{22} + T_{23} T_{32} + T_{31} T_{13} + T_{32} T_{23} + T_{33} T_{33}$$

$$(g_1)^2 = (T_{11} + T_{22} + T_{33})^2 = T_{11}T_{11} + T_{22}T_{22} + T_{33}T_{33} + 2T_{11}T_{22} + 2T_{11}T_{33} + 2T_{22}T_{33}$$

$$2g_2 = 2[T_{11}T_{22} - T_{12}T_{21} + T_{22}T_{33} - T_{23}T_{32} + T_{11}T_{33} - T_{31}T_{13}]$$

$$\left(g_{1}\right)^{2}-2g_{2}=T_{11}T_{11}+T_{12}T_{21}+T_{21}T_{12}+T_{22}T_{22}+T_{23}T_{32}+T_{31}T_{13}+T_{32}T_{23}+T_{33}T_{33}=g_{2}^{*}$$

同理可证 $g_3^* = (g_1)^3 - 3g_1g_2 + 3g_3$

2.2己知T与S互为转置。求证:它们有相同的主不变量。

证明:T,S的矩分别是:

$$trT = T_{\bullet i}^{i}$$

$$trS = S_{\bullet i}^{i}$$

$$tr(T \bullet T) = T_{\bullet i}^i T_{\bullet i}^j$$

$$tr(S \bullet S) = S^i_{\bullet i} S^j_{\bullet i}$$

$$tr(T \bullet T \bullet T) = T_{\bullet i}^{i} T_{\bullet k}^{j} T_{\bullet i}^{k}$$

$$tr(S \bullet S \bullet S) = S^{i}_{\bullet i} S^{j}_{\bullet k} S^{k}_{\bullet i}$$

又因为T与S互为转置

$$(T_{\bullet i}^{j})^{T} = S_{\bullet i}^{j}$$

$$(T_{\bullet i}^j)^T = T_{\bullet j}^i$$

$$S^{j}_{\bullet i} = T^{i}_{\bullet i}$$

将S用T的分量表示:

$$trS = S_{\bullet i}^i = T_{\bullet i}^i$$

$$tr(S \bullet S) = S^{i}_{\bullet j} S^{j}_{\bullet i} = T^{j}_{\bullet i} T^{i}_{\bullet j}$$

$$tr(S \bullet S \bullet S) = S_{\bullet j}^{i} S_{\bullet k}^{j} S_{\bullet i}^{k} = T_{\bullet i}^{j} T_{\bullet j}^{k} T_{\bullet k}^{i}$$

所以T与S有相同的矩,根据(P56 2.3.9)可知T与S有相同的主变量

2.3已知:任意二阶张量A,B,且 $T = A \cdot B$, $S = B \cdot A$ 求证:T = S具有相同的主不变量。

证明:
$$f_{1}^{T*}=tr(T)=T:G=tr(A\square B)=A\square B:G$$

$$=T_{.j}^{i}g_{i}g^{j}\square_{n}^{m}g_{m}g^{n}:g^{ab}g_{a}g_{b}$$

$$=T_{.j}^{i}T_{.n}^{m}\delta_{m}^{j}g_{i}g^{n}:g^{ab}g_{a}g_{b}$$

$$=T_{.j}^{i}T_{.n}^{m}\delta_{m}^{j}g_{i}g^{n}:g^{ab}g_{a}g_{b}$$

$$=T_{.j}^{i}T_{.n}^{m}\delta_{m}^{j}g^{ab}g_{ia}\delta_{b}^{n}$$

$$=T_{.m}^{i}T_{.b}^{m}g^{ab}g_{ia}$$

$$=T_{am}T^{ma}$$

$$f_{1}^{S*}=tr(S)=S:G=tr(B\square A)=B\square A:G$$

$$=T_{.n}^{m}g_{m}g^{n}\square_{.j}^{i}g_{i}g^{j}:g^{ab}g_{a}g_{b}$$

$$=T_{.n}^{m}T_{.j}^{i}\delta_{i}^{n}g_{m}g^{j}:g^{ab}g_{a}g_{b}$$

$$=T_{.n}^{m}T_{.j}^{i}\delta_{i}^{n}g_{m}g^{j}:g^{ab}g_{a}g_{b}$$

$$=T_{.i}^{m}T_{.b}^{i}g^{ab}g_{am}$$

$$=T_{ai}T^{ia}$$

$$f_{1}^{T*}=f_{1}^{S*}=f_{1}$$
所以二者具有相同的主不变量。

2.4 求证:

$$(1) \quad [T \bullet u \quad v \quad w] + [u \quad T \bullet v \quad w] + [u \quad v \quad T \bullet w] = \mathcal{I}_1^T [u \quad v \quad w]$$

(2)
$$[T \bullet a \ T \bullet b \ c] + [a \ T \bullet b \ T \bullet c] + [T \bullet a \ b \ T \bullet c] = \mathcal{I}_2^T [a \ b \ c]$$

证明: (1)

$$\begin{split} & \big[\boldsymbol{T} \bullet \boldsymbol{u} \quad \boldsymbol{v} \quad \boldsymbol{w} \big] + \big[\boldsymbol{u} \quad \boldsymbol{T} \bullet \boldsymbol{v} \quad \boldsymbol{w} \big] + \big[\boldsymbol{u} \quad \boldsymbol{v} \quad \boldsymbol{T} \bullet \boldsymbol{w} \big] \\ &= \epsilon_{ijk} T^i_{\bullet l} u^l \delta^j_m v^m \delta^k_n w^n + \epsilon_{ijk} \delta^i_l u^l T^j_{\bullet m} v^m \delta^k_n w^n + \epsilon_{ijk} \delta^i_l u^l \delta^j_m v^m T^k_{\bullet n} w^n \\ &= e_{ijk} T^i_{\bullet l} \delta^j_2 \delta^k_3 \epsilon_{lmn} u^l v^m w^n + e_{ijk} \delta^i_l T^j_{\bullet 2} \delta^k_3 \epsilon_{lmn} u^l v^m w^n + e_{ijk} \delta^i_l \delta^j_2 T^k_{\bullet 3} \epsilon_{lmn} u^l v^m w^n \\ &= \left(e_{i23} T^i_{\bullet 1} + e_{1j3} T^j_{\bullet 2} + e_{12k} T^k_{\bullet 3} \right) \epsilon_{lmn} u^l v^m w^n \\ &= \left(T^1_{\bullet 1} + T^2_{\bullet 2} + T^3_{\bullet 3} \right) \epsilon_{lmn} u^l v^m w^n \\ &= \mathcal{J}_1^T \big[\boldsymbol{u} \quad \boldsymbol{v} \quad \boldsymbol{w} \big] \end{split}$$

(2) 式左边

$$\begin{split} &= \left[T^{i}_{,j} \mathbf{a}^{j} \mathbf{g}_{i} \ T^{a}_{,b} \mathbf{b}^{b} \mathbf{g}_{a} \ \mathbf{c}^{c} \mathbf{g}_{c} \right] + \left[\mathbf{a}^{d} \mathbf{g}_{d} \ T^{i}_{,b} \mathbf{b}^{j} \mathbf{g}_{i} \ T^{a}_{,b} \mathbf{c}^{b} \mathbf{g}_{a} \right] + \left[T^{i}_{,j} \mathbf{a}^{j} \mathbf{g}_{i} \ \mathbf{b}^{e} \mathbf{g}_{e} \ T^{a}_{,b} \mathbf{c}^{b} \mathbf{g}_{a} \right] \\ &= T^{-i}_{,j} T^{-a}_{,b} a^{-j} b^{-b} c^{-c} \varepsilon_{iac} + T^{i}_{,j} T^{a}_{,b} a^{d} b^{j} c^{b} \varepsilon_{dia} + T^{i}_{,j} T^{a}_{,b} a^{j} b^{e} c^{b} \varepsilon_{iea} \\ &= \frac{1}{6} T^{i}_{,j} T^{a}_{,b} \left(a^{j} b^{b} c^{c} \varepsilon_{iea} \varepsilon_{jbc} \varepsilon^{jbc} + a^{d} b^{j} c^{b} \varepsilon_{dia} \varepsilon_{djb} \varepsilon^{djb} + a^{j} b^{e} c^{b} \varepsilon_{iea} \varepsilon_{jbb} \varepsilon^{jbb} \right) \\ &= \frac{1}{6} T^{i}_{,j} T^{a}_{,b} \left\{ \left(\delta^{i}_{j} \delta^{b}_{a} - \delta^{j}_{a} \delta^{b}_{i} \right) \left[\mathbf{a} \ \mathbf{b} \ \mathbf{c} \right] + \left(\delta^{i}_{j} \delta^{b}_{a} - \delta^{j}_{a} \delta^{b}_{i} \right) \left[\mathbf{a} \ \mathbf{b} \ \mathbf{c} \right] + \left(\delta^{i}_{j} \delta^{b}_{a} - \delta^{j}_{a} \delta^{b}_{i} \right) \left[\mathbf{a} \ \mathbf{b} \ \mathbf{c} \right] \right\} \\ &= \frac{1}{2} \left(T^{i}_{,j} T^{a}_{,b} \delta^{j}_{i} \delta^{b}_{a} - T^{i}_{,j} T^{a}_{,b} \delta^{j}_{a} \delta^{b}_{a} \right) \left[\mathbf{a} \ \mathbf{b} \ \mathbf{c} \right] \\ &= \frac{1}{2} \left(T^{i}_{,j} T^{a}_{,b} \delta^{j}_{i} \delta^{b}_{a} - T^{i}_{,j} T^{a}_{,b} \delta^{j}_{a} \delta^{b}_{a} \right) \left[\mathbf{a} \ \mathbf{b} \ \mathbf{c} \right] \\ &= \frac{1}{2} \left(T^{i}_{,j} T^{a}_{,b} \delta^{j}_{i} \delta^{b}_{a} - T^{i}_{,j} T^{a}_{,b} \delta^{j}_{a} \delta^{b}_{a} \right) \left[\mathbf{a} \ \mathbf{b} \ \mathbf{c} \right] \end{aligned}$$

 $= \frac{1}{2} \left(T_i^{i} T_a^{a} - T_a^{i} T_i^{a} \right) \begin{bmatrix} \mathbf{a} & \mathbf{b} & \mathbf{c} \end{bmatrix}_{=\phi_2^T} \begin{bmatrix} \mathbf{a} & \mathbf{b} & \mathbf{c} \end{bmatrix}_{\text{chi}} \text{ in } \mathbb{B}$

2.5 已知:实对称张量N,其特征方程具有三个不等的实根。 求证:N所对应的3个主轴方向 \mathbf{a}_1 , \mathbf{a}_2 , \mathbf{a}_3 是唯一的且互相正交。 证明:

不妨设3个不等实根分别为礼,礼,礼,礼

由 $N \bullet a_1 = \lambda a_1, N \bullet a_2 = \lambda a_2,$ 两边分别左点积 a_1 得:

$$\mathbf{a}_2 \bullet \mathbf{N} \bullet \mathbf{a}_1 = \mathbf{a}_2 \bullet \lambda_1 \mathbf{a}_1, \quad \mathbf{a}_1 \bullet \mathbf{N} \bullet \mathbf{a}_2 = \mathbf{a}_1 \bullet \lambda_2 \mathbf{a}_2$$

 $: a_1 \bullet N \bullet a_1 = a_1 \bullet N \bullet a_1$ (张量N为对称张量)

$$\therefore \mathbf{a}_2 \bullet \lambda_1 \mathbf{a}_1 = \mathbf{a}_1 \bullet \lambda_2 \mathbf{a}_2$$

即:
$$(\lambda_1 - \lambda_2)$$
 $\mathbf{a}_1 \cdot \mathbf{a}_2 = 0$

显然:
$$\lambda_1 - \lambda_2 \neq 0$$
, 且 $\mathbf{a}_1 \bullet \mathbf{a}_2 = 0$

2.6 **三知**:
$$N = e_1 e_1 + 2 e_2 e_2 - 2(e_1 e_2 + e_2 e_1) - 2(e_1 e_3 + e_3 e_1)$$

$$[N_{\bullet j}^i] = \begin{bmatrix} 1 & -2 & -2 \\ -2 & 2 & 0 \\ -2 & 0 & 0 \end{bmatrix}$$

求: (1) 主分量(从大到小排列)。 (2) 主方向对应的正交标准化基 $e_{1'}$, $e_{2'}$, $e_{3'}$ (右手系)。

解:
$$\mathcal{J}_1^N = 3$$
, $\mathcal{J}_2^N = \begin{vmatrix} 1 & -2 \\ -2 & 2 \end{vmatrix} + \begin{vmatrix} 2 & 0 \\ 0 & 0 \end{vmatrix} + \begin{vmatrix} 0 & -2 \\ -2 & 1 \end{vmatrix} = -6$

$$\mathcal{J}_3^N = \begin{vmatrix} 1 & -2 & -2 \\ -2 & 2 & 0 \\ -2 & 0 & 0 \end{vmatrix} = -8$$

$$\Delta(\lambda) = \lambda^3 - 3\lambda^2 - 6\lambda + 8 = 0$$

$$\lambda = \mu + 1$$

$$(\mu+1)^3 - 3(\mu+1)^2 - 6(\mu+1) + 8 = 0$$

$$\mu^3 + 3\mu^2 + 3\mu + 1 - 3\mu^2 - 6\mu - 3 - 6\mu - 6 + 8 = 0$$

$$\mu^3 - 9\mu = 0$$

$$\mu(\mu+3)(\mu-3)=0$$

$$\mu_1 = 0, \qquad \mu_2 = -3, \qquad \mu_3 = 3$$

$$\lambda_1 = \mu_3 + 1 = 4,$$
 $\lambda_2 = \mu_1 + 1 = 1,$ $\lambda_3 = \mu_2 + 1 = -2$

$$\begin{bmatrix} -3 & -2 & -2 \\ -2 & -2 & 0 \\ -2 & 0 & -4 \end{bmatrix} \boldsymbol{a}_1 = \boldsymbol{0} \qquad \boldsymbol{a}_1 = \begin{cases} 2/3 \\ -2/3 \\ -1/3 \end{cases}$$

$$\begin{bmatrix} 0 & -2 & -2 \\ -2 & 1 & 0 \\ -2 & 0 & -1 \end{bmatrix} \boldsymbol{a}_2 = \boldsymbol{0} \qquad \boldsymbol{a}_2 = \begin{bmatrix} 1/3 \\ 2/3 \\ -2/3 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -2 & -2 \\ -2 & 4 & 0 \\ -2 & 0 & 2 \end{bmatrix} \boldsymbol{a}_3 = \boldsymbol{0} \qquad \boldsymbol{a}_3 = \begin{cases} 2/3 \\ 1/3 \\ 2/3 \end{cases}$$

$$\therefore \quad a_1 \times a_2 = a_3$$

$$\therefore \quad \boldsymbol{e}_{i'} = \boldsymbol{a}_{i}$$

2.7 已知:

$$N = 10e_1e_1 + 4(e_1e_2 + e_2e_1) + 5e_2e_2 - 2(e_1e_3 + e_3e_1) + 3(e_2e_3 + e_3e_2) - e_3e_3$$

$$\begin{bmatrix} N_{\bullet j}^i \end{bmatrix} = \begin{bmatrix} 10 & 4 & -2 \\ 4 & 5 & 3 \\ -2 & 3 & -1 \end{bmatrix}$$

求: (1) 主分量(从大到小排列)。 (2) 主方向对应的正交标准化基 $e_{1'}$, $e_{2'}$, $e_{3'}$ (右手系)。

 $\mathcal{J}_{1}^{N} = 14, \qquad \mathcal{J}_{2}^{N} = \begin{vmatrix} 10 & 4 \\ 4 & 5 \end{vmatrix} + \begin{vmatrix} 5 & 3 \\ 3 & -1 \end{vmatrix} + \begin{vmatrix} -1 & -2 \\ -2 & 10 \end{vmatrix} = 6$

$$\mathcal{J}_3^N = \begin{vmatrix} 10 & 4 & -2 \\ 4 & 5 & 3 \\ -2 & 3 & -1 \end{vmatrix} = -192$$

$$\Delta(\lambda) = \lambda^3 - 14\lambda^2 + 6\lambda + 192 = 0$$

$$\lambda = \mu + \frac{14}{3}$$

$$\left(\mu + \frac{14}{3}\right)^3 - 14\left(\mu + \frac{14}{3}\right)^2 + 6\left(\mu + \frac{14}{3}\right) + 192 = 0$$

$$\mu^{3} + 14\mu^{2} + \frac{14^{2}}{3}\mu + \frac{14^{3}}{27} - 14\mu^{2} - 2 \times \frac{14^{2}}{3}\mu - \frac{14^{3}}{9} + 6\mu + 28 + 192 = 0$$

$$\mu^3 - \frac{178}{3}\mu + \frac{452}{27} = 0$$

$$\bigoplus \begin{vmatrix} \lambda - T_{1}^{1} & -T_{2}^{1} & -T_{3}^{1} \\ -T_{1}^{2} & \lambda - T_{2}^{2} & -T_{3}^{2} \\ -T_{1}^{3} & -T_{2}^{3} & \lambda - T_{3}^{3} \end{vmatrix}, \ \textcircled{2} = \begin{vmatrix} \lambda - T_{1}^{1} & -T_{1}^{2} & -T_{1}^{3} \\ -T_{2}^{1} & \lambda - T_{2}^{2} & -T_{2}^{3} \\ -T_{3}^{1} & -T_{3}^{2} & \lambda - T_{3}^{3} \end{vmatrix}$$
(2.1.12b) \Leftrightarrow

2.9 已知:任意二阶张量 \mathbf{T} 及其转置张量 \mathbf{T}^T ,又

$$\mathbf{X} = \mathbf{T} \cdot \mathbf{T}^T$$
, $\mathbf{Y} = \mathbf{T}^T \cdot \mathbf{T}$

求证: XY均为对称张量,且

$$\Delta(\lambda) = \det(\lambda \delta_i^i - X_{\cdot i}^i) = \det(\lambda \delta_i^i - Y_{\cdot i}^i)$$

(两张量的主分量相等,但对应主分量的基矢量并不相等) 证:

$$\mathbf{X}^{T} = (\mathbf{T} \cdot \mathbf{T}^{T})^{T} = (\mathbf{T}^{T})^{T} \cdot \mathbf{T}^{T} = \mathbf{T} \cdot \mathbf{T}^{T} = \mathbf{X}$$

$$\mathbf{Y}^{T} = (\mathbf{T}^{T} \cdot \mathbf{T})^{T} = \mathbf{T}^{T} \cdot (\mathbf{T}^{T})^{T} = \mathbf{T}^{T} \cdot \mathbf{T} = \mathbf{Y}$$

因此X,Y均为对称张量,两相量分别用分量表示:

$$X = T \cdot T^T = T_{ij}^i T_{ii}^m g^j g_m = X_{ij}^m g^j g_m$$

所以:
$$X_{\cdot i}^{i} = X_{\cdot i}^{\cdot j} = T_{\cdot i}^{i} T_{\cdot i}^{m} = T_{\cdot i}^{m} T_{\cdot i}^{i}$$

$$Y = T_{m}^{i} T_{i}^{m} g_{i} g^{j} = Y_{i}^{i} g_{i} g^{j} = X_{i}^{j} g_{i} g^{j}$$

则可知 X , Y 的特征多项式相同,特征值相等,则 $\lambda_{Y}=\lambda_{V}=\lambda$

2.10、已知任意二阶张量T及转置张量 T^T ,任意矢量u,

求证: $T \cdot u = u \cdot T^T$ 。

$$\widetilde{\mathbf{u}}: \quad \mathbf{T} \cdot \mathbf{u} = T_{ij} \mathbf{g}^i \mathbf{g}^j \cdot u^k \mathbf{g}_k = T_{ij} u^k \delta_k^j \mathbf{g}^i = T_{ij} u^j \mathbf{g}^i
\mathbf{u} \cdot \mathbf{T}^T = u^k \mathbf{g}_k \cdot T_{ij} \mathbf{g}^j \mathbf{g}^i = T_{ij} u^k \delta_k^j \mathbf{g}^i = T_{ij} u^j \mathbf{g}^i$$

:. 原式得证

2.11 已知任意二阶张量 $\boldsymbol{A}, \boldsymbol{B}$ 。求证: $\left(\mathbf{A} \bullet \mathbf{B}\right)^T = \mathbf{B}^T \bullet \mathbf{A}^T$

$$\mathbf{A} = A_{ij} \mathbf{g}^{j} \mathbf{g}^{j} \quad \mathbf{B} = B_{is} \mathbf{g}^{r} \mathbf{g}^{s} \quad \mathbf{B}^{T} \bullet \mathbf{A}^{T} = \left(B^{rs} \mathbf{g}_{i} \mathbf{g}_{s}\right)^{T} \bullet \left(A_{ij} \mathbf{g}^{j} \mathbf{g}^{j}\right)^{Ts}$$

$$(\mathbf{A} \bullet \mathbf{B})^{T} = \left(A_{ij} \mathbf{g}^{j} \mathbf{g}^{j} \bullet B^{rs} \mathbf{g}_{i} \mathbf{g}_{s}\right)^{T} = \left(B^{sr} \mathbf{g}_{i} \mathbf{g}_{s}\right) \bullet \left(A_{ji} \mathbf{g}^{j} \mathbf{g}^{j}\right)$$

$$= \left(A_{ij} B^{rs} \delta_{i}^{j} \mathbf{g}^{j} \mathbf{g}_{s}\right)^{T} = A_{ji} B^{rr} \delta_{s}^{i} \mathbf{g}_{i} \mathbf{g}^{j}$$

$$= \left(A_{ij} B^{js} \mathbf{g}^{j} \mathbf{g}_{s}\right)^{T} = A_{ji} B^{rr} \mathbf{g}_{i} \mathbf{g}^{j}$$

$$= \left(U_{i}^{s} \mathbf{g}^{j} \mathbf{g}_{s}\right)^{T} = U_{i}^{r} \mathbf{g}_{s} \mathbf{g}^{j}$$

$$= \left(U_{i}^{s} \mathbf{g}^{j} \mathbf{g}_{s}\right)^{T} = U_{i}^{s} \mathbf{g}_{s} \mathbf{g}^{j} = U_{i}^{s} \mathbf{g}^{j} \mathbf{g}_{s}$$

$$= U_{i}^{s} \mathbf{g}_{s} \mathbf{g}^{j} = U_{i}^{s} \mathbf{g}^{j} \mathbf{g}_{s}$$

$$\therefore (\mathbf{A} \bullet \mathbf{B})^{T} = \mathbf{B}^{T} \bullet \mathbf{A}^{T}$$

证明:

2-12 已知: T 为正则的二阶张量, u 为一矢量, $T \cdot u = 0$

求证: u=0

解: T 为正则的二阶张量

存在 T^{-1} 使 $T \cdot T^{-1} = T^{-1} \cdot T = G$

将等式两边都左乘 T^{-1}

左边= $T^{-1} \cdot T \cdot u = G \cdot u = u$

右边= $T^{-1} \cdot 0 = 0$

所以u=0

2.13 已知 T 为正则 2 阶张量。

求证: 其逆张量 T^1 的矩阵等于 T 的逆矩阵, $[T^1]=[T]^{-1}$

 $T=T^{ij}g_ig_j$

 $T^{^{-1}}\!\!=\!\!S_{k1}g_kg_1$

根据定义: $T \bullet T^{-1} = T^{-1} \bullet T = G$

点积缩去 gj与 gk有:

$$G = T_{ij}S_{kl}\delta_l^i g_i g_l = \delta_l^i g_i g_l$$

矩阵形式为: $[T][T^{-1}] = [E]$

又因为 T 正则,所以行列式不为零,所以矩阵[T] 可逆。

 $[T]^{-1} = [T^{-1}]$ 得证。

2.14 求证: (T^T)-1=(T-1)^T (T为正则的二阶张量)

证明:

2.16 (1) 已知: T 为任意二阶张量。求证: $T \cdot T^T \ge 0$, $T^T \cdot T \ge 0$

解: 由题意得

设 u 为任一非零矢量,它与二阶张量的点积 $\mathbf{u} \cdot \mathbf{T} = \mathbf{v}$, v 也是一矢量,因为 $(\mathbf{T} \cdot \mathbf{T}^T)^T = \mathbf{T} \cdot \mathbf{T}^T$,所以 $\mathbf{T} \cdot \mathbf{T}^T$ 为对称二阶张量。 $\mathbf{u} \cdot (\mathbf{T}^T \cdot \mathbf{T}) \cdot \mathbf{u} = (\mathbf{u} \cdot \mathbf{T}^T) \cdot (\mathbf{T} \cdot \mathbf{u}) = (\mathbf{T} \cdot \mathbf{u}) \cdot (\mathbf{T} \cdot \mathbf{u}) = |\mathbf{v}|^2 \geq 0$

故由定义 $\mathbf{u} \cdot \mathbf{N} \cdot \mathbf{u} = \mathbf{N} : \mathbf{u} \mathbf{u} \geq \mathbf{0}, \ \mathbf{T}^{\mathbf{T}} \cdot \mathbf{T} \geq \mathbf{0}$ 。

同理可得 $T^T \cdot T \ge 0$

2.17 已知:正交张量Q。

求证:
$$Q^T = Q^{-1}$$
亦为正交张量。

 $[Q^T]^{-1} = [Q^{-1}]^{-1} = Q$
解: $[Q^T]^T = Q$
则有 $[Q^T]^{-1} = [Q^T]^T$
故 Q^T 亦为正交张量; $[Q^{-1}]^{-1} = Q$

$$[Q^{-1}]^T = [Q^T]^T = Q$$

因此有,「 Q^{-1}]⁻¹ = $[Q^{-1}]^T$

故 O^{-1} 亦为正交张量;

综上,
$$Q^T = Q^{-1}$$
亦为正交张量。

2. 18. 已知:对于任意矢量 u, v, 均成立(Q?u)?(Q?v) = u?v

求证: $\mathbf{Q}^{\mathsf{T}} = \mathbf{Q}^{\mathsf{-1}}, \mathbf{Q}$ 为正交张量。

证明:要证 $\mathbf{Q}^T = \mathbf{Q}^{-1}$,Q为正交张量。考虑到 u, v 的任意性,只需证明 $\mathbf{Q}^T \bullet \mathbf{Q} = \mathbf{G}$,即 $\mathbf{Q}_i^{\ \ i} \bullet \mathbf{Q}_i^{\ \ i} = 1$

$$\begin{split} &(Q \bullet u) \bullet (Q \bullet v) = (Q \bullet v)^T \bullet (Q \bullet u) = (v \bullet Q^T) \bullet (Q \bullet u) = \\ &(v_i g^i \bullet Q_m^{\bullet 1} g_l g^m) \bullet (Q_{\bullet k}^n g_n g^k \bullet u^j g_j) = (v_i Q_m^{\bullet 1} \delta_l^i g^m) \bullet (Q_{\bullet k}^n u^j \delta_j^k g_n) \\ &= v_i Q_m^{\bullet i} Q_{\bullet j}^n u^j g^m \bullet g_n = v_i Q_m^{\bullet i} Q_{\bullet j}^n u^j \delta_n^m = v_i Q_n^{\bullet i} Q_{\bullet j}^n u^j = v_i Q_n^{\bullet i} Q_{\bullet j}^n \delta_n^j u^n \\ &= v_i Q_j^{\bullet i} Q_{\bullet j}^n u^n = v_n \delta_i^n Q_j^{\bullet i} Q_{\bullet j}^n u^n = v_n Q_j^{\bullet n} Q_{\bullet j}^n u^n = u \bullet v = u^m g_m \bullet v_n g^n \\ &= u^n v_n \\ &\Rightarrow Q_j^{\bullet n} Q_{\bullet j}^n = 1 \\ &2. \ 19 \ \exists \text{$\mathbb{H}:} \ \text{$\mathfrak{K}} \equiv \mathcal{V} \ \mathcal{O}_{+,+} \ \text{$\mathbb{H}} \oplus \mathcal{Q}_{+} \\ &\qquad \qquad \text{$\mathfrak{K}} \oplus \mathbb{H}:} \ (Q \cdot \mathcal{V}) \times (Q \cdot \mathcal{O}) = (\det Q) Q \cdot (\mathcal{V} \times \mathcal{O}) \end{split}$$

求证:
$$(Q \cdot V) \times (Q \cdot \omega) = (\det Q)Q \cdot (V \times \omega)$$

证明: $(Q \cdot V) \times (Q \cdot \omega) = (\det Q)Q \cdot (V \times \omega)$
证明: $(Q \cdot V) \times (Q \cdot \omega) = Q_{\cdot j}^i v^j Q_l^k \omega^l g_i \times g_k = \varepsilon_{ikm} Q_{\cdot j}^i Q_l^k v^j \omega^l g^m$
 $(\det Q)Q \cdot (V \times \omega) = Q_{\cdot 1}^i Q_{\cdot 2}^k Q_{\cdot 3}^m \varepsilon_{ikm} \varepsilon_{jnl} v^j \omega^l Q \cdot g^n$
 $= \varepsilon_{ikm} Q_{\cdot j}^i Q_l^k Q_n^m v^j \omega^l Q_s^n g^s$
 $= \varepsilon_{ikm} Q_{\cdot j}^i Q_l^k v^j \omega^l \delta_s^m g^s$
 $= \varepsilon_{ikm} Q_{\cdot j}^i Q_l^k v^j \omega^l g^m$

故:
$$(Q \cdot V) \times (Q \cdot \omega) = (\det Q)Q \cdot (V \times \omega)$$

2.20 已知: 矢量 wv,正则的二阶张量 B。求证:

$$(B \cdot v) \times (B \cdot w) = (\det B)(B^{-1})^T \cdot (v \times w)$$

证明:
$$(B \cdot v) \times (B \cdot w) = (\det B)(B^{-1})^T \cdot (v \times w)$$

则可得:
$$(B \cdot v) \times (B \cdot w) = B^i_{.j} B^m_{.n} V^j W^n B^q_{.b} \varepsilon_{imq} g^b = \det B \varepsilon_{jnb} V^j W^n g^b = \det B (v \times w)$$
即原命题成立。

21. 求证 2. 9 题与 2. 16 题中的 $\mathbf{X}=\mathbf{T} \bullet \mathbf{T}^\mathsf{T} = \mathbf{Y}=\mathbf{T}^\mathsf{T} \bullet \mathbf{T}$ 之间互为正交相似张量。即,存在正交张量 \mathbf{Q} ,使得 $\mathbf{X}=\mathbf{Q} \bullet \mathbf{Y} \bullet \mathbf{Q}^\mathsf{T}$ 证明: $\mathbf{Q} \cdot \mathbf{Y} \cdot \mathbf{Q}^\mathsf{T} = \mathbf{Q} \mathbf{T}^\mathsf{T} \mathbf{Q} \mathbf{T} = \mathbf{Q} \mathbf{T}^\mathsf{T} (\mathbf{Q} \mathbf{T}^\mathsf{T})^\mathsf{T} = (\mathbf{T} \mathbf{Q}^\mathsf{T})^\mathsf{T} (\mathbf{Q} \mathbf{T}^\mathsf{T})^\mathsf{T}$

又 Q 为正交张量,所以有 $Q^T = Q^{-1}$,所以 $Q^T Q = Q^{-1}Q = E$

故
$$\mathbf{Q} \cdot \mathbf{Y} \cdot \mathbf{Q}^T = (T\mathbf{Q}^T\mathbf{Q}T^T)^T = T^TT = X$$

2. 22 已知: **D** 为二阶对称张量 **N** 的偏斜张量。

$$\wp_1^D = 0, \wp_2^D = \wp_2^N - \frac{1}{3} (\wp_1^N)^2$$

求证:
$$\wp_3^D = \wp_3^N - \frac{1}{3}\wp_1^N\wp_2^N + \frac{2}{27}(\wp_1^N)^3$$

 $\wp_{2}^{D} = -\frac{1}{6} \left\{ \left(N_{\bullet 1}^{1} - N_{\bullet 2}^{2} \right)^{2} + \left(N_{\bullet 2}^{2} - N_{\bullet 3}^{3} \right)^{2} + \left(N_{\bullet 3}^{3} - N_{\bullet 1}^{1} \right)^{2} + \right.$

$$6\left(N_{\bullet 2}^{1}N_{\bullet 1}^{2}+N_{\bullet 3}^{2}N_{\bullet 2}^{3}+N_{\bullet 1}^{3}N_{\bullet 3}^{1}\right)\right\}$$

证: $\mathbf{N} = \mathbf{P} + \mathbf{D}$

其中,球形张量为 $\mathbf{P} = P_{\bullet j}^{i} \mathbf{g}_{i} \mathbf{g}^{j} = \frac{1}{3} \wp_{1}^{T} \mathbf{G} = \frac{1}{3} \wp_{1}^{T} \delta_{j}^{i} \mathbf{g}_{i} \mathbf{g}^{j}$

球形张量只有一个独立的分量

$$P_{\bullet j}^{i} = \frac{1}{3} \mathcal{D}_{1}^{T} \delta_{j}^{i} = \frac{1}{3} \mathcal{D}_{1}^{N} \delta_{j}^{i} = \begin{cases} \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right), i = j \\ 0, i \neq j \end{cases}$$

球形张量的三个主不变量为

$$\wp_1^P = \wp_1^T = \wp_1^N, \wp_2^P = \frac{1}{3} (\wp_1^N)^2, \wp_3^P = \frac{1}{27} (\wp_1^N)^3$$

偏斜张量 D 为

$$\mathbf{D} = D_{\bullet j}^{i} \mathbf{g}_{i} \mathbf{g}^{j} = \left(N_{\bullet j}^{i} - P_{\bullet j}^{i} \right) \mathbf{g}_{i} \mathbf{g}^{j}$$

$$D_{\bullet j}^{i} = N_{\bullet j}^{i} - \frac{1}{3} \mathcal{O}_{1}^{N} \delta_{j}^{i}$$

$$= \begin{cases} N_{\bullet j}^{i} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right), i = j \\ N_{\bullet j}^{i}, i \neq j \end{cases}$$

$$\begin{split} &\wp_{1}^{D} = \mathbf{G} : \mathbf{D} = \delta_{1}^{i} D_{\bullet i}^{I} = D_{i}^{I} = N_{\bullet 1}^{1} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right) \\ &+ N_{\bullet 2}^{2} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right) + N_{\bullet 3}^{3} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right) = 0 \end{split}$$

$$\mathcal{O}_{2}^{D} = \frac{1}{2} \delta_{lm}^{ij} D_{\bullet i}^{l} D_{\bullet j}^{m} = \frac{1}{2} \left(D_{\bullet i}^{i} D_{\bullet l}^{l} - D_{\bullet l}^{i} D_{\bullet i}^{l} \right) = \begin{vmatrix} D_{\bullet 1}^{1} & D_{\bullet 2}^{1} \\ D_{\bullet 1}^{2} & D_{\bullet 2}^{2} \end{vmatrix} +$$

$$\begin{vmatrix} D_{\bullet 2}^2 & D_{\bullet 3}^2 \\ D_{\bullet 3}^3 & D_{\bullet 3}^3 \end{vmatrix} + \begin{vmatrix} D_{\bullet 3}^3 & D_{\bullet 1}^3 \\ D_{\bullet 3}^1 & D_{\bullet 1}^1 \end{vmatrix} = D_{\bullet 1}^1 D_{\bullet 2}^2 - D_{\bullet 2}^1 D_{\bullet 1}^2 + D_{\bullet 2}^2 D_{\bullet 3}^3 - D_{\bullet 3}^2 D_{\bullet 2}^3 + D_{\bullet 3}^3 D_{\bullet 1}^1 - D_{\bullet 1}^3 D_{\bullet 3}^1$$

$$= \left(N_{\bullet 1}^{1} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right) \right) \left(N_{\bullet 2}^{2} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right) \right) - N_{\bullet 2}^{1} N_{\bullet 1}^{2} + N_{\bullet 3}^{3} \right) - N_{\bullet 2}^{1} N_{\bullet 1}^{2} + N_{\bullet 3}^{3} \right) \left(N_{\bullet 2}^{2} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right) \right) - N_{\bullet 3}^{2} N_{\bullet 2}^{3} + \left(N_{\bullet 3}^{3} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right) \right) - N_{\bullet 3}^{2} N_{\bullet 2}^{3} + \left(N_{\bullet 3}^{3} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right) \right) - N_{\bullet 1}^{3} N_{\bullet 3}^{1} \right) + \left(N_{\bullet 2}^{1} - N_{\bullet 2}^{2} \right)^{2} + \left(N_{\bullet 2}^{2} - N_{\bullet 3}^{3} \right)^{2} + \left(N_{\bullet 3}^{3} - N_{\bullet 1}^{1} \right)^{2} + \left(N_{\bullet 2}^{3} - N_{\bullet 3}^{1} \right)^{2} + \left(N_{\bullet 2}^{3} - N_{\bullet 3}^{1} \right)^{2} + \left(N_{\bullet 3}^{3} - N_{\bullet 1}^{1} \right)^{2} + \left(N_{\bullet 2}^{3} - N_{\bullet 3}^{1} \right)^{2} + \left(N_{\bullet 3}^{3} - N_{\bullet 1}^{1} \right)^{2} + \left(N_{\bullet 3}^{3} -$$

$$6\left(N_{\bullet 2}^{1}N_{\bullet 1}^{2}+N_{\bullet 3}^{2}N_{\bullet 2}^{3}+N_{\bullet 1}^{3}N_{\bullet 3}^{1}\right)\right\}$$

$$= N_{\bullet 1}^{1} N_{\bullet 2}^{2} + N_{\bullet 2}^{2} N_{\bullet 3}^{3} + N_{\bullet 3}^{3} N_{\bullet 1}^{1} - N_{\bullet 2}^{1} N_{\bullet 1}^{2} - N_{\bullet 3}^{2} N_{\bullet 2}^{3} - N_{\bullet 1}^{3} N_{\bullet 3}^{1} - \frac{1}{3} \left(N_{\bullet 1}^{1} + N_{\bullet 2}^{2} + N_{\bullet 3}^{3} \right)^{2} = \wp_{2}^{N} - \frac{1}{3} \left(\wp_{1}^{N} \right)$$

$$\wp^{D}_{3} = \begin{vmatrix} D_{\bullet 1}^{1} D_{\bullet 2}^{1} D_{\bullet 3}^{1} \\ D_{\bullet 1}^{2} D_{\bullet 2}^{2} D_{\bullet 3}^{2} \\ D_{\bullet 1}^{3} D_{\bullet 2}^{3} D_{\bullet 3}^{3} \\ D_{\bullet 1}^{3} D_{\bullet 2}^{3} D_{\bullet 3}^{3} \end{vmatrix} = D_{\bullet 1}^{1} D_{\bullet 2}^{2} D_{\bullet 3}^{3} + D_{\bullet 3}^{1} D_{\bullet 2}^{2} D_{\bullet 2}^{3} + D_{\bullet 1}^{3} D_{\bullet 2}^{1} D_{\bullet 2}^{3} + D_{\bullet 1}^{3} D_{\bullet 2}^{1} D_{\bullet 2}^{3} - D_{\bullet 2}^{3} D_{\bullet 3}^{3} + D_{\bullet 3}^{3} D_{\bullet 2}^{3} D_{\bullet 3}^{3} + D_{\bullet 3}^{3} D_{\bullet 2}^{3} D_{\bullet 3}^{3} D_{\bullet 3}^{3} D_{\bullet 3}^{3} D_{\bullet 3}^{3} + D_{\bullet 3}^{3} D_{\bullet 3}^{3} D_{\bullet 3}^{3} D_{\bullet 3}^{3} D_{\bullet 3}^{3} D_{\bullet 3}^{3} + D_{\bullet 3}^{3} D_{\bullet 3}^{3}$$

$$D_{\bullet 3}^{1} D_{\bullet 2}^{2} D_{\bullet 1}^{3} - D_{\bullet 1}^{1} D_{\bullet 1}^{2} D_{\bullet 2}^{3} D_{\bullet 2}^{3} - D_{\bullet 3}^{3} D_{\bullet 2}^{1} D_{\bullet 1}^{2} = \cdots = 0$$

$$\wp_{3}^{N} - \frac{1}{3}\wp_{1}^{N}\wp_{2}^{N} + \frac{2}{27}(\wp_{1}^{N})^{3}$$

得让 2.23

证明.

$$N \bullet a = (D + P) \bullet a = \lambda^N a$$

$$N_{\cdot j}^{i}a^{j} = \left(D_{\cdot j}^{i} + P_{\cdot j}^{i}\right)a^{j} = \lambda^{N}a^{j}$$

$$N_{\cdot j}^{i} a^{j} = \left(D_{\cdot j}^{i} + \frac{1}{3} f_{1}^{N} \delta_{j}^{i}\right) a^{j} = \lambda^{N} a^{j}$$

$$D_{\cdot j}^{i} a^{j} = (\lambda^{N} - \frac{1}{3} f_{1}^{N} \delta_{j}^{i}) a^{j} = \lambda^{D} a^{j}$$

也即:
$$\mathbf{D} \bullet \mathbf{a} = \lambda^D \mathbf{a}$$

:偏斜张量D与它对应的对称张量N具有相同的主方向

由 $N_{ij}^{i} = D_{ij}^{i} + \frac{1}{3} f_1^{N} \delta_j^{i}$ 偏 斜 张 量 **D**的 主 分 量 为 :

$$D_{i} = N_{i} - \frac{1}{3} f_{1}^{N}$$

[2.24] 已知: 二阶张量

$$T = -\frac{1}{2}e_1e_1 - \frac{\sqrt{3}}{2}e_1e_2 + \sqrt{3}e_2e_1 - e_2e_2 + 3e_3e_3$$

求: (1) 进行加法分解

(2) 进行乘法分解

解:(1)由二阶张量的表达式知,其二阶张量的分量为

$$[T] = [T_{ij}] = \begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0\\ \sqrt{3} & -1 & 0\\ 0 & 0 & 3 \end{bmatrix}$$

又因为, $T^T = T_{ji}e_{ij}$

$$[T^{\mathrm{T}}] = [T_{ji}] = [T_{ij}]^{\mathrm{T}} = \begin{bmatrix} -\frac{1}{2} & \sqrt{3} & 0 \\ -\frac{\sqrt{3}}{2} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

对二阶张量进行对称化与反对称化运算, $N = \frac{1}{2}(T + T^{T}); \Omega = \frac{1}{2}(T - T^{T})$

$$[N] = [N_{ij}] = \frac{1}{2}([T_{ij}] + [T_{ji}]) = \frac{1}{2} \left(\begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 \\ \sqrt{3} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix} + \begin{bmatrix} -\frac{1}{2} & \sqrt{3} & 0 \\ -\frac{\sqrt{3}}{2} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix} \right)$$

$$= \begin{bmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{4} & 0 \\ \frac{\sqrt{3}}{4} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$[\Omega] = [\Omega_{ij}] = \frac{1}{2}([T_{ij}] - [T_{ji}]) = \frac{1}{2} \left(\begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 \\ \sqrt{3} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix} - \begin{bmatrix} -\frac{1}{2} & \sqrt{3} & 0 \\ -\frac{\sqrt{3}}{2} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix} \right)$$

$$= \begin{bmatrix} 0 & -\frac{3\sqrt{3}}{4} & 0 \\ \frac{3\sqrt{3}}{4} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

師以

$$T = -\frac{1}{2}e_1e_1 - \frac{\sqrt{3}}{2}e_1e_2 + \sqrt{3}e_2e_1 - e_2e_2 + 3e_3e_3 = N + \Omega$$

$$= \left(-\frac{1}{2}e_1e_1 + \frac{\sqrt{3}}{4}e_1e_2 + \frac{\sqrt{3}}{4}e_2e_1 - e_2e_2 + 3e_3e_3\right) + \left(-\frac{3\sqrt{3}}{4}e_1e_2 + \frac{3\sqrt{3}}{4}e_2e_1\right)$$

(2)二阶张量作乘法分解:

$$T = H_1 \cdot Q_1$$

$$\overrightarrow{\Pi}(H_1)^2 = T \cdot T^{\mathrm{T}}$$

$$[\mathbf{T} \cdot \mathbf{T}^{\mathrm{T}}] = [T_{ij}][T_{ji}] = \begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 \\ -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 \\ -\frac{\sqrt{3}}{2} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} -\frac{1}{2} & \sqrt{3} & 0 \\ -\frac{\sqrt{3}}{2} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 9 \end{bmatrix}$$

$$\text{MK}[\mathbf{H}_{1}] = \begin{bmatrix} \sqrt{1} & 0 & 0 \\ 0 & \sqrt{4} & 0 \\ 0 & 0 & 3 \end{bmatrix}, \ [\mathbf{H}_{1}]^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix}$$

 $\overline{\mathbf{m}} \mathbf{Q}_1 = (\mathbf{H}_1)^{-1} \cdot \mathbf{T}$

则 $Q_1 = (H_1)^{-1}$ 1 又因为 $[(H_1)^{-1}] = [H_1]^{-1}$

$$[\boldsymbol{Q}_1] = [\boldsymbol{H}_1]^{-1}[\boldsymbol{T}] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix} \begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 \\ \sqrt{3} & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

经验证,

$$\left[\boldsymbol{Q}_{1}\cdot\boldsymbol{Q}_{1}^{\mathrm{T}}\right]=\left[\boldsymbol{Q}_{1}\right]\left[\boldsymbol{Q}_{1}^{\mathrm{T}}\right]=\left[\boldsymbol{Q}_{1}\right]\left[\boldsymbol{Q}_{1}\right]^{\mathrm{T}}$$

$$= \begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = [\mathbf{G}]$$
所以, \mathbf{Q}_1 是正交张量, \mathbf{H}_1 是正张量。
$$\mathbf{T} = -\frac{1}{2} \mathbf{e}_1 \mathbf{e}_1 - \frac{\sqrt{3}}{2} \mathbf{e}_1 \mathbf{e}_2 + \sqrt{3} \mathbf{e}_2 \mathbf{e}_1 - \mathbf{e}_2 \mathbf{e}_2 + 3 \mathbf{e}_3 \mathbf{e}_3 = \mathbf{H}_1 \cdot \mathbf{Q}_1$$
$$= (1\mathbf{e}_1 \mathbf{e}_1 + 2\mathbf{e}_2 \mathbf{e}_2 + 3\mathbf{e}_3 \mathbf{e}_3) \cdot \left(-\frac{1}{2} \mathbf{e}_1 \mathbf{e}_1 - \frac{\sqrt{3}}{2} \mathbf{e}_1 \mathbf{e}_2 + \frac{\sqrt{3}}{2} \mathbf{e}_2 \mathbf{e}_1 - \frac{1}{2} \mathbf{e}_2 \mathbf{e}_2 + 1 \mathbf{e}_3 \mathbf{e}_3 \right)$$

对于以下三种应力状态的应力张量 σ ,将其分解为球形 张量与偏斜张量S。求 J_1^{σ} , J_2^{S} 与 J_3^{S} ,以及偏斜张量S 的 ω 角。

- (1) 单向拉伸: $\sigma_1 = \sigma_0$ 0, $\sigma_2 = \sigma_3 = 0$; (2) 单向压缩 $\sigma_1 = \sigma_2 = 0$, $\sigma_3 = -\sigma_0 < 0$; (3) 纯剪切: $\sigma_1 = \tau > 0$, $\sigma_2 = 0$, $\sigma_3 = -\sigma_0 < 0$ $\sigma_1 = \tau > 0$, $\sigma_2 = 0$, $\sigma_3 = -\tau_0$

解: (1) 单向拉伸

$$\begin{bmatrix} \sigma_0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} \sigma_0/3 & 0 & 0 \\ 0 & \sigma_0/3 & 0 \\ 0 & 0 & \sigma_0/3 \end{bmatrix} + \begin{bmatrix} 2\sigma_0/3 & 0 & 0 \\ 0 & -\sigma_0/3 & 0 \\ 0 & 0 & -\sigma_0/3 \end{bmatrix}$$

$$\mathcal{J}_1^{oldsymbol{\sigma}} = oldsymbol{\sigma}_0$$

$$\begin{split} \mathcal{J}_{2}^{s} &= \begin{vmatrix} 2\sigma_{0}/3 & 0 \\ 0 & -\sigma_{0}/3 \end{vmatrix} + \begin{vmatrix} -\sigma_{0}/3 & 0 \\ 0 & -\sigma_{0}/3 \end{vmatrix} + \begin{vmatrix} -\sigma_{0}/3 & 0 \\ 0 & -\sigma_{0}/3 \end{vmatrix} + \begin{vmatrix} -\sigma_{0}/3 & 0 \\ 0 & 2\sigma_{0}/3 \end{vmatrix} \\ &= \begin{pmatrix} -\frac{2}{9} + \frac{1}{9} - \frac{2}{9} \end{pmatrix} \sigma_{0}^{2} = -\frac{1}{3}\sigma_{0}^{2} \\ &= \begin{pmatrix} 2\sigma_{0}/3 & 0 & 0 \\ 0 & -\sigma_{0}/3 & 0 \\ 0 & 0 & -\sigma_{0}/3 \end{vmatrix} = \frac{2}{27}\sigma_{0}^{3} \end{split}$$

$$\cos 3\omega = -\frac{\sqrt{27}\mathcal{J}_3^s}{2\left|\mathcal{J}_2^s\right|^{3/2}} = -\frac{\sqrt{27} \cdot 2\sigma_0^3/27}{2\left|-\sigma_0^2/3\right|^{3/2}} = -1$$

$$\omega = 60^{\circ}$$

(2) 单向压缩

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\sigma_0 \end{bmatrix} = \begin{bmatrix} -\sigma_0/3 & 0 & 0 \\ 0 & -\sigma_0/3 & 0 \\ 0 & 0 & -\sigma_0/3 \end{bmatrix} + \begin{bmatrix} \sigma_0/3 & 0 & 0 \\ 0 & \sigma_0/3 & 0 \\ 0 & 0 & -2\sigma_0/3 \end{bmatrix}$$
$$\mathcal{J}_1^{\sigma} = -\sigma_0$$

$$\begin{split} \mathcal{J}_{2}^{s} &= \begin{vmatrix} \sigma_{0}/3 & 0 \\ 0 & \sigma_{0}/3 \end{vmatrix} + \begin{vmatrix} \sigma_{0}/3 & 0 \\ 0 & -2\sigma_{0}/3 \end{vmatrix} + \begin{vmatrix} -2\sigma_{0}/3 & 0 \\ 0 & \sigma_{0}/3 \end{vmatrix} \\ &= \left(\frac{1}{9} - \frac{2}{9} - \frac{2}{9}\right)\sigma_{0}^{2} = -\frac{1}{3}\sigma_{0}^{2} \end{split}$$

$$J_3^s = \begin{vmatrix} \sigma_0/3 & 0 & 0 \\ 0 & \sigma_0/3 & 0 \\ 0 & 0 & -2\sigma_0/3 \end{vmatrix} = -\frac{2}{27}\sigma_0^3$$

$$\cos 3\omega = -\frac{\sqrt{27}\,\mathcal{I}_3^s}{2\left|\mathcal{I}_2^s\right|^{3/2}} = -\frac{\sqrt{27}\,\bullet\left(-2\,\sigma_0^3/27\right)}{2\left|-\sigma_0^2/3\right|^{3/2}} = 1$$

$$\omega = 0^{\circ}$$

(3) 纯剪切

$$\begin{bmatrix} \tau & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\tau \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + \begin{bmatrix} \tau & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\tau \end{bmatrix}$$

$$\mathcal{J}_1^{\sigma} = \mathcal{J}_3^{S} = 0$$

$$\mathcal{J}_{2}^{S} = \begin{vmatrix} \tau & 0 \\ 0 & 0 \end{vmatrix} + \begin{vmatrix} 0 & 0 \\ 0 & -\tau \end{vmatrix} + \begin{vmatrix} -\tau & 0 \\ 0 & \tau \end{vmatrix} = -\tau^{2}$$

$$\cos 3\omega = -\frac{\sqrt{27} \,\mathcal{J}_3^s}{2 \left|\mathcal{J}_2^s\right|^{3/2}} = -\frac{\sqrt{27} \bullet 0}{2 \left|-\tau^2\right|^{3/2}} = 0$$

$$\omega = 30^{\circ}$$

2.27 已知: 对称二阶张量 M 与 N 之间满足: $M^2 = N$ 。 求证: M 与 N 具有相同的主方向。

证明: $M \bullet a = \lambda^M a$

$$N \bullet a = M^2 \bullet a = M \bullet \lambda^M a = (\lambda^M)^2 a = \lambda^N a$$

即, M_iN 具有相同的主方向a。

2.28、已知: A为二阶张量, Q为任意正交张量, 对于一切Q,

均有 $\mathbf{Q} \cdot \mathbf{A} \cdot \mathbf{Q}^T = \mathbf{A}$ 。求证: \mathbf{A} 为球形张量。

证明:设二阶张量A在一组正交标准基 e_1, e_2, e_3 中的并矢展开式为

$$A = A_{11}e_1e_1 + A_{12}e_1e_2 + A_{13}e_1e_3 + A_{21}e_2e_1 + A_{22}e_2e_2$$

 $+A_{23}e_{2}e_{3}+A_{31}e_{3}e_{1}+A_{32}e_{3}e_{2}+A_{33}e_{3}e_{3}$

由于Q为任意正交张量,取正交张量 $Q = -e_1e_1 + e_2e_2 + e_3e_3$

则,
$$Q \cdot A \cdot Q^T = A_{11}e_1e_1 - A_{12}e_1e_2 - A_{13}e_1e_3 - A_{21}e_2e_1 + A_{22}e_2e_2$$

$$+A_{23}e_{2}e_{3}-A_{31}e_{3}e_{1}+A_{32}e_{3}e_{2}+A_{33}e_{3}e_{3}$$

由题知 $\mathbf{Q} \cdot \mathbf{A} \cdot \mathbf{Q}^T = \mathbf{A}$

则有: $A_{12} = -A_{12} = 0$, $A_{13} = -A_{13} = 0$, $A_{21} = -A_{21} = 0$, $A_{31} = -A_{21} = 0$

同理,取正交张量 $Q = e_1e_1-e_2e_2+e_3e_3$

则有 $A = A_{11}e_1e_1 + A_{22}e_2e_2 + A_{33}e_3e_3$

可得, $A_{23} = A_{32} = 0$

证得4为对称张量

由 $\mathbf{Q} \cdot \mathbf{A} \cdot \mathbf{Q}^T = \mathbf{A}$ 得

 $A_{11} = A_{22}$

同理,取正交张量 $Q = e_1e_1 + e_3e_2 - e_2e_3$

可证: $A_{22} = A_{33}$

故 $A_{11}(e_1e_1+e_2e_2+e_3e_3)$ 为球形张量。

2. 29 解

$$T = N + \Omega = \begin{bmatrix} N_1 & -\omega_3 & \omega_2 \\ \omega_3 & N_2 & -\omega_1 \\ -\omega_2 & \omega_1 & N_3 \end{bmatrix}$$

$$\operatorname{Tr}(T) = T^{i}_{\cdot,j}$$

$$Tr(T^2) = T^{i}_{.j} T^{j}_{.i}$$

$$\operatorname{Tr}(T^3) = T^{i}_{\cdot,j} T^{j}_{\cdot,k} T^{k}_{\cdot,i}$$

因主不变量与坐标的变换无关,因此可以将上试与矩阵中的元素分别对应

$$Tr(T) = N_1 + N_2 + N_3$$

$$Tr(T) = N_1^2 + N_2^2 + N_3^2 - 2\omega_1^2 - 2\omega_2^2 - 2\omega_3^2$$

$$Tr(T) = (N_1)^3 + (N_2)^3 + (N_3)^3$$
 (P83)