Zoom Range for image stream of UAV after reaching target

* Currently, images only exist at target
* Need for all pixels in the map
* Save an image of the whole map in perhaps 500 MB
  + Keep track of UAV coordinates, load corresponding pixel range of map, calculate corners of image, and load
  + How to save 0.5GB image in memory?
* 2 sets of GPS coordinates, actual and perceived
  + Image-displaying class receives actual coordinates at all times
    - Video stream therefore always ground truth
  + Drone might have wrong coordinates when hacked
* KIV : Image Overlay