BeamDyn User's Guide

Q. Wang, J. Jonkman, M. Sprague, and B. Jonkman

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Preface

This document offers a quick reference guide for the BeamDyn software program. It is intended to be used by the general user in combination with the FAST manual. The manual will be updated as new releases are issued and as needed to provide further information on advancements or modifications to the software.

Acknowledgments

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1 Introduction

BeamDyn is a time-domain structural-dynamics module for slender structures created by the National Renewable Energy Laboratory (NREL) through U.S. Department of Energy Wind and Water Power Program support. The module has been coupled into the FAST aero-hydro-servo-elastic wind turbine multi-physics engineering tool where it used to model blade structural dynamics. BeamDyn is designed to analyze beams that are made of composite materials, initially curved and twisted, and subject to large displacement and rotation deformations. BeamDyn can also be used for static analysis of beams.

The new BeamDyn module follows the requirements of the FAST modularization framework, couples to FAST version 8, and provides new capabilities for modeling initially curved and twisted composite wind turbine blades undergoing large deformation. BeamDyn can also be driven as a stand-alone code to compute the static and dynamic responses of slender structures (blades or otherwise) under prescribed boundary conditions uncoupled from FAST.

BeamDyn is based on the geometrically exact beam theory (GEBT) and is implemented using Legendre spectral finite elements (LSFEs). GEBT supports full geometric nonlinearity and large deflection, with bending, torsion, shear, and extensional degree-of-freedom (DOFs); anisotropic composite material couplings (using full 6 × 6 mass and stiffness matrices, including bend-twist coupling); and a reference axis that permits blades that are not straight (supporting built-in curve, sweep, and sectional offsets). LFSEs are p-type elements that combine the accuracy of global spectral methods with the geometric modeling flexibility of the h-type finite elements (FEs). For smooth solutions, LSFEs have exponential convergence rates compared to low-order elements that have algebraic convergence. Two spatial numerical integration schemes, including the reduced Gauss quadrature and a trapezoidal over-integration, have been implemented for FE analysis. The trapezoidal scheme is specifically designed for wind turbine blade analysis, where the cross-sectional beam properties may vary dramatically such that a large number of cross-sectional stations along the blade axis is needed. In this scheme, information at all specified stations, including stiffness and mass constants, will be captured such that the common practice of interpolating those to the quadrature points, which is usually lack of sound theoretical foundations, can be avoided. Time integration of the BeamDyn equations of motion is achieved through the implicit generalized- α solver, with user-specified numerical damping. Given the theoretical foundation, powerful numerical tools introduced above, BeamDyn can solve the complicate nonlinear composite beam problem in an efficient manner, for example, finishing the coupled transient dynamic analysis of composite wind turbine blade by a single 5^{th} -order LSFE with dozens of cross-sectional stations.

When coupled with FAST, loads and responses are transferred between BeamDyn, ElastoDyn, ServoDyn, and Aero-Dyn via the FAST driver program (glue code) to enable aero-elasto-servo interaction at each coupling time step. There is a separate instance of BeamDyn for each blade. At the root node, the six DOFs displacements (three translations and three rotations), velocities, and accelerations are inputs to BeamDyn from ElastoDyn; and the six reaction loads (three force and three moment resultants) at the root of the wind turbine blade are outputs from BeamDyn to ElastoDyn, including the blade-pitch command through ServoDyn. BeamDyn also outputs the local blade displacements, velocities, and accelerations to AeroDyn in order to calculate the local aerodynamic applied loads that become inputs for BeamDyn. In addition, BeamDyn can calculate member internal reaction loads, as requested by the user. Please refers to Figure 1 for the coupled interactions between BeamDyn and other modules in FAST. When uncoupled from FAST, the root motion and applied loads are specified via a stand-alone BeamDyn driver code.

The input file defines the blade geometry, cross-sectional material mass, stiffness, and damping properties, FE resolutions, and other simulation and output control parameters. The blade geometry is defined through a curvilinear blade reference axis by a series of key points in three-dimensional (3D) space along with the initial twist angles at these points. Each member contains at least three key points for the cubic spline fit implemented in BeamDyn; and is considered a LSFE with a parameter defining the order of the element. FE nodes, which are usually not evenly spaced along the element for LSFEs, will be generated by the module based on the mesh information. Blade properties are specified in a non-dimensional coordinate ranging from 0.0 to 1.0 along beam axis and are linear interpolated between two stations if needed by the spatial integration method.

The applied loads to BeamDyn can be either distributed loads at quadrature points or concentrated load at FE nodes

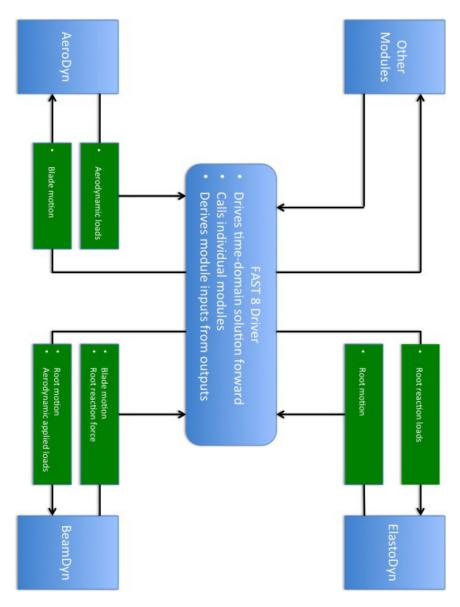


Figure 1. Coupled interaction between BeamDyn and FAST

or a combination of the two types of loads. When coupled to FAST, the aerodynamic loads computed by Aero-Dyn are transferred by the glue code at the nodes that are used for quadrature in BeamDyn.

This document is organized as follows. Section 2 details how to obtain the BeamDyn and FAST software archives and run either the stand-alone version of BeamDyn or BeamDyn coupled to FAST. Section 3 describes the BeamDyn input files. Section 4 discusses the output files generated by BeamDyn. Example input files are shown in Appendix A, B, and C. A summary of available output channels is found in Appendix D

2 Running BeamDyn

This section discusses how to obtain and execute BeamDyn from a personal computer. Both the stand-alone version and the FAST-coupled version of the software are considered.

2.1 Downloading the BeamDyn Software

There are two forms of the BeamDyn software to choose from: stand-alone and coupled to the FAST simulator. Alghough the user may not necessarily need both forms, he/she would likely need to be familiar with and run the stand-alone model if building a model of the blade from scratch. The stand-alone version is also helpful for model troubleshooting and may benefit users who are interested in conducting aero-hydro-servo-elastic simulations of onshore/offshore wind turbines. For this reason, BeamDyn can be obtained from two different repositories: one for the stand-alone BeamDyn and one for the coupled solution through FAST.

2.1.1 Stand-Alone BeamDyn Archive

Users can download the stand-alone BeamDyn archive from our Web server at https://nwtc.nrel.gov/BeamDyn. The file has a name similar to $BD_v1.00.00a.exe$, but may have a different version number. The user can then download the self-extracting archive (.exe) to expand the archive into a folder he/she specifies.

The archive contains the *bin*, *CertTest*, *Compiling*, *Documentation*, and *Source* folders. The *bin* folder includes the main executable file, *BeamDyn_win32.exe*, which is used to execute the stand-alone BeamDyn program. The *CertTest* folder contains a collection of sample BeamDyn input files and driver input files that can be used as templates for the user's own models. This manila may be found in the *Documentation* folder. The *Compling* folder contains files for compiling the stand-alone *BeamDyn_v1.00.00.exe* file with either Visual Studio or gFortran. The Fortran source code is located in the *Source* folder.

2.1.2 FAST Archive

Download the FAST archive, which includes a coupling to BeamDyn, from our Web server at https://nwtc.nrel.gov/FAST8. The file has a name similar to FAST_v8.12.00.exe, but may have a different version number. Run the downloaded self-extracting archive (.exe) to expand the archive into a user-specified folder. The FAST executable file is located in the archive's bin folder. Example models using the NREL 5-MW reference turbine are located in the CertTest folder.

2.2 Running BeamDyn

2.2.1 Running the Stand-Alone BeamDyn Program

The stand-alone BeamDyn program, *BeamDyn_v1.00.00.exe*, simulates static and dynamic responses of the user's input model, without coupling to FAST. Unlike the coupled version, the stand-alone software requires the use of a driver file in addition to the primary and blade BeamDyn input files. This driver file specifies inputs normally provided to BeamDyn by FAST, including motions of the blade root and externally applied loads. Both the BeamDyn summary file and the results output file are available when using the stand-alone BeamDyn (see Section 4 for more information regarding the BeamDyn output files).

Run the stand-alone BeamDyn software from a DOS command prompt by typing, for example:

>BeamDyn v1.00.00.exe Dvr 5MW Dynamic.inp

where, $Dvr_5MW_Dynamic.inp$ is the name of the BeamDyn driver input file, as described in Section 3.2.

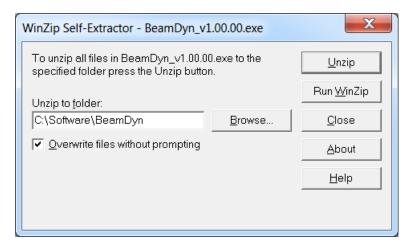


Figure 2. WinZip self-extractor main window

2.2.2 Running BeamDyn Coupled to FAST

Run the coupled FAST software from a DOS command prompt by typing, for example:

>FAST_v.8.12.00.exe Test26.fst

where *Test26.fst* is the name of the primary FAST input file. This input file has a feature switch to enable or disable the BeamDyn capabilities within FAST, and a corresponding reference to the BeamDyn input file. See the documentation supplied with FAST for further information.

3 Input Files

Users specify the blade model parameters; including its geometry, properties, and FE and output control parameters; via a primary BeamDyn input file and a blade property input file. When used in stand-alone mode, an additional driver input file is required. This driver file specifies inputs normally provided to BeamDyn by FAST, including simulation range, root motions (initial conditions), and externally applied loads.

No lines should be added or removed from the input files, except in tables where the number of rows is specified.

3.1 Units

BeamDyn uses the SI system (kg, m, s, N). Angles are assumed to be in radians unless otherwise specified.

3.2 BeamDyn Driver Input File

The driver input file is only needed for the stand-alone version of BeamDyn and contains inputs that are normally set by FAST, and that are necessary to control the simulation for uncoupled models.

The driver input file begins with two lines of header information, which is for the user but is not used by the software. If BeamDyn run in the stand-alone mode, the results output file will be prefixed with the same name of this driver input file.

A sample BeamDyn driver input file is given in Appendix A

3.2.1 Simulation Control Parameters

t_initial and *t_final* specify the starting time of the simulation and ending time of the simulation, respectively. *dt* specifies the time step size.

3.2.2 Gravity Parameters

Gx, Gy, and Gz specify the components of gravity vector along X, Y, and Z directions in the global coordinate system, respectively. In FAST, this is normally 0, 0, and -9.80665.

3.2.3 Inertial Frame Parameters

This section defines the relation between two inertial frames, the global coordinate system and initial blade reference coordinate system. GlbPos(1), GlbPos(2), GlbPos(3) specifies three components of the initial global position vector along X, Y, and Z directions resolved in the global coordinate system, see Figure 3. And the following 3×3 direction cosine matrix (DCM) relates the rotations from global coordinate system to blade coordinate system.

3.2.4 Floating Blade Reference Frame Parameters

This section specifies the parameters that defines the floating blade reference frame, which is a body-attached floating frame and the blade root is cantilevered at the origin of this frame. The floating blade reference fame is assumed to be in a constant rigid-body rotation mode about the origin of the global coordinate system, that is,

$$v_r = \omega_r \times r_t \tag{3.1}$$

where v_r is the root (origin of the floating blade reference frame) translational velocity vector; ω_r is the constant root (origin of the floating blade reference frame) angular velocity vector; and r_t is the global position vector introduced

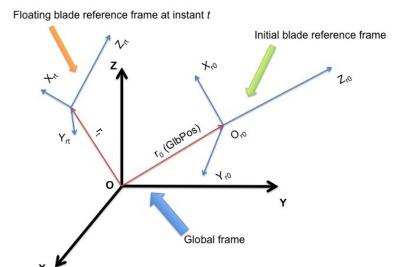


Figure 3. Global and blade coordinate systems in BeamDyn

in the previous section at instant t, see Figure 3. It is pointed out that the floating blade reference frame coincides with the initial floating blade reference frame at the beginning t=0. RootVel(4), RootVel(5), and RootVel(6) specify the three components of the root angular velocity vector about X, Y, and Z axises in global coordinate system, respectively. RootVel(1), RootVel(2), and RootVel(3), which are the three components of the root translational velocity vector along X, Y, and Z directions in global coordinate system, respectively, are calculated based on Eq. 3.1. BeamDyn can handle more complicate root motions by change the part, for example, in $BD_InputSolve$ subroutine in the Drvier_Beam.f90:

```
u%RootMotion%RotationVel(:,:) = 0.0D0
u%RootMotion%RotationVel(1,1) = IniVelo(5)
u%RootMotion%RotationVel(2,1) = IniVelo(6)
u%RootMotion%RotationVel(3,1) = IniVelo(4)
u%RootMotion%TranslationVel(:,:) = 0.0D0
u%RootMotion%TranslationVel(:,1) = &
MATMUL(BD_Tilde(real(u%RootMotion%RotationVel(:,1),BDKi)),temp_rr)
```

where IniVelo(5), IniVelo(6), and IniVelo(4) are the three components of the root angular velocity vector about X, Y, and Z axises in global coordinate system, respectively; $temp_rr$ is the global position vector at instant t.

The blade is initialized in the rigid-body motion mode, i.e., based on the root velocity information defined in this section and the position information defined in the previous section, the motion of other points along the blade are initialized as

$$a_{r0} = \omega_r \times (\omega_r \times r_0) \tag{3.2}$$

$$v_0 = v_{r0} + \omega \times P \tag{3.3}$$

$$\omega_0 = \omega_r \tag{3.4}$$

where a_{r0} is the initial root translational acceleration vector; v_0 and ω_0 the initial translational and angular velocity vectors along blade other than the root, respectively; and P is the position vector along the blade relative to the root.

3.2.5 Applied Load

This section defines the applied loads, including distributed and tip concentrated loads, for the analysis. The first six entries DistrLoad(i), $i \in [1,6]$, specify three components of uniformly distributed force vector and three components of uniformly distributed moment vector in the global coordinate systems, respectively. The following six entries TipLoad(i), $i \in [1,6]$, specify three components of concentrated tip force vector and three components of concentrated tip moment vector in global coordinate system, respectively. The distributed load defined in this section is assumed to be uniform along the blade and constant throughout the simulation; the tip load is a constant concentrated load applied at the tip of a blade.

BeamDyn is capable of handling more complex loading cases, for example, the time-dependent loads, through customizing of the source code (requiring a recompile of stand-alone BeamDyn). The user can define such loads in the *BD_InputSolve* solve in the Driver_Beam.f90 file, which is called every time step. The following section can be modified to define the concentrated load at each FE node:

```
! Define concentrated force vector
u%PointLoad%Force(:,:) = 0.0D0
! Define concentrated moment vector
u%PointLoad%Moment(:,:) = 0.0D0
```

where the first index in each array ranges from 1 to 3 for load vector components along three directions and the second index of each array ranges from 1 to **node_total**, where the latter is the total number of FE nodes. For example, a sinusoidal force along the X direction applied at the 2^{nd} FE node can be defined as

```
! Define concentrated force vector
u%PointLoad%Force(:,:) = 0.0D0
u%PointLoad%Force(1,2) = 1.0D+03*SIN((2.0*pi)*t/6.0)
! Define concentrated moment vector
u%PointLoad%Moment(:,:) = 0.0D0
```

with 1.0D + 03 the amplitude and 6.0 the period.

Similar to the concentrated load, the distributed loads can be defined in the same subroutine

```
IF(p%quadrature .EQ. 1) THEN
    DO i=1,p%ngp*p%elem_total+2
        u%DistrLoad%Force(1:3,i) = InitInput%DistrLoad(1:3)
        u%DistrLoad%Moment(1:3,i) = InitInput%DistrLoad(4:6)
    ENDDO

ELSEIF(p%quadrature .EQ. 2) THEN
    DO i=1,p%ngp
        u%DistrLoad%Force(1:3,i) = InitInput%DistrLoad(1:3)
        u%DistrLoad%Moment(1:3,i) = InitInput%DistrLoad(4:6)
    ENDDO
ENDIF
```

where p%ngp is the number of quadrature points; InitInput%DistrLoad(:) is the constant uniformly distributed loads BeamDyn reads from the driver input file, and p%elem_total is the total number of elements. The user can modify "InitInput%DistrLoad(:)" to define the loads based on need.

It is pointed out that the distributed loads are defined at the quadrature points for numerical integrations. For example, if Gauss quadrature is chosen (p%quadratrure .EQ. 1), then the distributed loads are defined at Gauss points plus the two end points of the beam (root and tip).

3.2.6 Primary Input File

InputFile is the file name of the primary BeamDyn input file. This name should be in quotations and can contain an absolute path or a relative path.

3.3 BeamDyn Primary Input File

The BeamDyn primary input file defines the blade geometry, FE and simulation options, output channels, and name of the blade input file. The geometry of the blade is defined by key point coordinates and initial twist angles (in units of degree) in the local blade coordinate system (IEC standard blade system where Z_r is along blade axis from root to tip, X_r directs normally toward the suction side, and Y_r directs normally toward the trailing edge).

The file is organized into several functional sections. Each section corresponds to an aspect of the BeamDyn model.

A sample BeamDyn primary input file is given in Appendix B

The primary input file begins with two lines of header information, which is for the user but is not used by the software.

3.3.1 Simulation Controls

User can set the *Echo* flag to "TURE" to have BeamDyn echo the contents of the BeamDyn input file (useful for debugging errors in the input file).

Analysis_Type specifies the type of an analysis. In the current version, there are two options: 1) static analysis, and 2) dynamic analysis. If BeamDyn is run in coupled FAST mode, this entry can be only set to 2, i.e., for dynamic analysis.

rhoinf specifies the numerical damping parameter (spectral radius of the amplification matrix) in the range of [0.0, 1.0] used in the generalized- α time integrator implemented in BeamDyn for dynamic analysis. For **rhoinf** = 1.0, no numerical damping is introduced and the generalized- α scheme is identical to the Newmark scheme; for **rhoinf** = 0.0, maximum numerical damping is introduced to help with convergence.

Quadrature specifies the spatial numerical integration scheme. There are two options: 1) Gauss quadrature; and 2) Trapezoidal quadrature. It is pointed out that in the current version, the Gauss quadrature is implemented in reduced form to improve efficiency and avoid shear locking. In the trapezoidal quadrature, only one member (FE element) can be defined in the following GEOMETRY section of the primary input file.

Refine specifies a refinement parameter used in trapezoidal quadrature. A value greater than unity will split the space between two input stations into Refine number of segments. The keyword "DEFAULT" may be used to set it to 1, i.e., no refinement is needed. This entry is not used in Gauss quadrature.

 $N_{-}Fact$ specifies a parameter used in the modified Newton-Ralphson scheme. If $N_{-}Fact = 1$ a full Newton iteration scheme is used, i.e., the global stiffness matrix is computed and factorized at each iteration; if $N_{-}Fact > 1$ a modified Newton iteration scheme is used, i.e., the global stiffness matrix is computed and factorized every $N_{-}Fact$ iterations within each time step. The keyword "DEFAULT" set $N_{-}Fact = 5$.

DTBeam specifies the fixed time step of the time-integration in seconds. The keyword "DEFAULT" may be used to indicate that the module should employ the time step prescribed by the driver code (FAST/stand-alone driver program).

NRMax specifies the maximum number of iterations in the Newton-Ralphson scheme. If convergence is not reached within this number of iterations, BeamDyn returns an error message and terminates the simulation. The keyword "DEFAULT" sets NRMax = 10.

Stop_Tol specifies a tolerance parameter used in convergence criteria of a nonlinear solution that is used for the termination of the iteration. The keyword "DEFAULT" sets $Stop_Tol = 1.0E - 05$.

3.3.2 Geometry Parameter

The blade beam model is composed of several *members* in series and each member is defined by at least three key points in BeamDyn. A cubic-spline-fit pre-processor implemented in BeamDyn automatically generates the member based on the key points and then interconnects the members into a blade. There is always a shared key points at adjacent members; therefore the total number of key points is related to number of members and key points in each member.

Member_Total specifies the number of beam members used in the structure.

KP_Total specifies the total number of key points used to define the beam members.

The following section contains *Member_Total* lines. Each line has two integers providing the member number (must be 1, 2, 3, etc., sequentially) and the number of key points in this member, respectively. It is noted that the number of key points in each member is not independent of the total number of key points and they should satisfy the following equality:

$$KP_t = \sum_{i=1}^{M_t} n_i - M_t + 1 \tag{3.5}$$

where KP_t is the total number of key points, M_t is the total number of members, and n_i is the number of key points in the i^{th} member. Because cubic splines are implemented in BeamDyn, n_i must be greater than or equal to three. Figure 4 shows two cases for member and key point definition.

The next section defines the key points information. Each key point is defined by three physical coordinates in IEC standard blade coordinate system along with a structural twist angle in the unit of degrees. The structural twist angle is also following the IEC standard which is defined as the twist about the negative Z axis. The key points are entered sequentially and there should be a total of *KP_Total* lines for BeamDyn to read in the information, after two header lines.

3.3.3 Mesh Parameter

Order_Elem specifies the order of shape functions for each finite element. Because LSFEs are adopted in BeamDyn, it is recommended to refine the mesh by increasing the order of elements (*p*-type) instead of increasing the number of elements. For Gauss quadrature, *Order_Elem* should be greater than one.

3.3.4 Material Parameter

BldFile is the file name of the blade input file. This name should be in quotations and can contain an absolute path or a relative path.

3.3.5 Pitch Actuator Parameter

In this release, the pitch actuator implemented in BeamDyn is not available. The *UsePitchAct* should be set to "FALSE" in this version, whereby the input blade-pitch angle prescribed by the driver code is used to orient the blade directly. *PitchJ*, *PitchK*, and *PitchC* specify the pitch actuator inertial, stiffness, and damping coefficient, respectively. In future releases, specifying *UsePitchAct* = TRUE will enable a second-order pitch actuator, whereby the pitch angular orientation, velocity, and acceleration are determined by the actuator based on the input blade-pitch angle prescribed by the driver code.

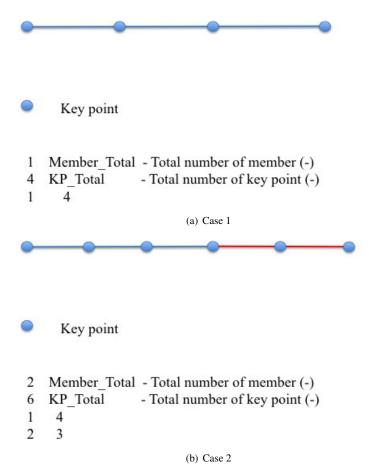


Figure 4. Member and key point definition. Case 1: one member defined by four key points; and Case 2: two members defined by six key points.

3.3.6 Outputs

In this section of the primary input file, the user sets flags and switches for the desired output behavior.

Specifying *SumPrint* = TRUE causes BeamDyn to generate a summary file with name *PrimaryInputFile.sum*. See Section 4.2 for summary file details.

OutFmt parameter controls the formatting of the results within the stand-alone BeamDyn's output file. It needs to be a valid Fortran format string, but BeamDyn currently does not check the validity. This input is unused when BeamDyn is used coupled to FAST.

NNodeOuts specifies the number of nodes to output to file. Currently, BeamDyn can output quantities at a maximum of nine nodes.

OutNd is a list *NNodeOuts* long of node numbers between 1 and *node_total* (total number of FE nodes), separated by any combination of commas, semicolons, spaces, and/or tabs. The nodal positions are given in the summary file, if output.

The *OutList* block contains a list of output parameters. Enter one or more lines containing quoted strings that in turn contain one or more output parameter names. Separate output parameter names by any combination of commas, semicolons, spaces, and/or tabs. If you prefix a parameter name with a minus sign, "-", underscore, "_", or the characters "m" or "M", BeamDyn will multiply the value for that channel by Đ1 before writing the data. The parameters are written in the order they are listed in the input file. BeamDyn allows you to use multiple lines so that you can break your list into meaningful groups and so the lines can be shorter. You may enter comments after the closing quote on any of the lines. Entering a line with the string "END" at the beginning of the line or at the beginning of a quoted string found at the beginning of the line will cause BeamDyn to quit scanning for more lines of channel names. Node-related quantities are generated for the requested nodes identified through the OutNd list above. If BeamDyn encounters an unknown/invalid channel name, it warns the users but will remove the suspect channel from the output file. Please refer to Appendix D for a complete list of possible output parameters and their names.

3.4 Blade Input File

The blade input file defines the cross-sectional properties at various stations along a blade and six damping coefficient for the whole blade. A sample BeamDyn blade input file is given in Appendix C. The blade input file begins with two lines of header information, which is for the user but is not used by the software.

3.4.1 Blade Parameters

Station_Total specifies the number cross-sectional stations along the blade axis used in the analysis.

 $Damp_Type$ specifies if structural damping is considered in the analysis. If $Damp_Type = 0$, then no damping is considered in the analysis and the six damping coefficient in the next section will be ignored. If $Damp_Type = 1$, structural damping will be included in the analysis.

3.4.2 Damping Coefficient

This section specifies six damping coefficients, μ_{ii} with $i \in [1,6]$, for six DOFs (three translations and three rotations). Viscous damping is implemented in BeamDyn where the damping forces are proportional to the strain rate. These are stiffness-proportional damping coefficients, whereby the 6x6 damping matrix at each cross section is scaled from the 6x6 stiffness matrix by these diagonal entries of a 6x6 scaling matrix:

$$\underline{\mathscr{F}}^{Damp} = \underline{\underline{\mu}} \, \underline{\underline{S}} \, \underline{\dot{\varepsilon}} \tag{3.6}$$

where \mathscr{Z}^{Damp} is the damping force, $\underline{\underline{S}}$ is the 6×6 cross-sectional stiffness matrix, $\underline{\dot{\varepsilon}}$ is the strain rate, and $\underline{\underline{\mu}}$ is the damping coefficient matrix defined as

$$\underline{\mu} = \begin{bmatrix} \mu_{11} & 0 & 0 & 0 & 0 & 0 \\ 0 & \mu_{22} & 0 & 0 & 0 & 0 \\ 0 & 0 & \mu_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & \mu_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & \mu_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & \mu_{66} \end{bmatrix}$$

$$(3.7)$$

3.4.3 Distributed Properties

This section specifies the cross-sectional properties at each of the *Station_Total* stations. For each station, a non-dimensional parameter η specifies the station location along the blade axis ranging from [0.0, 1.0]. The first and last station parameters must be set to 0.0 and 1.0, respectively.

Following the station location parameter η , there are two 6×6 matrices providing the structural and inertial properties for this cross-section. First is the stiffness matrix and then the mass matrix. It is noted that these matrices are defined in a local coordinate system along the blade axis following the IEC blade coordinate convention with Z_{rl} directing toward the unit tangent vector of the axis. For a cross-section without coupling effects, for example, the stiffness matrix is given as follows:

$$\begin{bmatrix} K_{ShrFlp} & 0 & 0 & 0 & 0 & 0 \\ 0 & K_{ShrEdg} & 0 & 0 & 0 & 0 \\ 0 & 0 & EA & 0 & 0 & 0 \\ 0 & 0 & 0 & EI_{Edg} & 0 & 0 \\ 0 & 0 & 0 & 0 & EI_{Flp} & 0 \\ 0 & 0 & 0 & 0 & 0 & GJ \end{bmatrix}$$

$$(3.8)$$

where K_{ShrEdg} and K_{ShrFlp} are the edge and flap shear stiffnesses, respectively; EA is the extension stiffness; EI_{Edg} and EI_{Flp} are the edge and flap stiffnesses, respectively; and GJ is the torsional stiffness.

A generalized sectional mass matrix is given by:

$$\begin{bmatrix} m & 0 & 0 & 0 & 0 & -mY_{cm} \\ 0 & m & 0 & 0 & 0 & mX_{cm} \\ 0 & 0 & m & mY_{cm} & -mX_{cm} & 0 \\ 0 & 0 & mY_{cm} & i_{Edg} & -i_{cp} & 0 \\ 0 & 0 & -mX_{cm} & -i_{cp} & i_{Flp} & 0 \\ -mY_{cm} & mX_{cm} & 0 & 0 & 0 & i_{plr} \end{bmatrix}$$

$$(3.9)$$

where m is the mass density per unit span; X_{cm} and Y_{cm} are the local coordinates of the sectional center of mass, respectively; i_{Edg} and i_{Flp} are the edge and flap mass moments of inertia per unit span, respectively; i_{plr} is the polar moment of inertia per unit span; and i_{cp} is the sectional cross-product of inertia per unit span. It is pointed out that for beam structure, the i_{plr} is given as (although this relationship is not checked by BeamDyn)

$$i_{plr} = i_{Edg} + i_{Flp} (3.10)$$

4 Output Files

BeamDyn produces three types of output files, depending on the options selected: an echo file, a summary file, and a time-series results file. The following sections detail the purpose and contents of these files.

4.1 Echo File

If the user sets the *Echo* flag to TRUE in the BeamDyn primary input file, the contents of this file will be echoed to a file with the naming convention *PrimaryInputFile.ech*. The echo file is helpful for debugging the input files. The contents of an echo file will be truncated if BeamDyn encounters an error while parsing an input file. The error usually corresponds to the line after the last successfully echoed line.

4.2 Summary File

BeamDyn generates a summary file with the naming convention, *PrimaryInputFile.sum* if the *SumPrint* parameter is set to TRUE. This file summarizes key information about the simulation, including:

- Blade mass.
- Blade length.
- Blade center of mass.
- Initial global position vector in BD coordinate system.
- Initial global rotation tensor in BD coordinate system.
- Analysis type.
- Numerical damping coefficient.
- Time step size.
- Maximum number of iterations in the Newton-Ralphson solution.
- Convergence parameter in the stopping criterion.
- Factorization frequency in the Newton-Ralphson solution.
- Numerical integration (quadrature) method.
- FE mesh refinement factor used in trapezoidal quadrature.
- Number of elements.
- Number of FE nodes.
- Initial position vectors of FE nodes in BD coordinate system.
- Initial rotation vectors of FE nodes in BD coordinate system.
- Quadrature point position vectors in BD coordinate system. For Gauss quadrature, the physical coordinates of Gauss points are listed. For trapezoidal quadrature, the physical coordinates of the quadrature points are listed.
- Sectional stiffness and mass matrices at quadrature points in local blade reference coordinate system. These are the data being used in calculations at quadrature points and they can be different from the section in Blade Input File since BeamDyn linearly interpolates the sectional properties into quadrature points based on need.
- Initial displacement vectors in BD coordinate system.

Table 1. Transformation between blade coordinate system and BD coordinate system.

Blade Frame	X_{r0}	Y_{r0}	Z_{r0}
BD Frame	x_2	<i>x</i> ₃	x_1

- Initial rotation displacement vectors in BD coordinate system.
- Initial translational velocity vectors in BD coordinate system.
- Initial angular velocity vectors in BD coordinate system.
- Requested output information.

All the quantities are outputs in this file in the BD coordinate system, the one being used internally in BeamDyn calculations. The initial blade coordinate system, denoted by a subscript r0 that follows the IEC standard, is related to the internal BD coordinate system by Table 1.

4.3 Results File

The BeamDyn time-series results are written to a text-based file with the naming convention *DriverInputFile.out* where *DriverInputFile* is the name of the driver input file when BeamDyn is run in the stand-alone mode. If BeamDyn is coupled to FAST, then FAST will generate a master results file that includes the BeamDyn results. The results in *DriverInputFile.out* are in table format, where each column is a data channel (the first column always being the simulation time), and each row corresponds to a simulation time step. The data channel are specified in the OUTPUT section of the primary input file. The column format of the BeamDyn-generated file is specified using the *OutFmt* parameters of the primary input file.

A	BeamDyn Driver Input File

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Input_5MW.inp"	TipLoad(6)	TipLoad(5)	TipLoad(4)	TipLoad(3)	TipLoad(2)	TipLoad(1)	DistrLoad(6)	DistrLoad(5)	DistrLoad(4)	DistrLoad(3)	DistrLoad(2)	DistrLoad(1)	!	RootVel(6)	RootVel(5)	RootVel(4)		0.0000円+00	1.000E+00	0.000E+00	global frame	lowing 3 by 3	GlbPos(3)	GlbPos(2)	GlbPos(1)	 Gz	GУ	Gx		dt t	t_final	t_initial		s of ro	BEAMDYN V1.00.00
InputFile - Name of the primary input file	- Component c	of concentrated moment vector at blade tip along Y	of concentrated moment vector at blade tip along X	along Z direction	of concentrated force vector at blade tip along Y	- Component of concentrated force vector at blade tip along X direction (N)	Z directio	of distributed moment vector along Y direction	- Component of distributed moment vector along X direction $(N-m/m)$	- Component of distributed force vector along Z direction (N/m)	of distributed force vector al	po		of angular velocity vector of the beam root about Z axis	- Component of angular velocity vector of the beam root about Y axis (rad/s)	- Component of angular velocity vector of the beam root about X axis (rad/s)	ROOT VELOCITY PARAMETER	1.000E+00	0.000E+00	0.000E+00	to reference blade frame	matrix is the direction cosine matrix , GlbDCM(3,3),	Ζ	ition vector of the reference blade frame along ${ m Y}$	- Component of position vector of the reference blade frame along X direction (m)	 - Component of gravity vector along Z direction (m/s^2)	- Component of gravity vector along Y direction (m/s^2)	- Component of gravity vector along X direction (m/s^2)	GRAVITY PARAMETER	- Time increment size (s)	- Ending time of simulation (s)	- Starting time of simulation (s)	SIMULATION CONTROL	ting NREL 5MW	O Driver INPUT FILE

В	BeamDyn	Primary	Input Fi	le: NRE	L 5-MW	Reference	ce Wind	Turbine

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0.000000E+00 0.000000E+00 0.000000E+00 6.884440E+09 0.000000E+00	0.000000E+00 0.000000E+00 3.362955E+01 5.471800E+02 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 8.063160E+09 0.000000E+00	0.000000E+00 0.000000E+00 3.272849E+01 5.937300E+02 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 9.144700E+09 0.000000E+00 0.000000E+00
0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 4.980060E+09 0.0000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 3.516100E+02 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 5.528360E+09 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 4.005300E+02 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 6.309540E+09 0.000000E+00
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00000	0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 4.936840E+0 0.000000E+0	0.000000E+00 0.000000E+00 0.000000E+00 7.009180E+09 0.000000E+00	0.000000E+00 0.000000E+00 4.037290E+09 0.000000E+00 0.000000E+00	0.00000E+00 4.037290E+08 0.000000E+00 0.000000E+00	0.149590 4.037290E+08 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.000000E+00
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0.0000 0.0000 0.0000 0.0000 4.4884	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.933740E+09 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 6.244530E+09 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 3.668340E+09 0.000000E+00 0.000000E+00	0.000000E+00 3.668340E+08 0.000000E+00 0.000000E+00 0.000000E+00	3.668340E+08 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00
	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.159100E+02 0.000000E+02	0.000000E+00 0.000000E+00 1.249266E+02 6.012800E+02 0.0000000E+00 0.0000000E+00	0.000000E+00 0.000000E+00 4.061860E+02 1.249266E+02 0.000000E+00 0.000000E+00	0.000000E+00 4.061860E+02 0.000000E+00 0.0000000E+00 0.000000E+00	.0618 .0000 .0000 .0000 .0000 .2492
	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 3.386520E+09 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 7.081700E+09 0.000000E+00	0.000000E+00 0.000000E+00 4.085970E+09 0.000000E+00 0.000000E+00	0.000000E+00 4.085970E+08 0.000000E+00 0.000000E+00 0.000000E+00	0.198370 4.085970E+08 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00
	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.465700E+02 0.0000000E+00	0.000000E+00 0.000000E+00 9.267993E+01 5.699000E+02 0.0000000E+00	0.000000E+00 0.000000E+00 4.168200E+02 9.267993E+01 0.000000E+00	0.000000E+00 4.168200E+02 0.000000E+00 0.000000E+00 0.000000E+00	4.168200E+02 0.000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 -9.267993E+01
	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 3.949460E+09 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 7.271660E+09 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 4.082350E+09 0.000000E+00 0.000000E+00	0.000000E+00 4.082350E+08 0.000000E+00 0.000000E+00 0.000000E+00	4.082350E 0.000000E+00 0.000000E+00 0.000000E+00

0.263410	3.494770E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	0.247150 3.011580E+08 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	3.528220E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -9.356487E+01	0.230890 3.147760E+08 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	3.814200E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -1.158983E+02
	0.000000E+00 3.494770E+02 0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 3.011580E+08 0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 3.528220E+02 0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 3.147760E+08 0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 3.814200E+02 0.000000E+00 0.000000E+00 0.000000E+00
	0.000000E+00 0.000000E+00 3.494770E+02 9.065783E+01 0.000000E+00	0.000000E+00 0.000000E+00 3.011580E+09 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 3.528220E+02 9.356487E+01 0.000000E+00	0.000000E+00 0.000000E+00 3.147760E+09 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 3.814200E+02 1.158983E+02 0.000000E+00 0.000000E+00
	0.000000E+00 0.000000E+00 9.065783E+01 4.537600E+02 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 4.948490E+09 0.000000E+00	0.000000E+00 0.000000E+00 9.356487E+01 4.687100E+02 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 5.048960E+09 0.000000E+00	0.000000E+00 0.000000E+00 1.158983E+02 5.465600E+02 0.000000E+00
	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.485600E+02 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.388650E+09 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.608400E+02 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.568960E+09 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.871100E+02 0.000000E+00
	-9.065783E+01 0.000000E+00 0.000000E+00 0.000000E+00 6.023200E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 3.113500E+08	-9.356487E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 6.295500E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 3.359200E+08	-1.158983E+02 0.000000E+00 0.000000E+00 0.000000E+00 7.336700E+02

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0.000000E+00	0.00000E+00	0.00000E+00	0.00000E+00	0.00000E+00	0.426020 1.632700E+08
-6.063944E+01 0.000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 3.888100E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 8.024000E+01 0.0000000E+01	0.000000E+00 0.000000E+00 6.063944E+01 3.085700E+02 0.000000E+00	0.000000E+00 0.000000E+00 3.138200E+02 6.063944E+01 0.000000E+00	0.000000E+00 3.138200E+02 0.000000E+00 0.000000E+00 0.000000E+00	3.138200E+02 0.000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 -6.063944E+01
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-6.418549E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 4.293700E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 9.436000E+01 0.0000000E+01	0.000000E+00 0.000000E+00 6.418549E+01 3.350100E+02 0.000000E+00	0.000000E+00 0.000000E+00 3.219900E+02 6.418549E+01 0.000000E+00	0.000000E+00 3.219900E+02 0.000000E+00 0.000000E+00 0.000000E+00	3.219900E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -6.418549E+01
0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.007500E+08	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.588710E+09 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 3.995280E+09 0.000000E+00	0.000000E+00 0.000000E+00 2.146860E+09 0.000000E+00 0.000000E+00	0.000000E+00 2.146860E+08 0.0000000E+00 0.0000000E+00 0.0000000E+00	0.360980 2.146860E+08 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00
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-4.427678E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.864800E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 4.942000E+01 0.0000000E+01	0.000000E+00 0.000000E+00 4.427678E+01 2.370600E+02 0.000000E+00	0.000000E+00 0.000000E+00 2.871200E+02 4.427678E+01 0.000000E+00	0.000000E+00 2.871200E+02 0.000000E+00 0.000000E+00 0.000000E+00	2.871200E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -4.427678E+01
0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.199800E+08	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 8.758000E+08 0.0000000E+08	0.000000E+00 0.000000E+00 0.000000E+00 3.139070E+09 0.000000E+00	0.000000E+00 0.000000E+00 1.432400E+09 0.000000E+00 0.000000E+00	0.000000E+00 1.432400E+08 0.000000E+00 0.000000E+00 0.000000E+00	0.458550 1.432400E+08 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00
-4.419242E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 3.265400E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 6.267000E+01	0.000000E+00 0.000000E+00 4.419242E+01 2.638700E+02 0.000000E+00	0.000000E+00 0.000000E+00 2.947340E+02 4.419242E+01 0.000000E+00	0.000000E+00 2.947340E+02 0.000000E+00 0.000000E+00 0.000000E+00	2.947340E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -4.419242E+01
0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.444700E+08	0.000000E+00 0.000000E+00 0.000000E+00 1.102380E+09 0.000000E+00	0.000000E+00 0.000000E+00 3.447140E+09 0.000000E+00	0.000000E+00 1.632700E+09 0.000000E+00 0.000000E+00	1.632700E+08 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00

0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00 7.608200E+07	0.588620 7.608200E+07 0.000000E+00
-3.391782E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.845900E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.216000E+01 0.000000E+01	0.000000E+00 0.000000E+00 3.391782E+01 1.624300E+02 0.000000E+00	0.000000E+00 0.000000E+00 2.416660E+02 3.391782E+01 0.000000E+00	0.000000E+00 2.416660E+02 0.000000E+00 0.000000E+00 0.000000E+00	2.416660E+02 0.000000E+00 0.0000000E+00 0.000000E+00 0.000000E+00 -3.391782E+01
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0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 5.347200E+08 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 2.554870E+09 0.000000E+00	0.000000E+00 0.000000E+00 1.047430E+09 0.000000E+00 0.000000E+00	0.00000E+00 1.047430E+08 0.000000E+00 0.000000E+00 0.000000E+00	0.523580 1.047430E+08 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00
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-3.124859E+01 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 3.124859E+01	0.000000E+00 0.000000E+00 1.794040E+02	0.000000E+00 1.794040E+02 0.000000E+00	1.794040E+02 0.000000E+00 0.000000E+00
0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.744000E+07	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.758800E+08 0.0000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 1.323360E+09 0.000000E+00	0.000000E+00 0.000000E+00 5.397000E+08 0.000000E+00 0.000000E+00	0.000000E+00 5.397000E+07 0.000000E+00 0.000000E+00 0.000000E+00	0.653660 5.397000E+07 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00
-3.031234E+01 0.000000E+00 0.000000E+00 0.000000E+00 1.296000E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.330000E+01	0.000000E+00 0.000000E+00 3.031234E+01 1.163000E+02 0.0000000E+00	0.000000E+00 0.000000E+00 2.002930E+02 3.031234E+01 0.000000E+00	0.000000E+00 2.002930E+02 0.000000E+00 0.000000E+00 0.000000E+00	2.002930E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -3.031234E+01
0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 3.598000E+07	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 2.386300E+00	0.000000E+00 0.000000E+00 0.000000E+00 1.584100E+09 0.000000E+00	0.000000E+00 0.000000E+00 6.480300E+08 0.000000E+00 0.000000E+00	0.000000E+00 6.480300E+07 0.000000E+00 0.000000E+00 0.000000E+00	0.621150 6.480300E+07 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00
-3.077900E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.521600E+02	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.733000E+01	0.000000E+00 0.000000E+00 3.077900E+01 1.348300E+02 0.000000E+00	0.000000E+00 0.000000E+00 2.206380E+02 3.077900E+01 0.000000E+00	0.000000E+00 2.206380E+02 0.000000E+00 0.000000E+00 0.000000E+00	2.206380E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00
0.000000E+00 0.000000E+00 0.000000E+00 4.592000E+07	0.000000E+00 0.000000E+00 3.145400E+08 0.0000000E+00	0.000000E+00 1.828730E+09 0.000000E+00	7.608200E+08 0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00

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	11 日日日日日 17 + + + -	0.000000E+00 0.000000E+00 4.018083E+01 8.578000E+00	0.000000E+00 0.000000E+00 1.544110E+02 4.018083E+01 0.000000E+00	0.000000E+00 1.544110E+02 0.000000E+00 0.000000E+00	1.544110E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00
0 0 0 0 0 0	0.000000E+ 0.000000E+ 0.000000E+ 1.072600E+ 0.000000E+	0.000000E+00 0.000000E+00 0.000000E+00 1.020160E+09 0.000000E+00	0.000000E+00 0.000000E+00 4.600100E+08 0.000000E+00 0.000000E+00	0.000000E+00 4.600100E+07 0.000000E+00 0.000000E+00 0.000000E+00	0.718700 4.600100E+07 0.000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00
00000	0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 7.300000E+0	0.000000E+00 0.000000E+00 4.114473E+01 9.893000E+01 0.000000E+00	0.000000E+00 0.000000E+00 1.650940E+02 4.114473E+01 0.000000E+00	0.000000E+00 1.650940E+02 0.000000E+00 0.000000E+00 0.000000E+00	1.650940E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -4.114473E+01
00000	0.000000E+ 0.000000E+ 0.000000E+ 1.260100E+	0.000000E+00 0.000000E+00 0.000000E+00 1.183680E+09 0.000000E+00	0.000000E+00 0.000000E+00 5.311500E+08 0.000000E+00 0.000000E+00	0.000000E+00 5.311500E+07 0.000000E+00 0.000000E+00 0.000000E+00	0.686180 5.311500E+07 0.0000000E+00 0.0000000E+00 0.000000E+00 0.000000E+00
000	0.000000E+ 9.960000E+ 0.000000E+	9.798000E+01 0.000000E+00 0.000000E+00	3.124859E+01 0.000000E+00 0.0000000E+00	0.000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 -3.124859E+01

1.072640E+02 0.000000E+00 0.000000E+00	0.816260 2.440400E+07 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00	1.295550E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -2.953206E+01	0.783760 3.288900E+07 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	1.389350E+02 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -3.133540E+01	0.000000E+00 0.000000E+00 0.000000E+00
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0.000000E+00 0.000000E+00 1.072640E+02 2.209638E+01	0.000000E+00 0.000000E+00 2.440400E+08 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 1.295550E+02 2.953206E+01 0.000000E+00	0.000000E+00 0.000000E+00 3.288900E+08 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 1.389350E+02 3.133540E+01 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00
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-2.209638E+01 0.0000000E+00 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 9.070000E+06	-2.953206E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 6.577000E+01	0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 1.453000E+07	-3.133540E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 7.515000E+01	0.000000E+00 0.000000E+00 1.628000E+07

0.897560 1.602500E+07 0.000000E+00 0.000000E+00 0.000000E+00	9.024800E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -2.056210E+01	0.881300 1.815200E+07 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00	9.877600E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -2.139686E+01	0.848780 2.116000E+07 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00	0.000000E+00 -2.209638E+01
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0.000000E+00 0.000000E+00 1.602500E+08 0.000000E+00	0.000000E+00 0.000000E+00 9.024800E+01 2.056210E+01 0.000000E+00	0.000000E+00 0.000000E+00 1.815200E+08 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 9.877600E+01 2.139686E+01 0.000000E+00	0.000000E+00 0.000000E+00 2.116000E+08 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00
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6.877200E+01 0.000000E+00 0.000000E+00 0.000000E+00	0.930080 1.000800E+07 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	7.290600E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -1.080904E+01	0.913820 1.092300E+07 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	8.300100E+01 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 -1.919315E+01	0.000000E+00 0.000000E+00
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0.000000E+00 0.000000E+00 6.877200E+01 1.055375E+01 0.000000E+00	0.000000E+00 0.000000E+00 1.000800E+08 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 7.290600E+01 1.080904E+01 0.000000E+00	0.000000E+00 0.000000E+00 1.092300E+08 0.000000E+00 0.000000E+00	0.000000E+00 0.000000E+00 8.300100E+01 1.919315E+01 0.000000E+00	0.000000E+00 0.000000E+00
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0.954470 5.332000E+06 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+0	5.934000E+01 0.000000E+0 0.000000E+0 5.934000E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0	0.946360 6.323000E+06 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	6.626400E+01 0.000000E+0 0.000000E+0 6.626400E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0 0.000000E+0	0.938210 9.224000E+06 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	-1.055375E+01 0.000000E+0
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	.000000E+0	.000000E+0	.000000E+0	.166900E+0	.000000E+0
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0E+01 0.000000E+00 0.000000	0.00000E	0.000000E+00	5.346274E-01	1.031900E+01	0.000000E+00	0.000000E+00
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0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00	0.00000E	0.00000E+00	0.000000E+00	0.000000E+00	1.145300E+01	0.000000E+00
	-6.169731E	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	1.145300E+01

D BeamDyn List of Output Channels

This is a list of all possible output parameters for the BeamDyn module. The names are grouped by meaning, but can be ordered in the OUTPUTS section of the BeamDyn primary input file as the user sees fit. N β , refers to output node β , where β is a number in the range [1,9], corresponding to entry β in the *OutNd* list. When coupled to FAST, " $B\alpha$ is prefixed to each output name, where α is a number in the range [1,3], corresponding to the blade number. The outputs are expressed in one of the following three coordinate systems:

- r: a floating reference coordinate system fixed to the root of the moving beam; when coupled to FAST for blades, this is equivalent to the IEC blade (b) coordinate system.
- 1: a floating coordinate system local to the deflected beam.
- g: the global inertial frame coordinate system; when coupled to FAST, this is equivalent to FAST's global inertial frame (i) coordinate system.

Channel Name (s)	IInita	Description
Channel Name(s)	Units	Description
RootFxr, RootFyr, RootFzr	(N), (N), (N)	Root reaction forces expressed in r
RootMxr, RootMyr, RootMzr	(N m), (N m), (N m)	Root reaction moments expressed in r
TipTDxr, TipTDyr, TipTDzr	(m), (m), (m)	Tip translational deflection (relative to the undeflected
TipRDxr, TipRDyr, TipRDzr	(-), (-), (-)	position) expressed in r Tip angular/rotational deflection Wiener-Milenković parameter (relative to the undeflected orientation)
TipTVXg, TipTVYg, TipTVZg	(m/s), (m/s), (m/s)	expressed in r Tip translational velocities (absolute) expressed in g
TipRVXg, TipRVYg, TipRVZg	(deg/s), (deg/s), (deg/s)	Tip angular/rotational velocities (absolute) expressed in q
TipTAXg, TipTAYg, TipTAZg	(m/s^2) , (m/s^2) , (m/s^2)	Tip translational accelerations (absolute) expressed in g
TipRAXg, TipRAYg, TipRAZg	(deg/s^2) , (deg/s^2) , (deg/s^2)	Tip angular/rotational accelerations (absolute) expressed in g
NβFxl, NβFyl, NβFzl	(N), (N), (N)	Sectional force resultants at Nß expressed in 1
NβMxl, NβMyl, NβMzl	(N m), (N m), (N m)	Sectional moment resultants at NB expressed in 1
NβTDxr, NβTDyr, NβTDzr	(m), (m), (m)	Sectional translational deflection (relative to the undeflected position) at Nß expressed in r
NβRDxr, NβRDyr, NβRDzr	(-), (-), (-)	Sectional angular/rotational deflection Wiener-Milenković parameter (relative to the undeflected orientation) at Nß expressed in r
ΝβΤΥΧ΄, ΝβΤΥΥ΄ς, ΝβΤΥΖ΄ς	(m/s), (m/s), (m/s)	Sectional translational velocities (absolute) at Nβ expressed in g
ΝβRVXg, ΝβRVYg, ΝβRVZg	(deg/s), (deg/s), (deg/s)	Sectional angular/rotational velocities (absolute) at Nβ expressed in g
ΝβΤΑΧg, ΝβΤΑΥg, ΝβΤΑΖg	(m/s^2) , (m/s^2) , (m/s^2)	Sectional translational accelerations (absolute) at NB expressed in q
ΝβRAXg, ΝβRAYg, ΝβRAZg	(\deg/s^2) , (\deg/s^2) , (\deg/s^2)	Sectional angular/rotational accelerations (absolute) at NB expressed in q
NβPFxl, NβPFyl, NβPFzl	(N), (N), (N)	Applied point forces at Nβ expressed in 1
NβPMxl, NβPMyl, NβPMzl	(N m), (N m), (N m)	Applied point moments at $N\beta$ expressed in 1
NβDFx1, NβDFy1, NβDFz1	(N/m), (N/m), (N/m)	Applied distributed forces at Nβ expressed in 1
NβDMxl, NβDMyl, NβDMzl	(N m/m), (N m/m), (N m/m)	Applied distributed moments at Nβ expressed in 1