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                                                                                                                                                                                                                                                                                                                  kp_xr kp_yr
                                                                                                                                                                                                                                                                                                                                                                                                                                           DEFAULT
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                      quadrature
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 analysis_type
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                                                                                                                                                                                                                                                                                                                                                                                           stop_tol
                                                                                                                                                                                                                                                                                                                                                                                                              NRMax
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             18.200925
                                                                                                                                                                                                                                                                                                                 initial_twist
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    SIMULATION CONTROL
20.200290
                             16.199715
                                          15.199725
                                                         14.199735
                                                                         13.200975
                                                                                       12.199755
                                                                                                      11.199765
                                                                                                                     10.199775
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                                                                                                                                                                                                                                                          ..199865
                                                                                                                                                                                                                                                                                                                                  - Member number; Number of key points in this member
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      - Numerical Damping Parameter for Generalized-alpha integrator (-)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   Echo input data to "<RootName>.ech" (flag)
                                                                                                                                                                                                                                                                                                                                                Total number of key points (-)
                                                                                                                                                                                                                                                                                                                                                                Total number of members (-)
                                                                                                                                                                                                                                                                                                                                                                                             Tolerance for stopping criterion (-) DEFAULT = 1.0E-5
                                                                                                                                                                                                                                                                                                                                                                                                            Max number of iterations in Newton-Ralphson algorithm (-). DEFAULT
                                                                                                                                                                                                                                                                                                                                                                                                                          Time step size (s). DEFAULT = glue/driver code time step
                                                                                                                                                                                                                                                                                                                                                                                                                                        Factorization frequency (-). DEFAULT = 5
                                                                                                                                                                                                                                                                                                                                                                                                                                                        Refinement factor for quadrature 2 (-). DEFAULT =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                       1: Gauss; 2: Trapezoidal (switch)
              10.232000
                             10.792000
                                           11.072000
                                                         11.561000
                                                                         12.192000
                                                                                       12.848000
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200
 5.0E+5
              2.0E+7
                                                                  "5MW_Blade_IEC.inp"
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                                          UsePitchAct -
                                                                                               order_elem
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                                                                   BldFile - Name of file containing properties for blade (quoted string)
                 1
                                                        PITCH ACTUATOR PARAMETERS
                                                                                    MATERIAL PARAMETER -----
                                                                                                               MESH PARAMETER ----
                                                                                                                                                         60.699885
                                                                                                                                                                                                                                                                                                                              50.199990
                                                                                                                                                                                                                                                                                                                                            48.201240
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                                          Whether a pitch actuator should be used (flag)
             Pitch actuator stiffness (kg-m^2/s^2) [used only when UsePitchAct is true]
                            Pitch actuator inertia (kg-m^2) [used only when UsePitchAct is true]
Pitch actuator damping (kg-m^2/s) [used only when UsePitchAct is true]
                                                                                                - Order of interpolation (basis) function (-)
                                                                                                                              0.000000
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"ES10.3E2" True SumPrint OutFmt OUTPUTS -- Print summary data to "<RootName>.sum" (flag) - Format used for text tabular output, excluding the time channel.

1, 3 NNodeOuts OutNd - Number of nodes to output to file [0 - 9] (-) - Nodes whose values will be output (-)

OutListParameters.xlsx. OutList ı The next line(s) contains a list of output parameters.

"Rootfxr, Rootfyr, Rootfzr"
"RootMxr, RootMyr, RootMzr"
"N1fxl,N1fyl,N1fzl"
"N1Mxl,N1Myl,N1Mzl"
"TipTDxr, TipTDyr, TipTDzr"
"TipRDxr, TipRDyr, TipRDzr"

END of input file (the word "END" must appear in the first 3 columns of this last OutList line)