00000 0.0 0.0 0.0 0.0 0.0 0.0 0.0 -9.8 0.0 30.0 2E-03 0.000E+00 0.000E+00 1.0 Dynamic 1.0006 1.000E+00 "BeamDyn_Input_5MW.inp" ---The following 3 by 3 --relates analysis of rotating NREL 5MW blade under gravity force global frame TipLoad(4)
TipLoad(5) TipLoad(2) RootVel(6) RootVel(4) Z S A S GX TipLoad(6) TipLoad(3) DistrLoad(1) GlbPos(2) t_initial TipLoad(1)DistrLoad(6) DistrLoad(5 DistrLoad(4) DistrLoad(3) DistrLoad(2) RootVel(5) GlbPos(3) GlbPos(1) final 0.000E+00 1.000E+00 0.000E+00 SIMULATION CONTROL -----APPLIED FORCE ROOT VELOCITY PARAMETER --FRAME PARAMETER ----GRAVITY PARAMETER ----PRIMARY INPUT FILE ---matrix is the direction cosine matrix, GlbDCM(3,3), to reference blade frame - Component of distributed 0.000E+00 0.000E+00 - Component of position vector of the reference blade - Component of position vector of the reference blade frame along \boldsymbol{X} direction - Component of gravity vector along Y direction (m/s^2) - Component of gravity vector along Z direction (m/s^2) - Starting time of simulation - Component 1.000E+00 - Component of angular velocity vector of the beam root about ${\tt Z}$ - Component of angular velocity vector of the beam root about ${\tt Y}$ Component of concentrated force vector at blade tip along X direction Component Component of distributed moment vector along Y direction (N-m/m) Component Component of distributed force vector along Z direction (N/m) Component Component of position vector of Component of gravity vector Time increment size Ending time of simulation Component Component Component Component Component of angular velocity vector of the beam root about X axis of concentrated moment vector at blade tip along Z direction of concentrated force vector at blade tip along Z direction of concentrated moment vector at blade tip along of concentrated moment vector at blade tip along X direction of concentrated force vector at blade tip along Y direction of distributed moment vector along Z direction (N-m/m) of distributed of distributed Name of the primary input file moment vector along X direction (N-m/m) force vector along X direction (N/m) force vector along along X direction (s) (s) the reference blade Y direction (m/s^2) (m/s^2) frame along frame along Y direction (N/m) Y direction axıs axis N direction (rad/s) (rad/s) (rad/s) (Z) (Z) (N) (N-m) (N-m) (H) (H) (m)

BEAMDYN V1.00.00 Driver INPUT FILE -