# Cache Memories: Why Programmers Need to Know!

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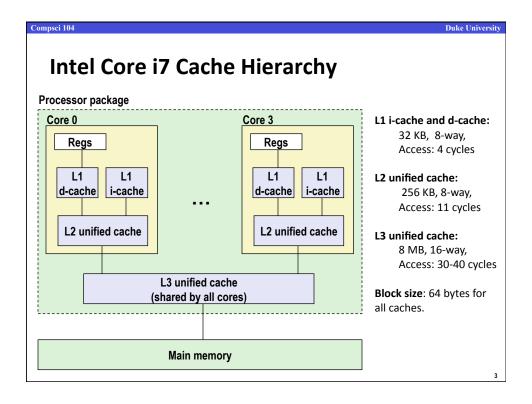
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### **Administrative**

- Homework #6 Due April 11
- Y86 Simulator- groups of two (email me group members)
  - Start this ASAP, get questions out of the way.

### **Today**

- Performance impact of caches
  - Rearranging loops to improve spatial locality
  - Using blocking to improve temporal locality
  - Data layout changes to improve locality



Compsci 104 **Duke University Cache Performance Metrics** Miss Rate Fraction of memory references not found in cache (misses / accesses) = 1 - hit rate Typical numbers (in percentages): • 3-10% for L1 • can be quite small (e.g., < 1%) for L2, depending on size, etc. • Time to deliver a line in the cache to the processor • includes time to determine whether the line is in the cache Typical numbers: • 1-2 clock cycle for L1 • 5-20 clock cycles for L2 Miss Penalty Additional time required because of a miss typically 50-200 cycles for main memory (Trend: increasing!)

### **Cache Performance**

CPU time = (CPU execution clock cycles + Memory stall clock cycles) x clock cycle time

Memory stall clock cycles = Memory accesses x Miss rate x Miss penalty

### Example

- Assume every instruction takes 1 cycle
- Miss penalty = 20 cycles
- Miss rate = 10%
- 1000 total instructions, 300 memory accesses
- Memory stall cycles? CPU clocks?

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### **Cache Performance**

- Memory Stall cycles = 300 \* 0.10 \* 20 = 600
- CPUclocks = 1000 + 600 = 1600
- 60% slower because of cache misses!
- Change miss penalty to 100 cycles
- CPUclocks = 1000 + 3000 = 4000 cycles

## **Writing Cache Friendly Code**

- Make the common case go fast
  - Focus on the inner loops of the core functions
- Minimize the misses in the inner loops
  - Repeated references to variables are good (temporal locality)
  - Stride-1 reference patterns are good (spatial locality)

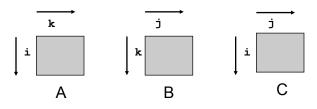
Key idea: Our qualitative notion of locality is quantified through our understanding of cache memories.

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### **Miss Rate Analysis for Matrix Multiply**

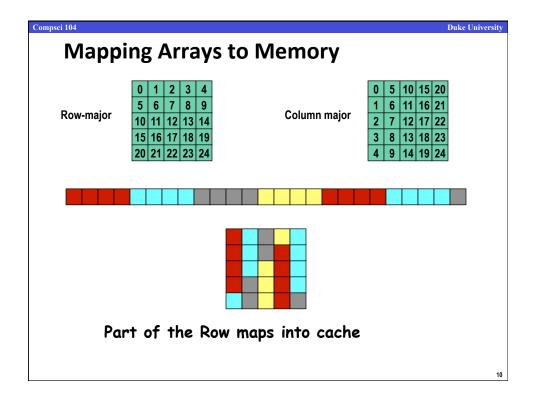
- Assume:
  - Line size = 32B (big enough for four 64-bit words)
  - Matrix dimension (N) is very large
    - Approximate 1/N as 0.0
  - Cache is not even big enough to hold multiple rows
- Analysis Method:
  - Look at access pattern of inner loop



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  Matrix Multiplication Example
                                                            Variable sum
   Description:
                                   /* ijk */
                                                           held in register
       Multiply N x N matrices
                                   for (i=0; i<n; i++)
                                     for (j=0; j<n; j++) {

    O(N³) total operations

                                        sum = 0.0; \leftarrow
       N reads per source
                                        for (k=0; k< n; k++)
         element
                                          sum += a[i][k] * b[k][j];
       N values summed per
                                       c[i][j] = sum;
         destination
          but may be able to
            hold in register
```



# **Layout of C Arrays in Memory (review)**

- C arrays allocated in row-major order
  - each row in contiguous memory locations
- Stepping through columns in one row:
  - for (i = 0; i < N; i++)
    sum += a[0][i];</pre>
  - accesses successive elements
  - if block size (B) > 4 bytes, exploit spatial locality
    - compulsory miss rate = 4 bytes / B
- Stepping through rows in one column:
  - for (i = 0; i < n; i++)
    sum += a[i][0];</pre>
  - accesses distant elements
  - no spatial locality!

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compulsory miss rate = 1 (i.e. 100%)

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# Matrix Multiplication (ijk)

```
/* ijk */
for (i=0; i<n; i++) {
  for (j=0; j<n; j++) {
    sum = 0.0;
    for (k=0; k<n; k++)
        sum += a[i][k] * b[k][j];
    c[i][j] = sum;
}
</pre>
```

Inner loop:

(i,\*)

(i,\*)

(i,j)

A

B

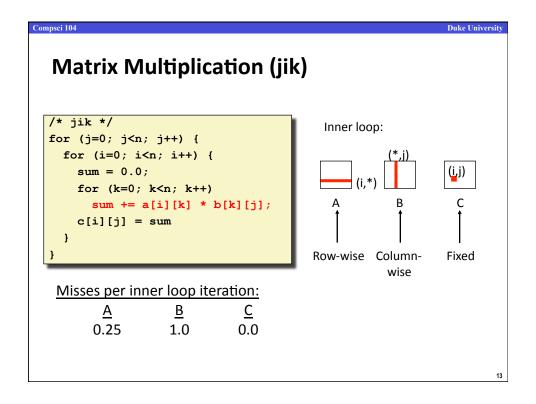
C

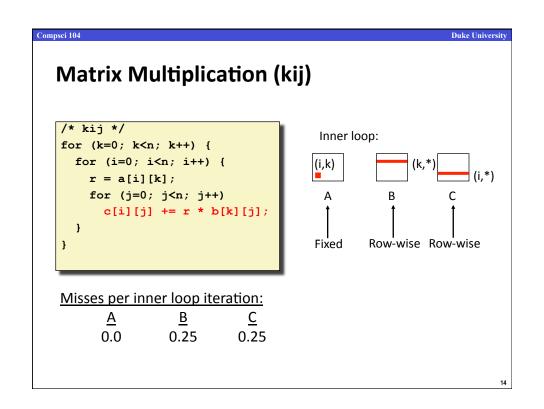
Row-wise

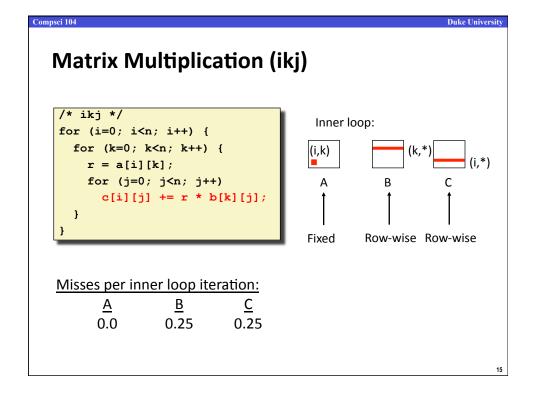
Column
wise

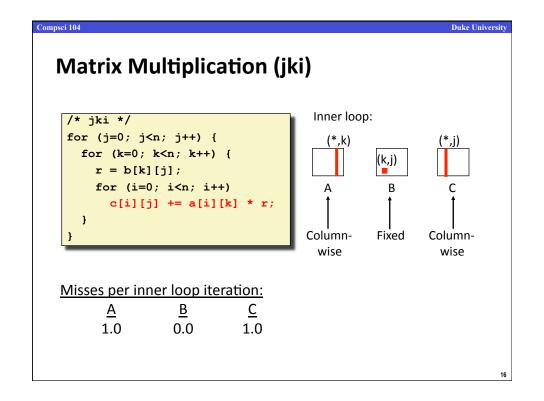
### Misses per inner loop iteration:

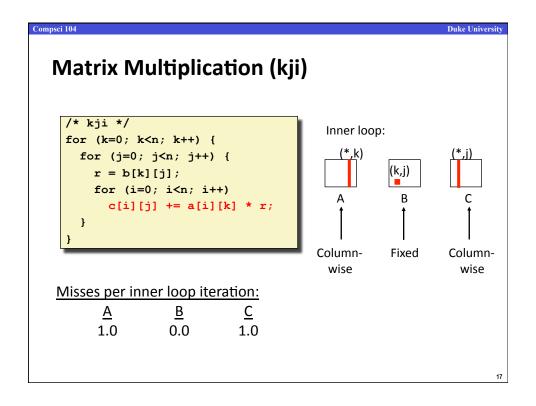
<u>A</u> <u>B</u> <u>C</u> 0.25 1.0 0.0



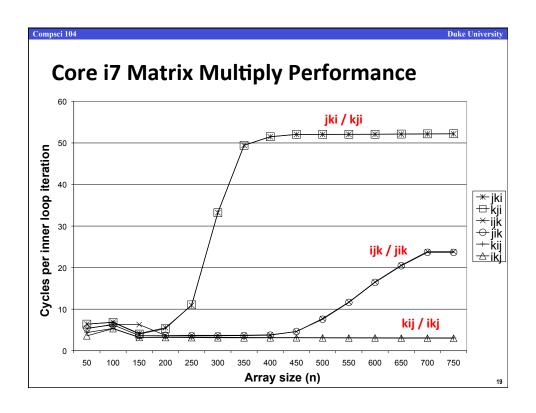








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   Summary of Matrix Multiplication
           for (i=0; i<n; i++) {
             for (j=0; j<n; j++) {
                                                   ijk (& jik):
              sum = 0.0;
                                                    • 2 loads, 0 stores
              for (k=0; k< n; k++)
                                                    • misses/iter = 1.25
                sum += a[i][k] * b[k][j];
              c[i][j] = sum;
            }
           for (k=0; k< n; k++) {
                                                   kij (& ikj):
            for (i=0; i<n; i++) {
                                                    • 2 loads, 1 store
             r = a[i][k];
             for (j=0; j<n; j++)
                                                    • misses/iter = 0.5
              c[i][j] += r * b[k][j];
           for (j=0; j<n; j++) {
                                                   jki (& kji):
            for (k=0; k<n; k++) {
                                                    • 2 loads, 1 store
              r = b[k][j];
              for (i=0; i<n; i++)
                                                    • misses/iter = 2.0
               c[i][j] += a[i][k] * r;
            }
```



# Improving Data Cache Performance

### Instruction Sequencing

- Loop Interchange: change nesting of loops to access data in order stored in memory (ijk vs kij, etc.)
- Loop Fusion: Combine 2 independent loops that have same looping and some variables overlap
- Blocking: Improve temporal locality by accessing "blocks" of data repeatedly vs. going down entire columns or rows

### Data Layout

- Merging Arrays: Improve spatial locality by single array of compound elements vs. 2 separate arrays
- Nonlinear Array Layout: Mapping 2 dimensional arrays to the linear address space
- Pointer-based Data Structures: node-allocation

**Loop Fusion Example** 

```
/* Before */
for (i = 0; i < N; i = i+1)
    for (j = 0; j < N; j = j+1)
        a[i][j] = 1/b[i][j] * c[i][j];
for (i = 0; i < N; i = i+1)
    for (j = 0; j < N; j = j+1)
        d[i][j] = a[i][j] + c[i][j];
/* After */
for (i = 0; i < N; i = i+1)
    for (j = 0; j < N; j = j+1)
    {
        a[i][j] = 1/b[i][j] * c[i][j];
        d[i][j] = a[i][j] + c[i][j];
}</pre>
```

2 misses per access to a & c vs. one miss per access

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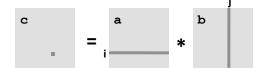
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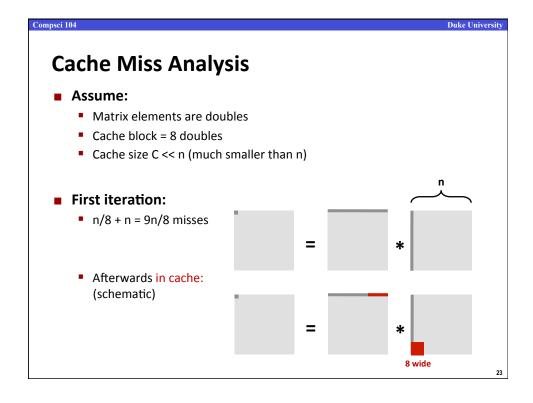
# **Example: Matrix Multiplication**

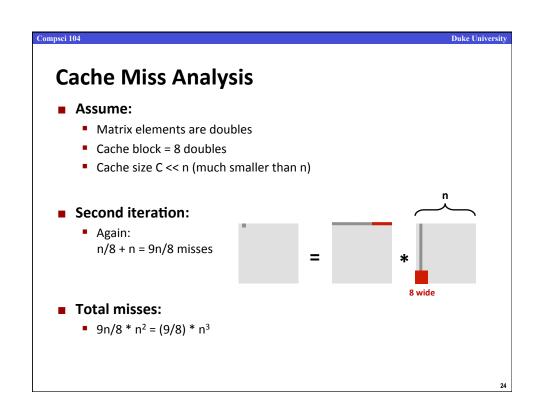
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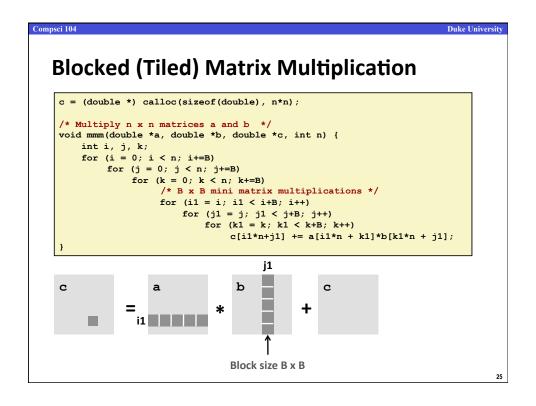
```
c = (double *) calloc(sizeof(double), n*n);

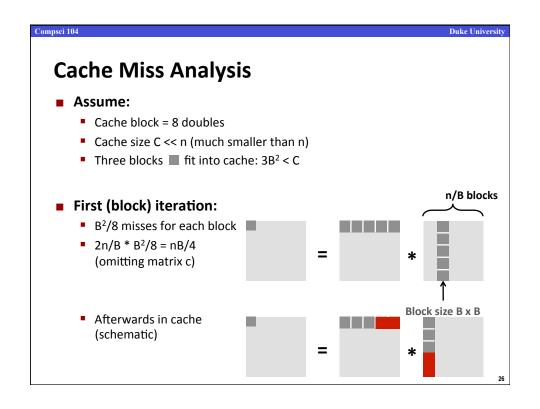
/* Multiply n x n matrices a and b */
void mmm(double *a, double *b, double *c, int n) {
   int i, j, k;
   for (i = 0; i < n; i++)
        for (j = 0; j < n; j++)
        for (k = 0; k < n; k++)
        c[i*n+j] += a[i*n + k]*b[k*n + j];
}</pre>
```

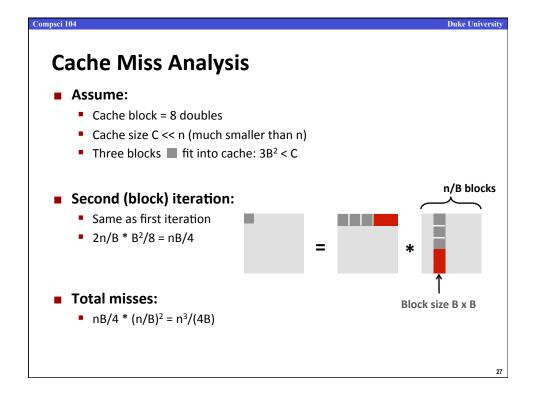






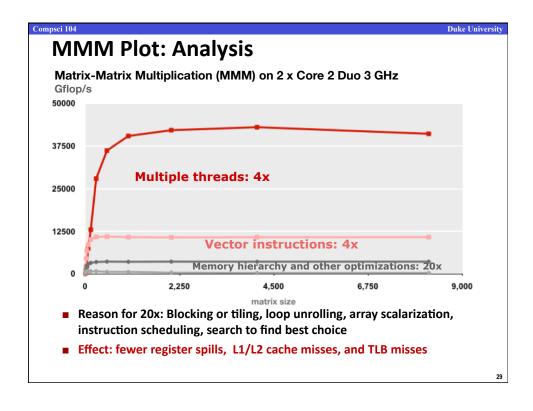






### **Summary**

- No blocking: (9/8) \* n³
- Blocking: 1/(4B) \* n<sup>3</sup>
- Suggest largest possible block size B, but limit 3B² < C!
- Reason for dramatic difference:
  - Matrix multiplication has inherent temporal locality:
    - Input data: 3n<sup>2</sup>, computation 2n<sup>3</sup>
    - Every array elements used O(n) times!
  - But program has to be written properly



Data Layout Optimizations

So far program control
Changes the order in which memory is accessed

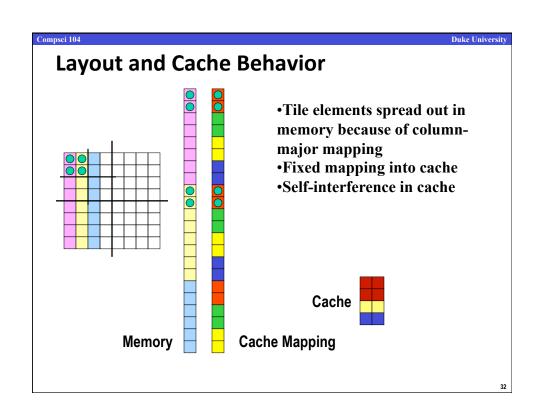
We can also change the way our data structures map to memory
2-dimensional array
Pointer-based data structures

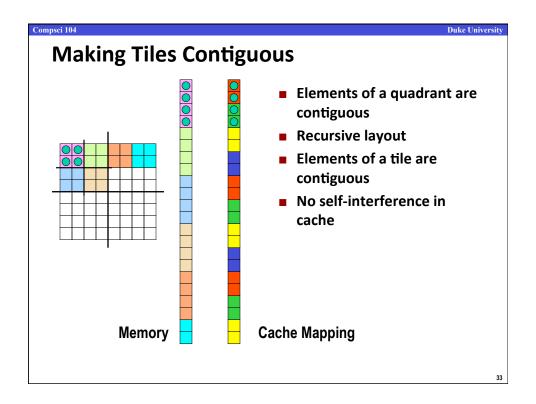
```
Merging Arrays Example

/* Before */
int val[SIZE];
int key[SIZE];

/* After */
struct merge {
   int val;
   int key;
  };
  struct merge merged_array[SIZE];

Reducing conflicts between val & key
```





### **Pointer-based Data Structures**

- Linked List, Binary Tree
- Basic idea is to group linked elements close together in memory
- Need relatively static traversal pattern
- Or could do it during garbage collection/compaction

### **Reducing I-Cache Misses by Compiler Optimizations**

### Instructions

- Reorder procedures in memory to reduce misses
- Profiling to look at conflicts

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# **Concluding Observations**

- Programmer can optimize for cache performance
  - How data structures are organized
  - How data are accessed
    - Nested loop structure
    - Blocking (tiling) is a general technique
- All systems favor "cache friendly code"
  - Getting absolute optimum performance is very platform specific
    - Cache sizes, line sizes, associativities, etc.
  - Can get most of the advantage with generic code
    - Keep working set reasonably small (temporal locality)
    - Use small strides (spatial locality)

# **Cache Memory Summary**

- Cost Effective Memory Hierarchy
- Work by exploiting locality (temporal & spatial)
- Associativity, Blocksize, Capacity (ABCs of caches)
- Know how a cache works
  - Break address into tag, index, block offset
- Know how to draw a block diagram of a cache
- CPU cycles/time, Memory Stall Cycles
- Your programs and cache performance

### **Next Time**

**■** Exceptions and Interrupts