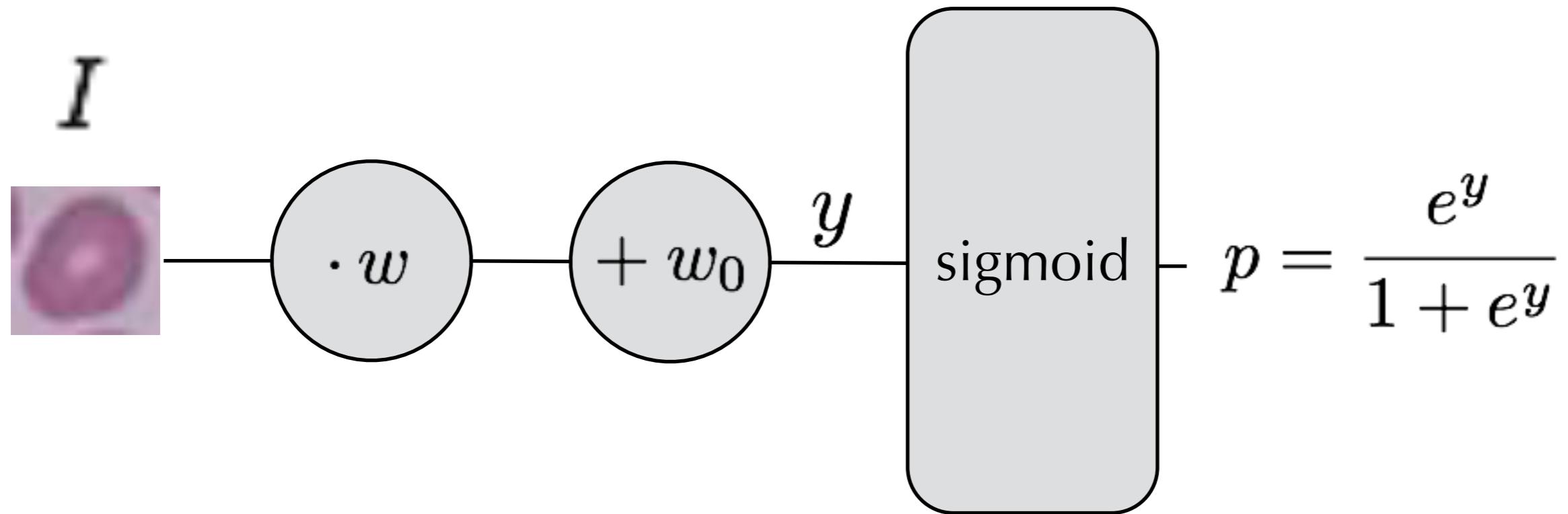


SSY097 - Image Analysis

Lecture 5 - (Convolutional) Neural Networks

*Torsten Sattler
(slides adapted from Olof Enqvist)*

Last Lecture



Learning linear classifiers

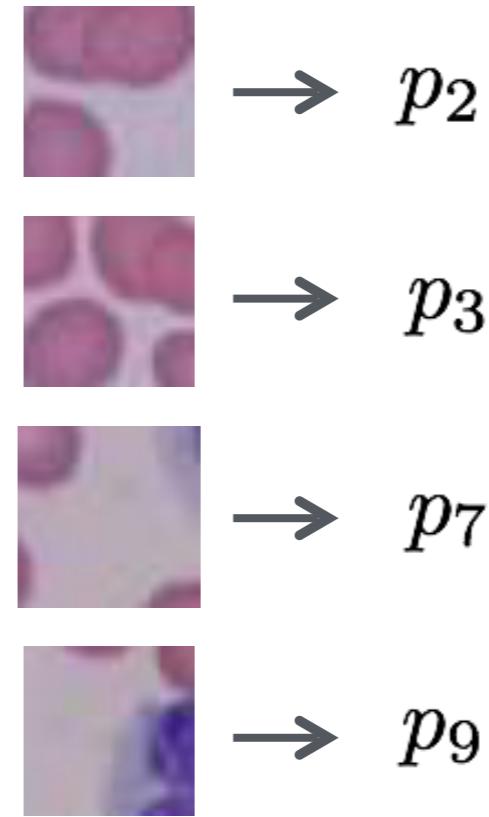
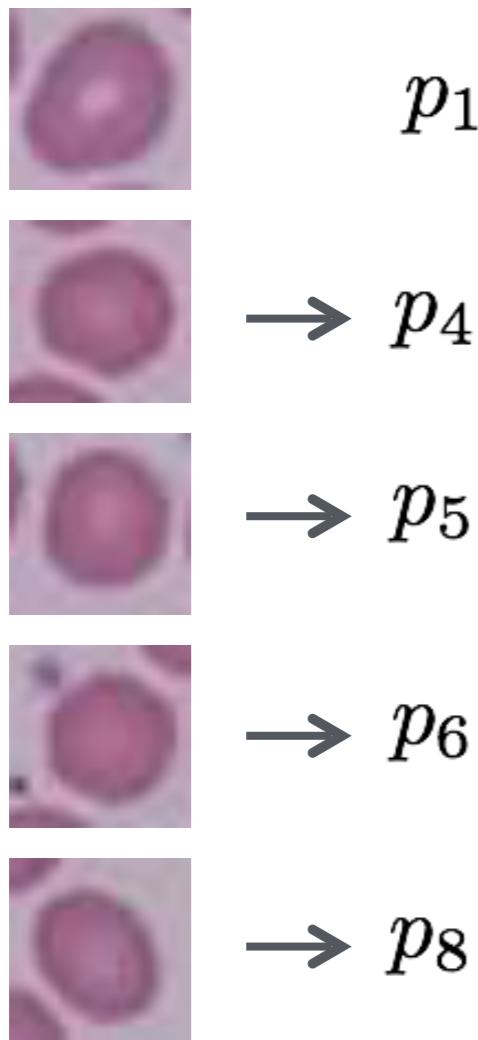
Last Lecture

7210414959
0690159734
9665407401
3134727121
1742351244
6355604195
7893746430
7029173297
7627847361
3693141769

$$p_k = \frac{e^{y_k}}{\sum_{m=0}^n e^{y_m}}$$

Softmax function for multi-class classification

Last Lecture

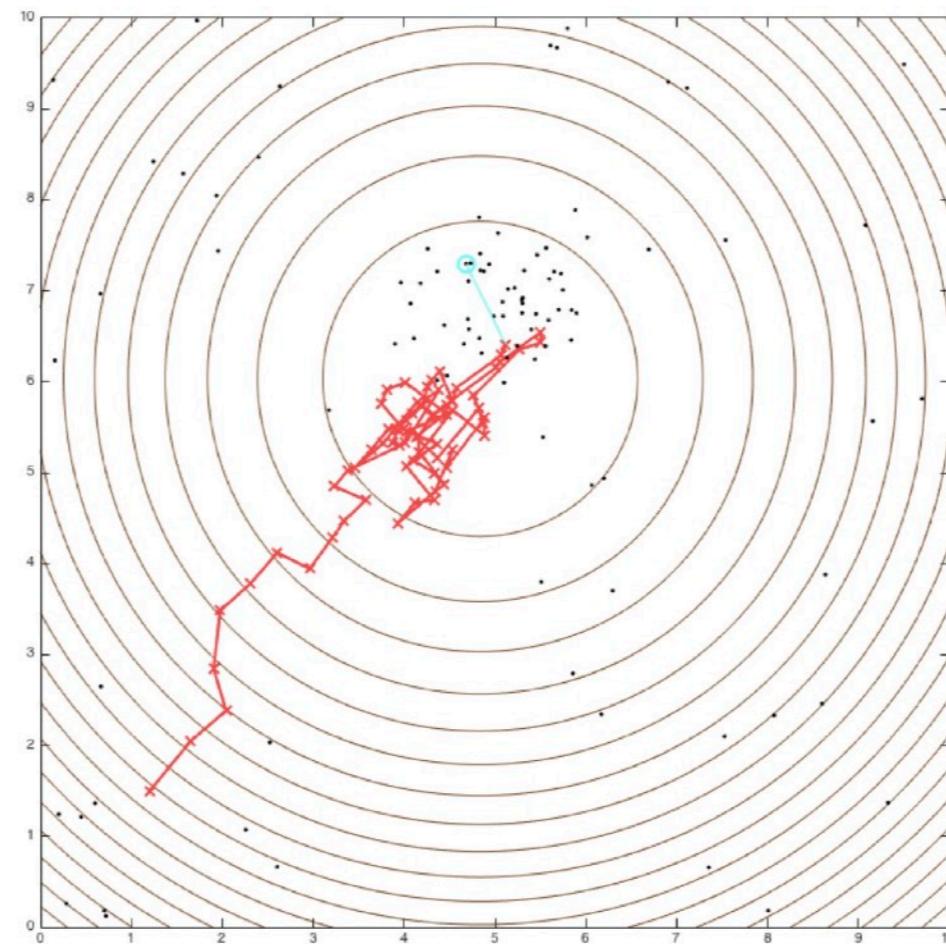


$$-\left(\sum_{\text{positive examples}} \ln p_i + \sum_{\text{negative examples}} \ln (1 - p_i) \right)$$

Loss function: Negative Log-Likelihood

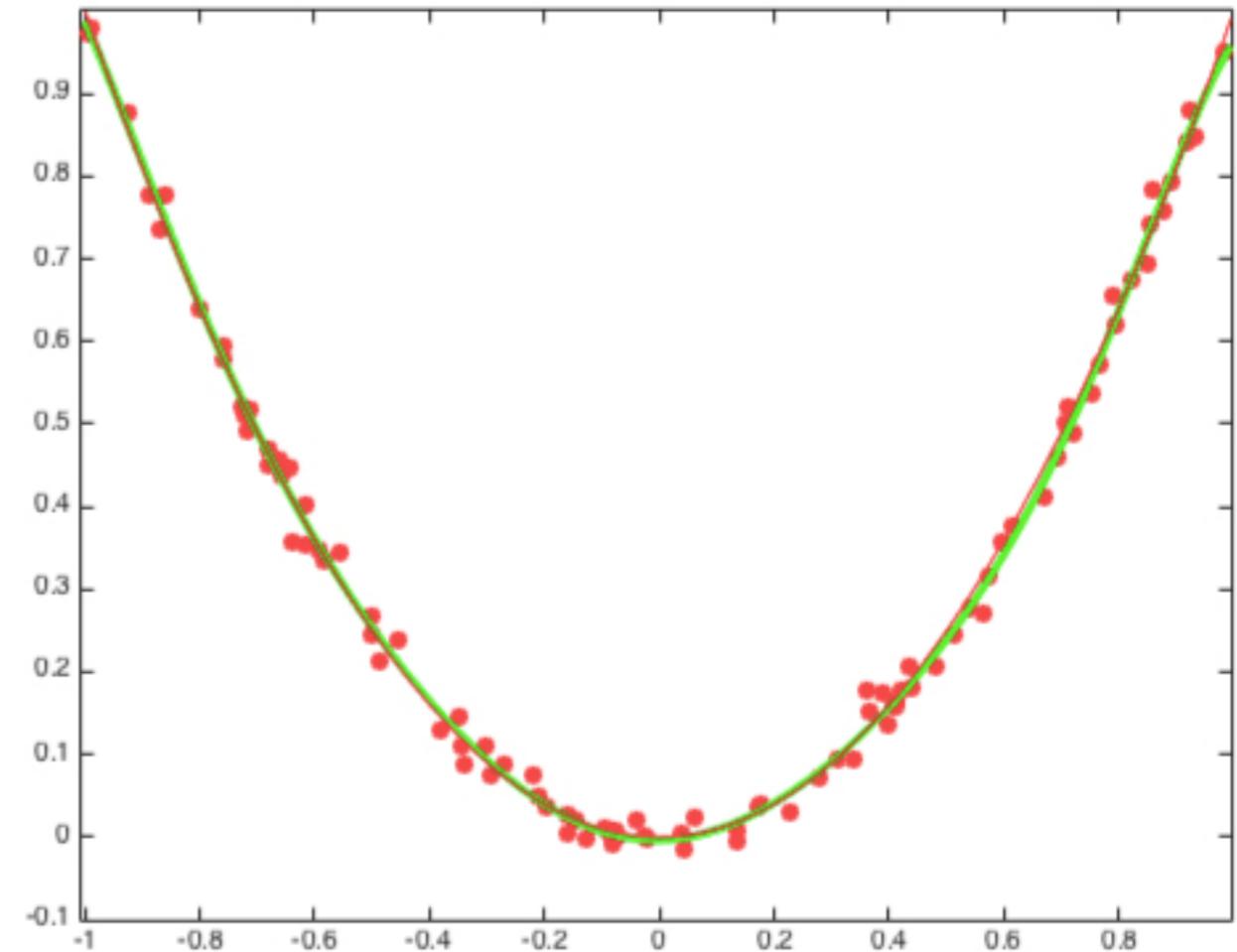
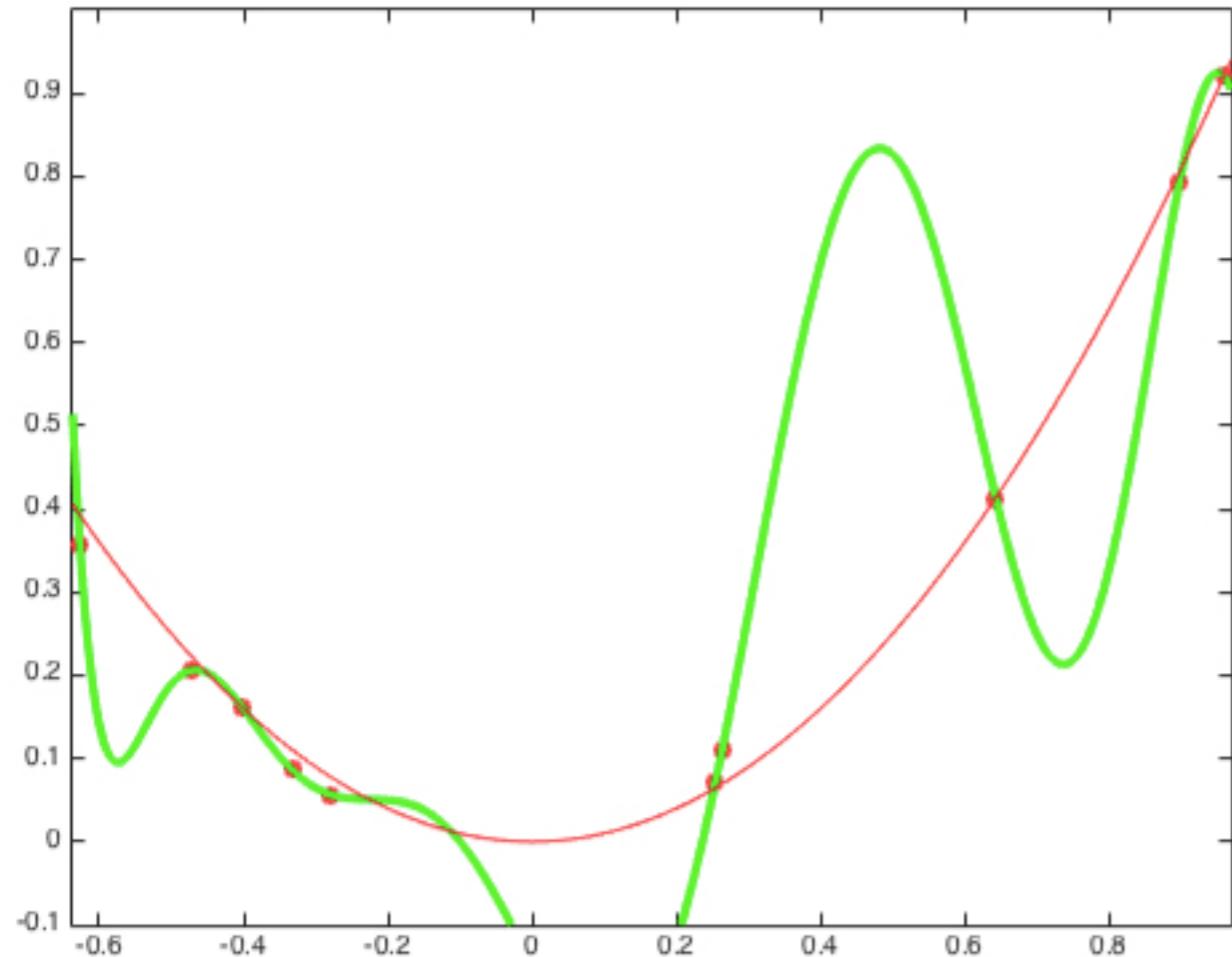
Last Lecture

$$\theta^{(k+1)} = \theta^{(k)} - \mu \sum_i \nabla L_i(\theta) \approx \theta^{(k)} - \mu \nabla L_i(\theta)$$



Stochastic Gradient Descent (with Momentum)

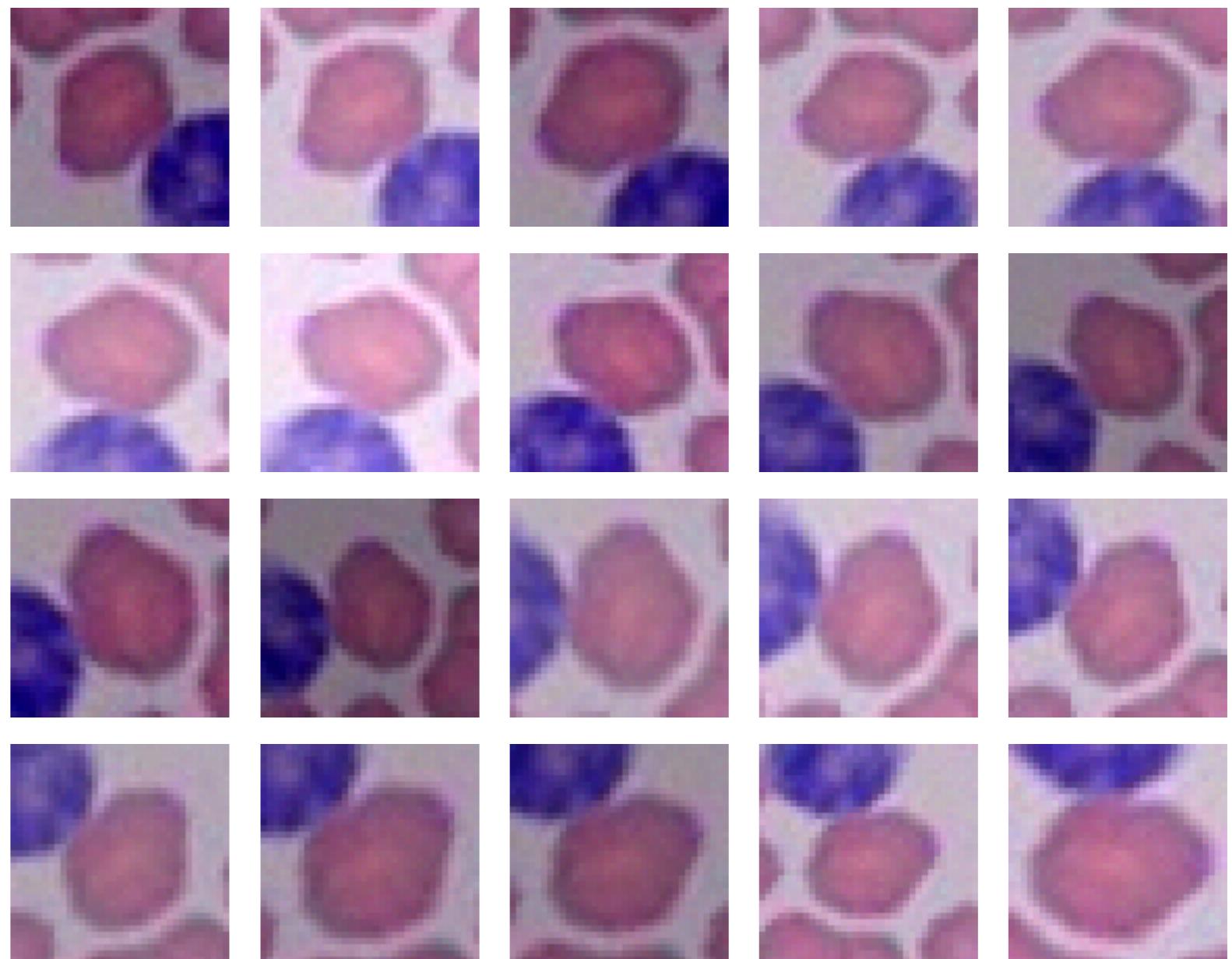
Last Lecture



Overfitting

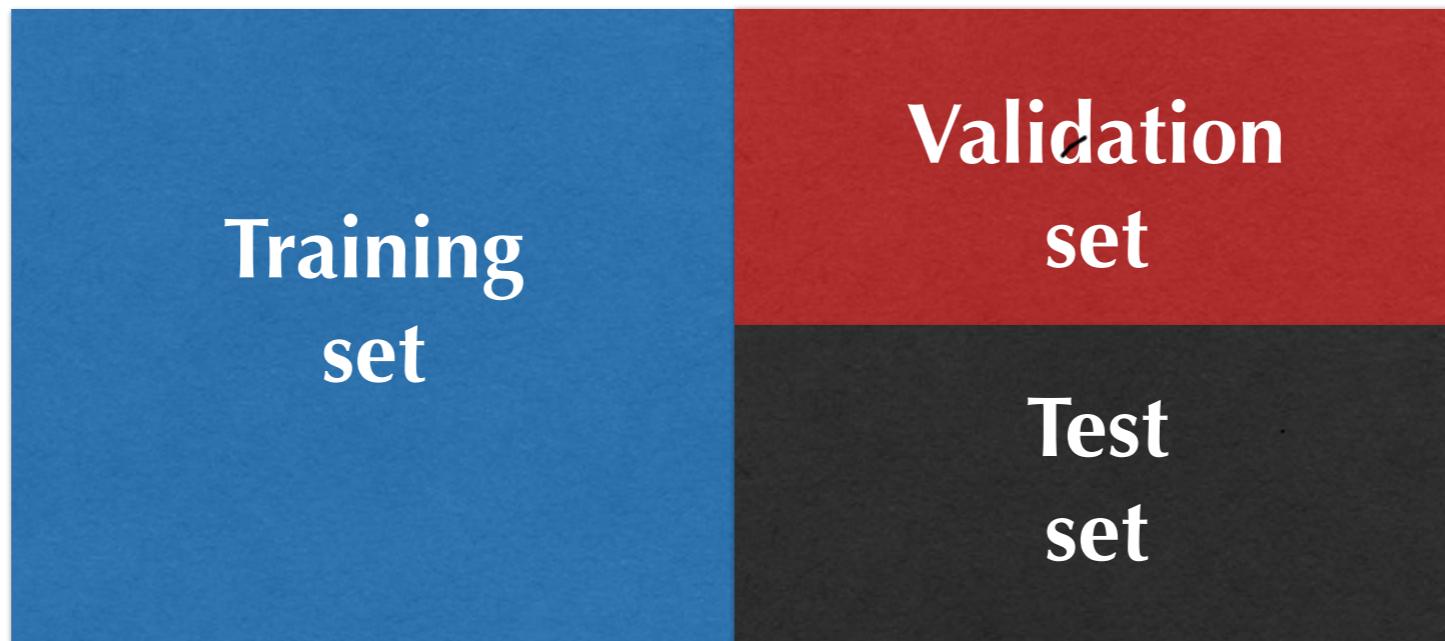
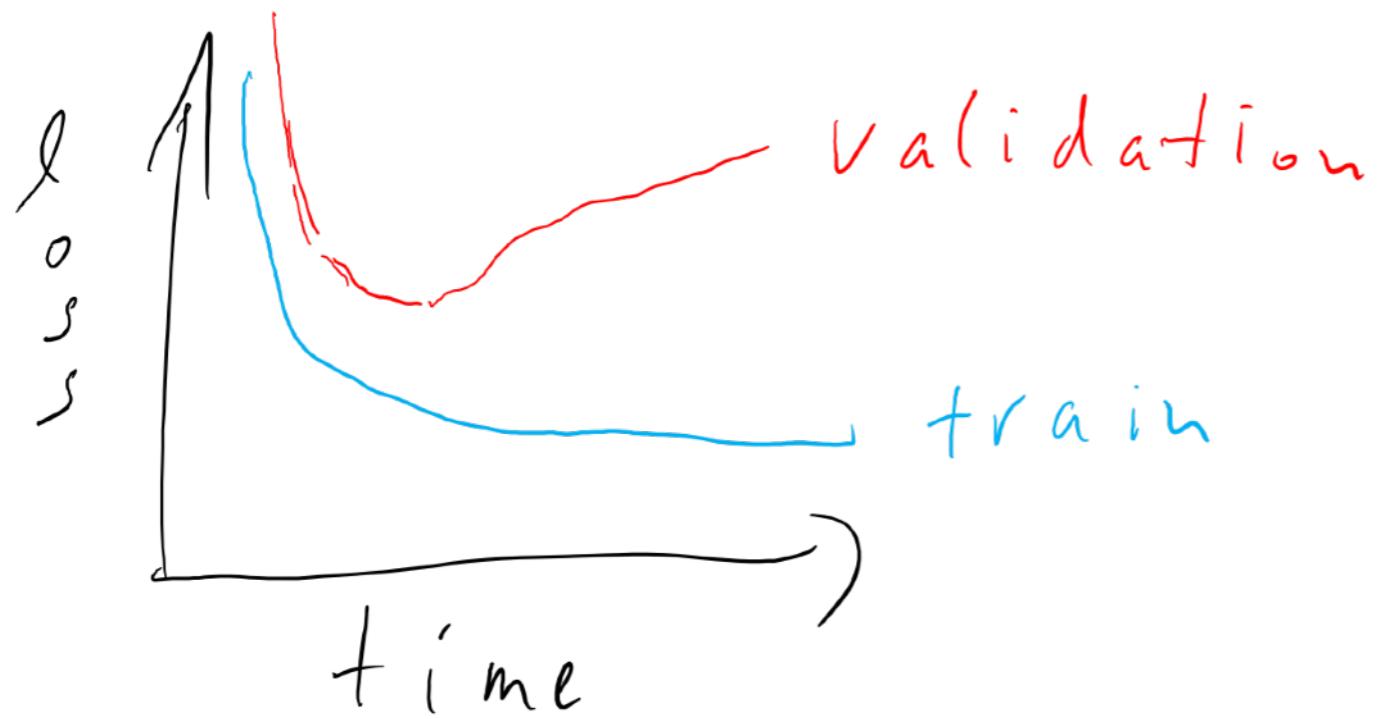
Last Lecture

- Rotate
- Scale
- Change brightness
- Add noise



Data augmentation

Last Lecture



Training, validation, test sets

Today

- Neural Networks
- Optimization: Backpropagation
- Convolutional Neural Networks
- Overfitting, Part II

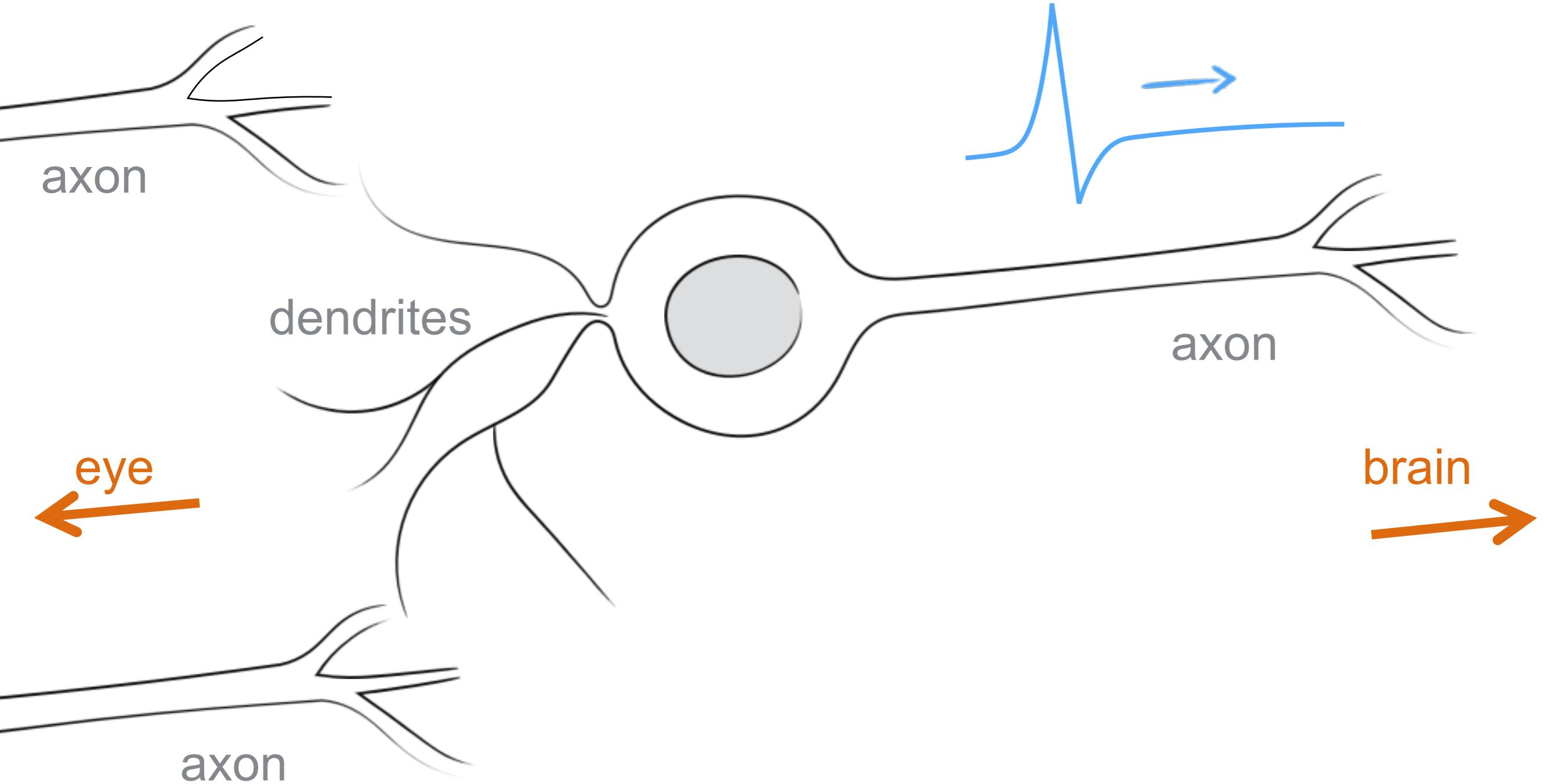
Neural Networks

Recognition Revisited

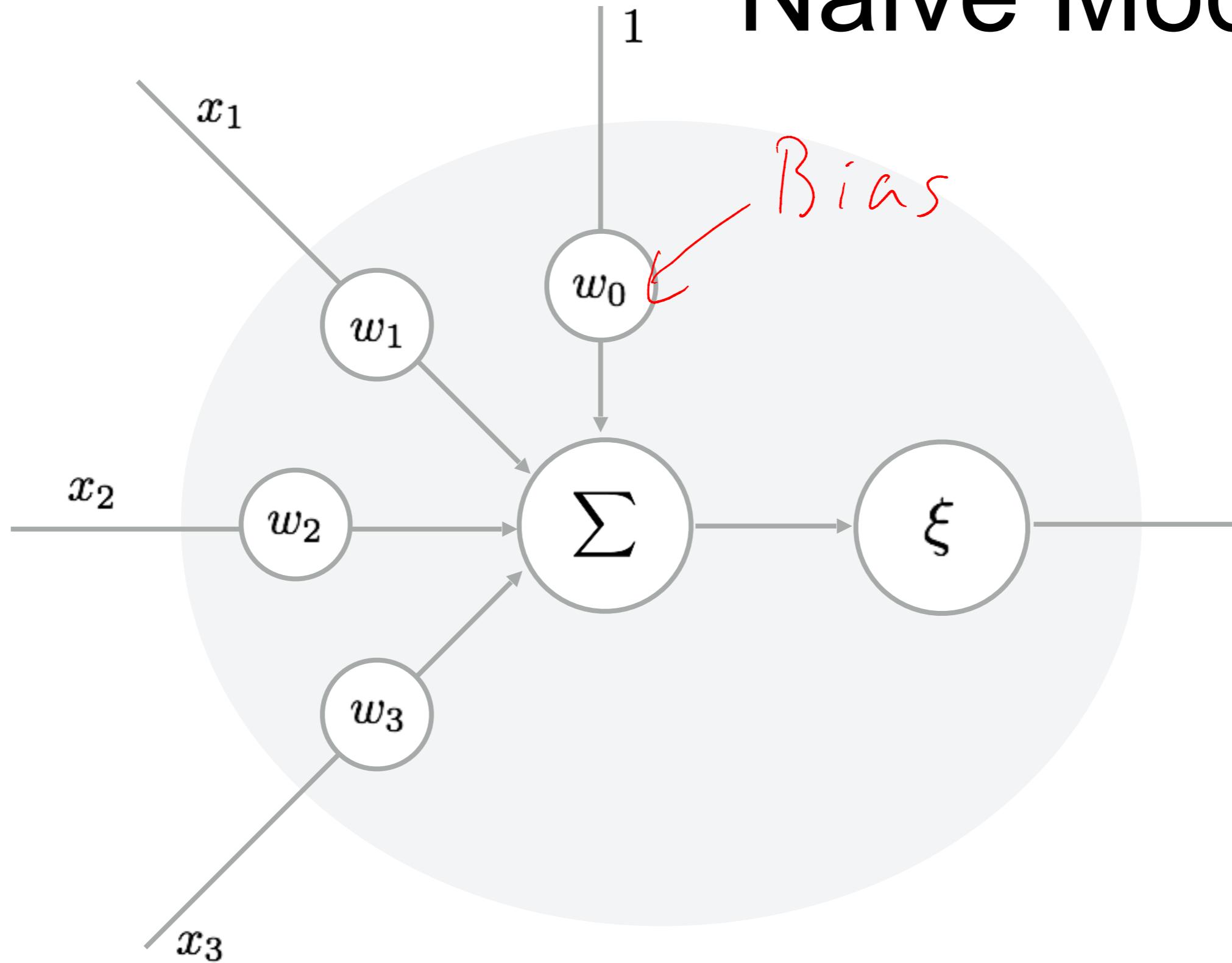


Is there a robin in this image?

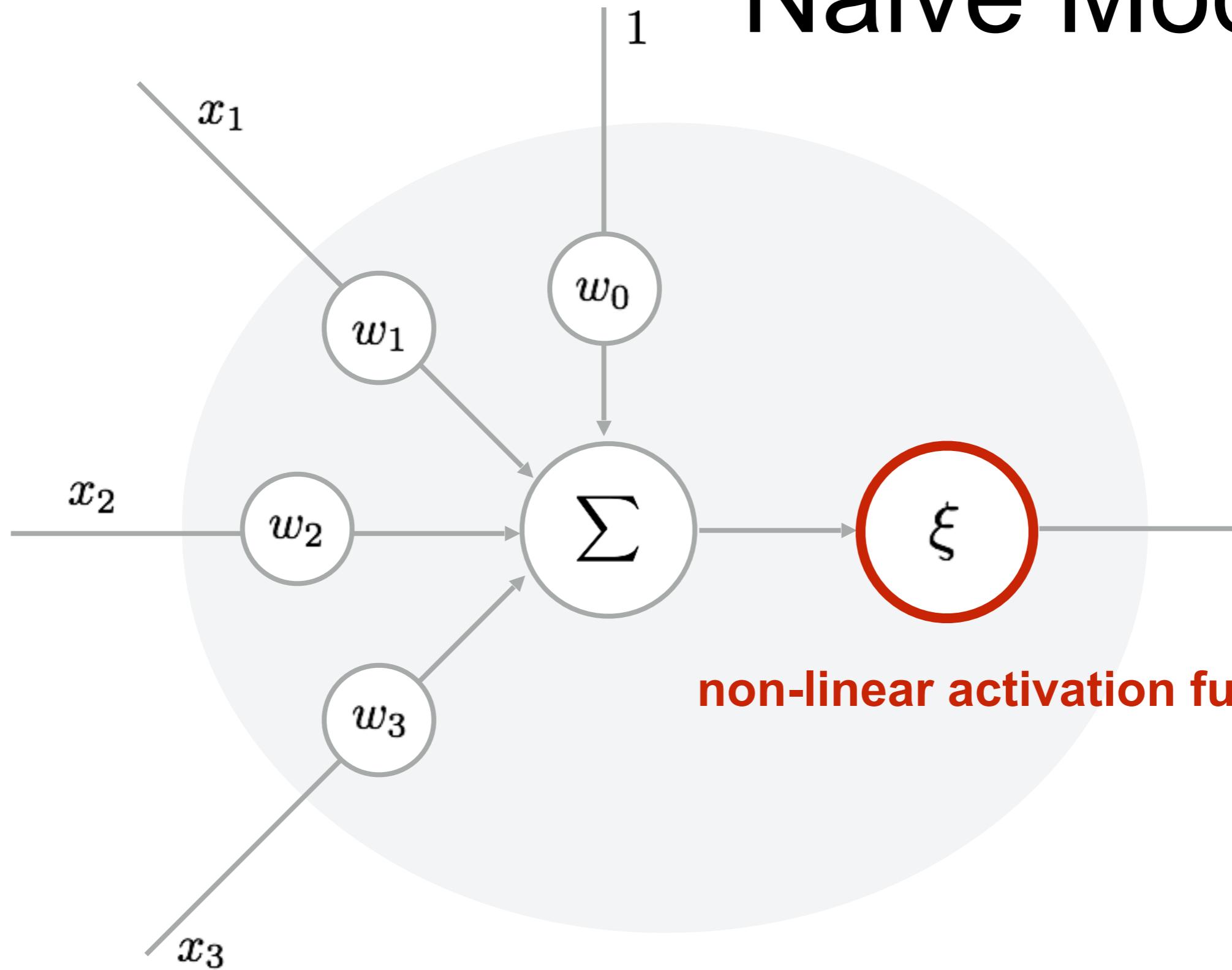
A Neuron



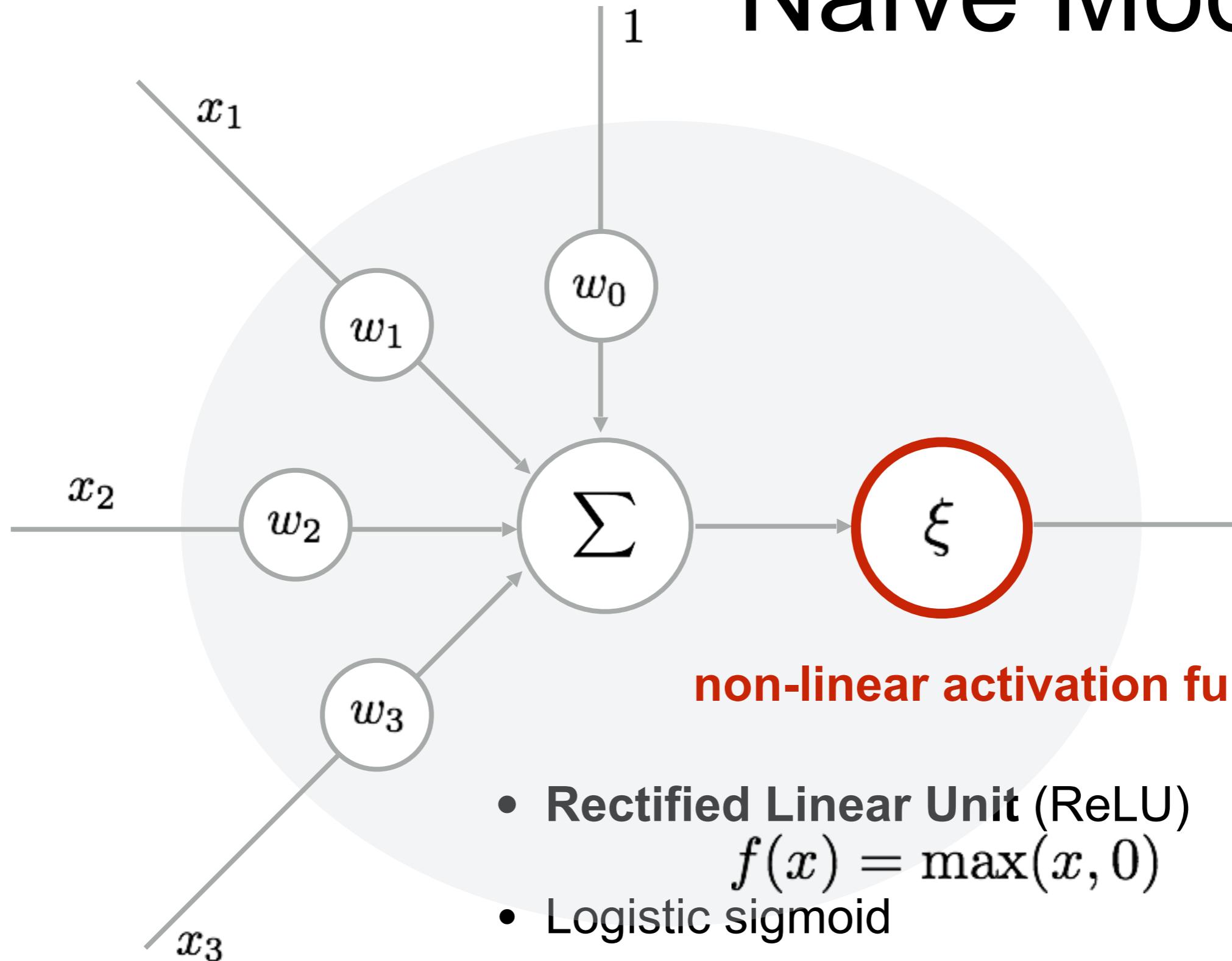
Naive Model



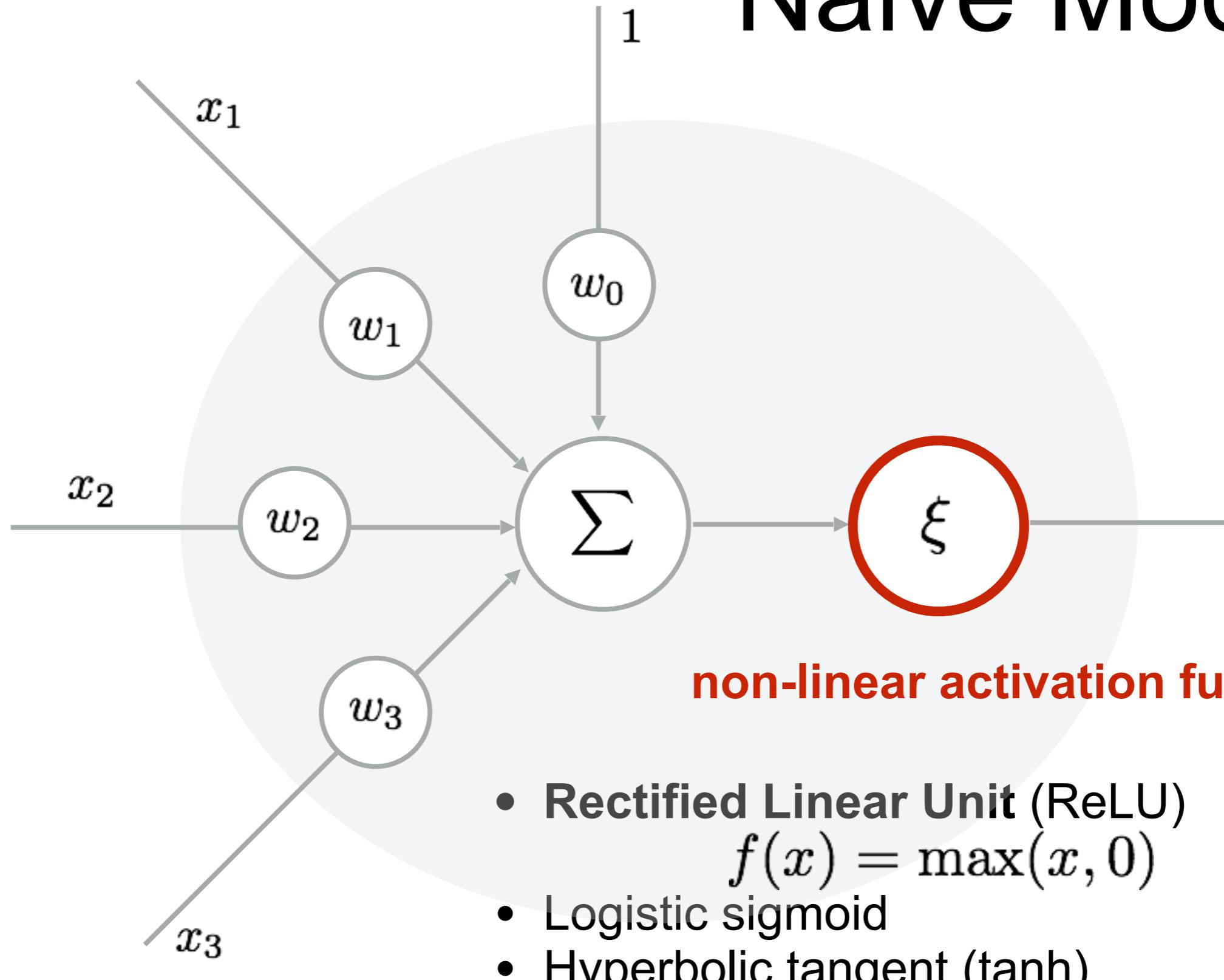
Naive Model



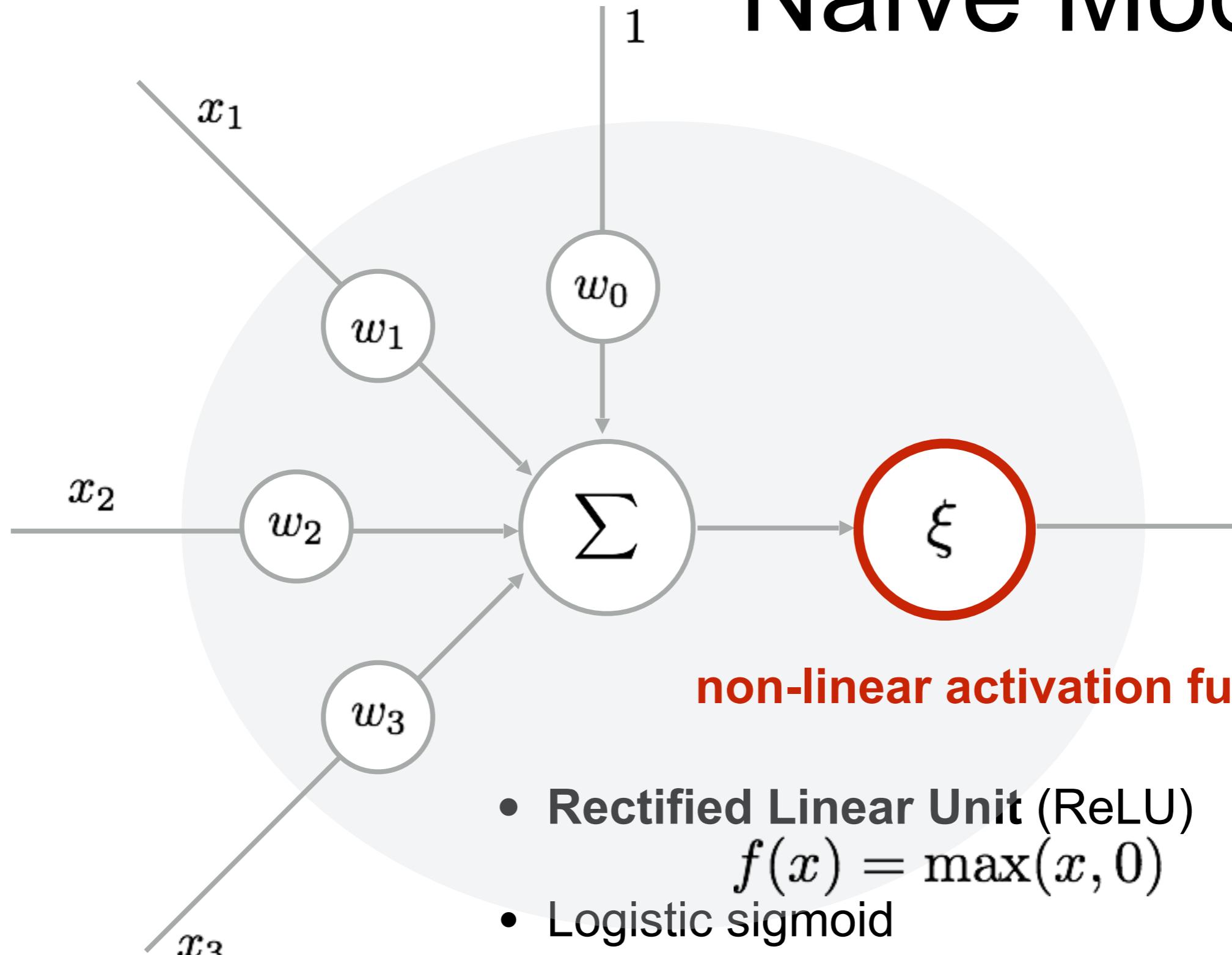
Naive Model



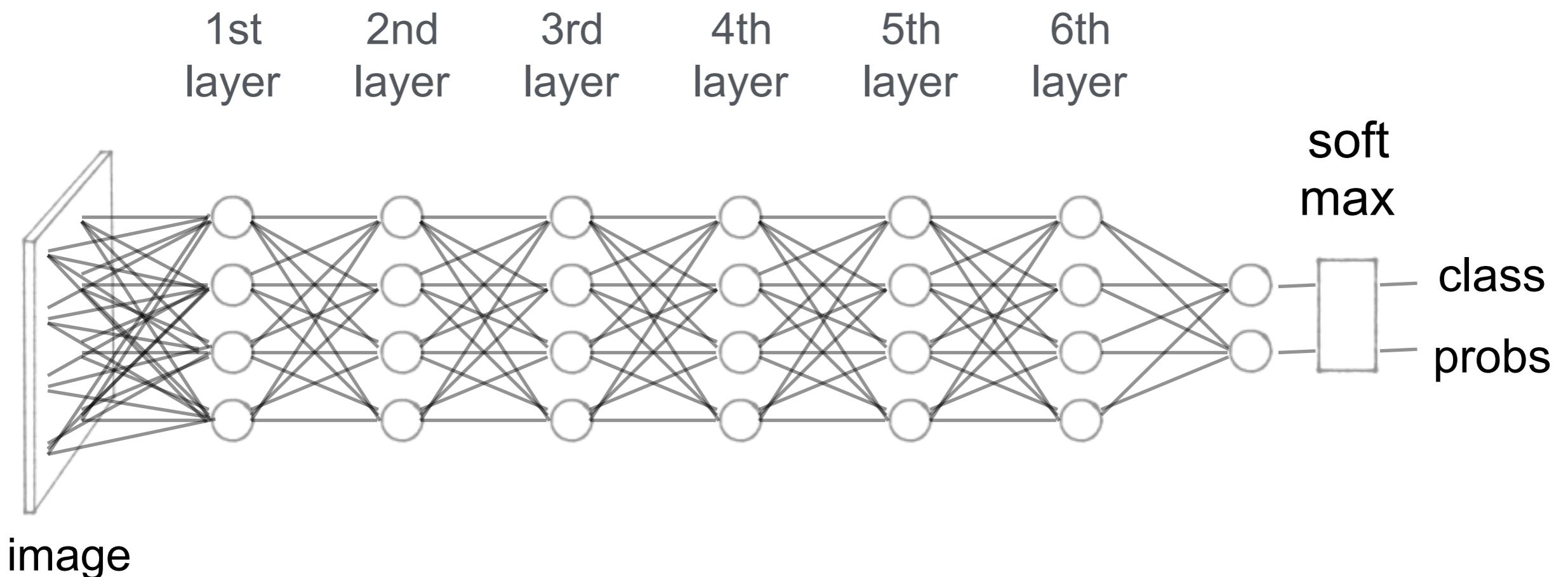
Naive Model



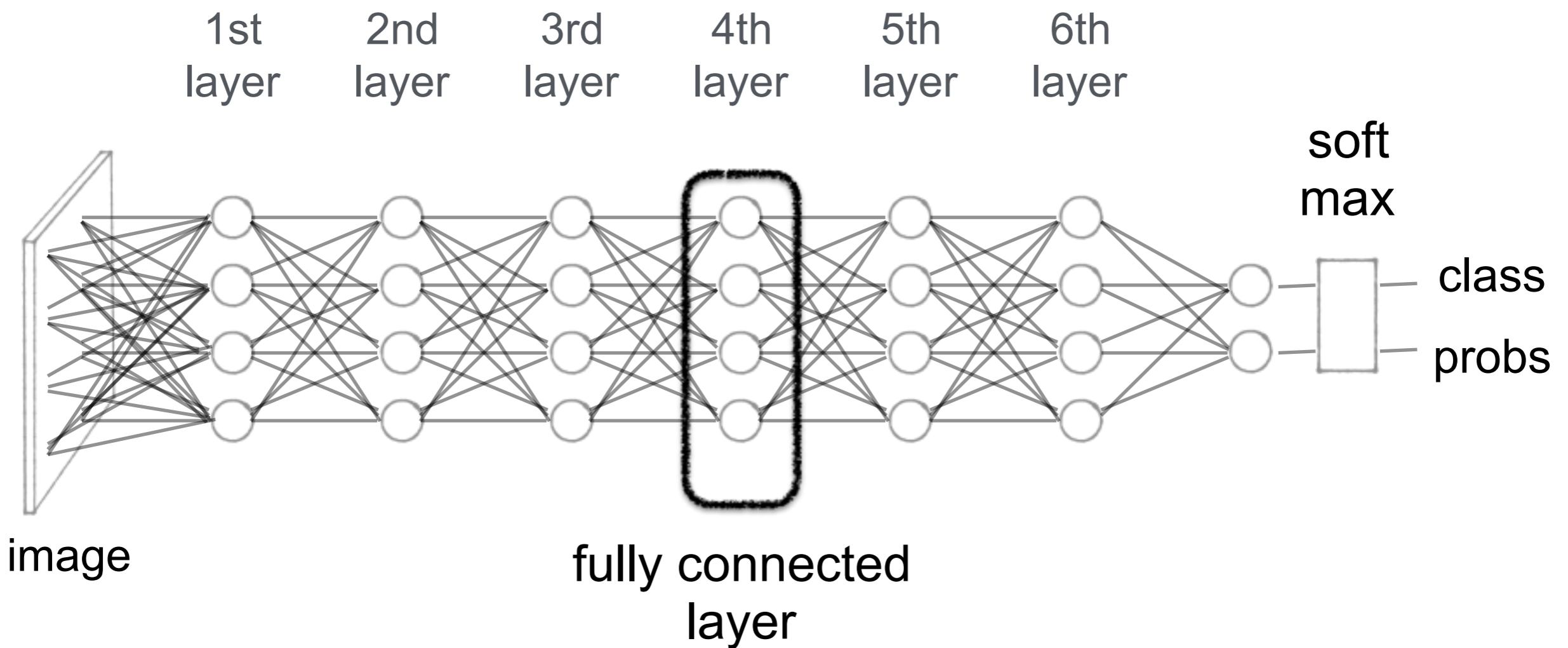
Naive Model



A Neural Network

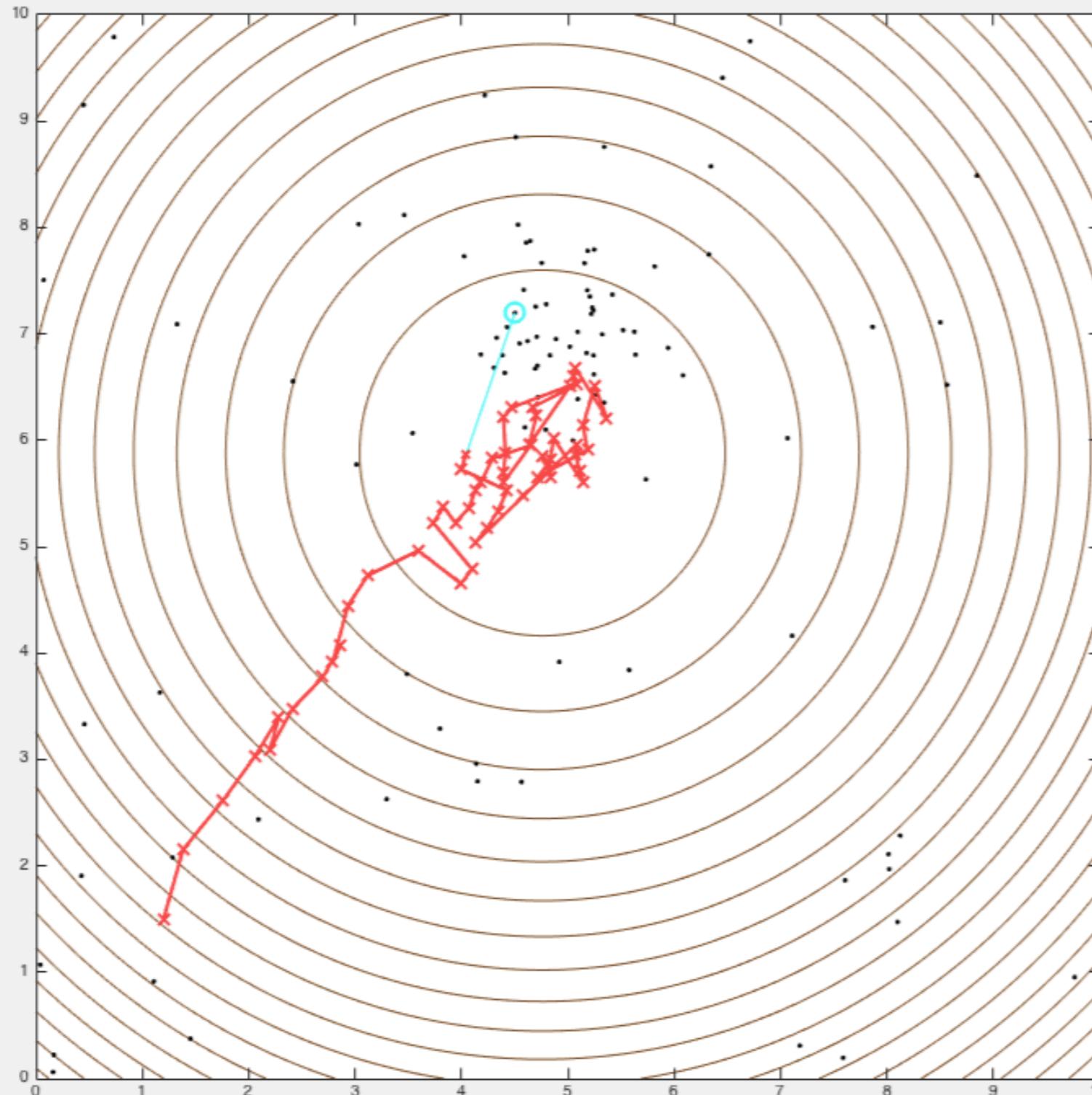


A Neural Network



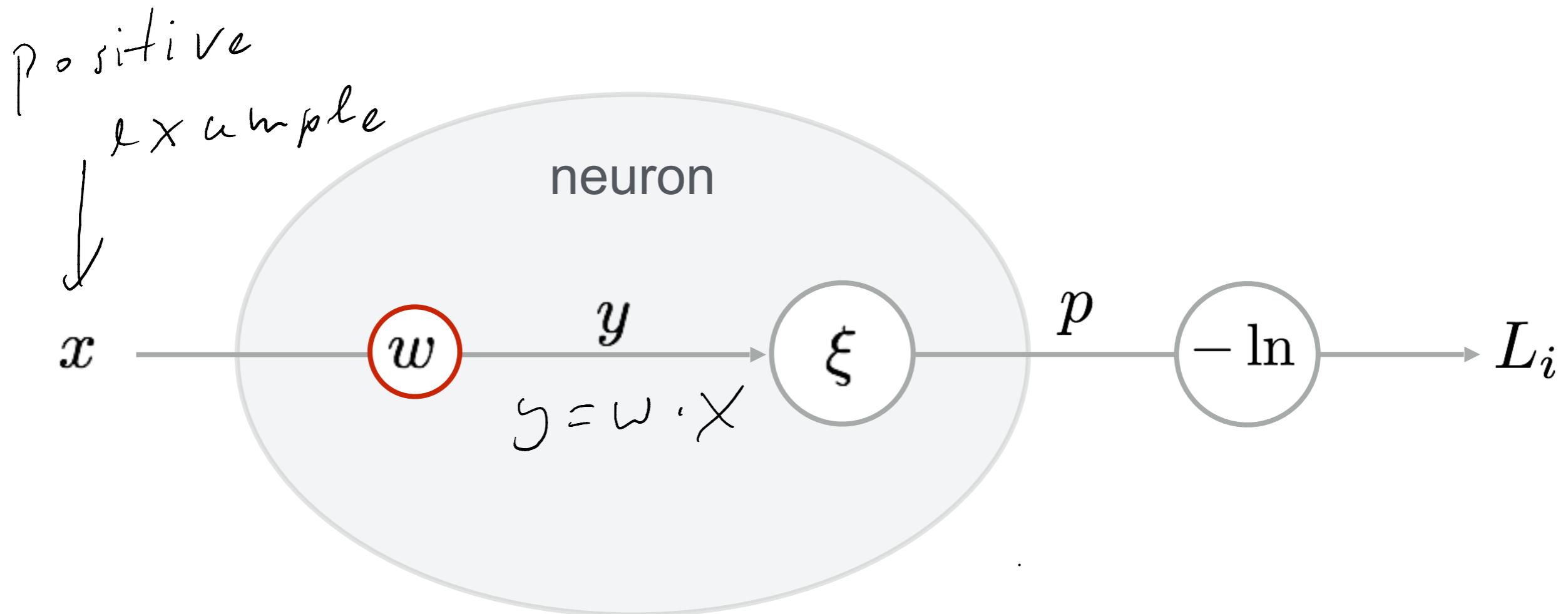
Optimization: Backpropagation (backprop)

Stochastic Gradient Descent

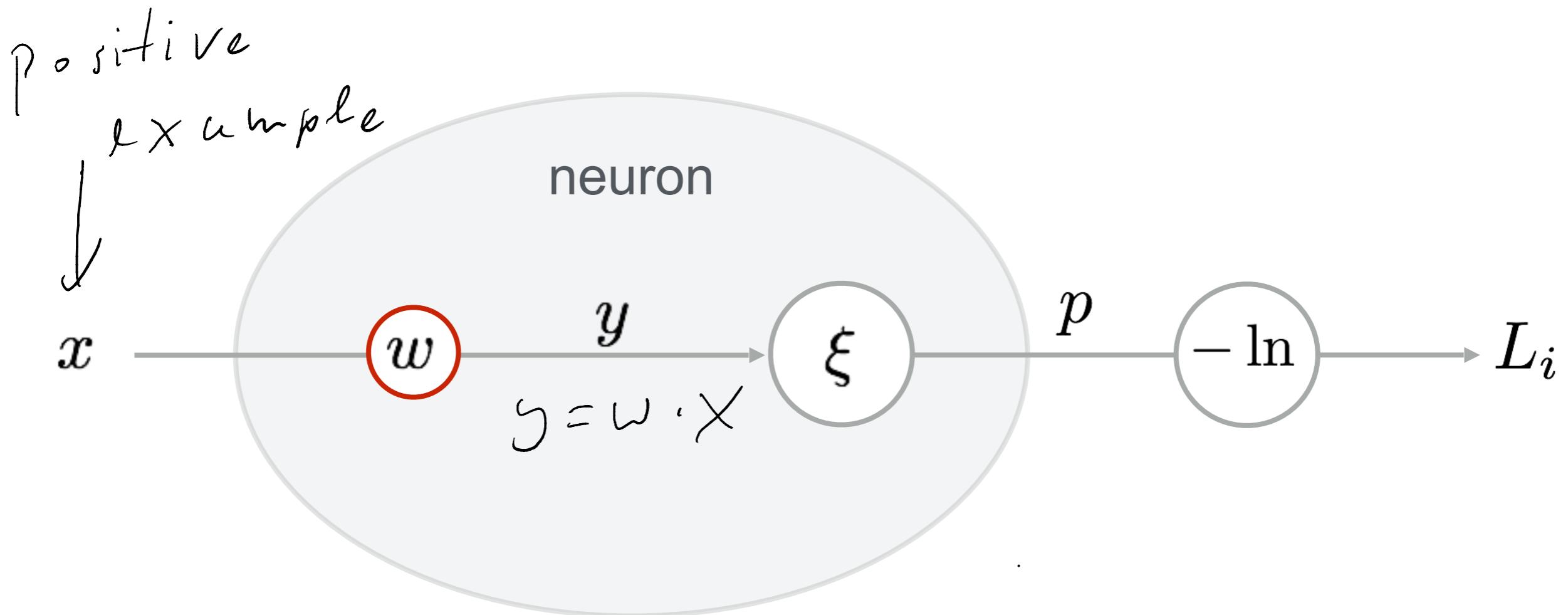


How do we differentiate?

The Chain Rule

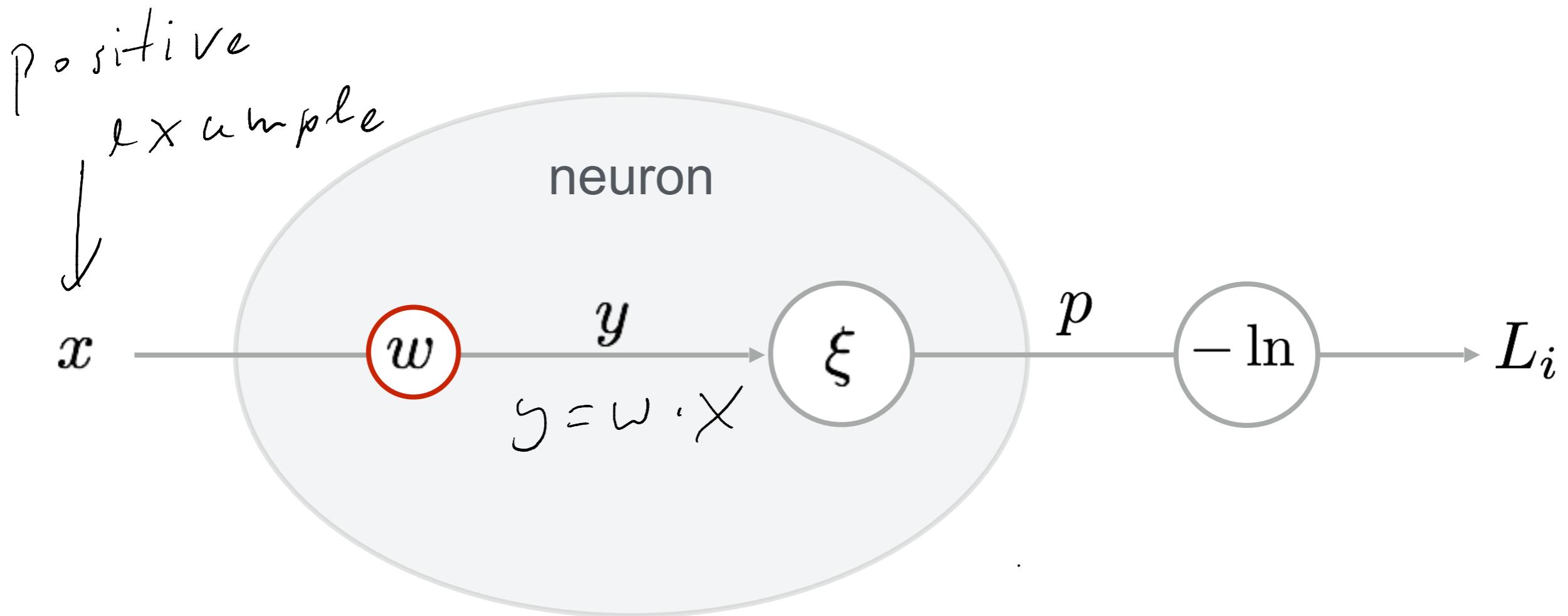


The Chain Rule



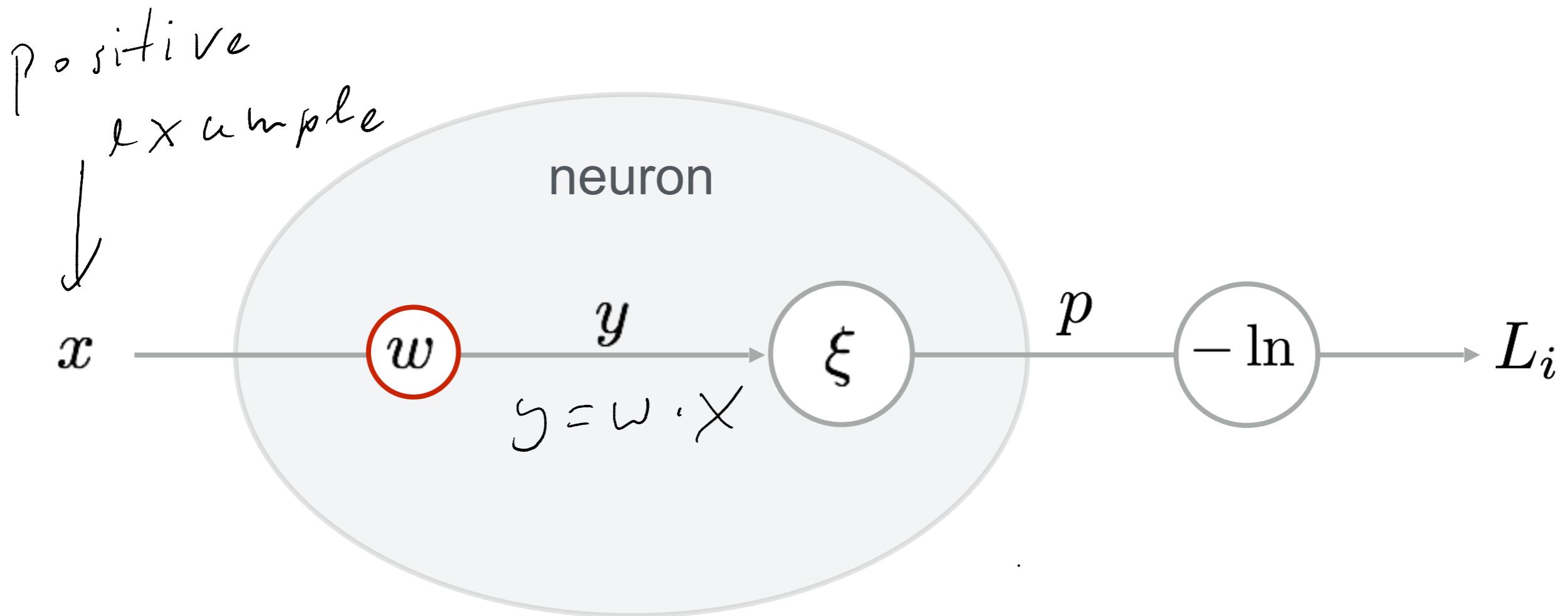
Gradient $\frac{\partial L_i}{\partial w}$

The Chain Rule



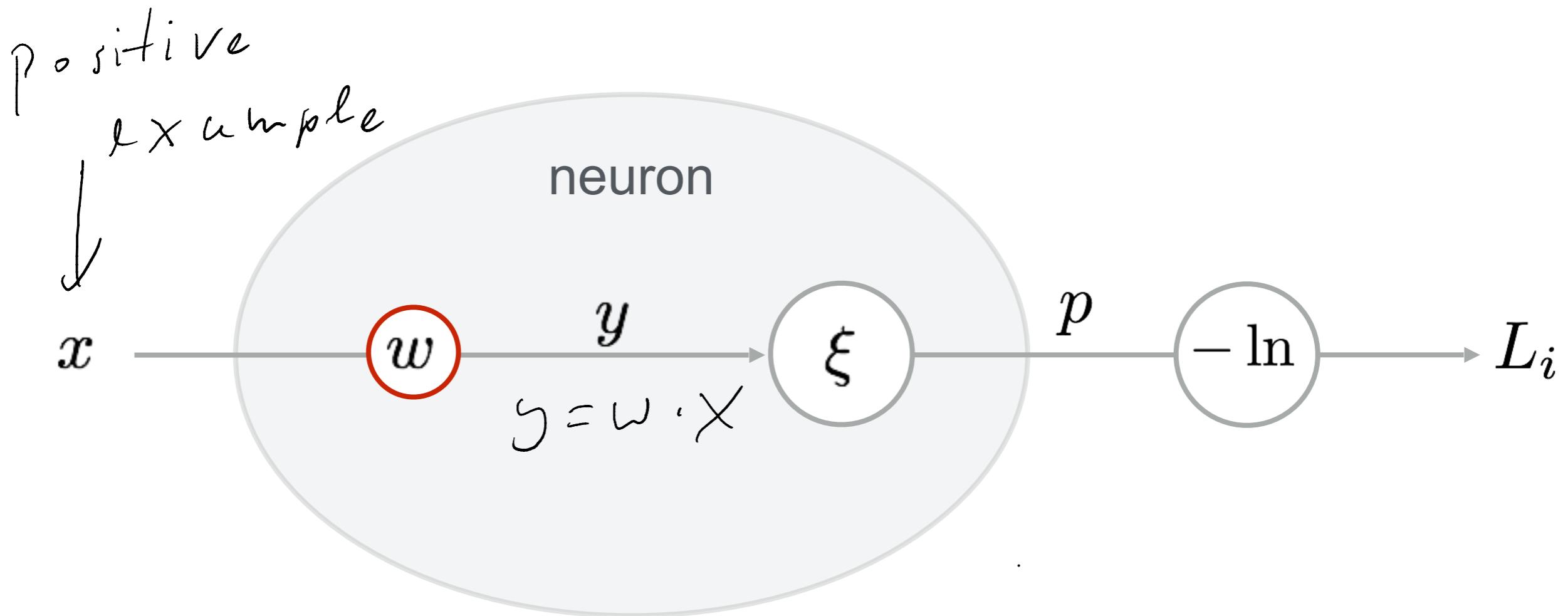
Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p}$

The Chain Rule



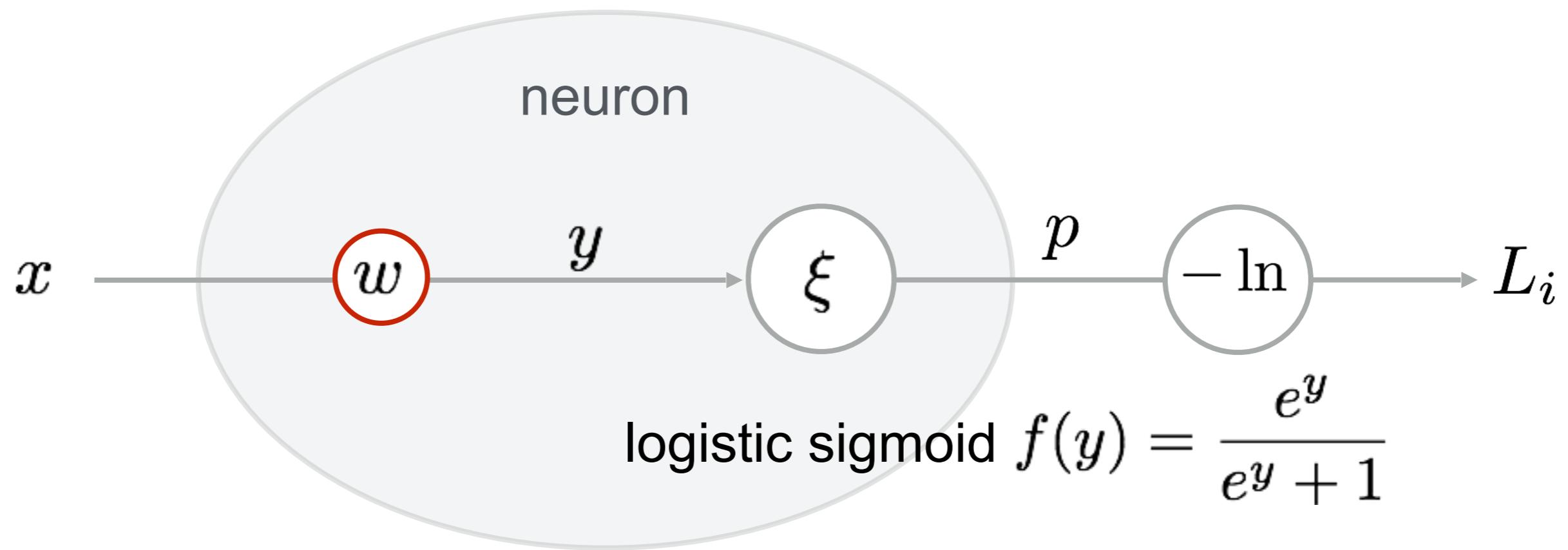
Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y}$

The Chain Rule



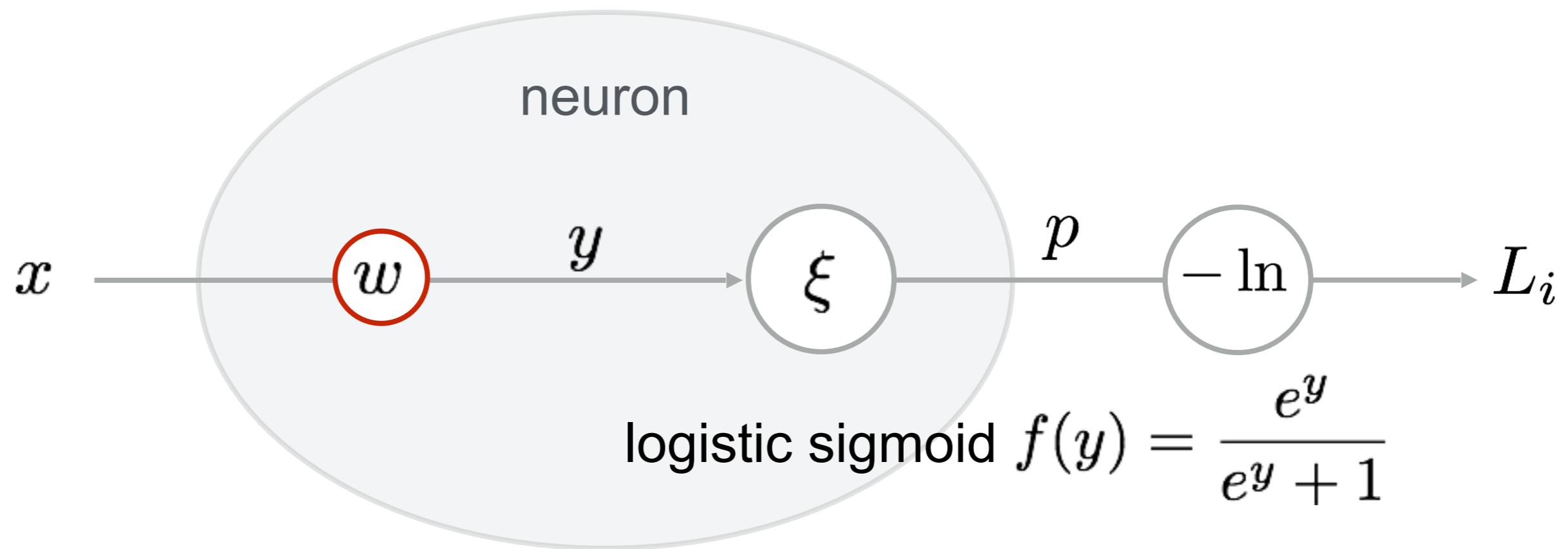
Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}$

The Chain Rule



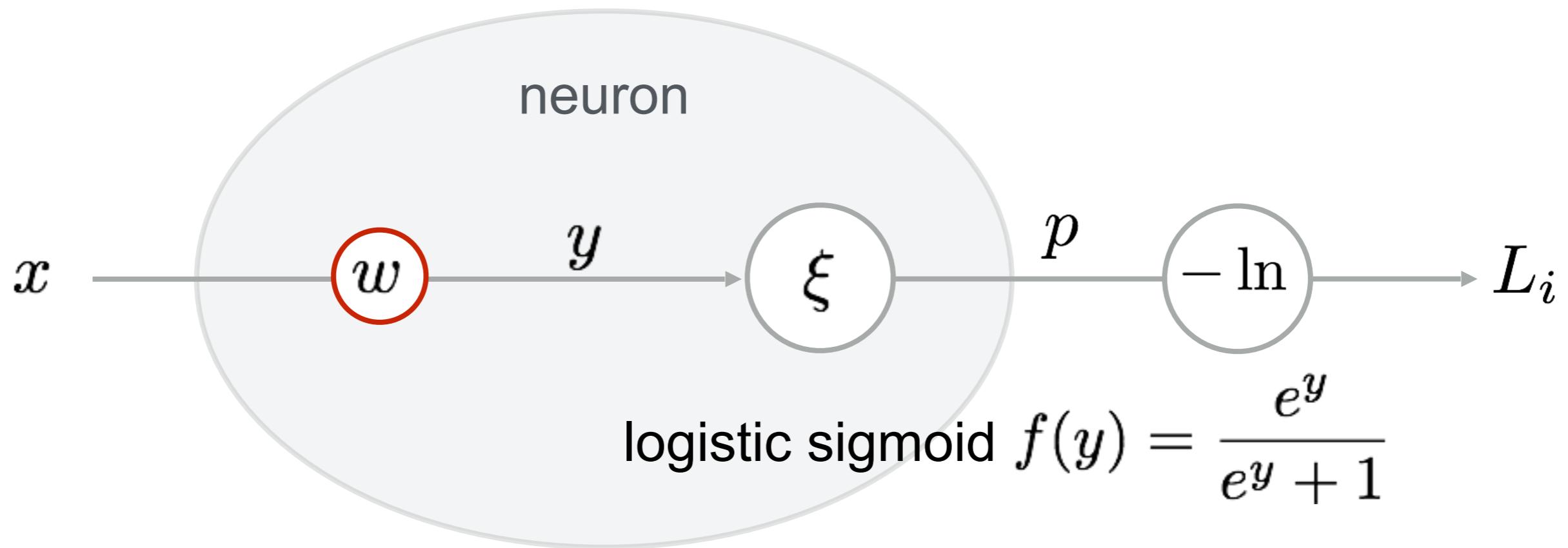
Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}$

The Chain Rule



Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}}$

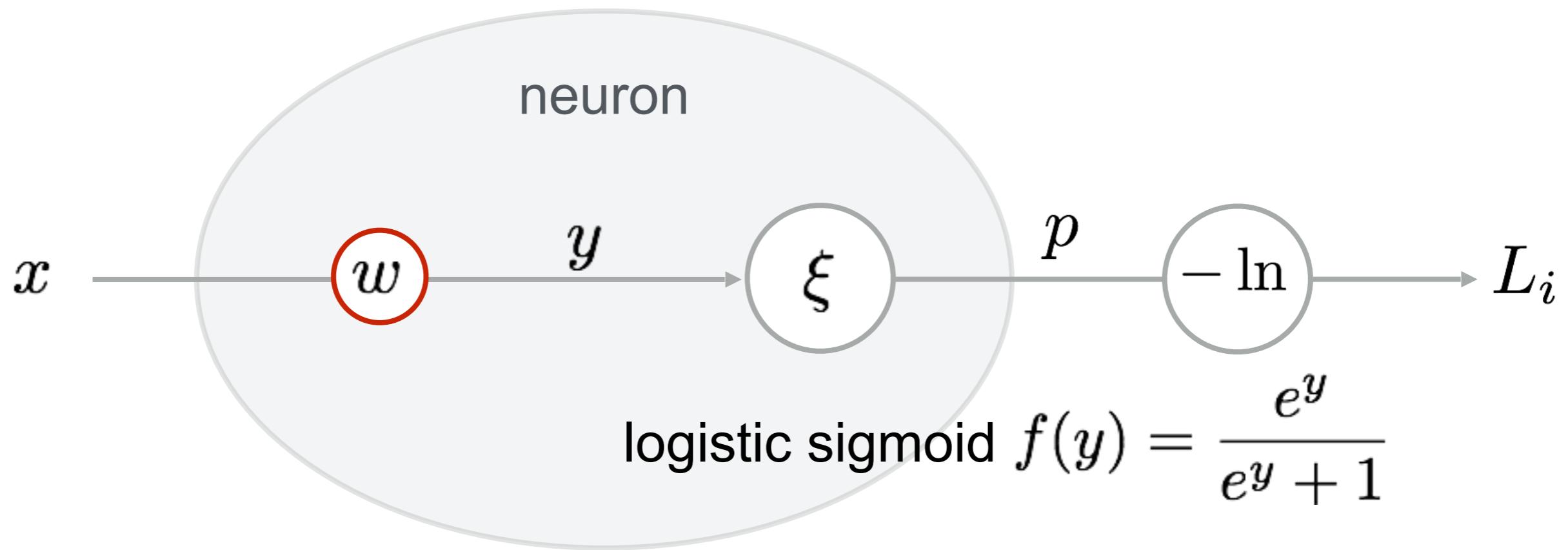
The Chain Rule



Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y}}_{\text{logistic sigmoid}} \frac{\partial y}{\partial w}$

$$\frac{\partial L_i}{\partial p} = \frac{\partial}{\partial p}(-\ln p)$$

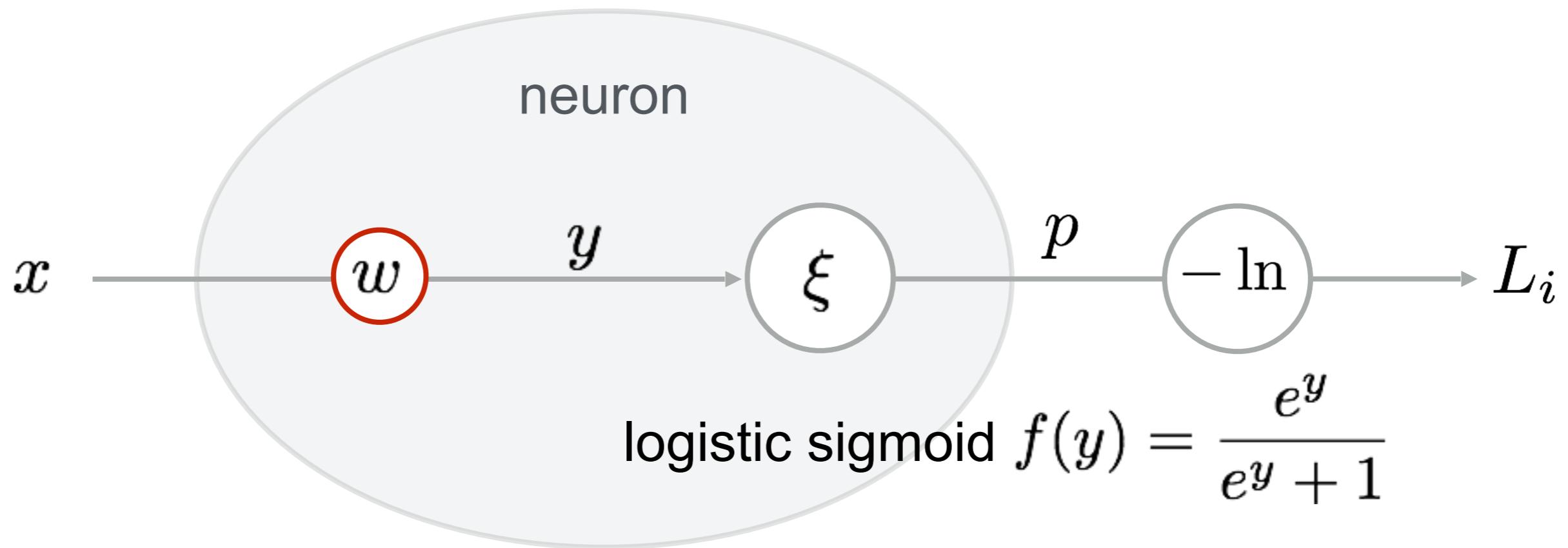
The Chain Rule



Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y}}_{\text{logistic sigmoid}} \frac{\partial y}{\partial w}$

$$\frac{\partial L_i}{\partial p} = \frac{\partial}{\partial p}(-\ln p) = -\frac{1}{p}$$

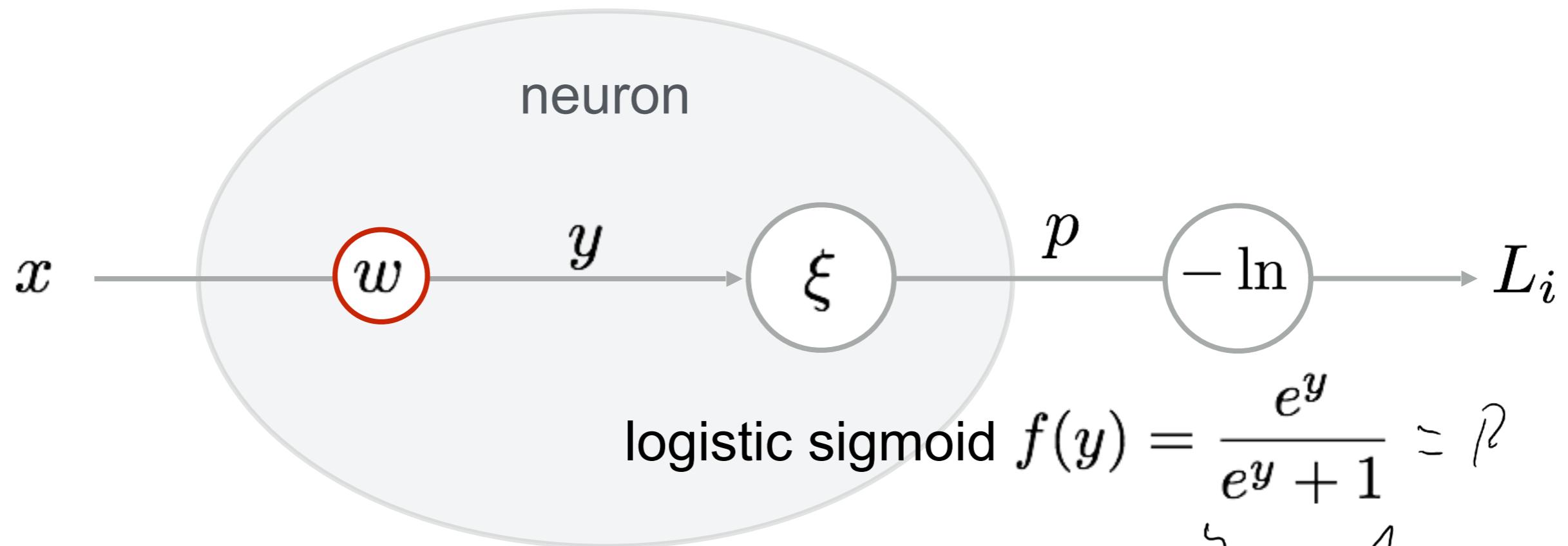
The Chain Rule



Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}}_{\frac{1}{p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}}$

$$\frac{\partial L_i}{\partial p} = \frac{\partial}{\partial p}(-\ln p) = -\frac{1}{p}$$

The Chain Rule

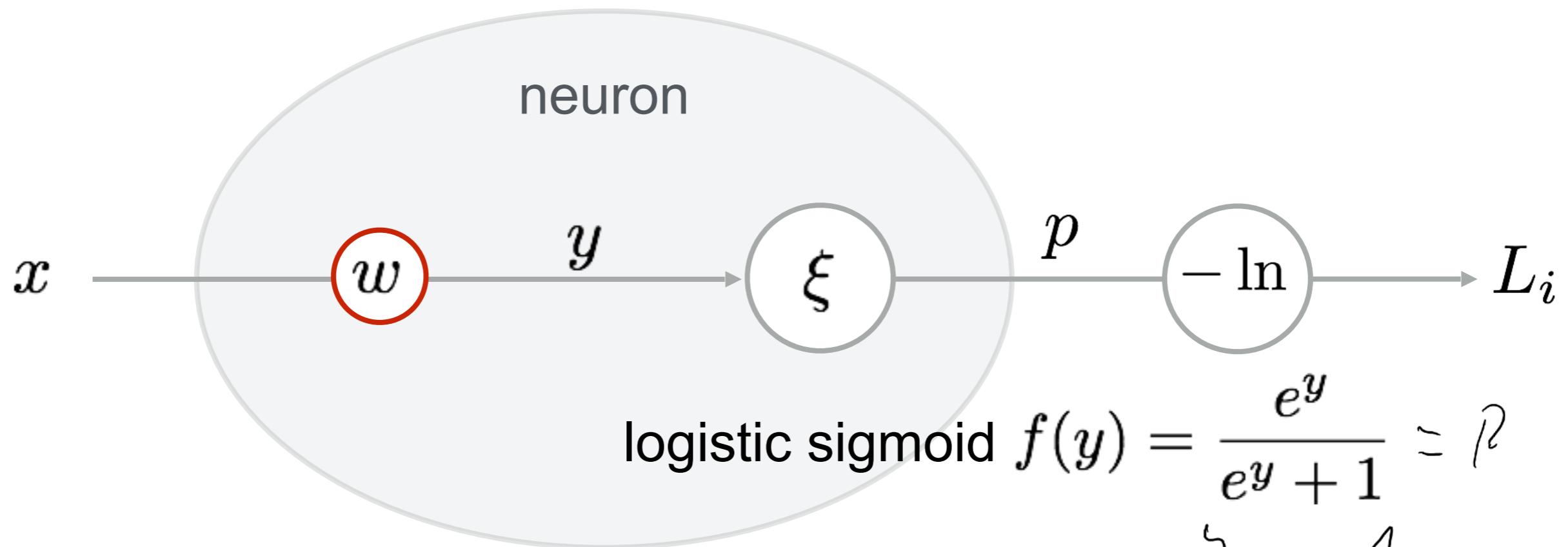


Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w} = -\frac{1}{p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}$

$$\frac{e^y}{e^y + 1} \cdot \frac{1}{e^y + 1} \cdot \underbrace{(1 + e^y - e^y)}_{1}$$

A handwritten note below the gradient calculation shows the simplification of the derivative of the logistic function: $\frac{e^y}{e^y + 1} \cdot \frac{1}{e^y + 1} \cdot (1 + e^y - e^y)$.

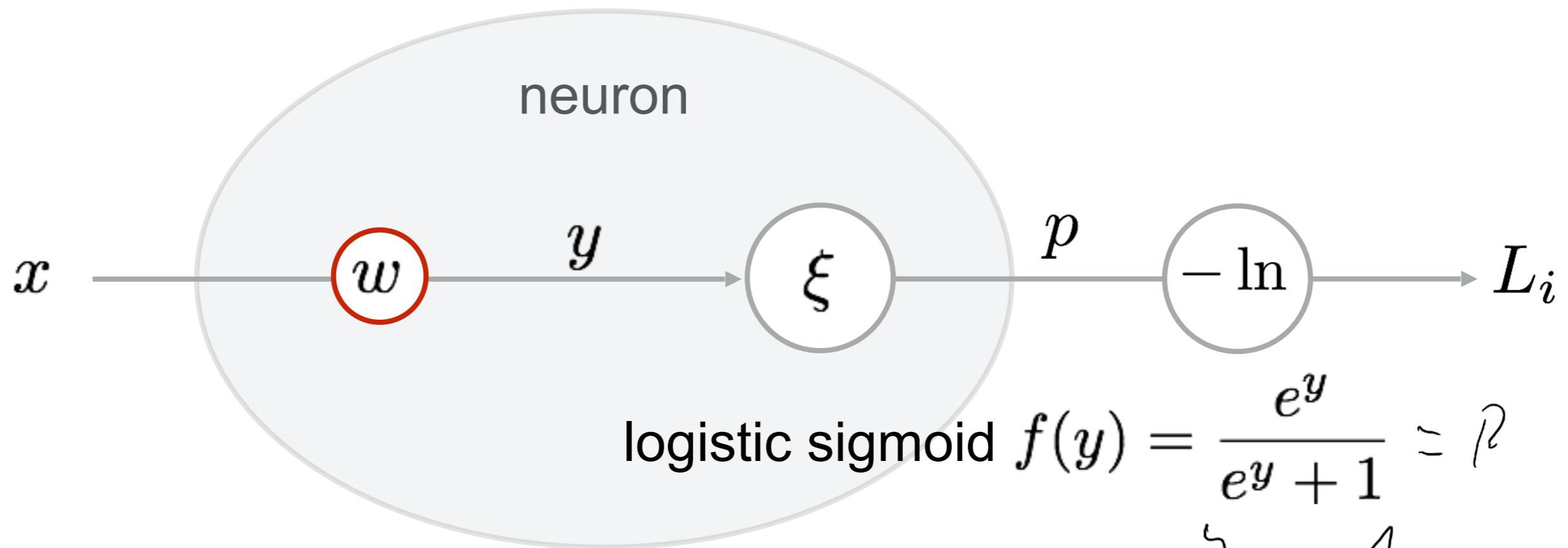
The Chain Rule



$$\text{Gradient } \frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w} = -\frac{1}{p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}$$

$\frac{e^y}{e^y + 1}, \frac{1}{e^y + 1}$

The Chain Rule

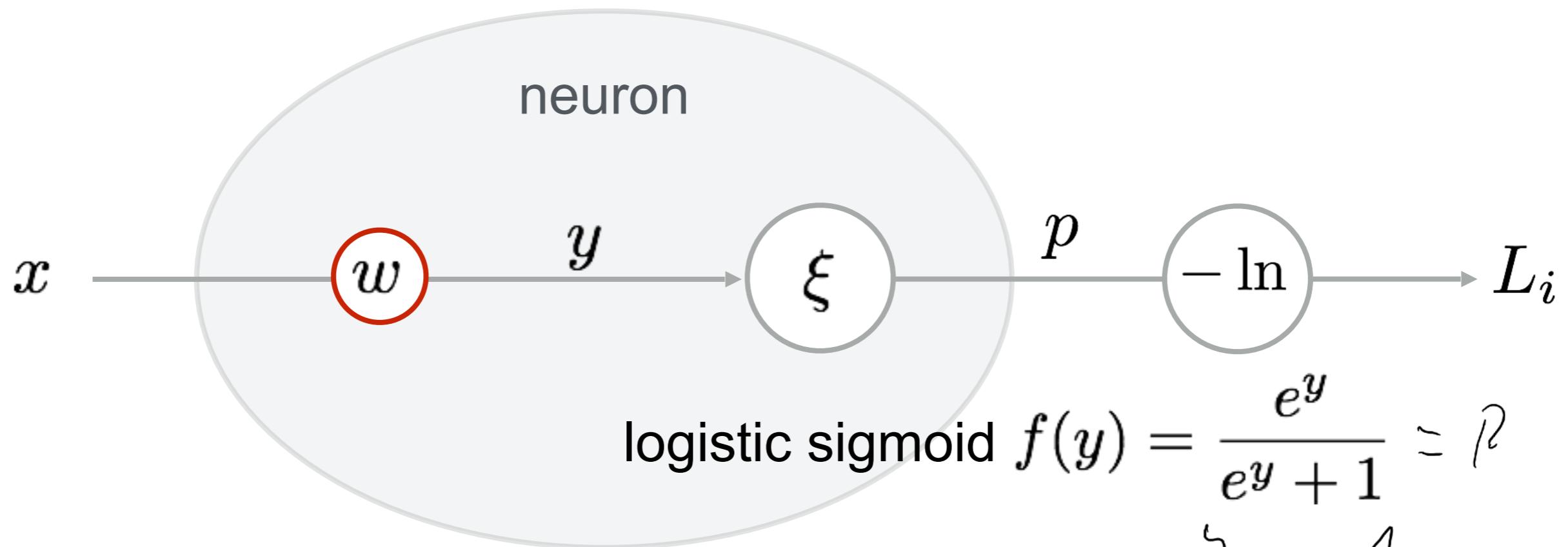


Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \underbrace{\frac{\partial y}{\partial w}}_{e^y(1+e^y-e^y)} = -\frac{1}{p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1}$$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1}$$

The Chain Rule

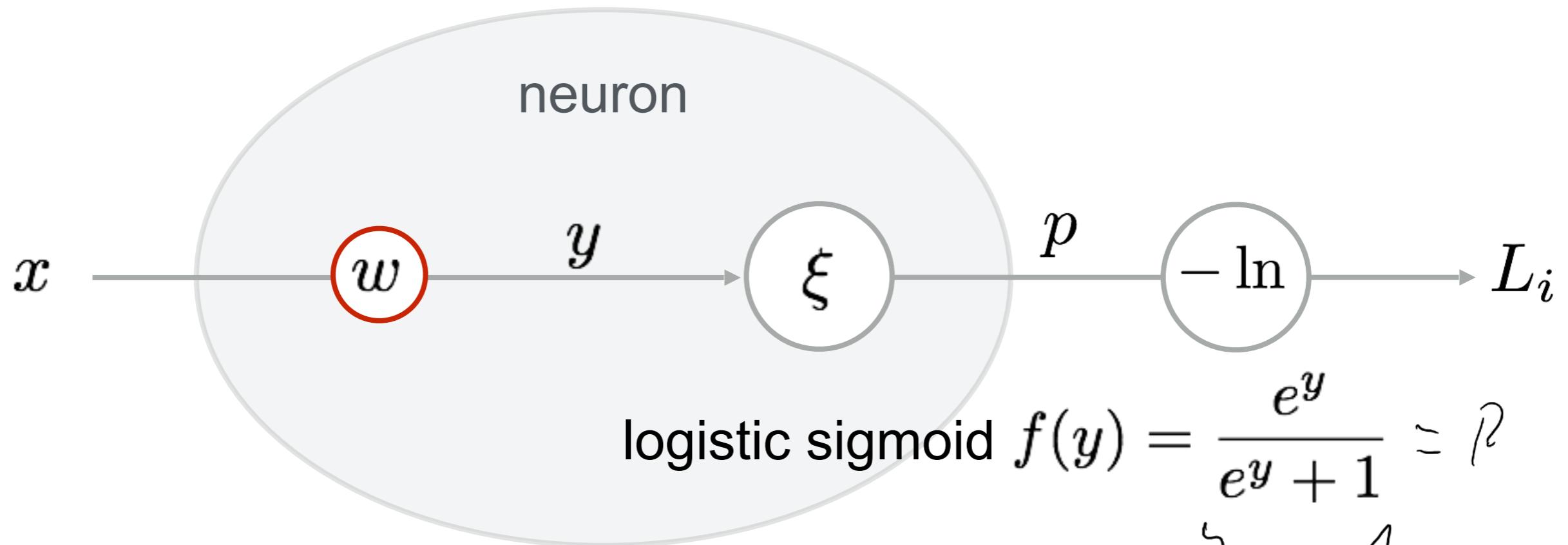


Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \underbrace{\frac{\partial y}{\partial w}}_{e^y(1+e^y-e^y)} = -\frac{1}{p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1} = \frac{e^y(1+e^y)-(e^y)^2}{(e^y + 1)^2}$$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1} = \frac{e^y(1+e^y)-(e^y)^2}{(e^y + 1)^2}$$

The Chain Rule

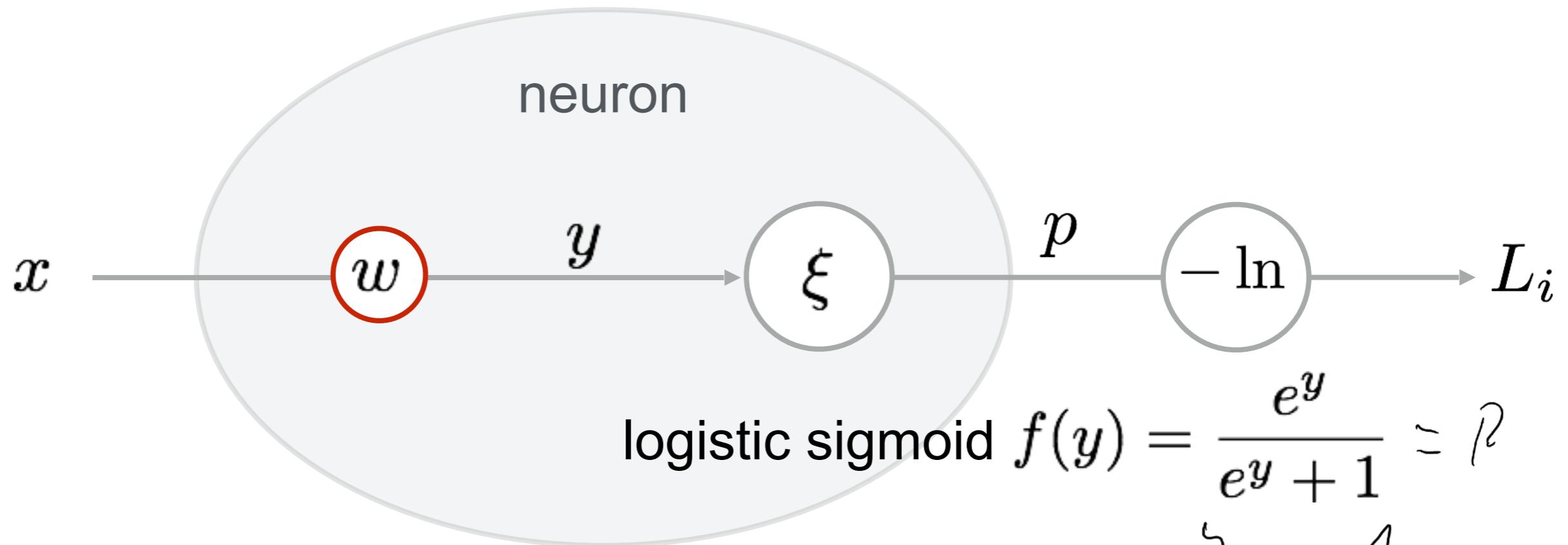


Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \underbrace{\frac{\partial y}{\partial w}}_{e^y(1+e^y-e^y)} = -\frac{1}{p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1} = \frac{e^y(1+e^y)-(e^y)^2}{(e^y+1)^2} = \frac{e^y}{(e^y+1)^2}$$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1} = \frac{e^y(1+e^y)-(e^y)^2}{(e^y+1)^2} = \frac{e^y}{(e^y+1)^2}$$

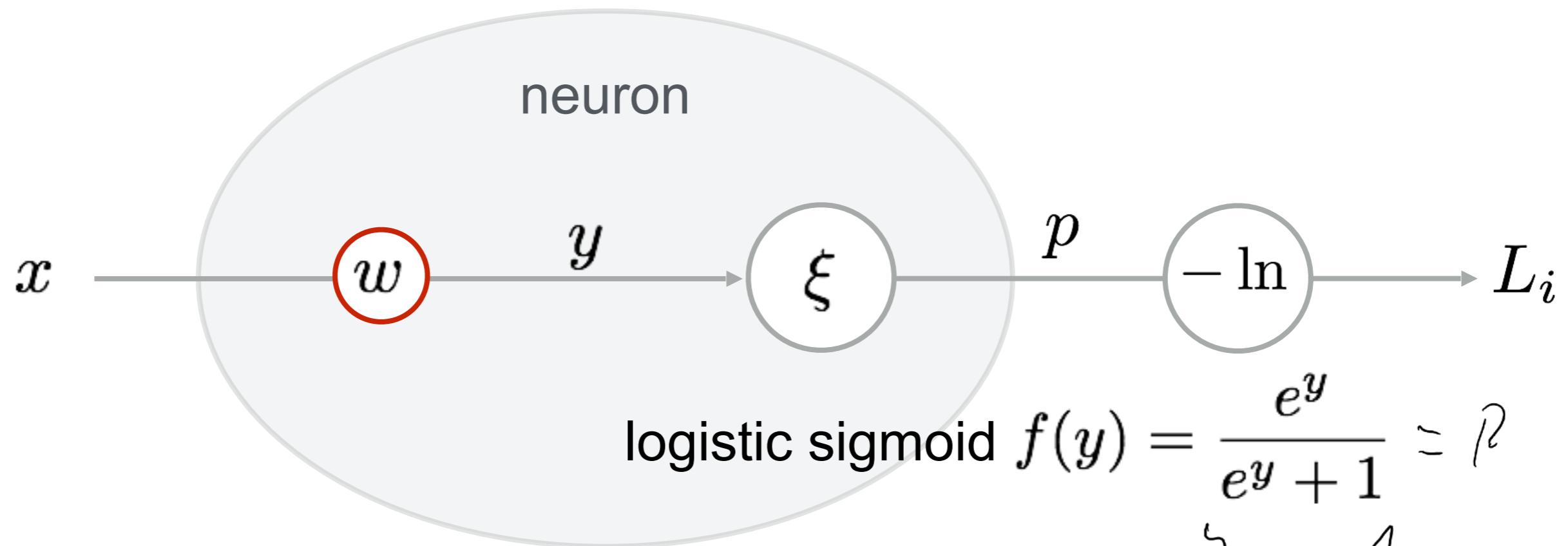
The Chain Rule



Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \underbrace{\frac{\partial y}{\partial w}}_{e^y(1+e^y-e^y)} = -\frac{1}{p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1} = \frac{e^y(1+e^y)-(e^y)^2}{(e^y+1)^2} = \frac{e^y}{(e^y+1)^2} = p(1-p)$$

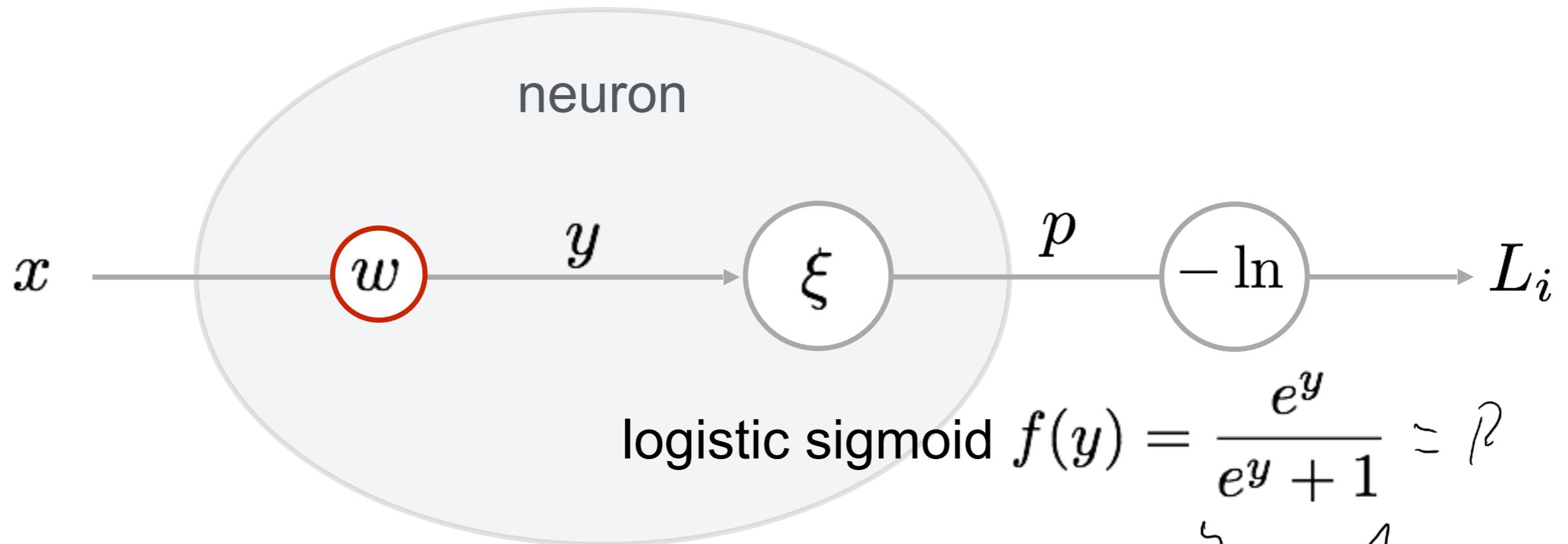
The Chain Rule



Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y}}_{e^y} \underbrace{\frac{\partial y}{\partial w}}_{\frac{1}{1+e^y - e^y}} = -\frac{1}{p(1-p)} \frac{\partial y}{\partial w}$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1} = \frac{e^y(1+e^y) - (e^y)^2}{(e^y + 1)^2} = \frac{e^y}{(e^y + 1)^2} = p(1-p)$$

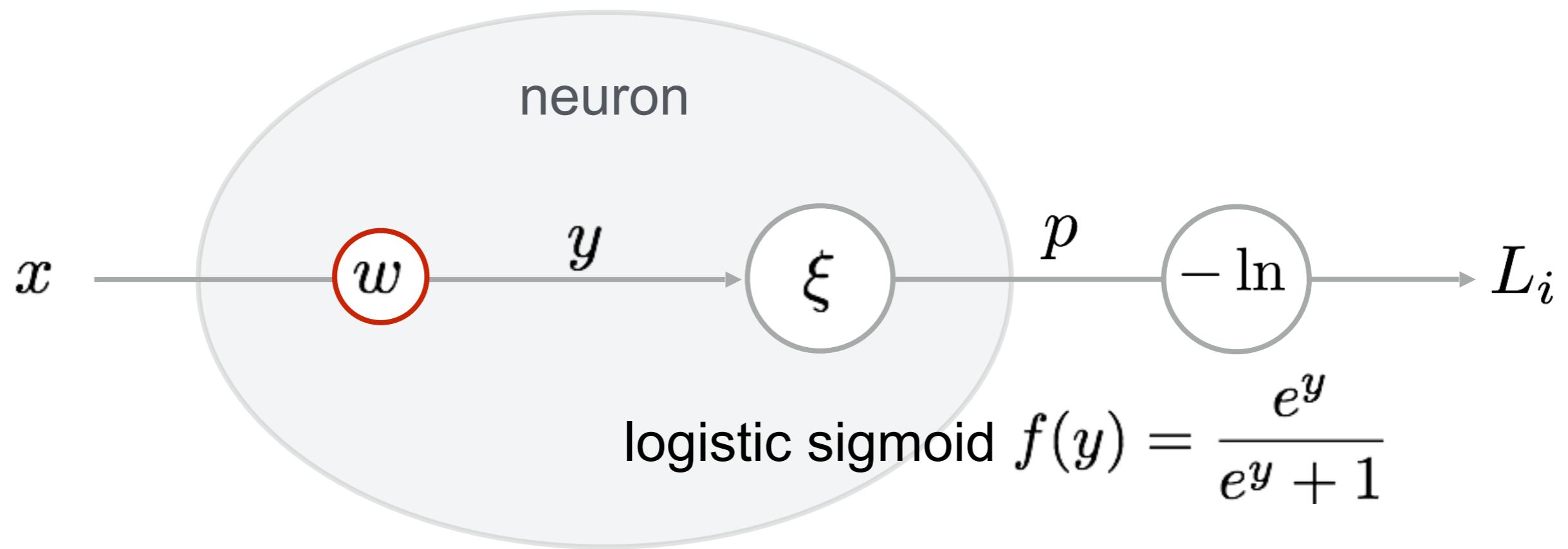
The Chain Rule



Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p}}_{\text{e}^y} \underbrace{\frac{\partial p}{\partial y}}_{(1 + e^y - e^y)} \underbrace{\frac{\partial y}{\partial w}}_{\frac{e^y}{(e^y + 1)^2}}$

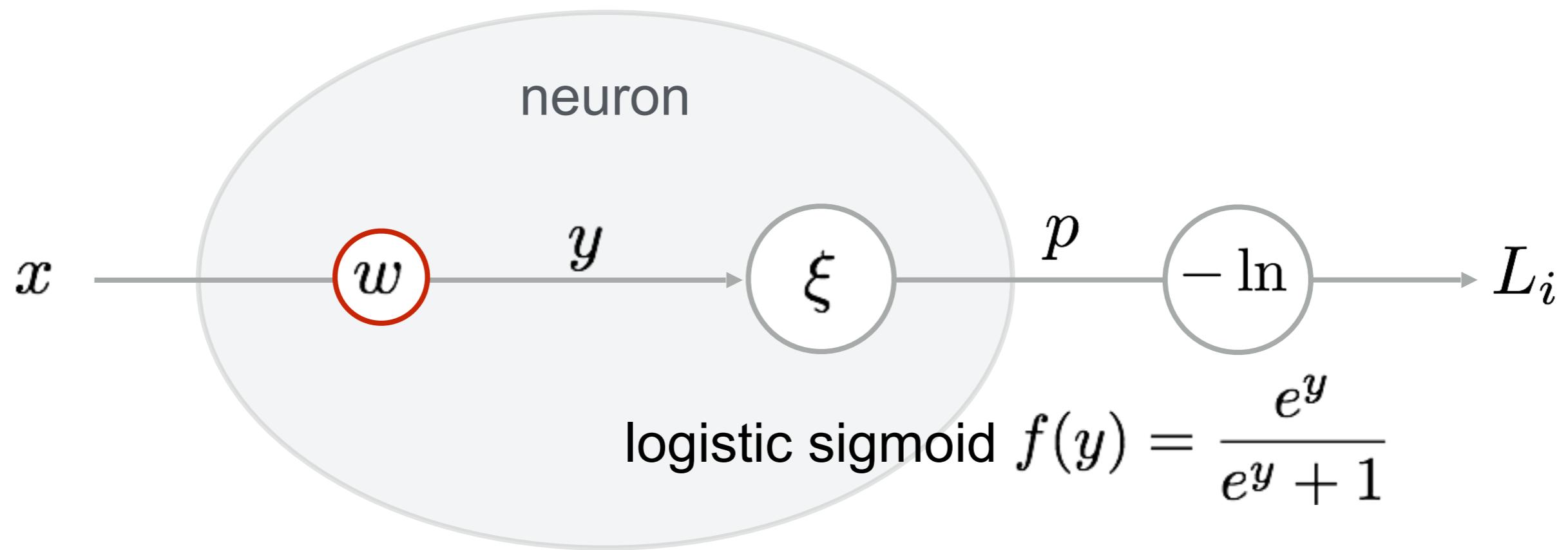
$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \frac{e^y}{e^y + 1} = \frac{e^y(1 + e^y) - (e^y)^2}{(e^y + 1)^2} = \frac{e^y}{(e^y + 1)^2} = p(1 - p)$$

The Chain Rule



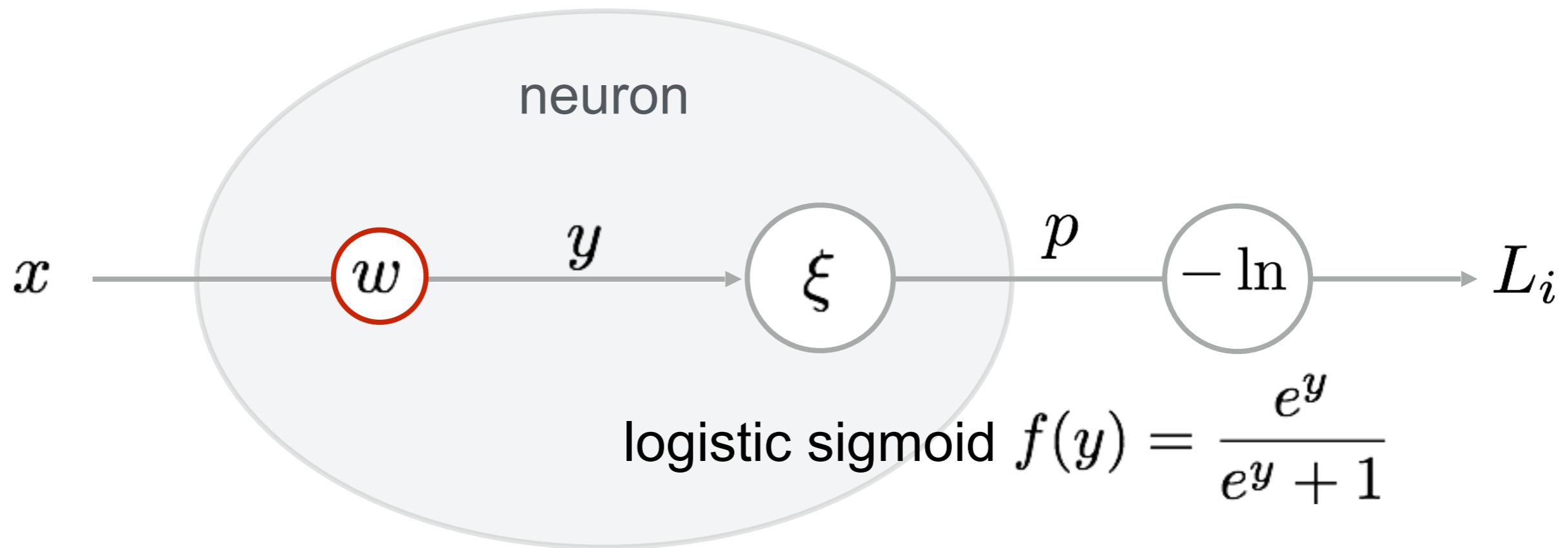
Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w} = (p - 1) \frac{\partial y}{\partial w}$

The Chain Rule



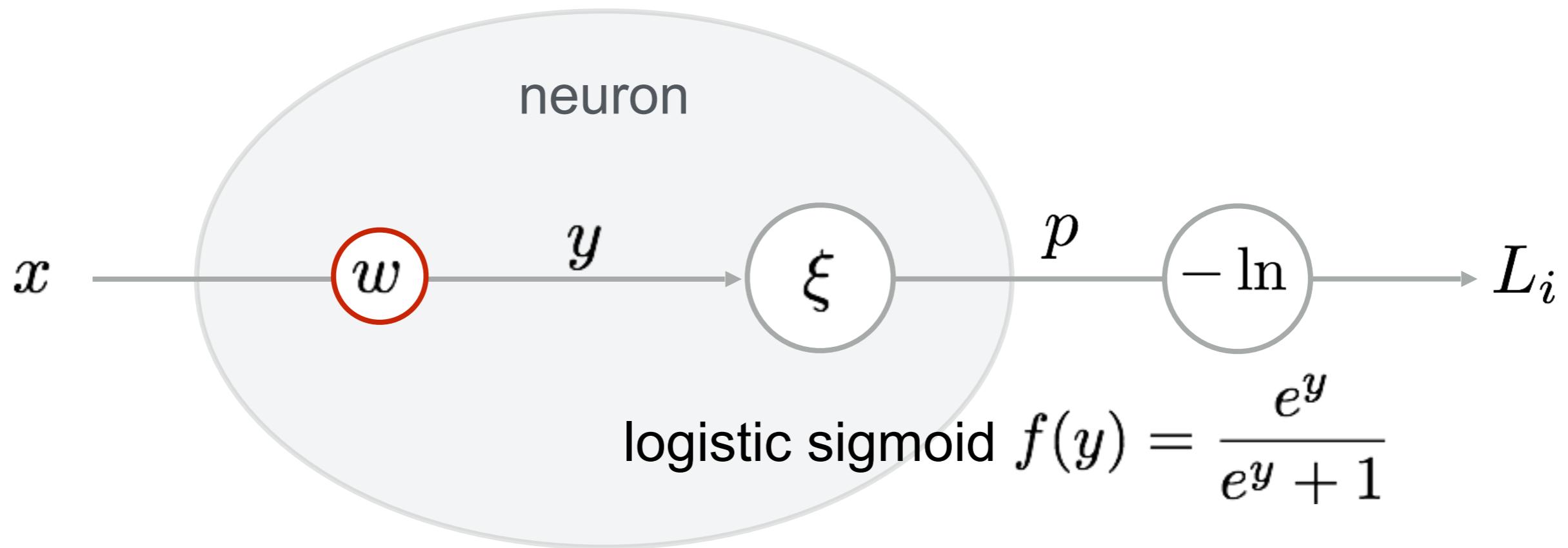
Gradient $\frac{\partial L_i}{\partial w} = \frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \underbrace{\frac{\partial y}{\partial w}}_{=} = (p - 1) \frac{\partial y}{\partial w}$

The Chain Rule



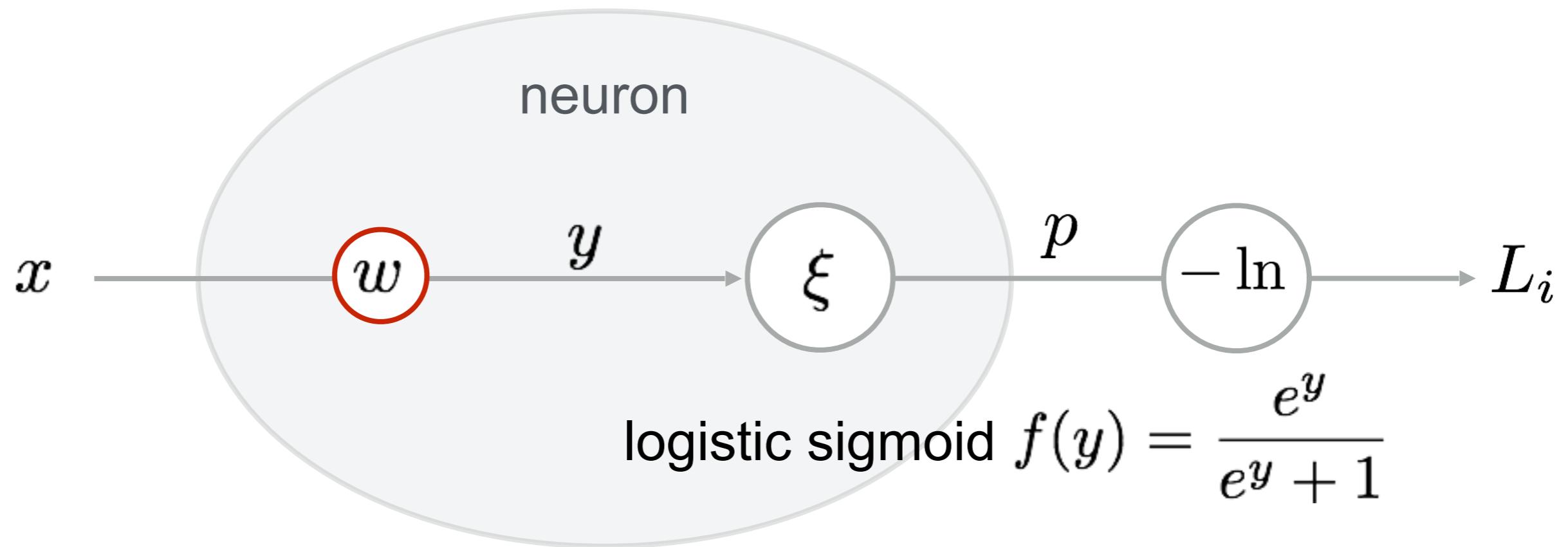
Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}}_{\frac{\partial y}{\partial w} = \frac{\partial}{\partial w}wx} = (p - 1) \frac{\partial y}{\partial w}$

The Chain Rule



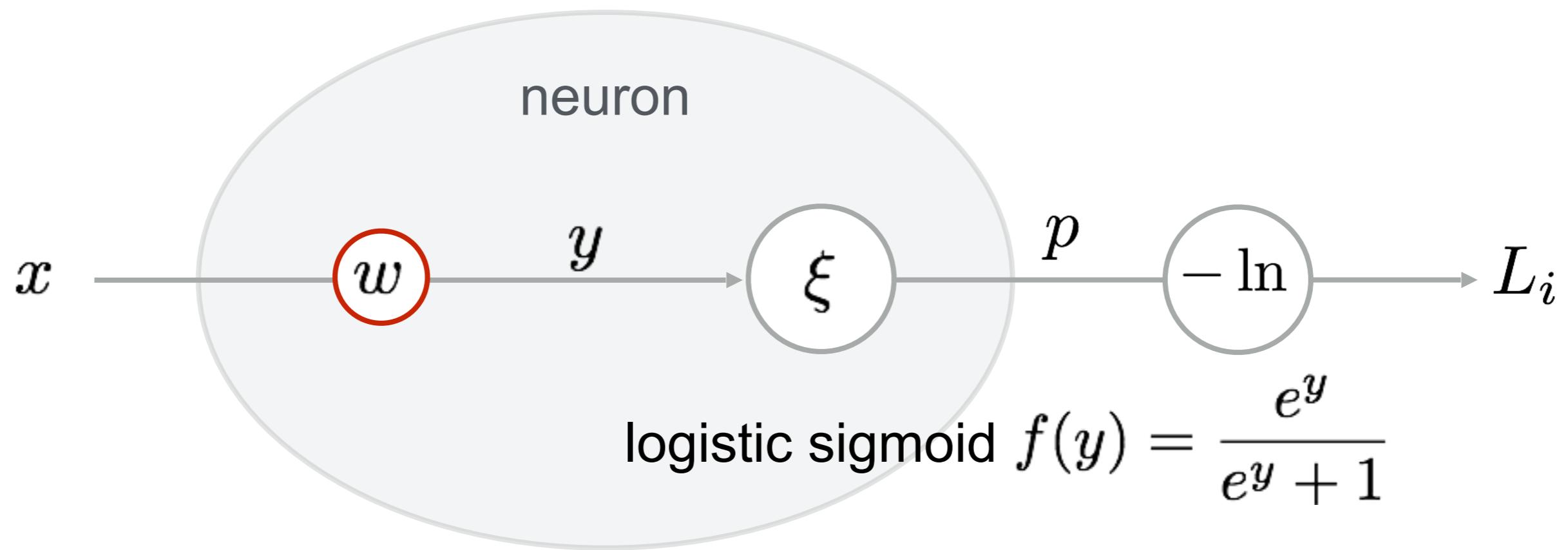
Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}}_{\frac{\partial y}{\partial w} = \frac{\partial}{\partial w} w x = x} = (p - 1) \frac{\partial y}{\partial w}$

The Chain Rule



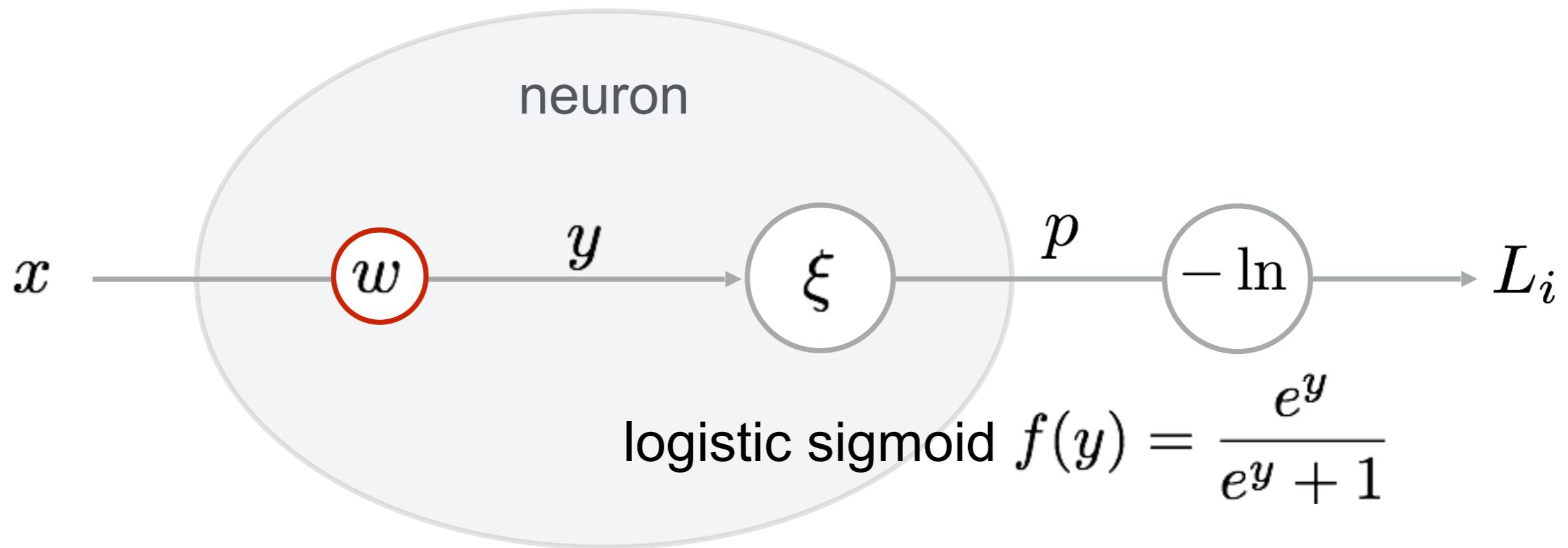
Gradient $\frac{\partial L_i}{\partial w} = \underbrace{\frac{\partial L_i}{\partial p} \frac{\partial p}{\partial y} \frac{\partial y}{\partial w}}_{\frac{\partial y}{\partial w} = \frac{\partial}{\partial w} w x = x} = (p - 1) \frac{\partial y}{\partial w} = (p - 1)x$

The Chain Rule



Gradient for positive example: $\frac{\partial L_i}{\partial w} = (p - 1)x$

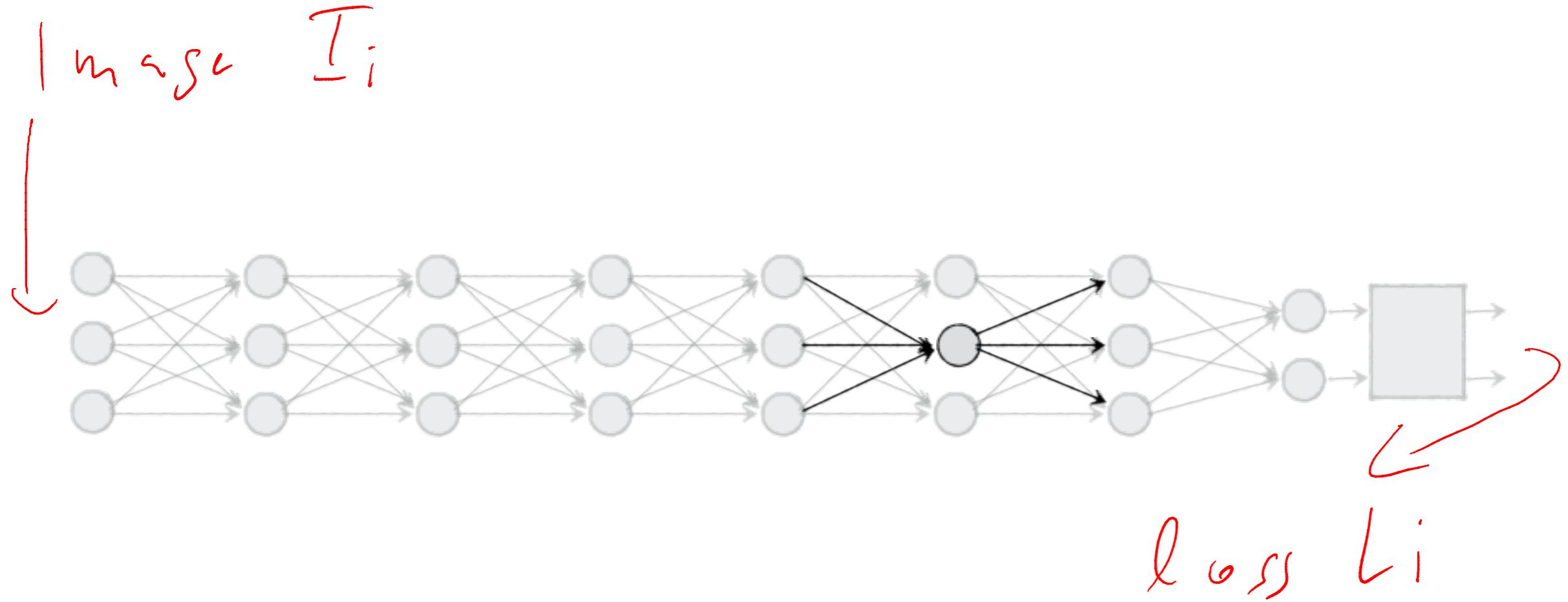
The Chain Rule



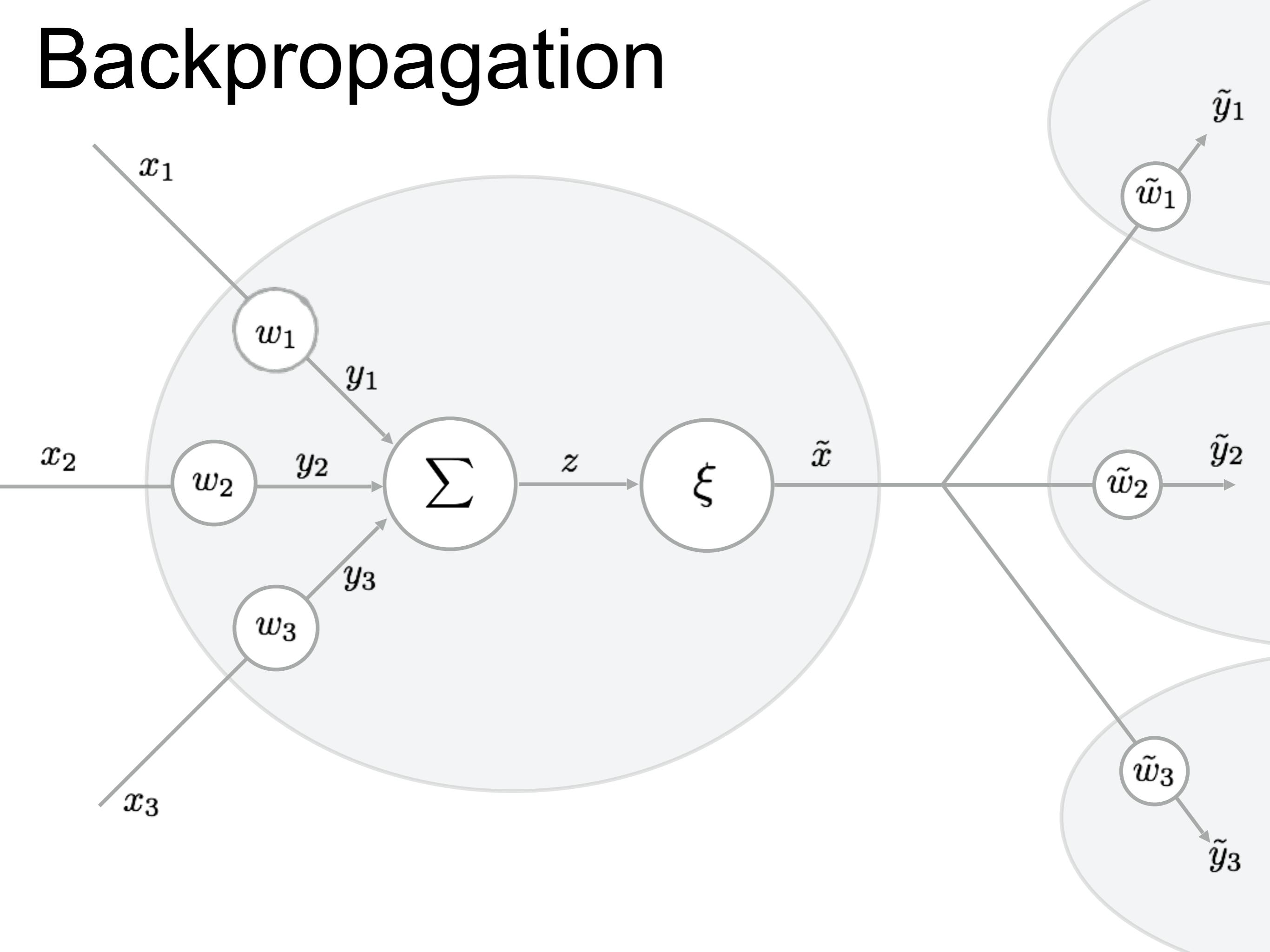
Gradient for positive example: $\frac{\partial L_i}{\partial w} = (p - 1)x$

Gradient for negative example: $\frac{\partial L_i}{\partial w} = px$

Network Structure

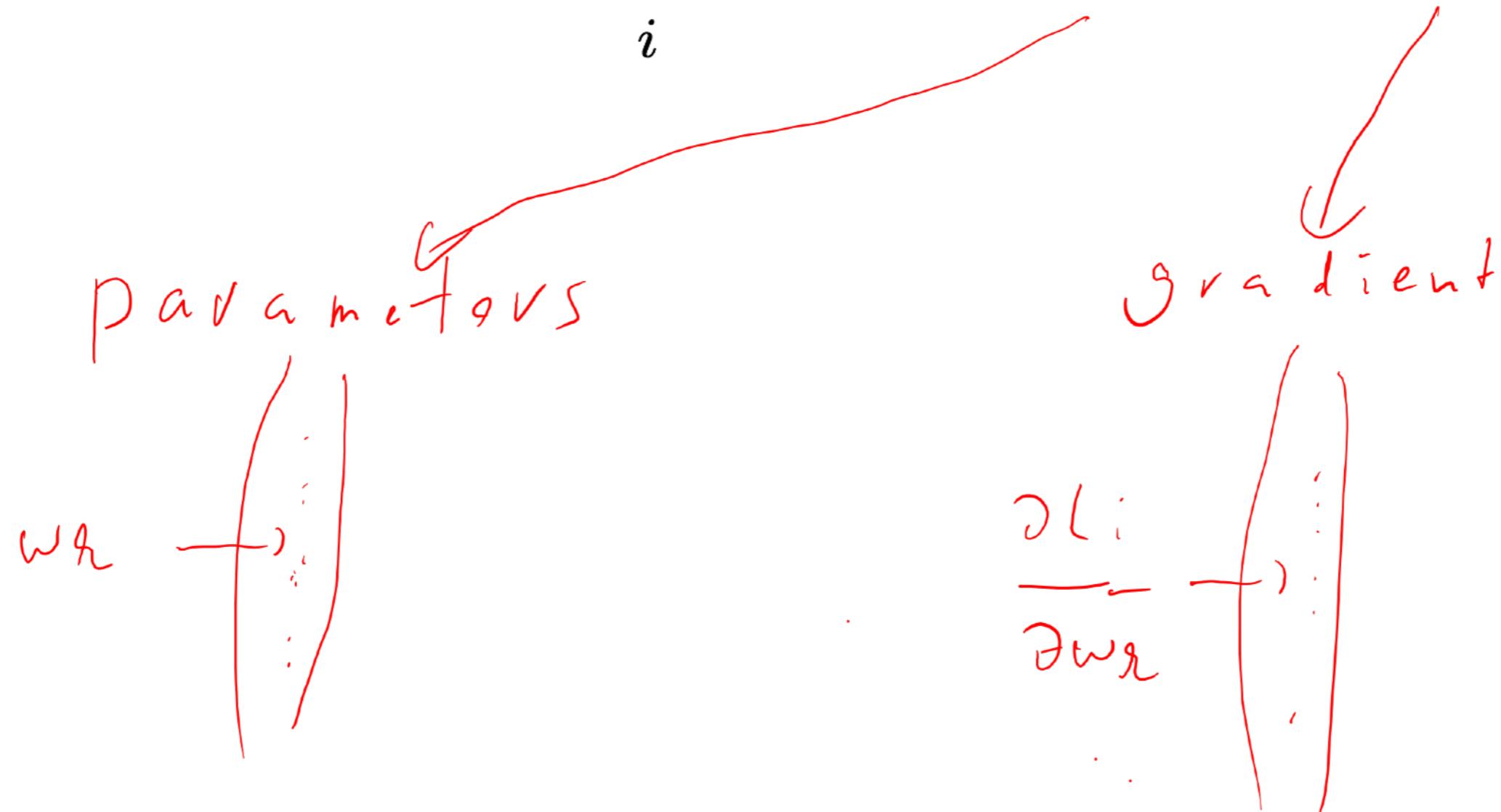


Backpropagation

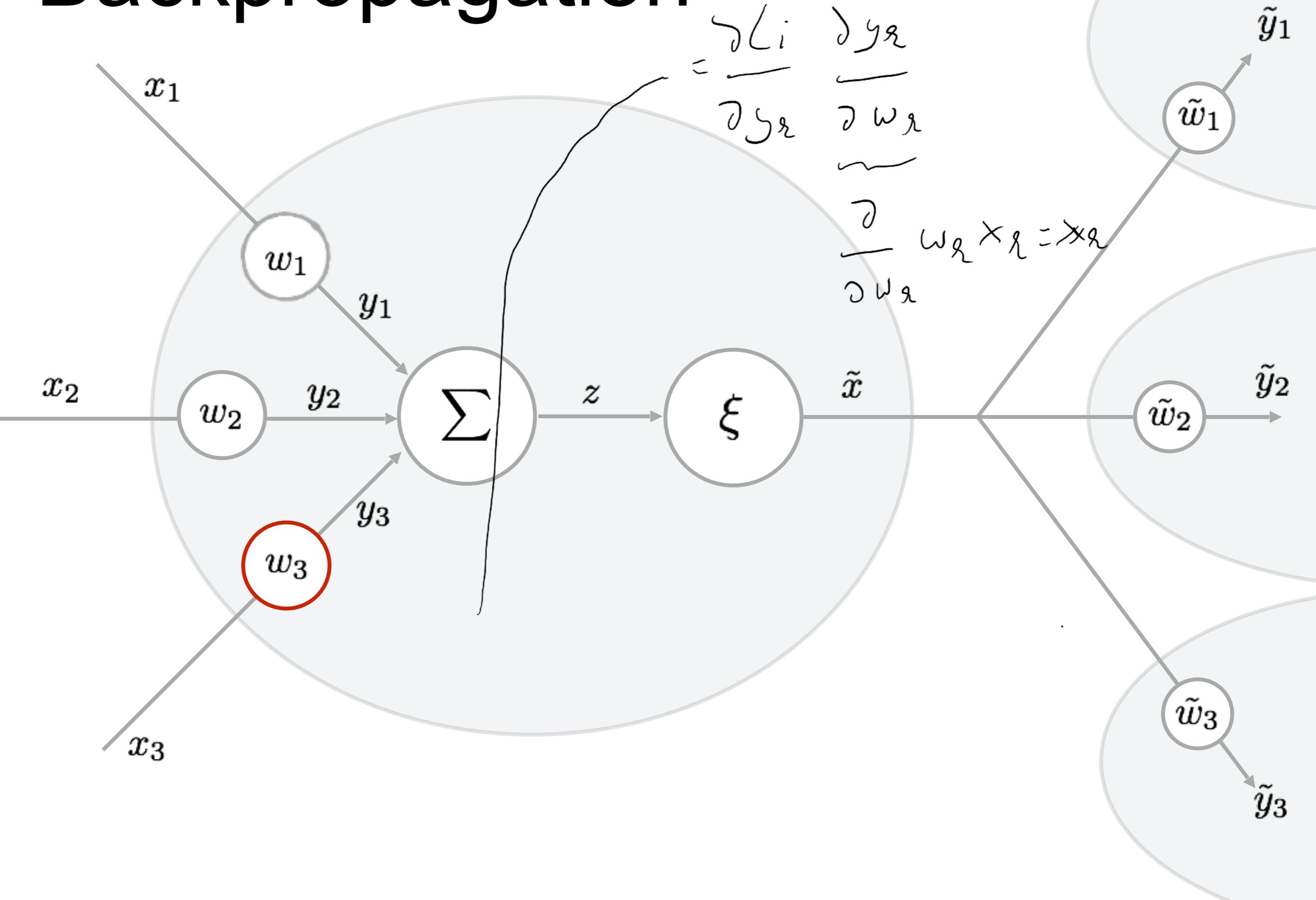


Stochastic Gradient Descent

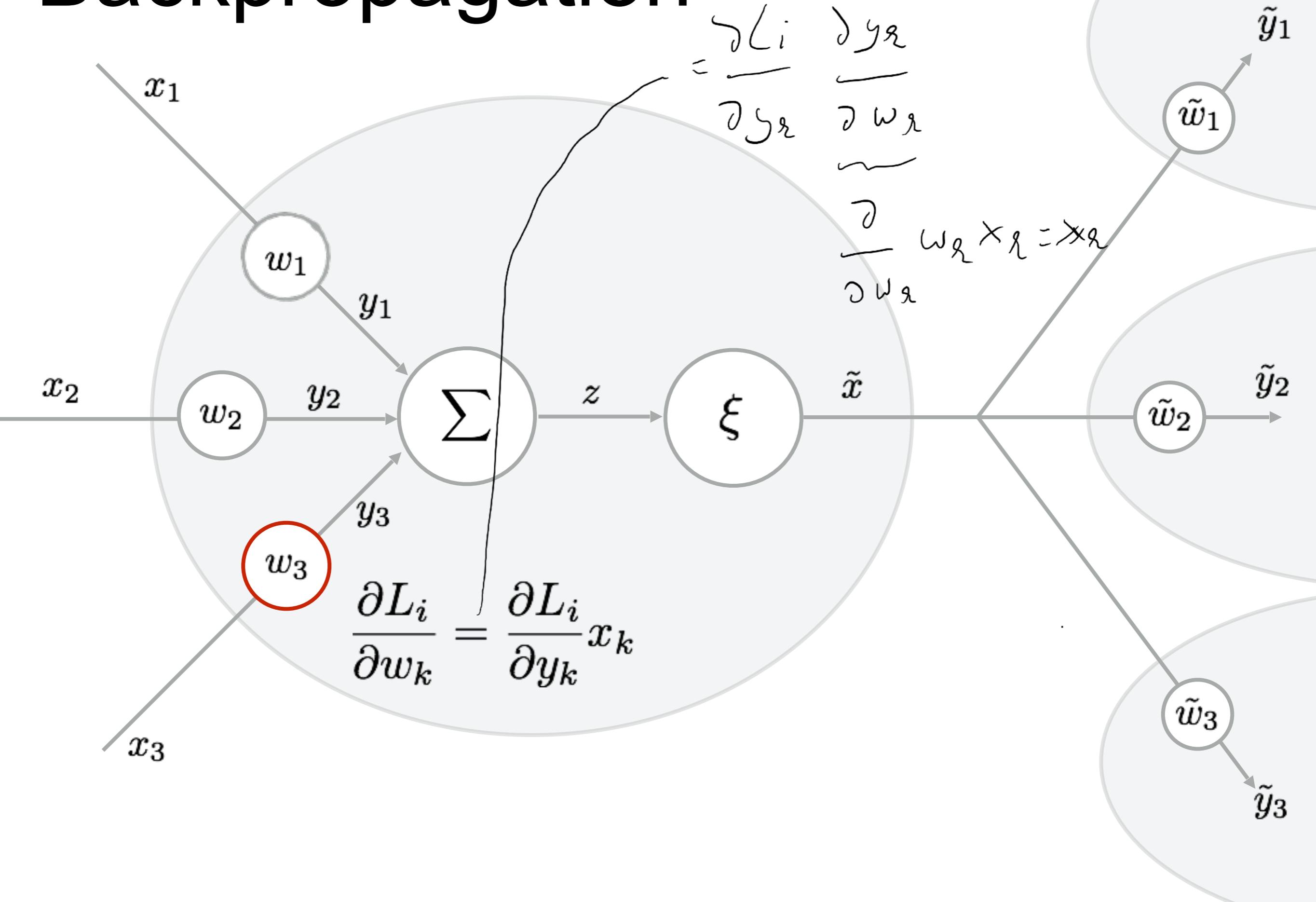
$$\theta^{(k+1)} = \theta^{(k)} - \mu \sum_i \nabla L_i(\theta) \approx \theta^{(k)} - \mu \nabla L_i(\theta)$$



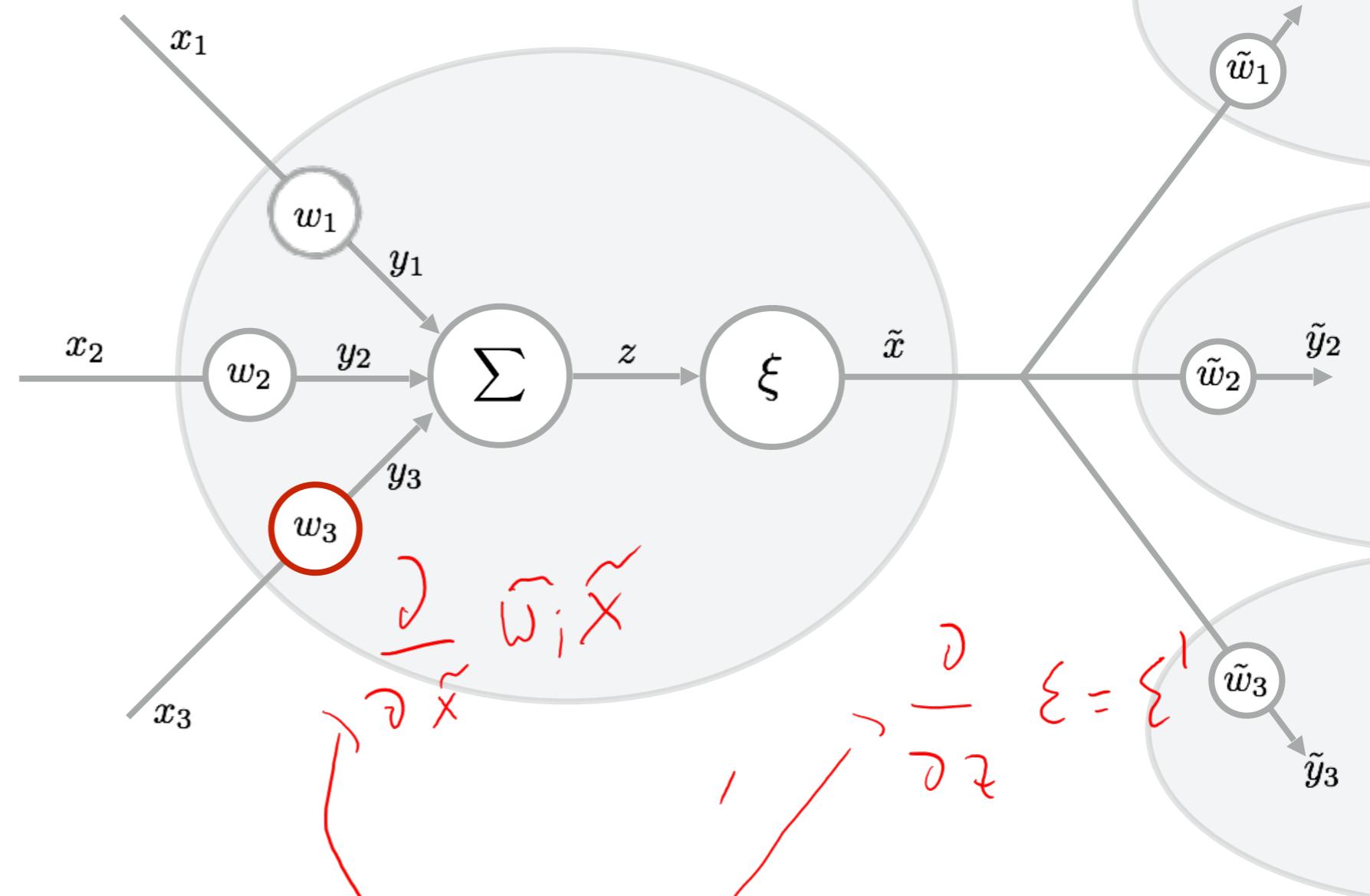
Backpropagation



Backpropagation



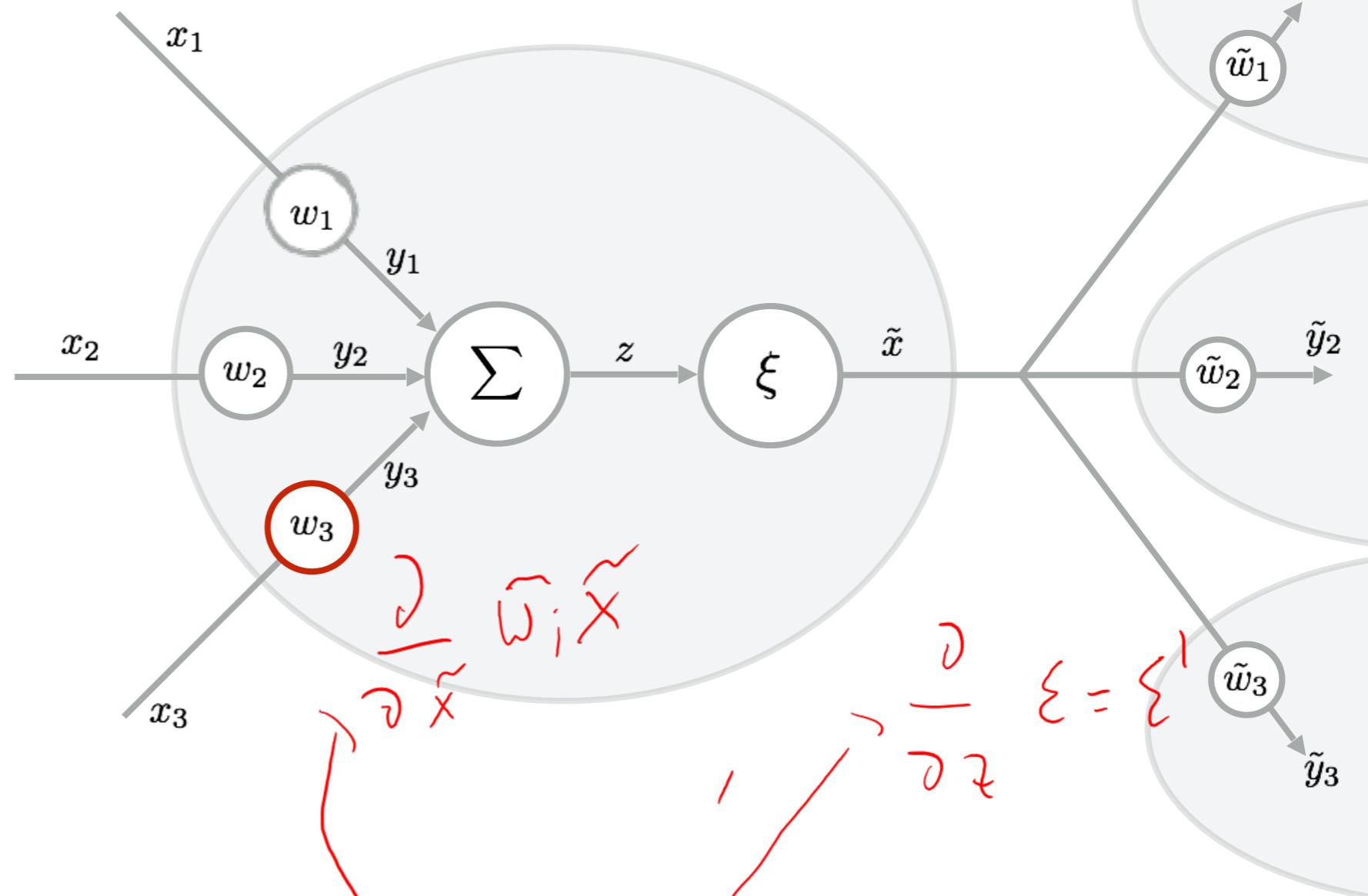
Backpropagation



$$\frac{\partial L_i}{\partial w_k} = \frac{\partial L_i}{\partial y_k} x_k$$

$$\frac{\partial}{\partial y_k} (\xi y_k) = 1$$

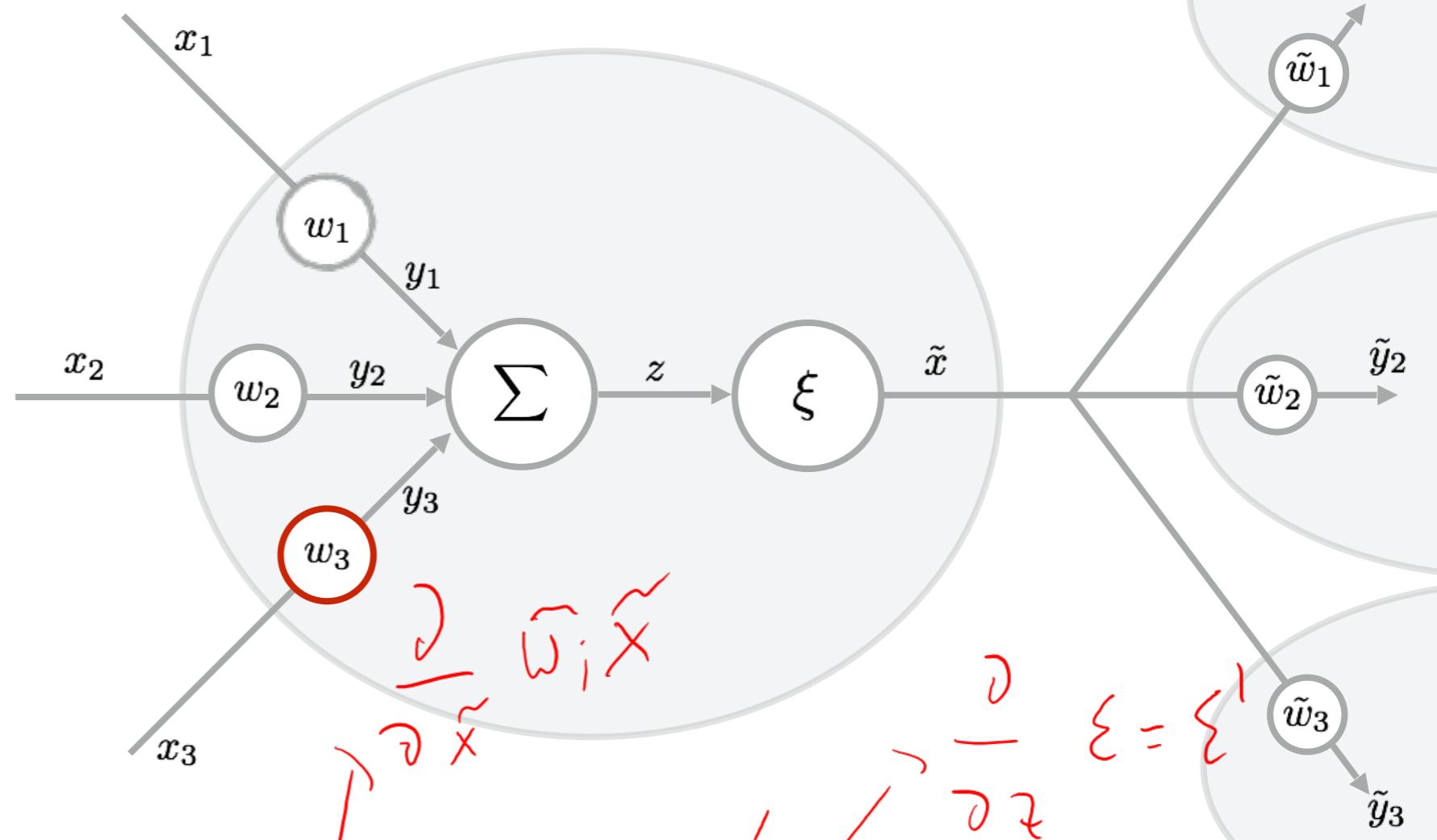
Backpropagation



$$\frac{\partial L_i}{\partial w_k} = \underbrace{\frac{\partial L_i}{\partial y_k}}_{x_k} x_k$$

$$\frac{\partial}{\partial z} (\xi y_i) = 1 \quad \text{if } \dots \cdot 1$$

Backpropagation



$$\frac{\partial L_i}{\partial w_k} = \underbrace{\frac{\partial L_i}{\partial y_k}}_{x_k} x_k$$

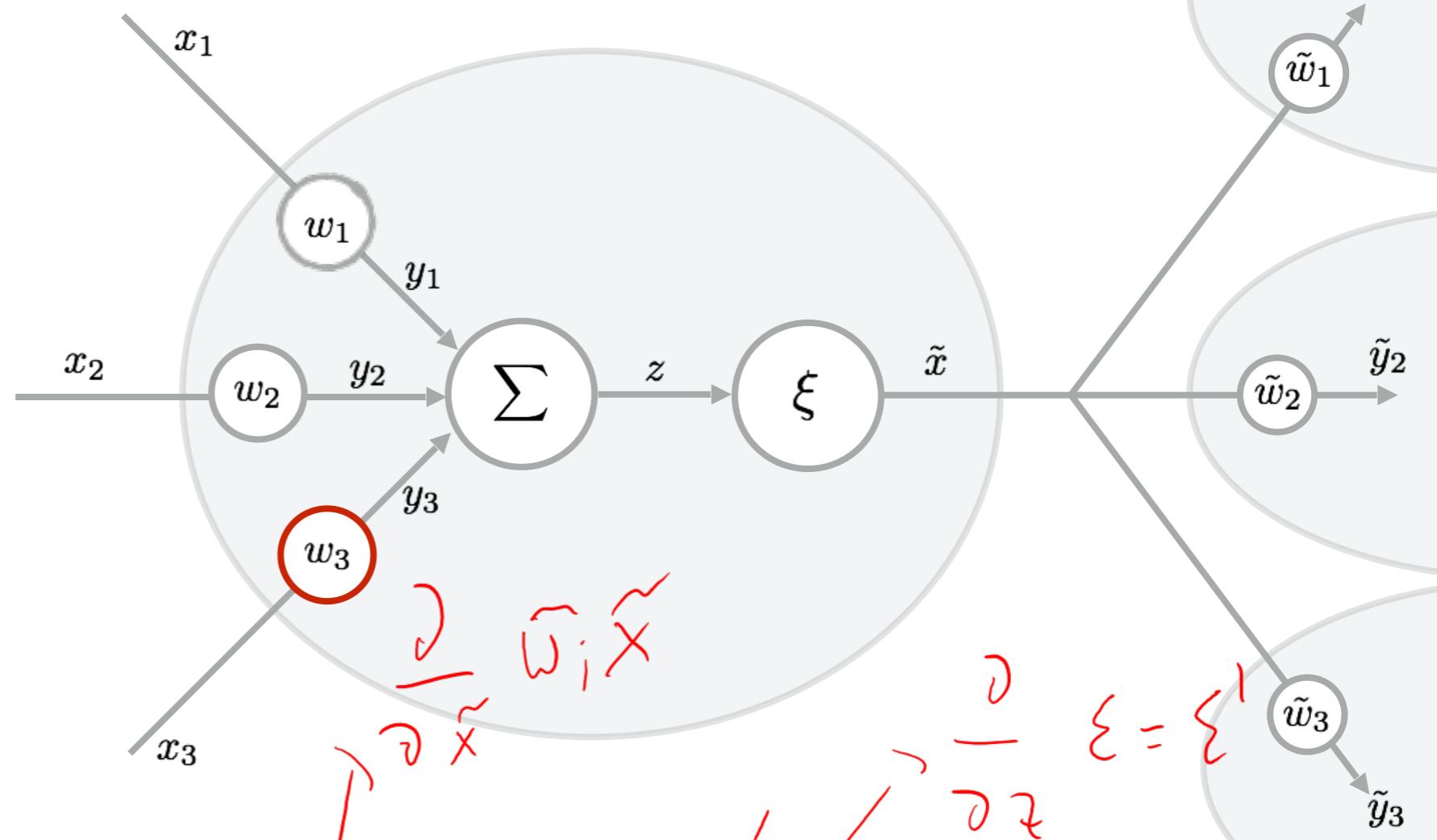
$$\frac{\partial L_i}{\partial y_k} = \sum_j \frac{\partial L_i}{\partial \tilde{y}_j} \frac{\partial \tilde{y}_j}{\partial y_k}$$

$$\frac{\partial}{\partial y_k} (\epsilon y_k) = 1$$

Q

• 1

Backpropagation



$$\frac{\partial L_i}{\partial w_k} = \underbrace{\frac{\partial L_i}{\partial y_k}}_{x_k} x_k$$

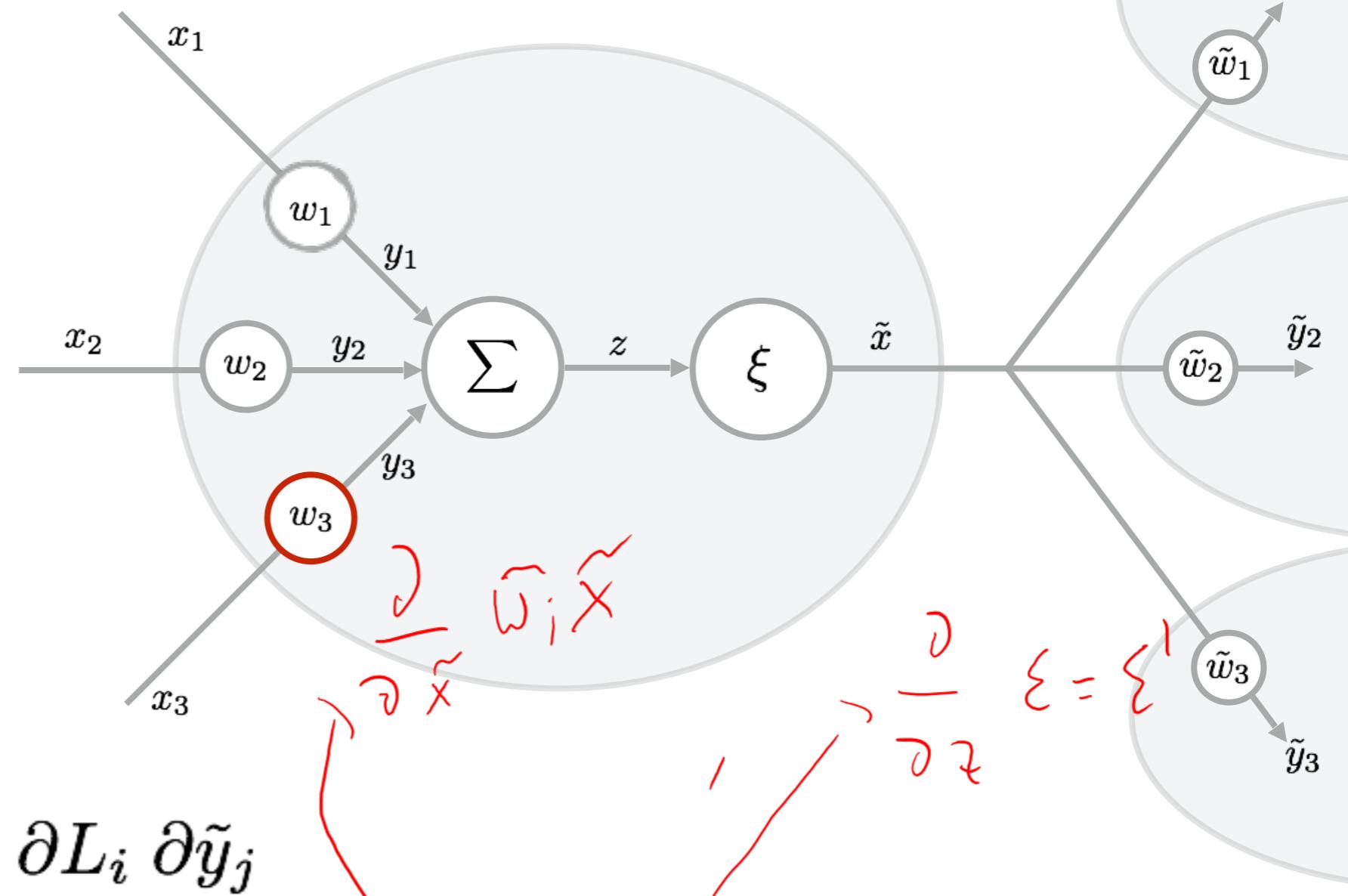
$$\frac{\partial L_i}{\partial y_k} = \sum_j \frac{\partial L_i}{\partial \tilde{y}_j} \underbrace{\frac{\partial \tilde{y}_j}{\partial y_k}}_1$$

$$\frac{\partial}{\partial \xi} (\xi y_i) = 1$$

α

$\cdot 1$

Backpropagation



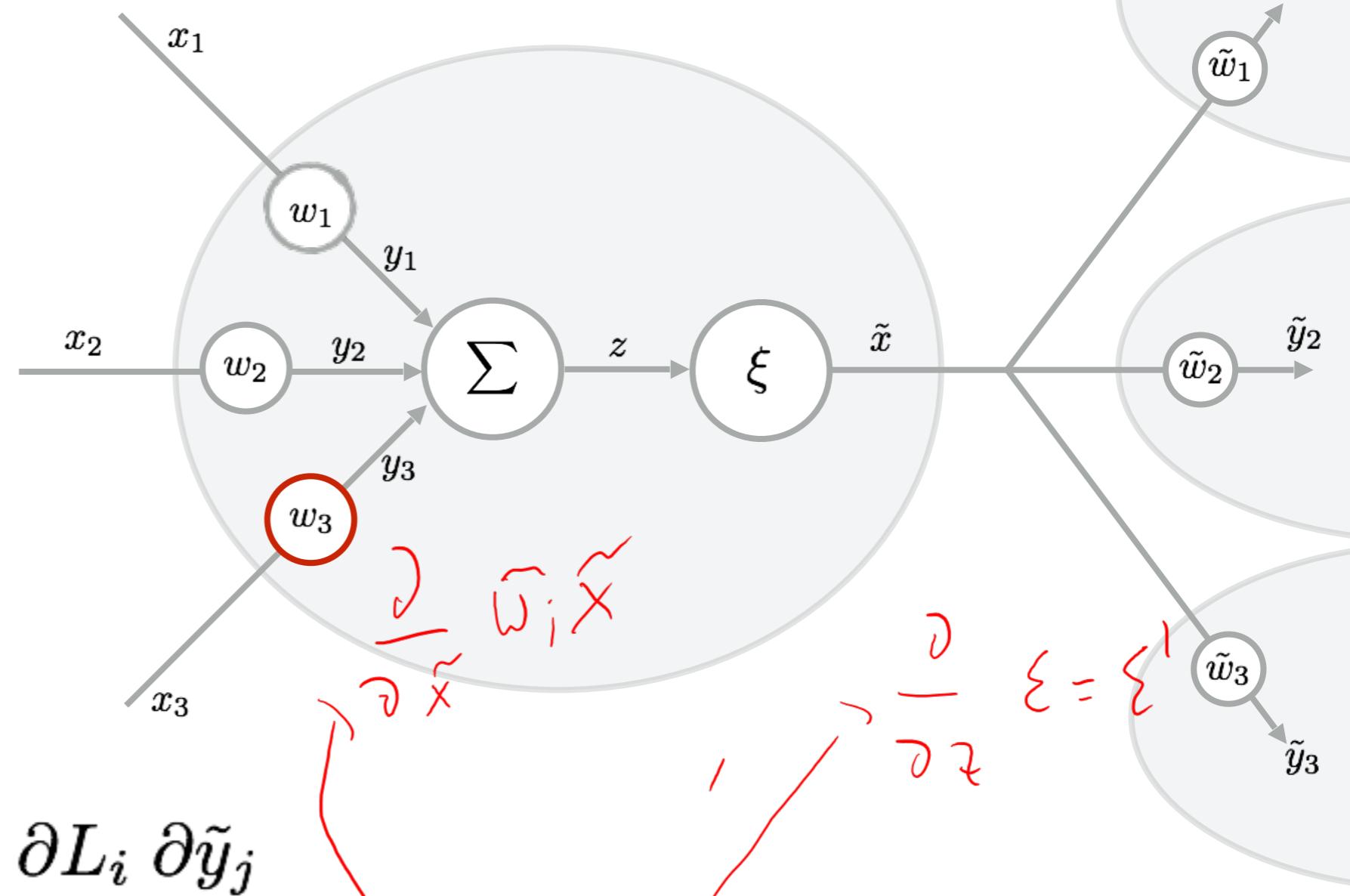
$$\frac{\partial}{\partial y_k} (\xi y_k) = 1$$

Q

$$\frac{\partial \tilde{y}_j}{\partial y_k} = \frac{\partial \tilde{y}_j}{\partial \tilde{x}} \frac{\partial \tilde{x}}{\partial z} \frac{\partial z}{\partial y_k}$$

• 1

Backpropagation

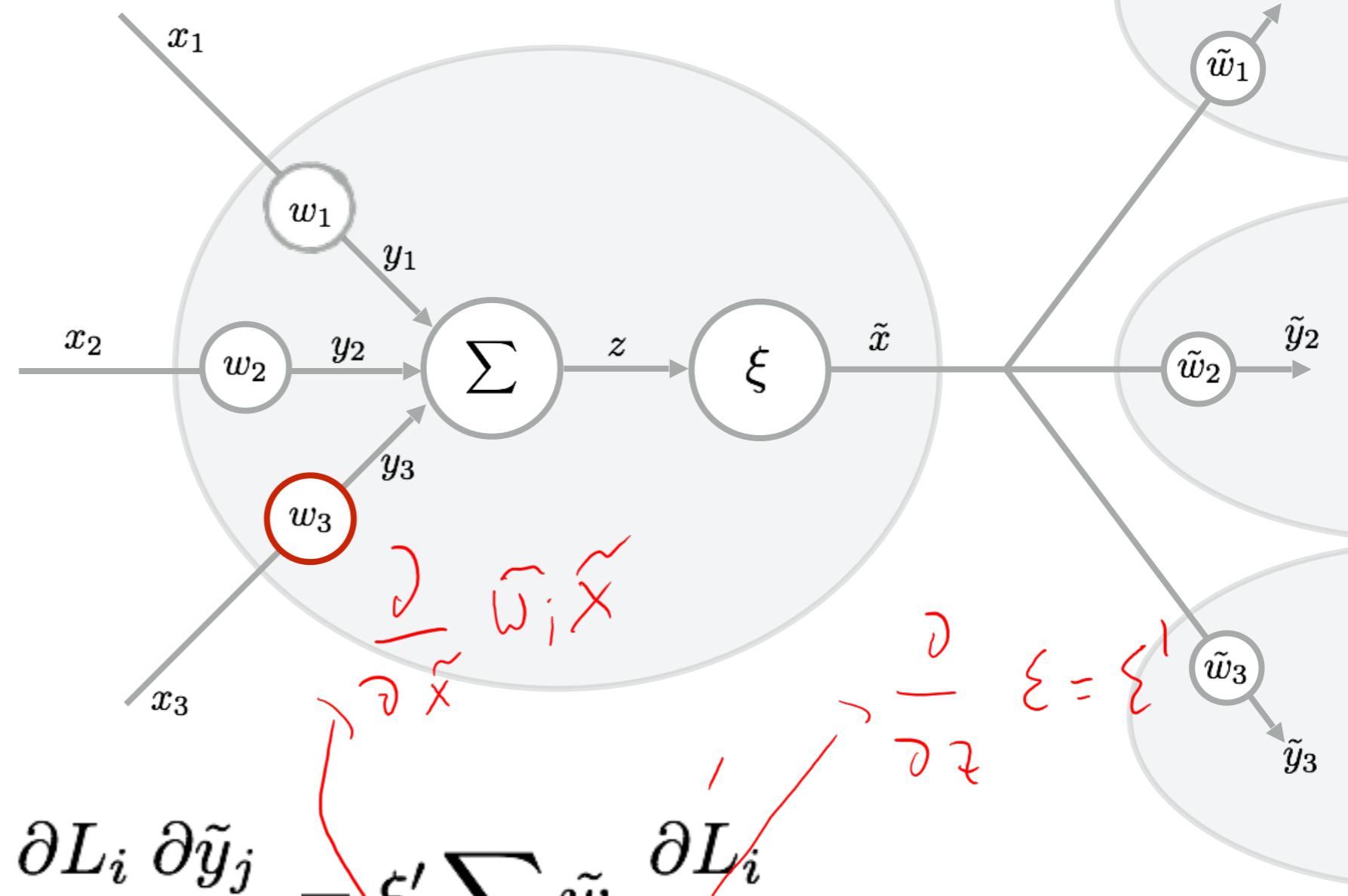


$$\frac{\partial}{\partial \xi} (\xi y_i) = 1$$

Q

$$\frac{\partial \tilde{y}_j}{\partial y_k} = \frac{\partial \tilde{y}_j}{\partial \tilde{x}} \frac{\partial \tilde{x}}{\partial z} \frac{\partial z}{\partial y_k} = \tilde{w}_j \xi' \cdot 1$$

Backpropagation

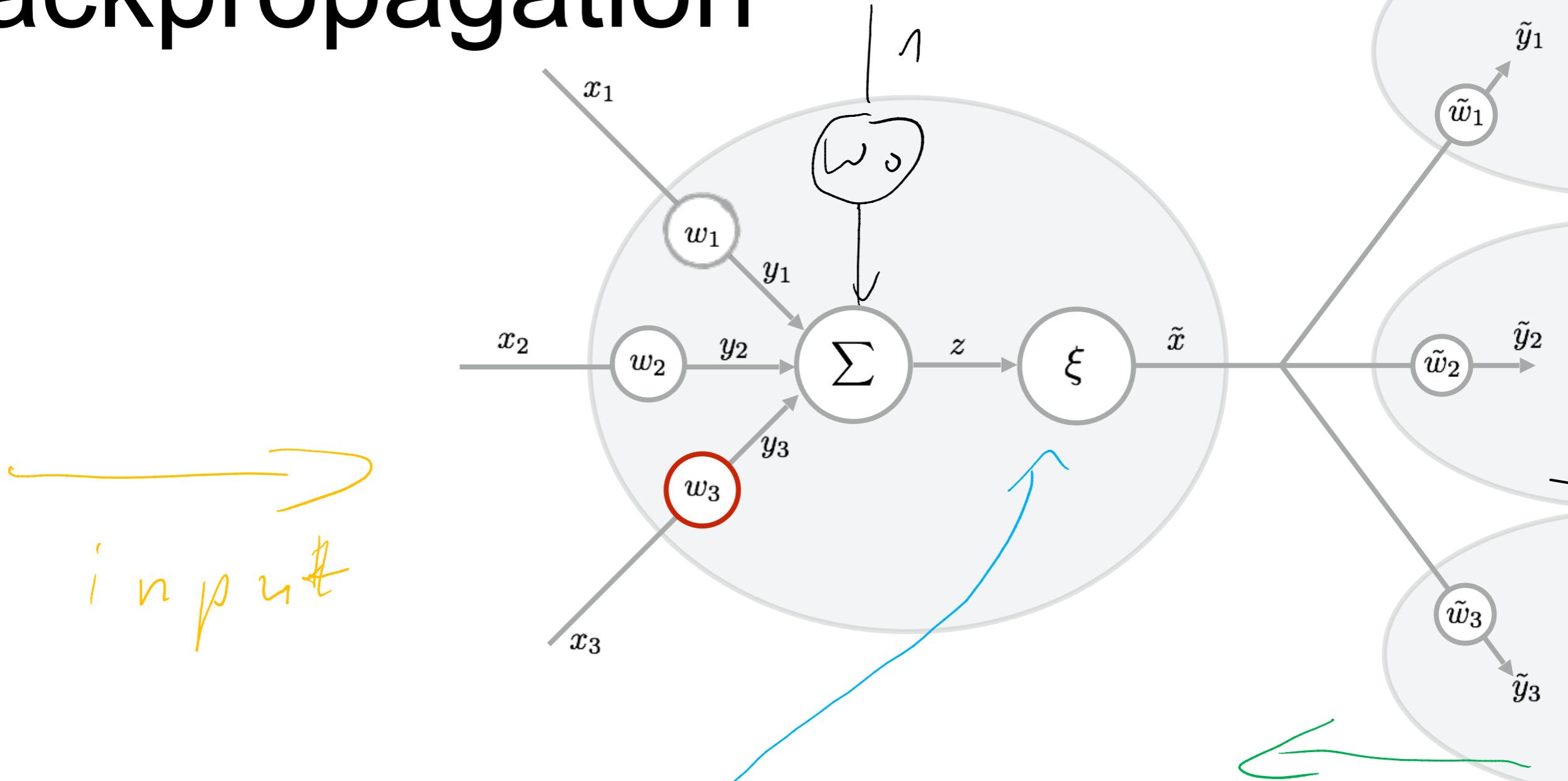


$$\frac{\partial}{\partial \xi} (\xi y_i) = 1$$

Q

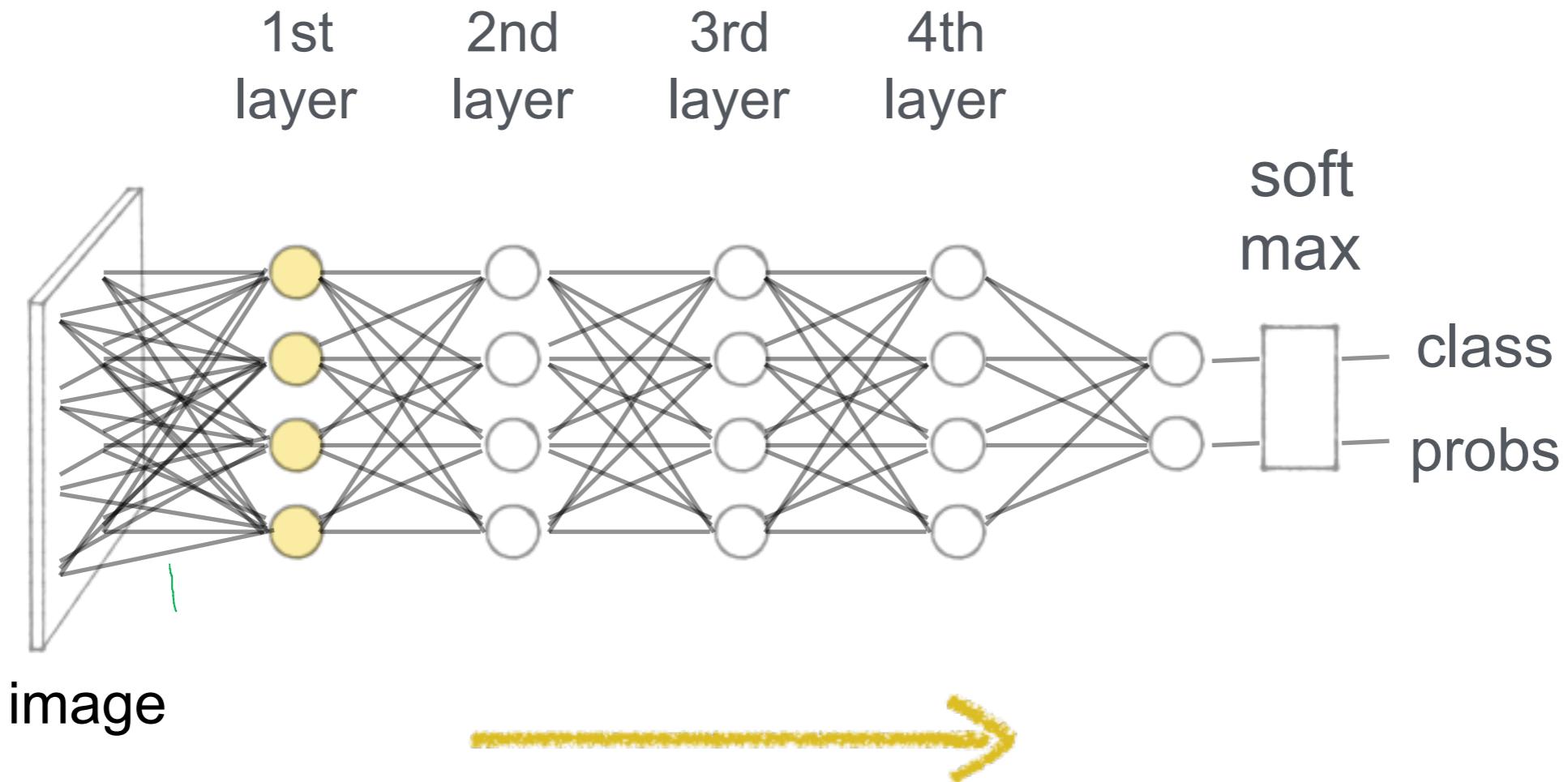
$$\frac{\partial \tilde{y}_j}{\partial y_k} = \frac{\partial \tilde{y}_j}{\partial \tilde{x}} \frac{\partial \tilde{x}}{\partial z} \frac{\partial z}{\partial y_k} = \tilde{w}_j \xi' \cdot 1$$

Backpropagation



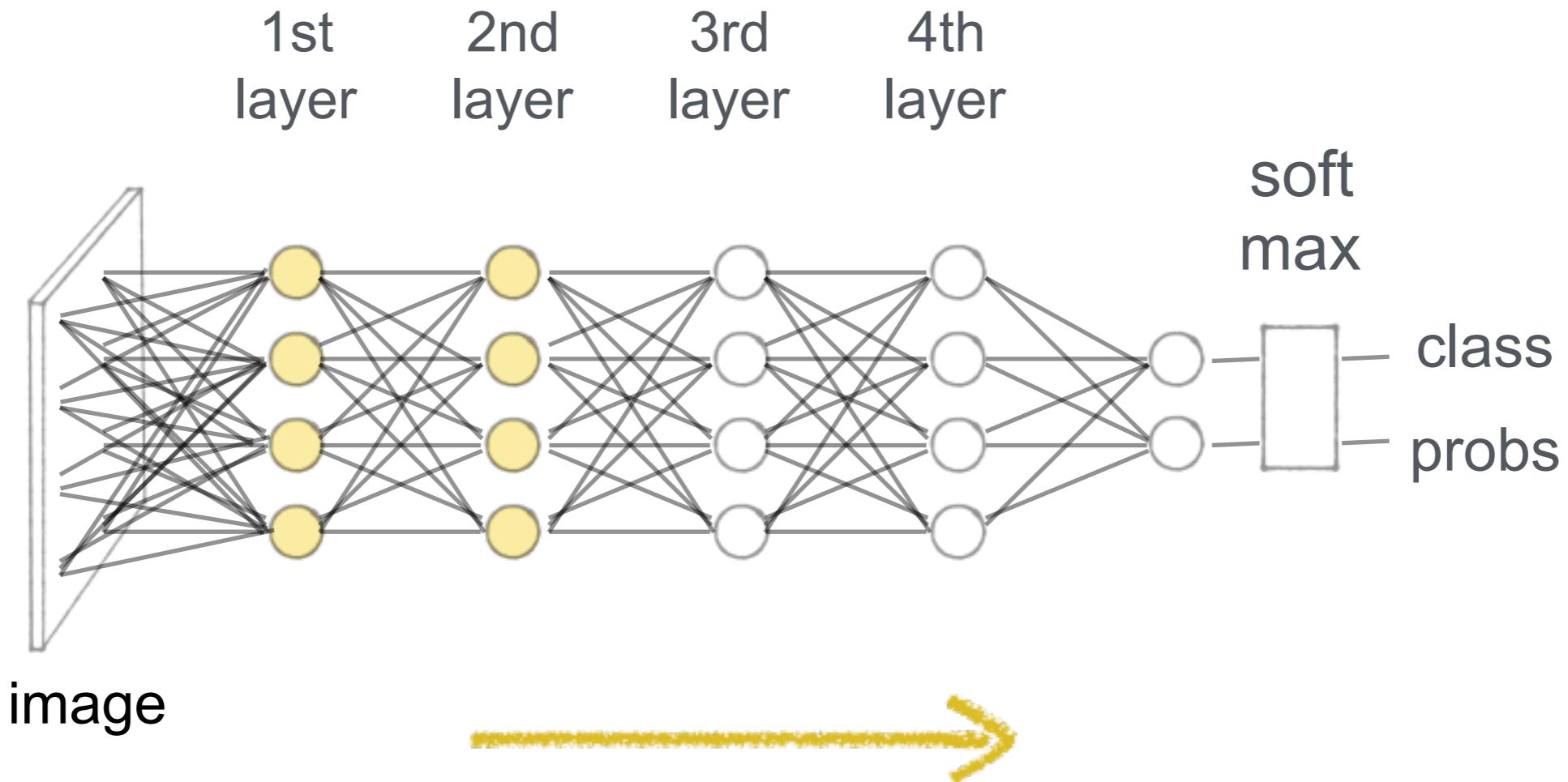
$$\frac{\partial L_i}{\partial w_k} = \cancel{x_k \xi'} \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backprop: Forward Pass



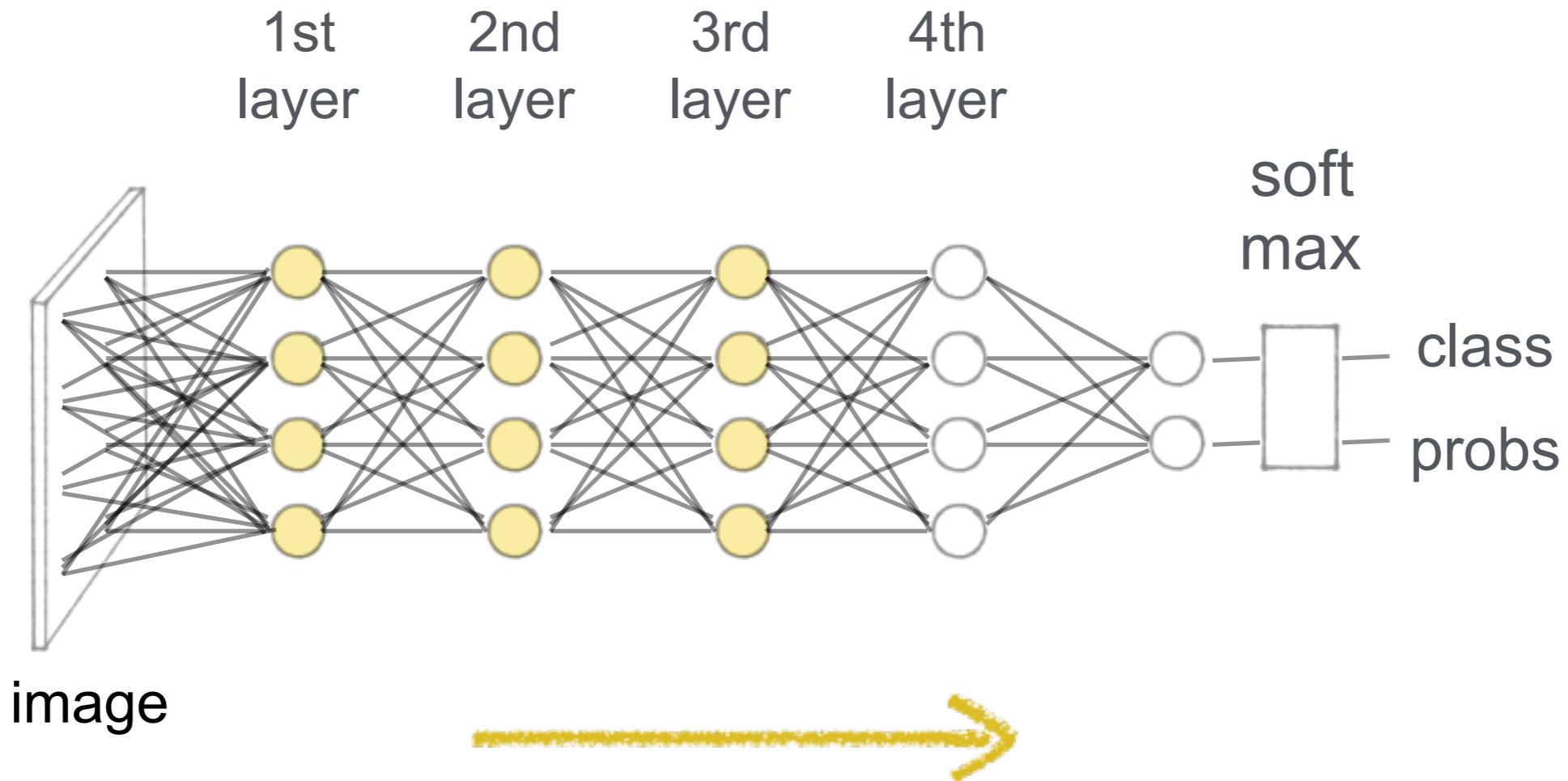
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backprop: Forward Pass



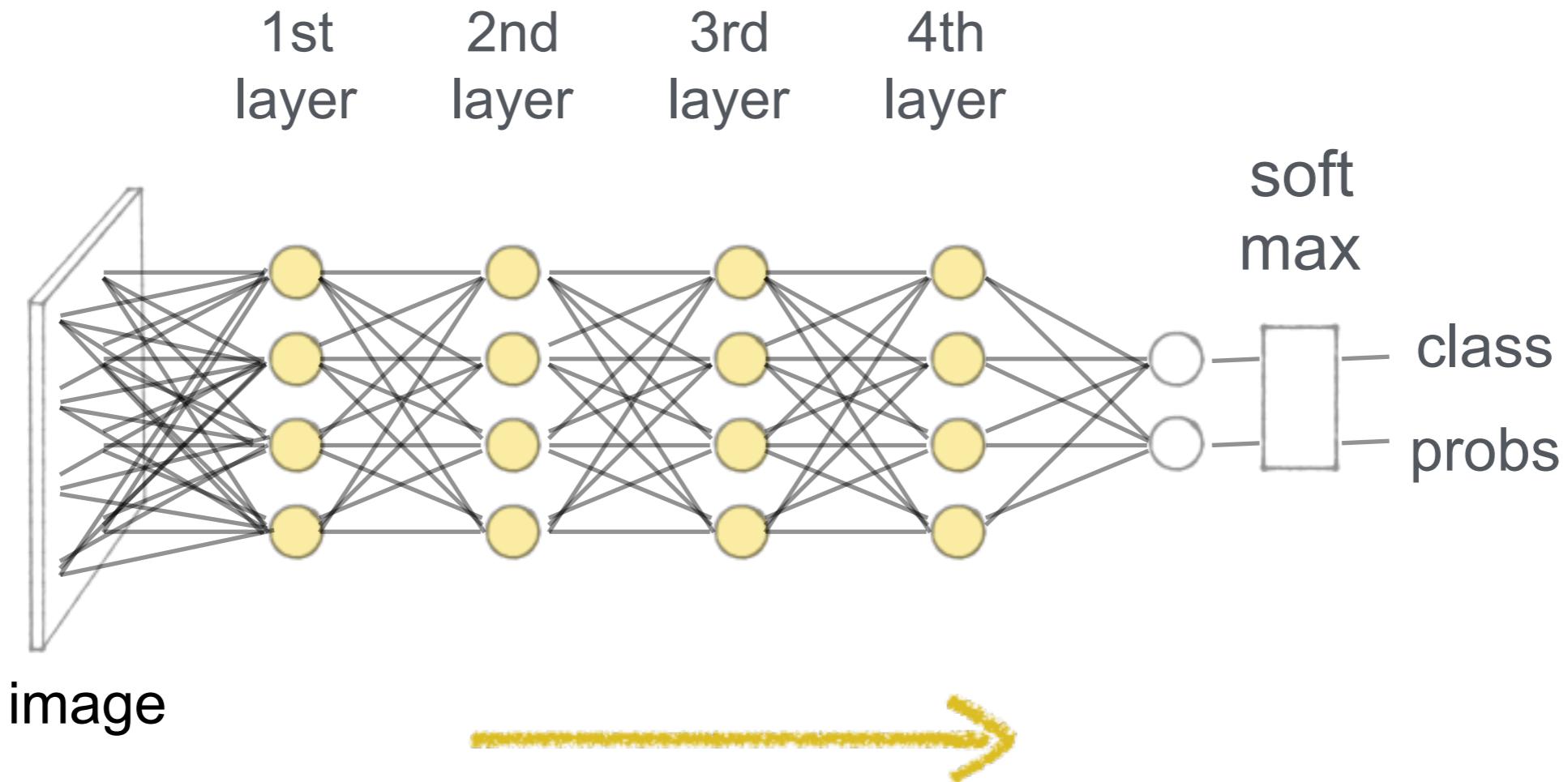
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backprop: Forward Pass



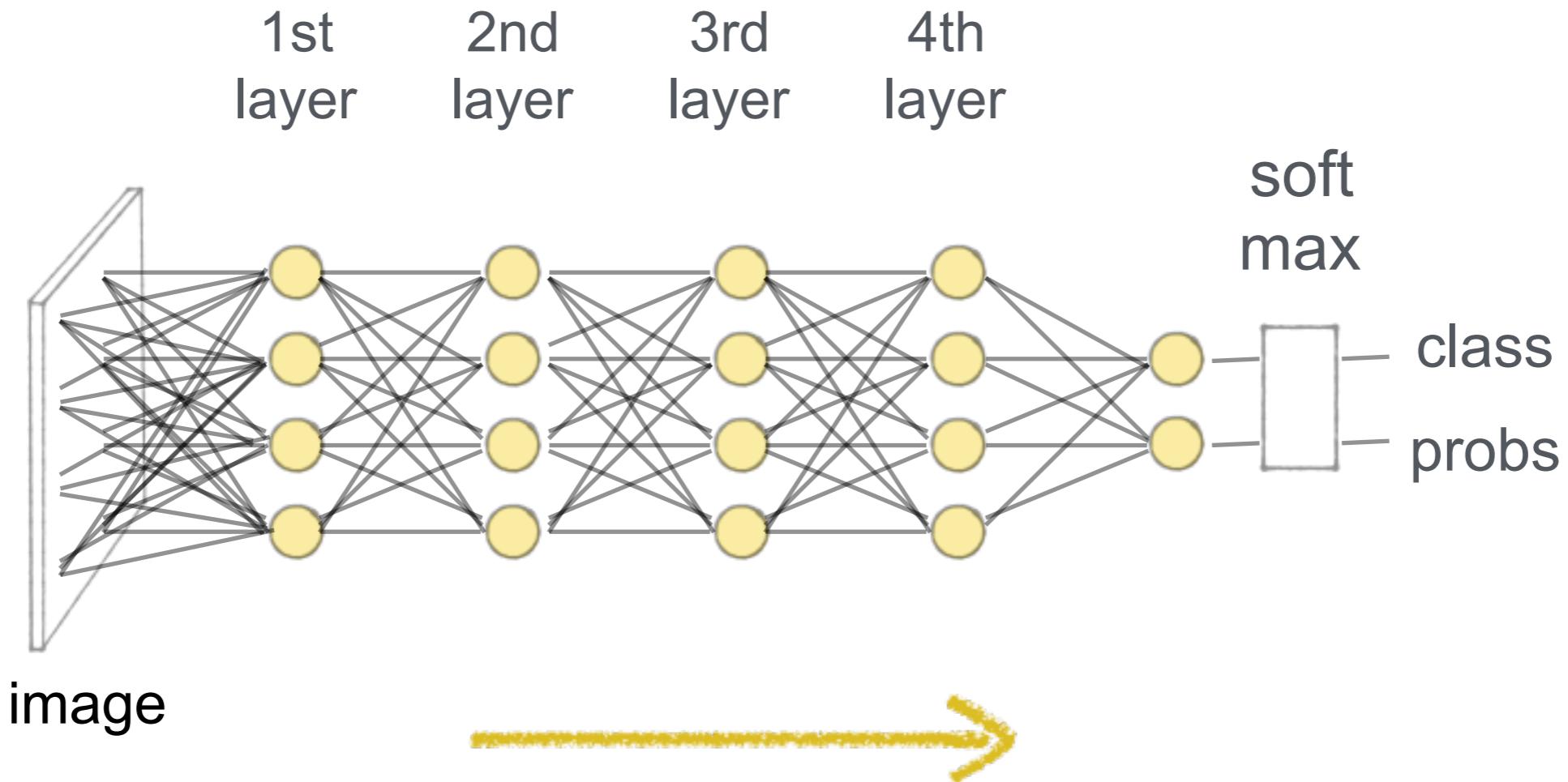
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backprop: Forward Pass



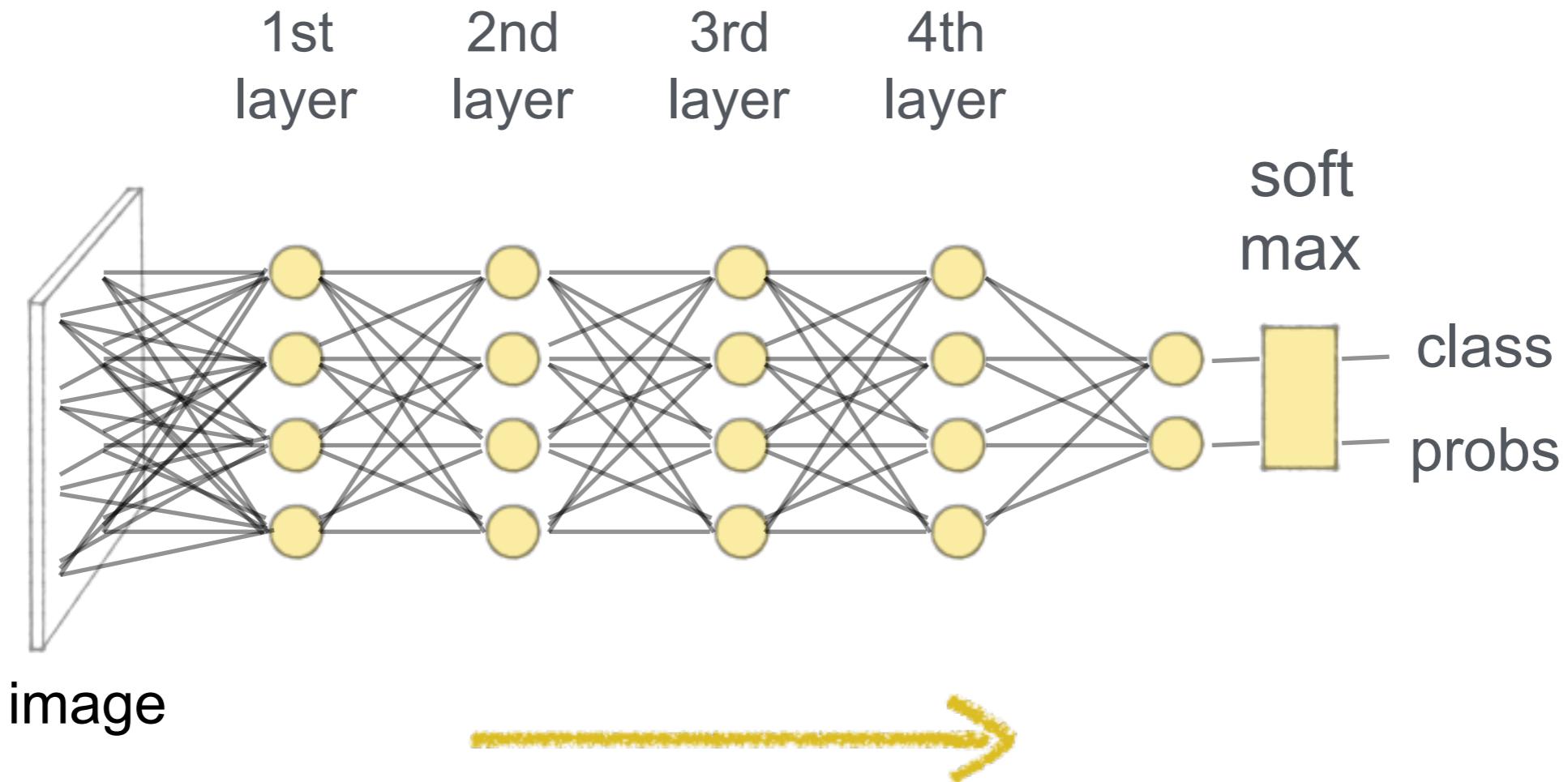
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backprop: Forward Pass



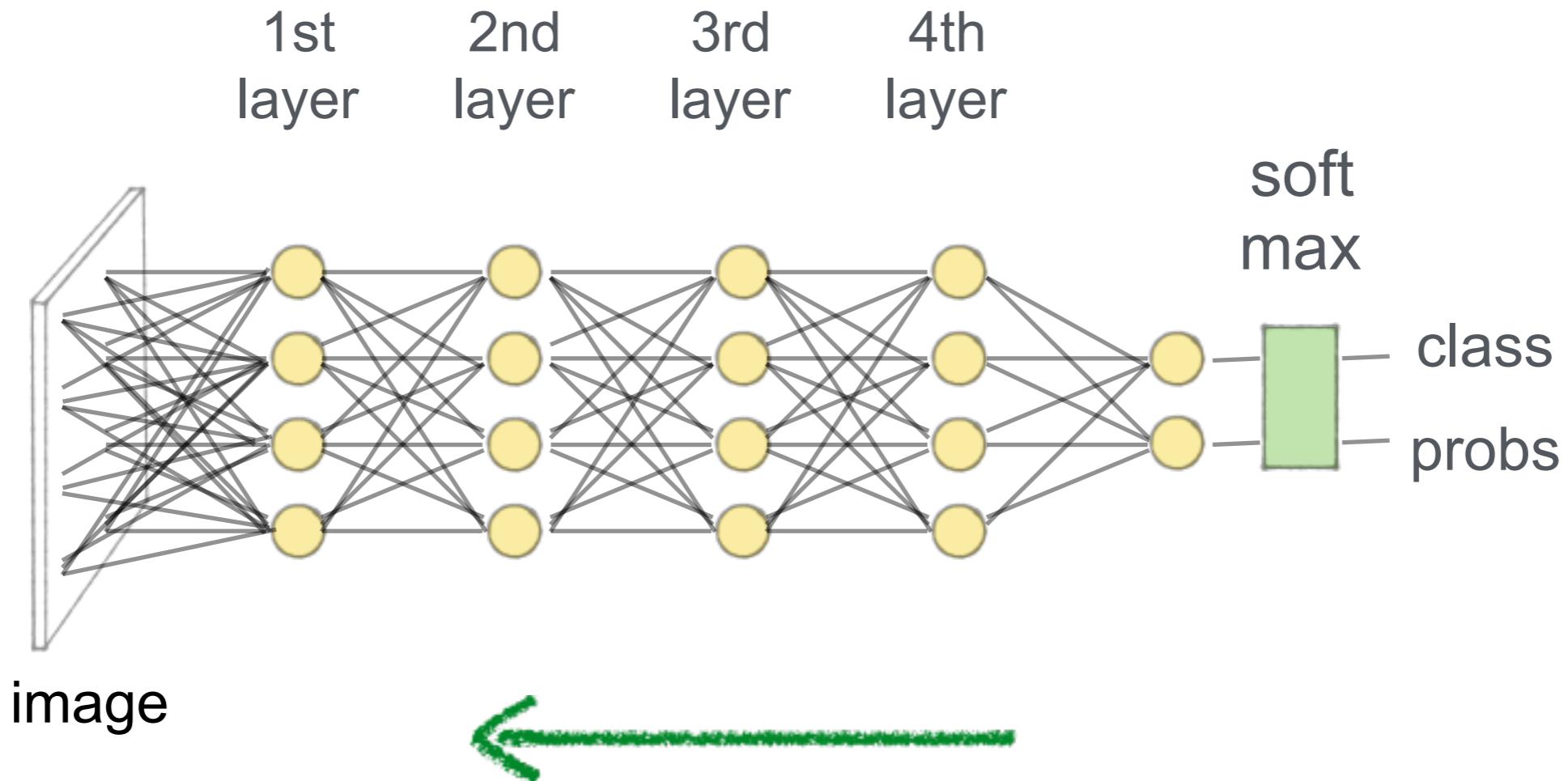
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backprop: Forward Pass



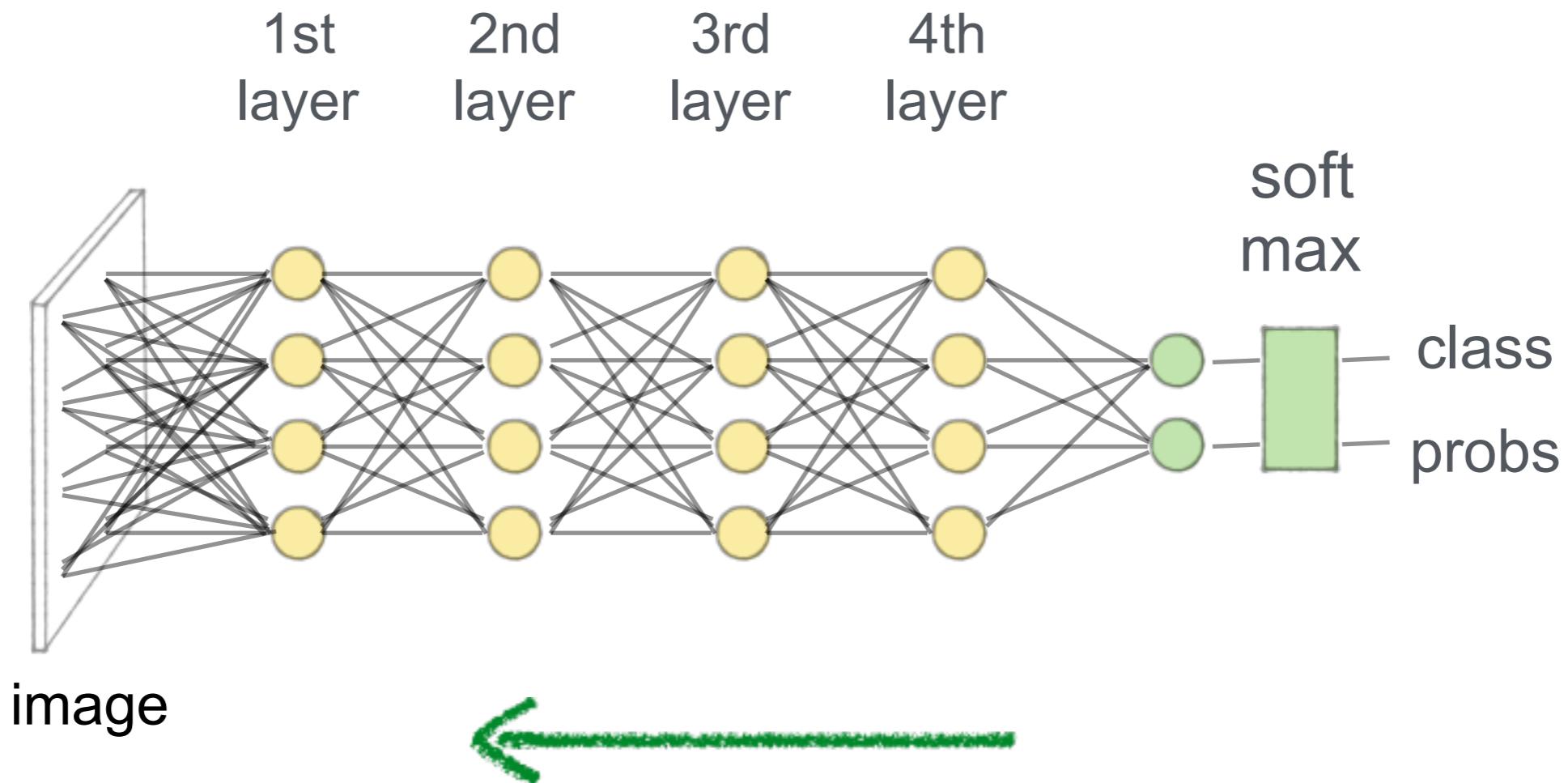
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backpropagation



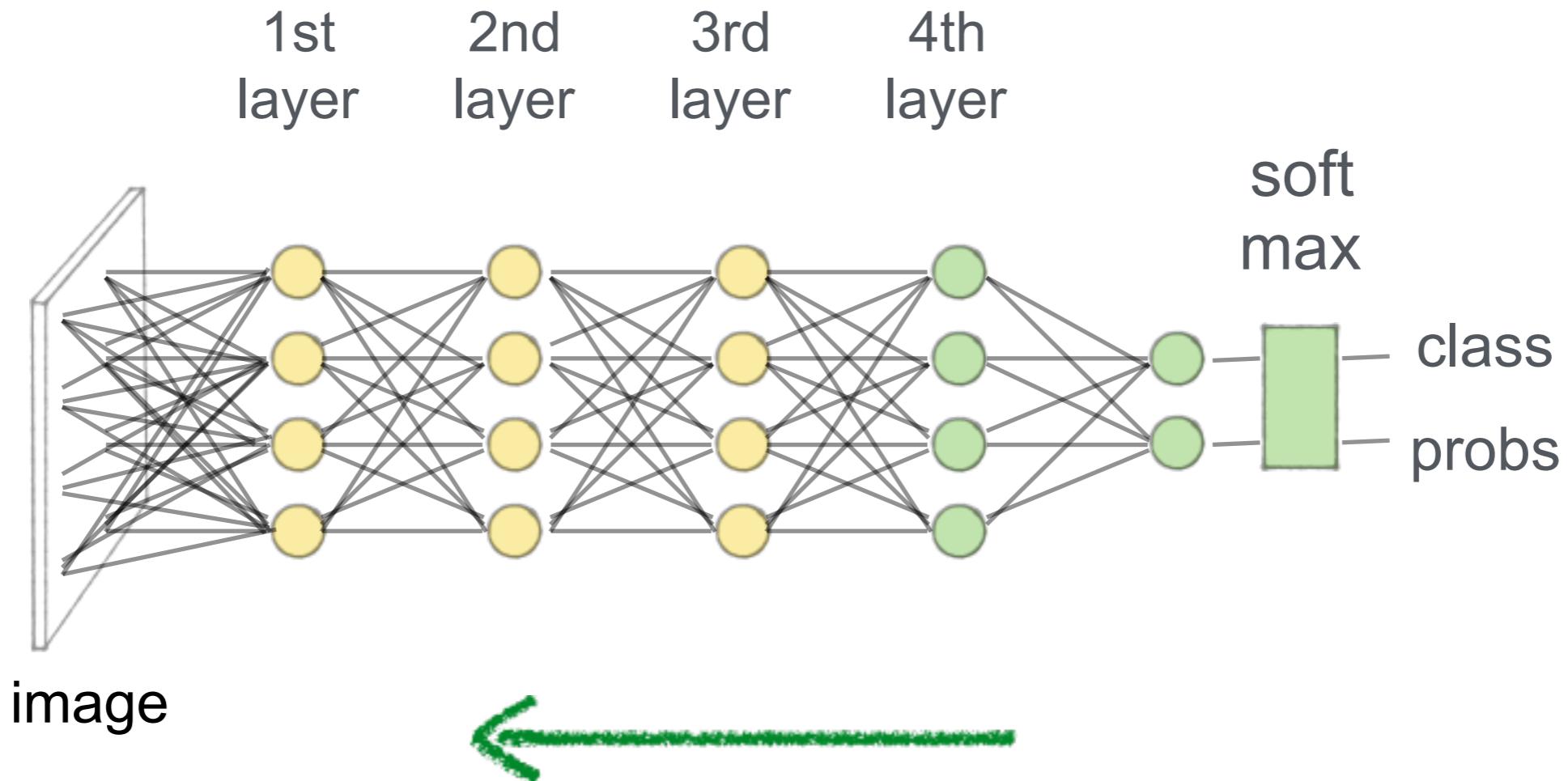
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \underline{\frac{\partial L_i}{\partial \tilde{y}_j}}$$

Backpropagation



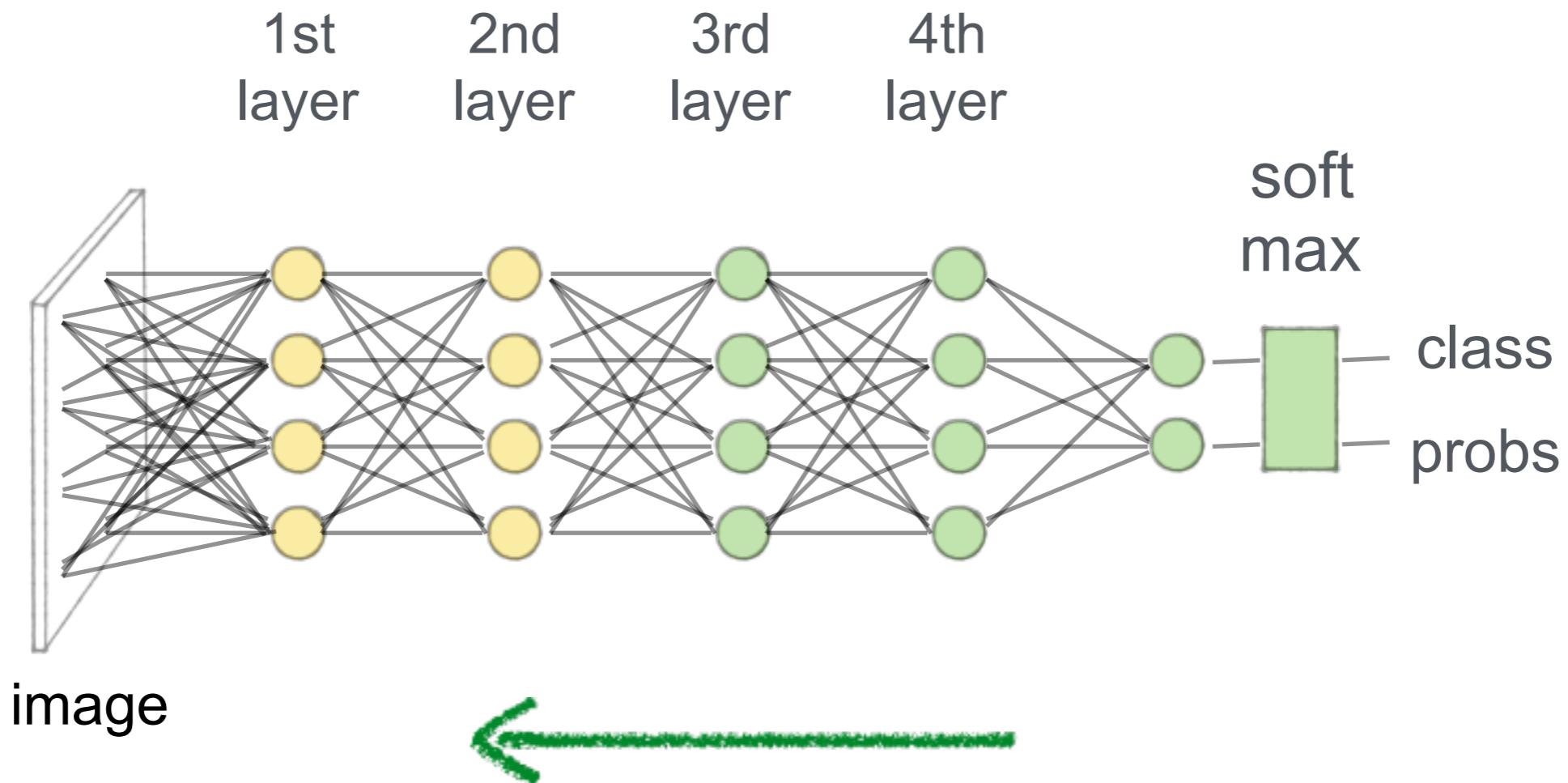
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \underline{\frac{\partial L_i}{\partial \tilde{y}_j}}$$

Backpropagation



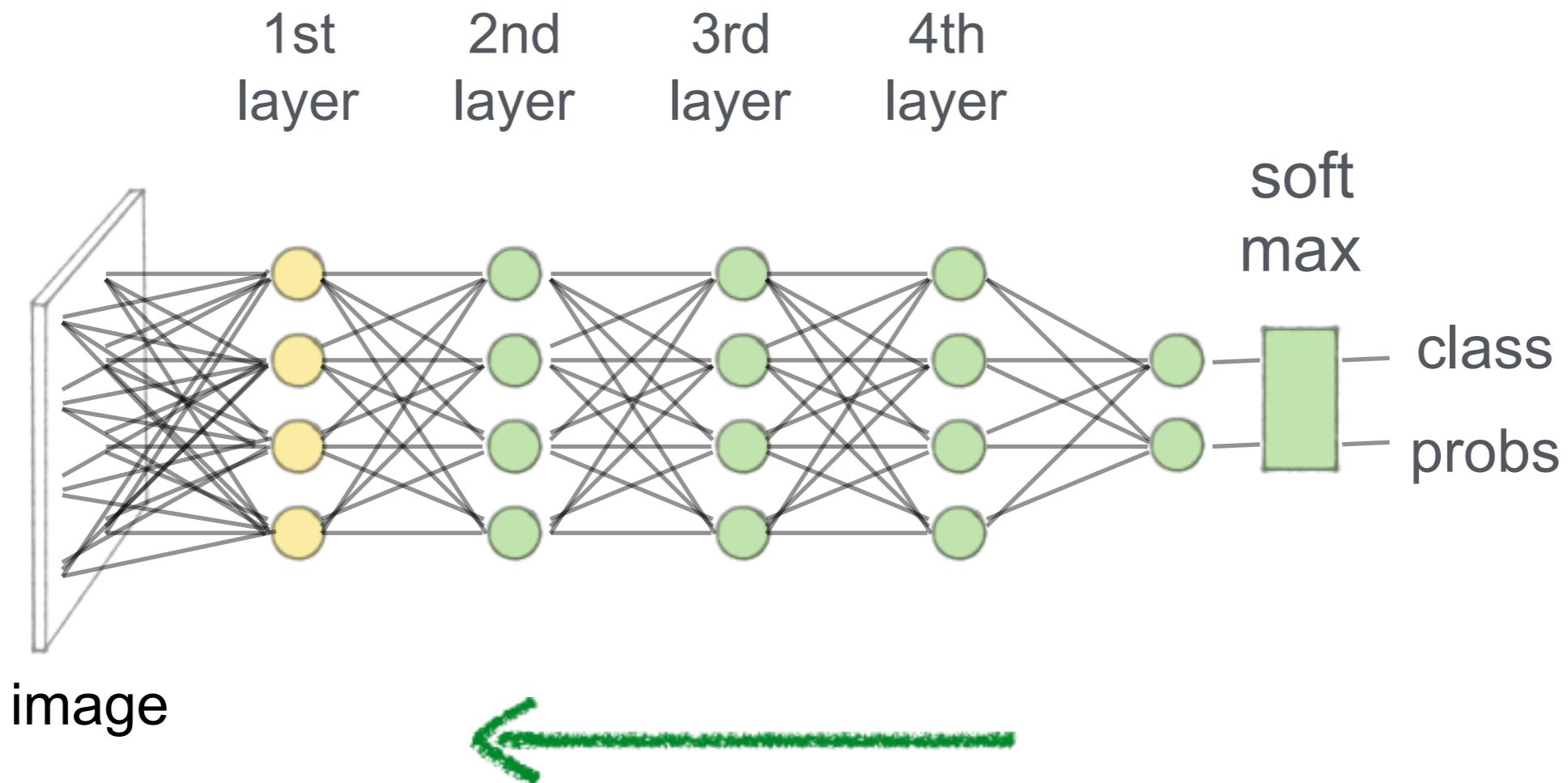
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \underline{\frac{\partial L_i}{\partial \tilde{y}_j}}$$

Backpropagation



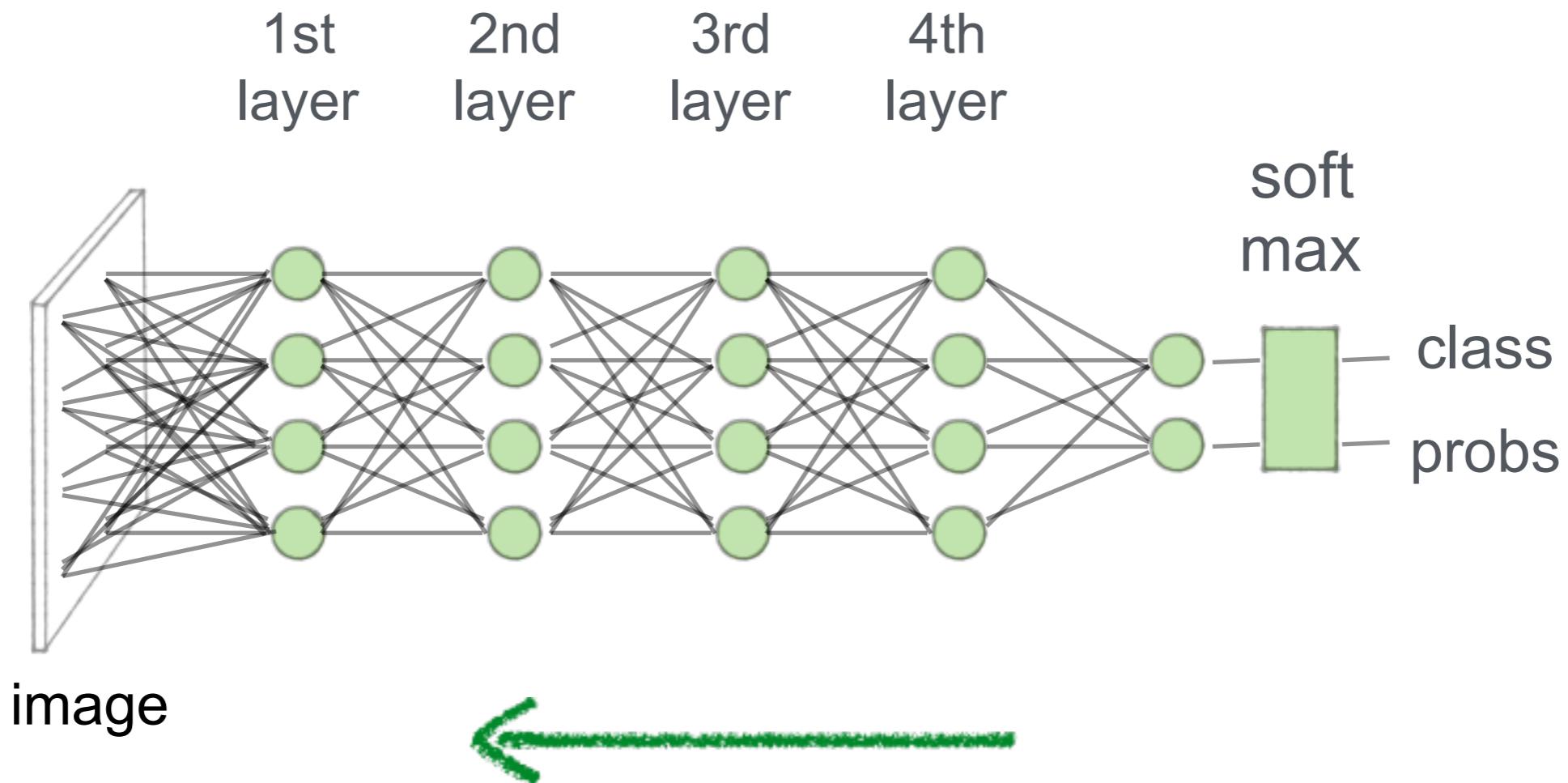
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backpropagation



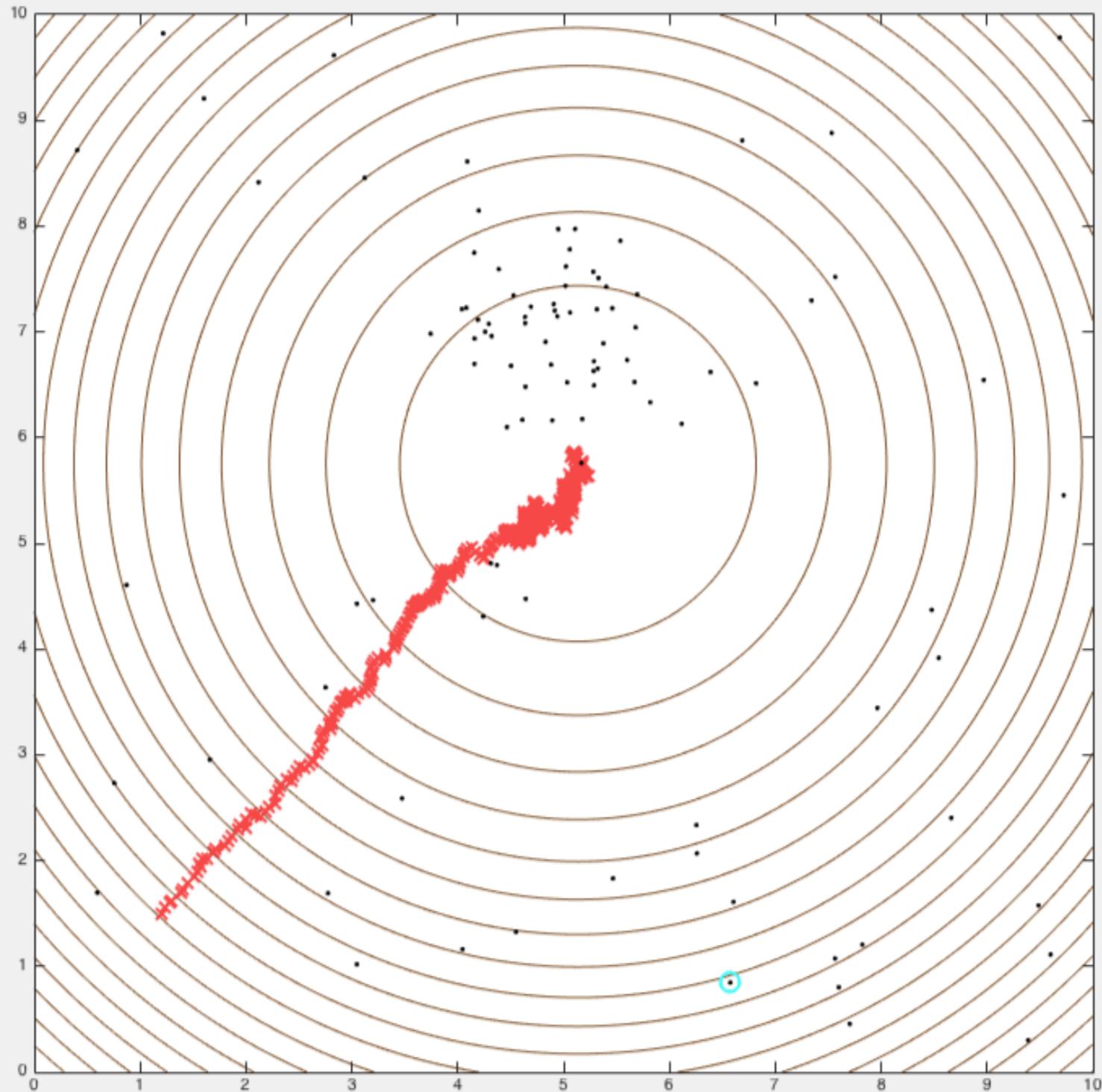
$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

Backpropagation

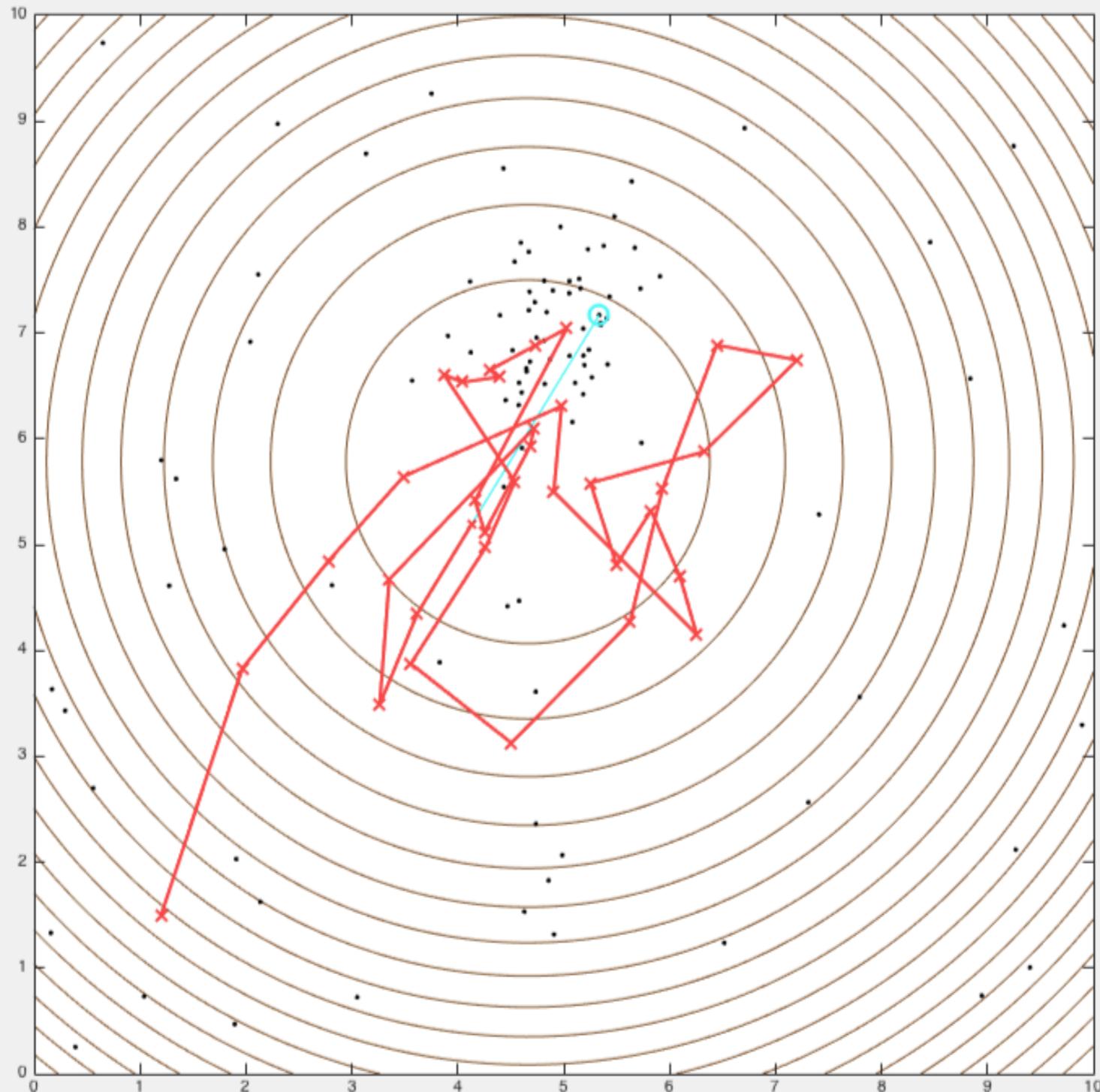


$$\frac{\partial L_i}{\partial w_k} = \underline{x_k} \xi' \sum_j \tilde{w}_j \frac{\partial L_i}{\partial \tilde{y}_j}$$

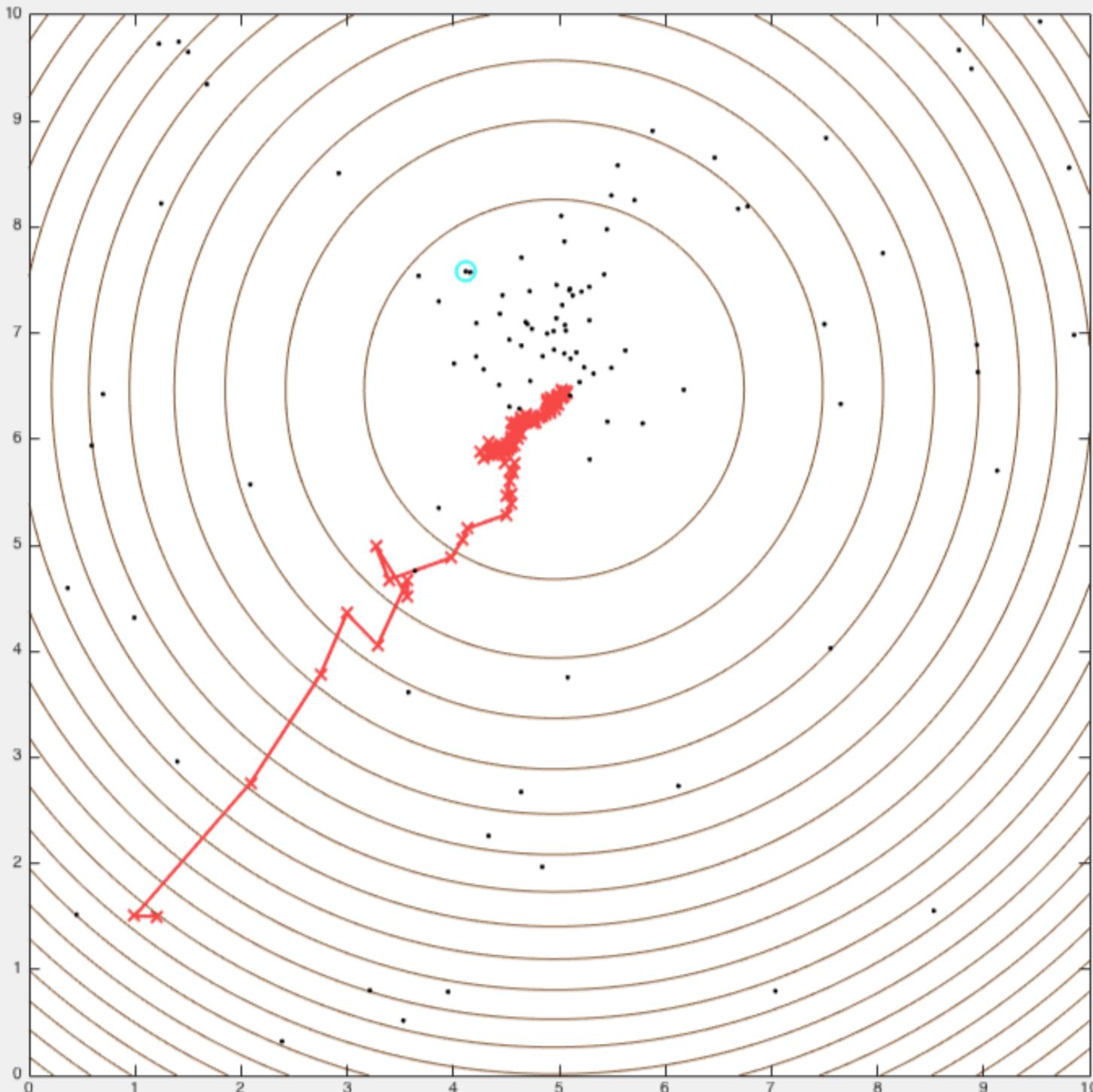
Small Learning Rate



Large Learning Rate

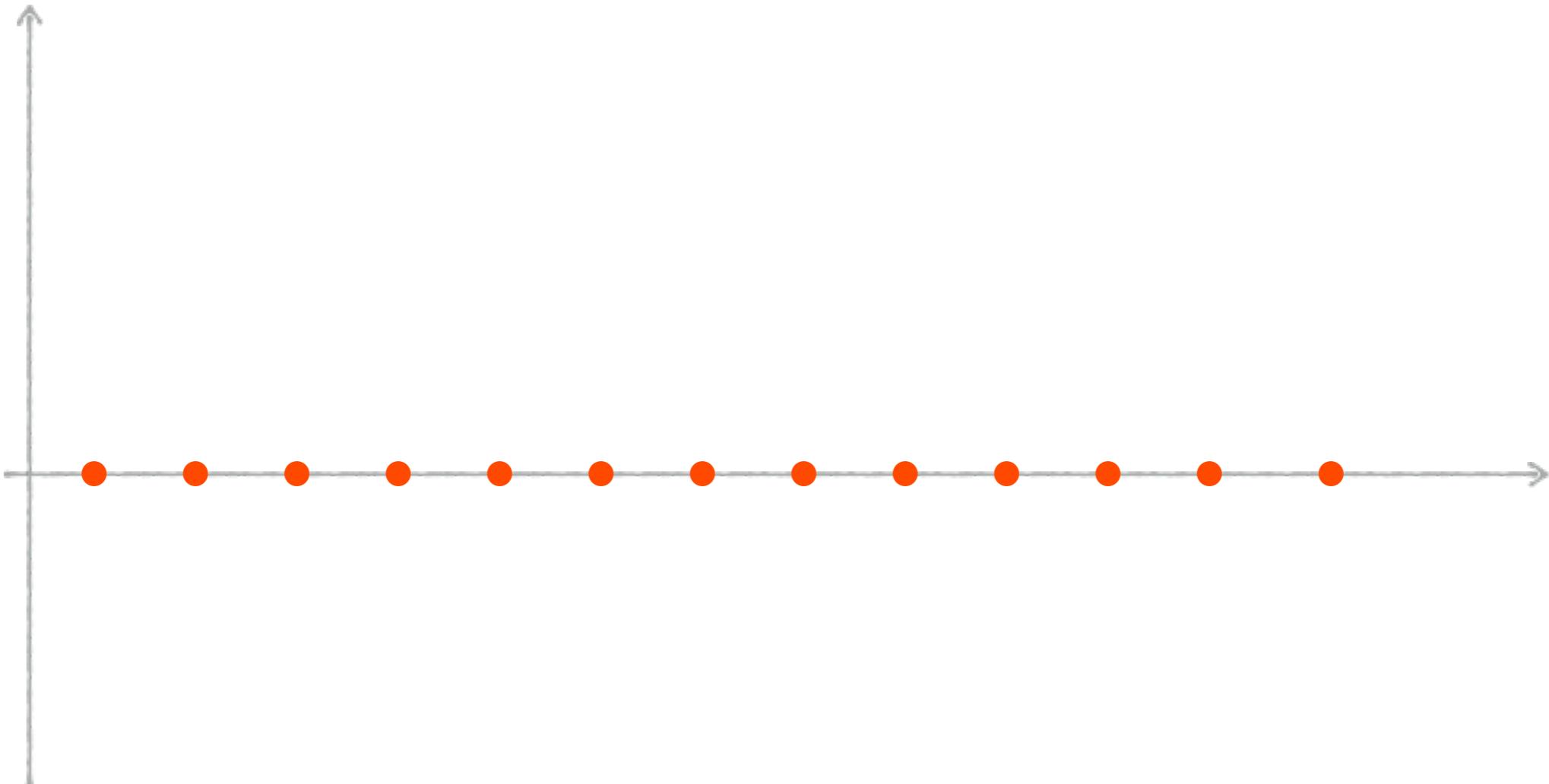


Decreasing Learning Rate

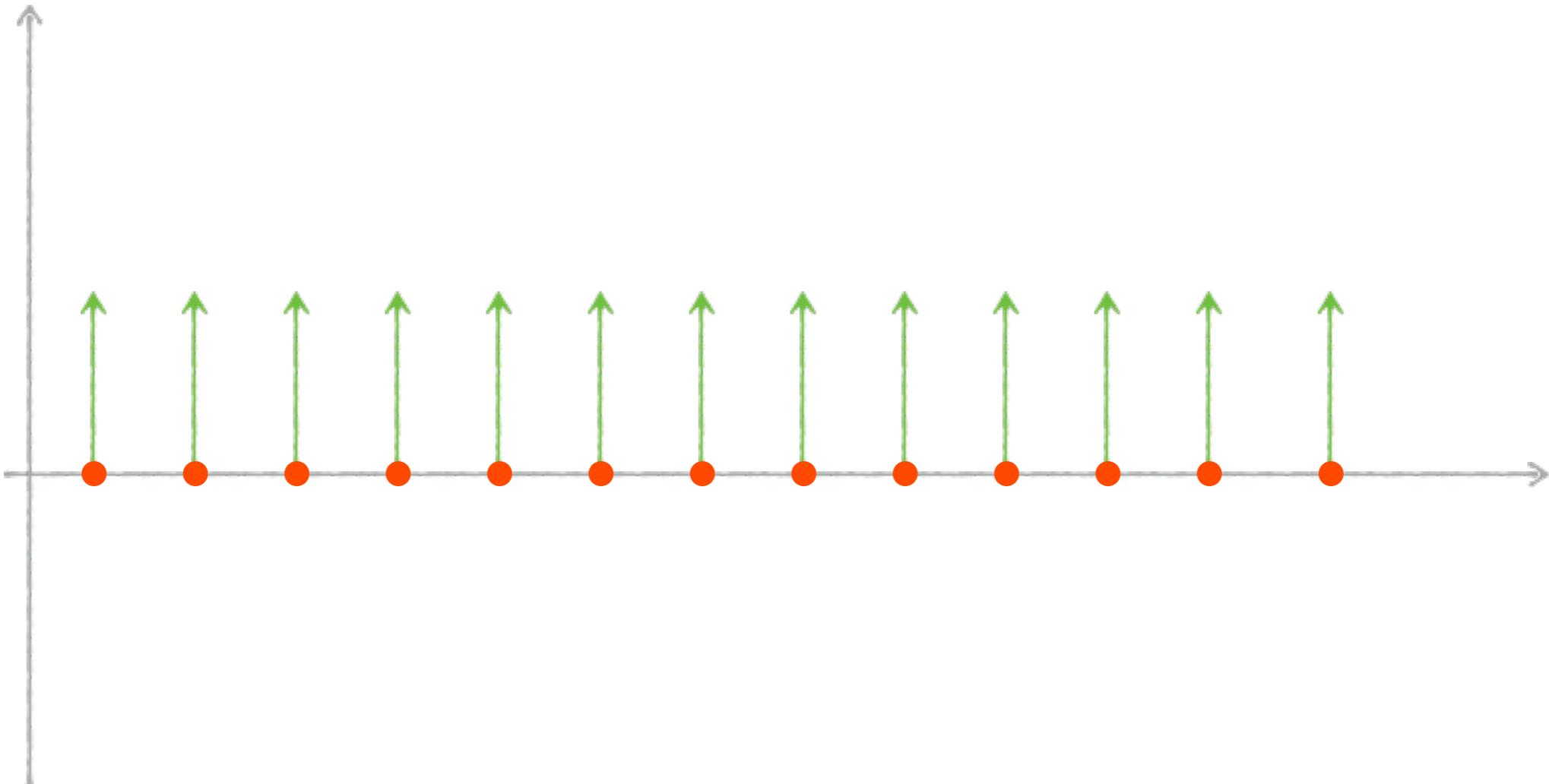


Decrease learning rate over time.

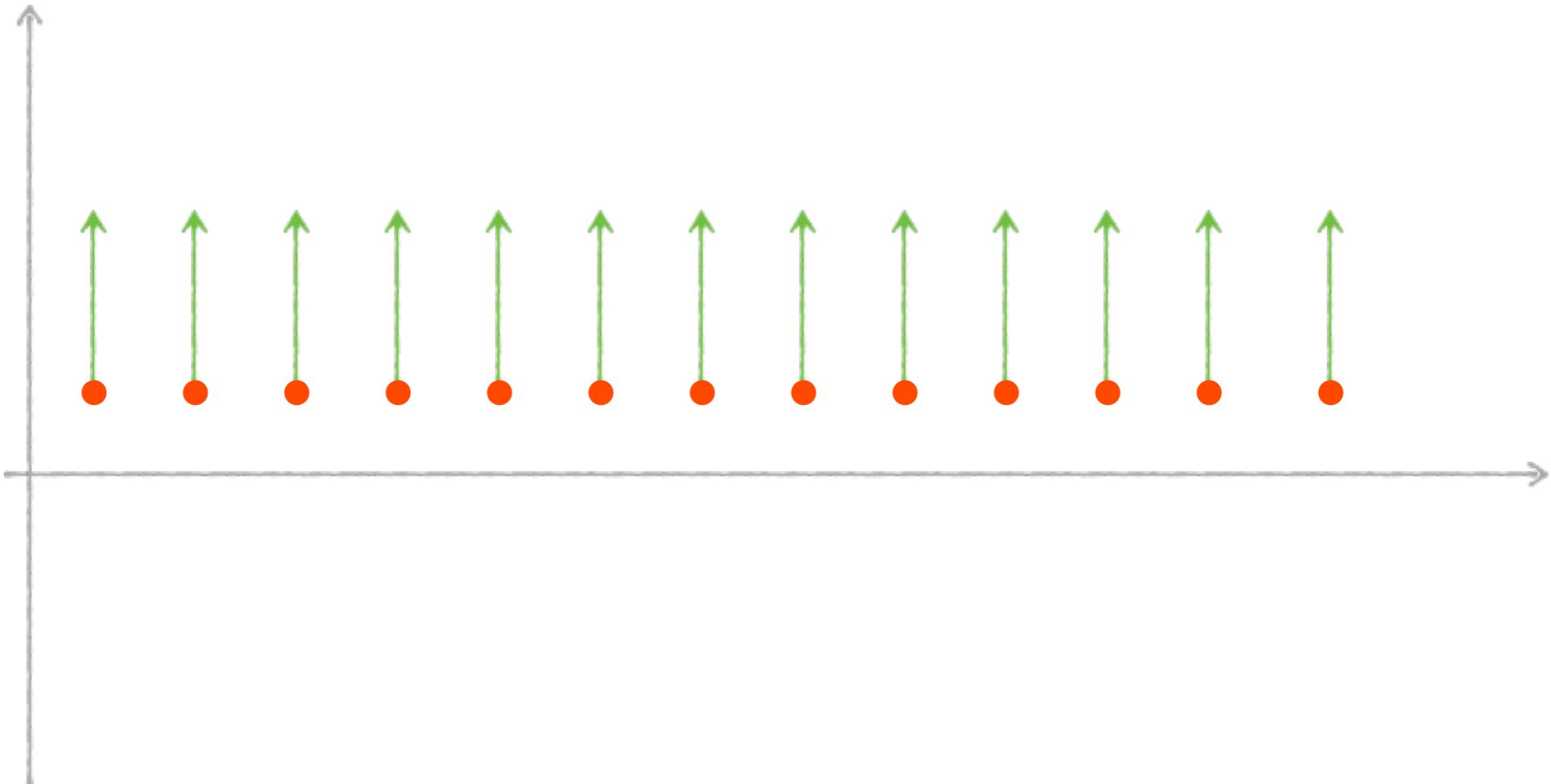
Weight Initialization



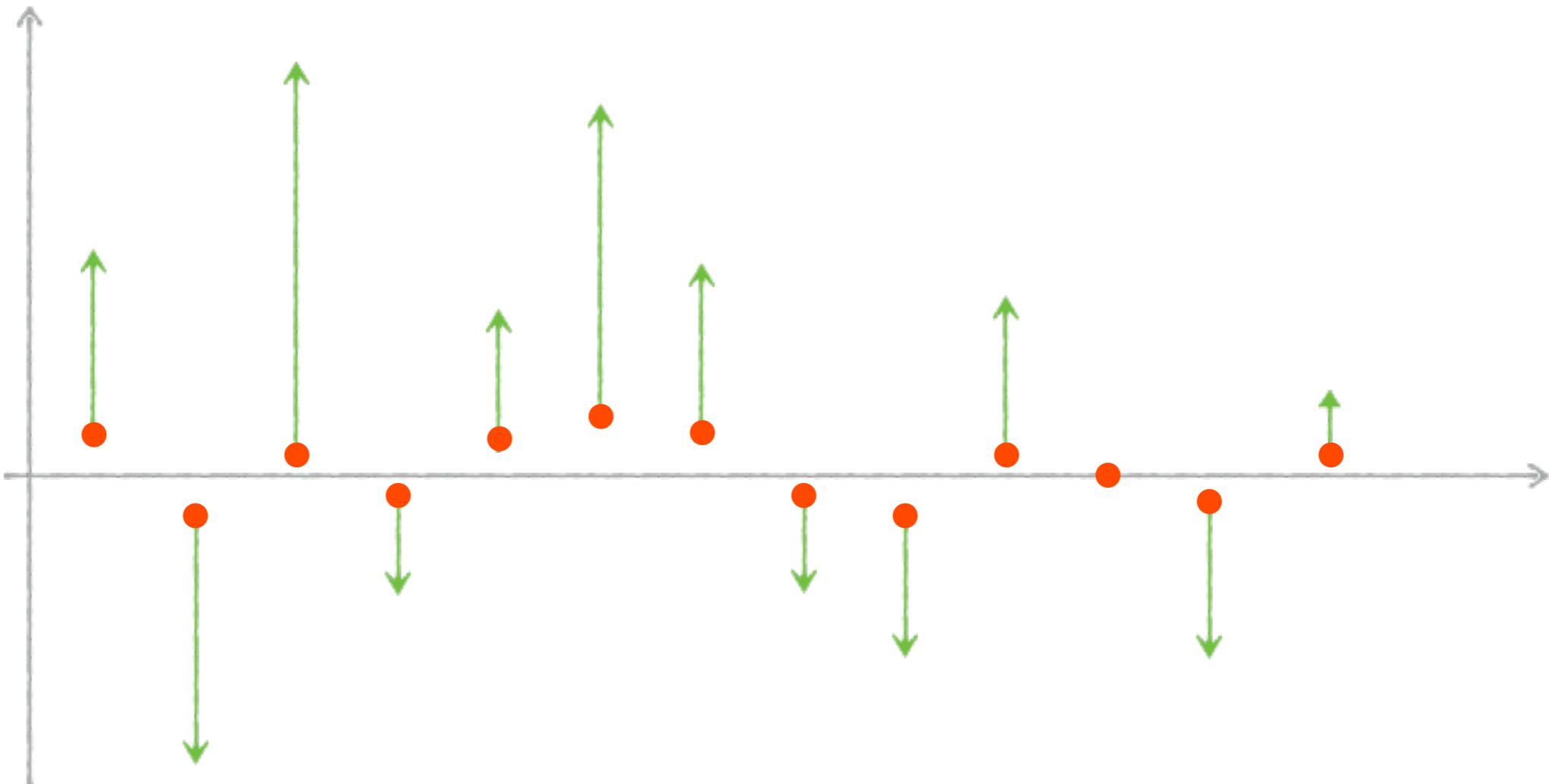
Weight Initialization



Weight Initialization



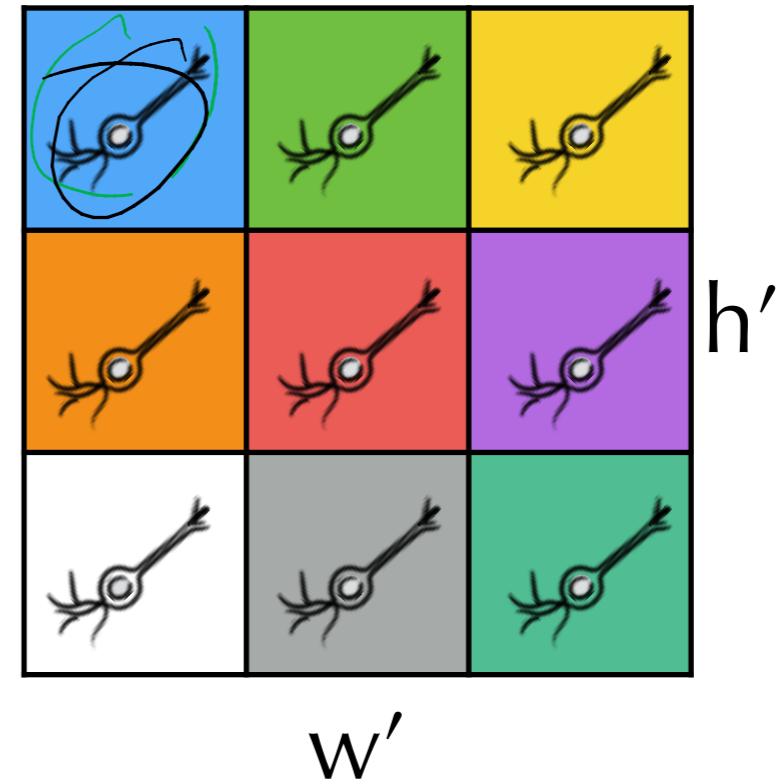
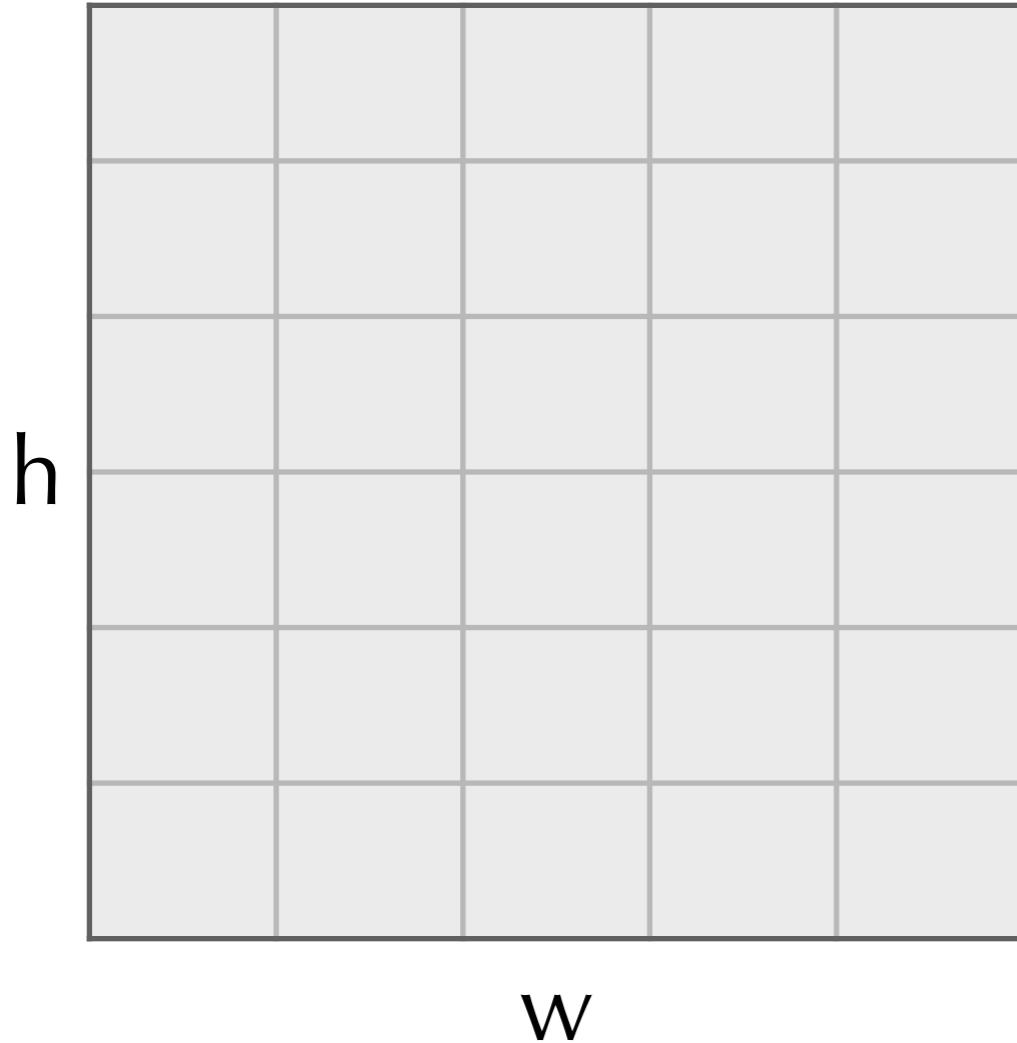
Weight Initialization



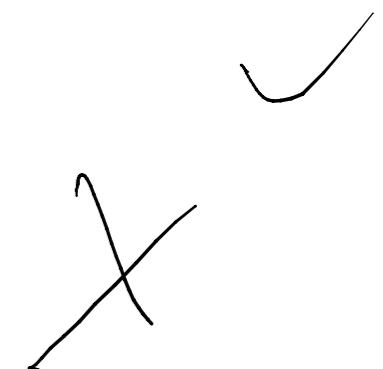
Convolutional Neural Networks

Fully Connected Layers

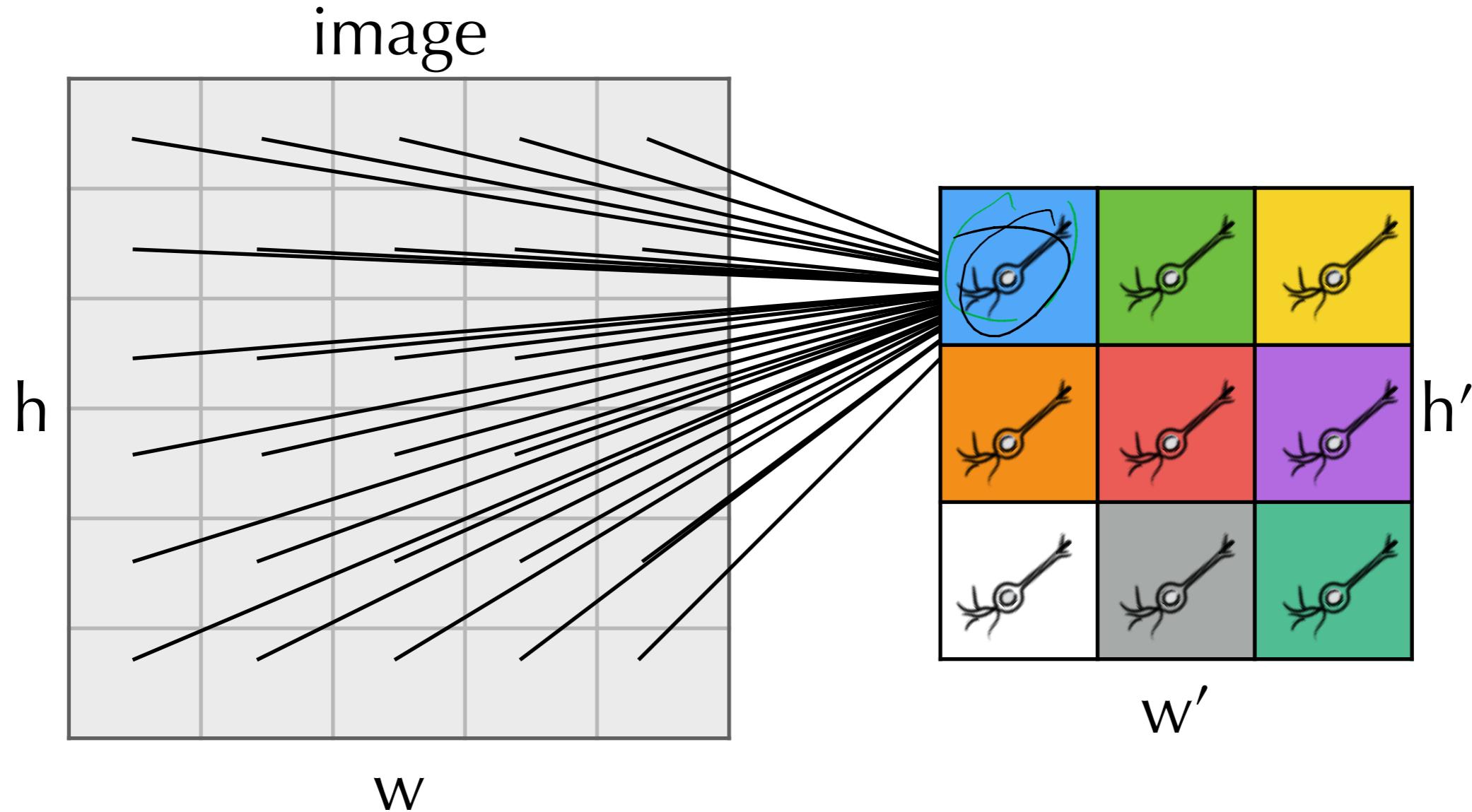
image



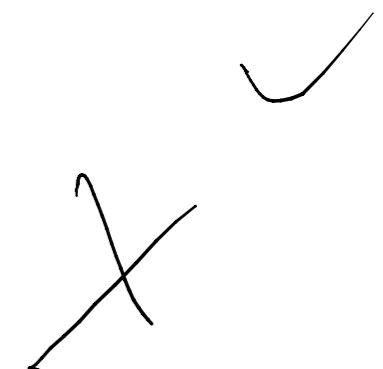
$w \cdot h \cdot w' \cdot h'$



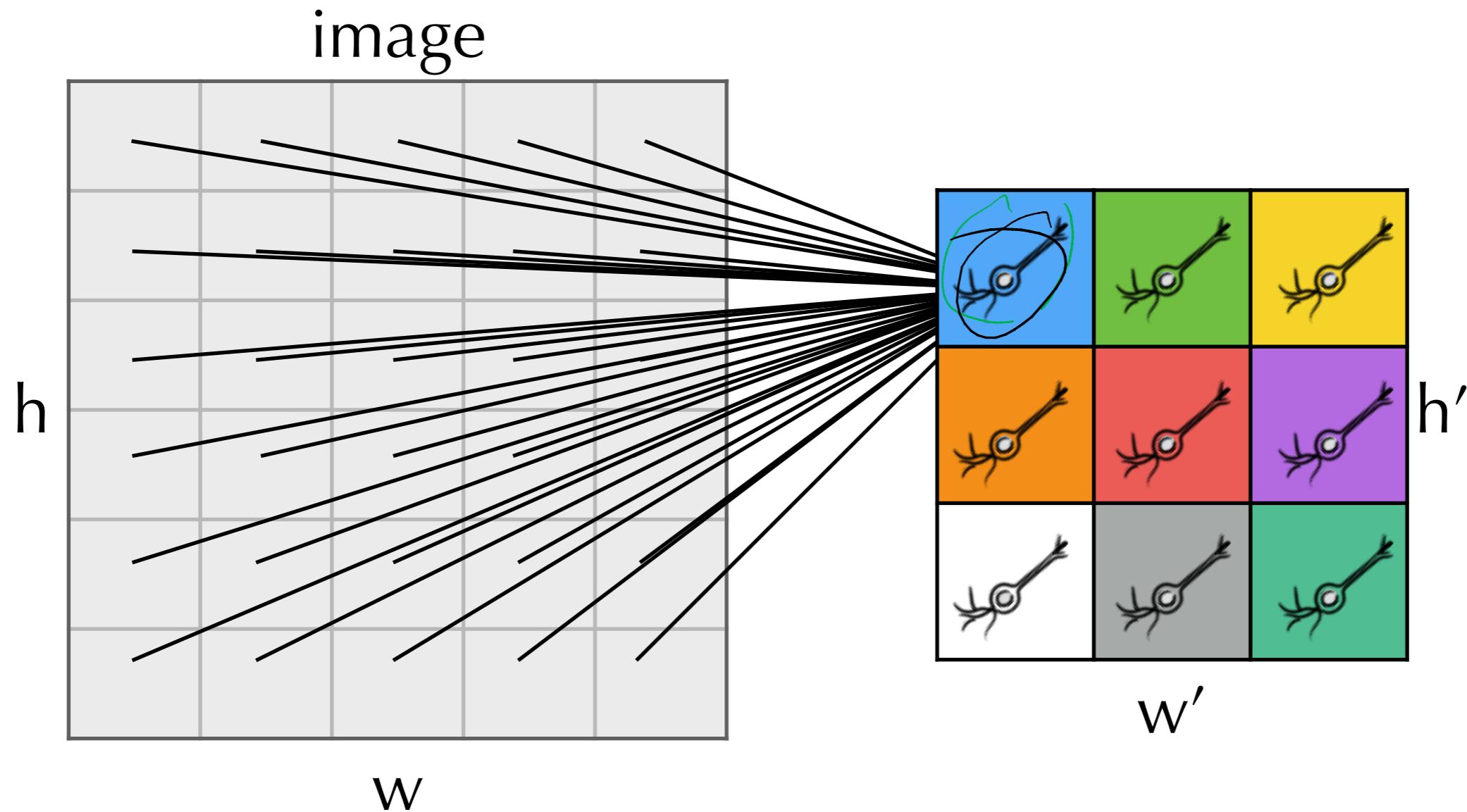
Fully Connected Layers



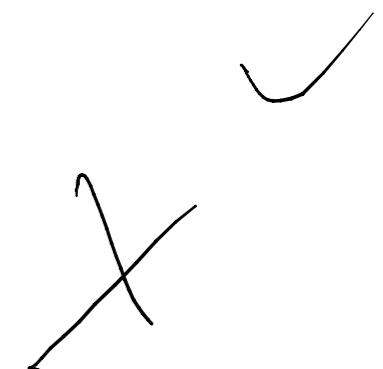
$$w \cdot h \cdot w' \cdot h'$$



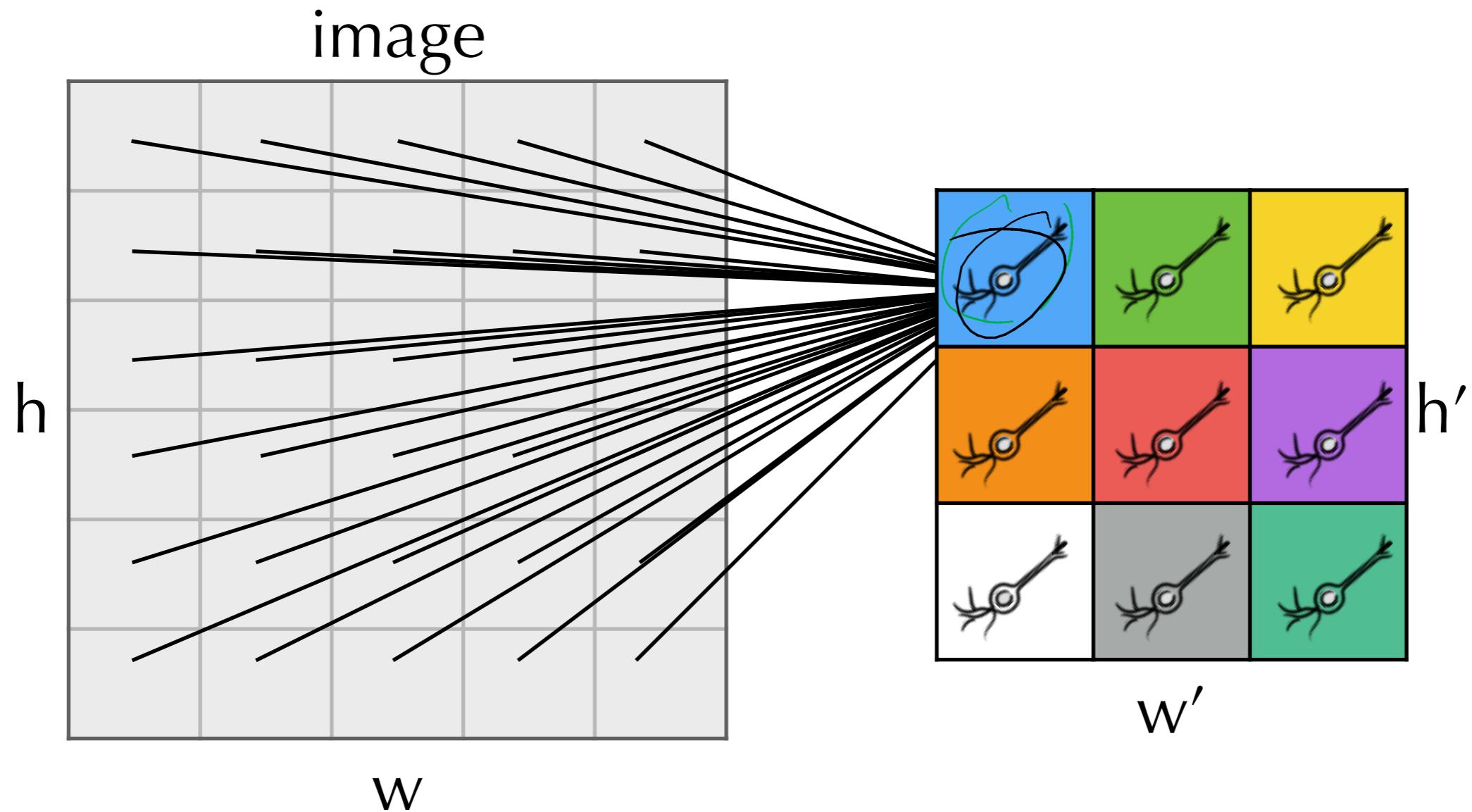
Fully Connected Layers



Number parameters: $w \cdot h \cdot w' \cdot h'$

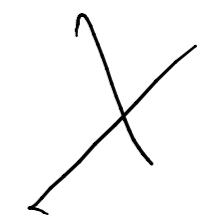


Fully Connected Layers

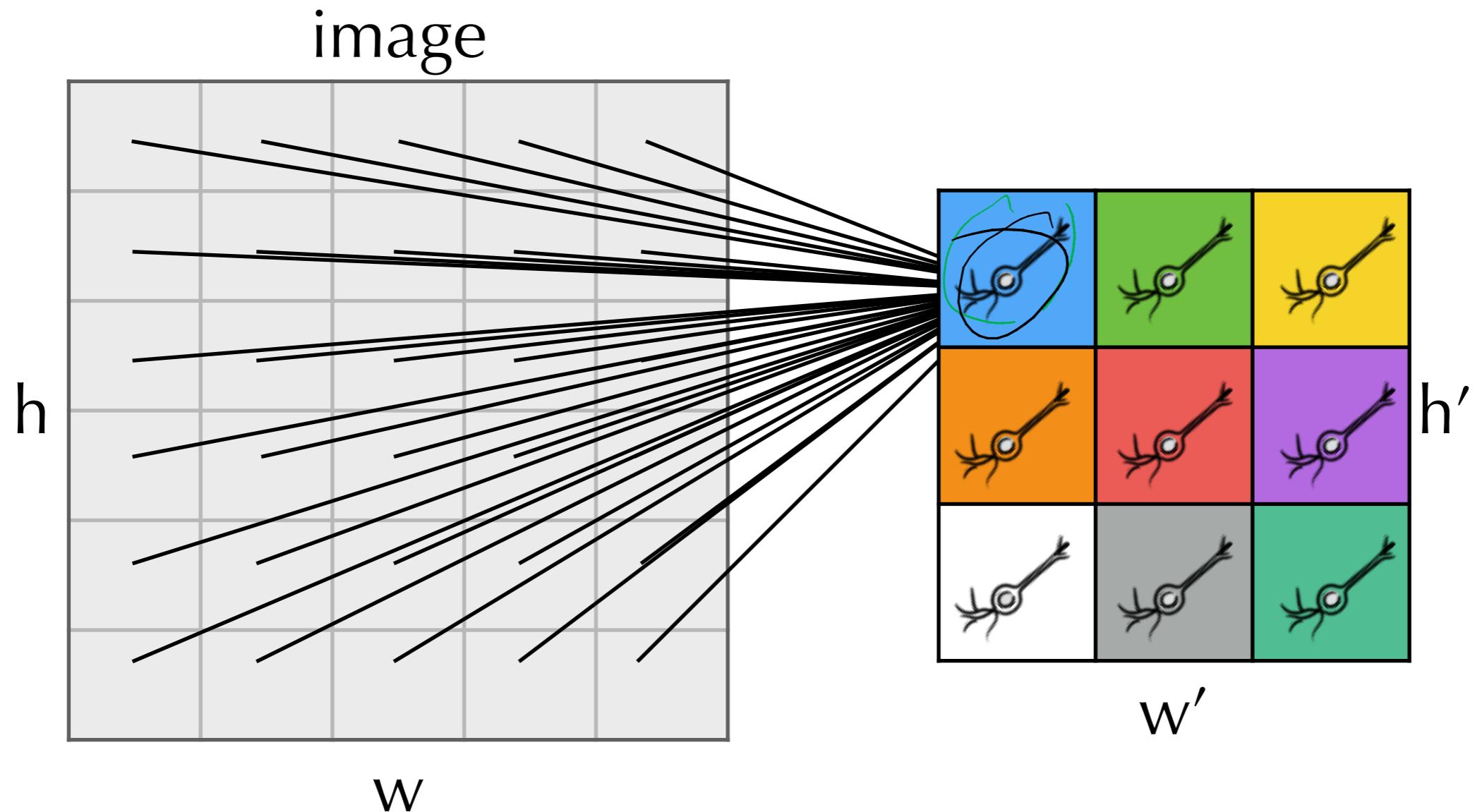


Number parameters: $w \cdot h \cdot w' \cdot h'$

Redundancy? ✓



Fully Connected Layers



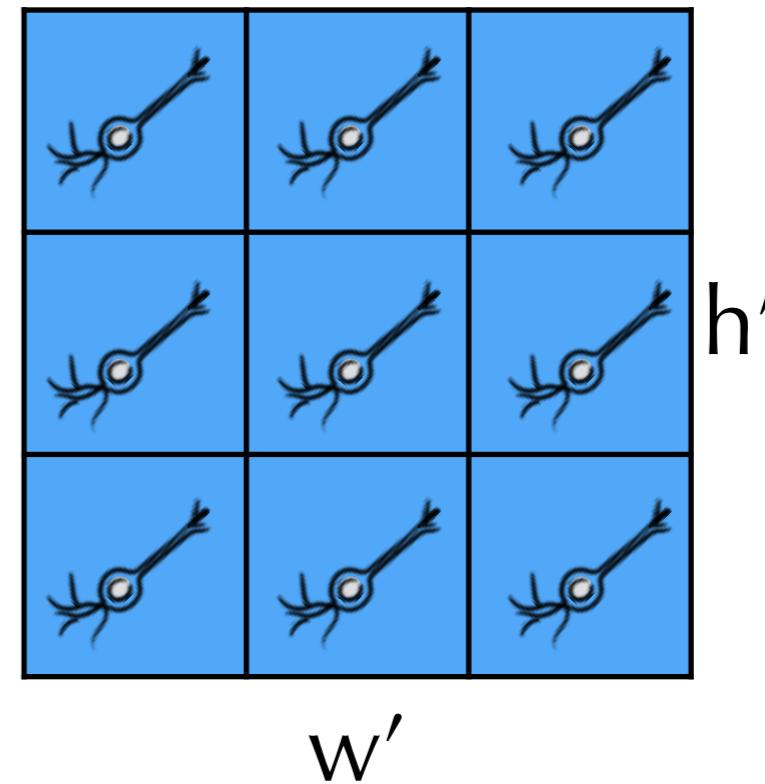
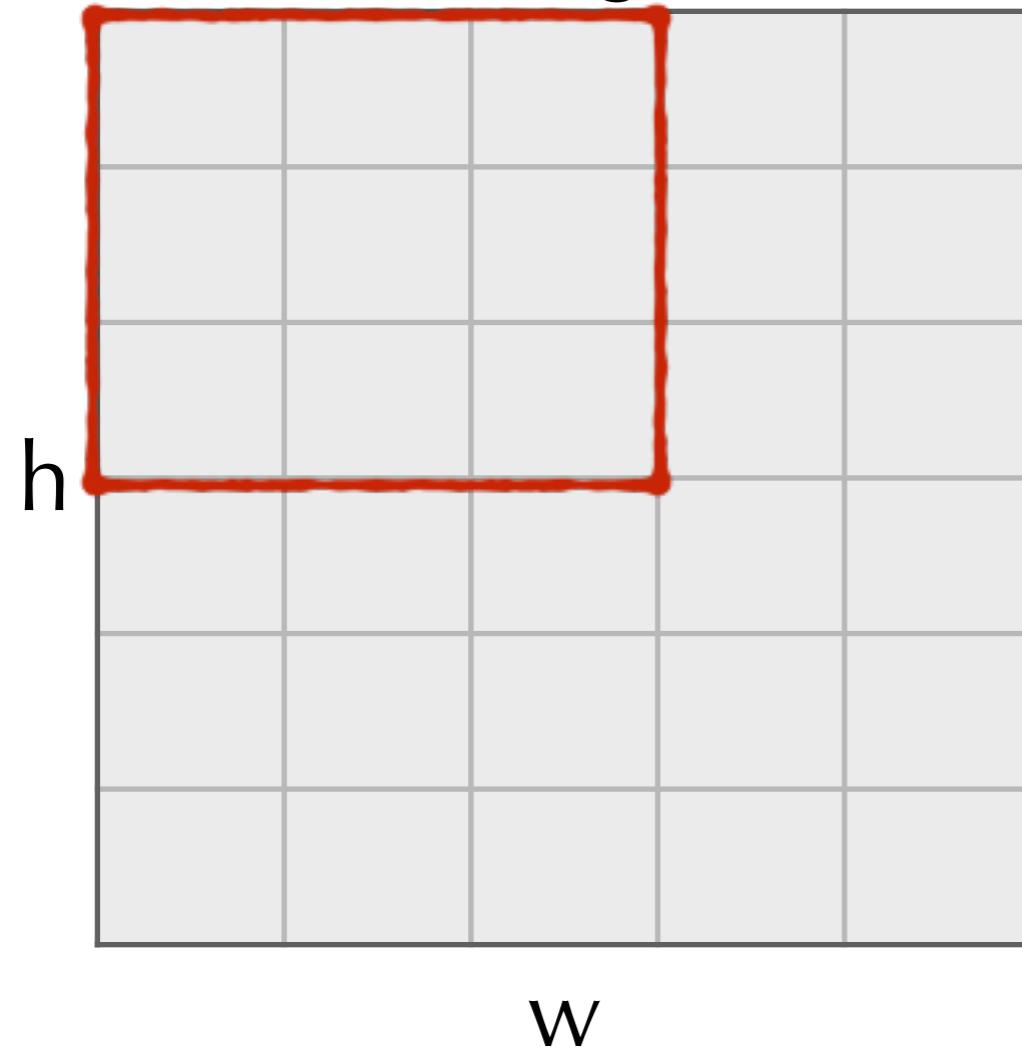
Number parameters: $w \cdot h \cdot w' \cdot h'$

Redundancy? ✓

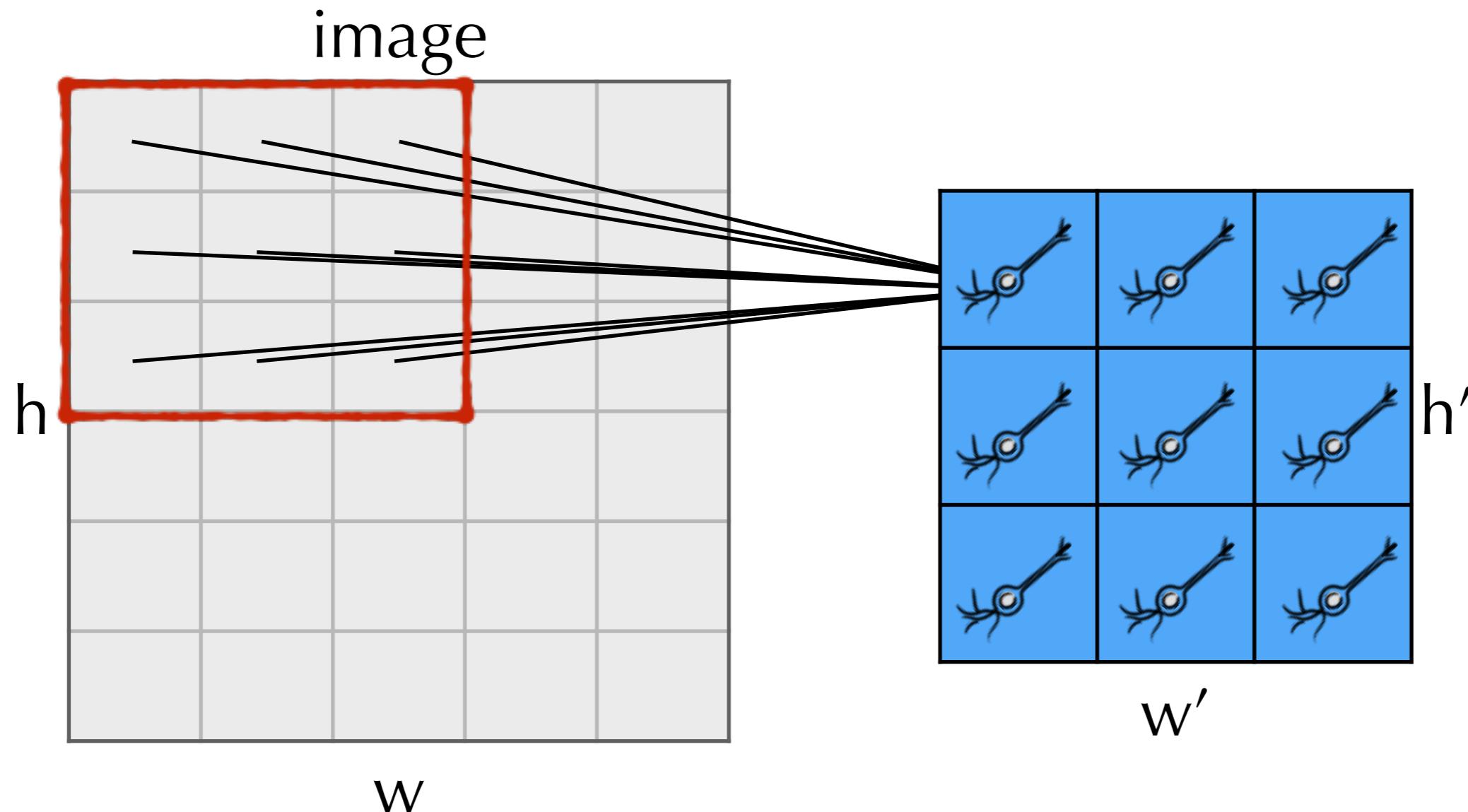
Locality? ✗

Convolutional Layers

image

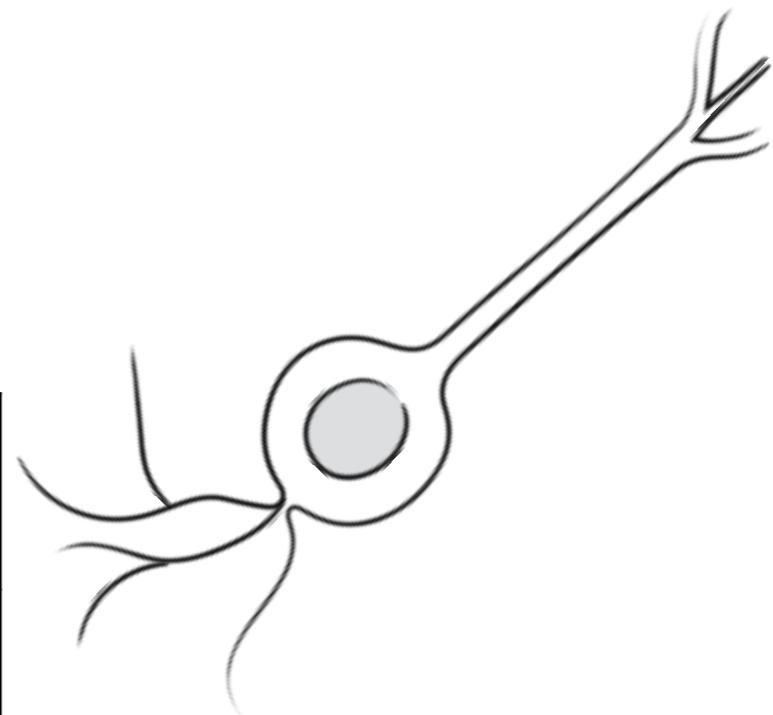


Convolutional Layers



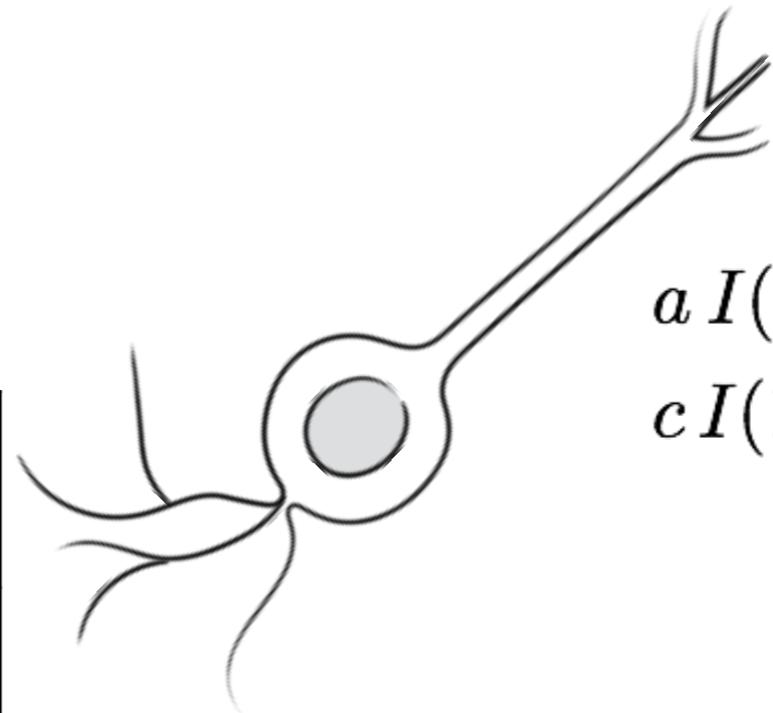
Translation Invariance

2	2	1	2	3
11	21	22	21	14
12	20	45	32	21
11	12	11	16	21
21	22	23	25	35



Translation Invariance

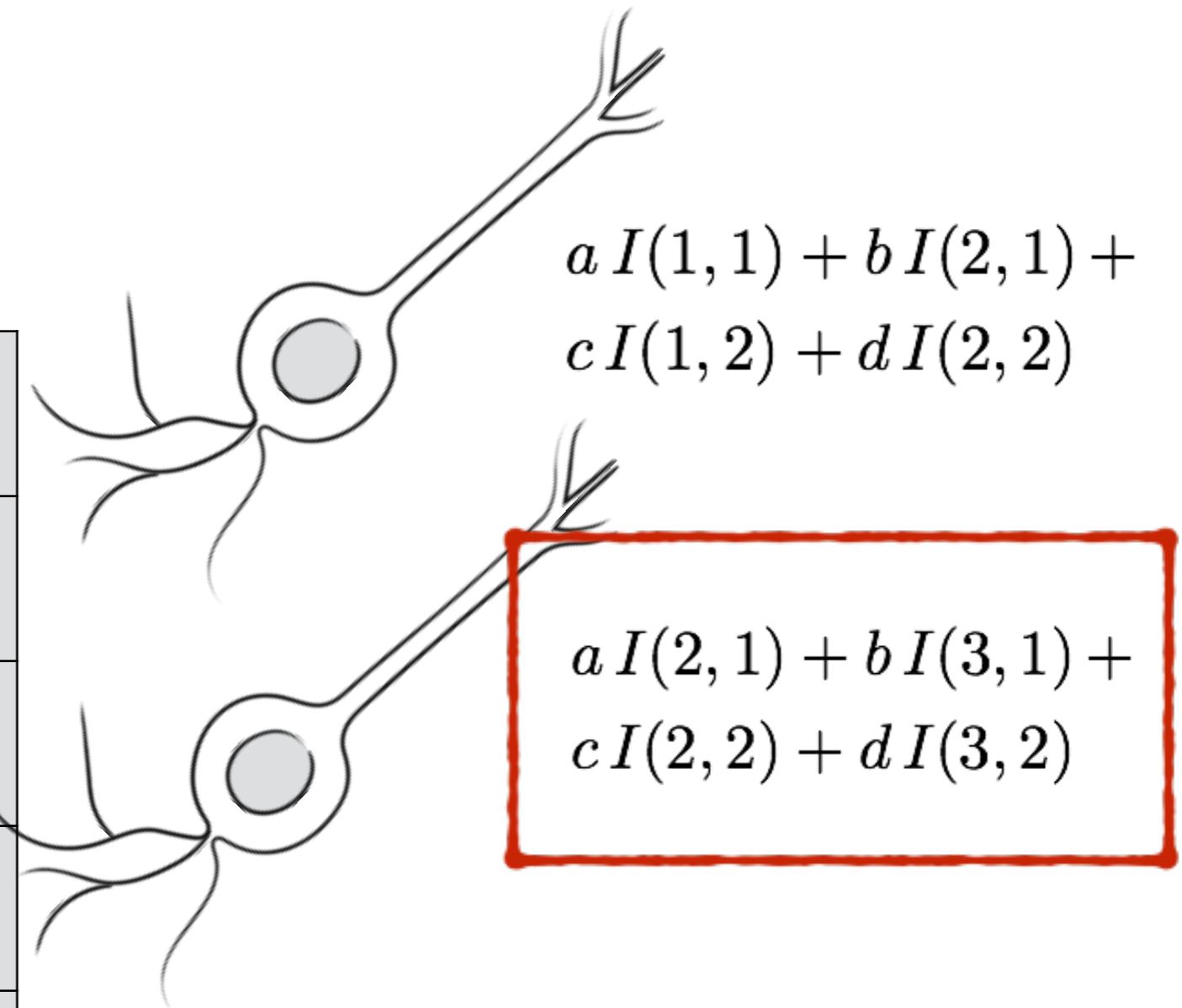
2	2	1	2	3
11	21	22	21	14
12	20	45	32	21
11	12	11	16	21
21	22	23	25	35



$$a I(1,1) + b I(2,1) + c I(1,2) + d I(2,2)$$

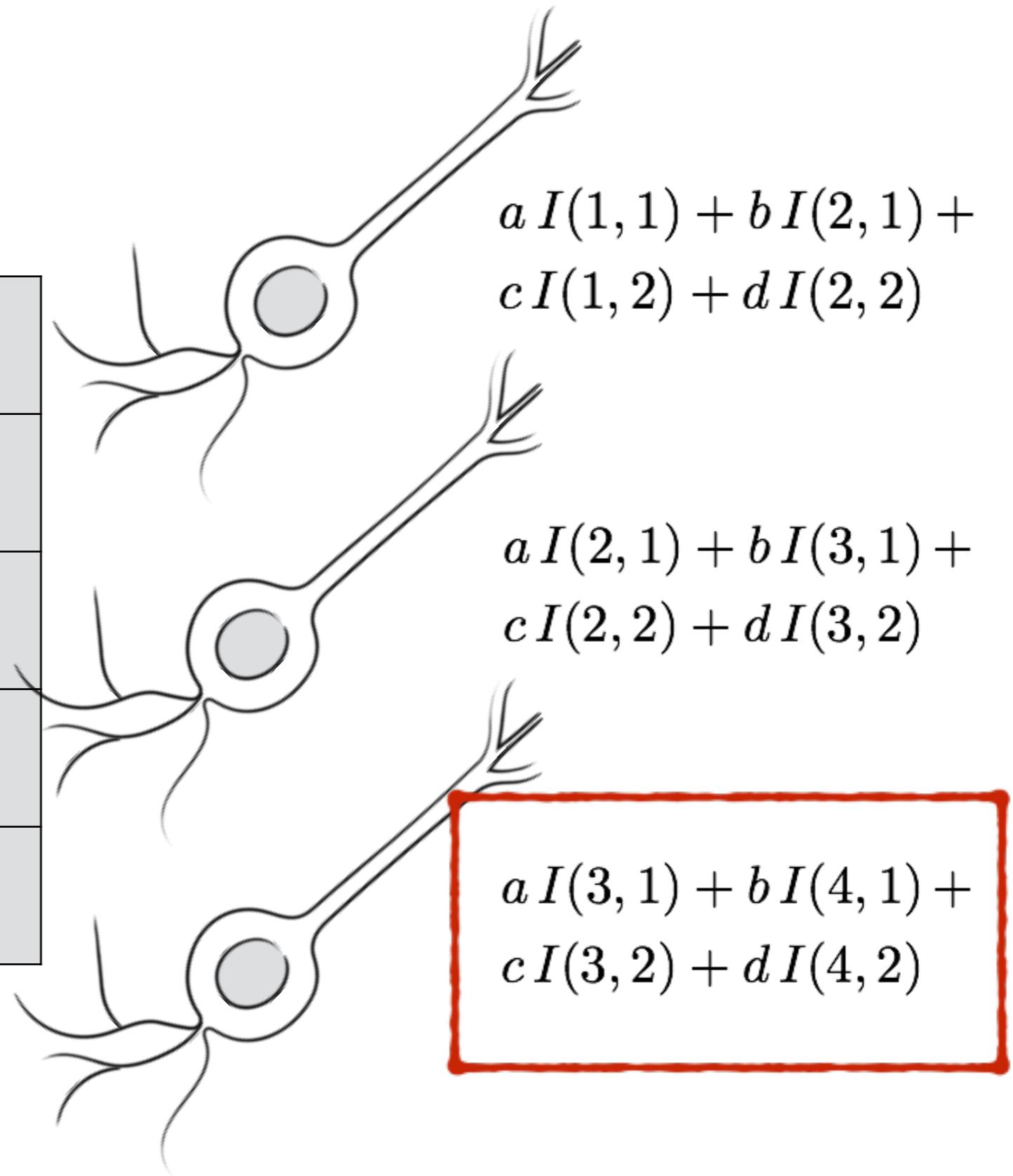
Translation Invariance

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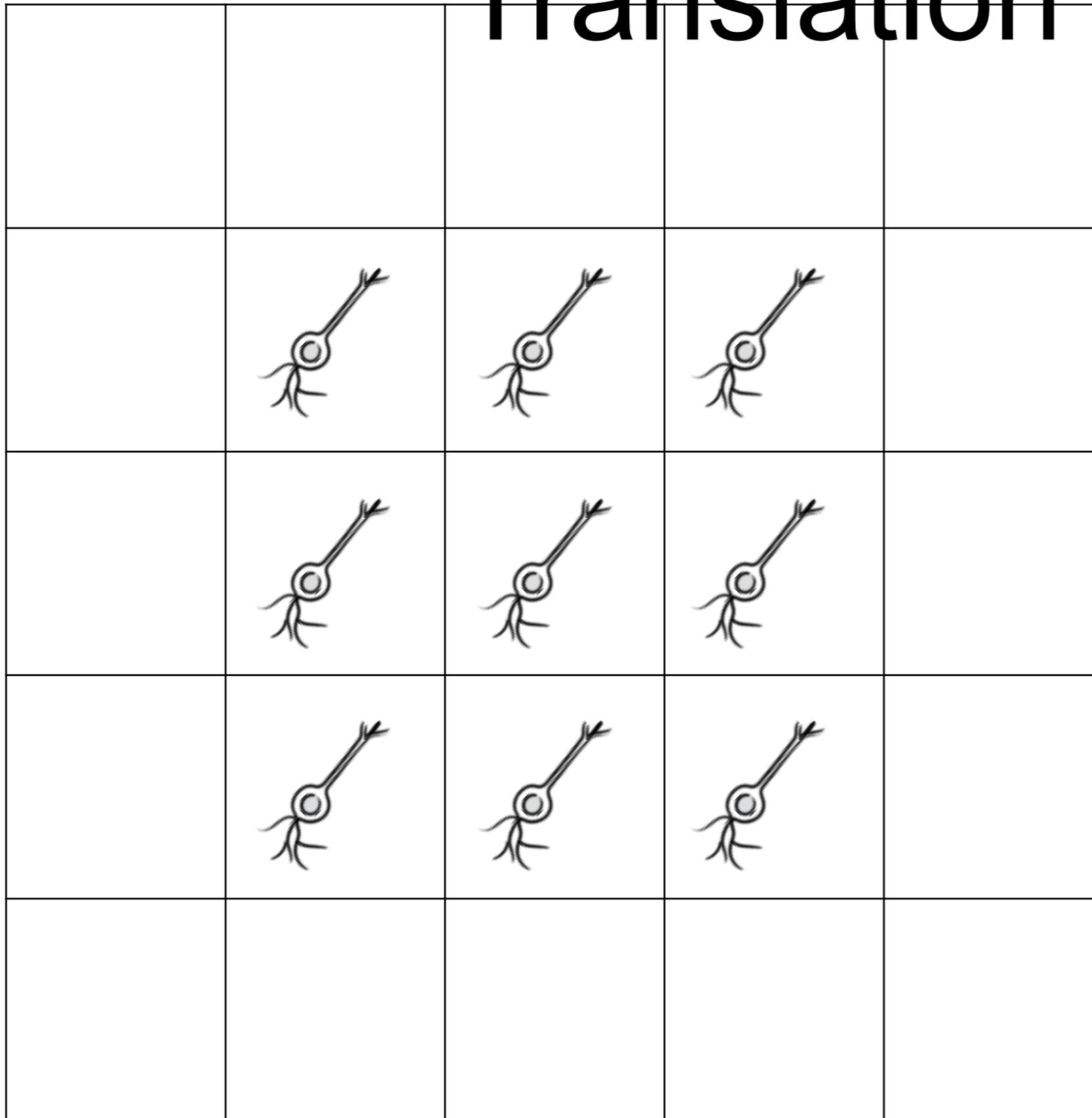


Translation Invariance

2	2	1	2	3
11	21	22	21	14
12	20	45	32	21
11	12	11	16	21
21	22	23	25	35

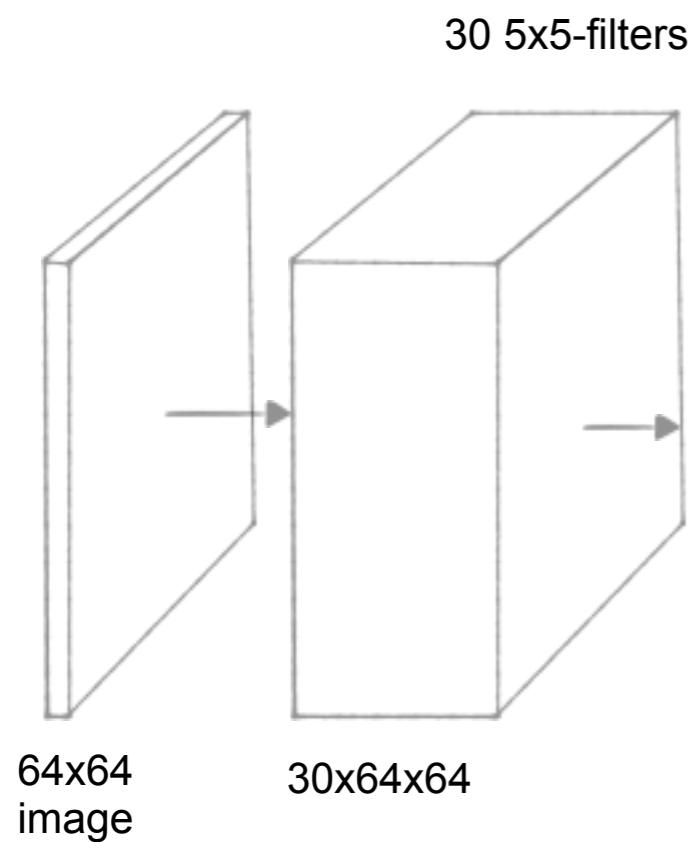


Translation Invariance



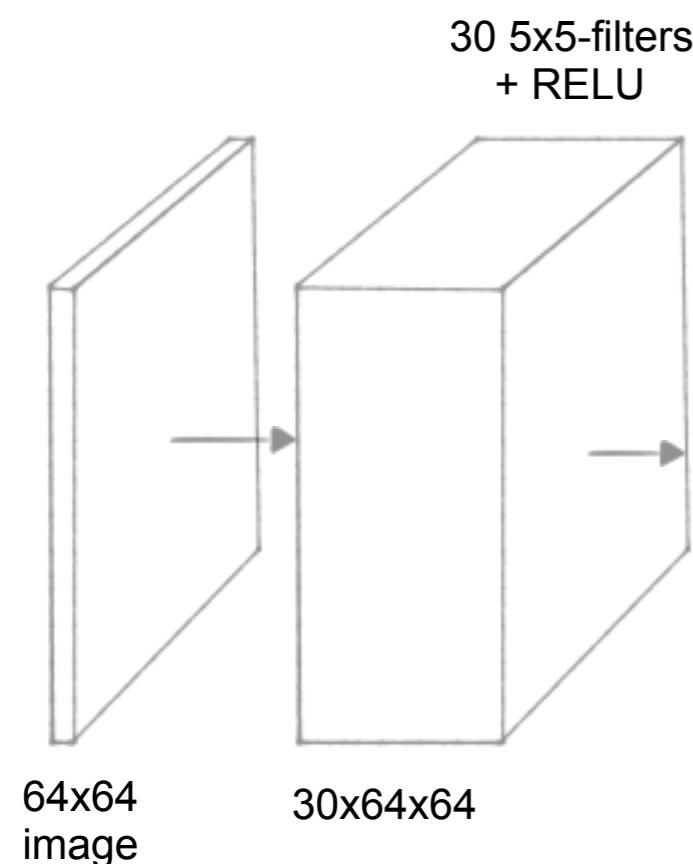
$$I \star \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

Network Structure



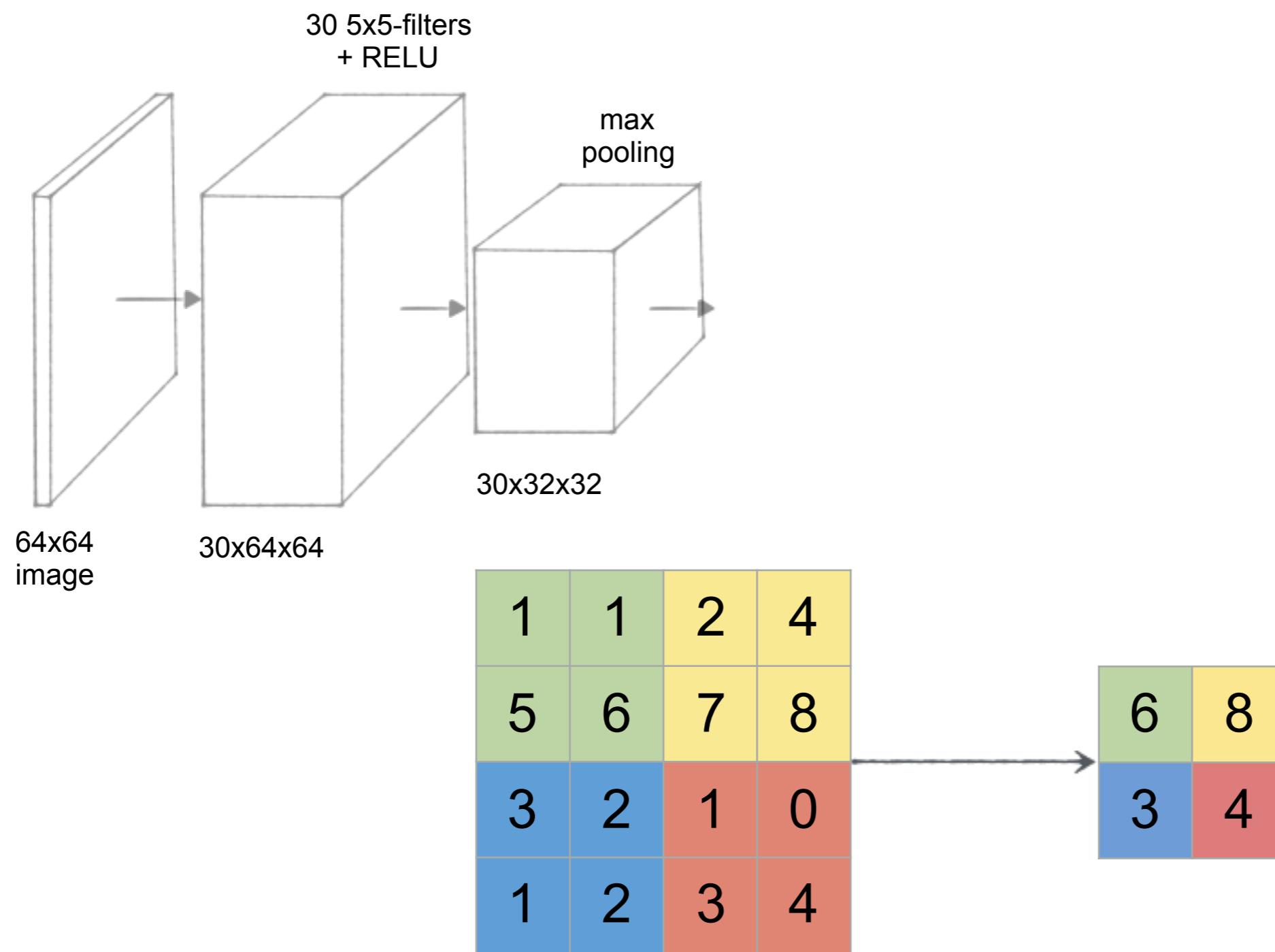
$$I \star w$$

Network Structure

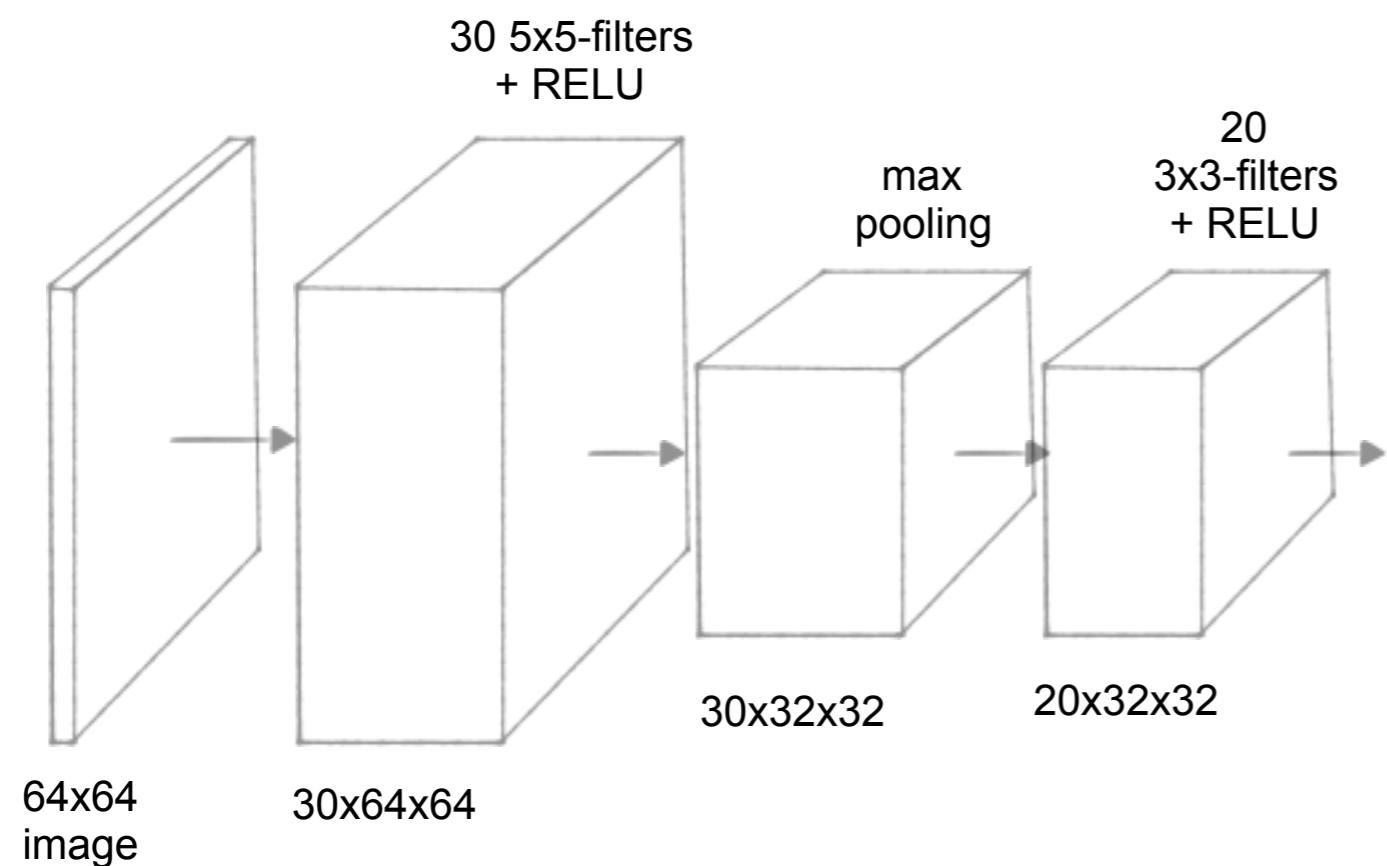


$$\max\{I \star w, 0\}$$

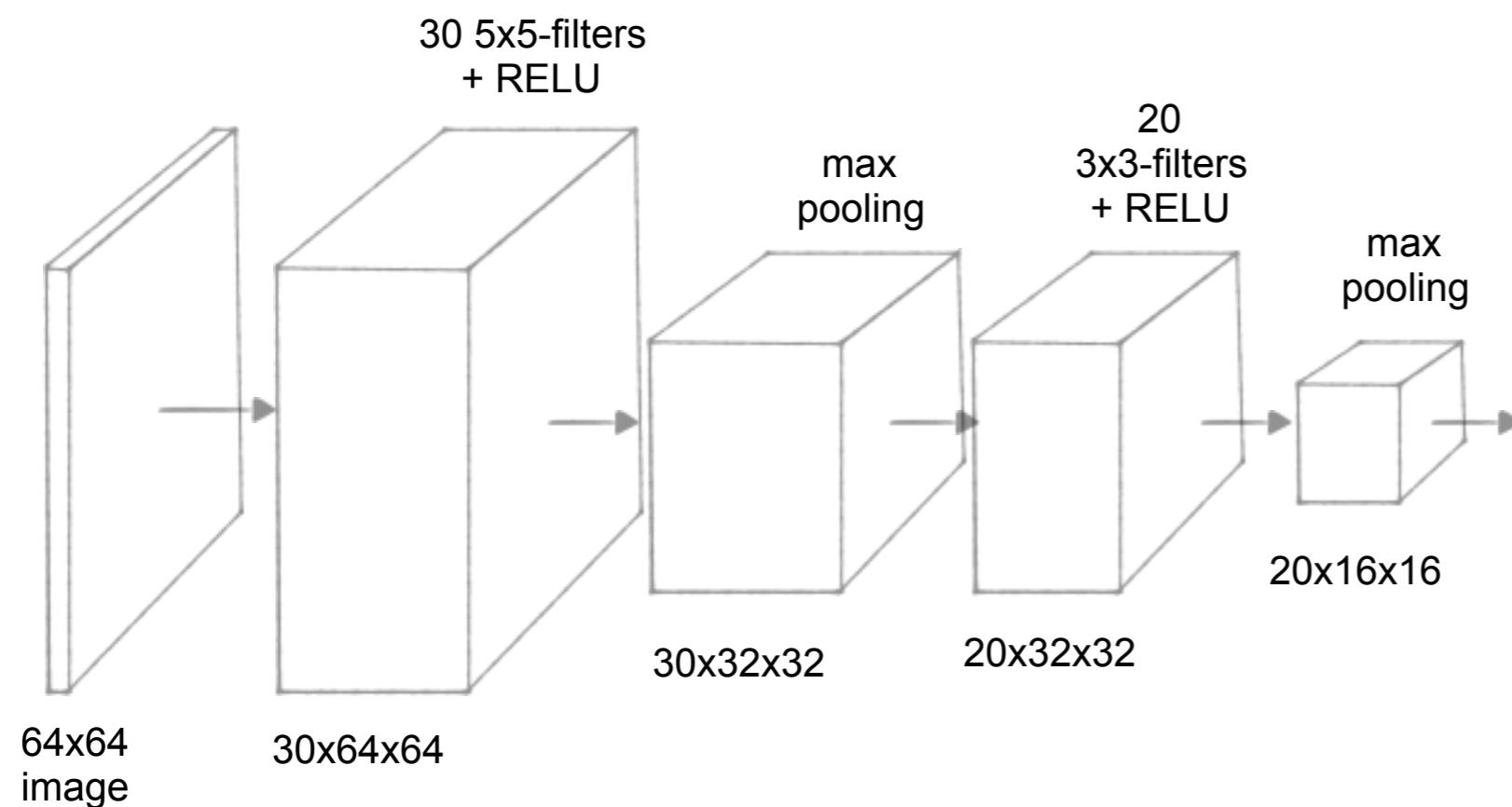
Network Structure



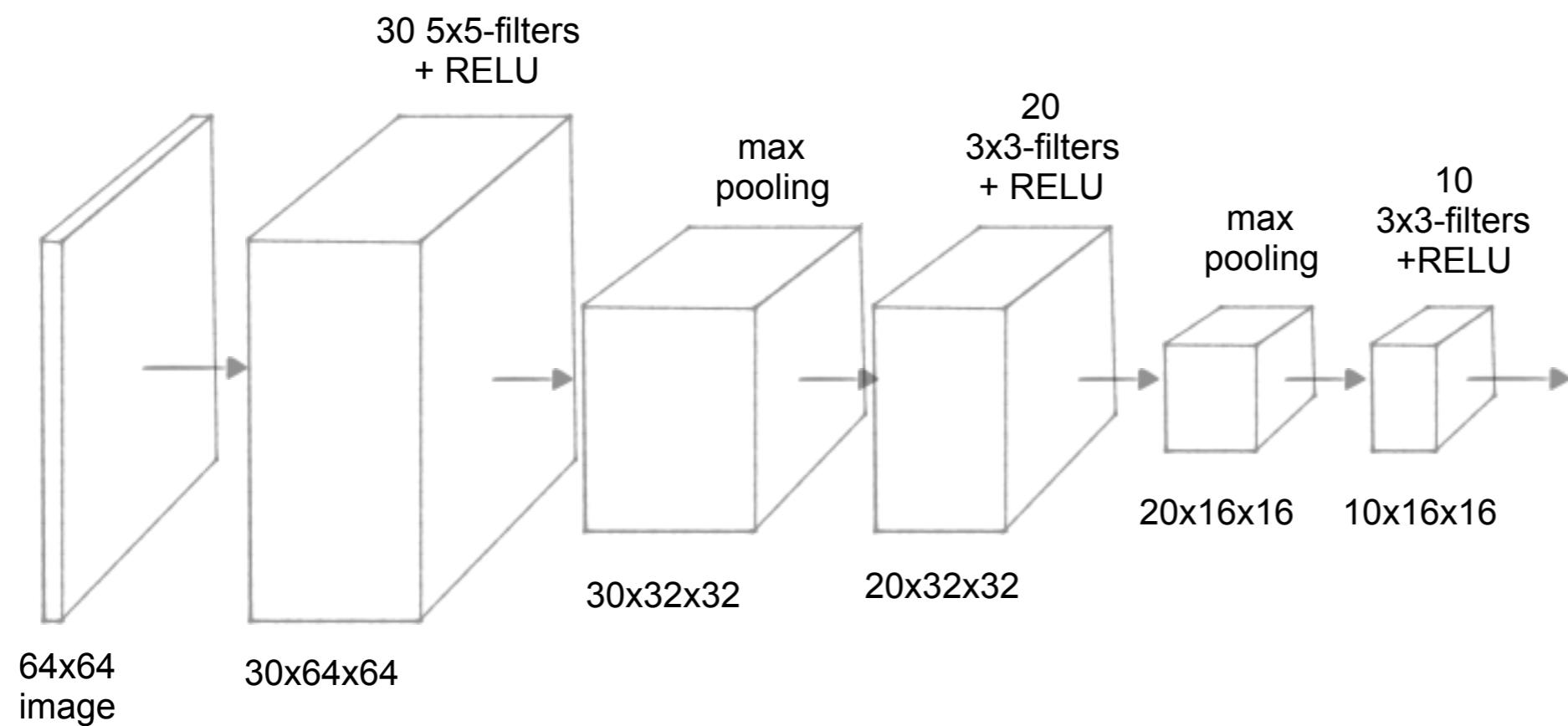
Network Structure



Network Structure

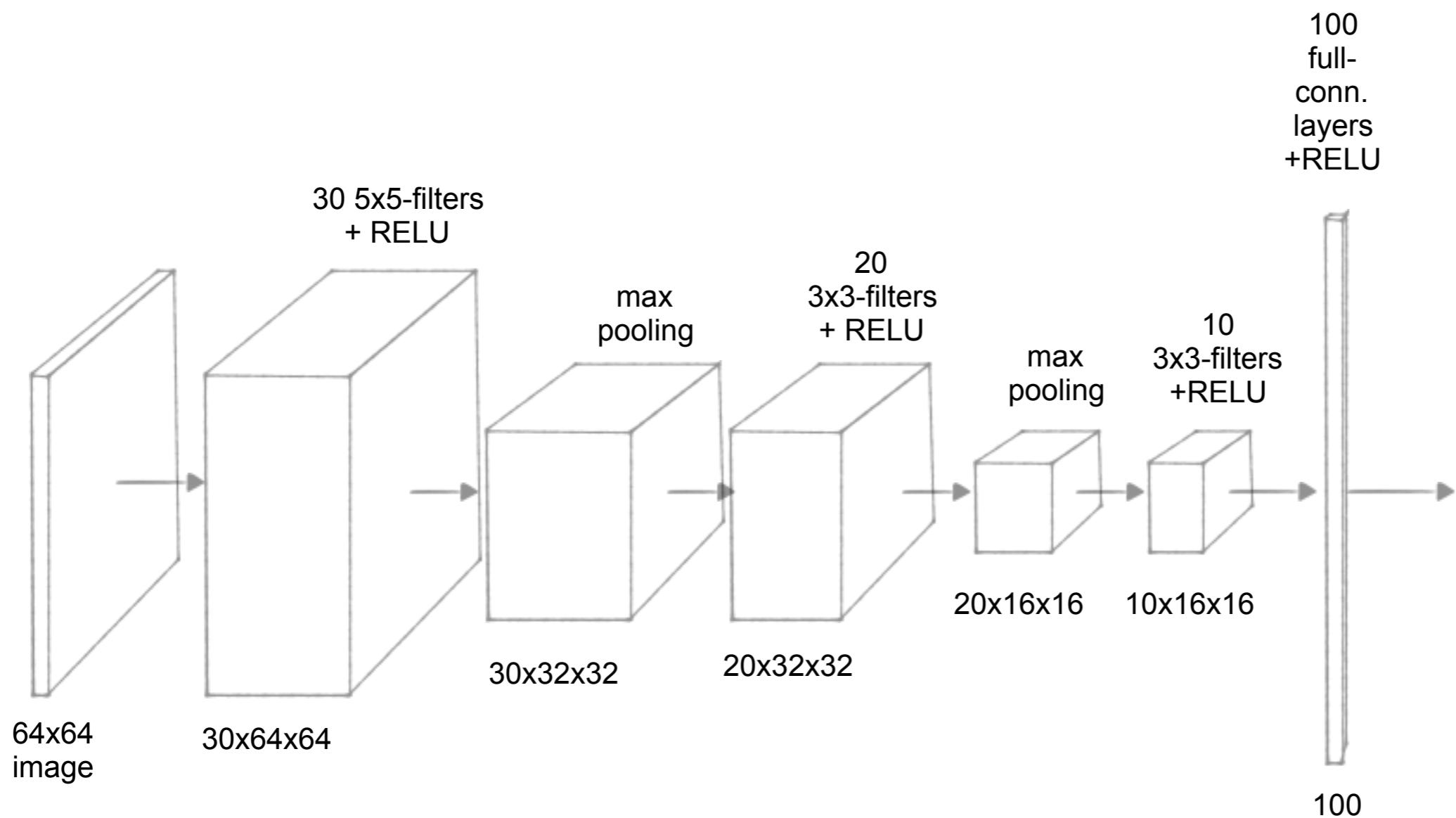


Network Structure



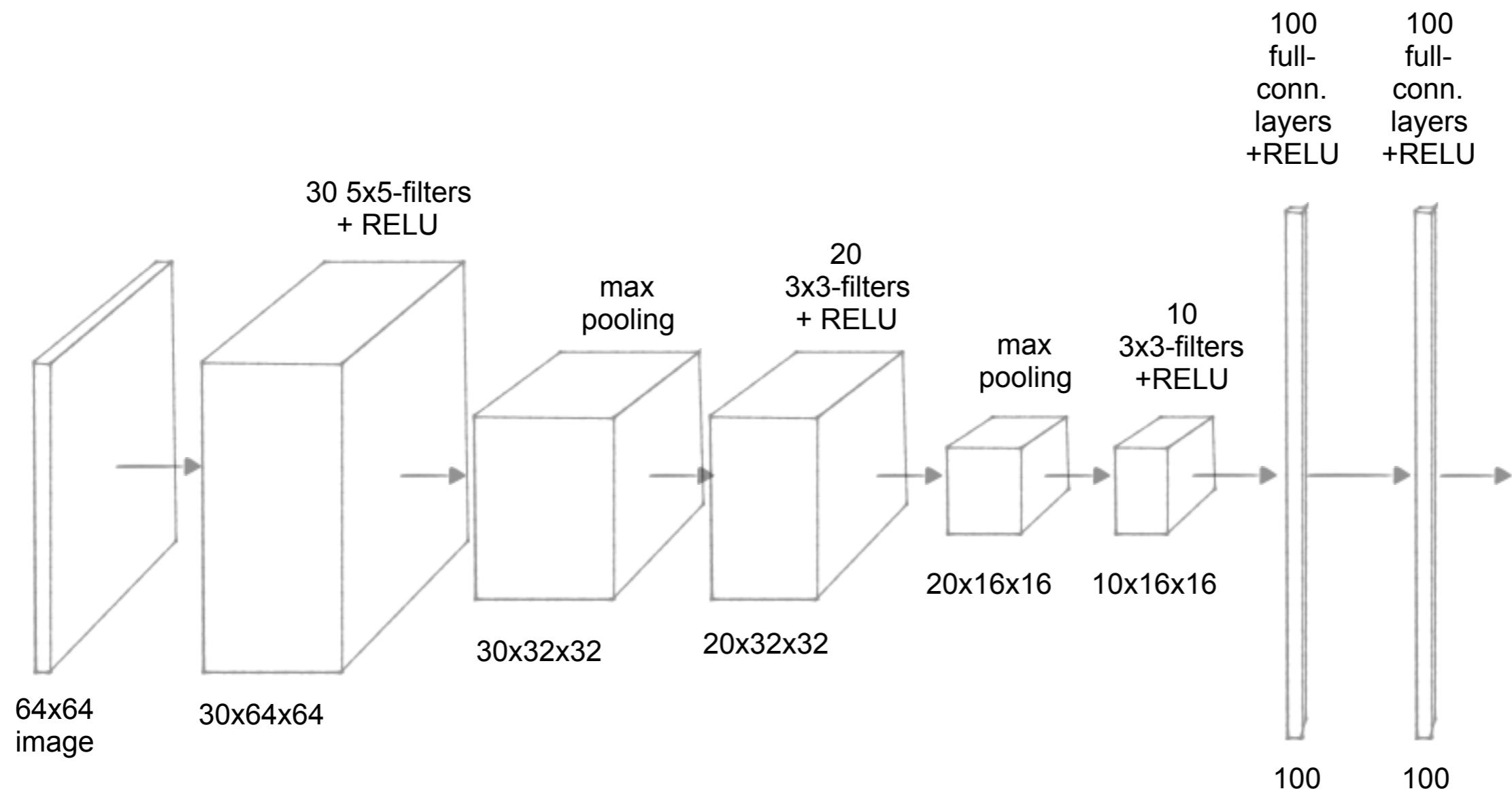
$$\max\{I \otimes f, 0\}$$

Network Structure

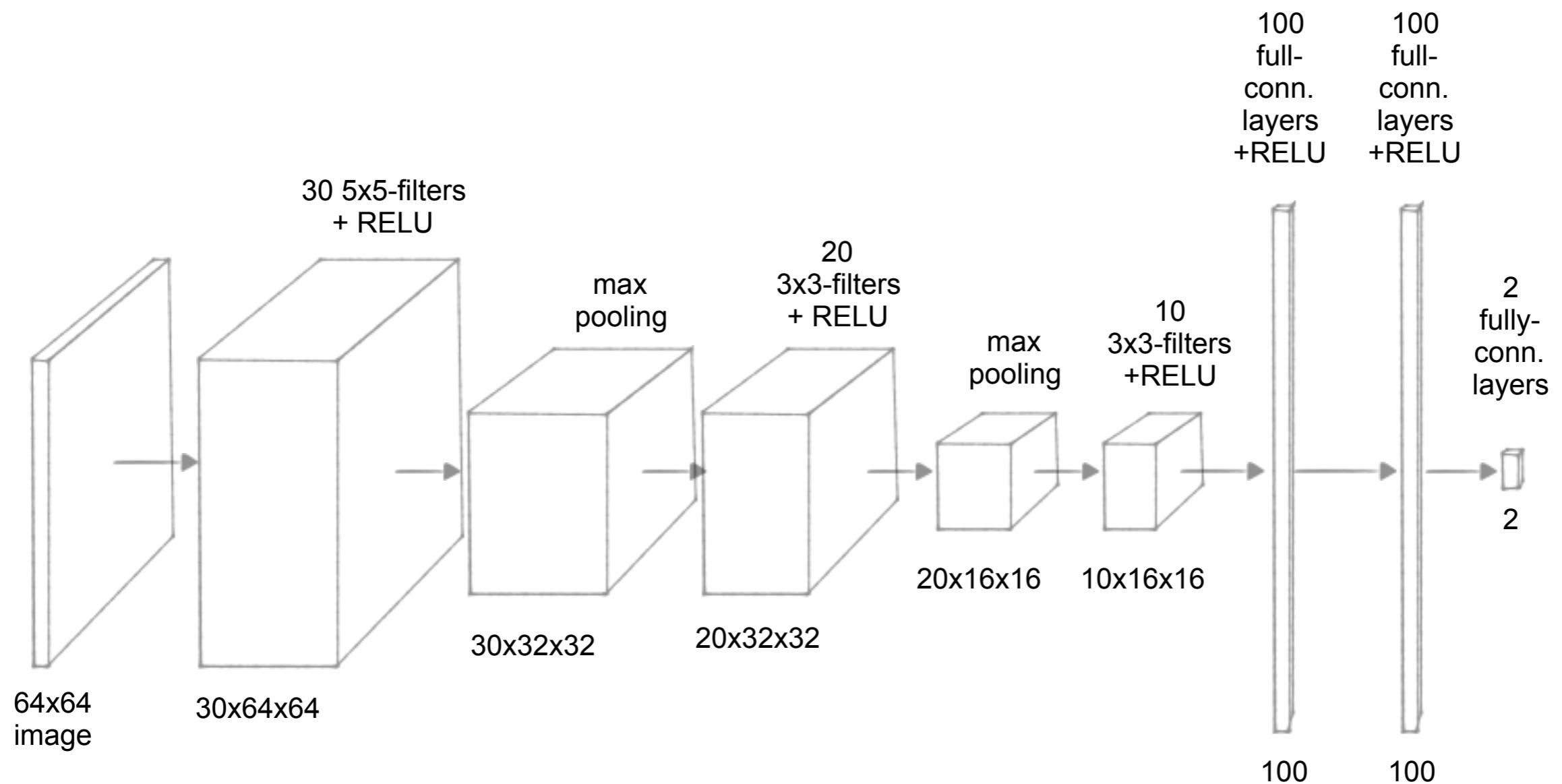


$$\sum_{i=1}^{10} \sum_{u=1}^{16} \sum_{v=1}^{16} w_{ijk} x_{ijk}$$

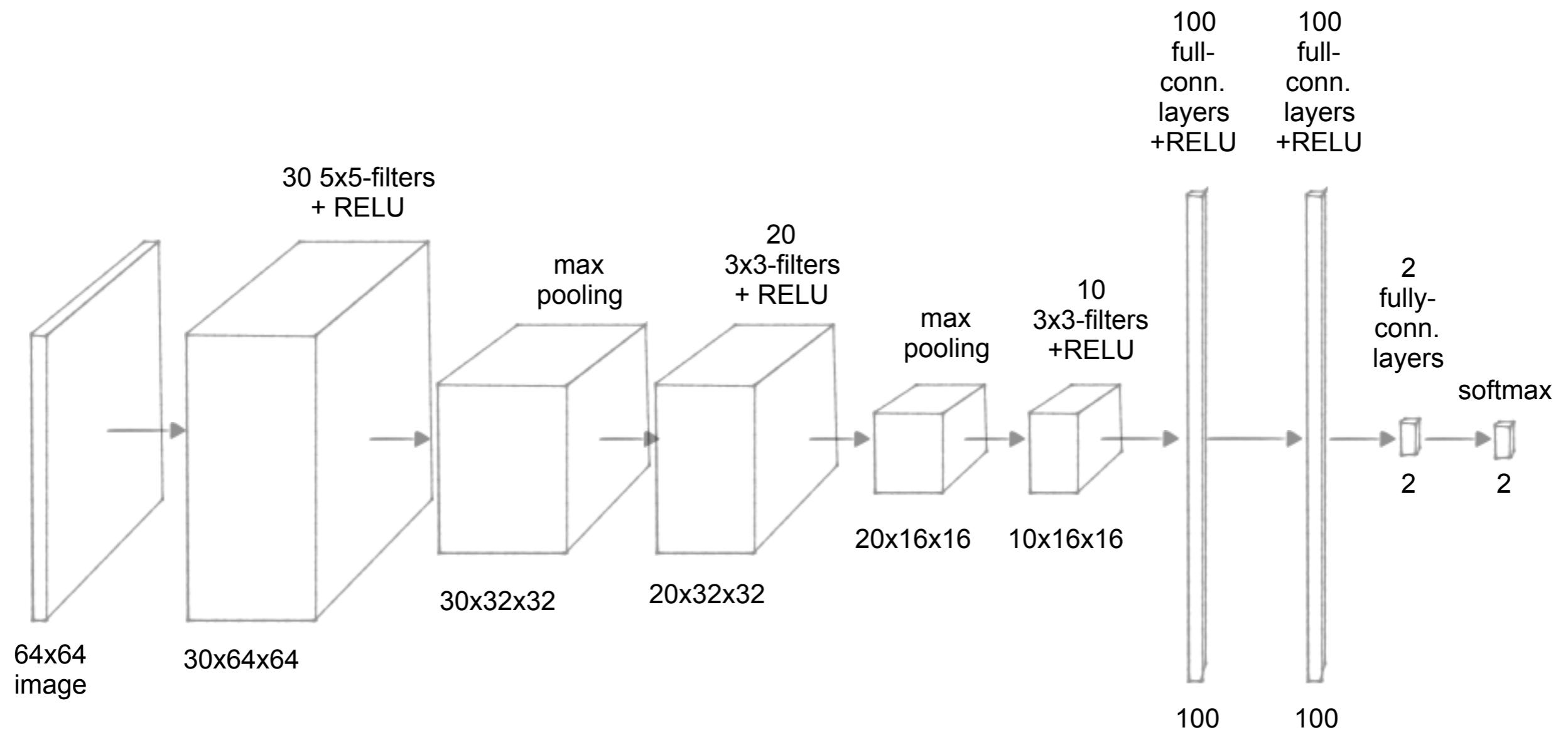
Network Structure



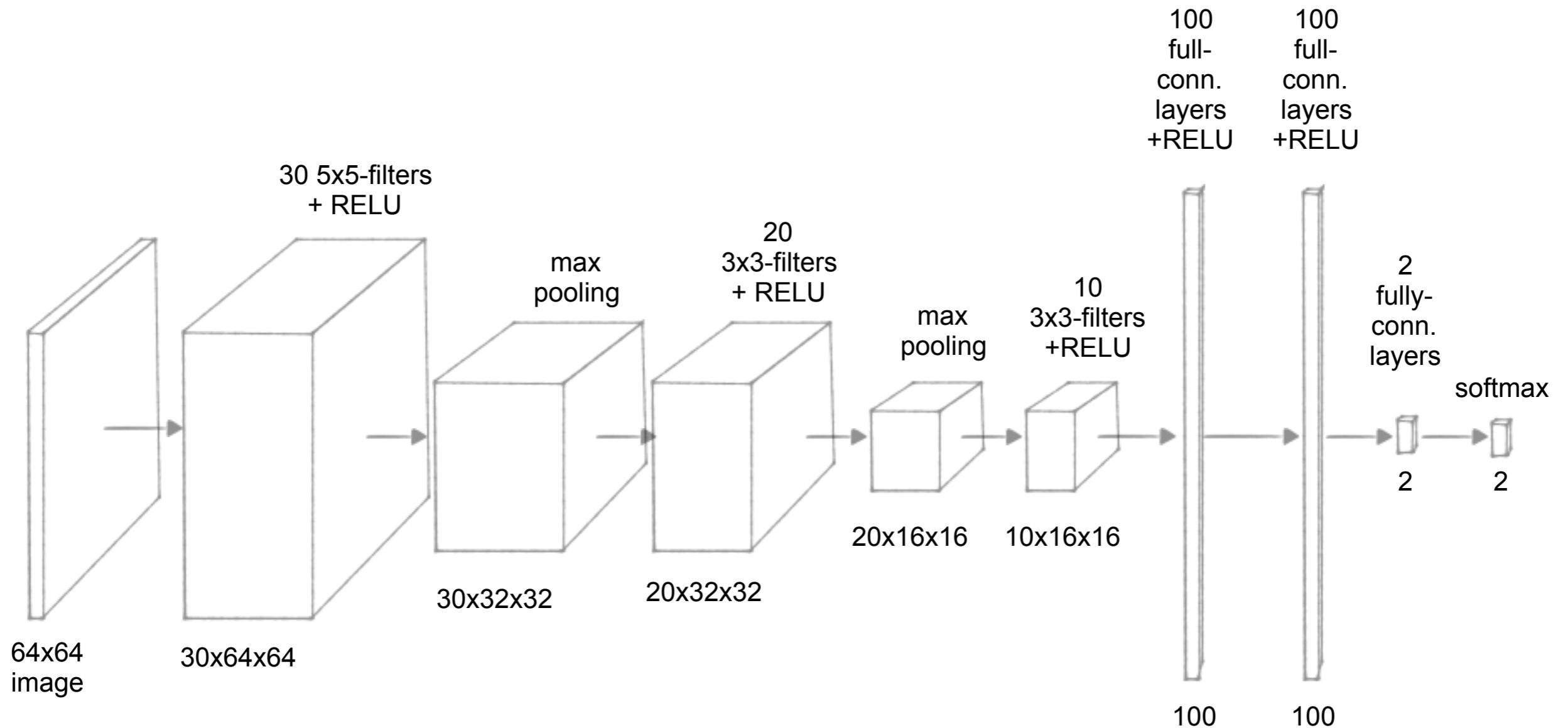
Network Structure



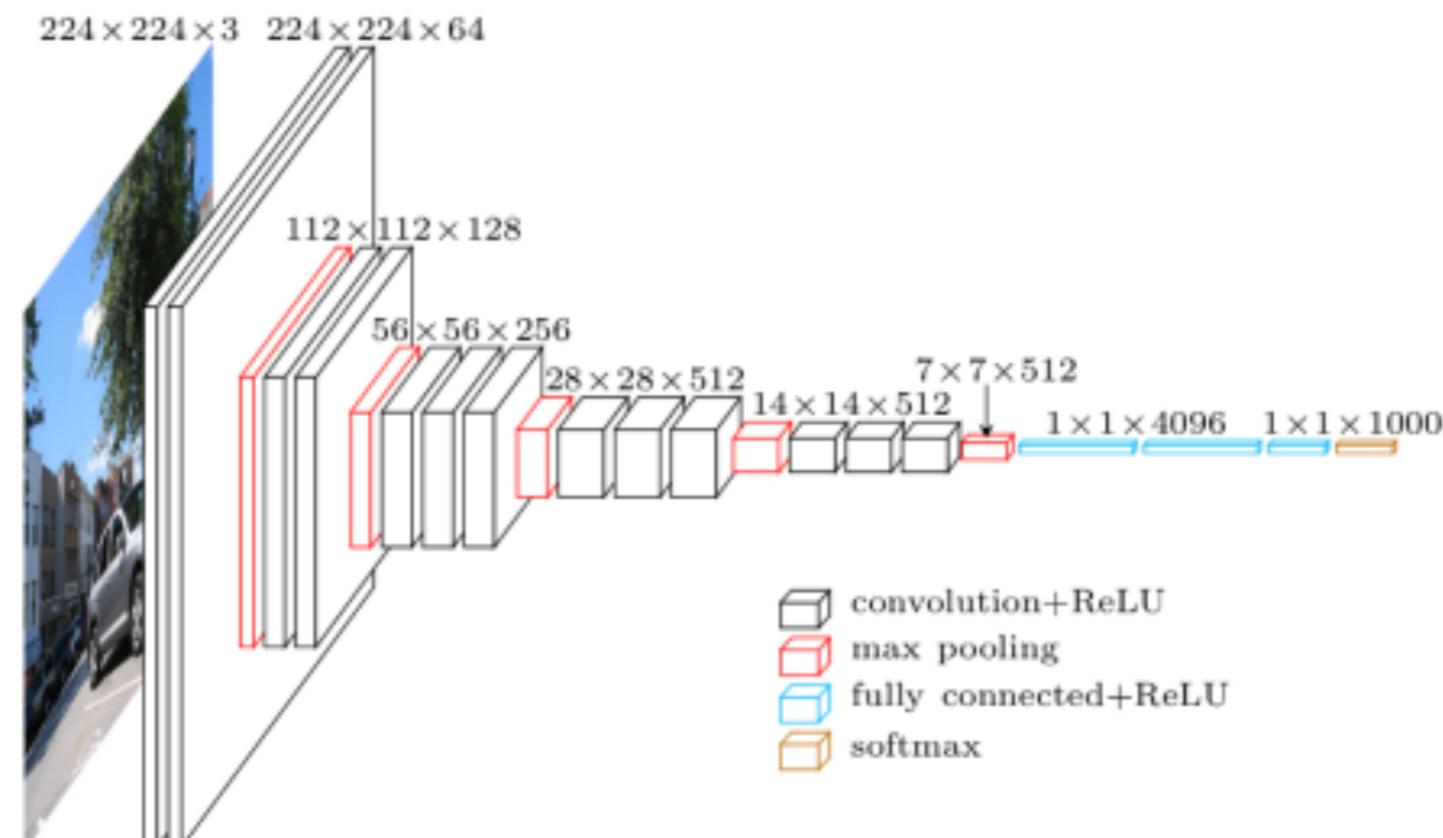
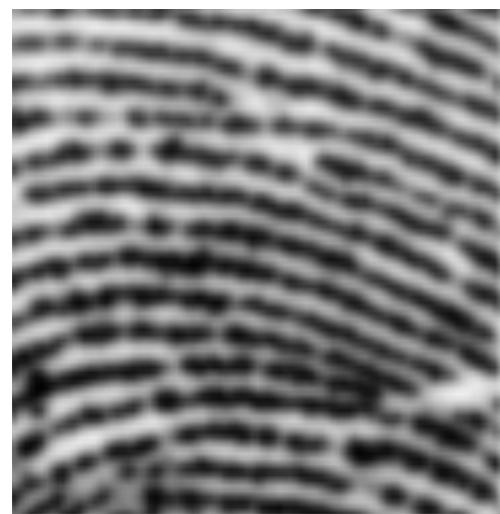
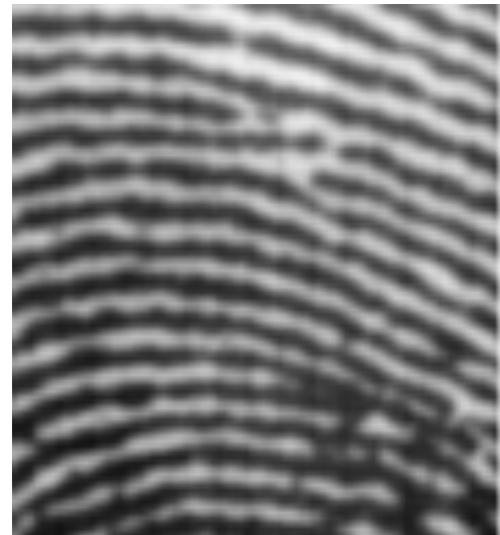
Network Structure



Number Parameters?



Live or Spoof?

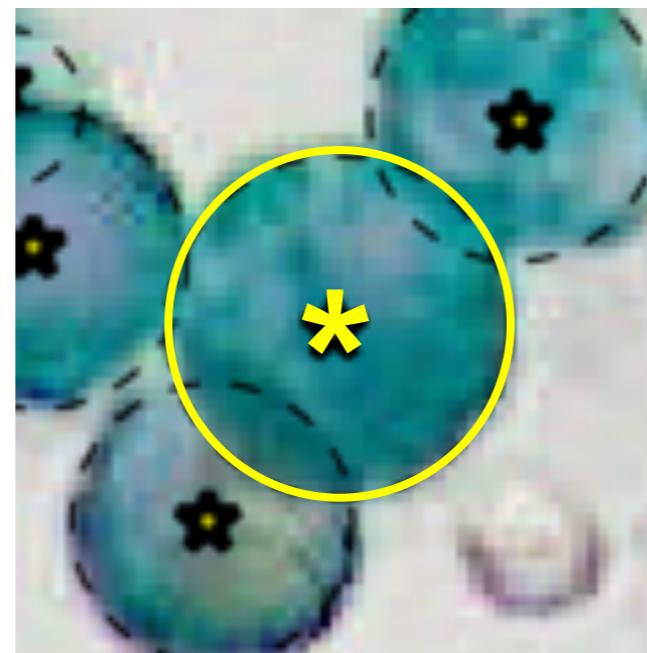


VGG-16

[Simonyan & Zisserman, Very Deep Convolutional Networks for Large-Scale Image Recognition, ICLR 2015]

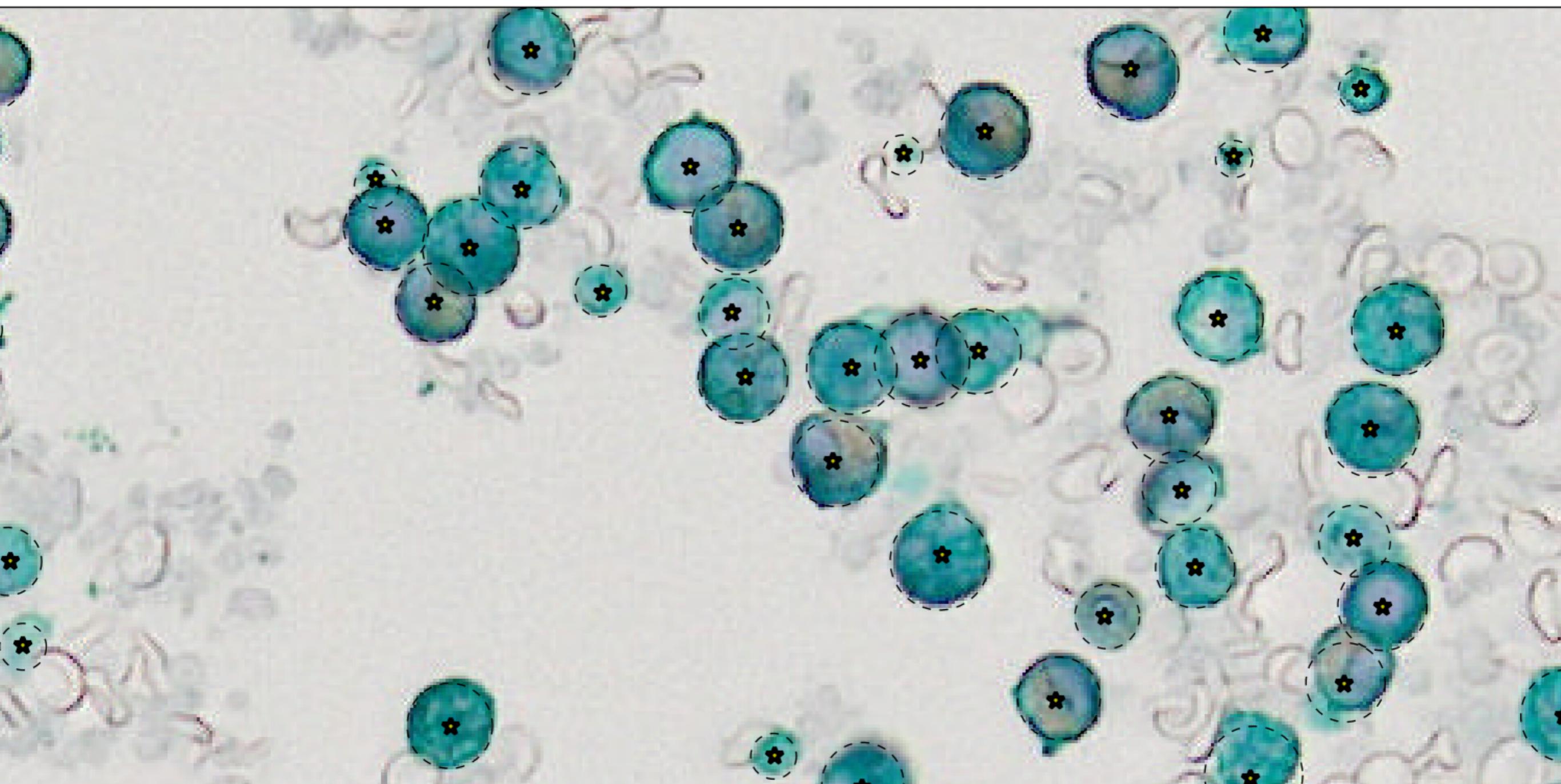
Regression: Centre and Radius

- No softmax
- Quadratic loss function

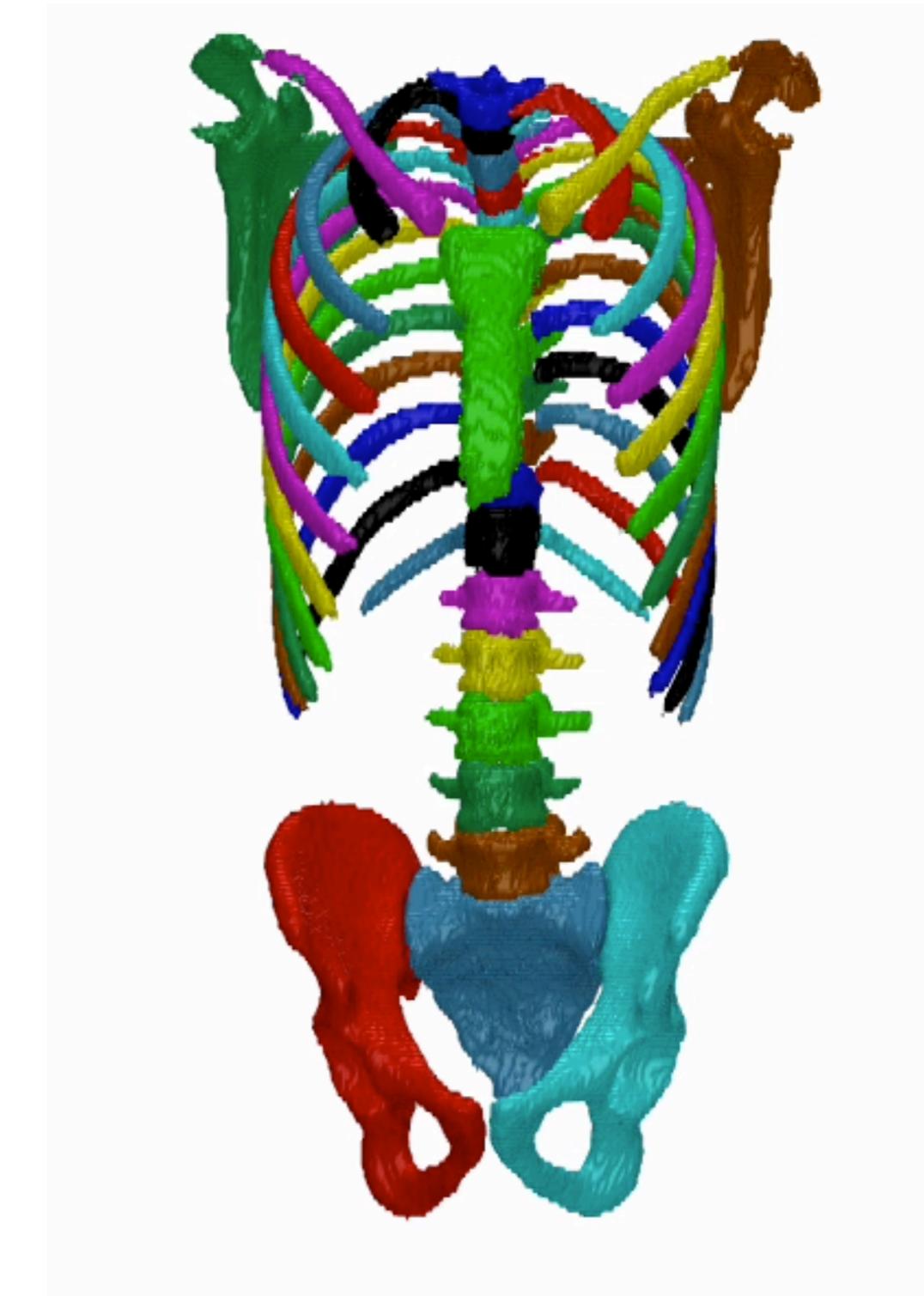
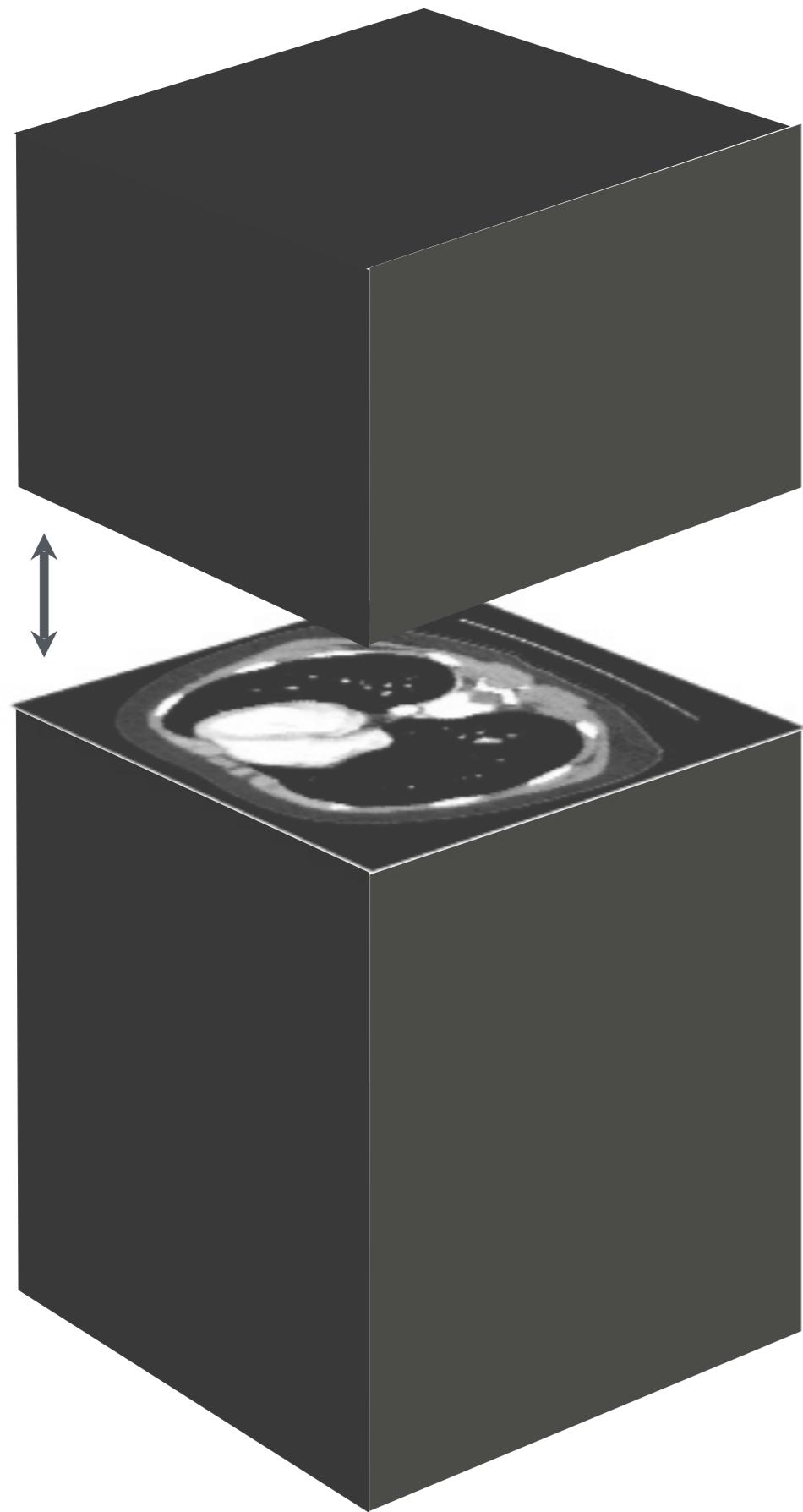


Centre and Radius

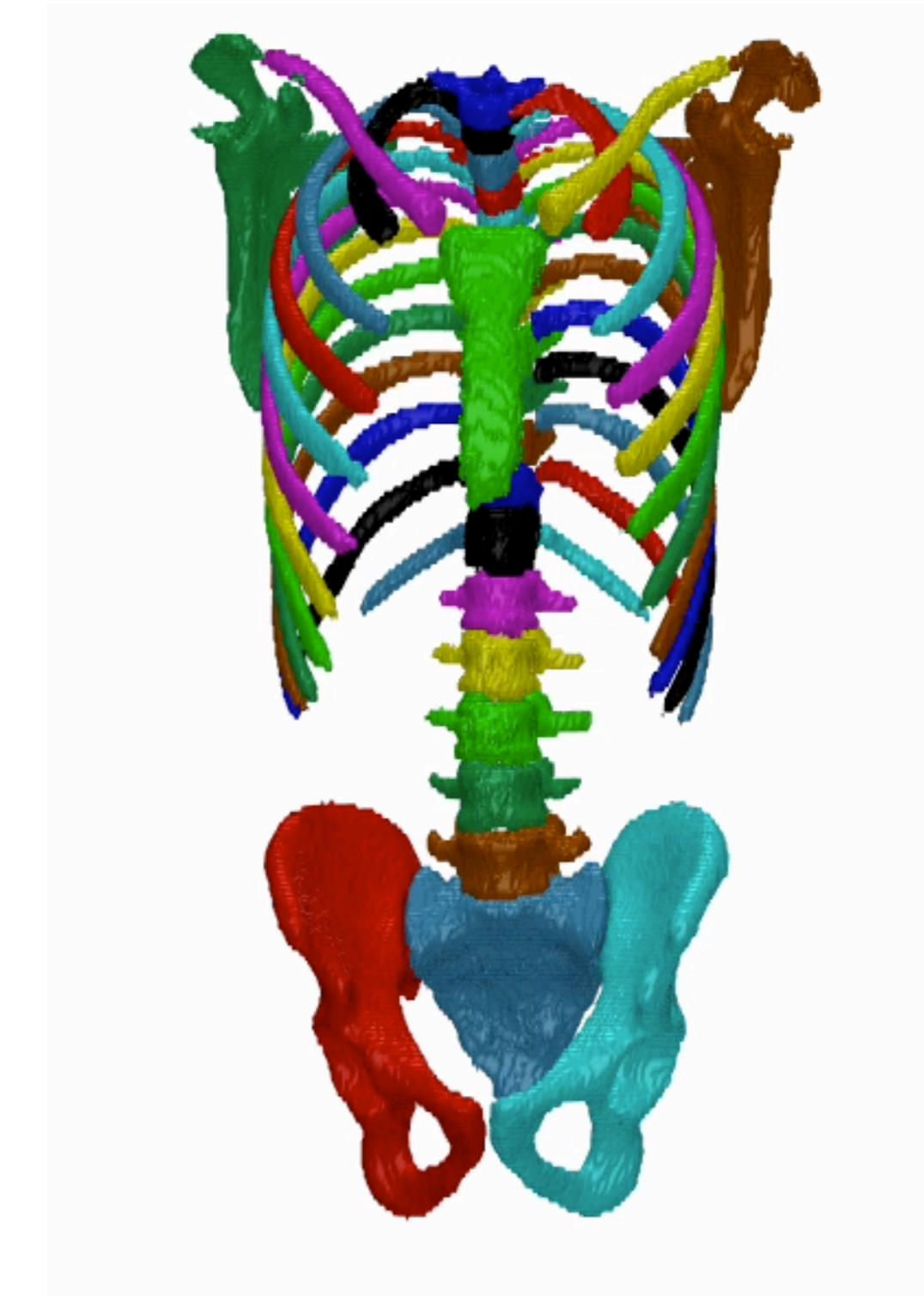
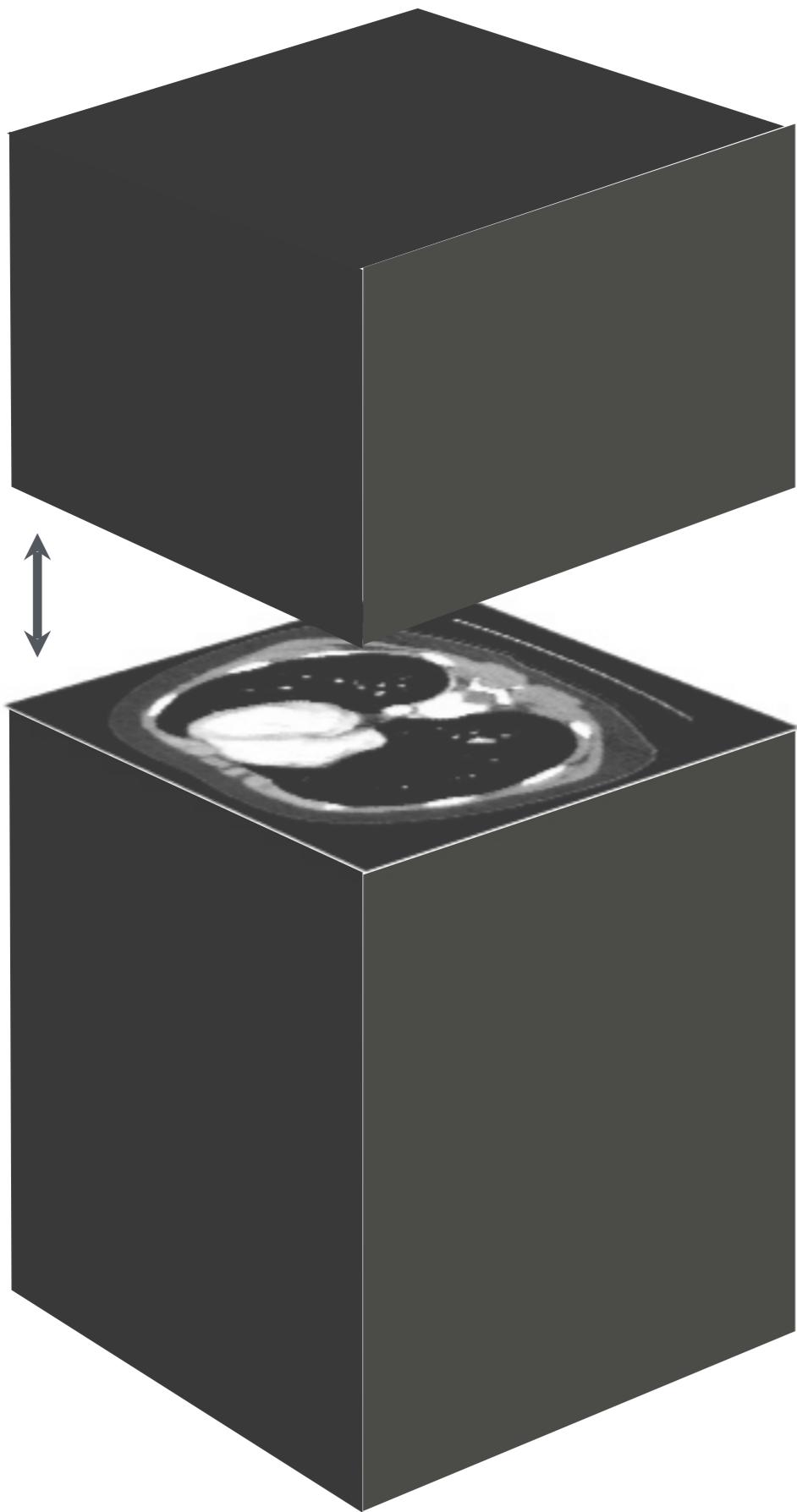
- No softmax
- Quadratic loss function



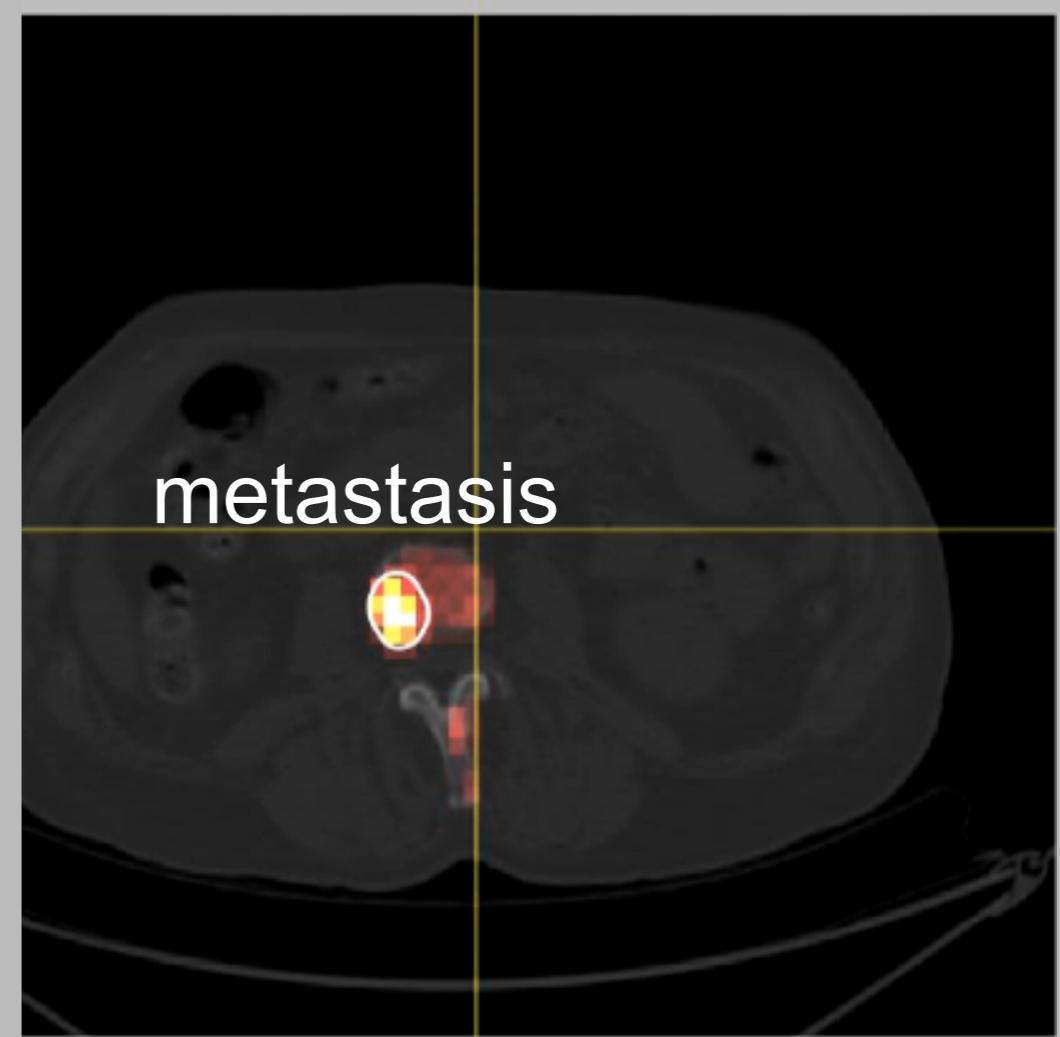
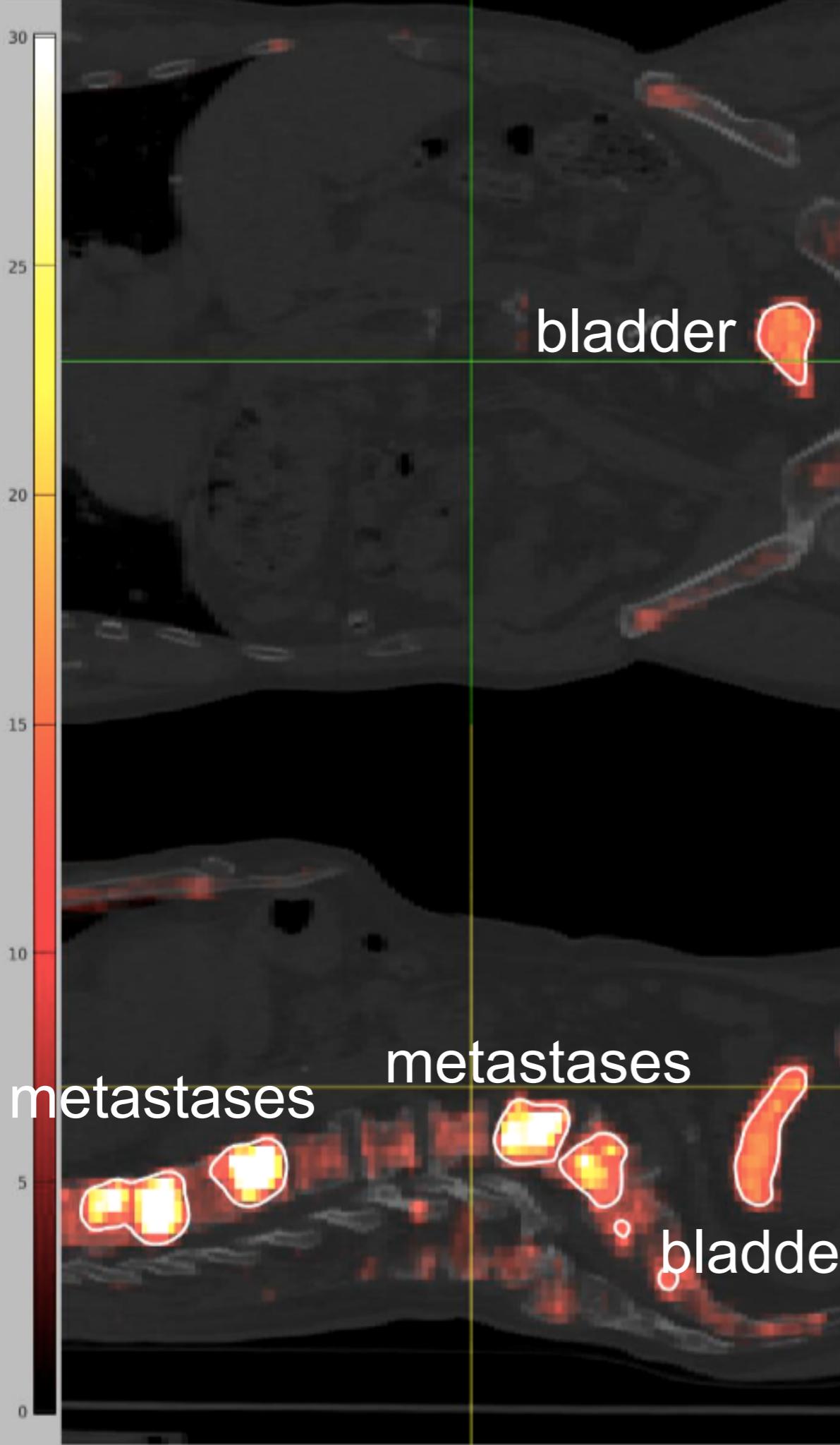
Segmentation



Segmentation



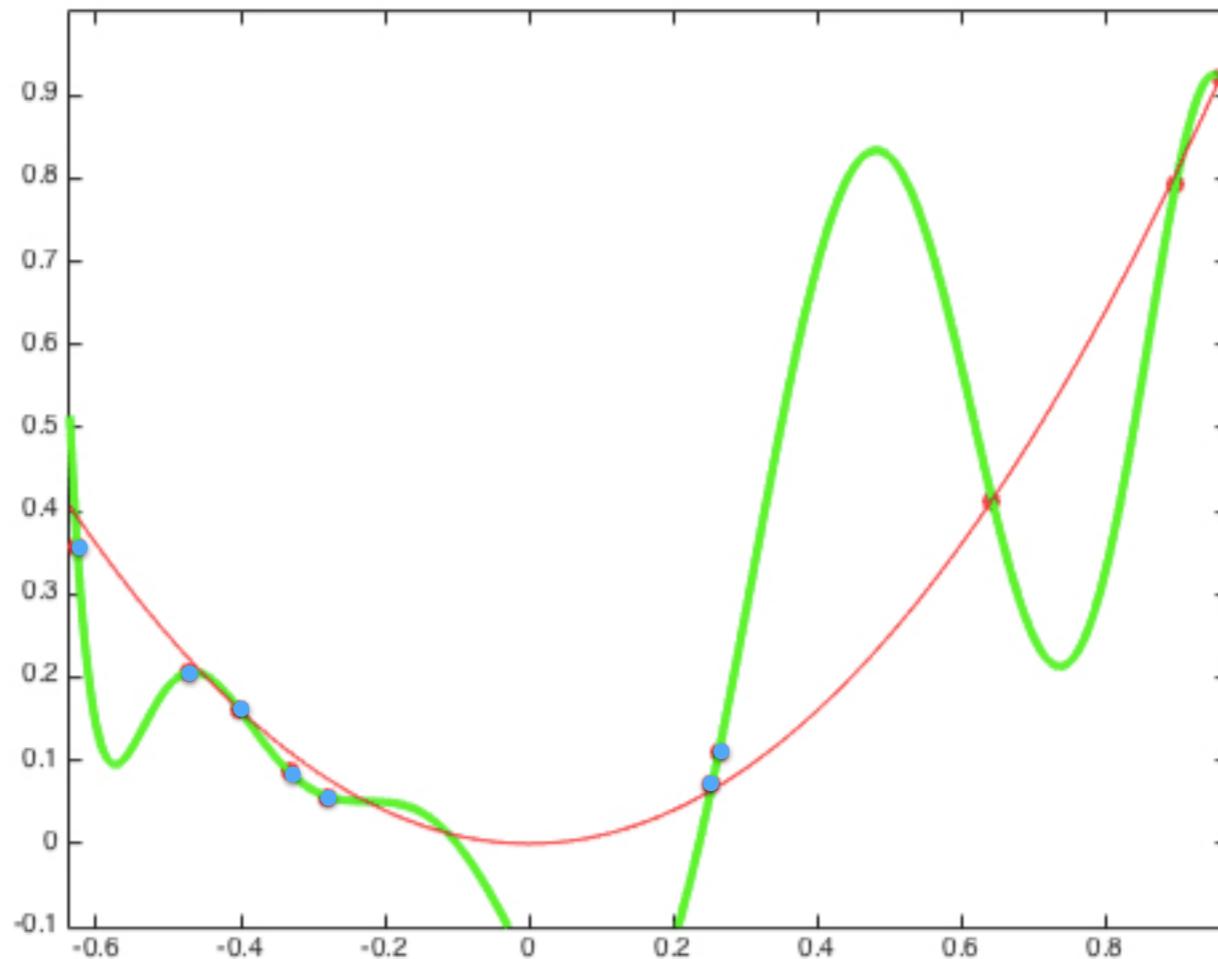
Diagnosis



Overfitting, Part II

Overfitting

10 data points - Fitting 10th degree polynomial



$$y = x^2$$

Overfitting

VGG-16 architecture



224

224

Overfitting

VGG-16 architecture



224



conv 1

224

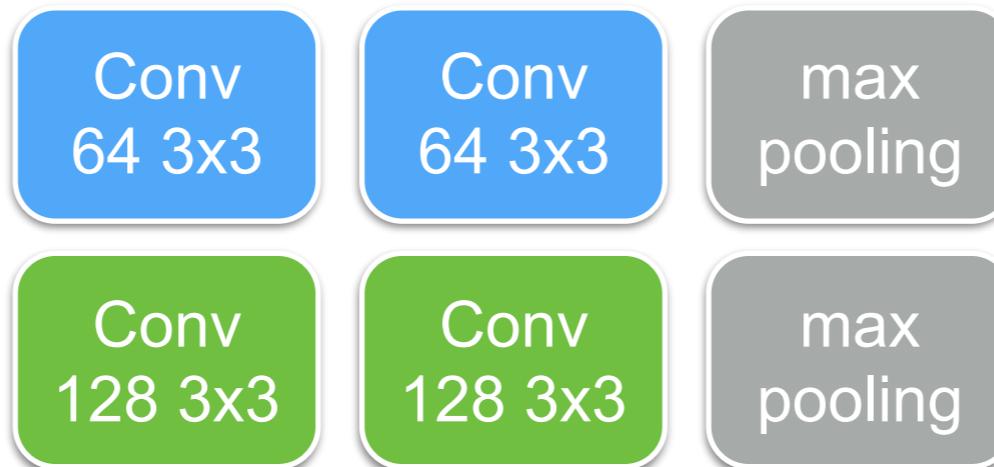
Overfitting

VGG-16 architecture



224

224



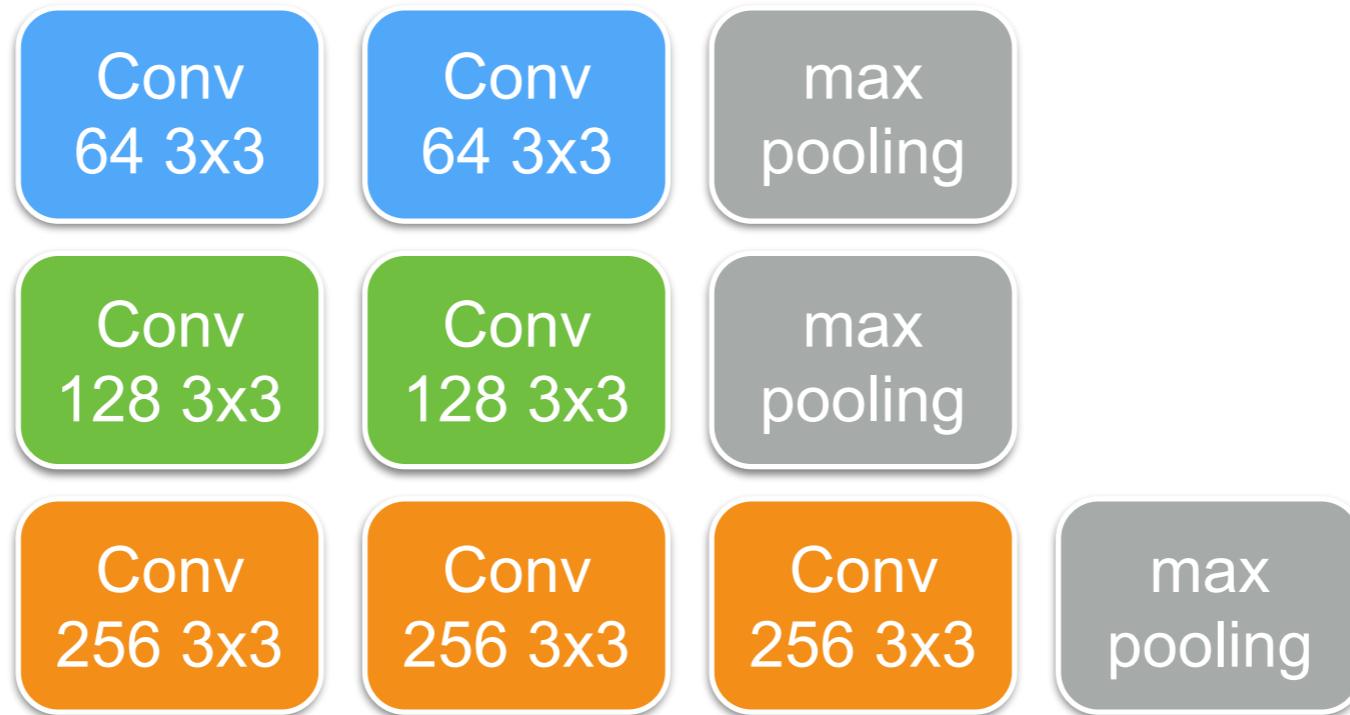
Overfitting

VGG-16 architecture



224

224



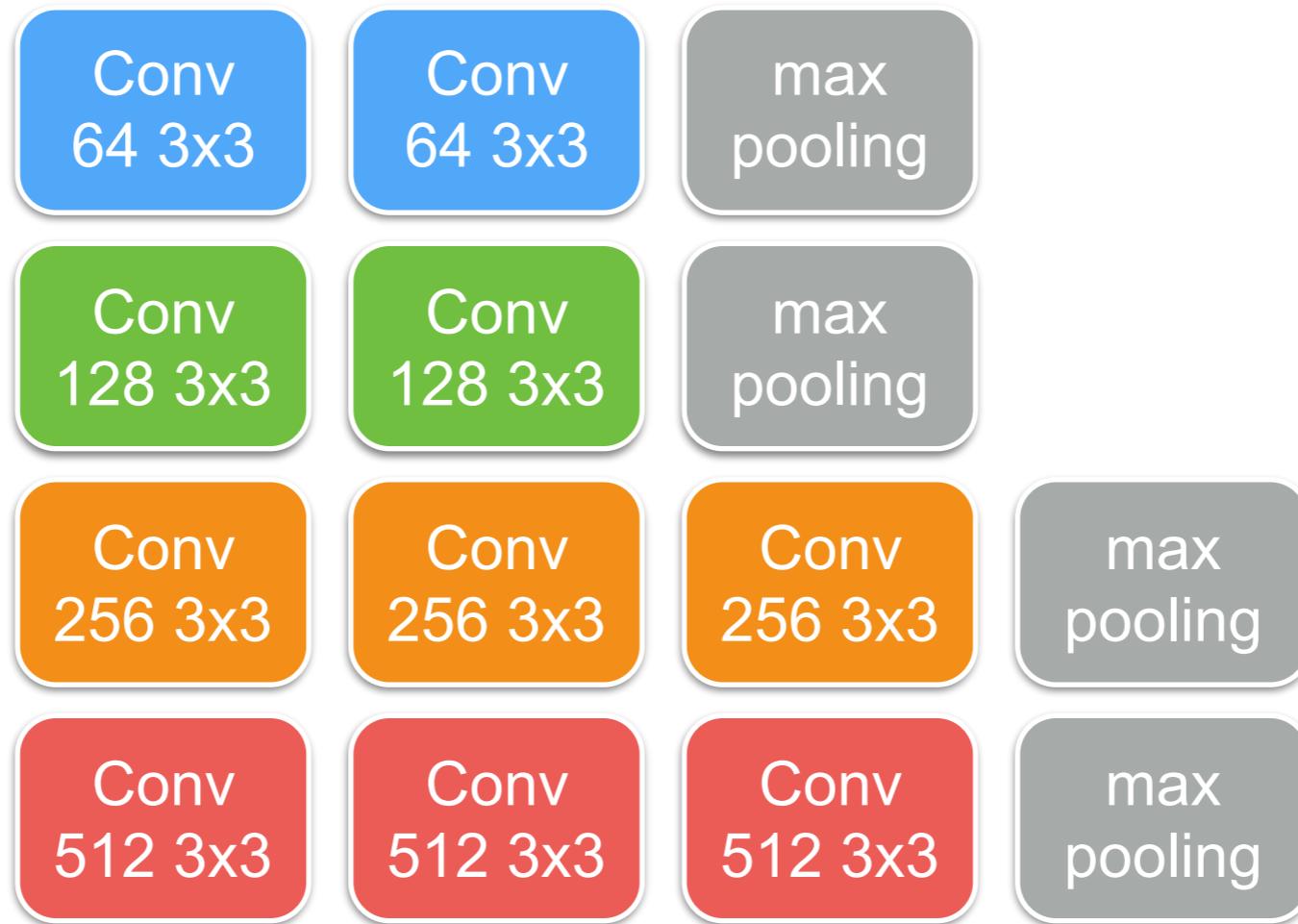
Overfitting

VGG-16 architecture



224

224



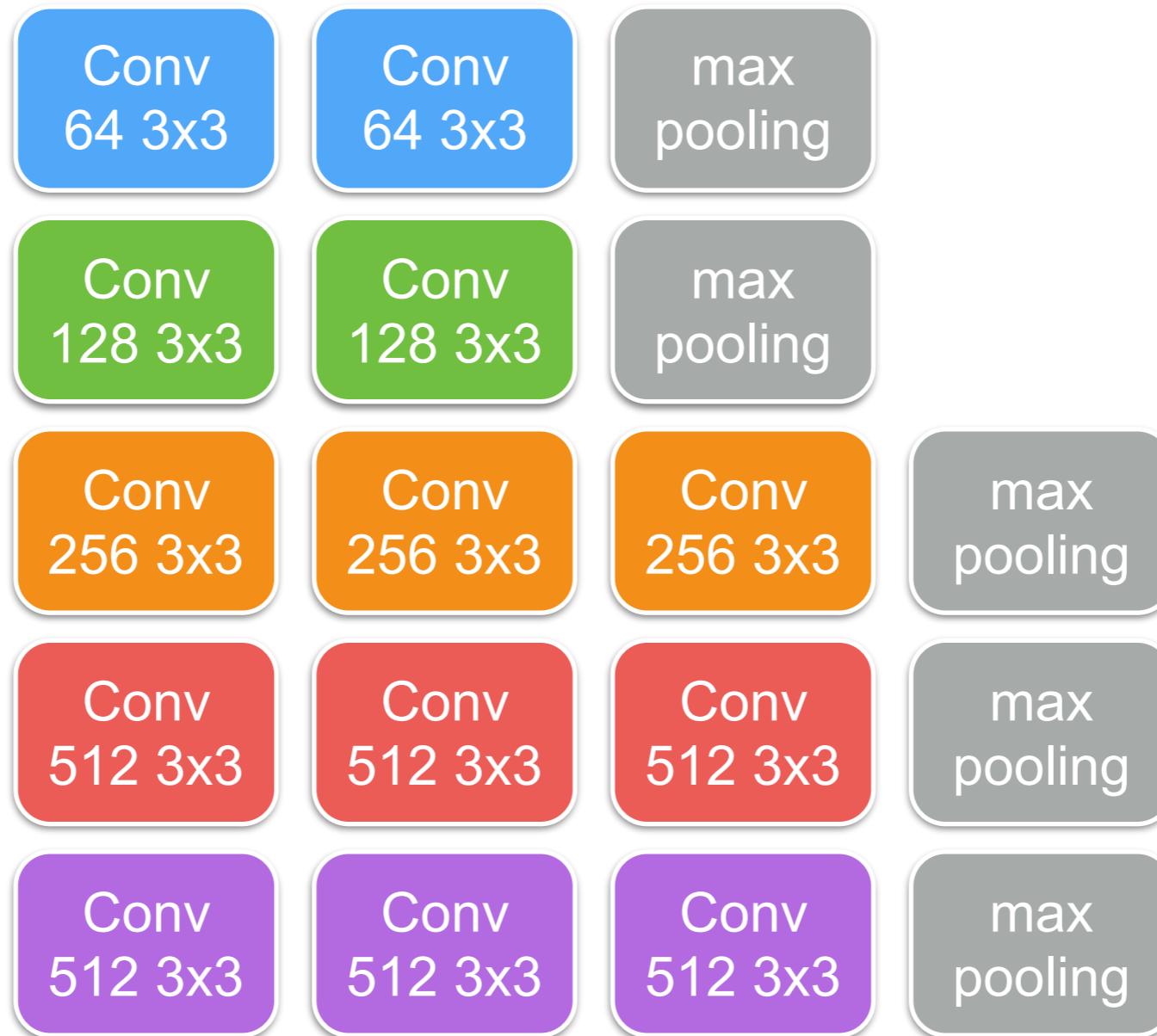
Overfitting

VGG-16 architecture



224

224



conv 1

conv 2

conv 3

conv 4

conv 5

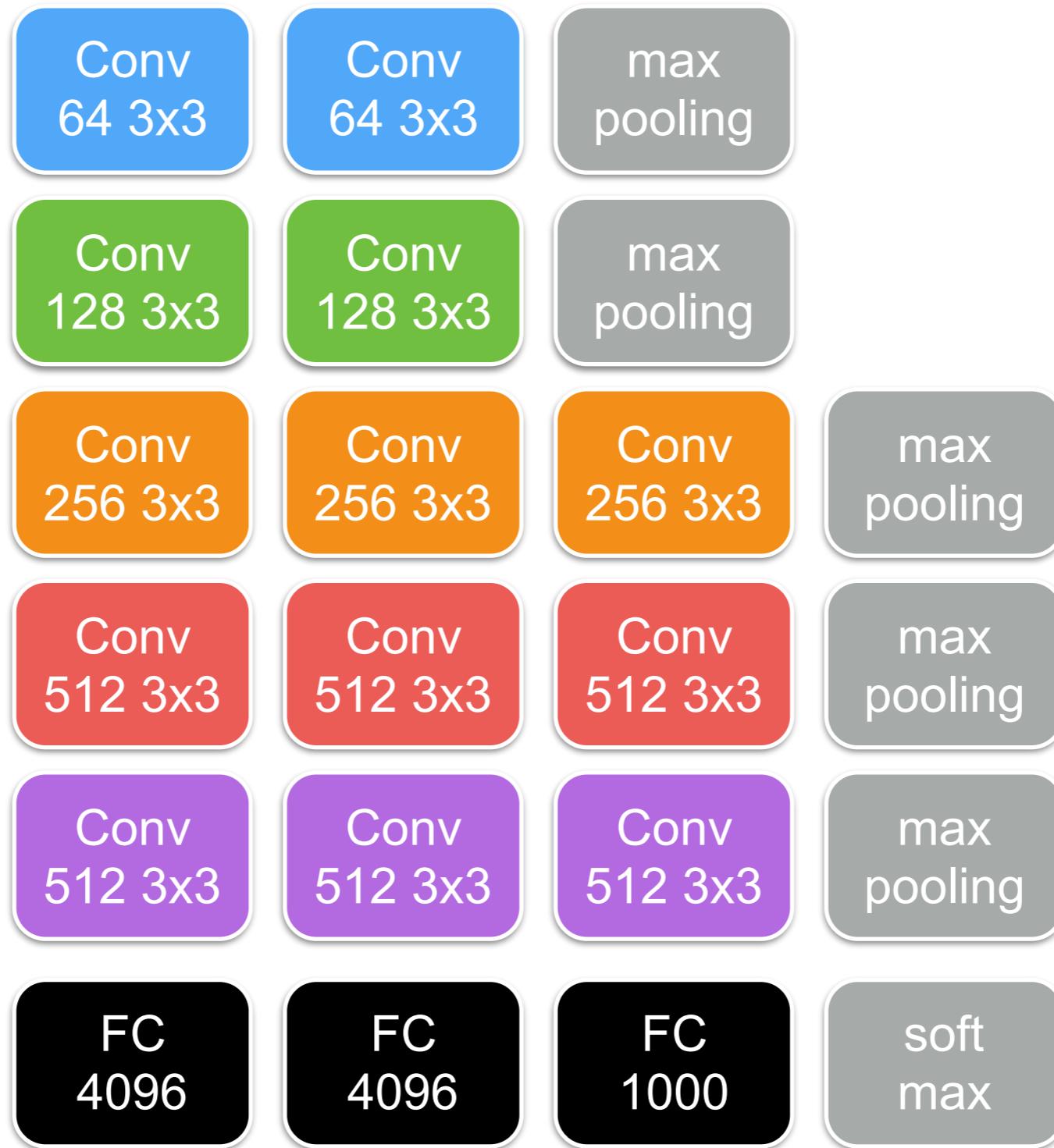
Overfitting

VGG-16 architecture



224

224



Overfitting

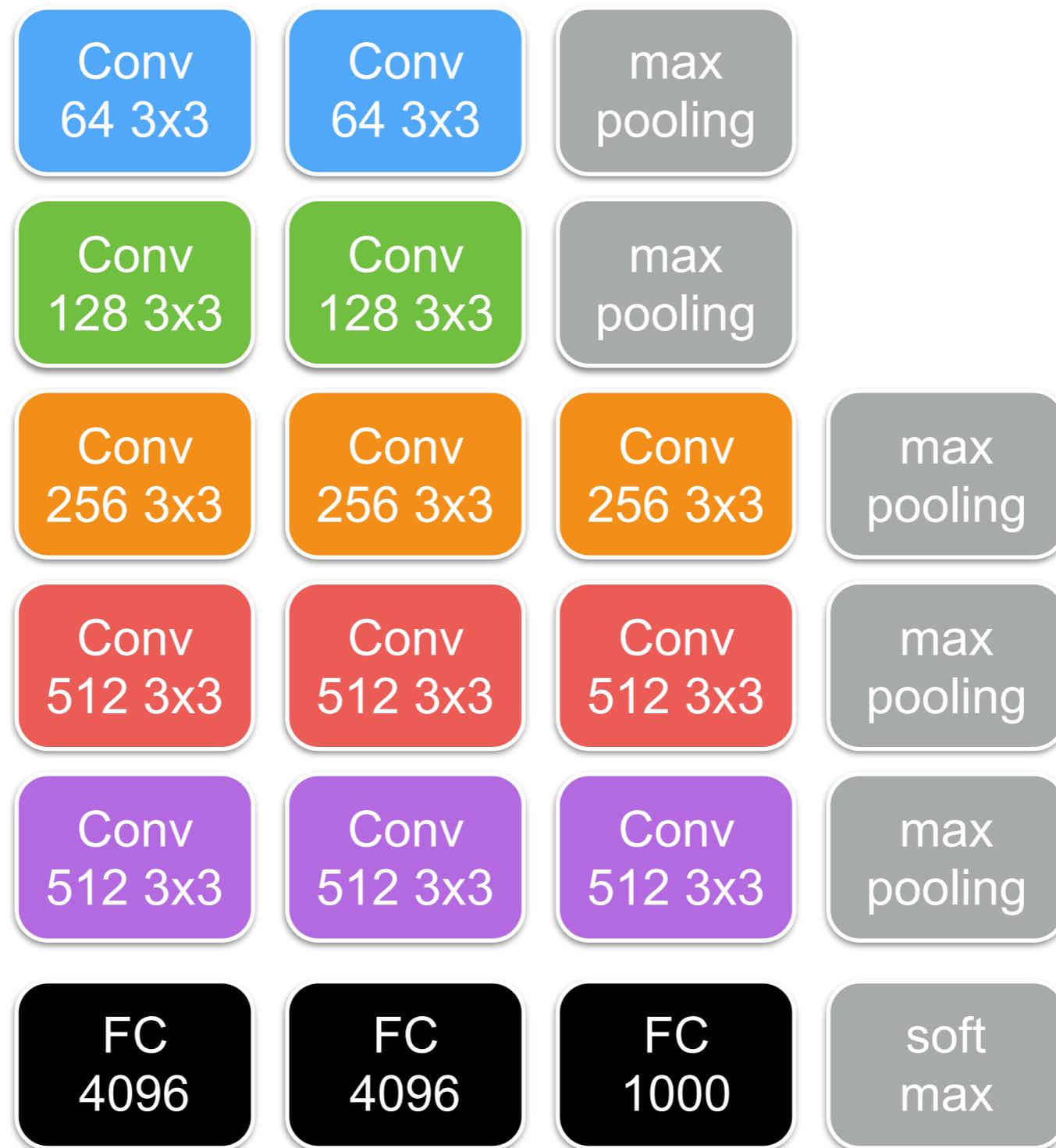
VGG-16 architecture



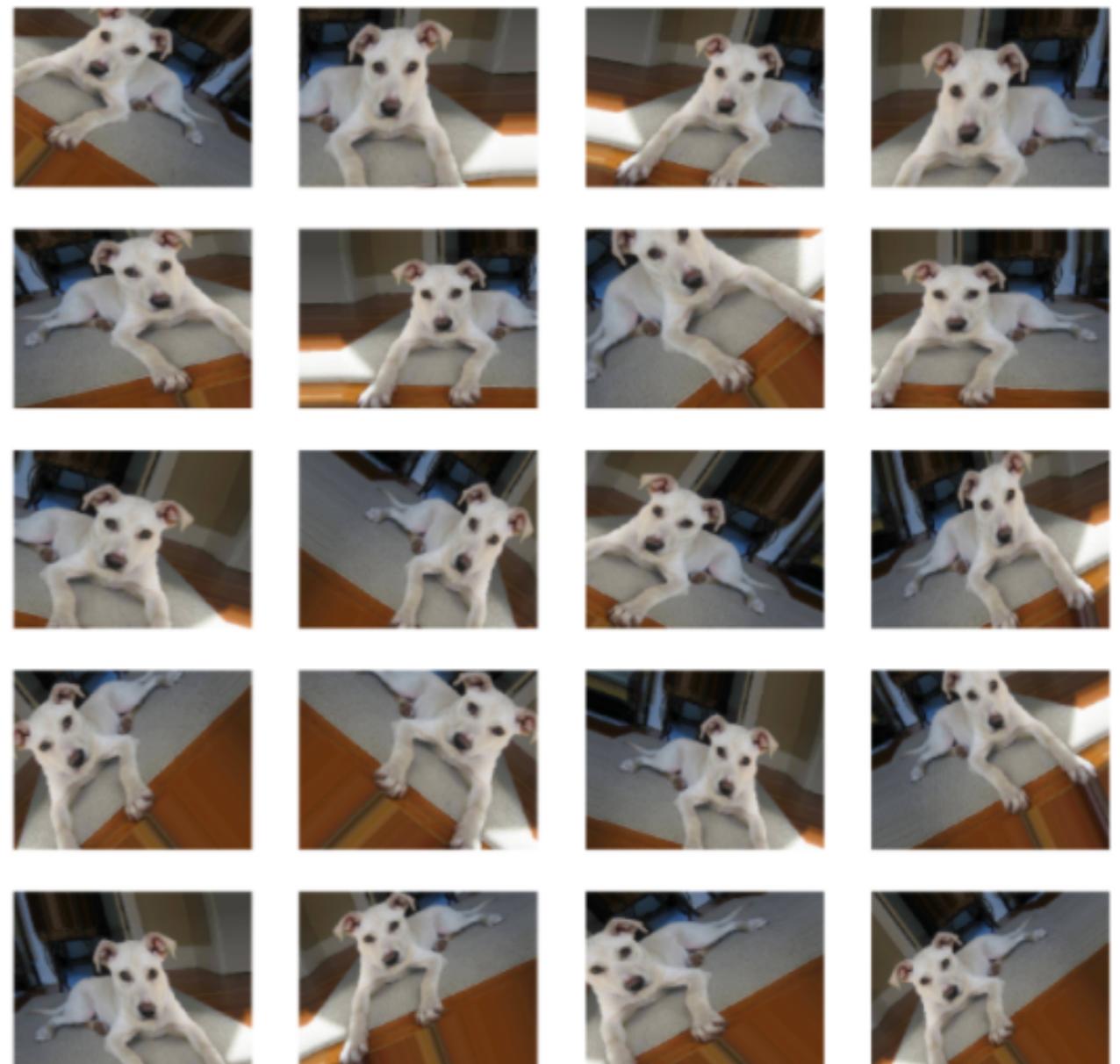
224

224

**~138M
parameters!**



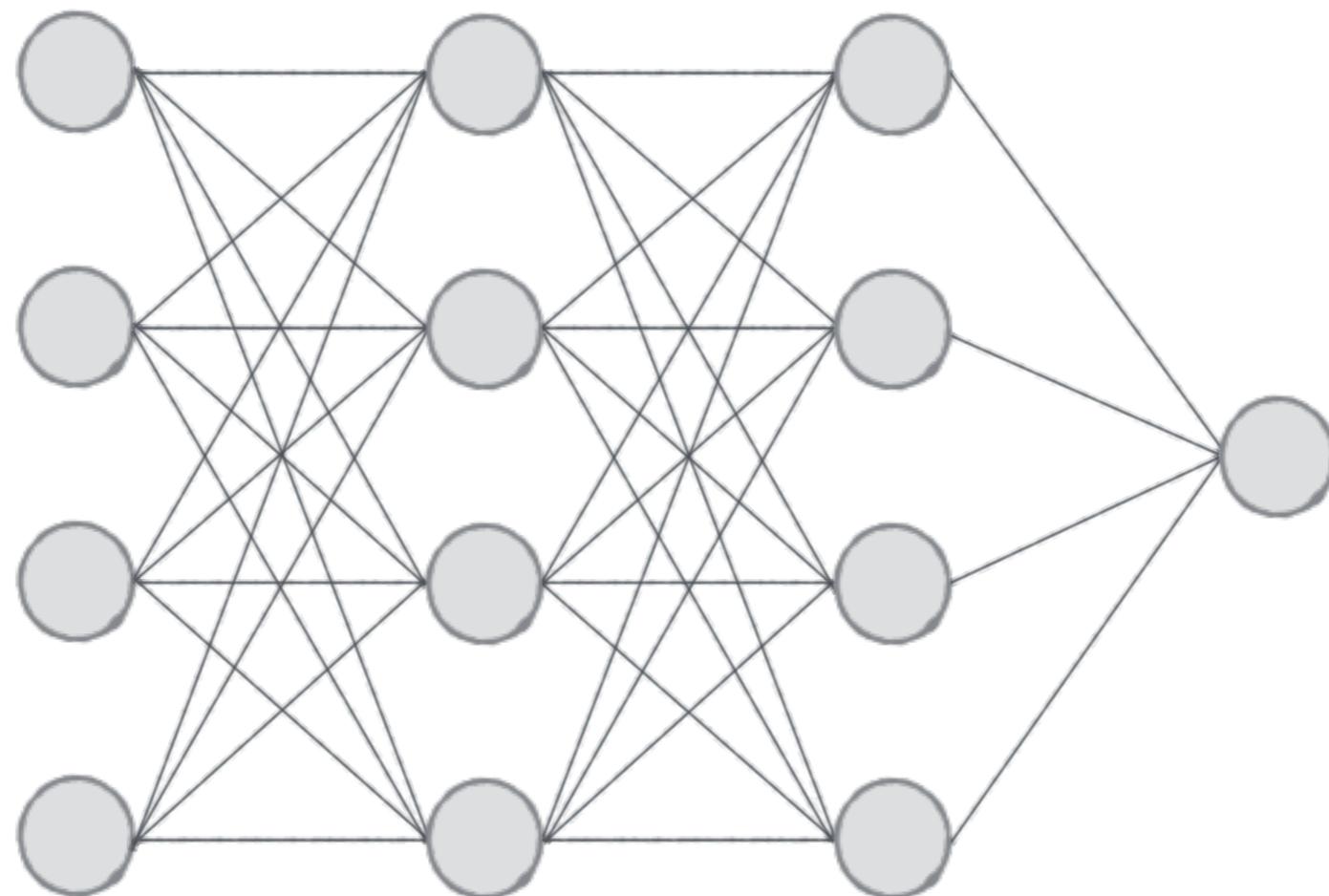
Data Augmentation



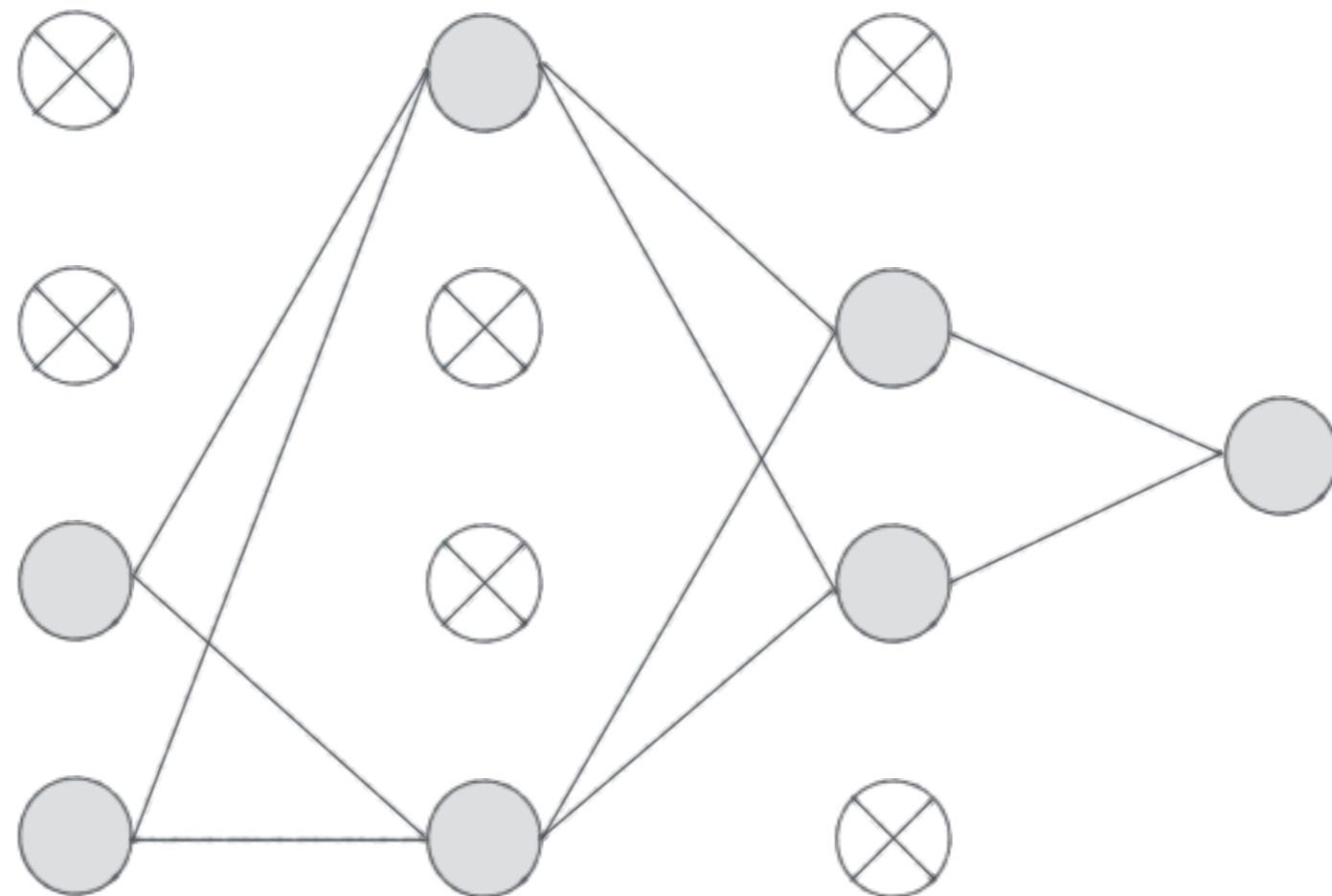
Regularization

$$L(w_1, \dots, w_n) + c \sum_i w_i^2$$

Dropout



Dropout



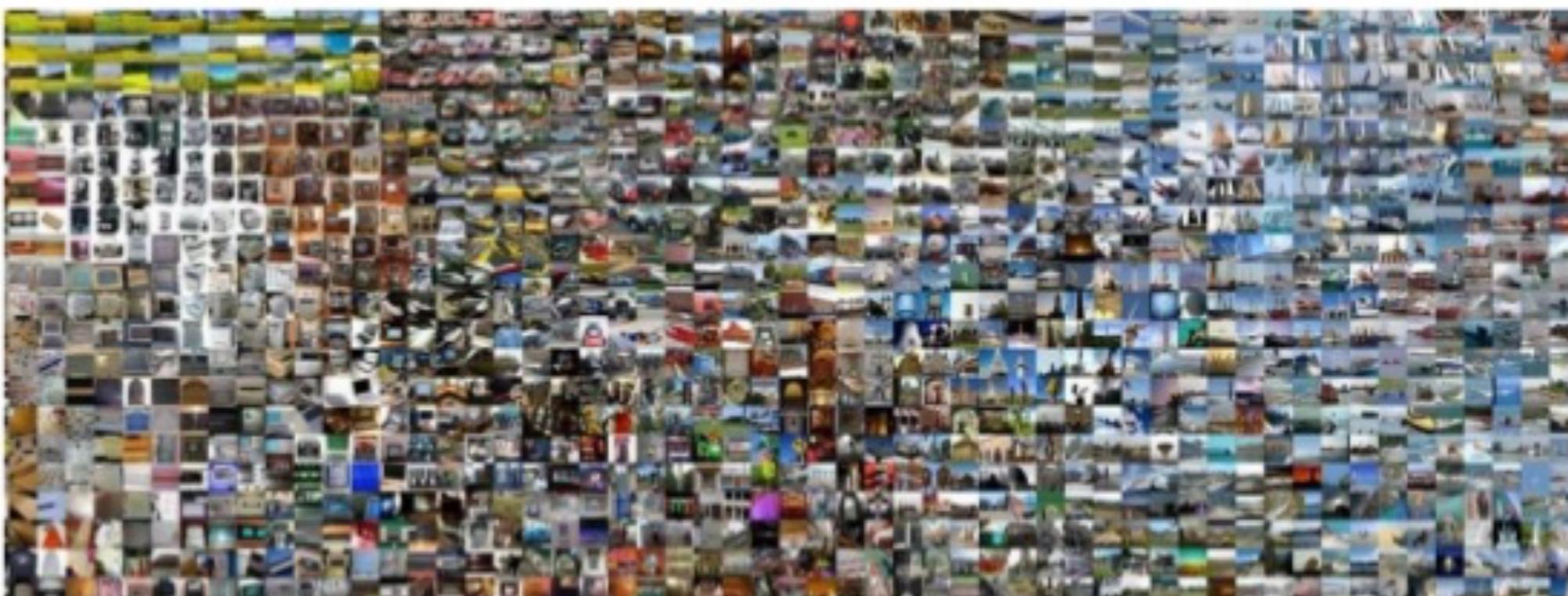
Randomly disable neurons for each minibatch

Dropout



Transfer Learning

IMAGENET



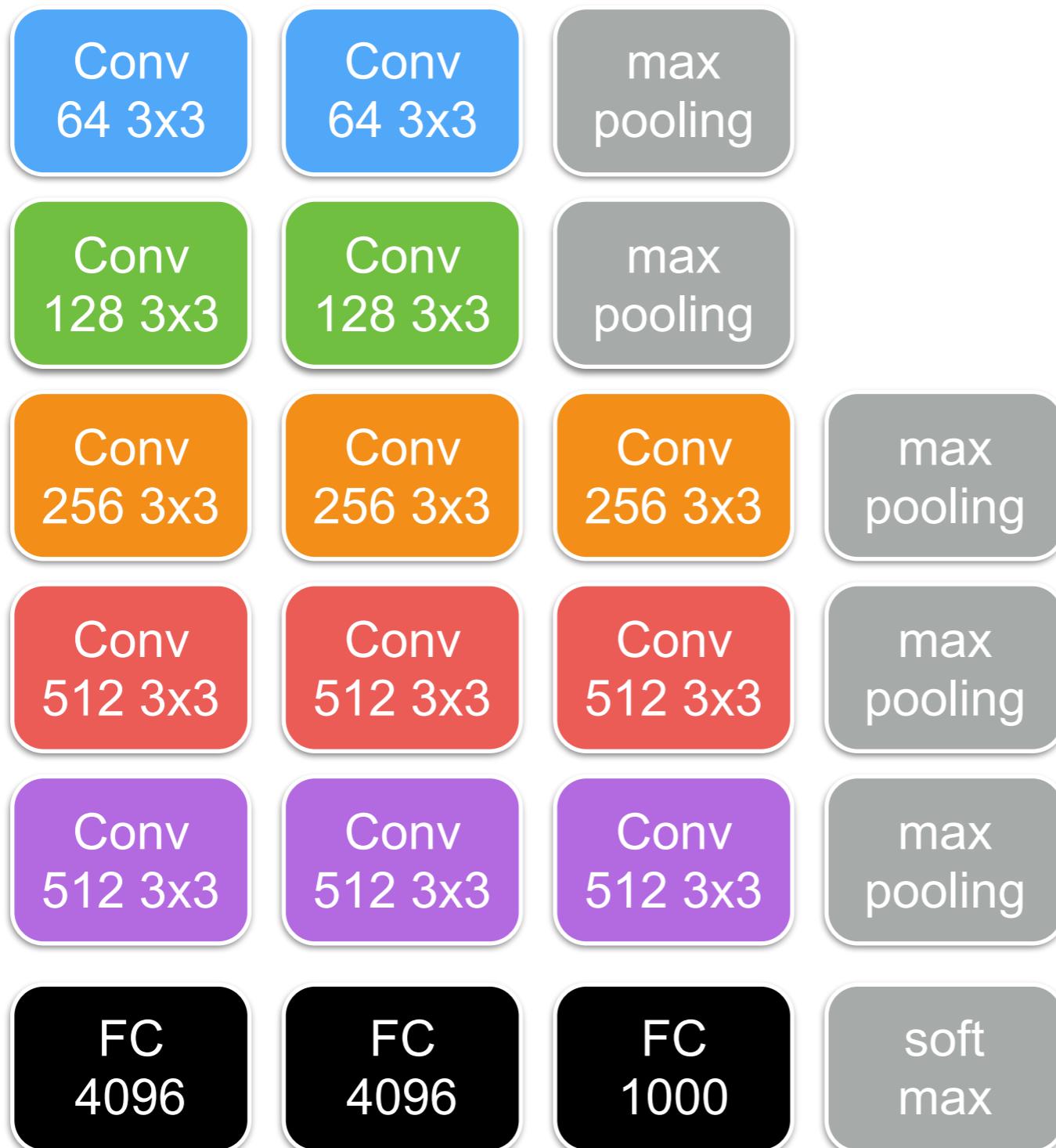
Russakovsky, O., Deng, J., Su, H., Krause, J., Satheesh, S., Ma, S., ... & Fei-Fei, L. (2015). [Imagenet large scale visual recognition challenge](#). *arXiv preprint arXiv:1409.0575*. [\[web\]](#)

3

14 million images of 1000 classes

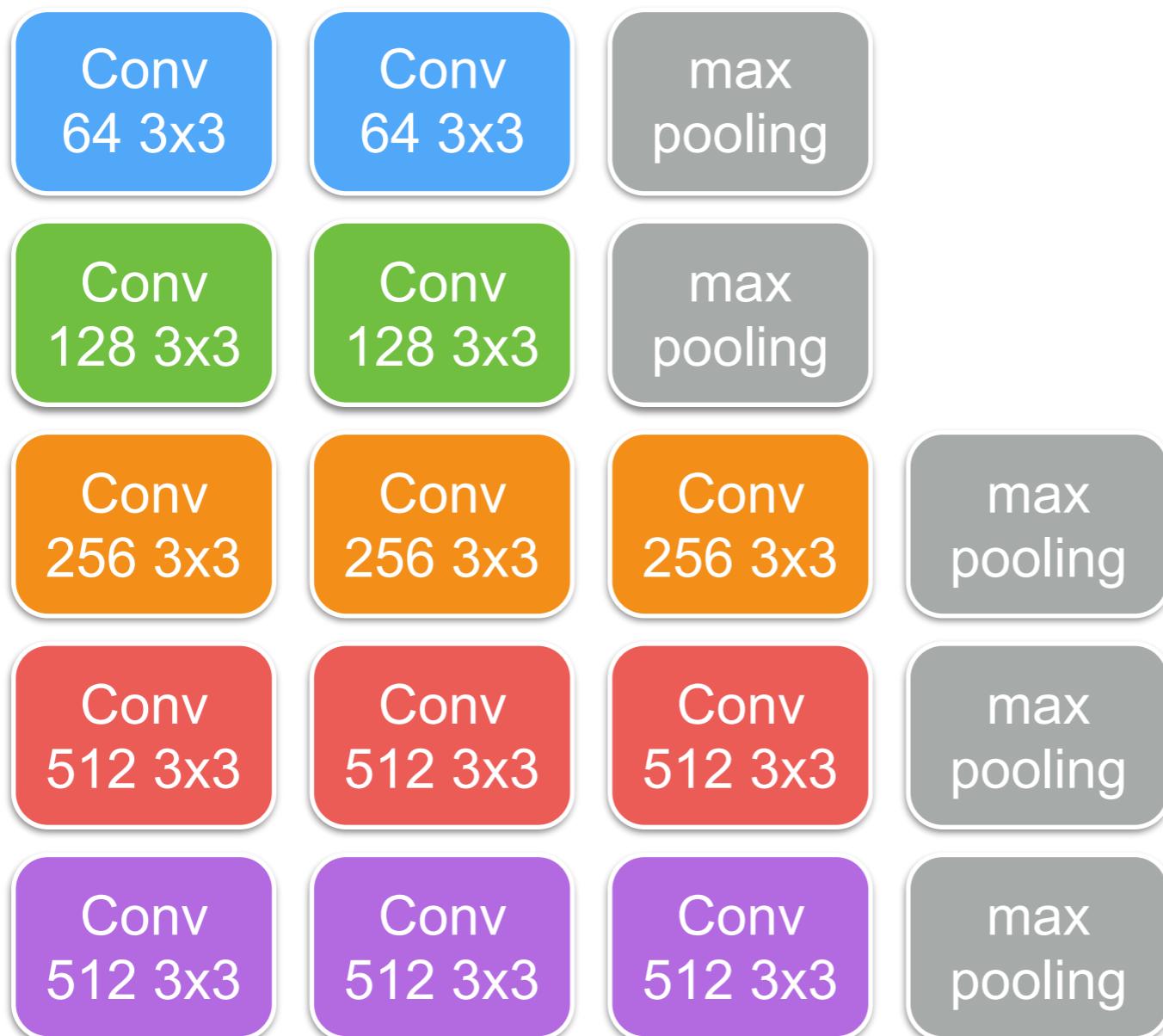
Transfer Learning

VGG-16 architecture



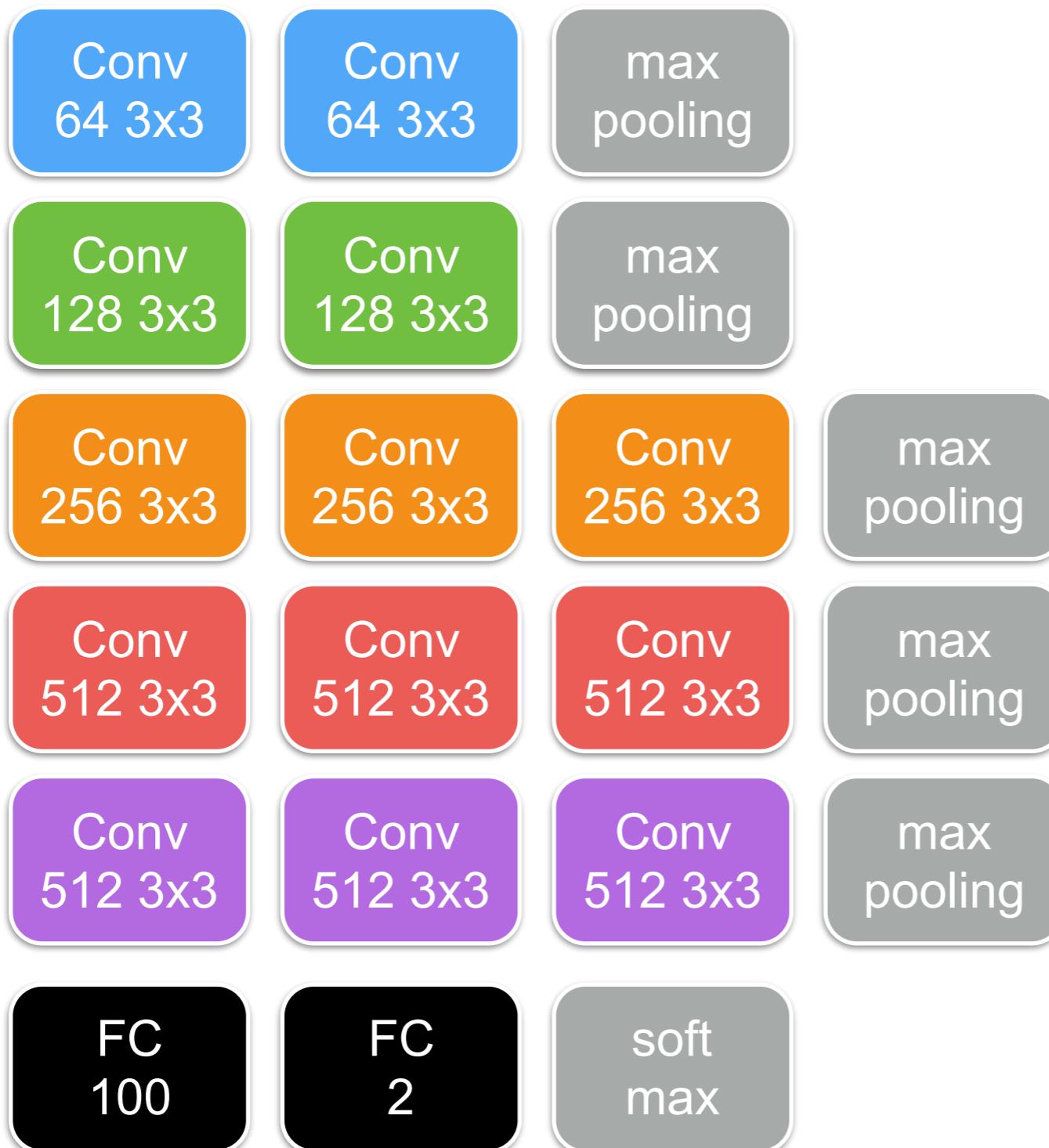
Transfer Learning

VGG-16 architecture



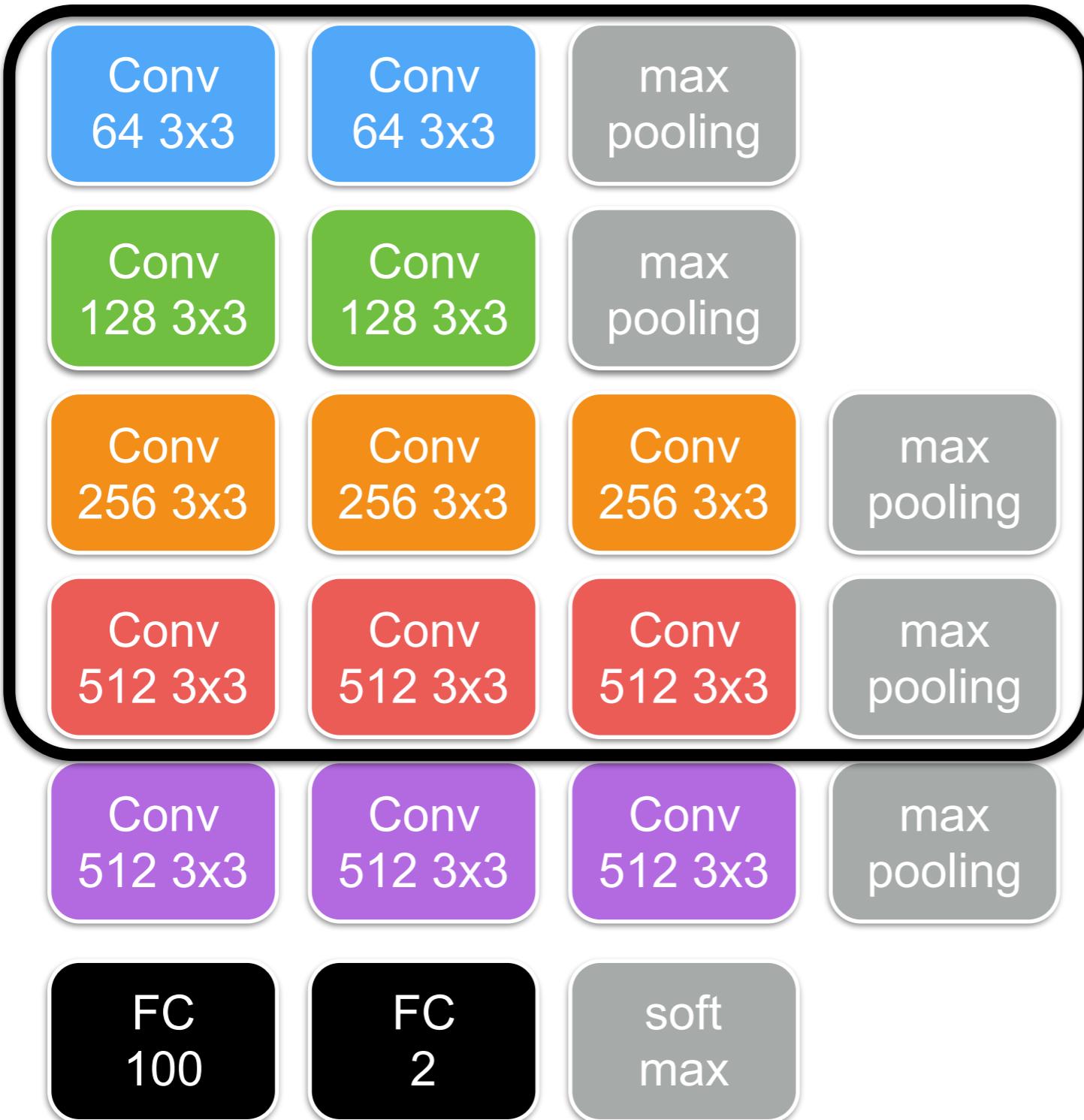
Transfer Learning

VGG-16 architecture



Transfer Learning

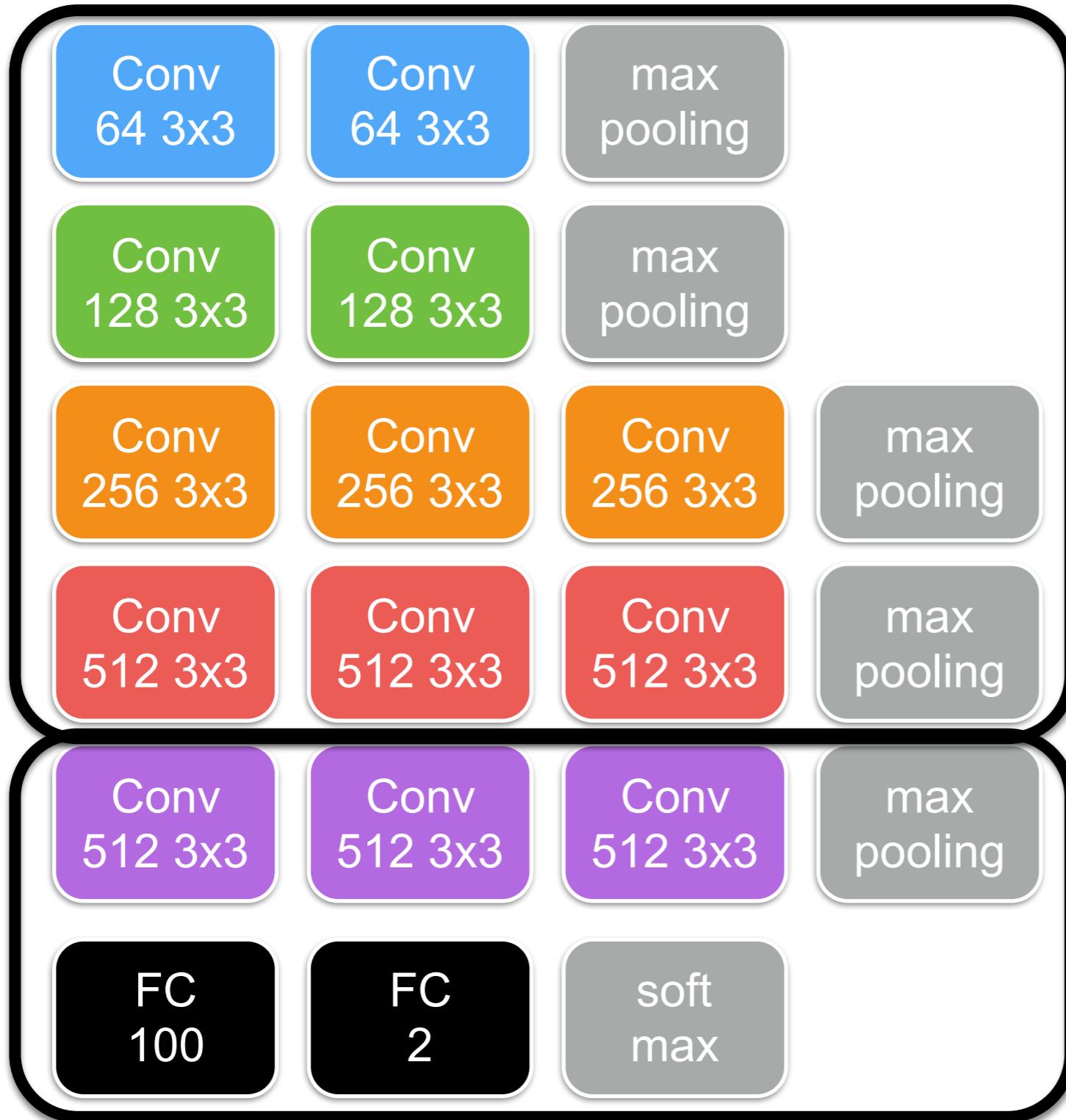
VGG-16 architecture



Fix weights

Transfer Learning

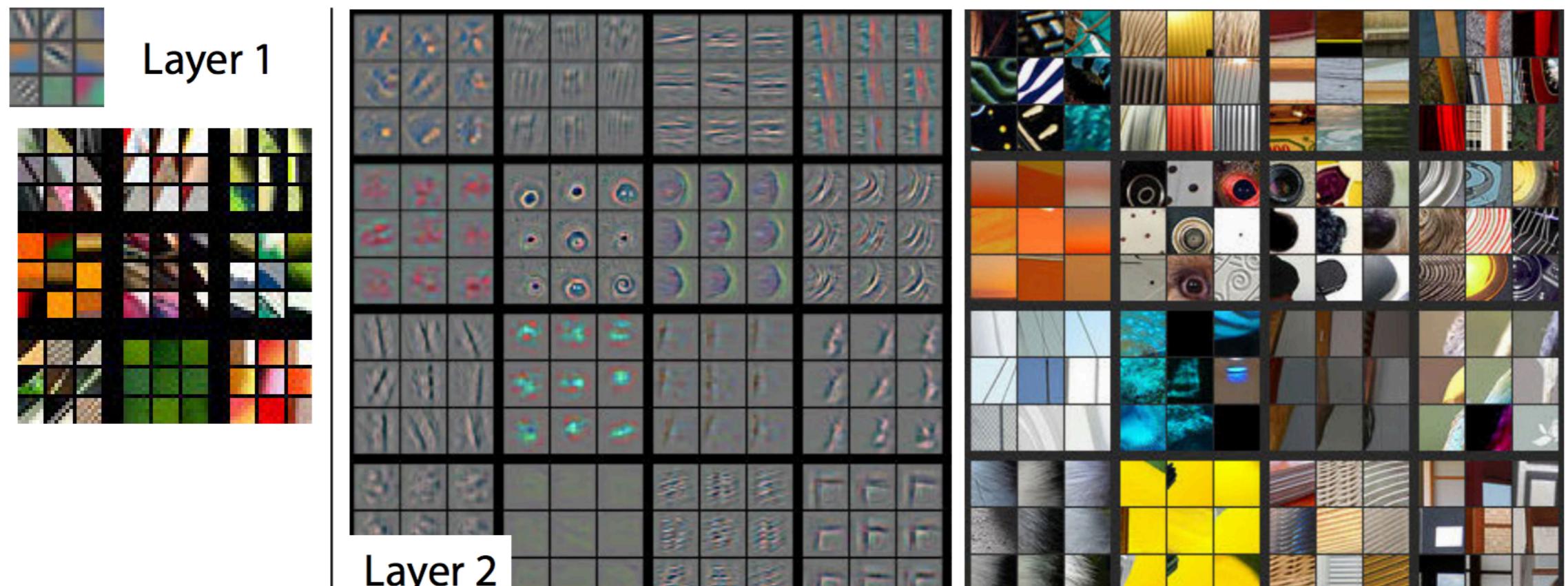
VGG-16 architecture



Fix weights

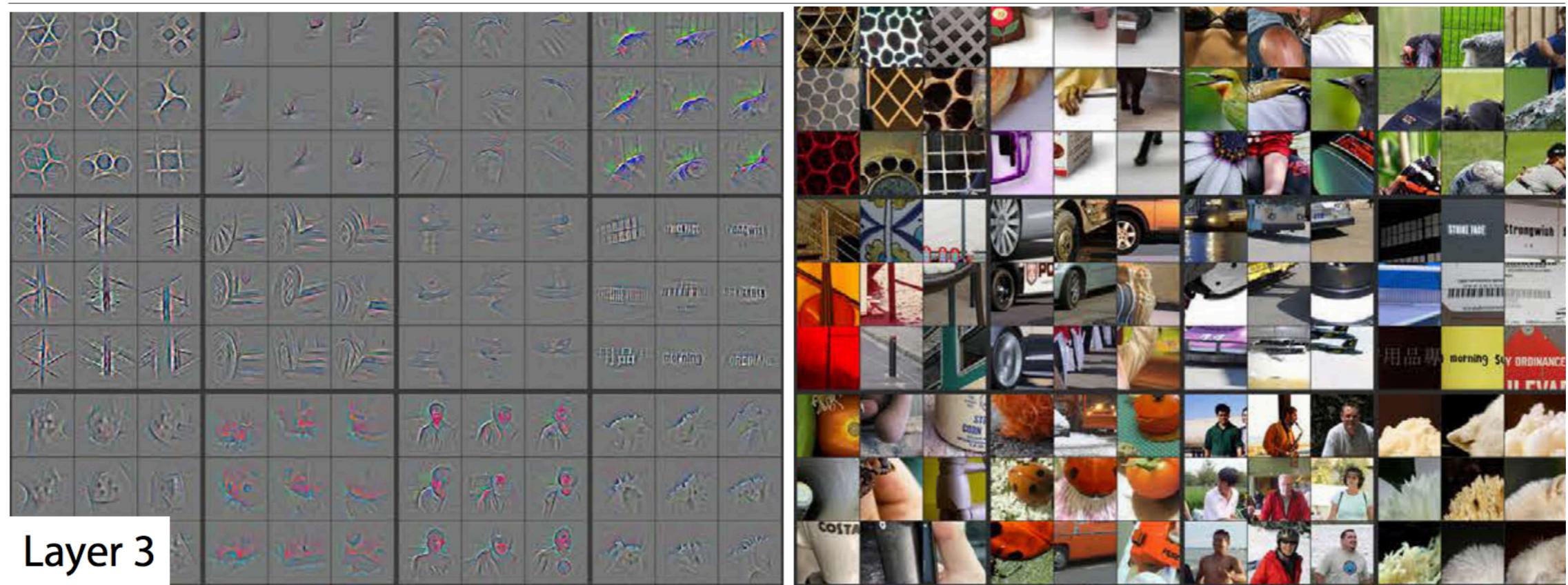
Train on limited data

Transfer Learning



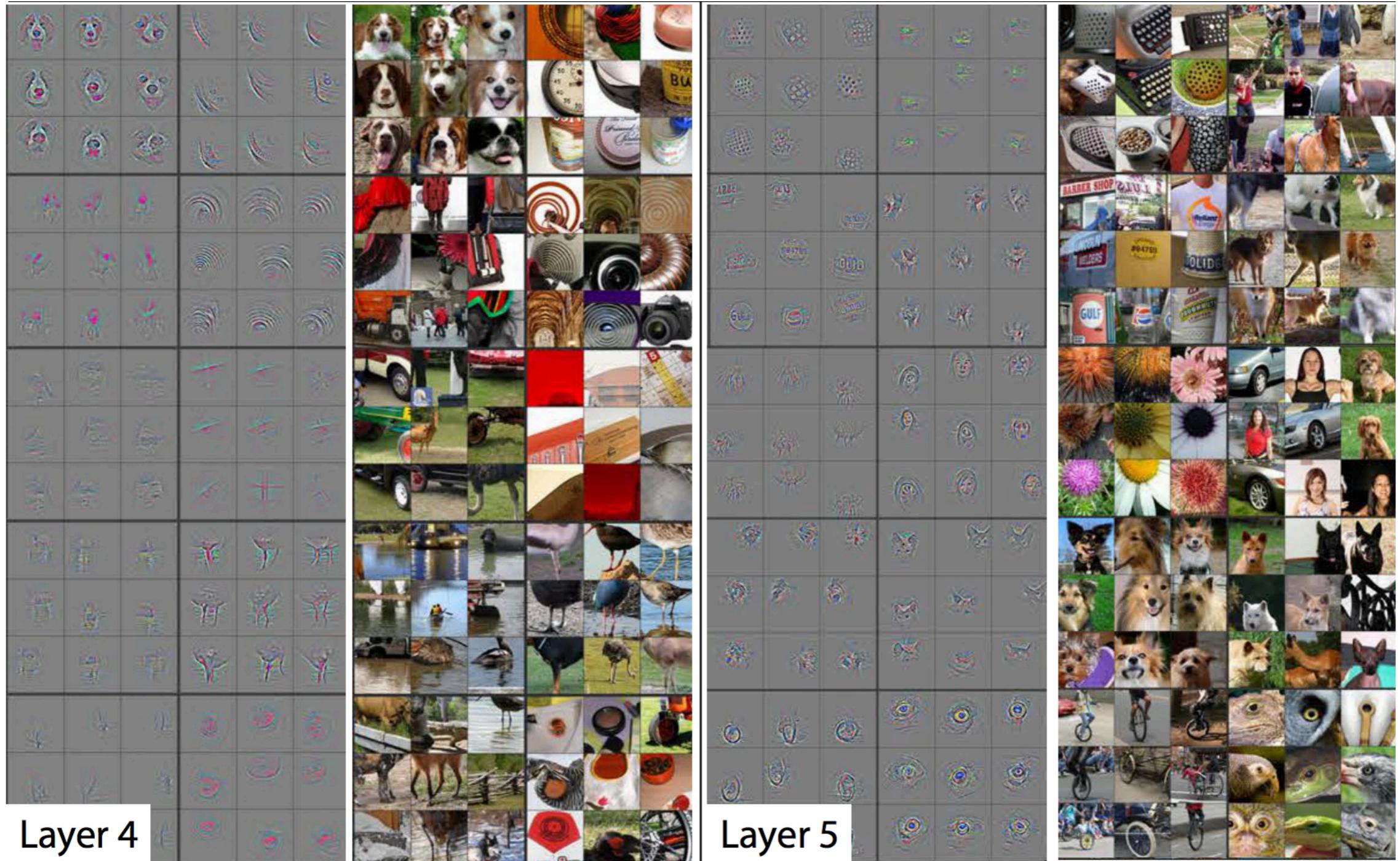
Low-level features: corners, edges, ...

Transfer Learning



Low-level features: mid-level features

Transfer Learning



Higher-level features: object parts & objects

[Zeiler & Fergus, Visualizing and Understanding Convolutional Networks, ECCV 2014]

Lessons Learned

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 - Layers: Fully connected, convolutional, activation functions, max pooling
 - Backpropagation
 - Handling overfitting

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