

# Applied Signal Processing

## Lecture 2

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- Finalize continuous time signals and systems
- Discrete time signals and systems
- Sampling

- On Thursday 11:30-12:30 Pick up DPS-kit
  - Bring signed agreement
- Sign up for project groups (4 students per group)
- Sign up for tutorial group

Assume  $x(t) = e^{j\omega_0 t}$ , the system output is

$$\begin{aligned}y(t) &= \int_{-\infty}^{\infty} h(\tau)x(t-\tau) d\tau \\&= \int_{-\infty}^{\infty} h(\tau)e^{j\omega_0(t-\tau)} d\tau \\&= \int_{-\infty}^{\infty} h(\tau)e^{-j\omega_0\tau} d\tau e^{j\omega_0 t} = H(\omega_0)e^{j\omega_0 t}\end{aligned}$$

We can define

Amplitude function:  $A(\omega) \triangleq |H(\omega)|$

Phase function:  $\phi(\omega) \triangleq \angle H(\omega)$

which gives

$$y(t) = A(\omega_0)e^{j(\omega_0 t + \phi(\omega_0))}$$

Assume  $x(t) = e^{j\omega_0 t}$ , then  $X(\omega) = \text{FT}[x(t)] = 2\pi\delta(\omega - \omega_0)$  and the system output is

$$\begin{aligned} Y(\omega) &= H(\omega)X(\omega) = H(\omega)2\pi\delta(\omega - \omega_0) \quad \Rightarrow \\ y(t) &= \text{FT}^{-1}[Y(\omega)] = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(\omega)2\pi\delta(\omega - \omega_0)e^{j\omega t} d\omega = \\ &= H(\omega_0)e^{j\omega_0 t} \end{aligned}$$

which gives

$$y(t) = A(\omega_0)e^{j(\omega_0 t + \phi(\omega_0))}$$

# Discrete time signals and systems

A discrete time (DT) signal is an collection of values  $x(n)$  where  $n = 0, \pm 1, \pm 2, \dots$  is the sample index.

Often (but not necessary)  $x(n)$  is the result of sampling a continuous time (CT) signal  $x_c(t)$

$$x(n) \triangleq x_c(n\Delta t), \quad n = 0, \pm 1, \pm 2, \dots$$

where  $\Delta t$  is the sampling period.

|                     |   |          |
|---------------------|---|----------|
| sampling period     | $\Delta t$                                  | [s]      |
| sampling frequency: | $f_s \triangleq \frac{1}{\Delta t}$         | [Hz=1/s] |
| sampling frequency: | $\omega_s \triangleq \frac{2\pi}{\Delta t}$ | [rad/s]  |
| Nyquist frequency:  | $\frac{f_s}{2}$                             | [Hz]     |

Dimensionless normalized frequencies  $f/f_s$  (or  $\omega/\omega_s$ ).

# Discrete Time Fourier Transform (DTFT)

The DTFT is

$$X(\omega) = \text{DTFT}[x(n)] \triangleq \sum_{n=-\infty}^{\infty} x(n)e^{-j\omega n\Delta t}$$

$\omega$  has unit radians per second.

For integer  $k$  we note that  $X(\omega + k\omega_s) = X(\omega)$  since  $e^{jkn\omega_s\Delta t} = e^{jkn2\pi} = 1$ , hence DTFT is a periodic function.

The Inverse DTFT is

$$x(n) = \text{DTFT}^{-1}[X(\omega)] = \frac{1}{\omega_s} \int_0^{\omega_s} X(\omega)e^{j\omega n\Delta t} d\omega$$

For DT signals convolution (filtering) is defined as

$$y(n) \triangleq \sum_{k=-\infty}^{\infty} h(k)x(n-k) = \sum_{k=-\infty}^{\infty} x(k)h(n-k)$$

The DTFT of  $y(n)$  is simply

$$Y(\omega) = H(\omega)X(\omega)$$

*Proof:* Since  $H(\omega) = \sum_{k=-\infty}^{\infty} h(k)e^{-j\omega k\Delta t}$  we have

$$\begin{aligned} y(n) &= \frac{1}{\omega_s} \int_0^{\omega_s} \sum_{k=-\infty}^{\infty} h(k)e^{-j\omega k\Delta t} X(\omega) e^{j\omega n\Delta t} d\omega = \\ &= \sum_{k=-\infty}^{\infty} h(k) \frac{1}{\omega_s} \int_0^{\omega_s} X(\omega) e^{j\omega(n-k)\Delta t} d\omega = \\ &= \sum_{k=-\infty}^{\infty} h(k)x(n-k) \end{aligned}$$



# DTFT transform pairs

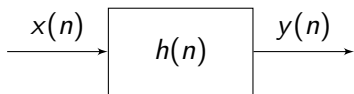
|                 | Time dom.                                | Fourier dom.  |
|-----------------|--|---|
| Delay           | $x(n - k)$                               | $e^{-j\Delta t \omega k} X(\omega)$   |
| Modulation      | $e^{j\omega_0 \Delta t n} x(n)$          | $X(\omega - \omega_0)$  |
| Constant        | 1  | $\omega_s \tilde{\delta}(\omega)$   |
| Kronecker delta | $\delta_n$                               | 1   |
| Conv.           | $\sum_{k=-\infty}^{\infty} h(k)x(n - k)$ | $H(\omega)X(\omega)$  |
| Freq. conv.     | $x(n)w(n)$                               | $\frac{1}{\omega_s} \int_0^{\omega_s} X(\lambda)W(\omega - \lambda) d\lambda$ |

where  $\tilde{\delta}(\omega) \triangleq \sum_{k=-\infty}^{\infty} \delta(\omega + k\omega_s)$

The Kronecker delta function (DT delta function) is

$$\delta_n \triangleq \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$$

DT Convolution is linear filtering



$x(n)$  - input,

$y(n)$  - output,

$h(n)$  - impulse response

$$y(n) = \sum_{k=-\infty}^{\infty} h(k)x(n-k)$$

$$\Leftrightarrow$$

$$Y(\omega) = H(\omega)X(\omega)$$

Causal system if  $h(n) = 0$  for  $n < 0$

Anti-causal if  $h(n) = 0$  for  $n > 0$

Non-causal otherwise

*Linear and Time Invariant (LTI):*

If inputs  $x_1(n)$  and  $x_2(n)$  yields outputs  $y_1(n)$  and  $y_2(n)$ ,

input  $\alpha x_1(n - n_1) + \beta x_2(n - n_2)$  yields output

$\alpha y_1(n - n_1) + \beta y_2(n - n_2)$

For DT signals with finite energy, Parseval's relation is

$$\sum_{n=-\infty}^{\infty} |x(n)|^2 = \frac{1}{\omega_s} \int_0^{\omega_s} |X(\omega)|^2 d\omega$$

Convenient to use the delay operator  $z^{-1}$  :

$$z^{-1}x(n) \triangleq x(n-1).$$

# Complex exponential input

Assume  $x(n) = e^{j\omega_0\Delta tn}$ , the system output is

$$\begin{aligned}y(n) &= \sum_{k=-\infty}^{\infty} h(k)x(n-k) \\&= \sum_{k=-\infty}^{\infty} h(k)e^{j\omega_0\Delta t(n-k)} \\&= \left( \sum_{k=-\infty}^{\infty} h(k)e^{-j\omega_0\Delta tk} \right) e^{j\omega_0\Delta tn} \\&= H(\omega_0)e^{j\omega_0\Delta tn}\end{aligned}$$

As before

Amplitude function:  $A(\omega) \triangleq |H(\omega)|$

Phase function:  $\phi(\omega) \triangleq \angle H(\omega)$

which gives

$$y(t) = A(\omega_0)e^{j(\omega_0 t + \phi(\omega_0))}$$

# A general difference equation

We can define the output as the following difference equation

$$y(n) \triangleq - \sum_{k=1}^{n_a} a_k y(n-k) + \sum_{k=0}^{n_b} b_k x(n-k)$$

Assuming stability (the recursion could make it unstable) take the DTFT of both sides

$$Y(\omega) = - \sum_{k=1}^{n_a} a_k e^{-j\omega\Delta tk} Y(\omega) + \sum_{k=0}^{n_b} b_k e^{-j\omega\Delta tk} X(\omega)$$

which imply

$$Y(\omega) = \frac{\sum_{k=0}^{n_b} b_k e^{-j\omega\Delta tk}}{1 + \sum_{k=1}^{n_a} a_k e^{-j\omega\Delta tk}} X(\omega) = H(\omega) X(\omega)$$



We aim to describe the following operations using the CT Fourier Transform:

- Sampling
- DT filtering
- Reconstruction

Need a CT signal model which can represent DT signals  $x_d$  and  $y_d$ .

The sampled DT signal is

$$x_d(n) = x(n\Delta t)$$

Consider the CT signal model of  $x_d(n)$ :

$$x_c(t) \triangleq \sum_{n=-\infty}^{\infty} \delta(t - n\Delta t)x(t) = \sum_{n=-\infty}^{\infty} \delta(t - n\Delta t)x_d(n)$$

The FT of this CT model signal is

$$\begin{aligned} X_c(\omega) &= \int_{-\infty}^{\infty} x_c(t) e^{-j\omega t} dt = \int_{-\infty}^{\infty} \sum_{n=-\infty}^{\infty} \delta(t - n\Delta t) x_d(n) e^{-j\omega t} dt \\ &= \dots = \sum_{n=-\infty}^{\infty} x_d(n) e^{-j\omega n\Delta t} \end{aligned}$$

which we recognize as the DTFT of  $x_d(n)$ . In summary we have the identity

### FT and DTFT relation

$$\begin{aligned} \text{FT}[x_c(t)] &= \text{DTFT}[x_d(n)] \\ X_c(\omega) &= X_d(\omega) \end{aligned}$$

To complete the picture we need to express  $X_c(\omega)$  (and thus also  $X_d(\omega)$ ) in terms of  $X(\omega)$ .



# FT and DTFT after Sampling

Start by expressing  $x(t)$  exactly at the sampling time instances using the inverse FT:

$$\begin{aligned}x_d(n) = x(n\Delta t) &= \int_{-\infty}^{\infty} X(\omega) e^{j\omega n\Delta t} \frac{d\omega}{2\pi} \\&= \sum_{k=-\infty}^{\infty} \int_{k\omega_s}^{(k+1)\omega_s} X(\omega) e^{j\omega n\Delta t} \frac{d\omega}{2\pi} \\&= [\text{Variable change: } \omega = \omega' + k\omega_s] \\&= \sum_{k=-\infty}^{\infty} \int_0^{\omega_s} X(\omega' + k\omega_s) e^{j(\omega' + k\omega_s)n\Delta t} \frac{d\omega'}{2\pi} \\&= \frac{1}{\omega_s} \int_0^{\omega_s} \underbrace{\frac{1}{\Delta t} \sum_{k=-\infty}^{\infty} X(\omega' + k\omega_s) e^{j\omega' n\Delta t}}_{X_d(\omega')} d\omega'\end{aligned}$$

last expression is the inverse DTFT of the signal  $x_d(n)$ .

We have shown

FT and DTFT after sampling

$$X_d(\omega) = X_c(\omega) = \frac{1}{\Delta t} \sum_{k=-\infty}^{\infty} X(\omega + k\omega_s)$$