



Digital Agriculture (with drones)

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Digital Agriculture (background)

- Digital agriculture (smart farming, e-agriculture) is the use of technologies to collect, store, analyse, and share data and information for agricultural purposes.
 - Precision agriculture, IoT, Artificial intelligence (AI), Robotics
- Mobile phenotyping is the use of mobile devices to collect and analyse data related to the physical characteristics of plants, animals – all things agriculture)
- Australian Plant Phenomics Network (APPN); DPIRD is the WA-node
 - High-resolution aerial/ground imagery for precise analyses
 - Real-time data capture for time-sensitive research
 - Data packages from pipelines using advanced analytics





My background (with Pivotel)

- Digital Agriculture Collaboration (2017-2021)
 - MOU with MU, DPIRD, others
 - 8 x PhD project/scholarships (two: livestream thermal for frost; IoT sensors)
- Katanning smart-farm (2021 2024)
 - LTE/4G network across farm; 2 towers; Starlink backhaul
- APPN/WA-node "mobile phenotyping" project (2024-2026)
 - Livestreaming drone imagery via Pivotel "Starlink-wifi-hub"

Data/images captured from these platforms produce GIS layers that are integrated with field-data enabling measurement of a range of otherwise difficult to measure traits related to plant performance

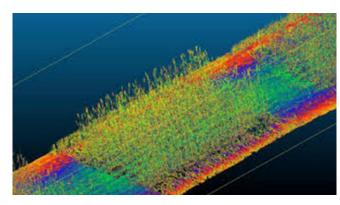


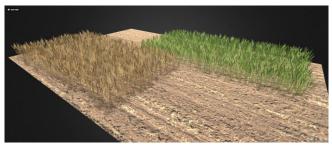
Our current projects (with Pivotel)

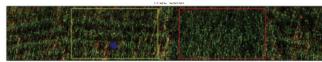
Projects

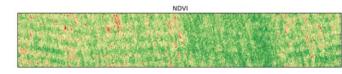
- 1: As part of a national pasture-nutrients project, we are looking at flying drones over trial sites to develop a calibration for identifying pasture species
- 2: This research (grants APPN-SIF, AEA-ignite?) seeks to stitch imagery into 3D incrementally as the drone flies over a site
- 3: This research uses UAVs to navigate obstacles and map the topography using RGB/Lidar
- 4: This research builds off earlier DPIRD/GRDC research that measures the impact of frost on wheat/chickpeas
- 5: This project utilises the digital-twin concept to monitor specific farm paddocks (or potentially whole farms) using routine UAV flights to monitor weed/crop health
- 6: This project is a collaboration similar to Project 5 but involves the environmental monitoring of a specific area
- 7: This project is a collaboration involving the facial recognition of sheep as they enter the shed.
- 8: This project involves specialised methane-capture trailers that are networked via an onfarm private network

Reference: "White Paper: Unleashing Digital Agriculture with Private LTE Networks, IoT, and Edge Computing", Pivotel, Mar-2024 [written by Dean...]











APPN "mobile phenotyping" project

Equipment

- Drones (DJI M300/M350, DJI M3M, DJI mini-4, Gryfn)
 - Imagery(Gryfn) = RGB (61 MP); hyperspectal (340 bands); LIDAR (128 ch; 5.2 Mpoints/sec))
 - Imagery(M3M) = RGB (20MP); multispectral (4x5MP;G/R/RE/NIR) [simultaneous; not overlapping)
 - Imagery(mini-4) = RGB (48MP)
- Robotics ...
 - Similar as drones (but with lights...use remotely/at-night?)
- Handheld (in field)
 - RGB, hyperspectral, thermal
- Mobile/ute-based Starlink-wifi hub
 - Portable (< 32kg); batteries (>4hours); Starlink backhaul; wifi6/7; edge-computer; secure router/hub; plugins for: power (charge drone-batteries), internet-port, and chargeable/solar-panels; geotagged hea tolerance/lockable container (with some room to store stuff)

Software

- Livestreaming via DJI-customised-wifi = <u>AVCRM</u>-connect/live
- Custom-build livestreaming = drone via wifi6+Pi-5 to starlink-wifi to cloudserver
 - Aim to provide more bandwidth from drone to Starlink-wifi-hub

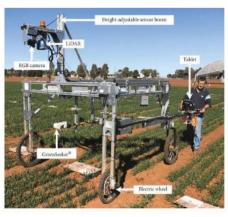




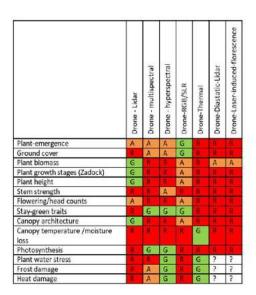


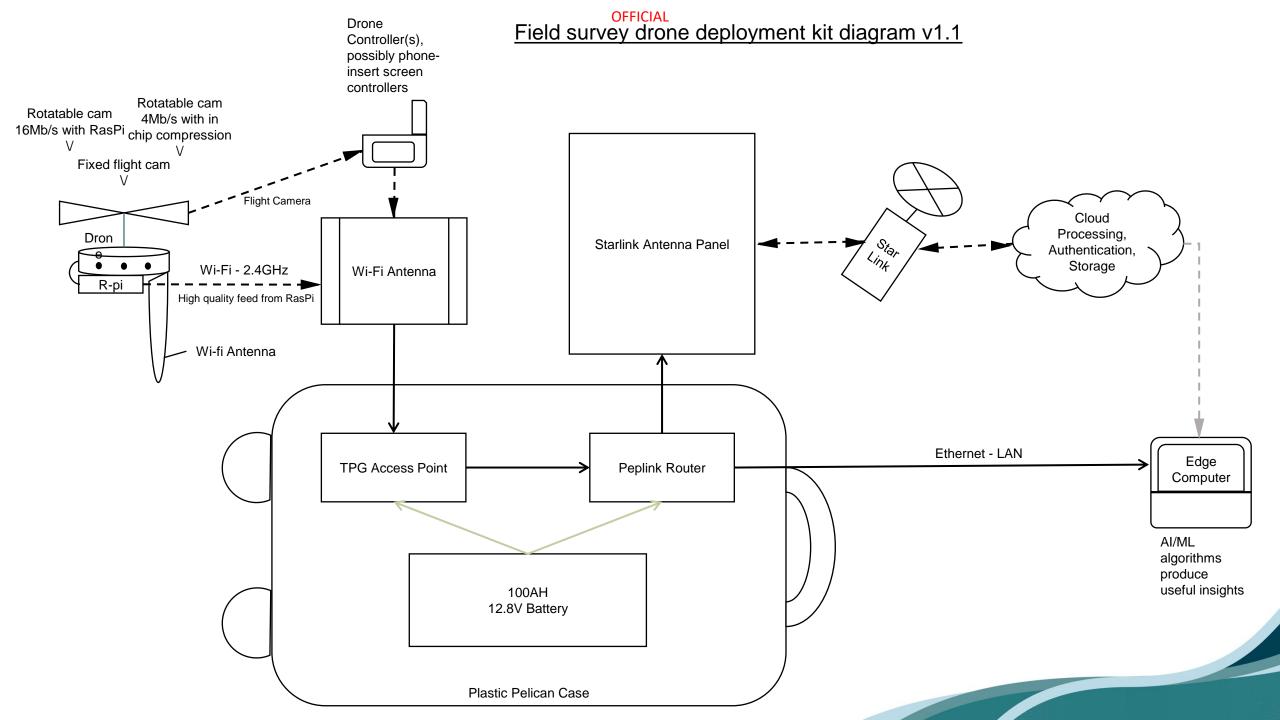






Deery et al. 2021





Data

- APPN delivers a service using mobile equipment to collect field-based data
- Locations: research trials (~500m x 200m); paddocks/vineyards (~1.5km x 1.5km); transects/environment (several paddocks)
- Data at different resolutions (eg <0.2mm/pixel; 1-2cm/pixel); Higher-res data takes longer to collection (ie drone flies closer to ground); more throughput via wifi
 - RGB(low) = 200Mb [10cm resolution by 12MP camera]
 - RGB(high) = 50GB [1 cm resolution over 0.5 hectare by 42MP camera]
 - LIDAR = 1TB [high resolution, medium altitude; 30min flight]
 - Hyperspectral = 100GB [100 bands x 1000x1000 pixel image]
 - Thermal = 1TB [30fps at 640x480 for 10 min flight]
 - RGB + thermal/multispectral = 1.1TB (2 x cameras per flight)

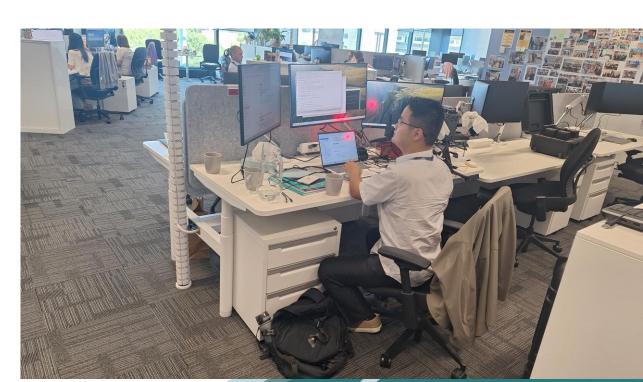




Live-streaming

- APPN/WA-node is about delivering a mobilephenotyping service, which includes datadesign/equipment, data-collection/analyses and data-packaging/reporting.
- Locations: research trials (~500m x 500m); paddocks/vineyards (~1.5km x 1.5km); transects/environment (several paddocks)
- Issues
 - Signal range/interference
 - Bandwidth
 - Battery life
 - Image quality/stability
 - Environmental (weather, terrain/obstacles)
 - Operational (planning, equipment, CASA regulations)





Thank you

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