

## ☆ Concurrent Container

struct concurrent container

void construct(int N)

int get(int index)

lock.acquire();

init mutex(&lock); resize(N);

// returns element by its index.

if (index < 0 || index > size) ( return -INT MAX; int result = data[index]; lock.release(); return result;

// sets element value by its index.

if (index < 0 || index > size) {

void set(int index, int value)

lock.acquire();

return;

void resize(int N) lock.acquire();

size = N;

void destroy()

free (data); data = NULL;

size = 0;

mutex lock; int size: int \* data;

Pick the correct choices

The implementation can cause a deadlock.

The implementation can cause a resource leak.

destroy\_mutex(&lock);

data[index] = value; lock.release();

data = (int \*)malloc(size);

for (int i = 0; i < size; ++i) data[i] = 0; lock.release();

{

Consider the following implementation of a container that will be used in a concurrent environment. The container is supposed to be used like an indexed array, but provide thread-safe access to elements.

// assume it's called for any new instance once before it's ever used

// extend maximum capacity of the container so we can add more elements

 $\ensuremath{//}$  Ensure we store 0 for elements that have never been set

// Assume nobody (except the member methods) is ever going to access these fields directly

Which of the following problems do you think are present in the implementation? You may select multiple options.

// assume it's only called once when the container object is destroyed and no one is going to use it anymore

```
3
```



```
7
```

```
≣
0
```





6 7

≣ 8









```
7
```











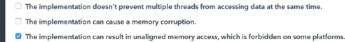


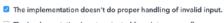












 $\hfill \square$  The implementation is not protected from integer overflow errors.

 $\hfill \square$  The implementation is actually correct and thread-safe. Clear selection

## ☆ Cat Pictures Backup

Complete the blanks in the following question with the appropriate answer.

Luke has just bought 7 disk drives and grouped them together into a single logical drive so he could back up all funny cat pictures from the internet. Luke's drive usage can be described as a sustained workload of 200,000 write operations per second with following distribution:

- 512 bytes 20% of all operations
- 1024 bytes 30% of all operations 4096 bytes 40% of all operations
- 16384 bytes 10% of all operations

Each write operation appends sequentially to an individual drive, and the load is evenly distributed among all drives. There is no compression, garbage collection, or redundancy elimination involved.

Assuming each drive has a capacity of exactly 513 GiB (1 GiB = 1024 MiB, 1 MiB = 1024 KiB, 1 KiB = 1024 bytes), how soon will Luke's array be filled from completely empty to 86% (at that point, Luke should probably consider buying few more disks)? Please round the answer to minutes.

Answer: 75 minutes

5

7 ∷

0

1

2

3

6

7

▦

0

1

6

## ☆ DFS in Binary Tree

Complete the blanks in the following question with the appropriate answer.

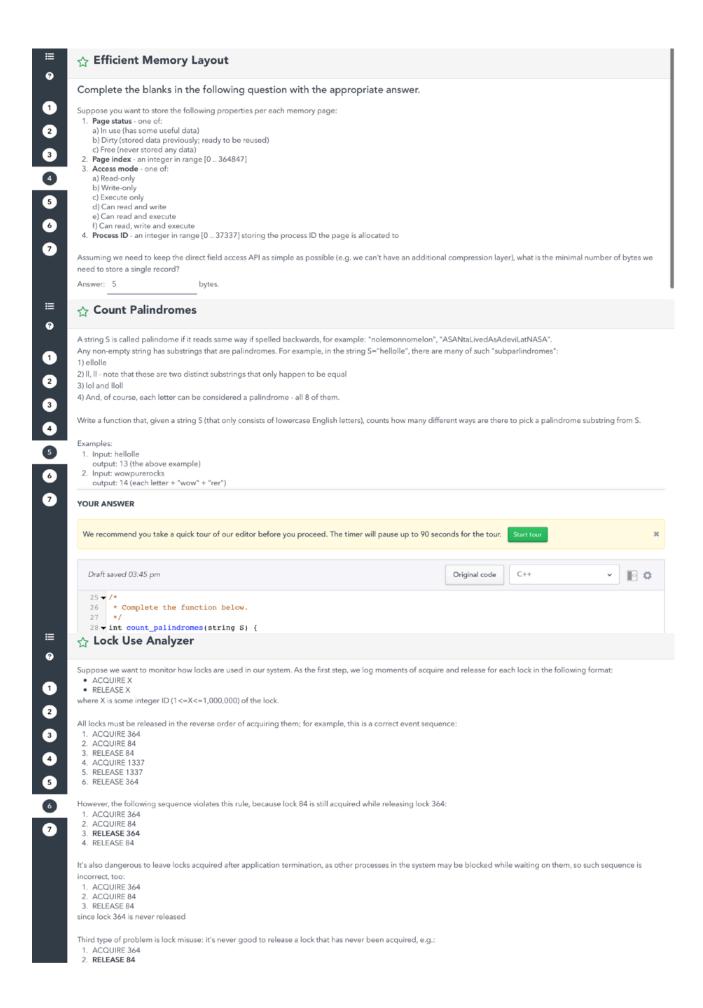
Jim wrote the following program to perform a depth-first search (DFS) in a binary tree;

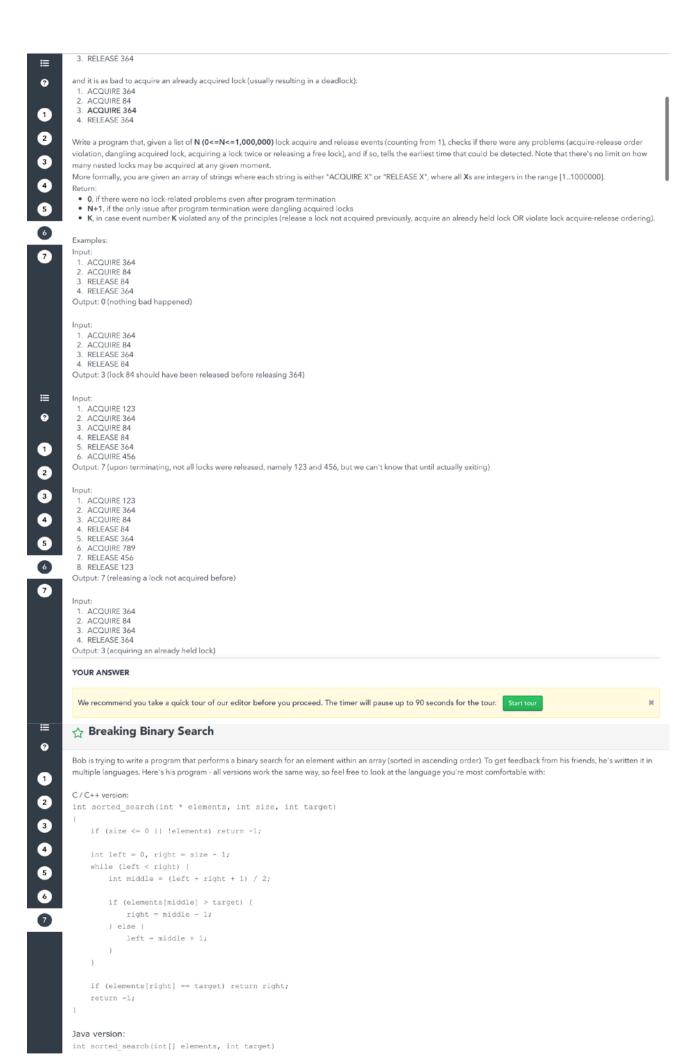
```
struct Node
   int value;
   Node * parent;
   Node * left_child;
   Node * right_child;
   bool visited;
1:
Node * dfs(Node * node, int target)
   printf("%d ", node->value);
   node->visited = true;
   if (node->value == target) {
       return node;
   Node * nodes[3] = {node->right_child,
                      node->parent,
                      node->left_child};
   for (int i = 0; i < 3; ++i) {
       if (nodes[i] && !nodes[i]->visited) {
           Node * result = dfs(nodes[i], target);
           if (result) {
               return result;
```

return NULL;

≡ 0

```
root
               right_child
```





```
if (elements == null || elements.length <= 0) return -1;
0
             int left = 0, right = elements.length - 1;
             while (left < right) (
1
                 int middle = (left + right + 1) / 2;
2
                  if (elements[middle] > target) {
                      right = middle - 1;
3
                  } else {
                      left = middle + 1;
             }
             if (elements[right] == target) return right;
             return -1;
7
        Python version:
        def sorted_search(elements, target):
             if not elements or len(elements) <= 0:
                  return -1
             left = 0
             right = len(elements) - 1
             while left < right:
                 middle = (left + right + 1) / 2
≣
                  if elements[middle] > target:
                     right = middle - 1
8
                  else:
                       left = middle + 1
1
             if elements[right] == target:
2
                 return right
             return -1
3
4
         Is Bob's program correct? If not, what valid input will lead to an incorrect result?
         Write a program that either:
          1. prints "CORRECT" (without quotes) if Bob's binary search implementation is correct.
5
            prints a sorted array and a target number that makes Bob's implementation return the wrong result. In this case, your program should output exactly 3 lines:
             a) first line should contain the number of elements in the input array
b) second line should contain space-delimited elements of the input array
             c) third line should contain the target number.
          We recommend you take a quick tour of our editor before you proceed. The timer will pause up to 90 seconds for the tour. Start tour
                                                                                                                                                     v 📗 🜣
                                                                                                           Original code
                                                                                                                            C++
             1 		 #include <cmath>
             2 #include <cstdio>
             3 #include <vector>
              #include <iostream>
```