

Modeling and Computation in the Space of Language: Symbolic and LLM-Based Approaches

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**Statistical and Computational Challenges in Probabilistic Scientific Machine
Learning (SciML)**

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Overview

01

Introduction

Modeling & Computing in the space of Language

02 Finite expression method (FEX)

Concept & theory & formulation

03

Auto-Computing via LLM

Scientific assistant: modeling, planning, coding, computing

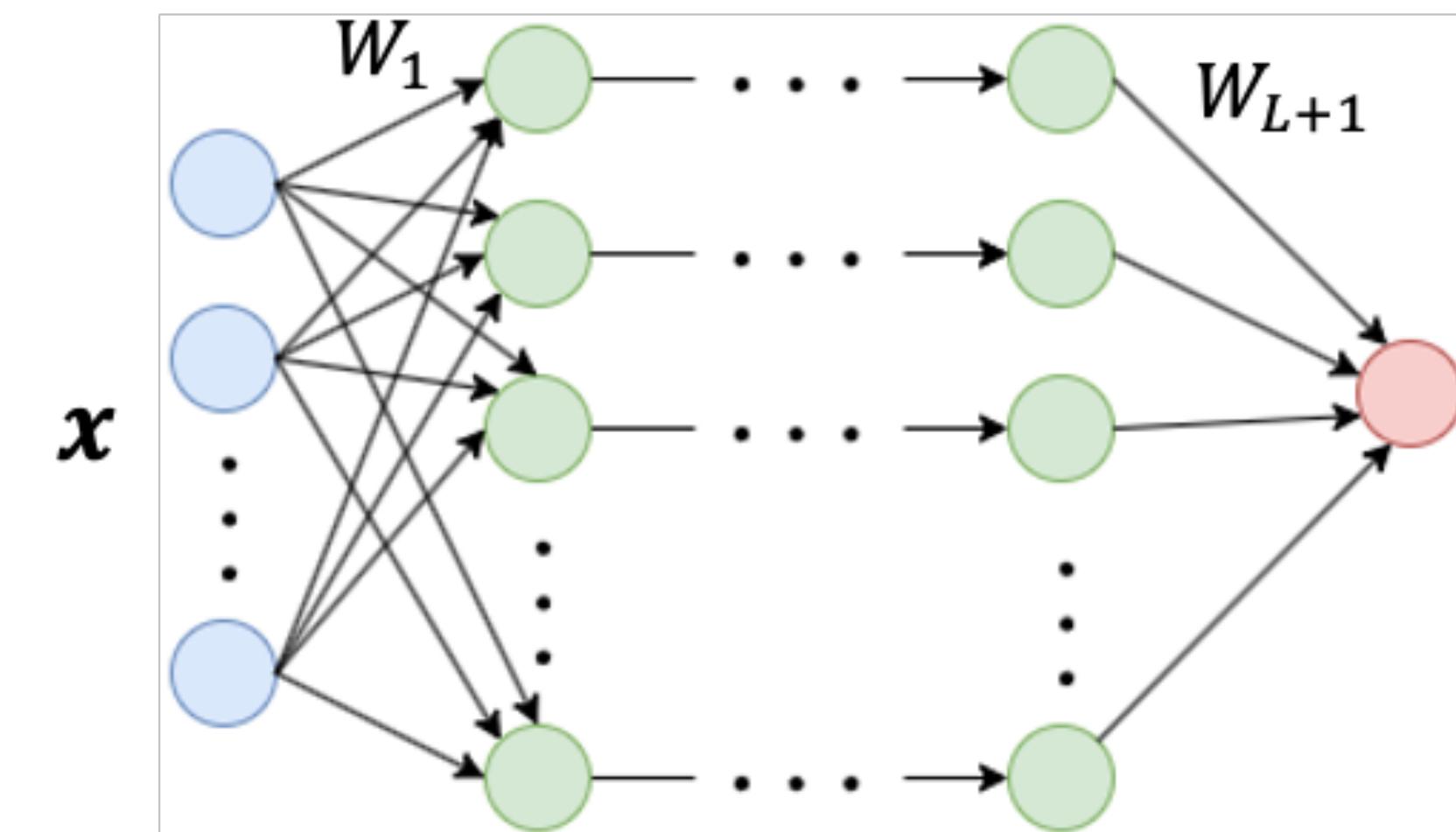
04 Summary and future

Efficiency & future vision

Neural network (NN) and its advantages

Neural network

- Fully-connected neural network:
 $\phi(\mathbf{x}; \theta) = W_{L+1} h_L \circ \dots \circ h_1(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^d$
- Hidden layer: $h_\ell(\mathbf{x}) = \sigma(W_\ell \mathbf{x} + b_\ell)$
- The σ is a nonlinear activation
- Parameter set: $\theta = \{W_\ell\}_{\ell=1}^{L+1} \cup \{b_\ell\}_{\ell=1}^L$



Theory and applications

- NN approximation: curse of dimensionality debate (Shen, Y., Zhang, JMLR 2022)
- NN optimization: gap between theory and practice (Na, Y., arXiv:2502.05360)
- Practical applications in high-dimensional problems

Two prototypes for differential equations (DEs)

NN \approx Target

Learn physical laws as descriptor

Dynamical system: $\frac{dx}{dt} = f(x), \quad x \in \mathbb{R}^d$

- Given historical data $\{x^t\}_{t=0}^T$ and learn a surrogate $\hat{f} \approx f$, e.g., NN $f(x; \theta) \approx f(x)$.
- Training:** $\min_{\theta} \frac{1}{T} \sum_{t=1}^T \|x^t - \hat{x}^t\|^2$, with $\hat{x}^t = \text{Integrator}(f(\cdot; \theta), x^{t-1}, \Delta t)$.
- Prediction:** $x^t = \text{Integrator}(f(\cdot; \theta^*), x^{t-1}, \Delta t), t > T$.

Solve PDE as parametrization

Boundary value problem: $\begin{cases} \mathcal{D}u(x) = f(x), x \in \Omega \subset \mathbb{R}^d \\ \mathcal{B}u(x) = g(x), x \in \partial\Omega \end{cases}$

- Approximate the PDE solution with NN, e.g., $u(x; \theta) \approx u(x)$.
- Training:** $\min_{\theta} \left\| \mathcal{D}u(x; \theta) - f(x) \right\|_{L^2(\Omega)}^2 + \left\| \mathcal{B}u(x; \theta) - g(x) \right\|_{L^2(\partial\Omega)}^2$.
- Differential operator \leftarrow auto-differentiation/finite difference.
- Integral \leftarrow Monte Carlo integration.

NN Limitations

- Limited accuracy for engineering applications: $O(10^{-2})$ to $O(10^{-4})$
- Expert knowledge needed/Try-and-error for good architecture
- Poor data efficiency
- Lack of interpretability

Is there an alternative to neural network-based methods that offers



High accuracy

**Less data
needed**



Interpretability

**Less reliance
on expert**

Modeling & Computing in the Right Space

- Sparse Grids

- “Right Space” - the solution can be approximated well by sparse combinations of basis functions

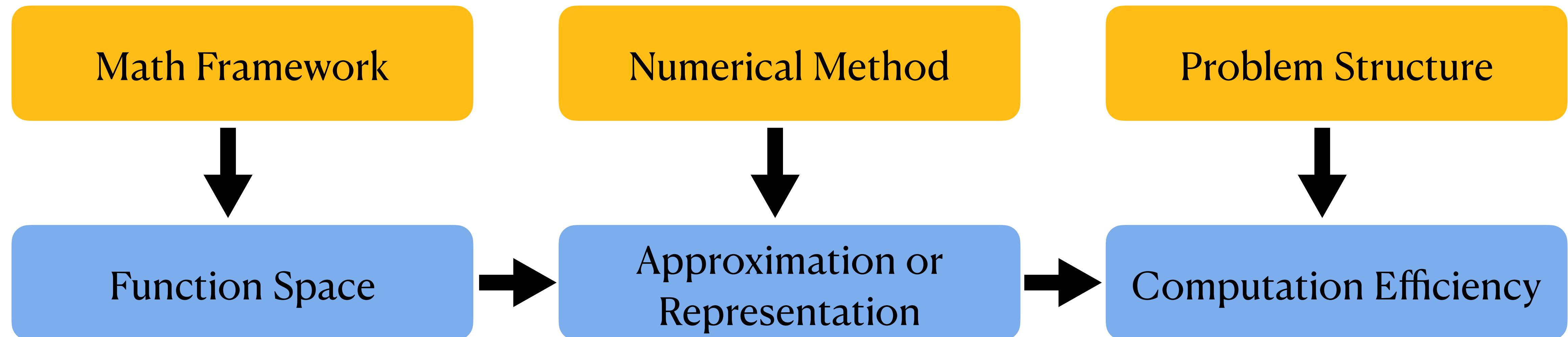
- Low-Rank Tensor Methods

- “Right Space” - the solution can be approximated by a sum of products of lower-dimensional functions

- Neural Network Methods

- “Right Space” - the implicit function space learned by the network during training

Modeling & Computing in the Right Space



- Our research is a big search (optimization) process
- Our “search” is in a space of natural language
- Our “optimization” is mixed-integer programming and gradient-free

Modeling & Computing in the Space of Natural Language

New Paradigm for New Investigation, Method, and Application

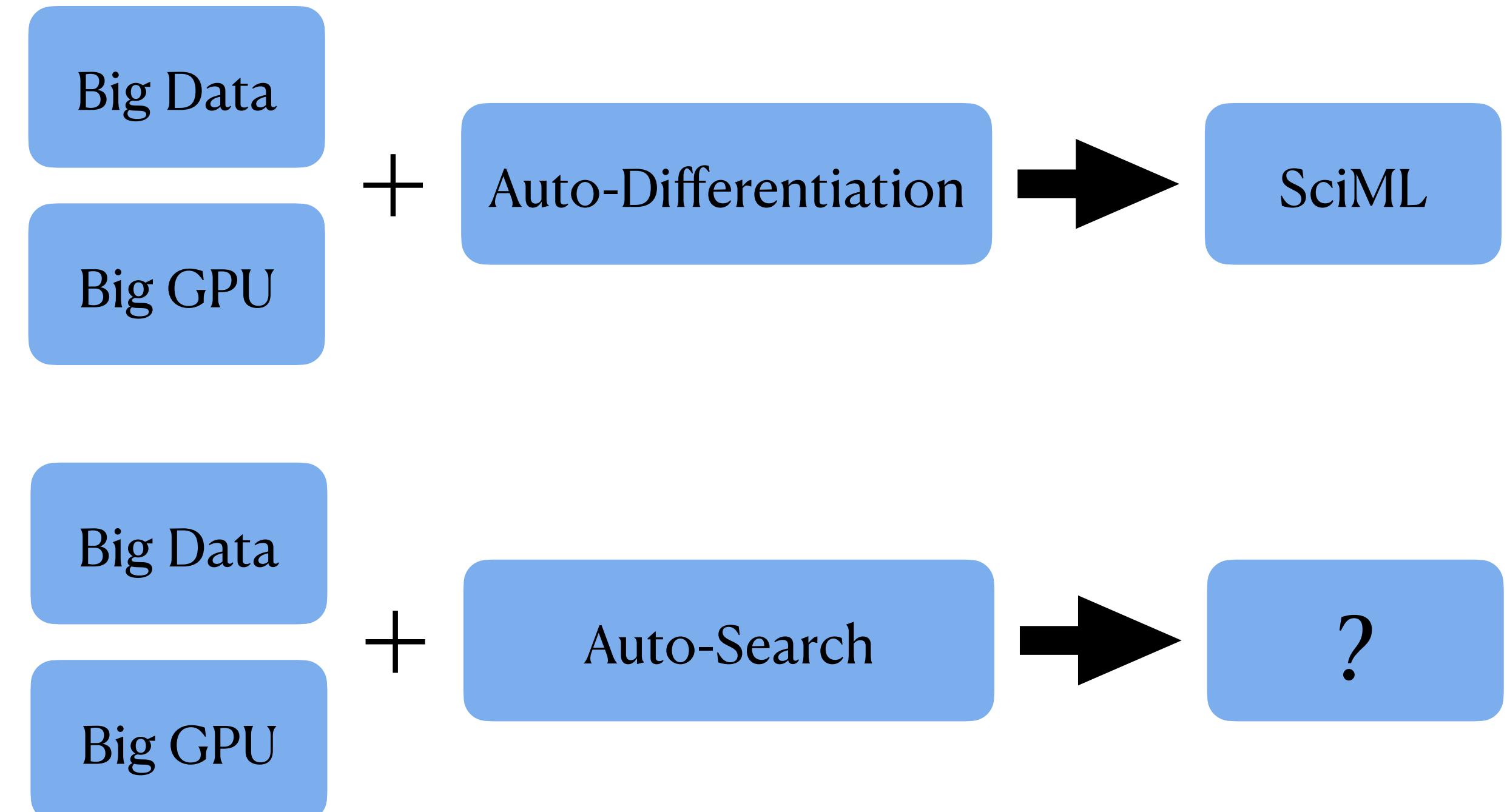
Two Complementary Approaches:

- Symbolic learning (Finite Expression Method)
- Large language model (LLM)

Applications:

- Search for a solution
- Search for a mathematical model
- Search for a computational algorithm
- Search for executable code
- ...

Our vision:



Two Complementary Approaches:

- **Symbolic learning (Finite Expression Method)**
- Large language model (LLM) for modeling and computing assistant

Finite Expression Method (FEX) Methodology

Liang and Y. [arXiv:2206.10121](https://arxiv.org/abs/2206.10121)

Motivating Problem:

- A **structured** high-dimensional Poisson equation

$$-\Delta u = f \quad \text{for } x \in \Omega, \quad u = g \text{ for } x \in \partial\Omega$$

with a solution $u(x) = \frac{1}{2} \sum_{i=1}^d x_i^2$ of low complexity $O(d)$, i.e., $O(d)$ operators in this expression

Idea:

- Find an explicit expression that approximates the solution of a PDE
- Function space with finite expressions
 - **Mathematical expressions:** a combination of symbols with rules to form a valid function, e.g., $\sin(2x) + 5$
 - **k -finite expression:** a mathematical expression with at most k operators
 - Function space in FEX: \mathbb{S}_k as the set of s -finite expressions with $s \leq k$

Finite Expression Method (FEX) Theory

Liang and Y. [arXiv:2206.10121](https://arxiv.org/abs/2206.10121)

Advantages in Real Analysis: “No” curse of dimensionality in approximation

Theorem (Liang and Y. 2022) Suppose the function space is \mathbb{S}_k generated with operators including ``+”, ``-”, `` \times ”, `` $/$ ”, `` $\max\{0,x\}$ ”, `` $\sin(x)$ ”, and `` 2^x ”. Let $p \in [1, +\infty)$. For any f in the Holder function class $\mathcal{H}_\mu^\alpha([0,1]^d)$ and $\varepsilon > 0$, there exists a k-finite expression ϕ in \mathbb{S}_k such that

$$\|f - \phi\|_{L^p} \leq \varepsilon,$$

if

$$k \geq \mathcal{O}(d^2(\log d + \log \frac{1}{\varepsilon})^2).$$

Finite Expression Method (FEX) Practice

Advantages in Practice:

- Leverage the power of descriptive structures of problems

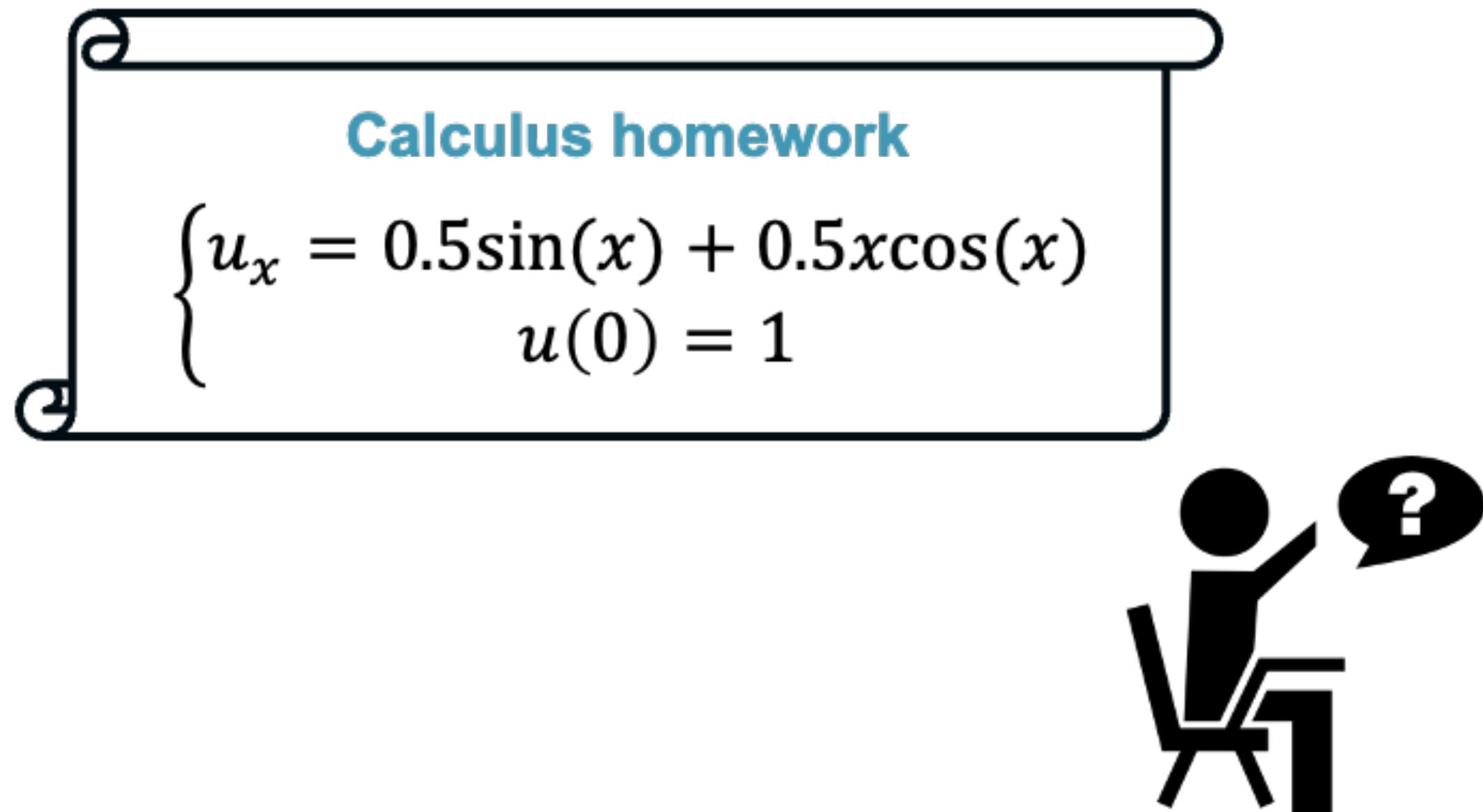
Question:

- How to do computation with description?

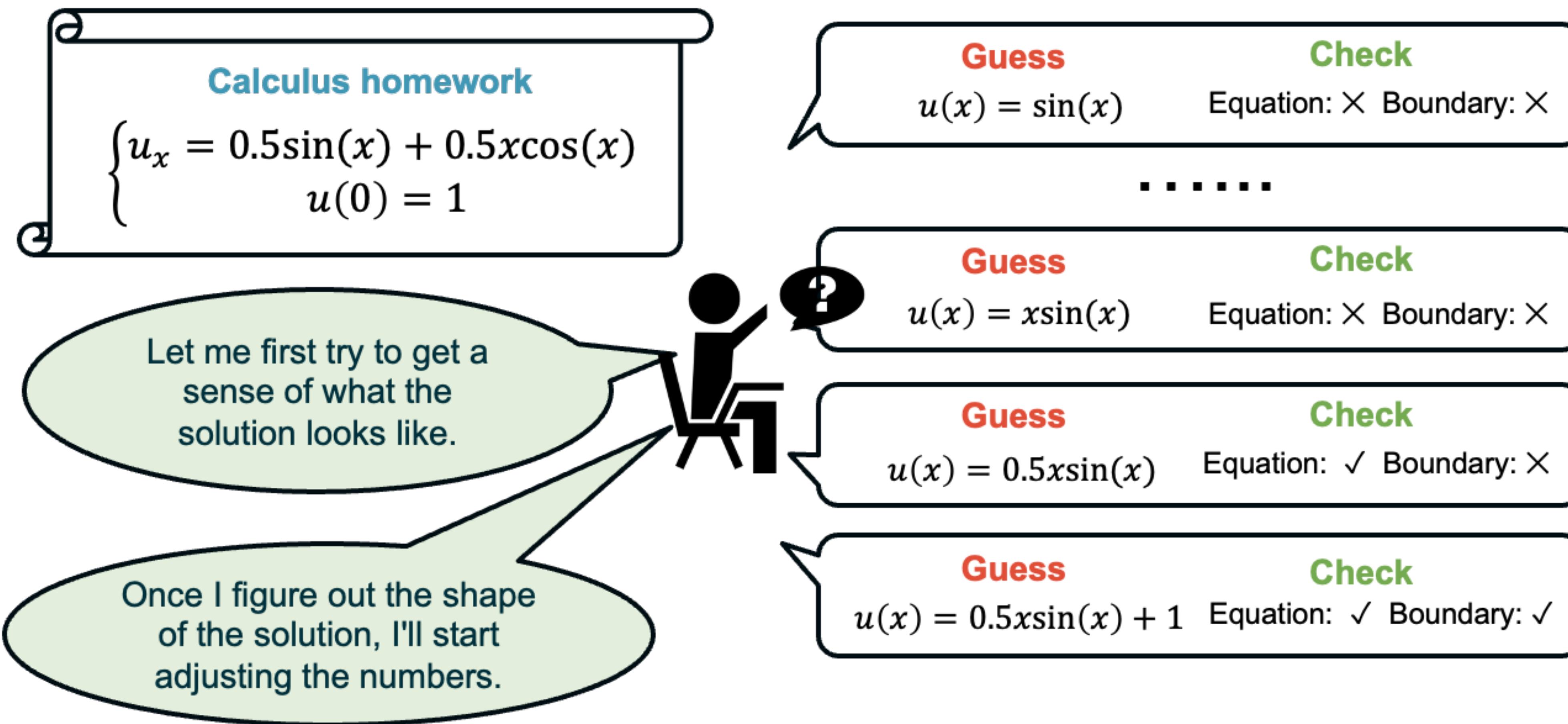
Answers:

- **Symbolic machine learning**
- Large language models
- Bayesian perspective

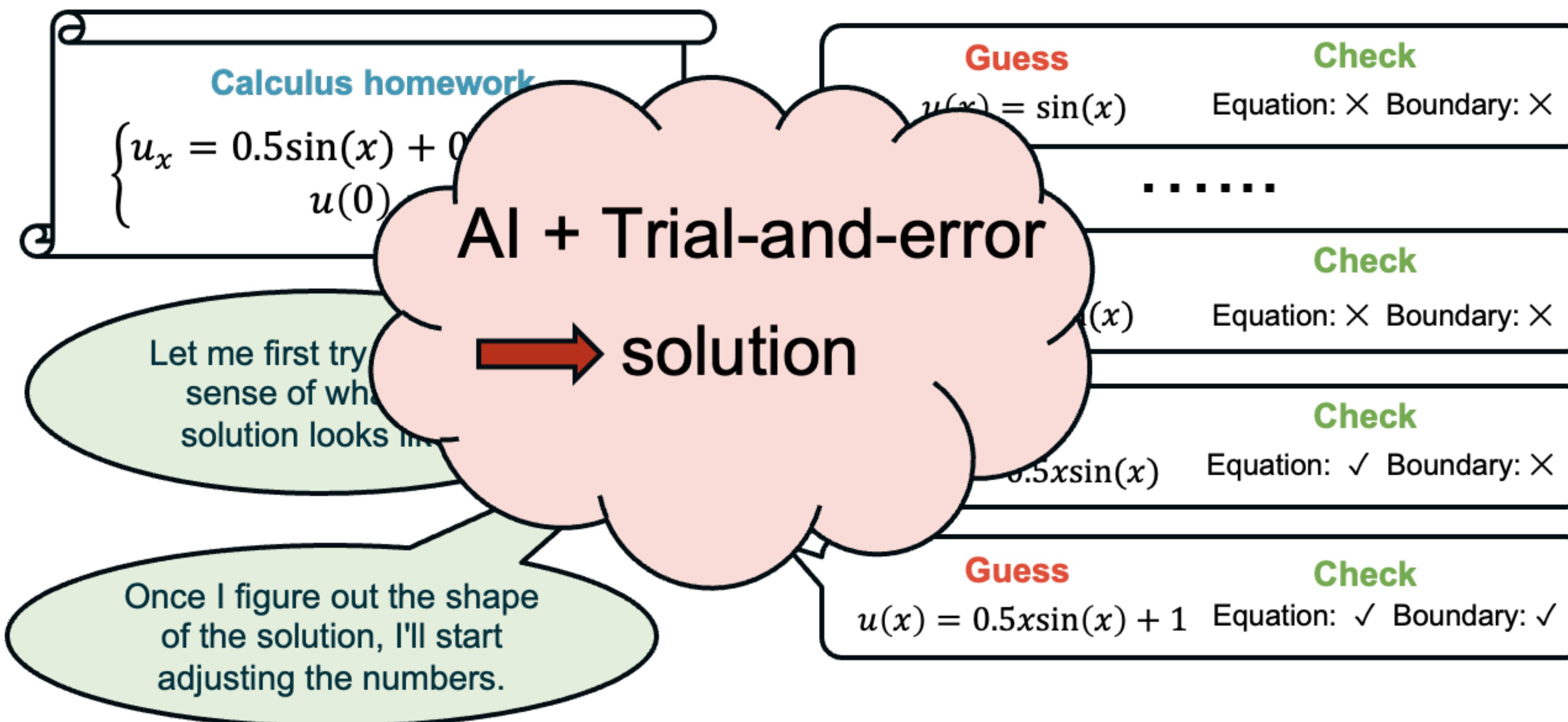
Ideas: Automatic Trial-and-Error for Structures and Refinement



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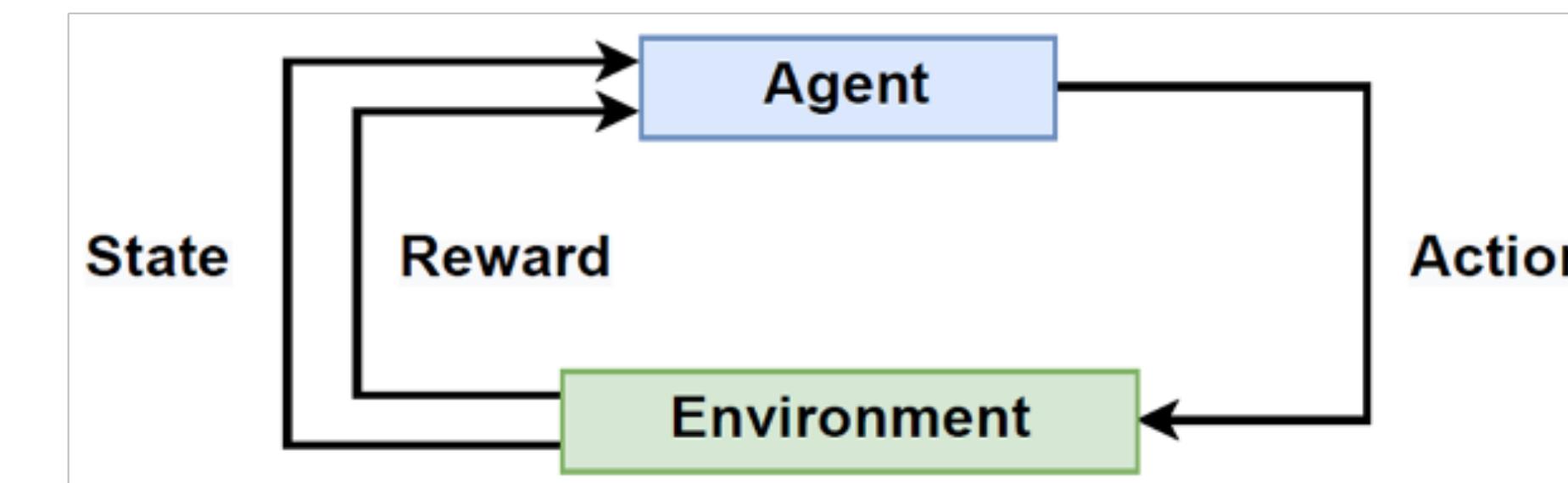
Ideas: Automatic Trial-and-Error for Structures and Refinement



Reinforcement Learning (RL)



- Reinforcement learning: train AI agent to make decision



Playing video games (source: CLVR lab @ USC)

- Objective is to learn $\pi : \max_{\pi} \mathbb{E}_{\tau \sim \pi} R(\tau)$
 π is a policy, τ is an episode, $R(\tau)$ is cumulative reward
- Methods: Policy gradient, etc.

Finite Expression Method for Solving PDEs

Liang and Y. [arXiv:2206.10121](https://arxiv.org/abs/2206.10121)

Least square based FEX

- e.g., $\mathcal{D}(u) = f$ in Ω and $\mathcal{B}(u) = g$ on $\partial\Omega$
- A mathematical expression u^* to approximate the PDE solution via

$$u^* = \arg \min_{u \in \mathbb{S}_k} \mathcal{L}(u) := \arg \min_{u \in \mathbb{S}_k} \|\mathcal{D}u - f\|_2^2 + \lambda \|\mathcal{B}u - g\|_2^2$$

- Or numerically

$$u^* = \arg \min_{u \in \mathbb{S}_k} \mathcal{L}(u) := \arg \min_{u \in \mathbb{S}_k} \frac{1}{n} \sum_{i=1}^n |\mathcal{D}u(x_i) - f(x_i)|^2 + \lambda \frac{1}{m} \sum_{j=1}^m |\mathcal{B}u(x_j) - g(x_j)|^2$$

- Question: how to solve this combinatorial optimization problem? Reinforcement learning

Numerical Comparison

Liang and Y. [arXiv:2206.10121](https://arxiv.org/abs/2206.10121)

- NN method:

- Neural networks with a ReLU^2 -activation function
- ResNet with depth 7 and width 50

- FEX method:

- Depth 3 binary tree
- Binary set $\mathbb{B} = \{ +, -, \times \}$
- Unary set $\mathbb{U} = \{0, 1, \text{Id}, (\cdot)^2, (\cdot)^3, (\cdot)^4, \exp, \sin, \cos\}$

- The right space: solutions with simple descriptive structures

Solving High-Dimensional PDEs with FEX

Poisson equation

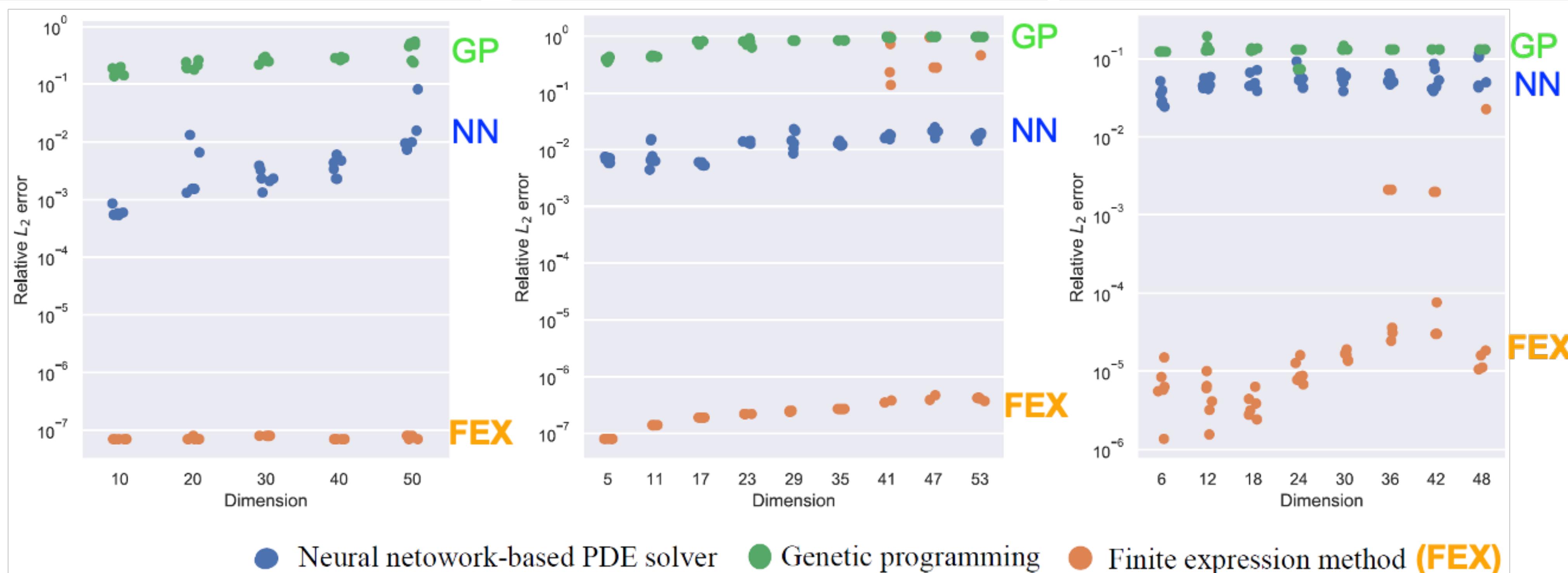
$\Omega = [0,1]^d$
 $-\Delta u = f$ for $x \in \Omega$ and $u = g$ on $\partial\Omega$
 True solution: $u(x) = \frac{1}{2}\sum_{i=1}^d x_i^2$

Linear conservation law

$T \times \Omega = [0,1] \times [-1,1]^d$
 $\frac{\pi d}{4} u_t - \sum_{i=1}^d u_{x_i} = 0$ and $u(0, x) = \sin\left(\frac{\pi}{4} \sum_{i=1}^d x_i\right)$
 True solution: $u(x) = \sin(t + \frac{\pi}{4} \sum_{i=1}^d x_i)$

Nonlinear Schrödinger equation

$\Omega = [-1,1]^d$
 $-\Delta u + u^3 + Vu = f$ for $x \in \Omega$
 True solution: $u(x) = \exp(\sum_{i=1}^d \cos(x_i)/d)$

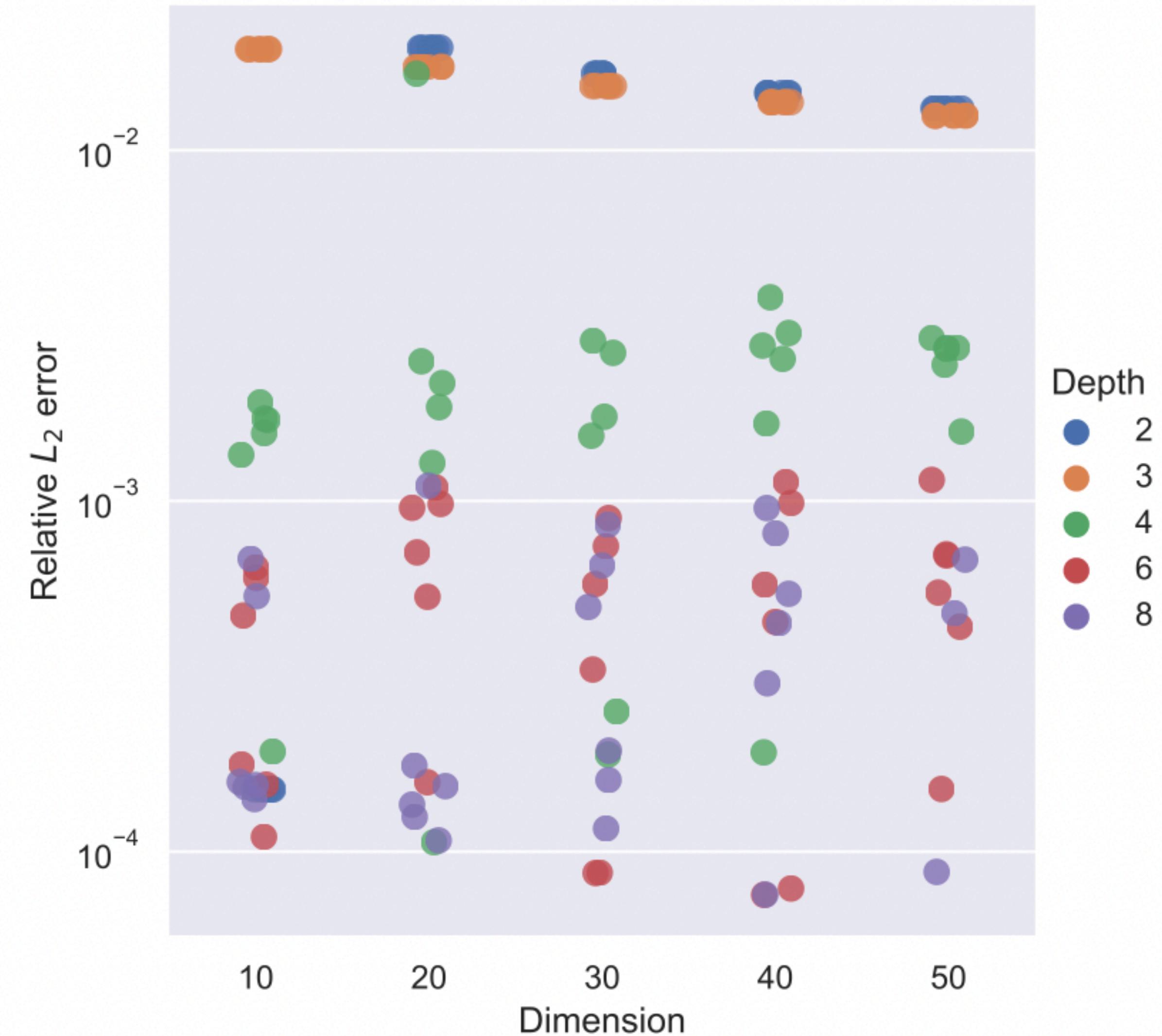


Poisson Equation

Liang and Y. arXiv:2206.10121

Convergence Test:

- True solution $u(x) = \frac{1}{2} \sum_{i=1}^d x_i^2$
- Binary set $\mathbb{B} = \{ +, -, \times \}$
- Unary set $\mathbb{U} = \{0, 1, \text{Id}, (\cdot)^3, (\cdot)^4, \exp, \sin, \cos\}$
- No expression tree to exactly represent $u(x)$



FEX for Partial Integral Differential Equations

Hardwick, Liang, Y., arxiv:2410.00835

$$\frac{\partial u}{\partial t} + b \cdot \nabla u + \frac{1}{2} \text{Tr}(\sigma \sigma^T H(u)) + Au + f = 0$$

$$u(T, \cdot) = g(\cdot)$$

$$Au(t, x) = \int_{\mathbb{R}^n} (u(t, x + G(x, z)) - u(t, x) - G(x, z) \cdot \nabla u(t, x)) \nu(dz)$$

$G(x, z) \in \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, and ν is a Levy measure associated with a Poisson random measure.

Dimension	2	4	6	8	10	20	30
FEX-PG	2.99e-7	3.17e-7	5.16e-7	7.26e-7	2.05e-7	8.02e-7	4.49e-7
TD-NN [23]	0.00954	0.00251	0.00025	0.00671	0.01895	0.00702	0.01221

Dimension	40	50	60	70	80	90	100
FEX-PG	9.05e-7	4.27e-7	4.55e-7	3.54e-7	5.89e-7	6.44e-7	5.64e-7
TD-NN [23]	0.00956	0.00219	0.00944	0.00044	0.00277	0.00460	0.00548

Committer Function for Rare Events

Song, Cameron, Yang arXiv:2306.12268, SISC, 2025

$$\begin{cases} (Lq)(\mathbf{x}) = 0 & \text{for } \mathbf{x} \notin A \cup B \\ q(\mathbf{x}) = 0 & \text{for } \mathbf{x} \in A \\ q(\mathbf{x}) = 1 & \text{for } \mathbf{x} \in B. \end{cases}$$

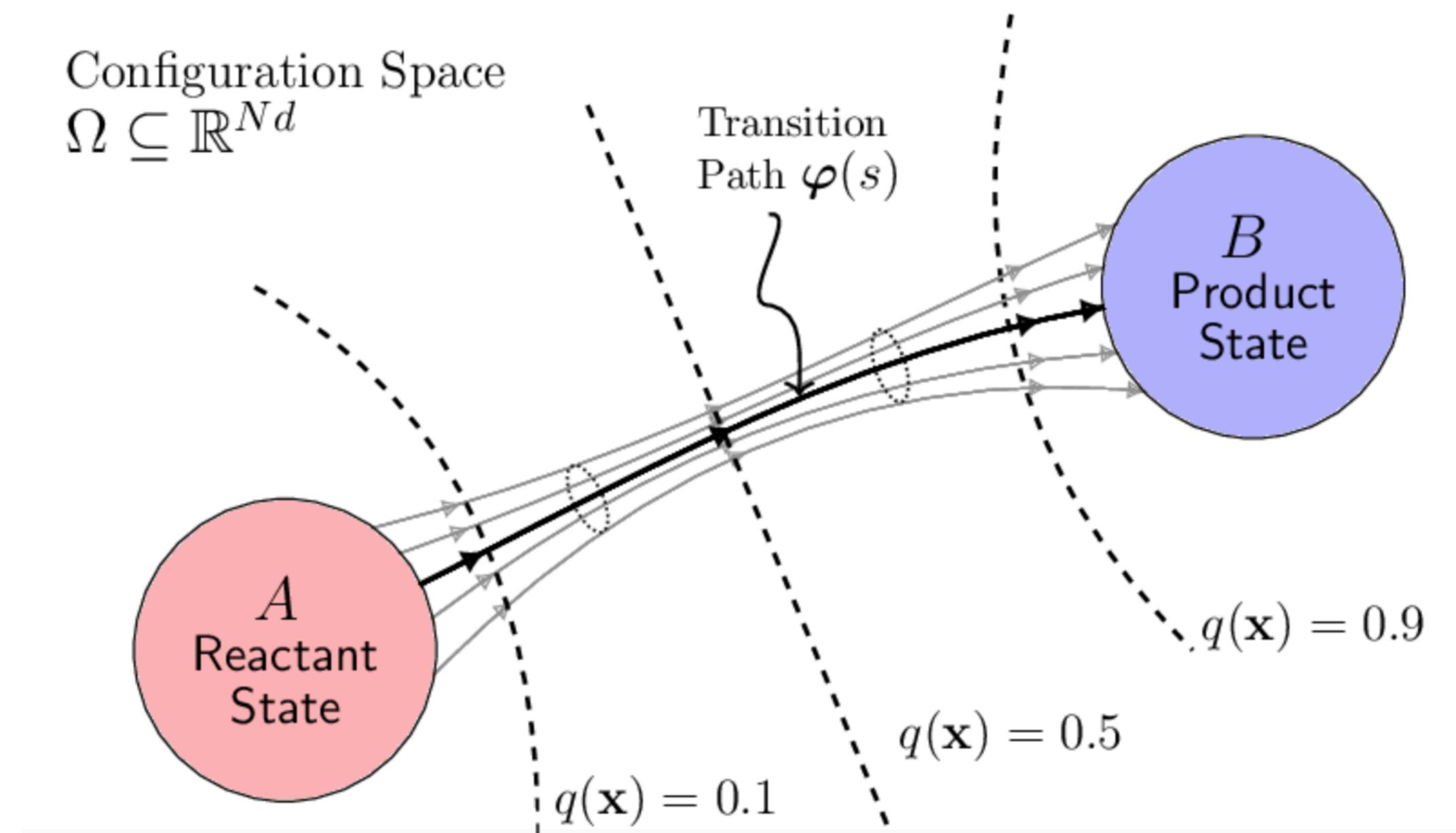
where L is the infinitesimal generator of the process

defined as:

$$Lq = -\beta^{-1} \Delta q + \nabla V \cdot \nabla q$$

Previous work

- Diffusion map, Coifman et al. (2008), Lai & Lu (2018), Evans et al. (2023)
- Neural network, Khoo et al. (2019), Li et al. (2019), Li et al. (2022)
- Tensor network, Chen et al. (2023)



Committer Function for Rare Events

Song, Cameron, Yang arXiv:2306.12268, SISC, 2025

Difficulty

- Curse of dimensionality: dimension \propto number of atoms

Physical Structure

- Low-dimensional structure: a small number of collective variables

Machine Learning

- FEX to identify the low-dimensional structure
- Transfer a high-dimensional problem into a low-dimensional one

Committer Function for Rare Events

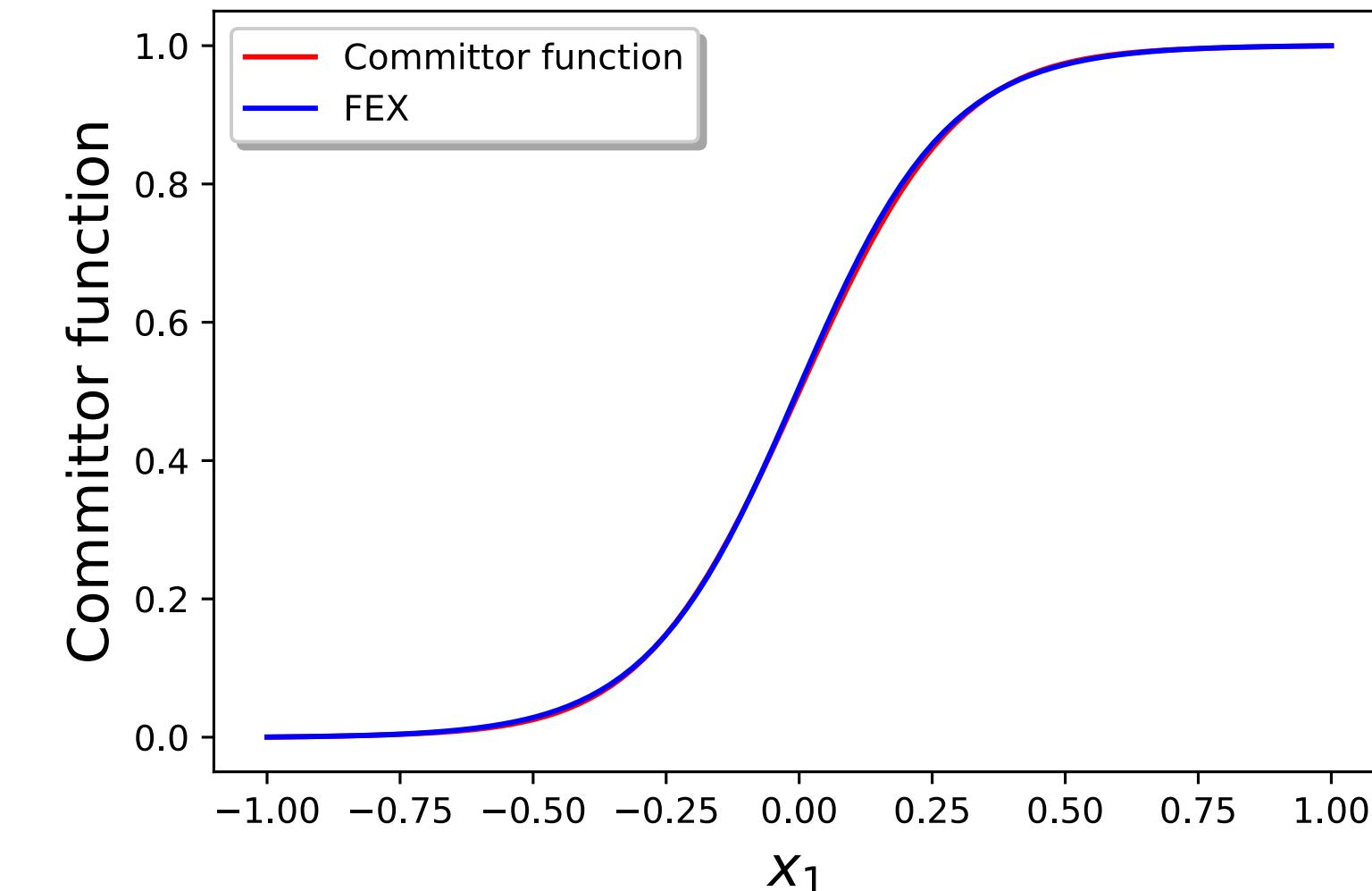
Song, Cameron, Yang arXiv:2306.12268, SISC, 2025

Example: Double-Well potential

$$V(\mathbf{x}) = \underbrace{(x_1^2 - 1)^2}_{\text{collective variable}} + 0.3 \sum_{i=2}^d x_i^2$$

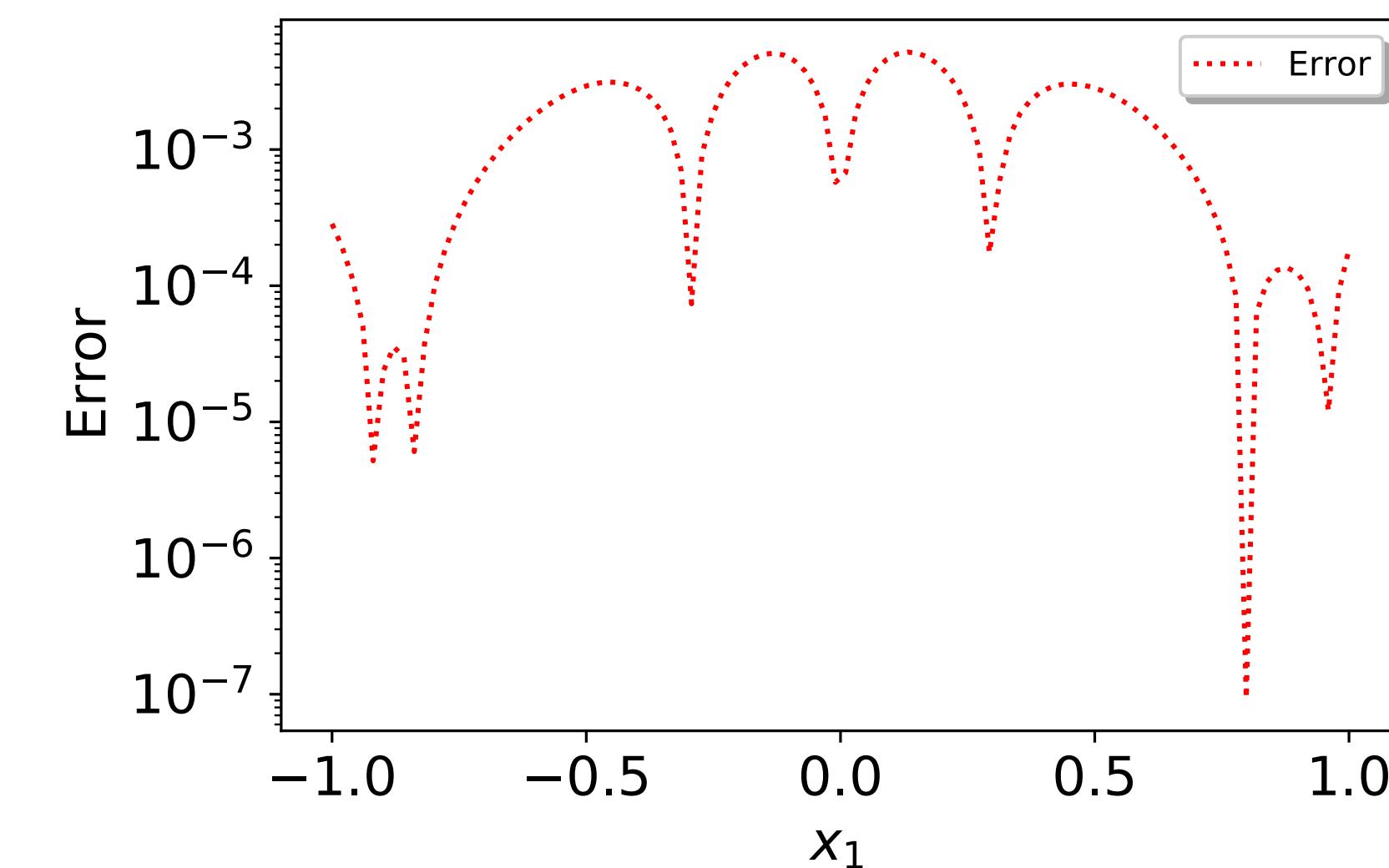
with

$$A = \{x \in \mathbb{R}^d \mid x_1 \leq -1\}, \quad B = \{x \in \mathbb{R}^d \mid x_1 \geq 1\}$$



The ground truth solution is $q(\mathbf{x}) = f(x_1)$

$$\frac{d^2f(x_1)}{dx_1^2} - 4x_1(x_1^2 - 1) \frac{df(x_1)}{dx_1} = 0, \quad f(-1) = 0, \quad f(1) = 1$$



Committer Function for Rare Events

Song, Cameron, Yang arXiv:2306.12268, SISC, 2025

FEX identifies the following representation

$$\text{Eqn 1: } \alpha_{1,1}x_1 + \dots + \alpha_{1,10}x_{10} + \beta_1$$

$$\text{Eqn 2: } \alpha_{2,1} \tanh(x_1) + \dots + \alpha_{2,10} \tanh(x_{10}) + \beta_2$$

$$\mathcal{J}(\mathbf{x}) = \alpha_3 \tanh(\text{Eqn 1} + \text{Eqn 2}) + \beta_3$$

where $\alpha_3 = 0.5, \beta_3 = 0.5$

	α_1	α_2	α_3	α_4	α_5	α_6	α_7	α_8	α_9	α_{10}	β
Eqn 1	1.6798	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Eqn 2	1.9039	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

FEX discovers that $q(\mathbf{x}) = f(x_1)$ and hence transfers a high-dimensional problem into a **low-dimensional** one.

FEX for Learning Physical Laws

- **Interpretable** learning outcomes v.s. blackbox neural networks
- **Higher accuracy** v.s. existing symbolic regression tools
- A nonlinear approach to generate **a large set** of expressions from **a small collection** of operators
 - SINDy¹: require a large manually designed dictionary
 - PDE-Net²: only capable of polynomials of operators
 - GP: Genetic programming with poor accuracy
 - SPL³: Monte Carlo tree search with poor accuracy

1. Brunton, Proctor, Nathan, Discovering governing equations from data by sparse identification of nonlinear dynamical systems, PNAS, 2016
2. Long, Lu, Dong, PDE-Net 2.0: Learning PDEs from data with a numeric-symbolic hybrid deep network, Journal of Computational Physics 2019
3. Sun et al. Symbolic Physics Learner: Discovering governing equations via Monte Carlo tree search. ICLR 2023

FEX for Learning Physical Laws

2D Burgers equation with periodic boundary conditions on $(x, y, t) \in [0, 2\pi]^2 \times [0, 10]$:

$$\frac{\partial u}{\partial t} = -u \frac{\partial u}{\partial x} - v \frac{\partial u}{\partial y} + \nu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$\frac{\partial v}{\partial t} = -u \frac{\partial v}{\partial x} - v \frac{\partial v}{\partial y} + \nu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

$$u(x, y, 0) = u_0(x, y)$$

$$v(x, y, 0) = v_0(x, y)$$

$$\nu = 0.1$$

	PDE-Net 2.0	SINDy	GP	SPL	FEX
Mean Absolute Error	1.086×10^{-3}	3.239×10^{-1}	4.973×10^{-1}	2.1×10^{-1}	2.021×10^{-4}

Finite Expression Method (FEX) Practice

Advantages:

- Leverage the power of descriptive structures of problems

Question:

- How to do computation with description?

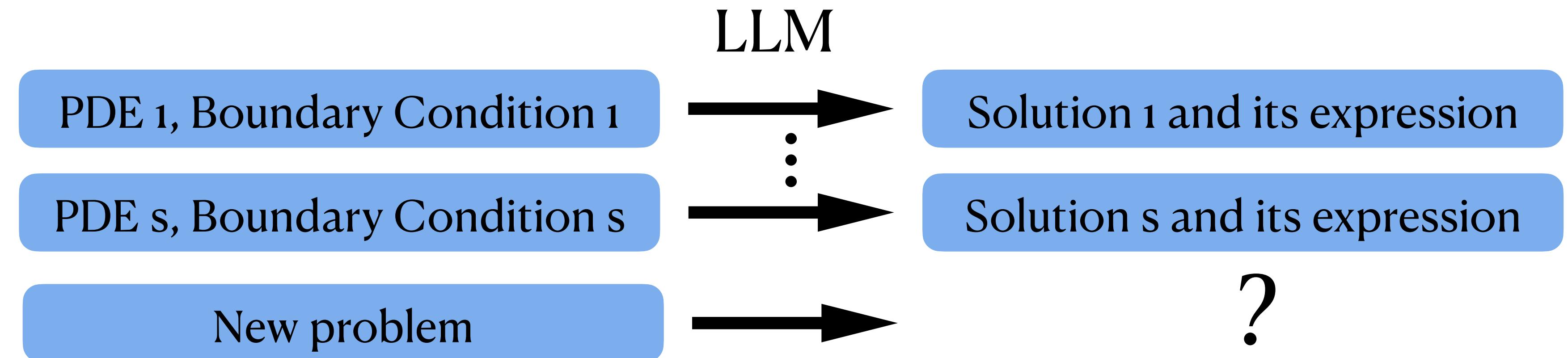
Answers:

- Symbolic machine learning
- Large language models
- Bayesian perspective

Unraveling Symbolic Structures in FEX with LLMs

Bhatnagar, Liang, Patel, Y., arXiv:2503.09986

Fine-tune LLM &
prompt engineering



$u(x)$	Method	Binary Size	Unary Size	Iters	Time [m]	Error
$4 \cos(4x^2 \cos(x_0))$	LLM-informed	1	2	4.25	8.25	0
	Uninformed	3	9	167	340	0
$4x_1^3 + 4x_1^2 + 2 \cos(4x_1^3 \cos(x_0))$	LLM-informed	2	4	102	286	10^{-8}
	Uninformed ⁶	3	9	2000+	2400+	N/A
$128x_2^3 + 2x_2 e^{4x_2^4}$	LLM-informed	2	4	34.5	40.5	4×10^{-7}
	Uninformed	3	9	90	186	6×10^{-7}
$64x_1^2 e^{2x_2}$	LLM-informed	1	3	15.5	21	3×10^{-8}
	Uninformed	3	9	103.5	161	3×10^{-8}

Finite Expression Method (FEX) Practice

Advantages:

- Leverage the power of descriptive structures of problems

Question:

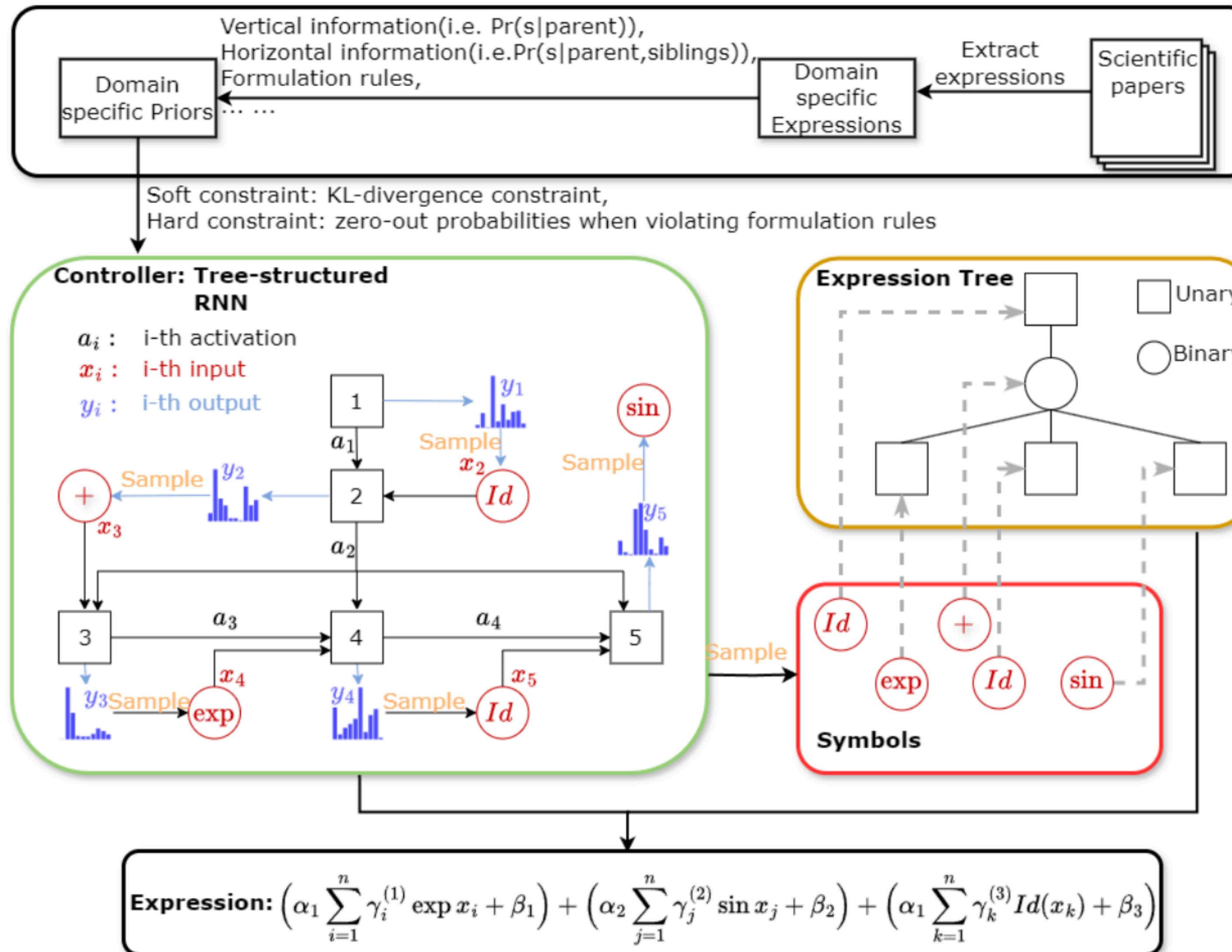
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Answers:

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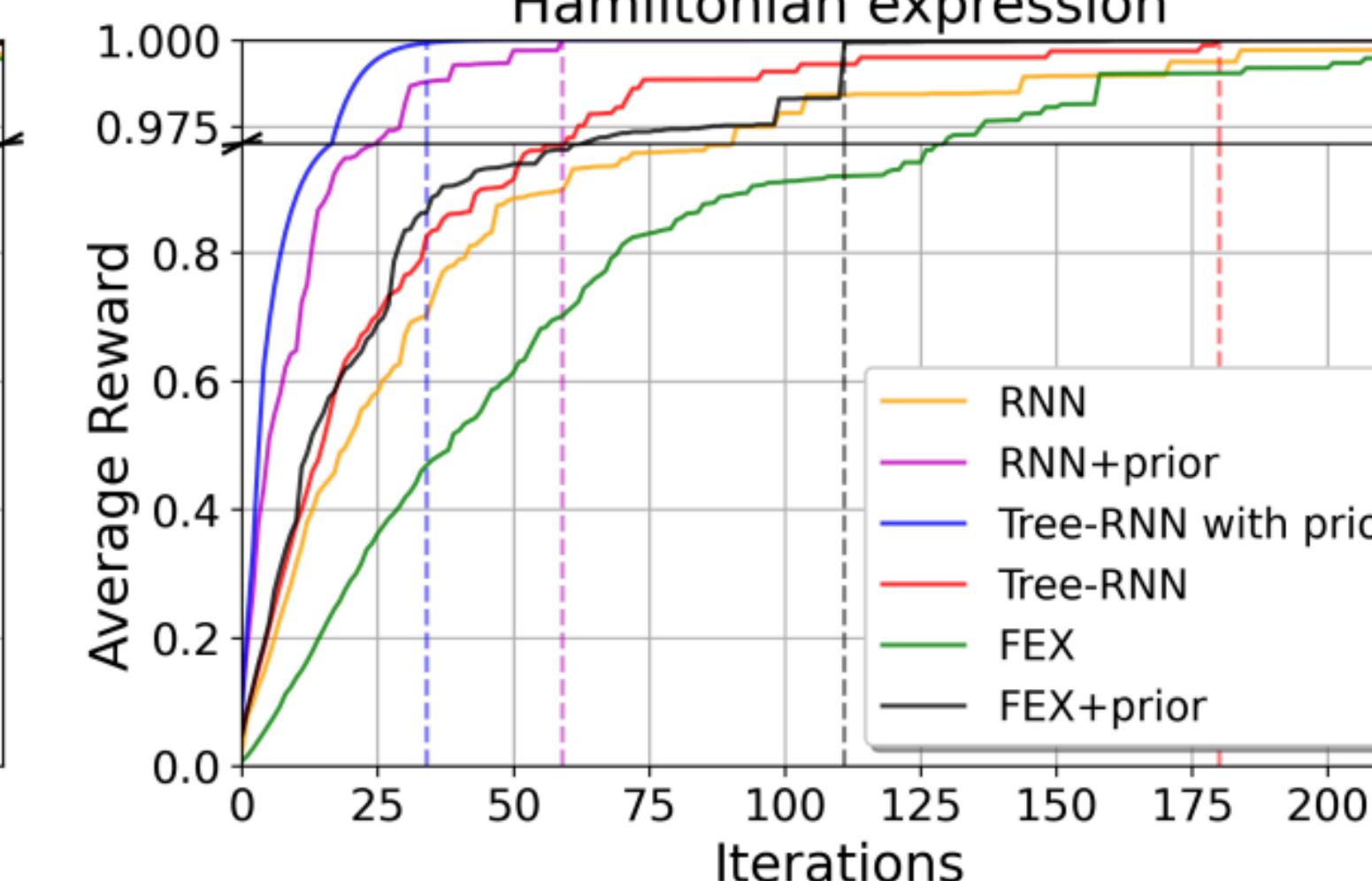
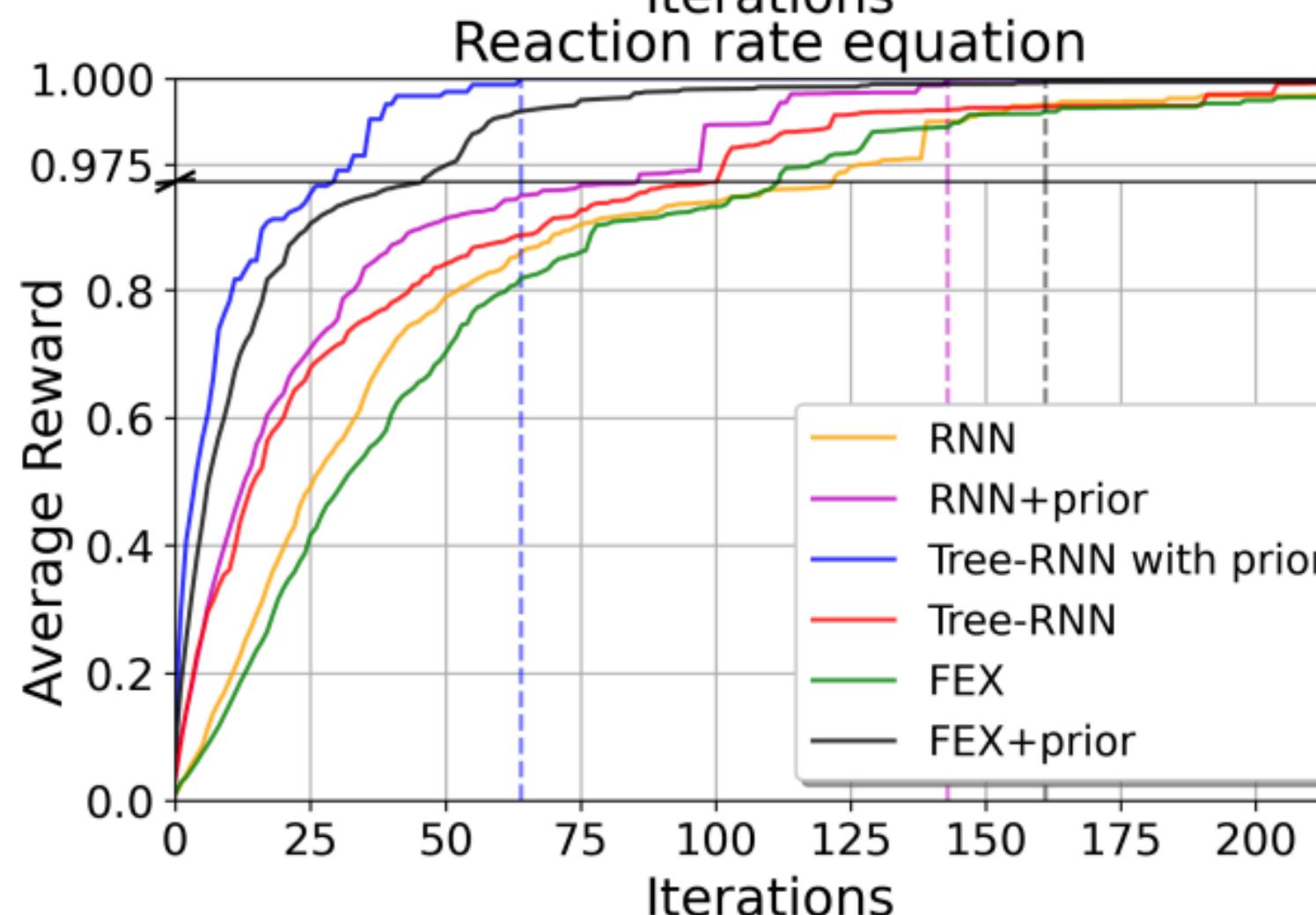
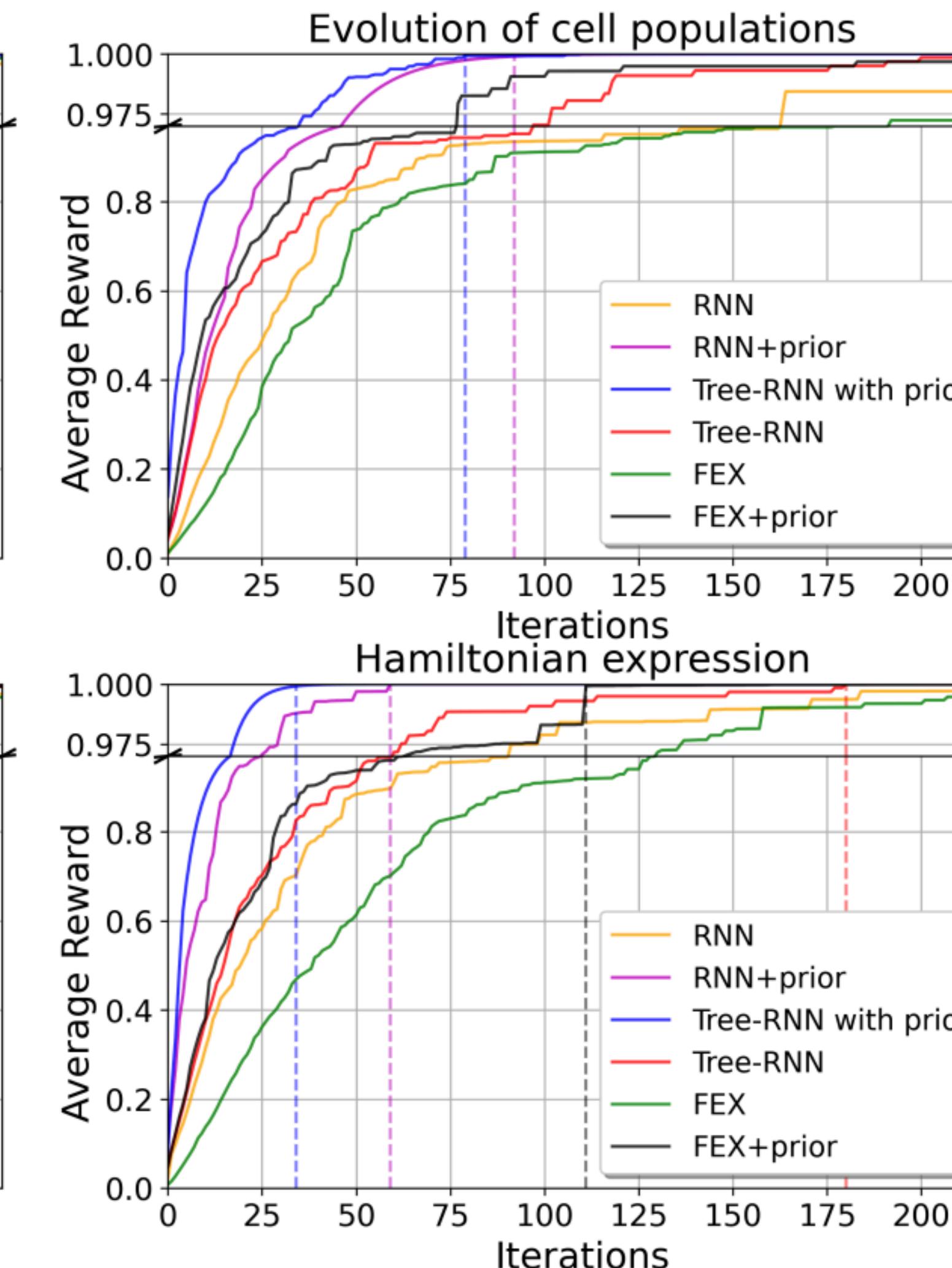
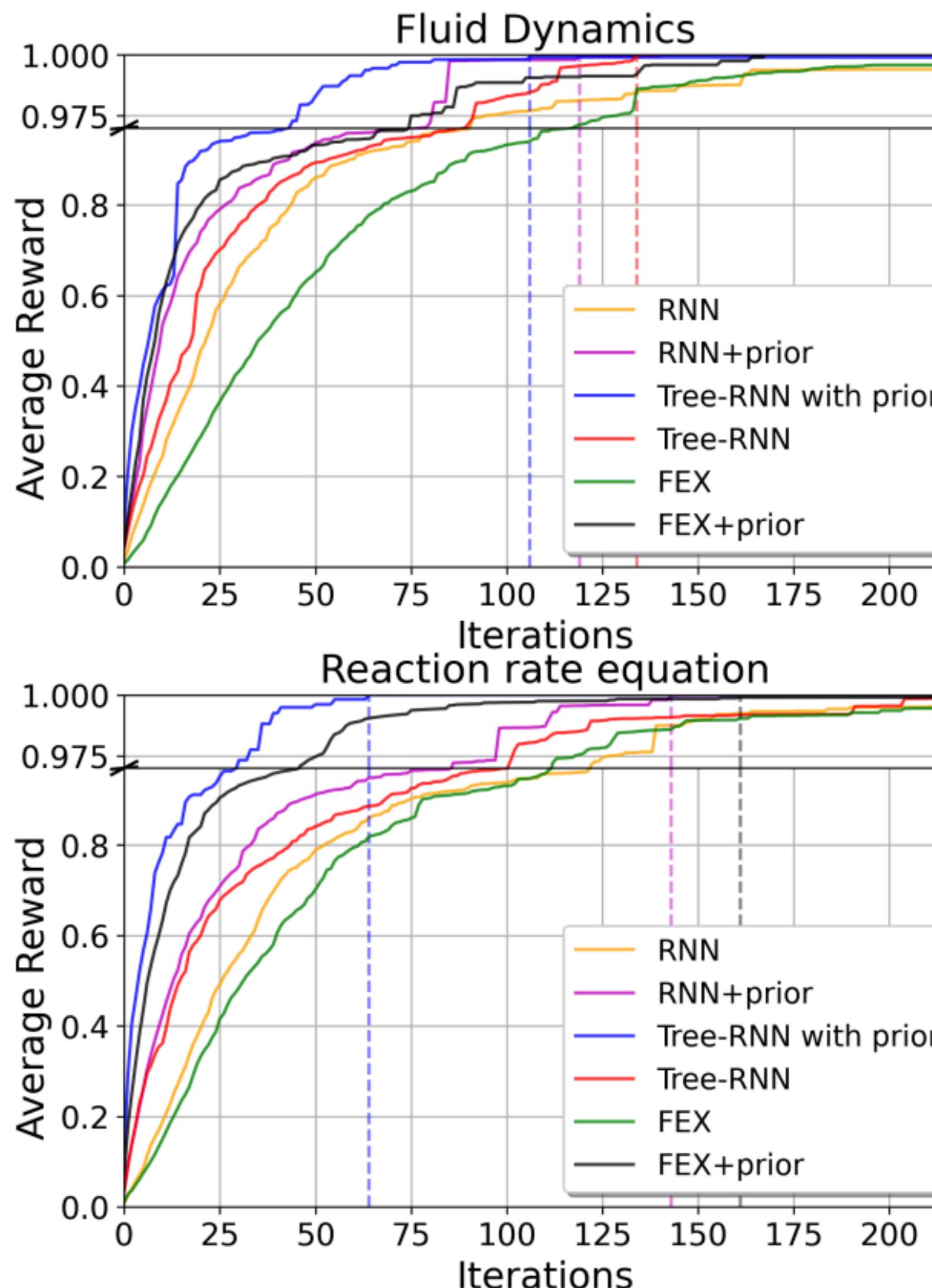
Bayesian Symbolic Learning

Huang, Wen, Adusumilli, Choudhary, Y., arXiv:2503.09592

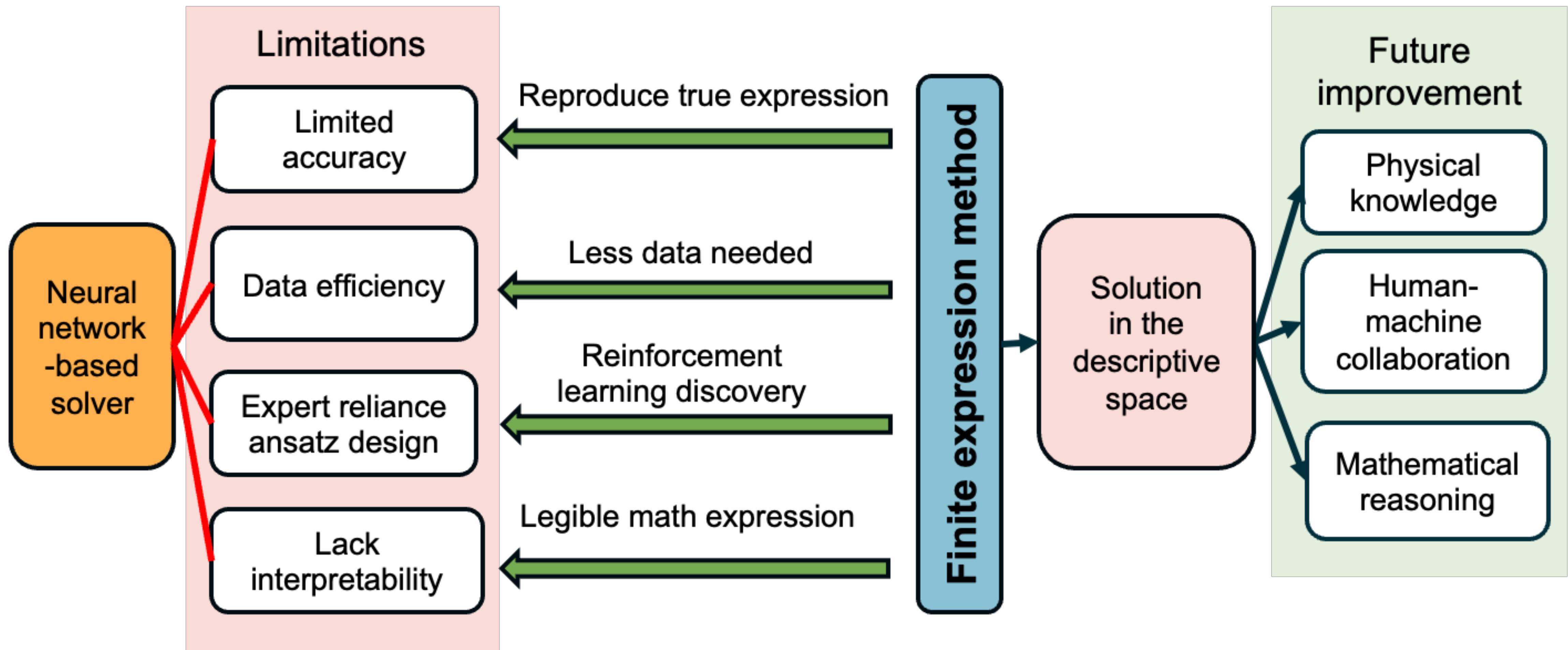


Bayesian Symbolic Learning

Huang, Wen, Adusumilli, Choudhary, Y., arXiv:2503.09592



Summary & Discussion



Two Complementary Approaches:

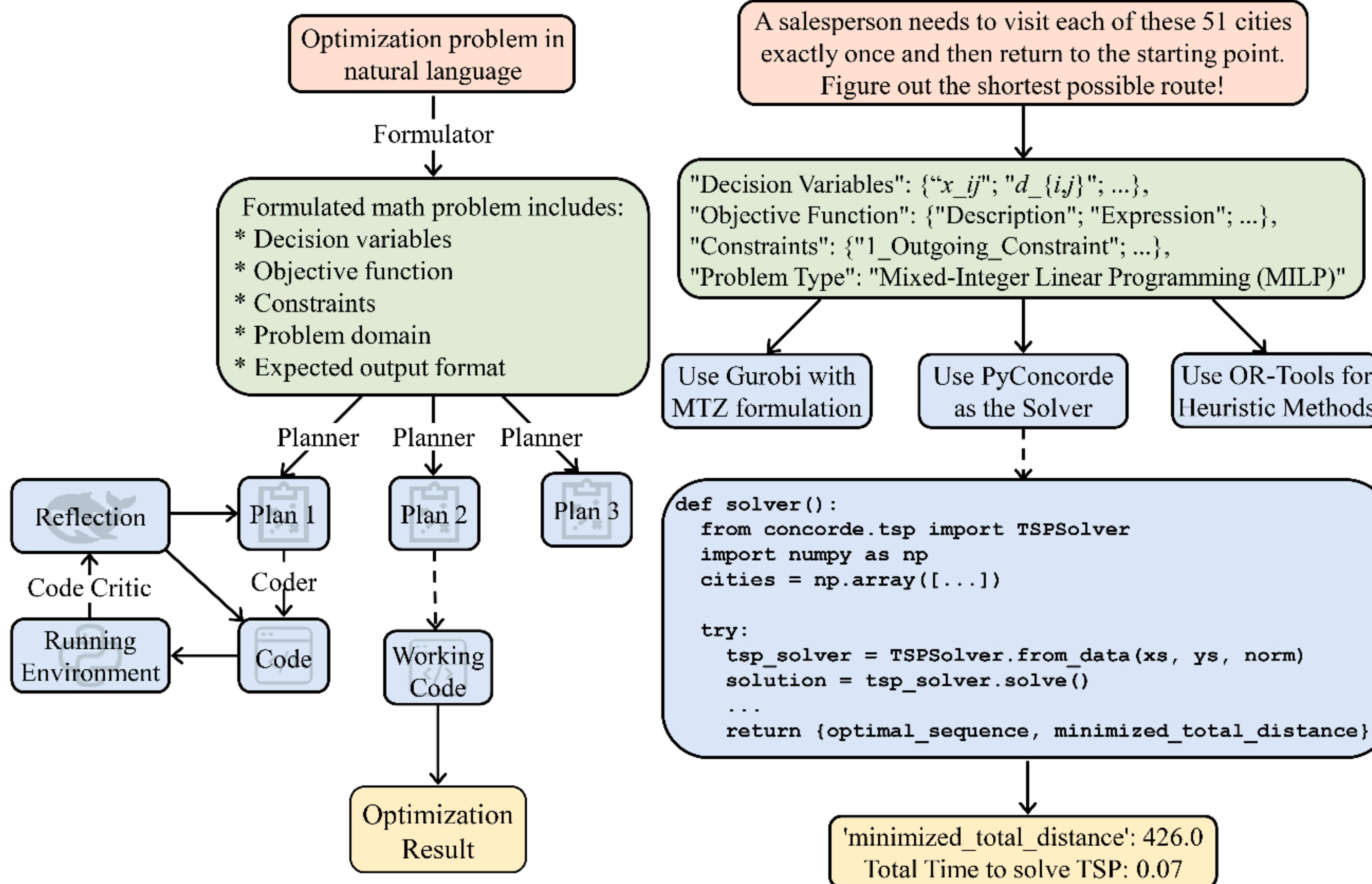
- Symbolic learning (Finite Expression Method)
- **Large language model (LLM) for modeling and computing assistant**

LLM Agents for Modeling & Computing from Natural Language

OptimAI: Thind, Sun, Liang, Y., arXiv:2504.16918

- Our research is a big search (optimization) process
- Our “search” is in a space of natural language
- Our “optimization” is mixed-integer programming and gradient-free
- **Example:** automatic optimization modeling, solving, and testing

Overview and New Features of OptiMILP



LLM Agents for Modeling & Computing from Natural Language

OptimAI: Thind, Sun, Liang, Y., arXiv:2504.16918

Table 1: Comparison of Functional Capabilities between OptimAI and Prior Methods.

Functional Capabilities	OptiMUS	Optibench	CoE	OptimAI
Natural language input	✗	✓	✓	✓
Planning before coding	✗	✗	✓	✓
Multi-solver support	✗	✗	✗	✓
Switching between plans	✗	✗	✗	✓
Code generation	✓	✓	✓	✓
Distinct LLM collaboration	✗	✗	✗	✓

LLM Agents for Modeling & Computing from Natural Language

OptimAI: Thind, Sun, Liang, Y., arXiv:2504.16918

Table 2: Previous work on using LLMs for optimization.

Work	Dataset Proposed	Size	Problem Type(s)
NL4Opt Competition [8]	NL4Opt	289	LP
Chain-of-Experts (CoE) [9]	ComplexOR	37	LP, MILP
OptiMUS [10, 11, 12]	NLP4LP	67	LP, MILP
Optibench [13]	Optibench	605	LP, NLP, MILP, MINLP
OR-LLM-Agent [14]	OR-LLM-Agent	83	LP, MILP

Abbreviations: LP - Linear Programming, NLP - Nonlinear Programming, MI - Mixed-Integer.

LLM Agents for Modeling & Computing from Natural Language

OptimAI: Thind, Sun, Liang, Y., arXiv:2504.16918

Table 3: Accuracy comparison between OptimAI and state-of-the-art methods.

Agent \ Dataset	NLP4LP	Optibench Linear w/o Tab.	Optibench Linear w/ Tab.	Optibench Nonlin. w/o Tab.	Optibench Nonlin. w/ Tab.
OptiMUS [11]	71.6%	-	-	-	-
Optibench [13]	-	75.4%	62.5%	42.1%	32.0%
Ours w/ GPT-4o	79.1%	81.2%	73.8%	72.0%	48.0%
Ours w/ GPT-4o+o1-mini	88.1%	84.2%	80.0%	77.3%	56.0%
Ours w/ QwQ (by Qwen)	79.1%	86.2%	77.5%	81.6%	50.0%
Ours w/ DeepSeek-R1	82.1%	87.4%	78.8%	79.5%	60.0%

All evaluations were conducted under a zero-shot prompting setting. GPT-4o+o1-mini refers to using o1-mini as the planner while employing GPT-4o for all other roles.

LLM Agents for Modeling & Computing from Natural Language

OptimAI: Thind, Sun, Liang, Y., arXiv:2504.16918

Table 4: Generalization of OptimAI across NP-hard combinatorial optimization problems.

	Math Programming	TSP	JSP	Set Covering
OptimAI	✓	✓	✓	✓
OptiMUS	✓	✗	✗	✗
Optibench	✓	✗	✗	✗

Traveling salesman problem (TSP), job shop scheduling problem (JSP), and set covering problem.

LLM Agents for Modeling & Computing from Natural Language

OptimAI: Thind, Sun, Liang, Y., arXiv:2504.16918

Table 5: Synergistic effects of combining heterogeneous LLMs.

Planner \ Remaining Roles	Llama 3.3 70B	DeepSeek-R1 14B	Gemma 2 27B
Llama 3.3 70B	59%	54%	54%
DeepSeek-R1 14B	68%	50%	41%
Gemma 2 27B	77%	59%	54%

LLM Agents for Modeling & Computing from Natural Language

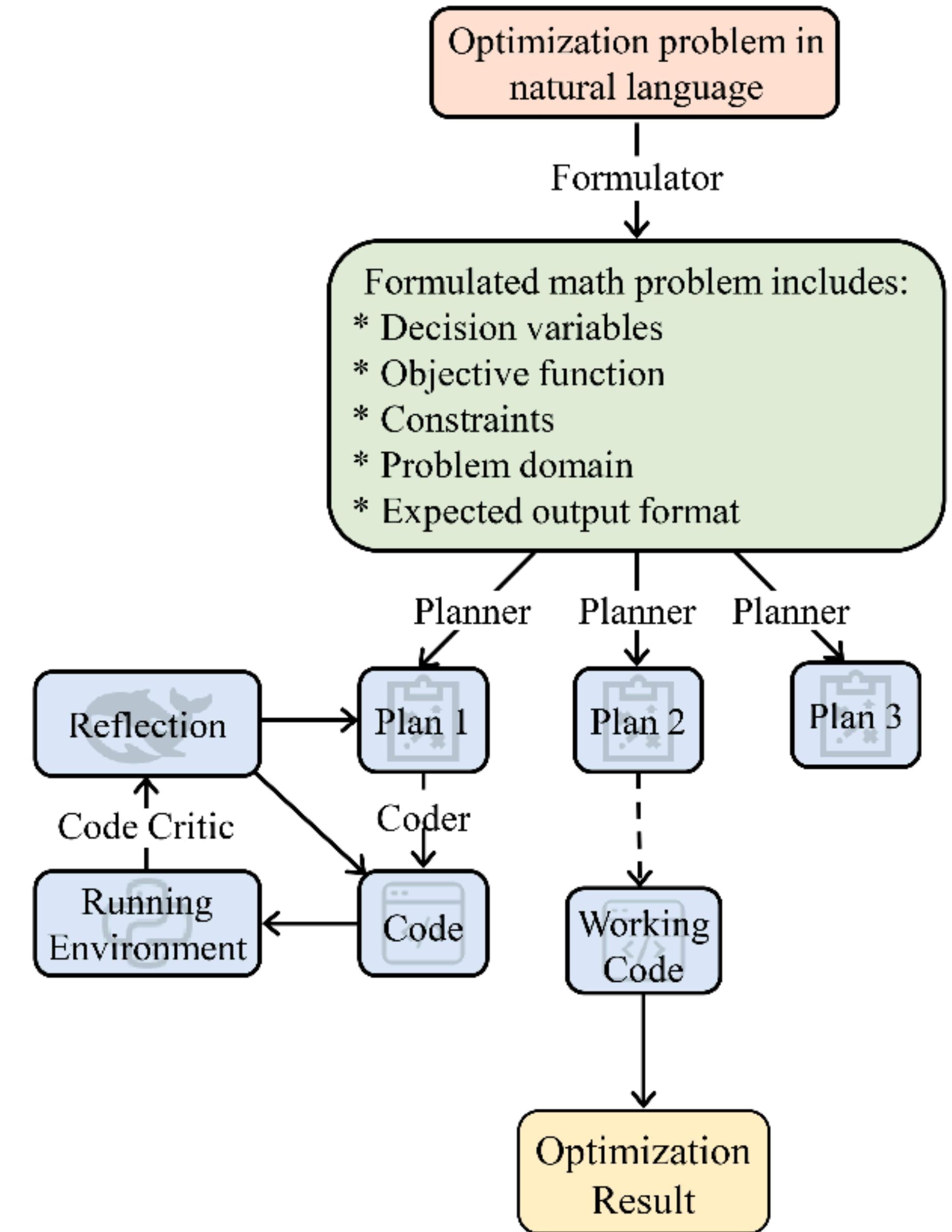
OptimAI: Thind, Sun, Liang, Y., arXiv:2504.16918

Table 6: Ablation study of OptimAI design.

Formulator	Planner	Code Critic	Revisions	Executability	Productivity
✓	✓	✓	1.7	3.6	6.8
✗	✓	✓	2.0	3.2	6.3
✓	✗	✓	7.8	3.1	1.2
✓	✓	✗	6.2	3.3	2.2

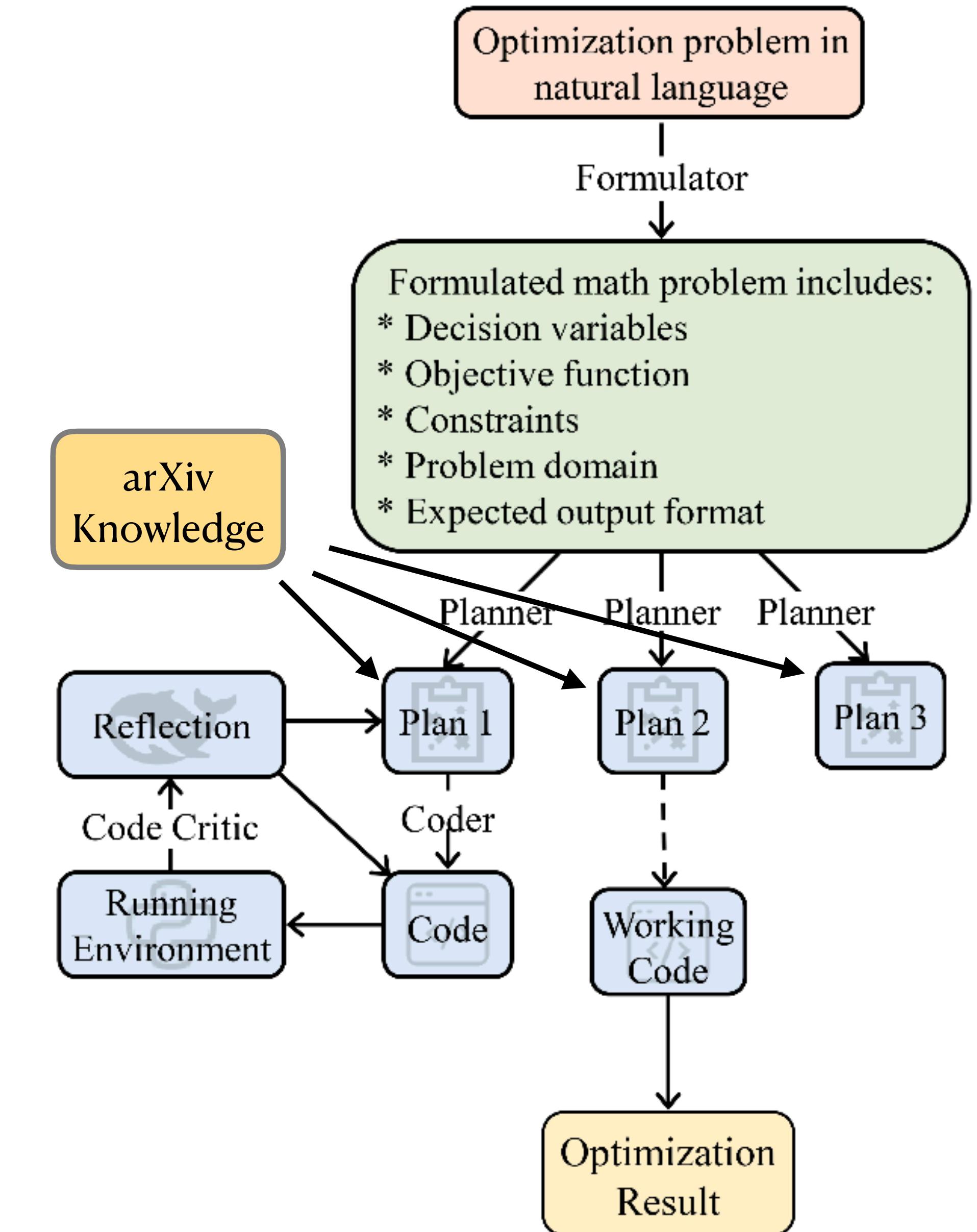
OptimAI Roadmap:

- Non-expert users for LP, NLP, MILP, MINLP
- Bayesian approach with arXiv knowledge
- Reasoning with chain of thoughts
 - Algorithm analysis
 - Coding analysis
- Optimization AI assistant with human in the loop



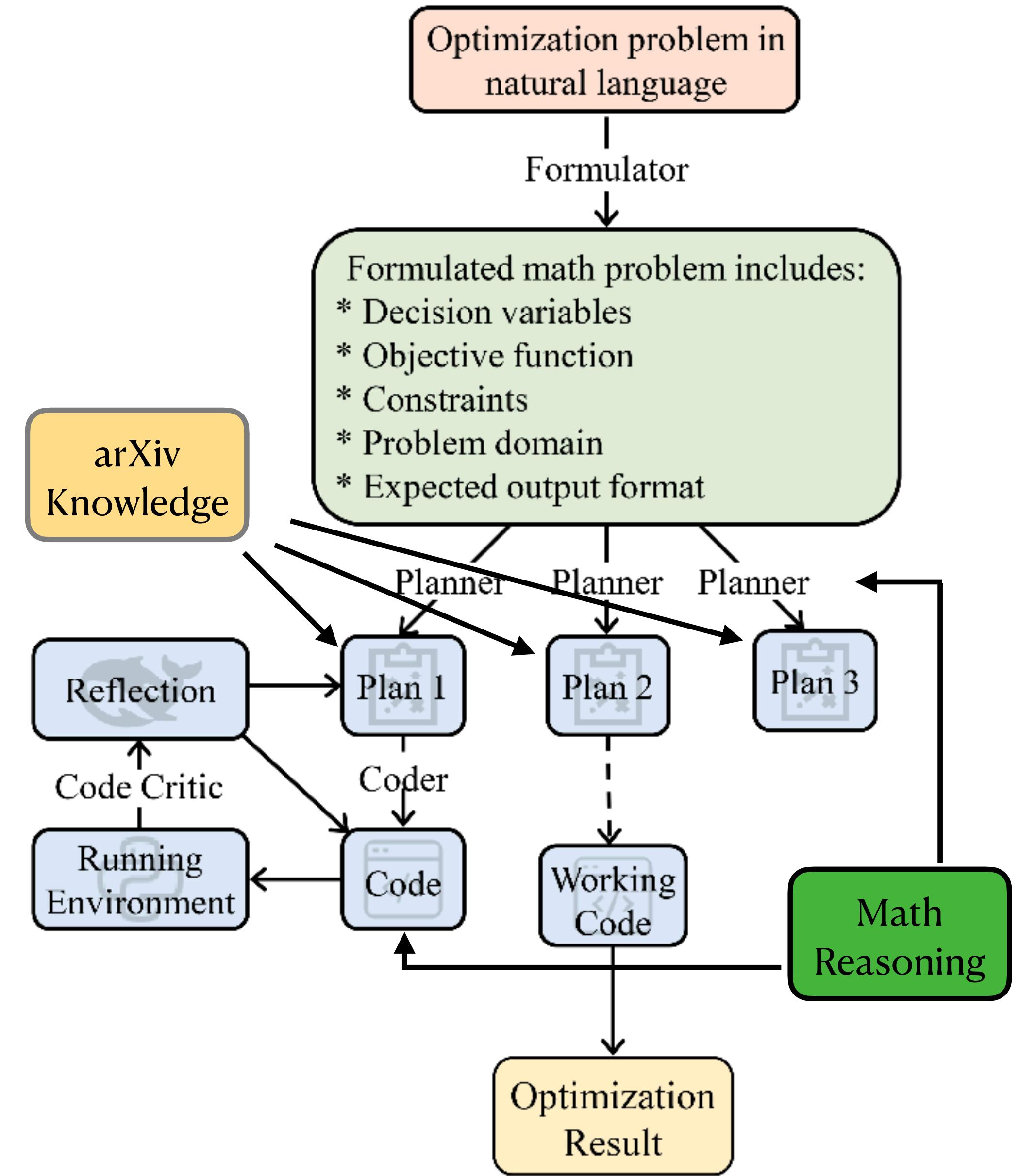
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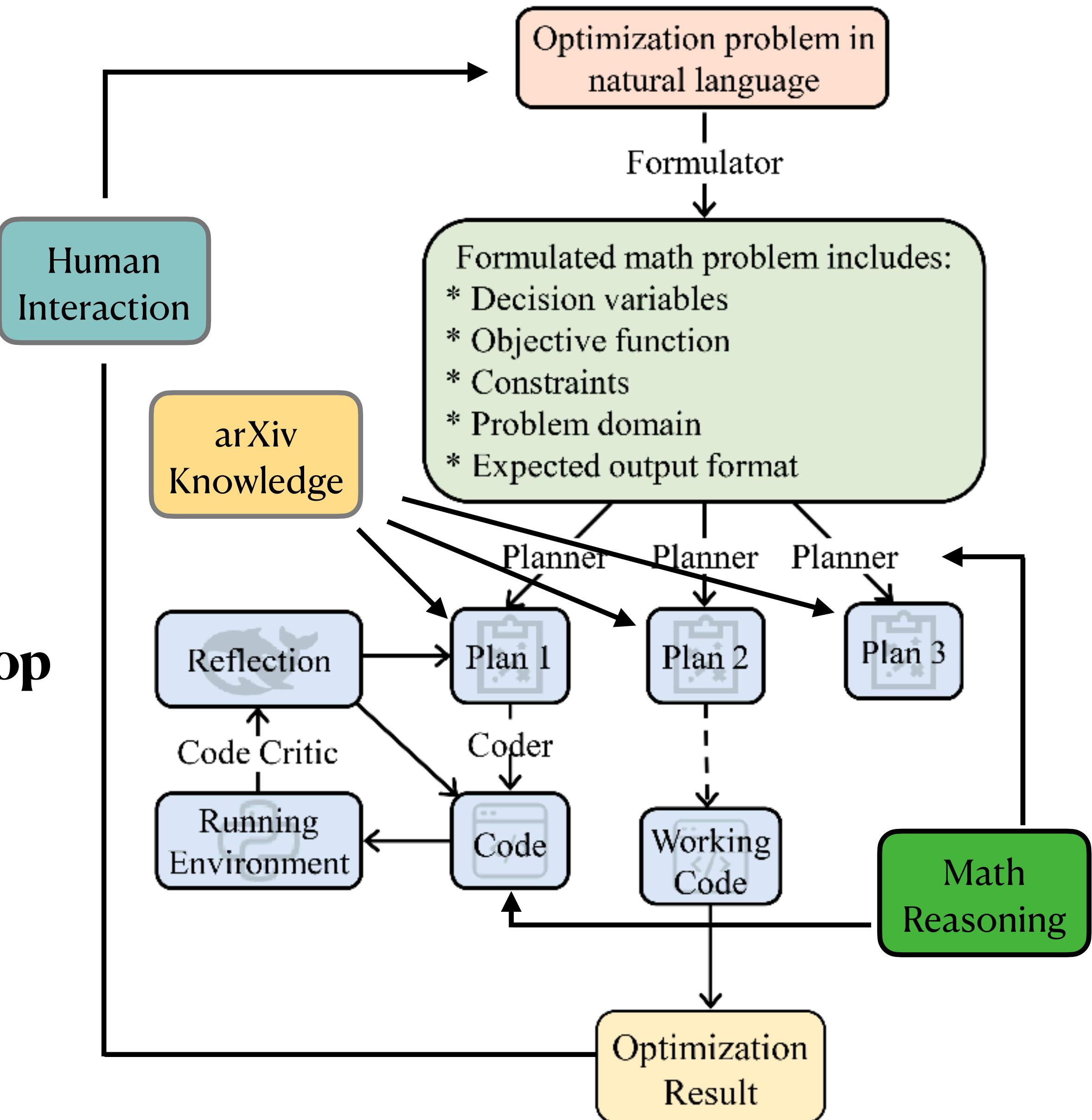
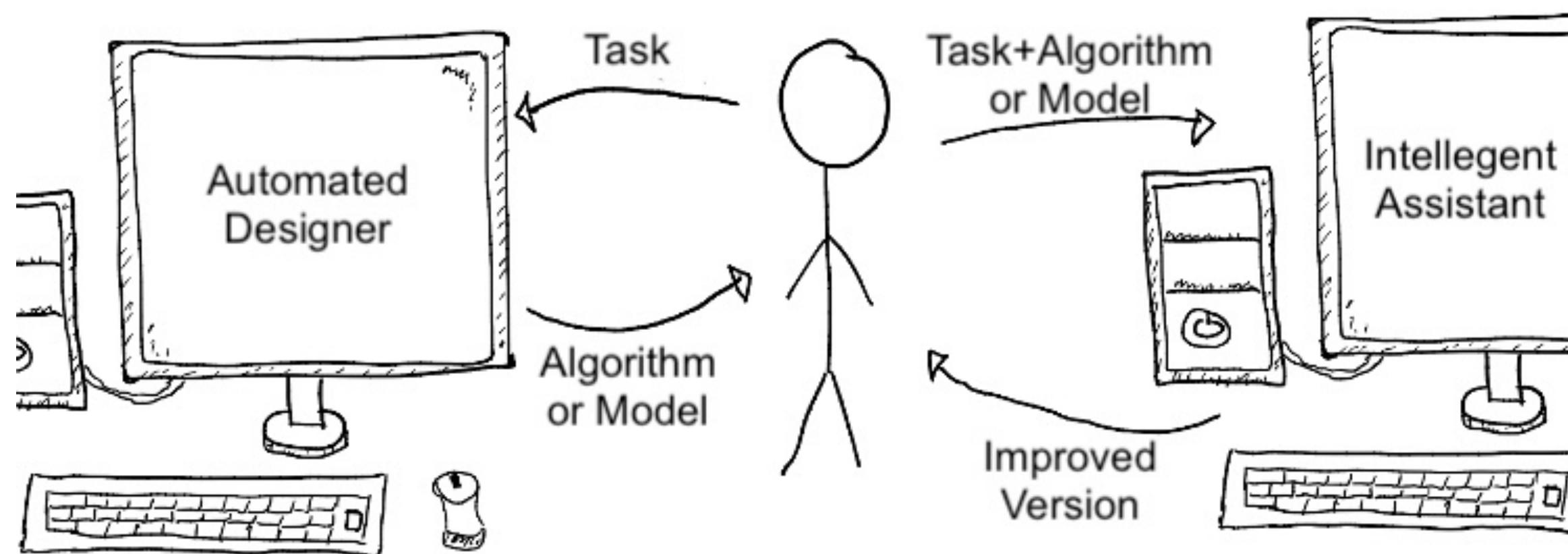
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Take Home Messages

- Modeling and Computing **in description**
- Leverage the power of **descriptive structures** of challenging problems
- Leverage the power of **automatic big search**

Finite Expression Method

Least square based FEX

- e.g., $\mathcal{D}(u) = f$ in Ω and $\mathcal{B}(u) = g$ on $\partial\Omega$
- A mathematical expression u^* to approximate the PDE solution via

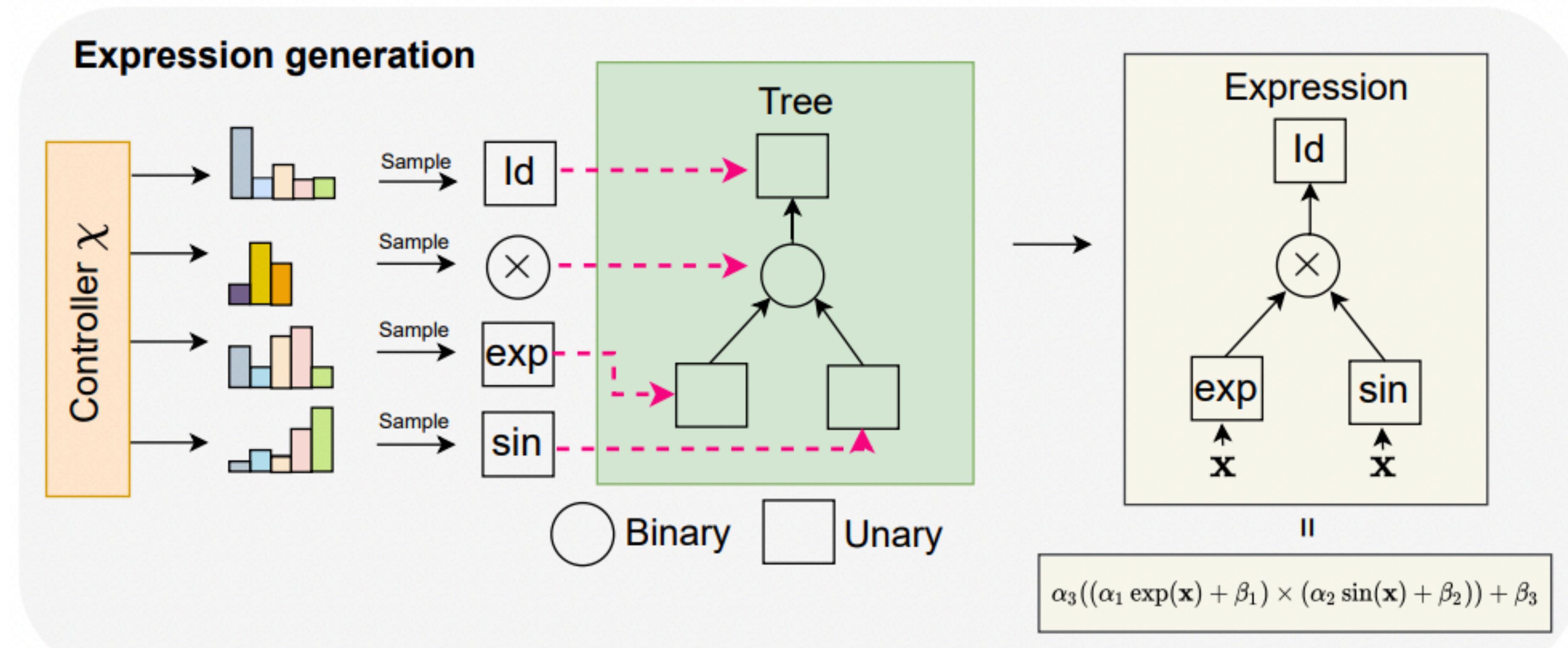
$$u^* = \arg \min_{u \in \mathbb{S}_k} \mathcal{L}(u) := \arg \min_{u \in \mathbb{S}_k} \|\mathcal{D}u - f\|_2^2 + \lambda \|\mathcal{B}u - g\|_2^2$$

- Or numerically

$$u^* = \arg \min_{u \in \mathbb{S}_k} \mathcal{L}(u) := \arg \min_{u \in \mathbb{S}_k} \frac{1}{n} \sum_{i=1}^n |\mathcal{D}u(x_i) - f(x_i)|^2 + \lambda \frac{1}{m} \sum_{j=1}^m |\mathcal{B}u(x_j) - g(x_j)|^2$$

- Question: how to solve this combinatorial optimization problem?

Continuous Relaxation of FEX



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- Continuous relaxation with k probability distributions for selecting k operators

$$\begin{aligned} (P_1^*, \dots, P_k^*) &= \arg \min_{\alpha, \beta} \min_{P_1, \dots, P_k} \mathbb{E}_{u \sim (P_1, \dots, P_k)} [\mathcal{L}(u)] \\ &= \arg \min_{\alpha, \beta} \min_{P_1, \dots, P_k} \mathbb{E}_{u \sim (P_1, \dots, P_k)} [\|\mathcal{D}u - f\|_2^2 + \lambda \|\mathcal{B}u - g\|_2^2] \end{aligned}$$

and gradient descent in the space of probability distributions

- Finally, $u^* \sim (P_1^*, \dots, P_k^*)$ with the optimal parameters α^* and β^*