

## GP2D

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### ABSTRACT

*GP2D*: 2D input  $\rightarrow$  2D prediction

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#### 1. GP2D

The multivariate normal distribution:

$$p(\mathbf{f}|\mathbf{d}) = \mathcal{N}(\mathbf{f}|\boldsymbol{\mu}, \Sigma_{\mathbf{f}|\mathbf{d}}) \quad (1)$$

$$\Sigma_{\mathbf{f}|\mathbf{d}} = (\Sigma_{\mathbf{d}}^{-1} + \Sigma_{\mathbf{f}}^{-1})^{-1} \quad (2)$$

$$\boldsymbol{\mu} = \Sigma_{\mathbf{f}|\mathbf{d}} \Sigma_{\mathbf{d}}^{-1} \mathbf{d} = \Sigma_{\mathbf{f}} (I + \Sigma_{\mathbf{d}}^{-1} \Sigma_{\mathbf{f}})^{-1} \Sigma_{\mathbf{d}}^{-1} \mathbf{d} \quad (3)$$

Assuming

$$\Sigma_{\mathbf{d}} = \sigma^2 I \quad (4)$$

$$\Sigma_{\mathbf{f}} = K = K_Y \otimes K_X \quad (5)$$

and an eigendecomposition of  $K$ ,  $K_X$ , and  $K_Y$  as

$$K \equiv Q \Lambda Q^\top = (U_Y \otimes U_X) (\Lambda_Y \otimes \Lambda_X) (U_Y \otimes U_X)^\top \quad (6)$$

$$K_X \equiv U_X \Lambda_X U_X^\top \quad (7)$$

$$K_Y \equiv U_Y \Lambda_Y U_Y^\top, \quad (8)$$

and an identity

$$(A^\top \otimes B) \text{vec}(X) = \text{vec}(BXA), \quad (9)$$

we obtain (isomorphism,  $\mathbf{d} = \text{vec}(D)$ ,  $D = \text{mat}(\mathbf{d}) \in \mathcal{R}^{N_X \times N_Y}$ )

$$\boldsymbol{\mu} = K(K + \sigma^2 I)^{-1} \mathbf{d} \quad (10)$$

$$= KQ(\Lambda + \sigma^2 I)^{-1} Q^\top \mathbf{d} \quad (11)$$

$$= KQ(\Lambda + \sigma^2 I)^{-1} (U_Y \otimes U_X)^\top \mathbf{d} \quad (12)$$

$$= KQ(\Lambda + \sigma^2 I)^{-1} (U_Y^\top \otimes U_X^\top) \mathbf{d} \quad (13)$$

$$= KQ(\text{diag}(\Lambda + \sigma^2 I)^{-1} \odot \text{vec}(U_X^\top D U_Y)) \quad (14)$$

$$= K(U_Y \otimes U_X)(\text{diag}(\Lambda + \sigma^2 I)^{-1} \odot \text{vec}(U_X^\top D U_Y)) \quad (15)$$

$$= K(U_Y \otimes U_X) \mathbf{p} \quad (16)$$

$$= (K_Y \otimes K_X) \text{vec}(U_X P U_Y^\top) \quad (17)$$

$$= \text{vec}(K_X U_X P U_Y^\top K_Y) \quad (18)$$

where  $\mathbf{p} = (\text{diag}(\Lambda + \sigma^2 I)^{-1} \odot \text{vec}(U_X^\top D U_Y))$  and

$$P = \text{mat}(\mathbf{p}) = L \odot (U_X^\top D U_Y) \quad (19)$$

$$L = \text{mat}(\mathbf{l}) = 1 \odot (\boldsymbol{\kappa}_S^\top \otimes \boldsymbol{\kappa}_T + \sigma^2 E) \quad (20)$$

where  $\odot$  is an element-wise deviation,  $E$  is a matrix whose elements are unity, and  $\boldsymbol{\kappa}_S^\top$  and  $\boldsymbol{\kappa}_T$  are the column vector made of the eigenvalues of  $K_S$  and  $K_T$ .

The isomorphic expression for  $M = \text{mat}(\boldsymbol{\mu})$  is given by

$$M = K_X U_X P U_Y^\top K_Y. \quad (21)$$

For the prediction of  $K^* = (K_Y^* \otimes K_X^*)$ , we obtain

$$\boldsymbol{\mu} = K^* \text{vec}(U_X P U_Y^\top) \quad (22)$$

$$= (K_Y^* \otimes K_X^*) \text{vec}(U_X P U_Y^\top) \quad (23)$$

$$= \text{vec}(K_X^* U_X P U_Y^\top (K_Y^*)^\top) \quad (24)$$

The isomorphic expression is

$$M^* = K_X^* U_X P U_Y^\top (K_Y^*)^\top \quad (25)$$