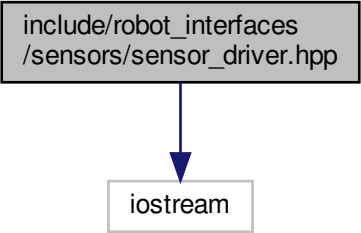


```
include/robot_interfaces  
/sensors/sensor_driver.hpp
```



```
graph TD; A["include/robot_interfaces  
/sensors/sensor_driver.hpp"] --> B["iostream"]
```

iostream