

robot\_interfaces::RobotDriver  
< Action, Observation >

Driver

```
classDiagram
    class robot_interfaces__RobotDriver["robot_interfaces::RobotDriver< Action, Observation >"]
    class Driver
    Driver --|> robot_interfaces__RobotDriver
```

The diagram illustrates a class hierarchy. At the top is a white rectangular box with a black border containing the text "robot\_interfaces::RobotDriver" and "< Action, Observation >". Below this box is a smaller, gray rectangular box with a black border containing the text "Driver". A blue arrow points vertically from the top of the "Driver" box to the bottom of the "robot\_interfaces::RobotDriver" box, indicating that the Driver class inherits from or implements the RobotDriver interface.