

Env



```
graph BT; A["trifinger_simulation.gym_wrapper.envs.trifinger_reach.TriFingerReach"] --> B[Env]
```

The diagram illustrates a class inheritance relationship. At the bottom is a gray rectangular box with a black border containing the text `trifinger_simulation.gym_wrapper.envs.trifinger_reach.TriFingerReach`. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box with a gray border at the top. This top box contains the text `Env`.

`trifinger_simulation.gym
_wrapper.envs.trifinger
_reach.TriFingerReach`