

```
robot_interfaces::RobotDriver  
< robot_interfaces::NJointAction  
< N_JOINTS >, robot_interfaces  
::NJointObservation< N_JOINTS > >
```

```
blmc_robots::NJointBlmcRobot  
Driver< robot_interfaces  
::NJointObservation< N_JOINTS  
>, N_JOINTS, N_MOTOR_BOARDS >
```

```
blmc_robots::SimpleNJoint  
BlmcRobotDriver< N_JOINTS,  
N_MOTOR_BOARDS >
```

