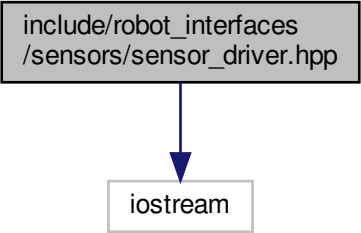


```
include/robot_interfaces  
/sensors/sensor_driver.hpp
```



The diagram consists of a gray rectangular box at the top containing the file path `include/robot_interfaces/sensors/sensor_driver.hpp`. A blue arrow points vertically downwards from the bottom center of this box to a white rectangular box with a gray border. This second box contains the text `iostream`.

```
iostream
```