```
robot interfaces::RobotDriver
< robot interfaces::NJointAction
< N JOINTS >, Observation >
blmc robots::BlmcJointModules
        < N JOINTS >
```

blmc robots::NJointBlmcRobot

Driver< Observation, N JOINTS, N MOTOR BOARDS >:: Config

blmc robots::MotorParameters

joint modules

config

motor parameters

blmc robots::NJointBlmcRobot Driver< Observation, N JOINTS, N MOTOR BOARDS >