

```
blmc_robots::NJointBlmcRobot  
Driver< robot_interfaces  
::NFingerObservation< N_FINGERS  
>, N_FINGERS *robot_interfaces  
::JOINTS_PER_FINGER, N_FINGERS  
*robot_interfaces::BOARDS_PER_FINGER >
```

robot\_fingers::NFingerDriver< 3 >

robot\_fingers::TriFinger  
Driver

