```
robot interfaces::RobotDriver
< robot interfaces::NJointAction
< N JOINTS >, robot interfaces
::NJointObservation< N_JOINTS > >
  blmc robots::BlmcJointModules
                                        joint modules
         < N JOINTS >
                                                             blmc robots::NJointBlmcRobot
                                                                                                            blmc robots::SimpleNJoint
                                                             Driver< robot interfaces
                                                                                                            BlmcRobotDriver< N JOINTS,
                                                             ::NJointObservation< N JOINTS
                                            config
                                                                                                               N MOTOR BOARDS >
 blmc robots::NJointBlmcRobot
                                                             >, N JOINTS, N MOTOR BOARDS >
 Driver< Observation, N JOINTS,
                                       motor parameters
  N MOTOR BOARDS >:: Config
  blmc robots::MotorParameters
```