

# EE120 - Fall'19 - Lecture 21 Notes<sup>1</sup>

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## The z-Transform

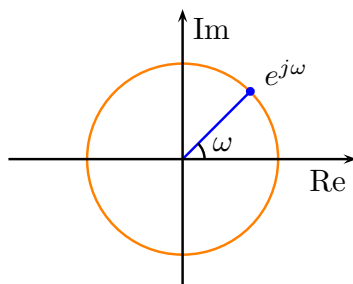
The z-Transform is defined as:

$$X(z) := \sum_{n=-\infty}^{\infty} x[n]z^{-n} \quad (1)$$

where  $z \in \mathbb{C}$ . It recovers the DTFT when  $z$  is on the unit circle, i.e., when  $z = e^{j\omega}$  for some  $\omega \in [0, 2\pi)$ :

$$X(z) \Big|_{z=e^{j\omega}} = X(e^{j\omega}). \quad (2)$$

Thus, the DTFT converges if the region of convergence (ROC) for the z-transform includes the unit circle.



Example 1:  $x[n] = \delta[n] \rightarrow X(z) = 1$ , ROC: entire complex plane

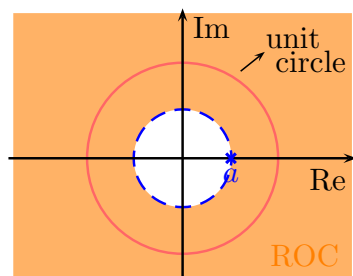
Example 2:  $x[n] = a^n u[n]$

$$X(z) = \sum_{n=0}^{\infty} a^n z^{-n} = \sum_{n=0}^{\infty} (az^{-1})^n = \frac{1}{1 - az^{-1}} \quad \text{if } \underbrace{|az^{-1}| < 1}_{\text{ROC: } |z| > |a|}$$

Poles and zeros:  $X(z) = \frac{z}{z-a} \rightarrow$  pole at  $z = a$ , zero at  $z = 0$ .

DTFT:

$$X(e^{j\omega}) = \frac{1}{1 - ae^{-j\omega}} \quad \text{if } |a| < 1$$



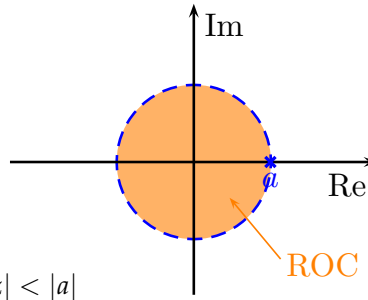
Chapter 10 in Oppenheim & Willsky



Figure 1: Former Berkeley EECS professors Lotfi Zadeh (above) and Eliahu Jury (below) were among those who developed the theory of z transforms in the 1950s. Research in sampling was partly motivated by radar which came to prominence during World War II.

Example 3:  $x[n] = -a^n u[-n-1]$

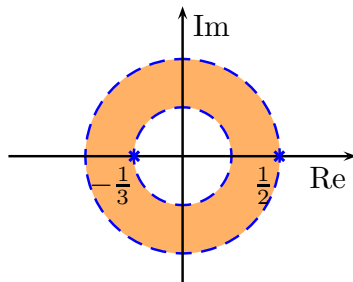
$$\begin{aligned}
 X(z) &= \sum_{n=-\infty}^{-1} -a^n z^{-n} = \sum_{n=1}^{\infty} -a^{-n} z^n \\
 &= 1 - \sum_{n=0}^{\infty} (a^{-1}z)^n \\
 &= 1 - \frac{1}{1 - a^{-1}z} \quad \text{if } |a^{-1}z| < 1 \\
 &= \frac{-a^{-1}z}{1 - a^{-1}z} = \frac{1}{1 - az^{-1}} \quad \text{ROC: } |z| < |a|
 \end{aligned}$$



DTFT converges is  $|a| > 1$ .

Example 4:  $x[n] = -\left(\frac{1}{2}\right)^n u[-n-1] + \left(\frac{-1}{3}\right)^n u[n]$

$$\begin{aligned}
 X(z) &= \frac{1}{1 - \frac{1}{2}z^{-1}} + \frac{1}{1 + \frac{1}{3}z^{-1}} = \frac{z}{z - \frac{1}{2}} + \frac{z}{z + \frac{1}{3}} = \frac{2z(z - \frac{1}{12})}{(z - \frac{1}{2})(z + \frac{1}{3})} \\
 &\quad \underbrace{|z| < \frac{1}{2} \quad |z| > \frac{1}{3}}_{\text{ROC: } \frac{1}{3} < |z| < \frac{1}{2}}
 \end{aligned}$$



Example 5:  $x[n] = \left(\frac{1}{2}\right)^n u[n] - \left(\frac{-1}{3}\right)^n u[-n-1]$

$$\text{ROC} = \{z : |z| > \frac{1}{2}\} \cap \{z : |z| < \frac{1}{3}\} = \emptyset$$

Example 6:  $x[n] = a^n, a \neq 0$ .

$$x[n] = a^n u[n] + a^n u[-n-1]$$

$$\text{ROC} = \{z : |z| > a\} \cap \{z : |z| < a\} = \emptyset$$

### Properties of the ROC

Section 10.2 in Oppenheim & Willsky

As seen in the examples above, the ROC is a ring or disk in the  $z$ -plane, centered at the origin. Note that it does not contain any poles. If  $x[n]$  is right-sided (e.g., Example 1) then the ROC extends from the outermost pole to  $\infty$ .

### Inverse z-Transform by Partial Fraction Expansion

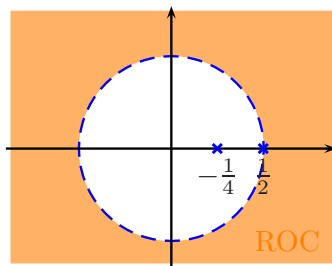
Example 7:

$$X(z) = \frac{1}{\left(1 - \frac{1}{4}z^{-1}\right)\left(1 - \frac{1}{2}z^{-1}\right)} = \frac{A_1}{1 - \frac{1}{4}z^{-1}} + \frac{A_2}{1 - \frac{1}{2}z^{-1}}$$

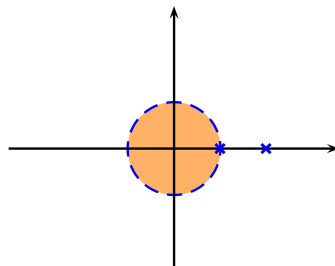
$$A_1 = \left(1 - \frac{1}{4}z^{-1}\right) X(z) \Big|_{z=\frac{1}{4}} = -1$$

$$A_2 = \left(1 - \frac{1}{2}z^{-1}\right) X(z) \Big|_{z=\frac{1}{2}} = 2$$

1)

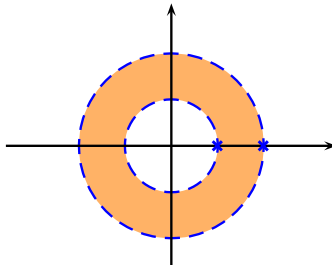


2)



$$x[n] = \left[ 2 \left(\frac{1}{2}\right)^n - \left(\frac{1}{4}\right)^n \right] u[n] \quad x[n] = - \left[ 2 \left(\frac{1}{2}\right)^n - \left(\frac{1}{4}\right)^n \right] u[-n-1]$$

3)



$$x[n] = -2 \left(\frac{1}{2}\right)^n u[-n-1] - \left(\frac{1}{4}\right)^n u[n]$$

How to perform a PFE in general?

$$X(z) = \frac{b_0 + b_1 z^{-1} + \dots + b_M z^{-M}}{a_0 + a_1 z^{-1} + \dots + a_N z^{-N}}, \quad a_0 \neq 0$$

Suppose unrepeated poles:  $d_1, d_2, \dots, d_N$ .

If  $M < N$ ,

$$X(z) = \sum_{k=1}^N \frac{A_k}{1 - d_k z^{-1}}$$

If  $M \geq N$ ,

$$\begin{aligned}
 X(z) &= \sum_{r=0}^{M-N} B_r z^{-r} + \sum_{k=1}^N \frac{A_k}{1 - d_k z^{-1}} \\
 &\quad \Downarrow \\
 x[n] &= \sum_{r=0}^{M-N} B_r \delta[n-r] + \underbrace{\sum_{k=1}^N A_k d_k^n u[n]}_{\text{if right-sided}}
 \end{aligned}$$

Example 8:

$$\begin{aligned}
 X(z) &= \frac{1 + 2z^{-1} + z^{-2}}{1 - \frac{3}{2}z^{-1} + \frac{1}{2}z^{-2}} \quad M = N = 2 \\
 &= B_0 + \frac{A_1}{1 - \frac{1}{2}z^{-1}} + \frac{A_2}{1 - z^{-1}}
 \end{aligned}$$

Matching coefficients:  $A_1 = -9$ ,  $A_2 = 8$ ,  $B_0 = 2$ .

$$x[n] = 2\delta[n] - 9\left(\frac{1}{2}\right)^n u[n] + 8u[n].$$

Differentiation (in z-domain) Property:

$$\begin{aligned}
 x[n] &\xleftrightarrow{\mathcal{Z}} X(z) & \text{ROC} = R \\
 nx[n] &\xleftrightarrow{\mathcal{Z}} -z \frac{dX(z)}{dz} & \text{ROC} = R
 \end{aligned}$$

Proof:

$$\begin{aligned}
 X(z) &= \sum_{n=-\infty}^{\infty} x[n] z^{-n} \\
 \frac{dX(z)}{dz} &= \sum_{n=-\infty}^{\infty} -nx[n] z^{-(n+1)} = -z^{-1} \sum_{n=-\infty}^{\infty} nx[n] z^{-n} \\
 &= \sum_{n=-\infty}^{\infty} nx[n] z^{-n} = -z \frac{dX(z)}{dz}
 \end{aligned}$$

Example 9:

$$\begin{aligned}
 a^n u[n] &\xleftrightarrow{\mathcal{Z}} \frac{1}{1 - az^{-1}} \\
 na^n u[n] &\xleftrightarrow{\mathcal{Z}} -z \frac{d}{dz} \left\{ \frac{1}{1 - az^{-1}} \right\} = z \frac{az^{-2}}{(1 - az^{-1})^2} = \frac{az^{-1}}{(1 - az^{-1})^2}
 \end{aligned}$$

Back to Partial Fraction Expansions: If  $d_k$  is a pole of multiplicity two, include two terms:

$$\begin{aligned}
 &A_{k_1} \frac{1}{1 - d_k z^{-1}} + A_{k_2} \frac{d_k z^{-1}}{(1 - d_k z^{-1})^2} \\
 &\quad \Downarrow \\
 &(A_{k_1} + A_{k_2} n) d_k^n u[n]
 \end{aligned}$$

Example 10:  $X(z) = \frac{-\frac{1}{2} + z^{-1}}{(1 - \frac{1}{2}z^{-1})^2} \quad \begin{matrix} M = 1 \\ N = 2 \end{matrix} \quad |z| > \frac{1}{2}$

$$= A_{11} \frac{1}{1 - \frac{1}{2}z^{-1}} + A_{12} \frac{\frac{1}{2}z^{-1}}{(1 - \frac{1}{2}z^{-1})^2}$$

$$= \frac{A_{11} + \frac{1}{2}(A_{12} - A_{11})z^{-1}}{(1 - \frac{1}{2}z^{-1})^2}$$

$$\left. \begin{matrix} A_{11} = -\frac{1}{2} \\ \frac{1}{2}(A_{12} - A_{11}) = 1 \end{matrix} \right\} A_{12} = \frac{3}{2}$$

$$x[n] = \left(-\frac{1}{2} + \frac{3}{2}n\right) \left(\frac{1}{2}\right)^n u[n]$$

Signal	Transform	ROC
$\delta[n]$	1	all $z$
$\delta[n - m]$	$z^{-m}$	all $z$ except $z = 0$ if $m > 0$ , all $z$ except $z = \infty$ if $m < 0$
$u[n]$	$\frac{1}{1 - z^{-1}}$	$ z  > 1$
$-u[-n - 1]$	$\frac{1}{1 - z^{-1}}$	$ z  < 1$
$a^n u[n]$	$\frac{1}{1 - az^{-1}}$	$ z  > a$
$-a^n u[-n - 1]$	$\frac{1}{1 - az^{-1}}$	$ z  < a$
$na^n u[n]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z  > a$
$-na^n u[-n - 1]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z  < a$
$\cos(\omega_0 n) u[n]$	$\frac{1 - \cos(\omega_0)z^{-1}}{1 - 2\cos(\omega_0)z^{-1} + z^{-2}}$	$ z  > 1$
$\sin(\omega_0 n) u[n]$	$\frac{\sin(\omega_0)z^{-1}}{1 - 2\cos(\omega_0)z^{-1} + z^{-2}}$	$ z  > 1$
$r^n \cos(\omega_0 n) u[n]$	$\frac{1 - r\cos(\omega_0)z^{-1}}{1 - 2r\cos(\omega_0)z^{-1} + r^2z^{-2}}$	$ z  > r$
$r^n \sin(\omega_0 n) u[n]$	$\frac{r\sin(\omega_0)z^{-1}}{1 - 2r\cos(\omega_0)z^{-1} + r^2z^{-2}}$	$ z  > r$

Table 1: z transforms of several functions.

### Properties of the z-Transform

1) Linearity:  $ax_1[n] + bx_2[n] \longleftrightarrow aX_1(z) + bX_2(z)$

ROC contains  $R_1 \cap R_2$  where  $R_i$  is the ROC of  $x_i[n]$ ,  $i = 1, 2$ .

2) Time Shifting:  $x[n - n_0] \longleftrightarrow z^{-n_0}X(z)$

ROC unchanged, except for possible addition/deletion of 0 and  $\infty$ .

Example 11: Find the inverse z-Transform (right-sided) of

$$X(z) = \frac{1}{z^{-1} \left(1 - \frac{1}{2}z^{-1}\right)} = z \frac{1}{1 - \frac{1}{2}z^{-1}}$$

$$x[n] = \left(\frac{1}{2}\right)^{n+1} u[n+1]$$

3) Scaling in the z-domain:

$$z_0^n x[n] \xleftrightarrow{\mathcal{Z}} X\left(\frac{z}{z_0}\right) \quad \text{ROC} = |z_0| \cdot R$$

where  $R$  is the ROC of  $x[n]$ . Compare to:

$$e^{j\omega_0 n} x[n] \xleftrightarrow{DTFT} X(e^{j(\omega - \omega_0)})$$

$$e^{s_0 t} x(t) \xleftrightarrow{\mathcal{L}} X(s - s_0) \quad \text{ROC} = R + \text{Re}\{s_0\}$$

4) Time Reversal:

$$x[-n] \xleftrightarrow{\mathcal{Z}} X\left(\frac{1}{z}\right) \quad \text{ROC} = 1/R$$

Example 12:

$$x[n] = \left(\frac{1}{2}\right)^n u[n] \leftrightarrow X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} \quad |z| > \frac{1}{2}$$

$$x[-n] = 2^n u[-n] \leftrightarrow X\left(\frac{1}{z}\right) = \frac{1}{1 - \frac{1}{2}z} = \frac{-2z^{-1}}{1 - 2z^{-1}} \quad |z| < 2$$

5) Convolution Property:

$$x_1[n] * x_2[n] \xleftrightarrow{\mathcal{Z}} X_1(z)X_2(z) \quad \text{ROC contains } R_1 \cap R_2$$

6) Differentiation in z-domain:

$$nx[n] \xleftrightarrow{\mathcal{Z}} -z \frac{dX(z)}{dz} \quad \text{ROC unchanged}$$

Proof and example on page 4.

7) Initial Value Theorem: If  $x[n] = 0$  for  $n < 0$ , then

$$x[0] = \lim_{z \rightarrow \infty} X(z)$$

Proof:  $X(z) = x[0] + \underbrace{x[1]z^{-1} + x[2]z^{-2} + \dots}_{\rightarrow 0 \text{ as } z \rightarrow \infty}$