→ Chapter 1

Preliminary Knowledge
Probability and Random Variables

Chap 1: Preliminary Knowledge

Outline

- 1.1 Probability Space
- 1.2 Random Variables
- 1.3 Moments of Random Variables
- 1.4 Special Distribution
- 1.5 Characteristic Functions

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1. Probability Space (Ω , F, P)

Sample Space: Ω

The set of all possible outcomes in any given experiments.

Borel Field(or σ Field) : F

The collection of all possible events from the sample space.

Probability: P

• P is a probability law (i.e. probability function $P(\cdot)$) that assigns a number to each event in F.

1. Probability Space (Ω , F, P)

Measurable Space:

The pair (Ω, F) is called a measurable space.

Probability Space:

The triple (Ω, F, P) is called a probability space.

2. Conditional Probability

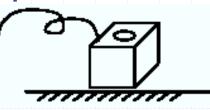
Def. The conditional event for A given B, A/B, is the event A under the stipulation that B has occurred.

Def. If A and B are events in F with P(B) ≠ 0, the conditional probability of A given B is

P(A/B)=P(AB)/P(B).

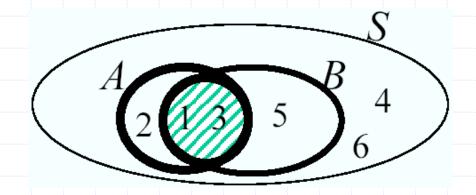
2. Conditional Probability

Examples:



$$A = \{1,2,3\}$$

 $B = \{1,3,5\}$

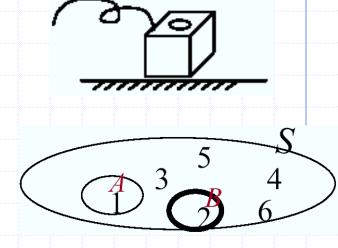


$$\rightarrow P(A/B) = \frac{P(AB)}{P(B)} = \frac{1/3}{1/2} = \frac{2}{3}$$

2. Conditional Probability

Properties:

(1)
$$AB = 0 \rightarrow P(A/B) = 0$$

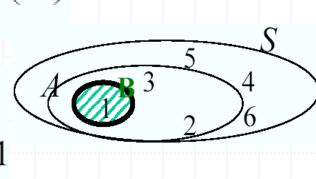


(2)
$$A \subset B \to A \cdot B = A$$

$$\to P(A / B) = \frac{P(A)}{P(B)} \ge P(A)$$

(3)
$$B \subset A \rightarrow AB = B$$

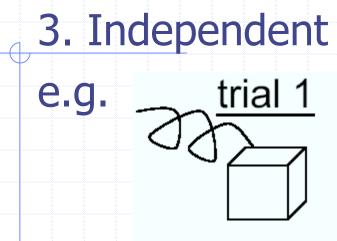
$$\rightarrow P(A/B) = \frac{P(B)}{P(B)} = 1$$



3. Independent

Def. Two events A & B are independent if P(AB)=P(A)P(B)

$$P(A/B) = \frac{P(AB)}{P(B)} = \frac{P(A)P(B)}{P(B)} = P(A)$$



$$S_1 = \{1, 2, 3, 4, 5, 6\}$$

 $A_1 = \{1\}$ $P(A_1) = \frac{1}{6}$

$$S_1 = \{1,2,3,4,5,6\}$$

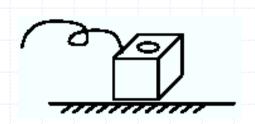
 $A_2 = \{1\}$ $P(A_2) = \frac{1}{6}$

If $A_1 \& A_2$ are independent, $P(A_1A_2) = P(A_1)P(A_2)$

3. Independent

The space of A_1A_2 is $S = S_1 \times S_2 = \{ (1,1), (1,2), (1,3), ..., (6,6) \}$ S is a new space.

Event A_1A_2 consisting of all ordered-pairs (S_{1i}, S_{2j}) , S_{1i} A_1 , S_{2i} A_2 is a subset of S.



3. Independent

$$e.g.1$$
 a single trial

$$A = \{1\}$$
 $B = \{2\}$

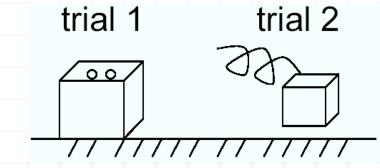
A & B are Mutually Exclusive Events

$$P(A/B) = \frac{P(AB)}{P(B)} = \frac{P(\phi)}{P(B)} = 0$$

e.g. 2 two trials

$$A = \{1\}$$
 $B = \{2\}$

A & B are Independent Events



$$P(A/B) = \frac{P(AB)}{P(B)} = \frac{P(A)P(B)}{P(B)} = P(A)$$

3. Independent

e.g. Given
$$P(A_1) = 1/2$$

 $P(A_2) = 1/4$
 $P(A_3) = 1/4$
 $P(A_1A_2) = 1/8$
 $P(A_1A_3) = 1/8$
 $P(A_2A_3) = 1/8$
 $P(A_1A_2A_3) = 1/32$

Are A₁, A₂& A₃ independent?

3. Independent

For events A_1 , A_2 , ..., A_n (which may or may not be independent), the probability of the simultaneous occurrence of the n events is

$$P(A_1A_2\cdots A_n) =$$
 $P(A_1)\cdot P(A_2/A_1)\cdot P(A_3/A_1A_2)\cdots P(A_n/A_1A_2...A_{n-1})$

• If events $A_1, A_2, ..., A_n$ are independent, then $P(A_1A_2 \cdots A_i) = P(A_1) \cdot P(A_2) \cdot \cdots P(A_i)$, i = 2,3,...n

4. Theorem of total probability

$$P(B) = P(B/A_1)P(A_1) + \dots + P(B/A_n) \cdot P(A_n)$$

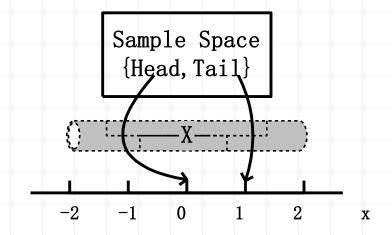
5. Bayes equation

? Help!

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<u>Def.</u> A real one value function of the elements of a sample space.



Obtained by mapping a sample space to real axis.

Discrete vs. Continuous random variables

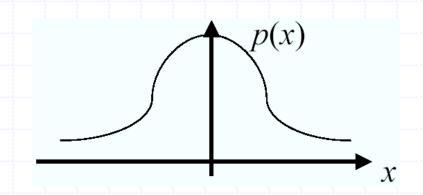
1. Probability Density Function (p.d.f.)

<u>Def:</u> Let x represent a continuous random variable in a sample space S. For each x we have a p.d.f. p(x) which is a function that satisfies the following:

$$1) p(x) \ge 0 \,\forall \, x \in S$$

$$2) \int p(x) dx = 1$$

$$3) \forall x_1 < x_2 \quad \text{in } S$$



The probability of

$$x \in [x_1, x_2] = P(x_1 \le x \le x_2) = \int_{x_1}^{x_2} p(x) dx$$

2. Probability Distribution Function

<u>Def:</u> The Probability Distribution Function $F(x_1)$ of a random variable X is the probability that X is less than or equal to x_1 ,

$$\mathsf{F}^{\mathsf{r}}(x_1) = \int_{-\infty}^{x_1} p(x) dx = P(x \le x_1)$$

2. Probability Distribution Function

Note:

The x in p(x) and F(x) is not a random variable but a value of the random variable X.

The p.d.f.p(x) is not a probability but a rate of change of the probability F(x), i.e. $\frac{d|F(x)|}{dx}$

The distribution function F(x) of random variable X is the probability that X has a value less than or equal to the value x.

3. p.d.f. of Linearly Combined Random Variables Let X_1, X_2, \ldots, X_n are n independent variables & $p_{x_1}(x_1), p_{x_2}(x_2), \ldots, p_{x_n}(x_n)$ are their p.d.f s respectively.

Let
$$Y1 = X_1 + X_2$$
, $Y2 = X_1 + X_2 + ... + X_n$

Then, the p.d.f of Y is

$$p_{y}(y) = p_{x_1} \otimes p_{x_2} \otimes \cdots \otimes p_{x_n}$$

4. Two-Dimensional Distributions

<u>Def.</u> The joint probability density function of two random variables X and Y is a function p(x,y) that possesses the properties

$$i)$$
 $p(x,y) \ge 0$

(ii)
$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p(x, y) \, dx \, dy = 1$$

iii)
$$P(x_1 \le x \le x_2, y_1 \le y \le y_2) = \int_{y_1}^{y_2} \int_{x_1}^{x_2} p(x, y) dx dy$$

4. Two-Dimensional Distributions

<u>Def.</u> The joint probability distribution function is

$$\mathsf{F}(x,y) = \int_{-\infty}^{y} \int_{-\infty}^{x} p(x,y) \, dx \, dy$$

so
$$p(x,y) = \frac{\partial^2 \mathbf{F}(x,y)}{\partial x \partial y}$$
.

<u>Def.</u> The random variables X and Y with p.d.f. $p_x(x)$ and $p_y(y)$ are independent if

$$p(x, y) = p_x(x) p_y(y)$$

4. Two-Dimensional Distributions

<u>Def.</u> The maginal probabiliy density functions of the variables *X* and *Y* are

$$p_X(x) = \int_{-\infty}^{\infty} p(x, y) dy \qquad p_Y(y) = \int_{-\infty}^{\infty} p(x, y) dx$$

<u>Def.</u> The maginal probability distribution functions are

$$F_X(x) = \int_{-\infty}^x p_X(x) dx = \int_{-\infty}^x \int_{-\infty}^\infty p(x, y) dy dx$$

$$F_Y(y) = \int_{-\infty}^{y} p_Y(y) dy = \int_{-\infty}^{y} \int_{-\infty}^{\infty} p(x, y) dx dy$$

4. Two-Dimensional Distributions *E.g.*

Find *k* for the 2D p.d.f.

$$p_{XY}(x, y) = \begin{cases} ke^{-2x-3y} & x \ge 0, y \ge 0\\ 0 & \text{otherwise} \end{cases}$$

Problems

Let X_1, X_2, \ldots, X_n are n independent variables

& $p_{x_1}(x_1)$, $p_{x_2}(x_2)$, ..., $p_{x_n}(x_n)$ are their p.d.fs respectively. Find the p.d.fs of

- (1) Y=min (X_1, X_2)
- (2) Y=max (X_1, X_2)
- (3) Y = h(X1)
- (4) Y1=h1(X1,X2)

Y2=h2(X1,X2)

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1. Moments

Def.1 The *n*th moment of p(x) (about the origin)

$$E\left[\mathbf{x}^{n}\right] = \int_{-\infty}^{\infty} x^{n} \cdot p(x) dx \qquad n = 1, 2, ...$$

*Def.*2 The *n*th moment of p(x) about the x_0

$$E\left[(\mathbf{x}-x_0)^n\right] = \int_{-\infty}^{\infty} (\mathbf{x}-x_0)^n \cdot p(\mathbf{x}) d\mathbf{x}$$

$$n = 1, 2, ...$$

(1) Expectation=Mean of X:

The first moment (n=1) (about the origin)

$$\overline{x} = E[x] = \int_{-\infty}^{\infty} x \cdot p(x) dx$$

expected value = mean value = ensemble average

(2) Mean square of X:

The second moment (*n*=2) (about the origin)

$$\overline{x^2} = E[x^2] = \int_{-\infty}^{\infty} x^2 \cdot p(x) dx$$

(3) Variance= second moment (n=2) (about the mean, i.e. central moment)

$$\sigma^{2} = Var(X)$$

$$= E[(X - E(X))^{2}] = E(X^{2}) - (E(X))^{2}$$

$$= \frac{1}{x^{2}} - \frac{1}{x^{2}}$$

(4) Standard Deviation = $\sqrt{\text{Var}(X)}$

2. Functions of Random Variable

• If g(X) is an arbitrary function of X, the expected value of g(X) is

$$E[\mathbf{g}(\mathbf{x})] = \int_{-\infty}^{\infty} g(x) \cdot p(x) dx$$

X and g(X) are continuous random variables.

3. Moments of 2-D p.d.f.

<u>Def.</u> The moments of a joint p.d.f. p(x,y) are called joint moments

$$\mu'_{i,j} = E[x^i y^j] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x^i y^j p(x,y) dx dy$$

where i, j = 0, 1, 2, 3, ..., and the order of $\mu'_{i,j}$ is i + j.

Note:
$$E[x] = \mu'_{1,0} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x^{i} p(x, y) dx dy$$

 $E[y] = \mu'_{0,1} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y^{j} p(x, y) dx dy$

- 3. Moments of 2-D p.d.f.
- If g(X, Y) is an arbitrary function of X and Y, the expected value of g(X, Y) is

$$E[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) p_{XY}(x,y) dxdy$$

X, Y and g(X, Y) are continuous random variables.

3. Moments of 2-D p.d.f.

<u>Def.</u> The central moments (i.e. moments about the mean) are

$$\mu_{ij} = \mathrm{E}[(x - \overline{x})^{i}(y - \overline{y})^{j}]$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \overline{x})^{i} (y - \overline{y})^{j} p(x, y) dx dy$$

where i, j = 0, 1, 2, 3, ..., and the order of μ_{ij} s i + j.

Note:

The moment μ_{11} is called the covariance of two variables.

3. Moments of 2-D p.d.f.

Covariance

$$\operatorname{Cov}(X,Y) = E[(X - E(X))(Y - E(Y))] = E(XY) - E(X)E(Y)$$

e.g.

Find: the three 2^{nd} order moments of the random variables X and Y.

4. Correlation

Correlation:

<u>Def.</u> The numerical measure of the similarity between X and Y is the normalised correlation coefficients and is defined as

$$\rho_{XY} = \frac{\text{Cov}(X,Y)}{\sqrt{\text{Var}(X)\text{Var}(Y)}}$$

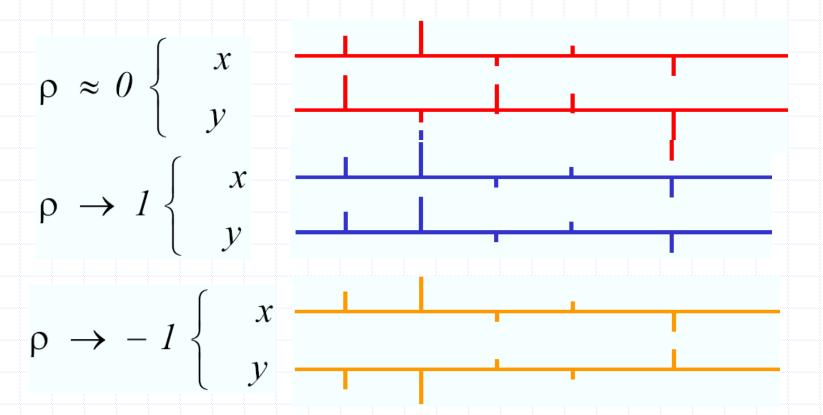
4. Correlation

Properties of Correlation:

- (i) ρ [-1, 1]
- (ii) $\rho=0$ if X and Y are uncorrelated (i.e. $\mu_{11}=0$ or Cov(X,Y)=0).

<u>Def:</u> Random variables X and Y are uncorrelated if $\rho = 0$ or $\mu_{11} = 0$ or Cov(X, Y) = 0.

4. Correlation



4. Correlation

Independent and Uncorrelated:

Theorem: If X and Y are statistically independent then they are uncorrelated.

e.g.

Given: X and Y are 2 independent random variables and U=X+Y, V=X-Y

Find: the condition under which *U* and *V* are uncorrelated.

5. If X and Y are independent then

$$\operatorname{Cov}(X,Y) = \rho_{XY} = 0$$

$$E(XY) = E(X)E(Y)$$

$$Var(X + Y) = Var(X) + Var(Y)$$

For any X and Y

$$E(X+Y) = E(X) + E(Y)$$

$$E(aX) = aE(X)$$

$$Var(aX) = a^2 Var(X)$$

$$\operatorname{Var}(X+Y) = \operatorname{Var}(X) + \operatorname{Var}(Y) + 2\operatorname{Cov}(X,Y)$$

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1.4 Special Distributions

- Discrete
 - Bernoulli
 - Binomial
 - Geometric
 - Poisson
- Continuous
 - Uniform
 - Exponential
 - Normal

1). Bernoulli Distribution "Single coin flip", p = Pr (success)

Let N = 1 if success, 0 otherwise

$$\Pr(N = n) = \begin{cases} p, & n = 1\\ 1 - p, & n = 0 \end{cases}$$

$$E(N) = p$$

$$Var(N) = p(1 - p)$$

2). Binomial Distribution
"n independent coin flips", p = Pr(success) N = k of successes

$$\Pr(N=k) = \binom{n}{k} p^k (1-p)^{n-k}, k = 0,1,...,n$$

$$E(N) = np$$

$$Var(N) = np(1-p)$$

3). Geometric Distribution

"independent coin flips" p = Pr(success)

N = k of flips until (including) first success

$$\Pr(N = k) = (1 - p)^{k-1} p, k = 1, 2, ...$$

$$E(N) = 1/p$$

$$Var(N) = (1 - p)/p^{2}$$

Memoryless property:

Have flipped *k* times without success.

$$Pr(N = k + n | N > k) = (1 - p)^{n-1} p$$
 (still geometric)

- 4). Poisson Distribution "Occurrence of rare events"

 λ = average rate of occurrence per period;

N = k of events in an arbitrary period

$$\Pr(N=k) = \frac{\lambda^k e^{-\lambda}}{k!}, k = 0,1,2,...$$

$$E(N) = \lambda$$

$$\operatorname{Var}(N) = \lambda$$

2. Continuous Distribution

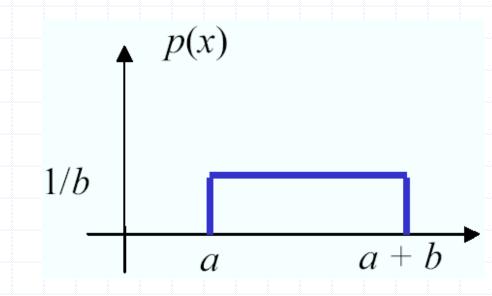
1) Uniform Distribution

Random variable X is equally likely to fall anywhere within interval (a, b).

$$f_X(x) = \frac{1}{b-a}, \quad a \le x \le b$$

$$E(X) = \frac{a+b}{2}$$

$$Var(X) = \frac{(b-a)^2}{12}$$



2. Continuous Distribution

2) Exponential Distribution

Random variable X is nonnegative and it is most likely to fall near 0.

$$f_X(x) = \lambda e^{-\lambda x}, \quad x \ge 0$$

$$F_X(x) = 1 - e^{-\lambda x}, \quad x \ge 0$$

$$E(X) = \frac{1}{\lambda}$$

$$\operatorname{Var}(X) = \frac{1}{\lambda^2}$$



Also memoryless
$$P\{x > s + t \mid x > s\} = P\{x > t\}$$

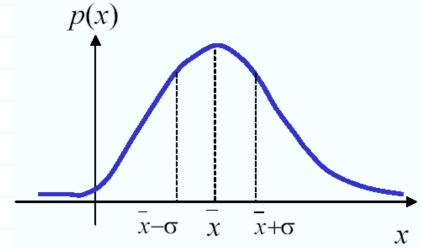
2. Continuous Distribution

3) Normal Distribution

X follows a "bell-shaped" density function

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}}e^{-(x-\mu)^2/2\sigma^2}, \quad -\infty < x < \infty$$

$$E(X) = \mu$$
$$Var(X) = \sigma^2$$



From the central limit theorem, the distribution of the sum of independent and identically distributed random variables approaches a normal distribution as the number of summed random variables goes to infinity.

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1. Definition
The characteristic function is defined as

$$\phi_X(t) = Ee^{itX}$$

where t is a real number and i is an imaginary unit.

$$\phi_X(t) = \begin{cases} \sum_{j \in S} e^{itx_j} P(x_j) & \text{for a discrete-type random} \\ \int_{S} e^{itx} f(x) dx & \text{for a continuous-type random} \\ & \text{variable} \end{cases}$$

where S stands for the sample space.

- 2. Properties of Characteristic Function
- (i) $\phi(t)$ always exist since $|e^{itx}|$ is a continuous and bounded function for all finite real values of t and x.

(ii)
$$\phi(0) = 1$$

(iii)
$$|\phi(t)| = |E[e^{itx}]| \le 1$$

(iv) $\phi(-t) = \phi^*(t)$, where $\phi^*(t)$ denotes the complex conjugate to $\phi(t)$

2. Properties of Characteristic Function

(v)
$$E[x^r] = \frac{1}{i^r} \phi^{(r)}(0)$$

- e.g. Obtain the mean and variance of the Bernoulli distribution whose probability mass function is given by $p(x) = p^x (1-p)^{1-x}$, where x = 0 or 1.
- (vi) X is a random variable. Y=aX+b, where a and b are constants. Then, the characteristic function of Y is

$$\phi_{y}(t) = e^{ibt}\phi_{x}(at)$$

2. Properties of Characteristic Function

(vii) The random variables X_1 , X_2 , ..., X_n are statistically independent. Let

$$Y = X_1 + X_2 + \ldots, + X_n$$

Then, the characteristic function of Y is

$$\phi_{y}(t) = \phi_{x_1}(t)\phi_{x_2}(t)\cdots\phi_{x_n}(t)$$

3. Theorems 1

◆ If *X* is a discrete-type random variable, its probability mass function p(x) can be obtained by

$$p(x) = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} \phi(t) e^{-itx} dt$$

If X is a continuous-type random variable, its probability density function p(x) can be obtained

$$p(x) = \frac{1}{2\pi} \int_{-T}^{T} \phi(t) e^{-itx} dt$$

where

$$\int_{-\infty}^{\infty} |\phi(t)| dt < \infty$$

4. Theorem 2 (Uniqueness Theorem)

Let X and Y be two random variables with characteristic functions $\phi_X(t)$ and $\phi_Y(t)$, respectively.

If $\phi_X(t) = \phi_Y(t)$ for all values of t, then X and Y have the same probability distribution.

Moment Generating Function

Definition

The moment generating function is defined as

$$M_X(t) = E[e^{tX}]$$

where *t* is a real number.

$$M_X(t) = \begin{cases} \sum_{j \in S} e^{tx_j} p(x_j) & \text{for a discrete-type random} \\ \int_{s} e^{tx} f(x) dx & \text{for a continuous-type random} \\ variable \end{cases}$$

where S stands for the sample space.

Generating Function and Probability Generating Function

• Let $\{a_n\}$ denote a sequence of numbers. The Generating Function for the sequence $\{a_n\}$ as

$$a^{g}(z) = \sum_{n=0}^{\infty} a_n z^n \qquad |z| < R$$

R is the convergence region.

Let X denote a discrete random variable and

$$a_n = P\{X=n\}$$

Then $P_X(z)=a^g(z)=E[z^X]$ is called the probability generating function for the random variable X.

Homework

- **1.1**
- **1.6**
- What is the characteristic function of an exponential random variable X? Find $E[X^3]$.
- What is the probability generating function of an binomial random variable?
- ♦ 1.15 (2nd book)

End of chapter 1