Chapter 2 Stochastic Processes

Chapter 2: Stochastic Processes

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2.4 Some Important Stochastic Processes

- 2.4.1 Gaussian(Normal) Processes
- 2.4.2 Independent Increment Processes
- 2.4.3 Wiener(-Levy) Processes
- 2.4.4 Markov Processes
- 2.4.5 Counting Processes
- 2.4.6 Poisson Processes
- 2.4.7 Bernoulli Processes
- 2.4.8 Narrow band Processes

2.4.1 Gaussian(Normal) Processes

(in 2.2.2 of textbook)

Def.1 Gaussian process

A stochastic process $\{x(t), t \in T\}$ is a Gaussian process if the random vectors

$$(X(t_1), X(t_2), ..., X(t_n))$$

have a joint Gaussian (Normal) distribution for all n-tuples $(t_1, t_2, ..., t_n)$ with $t_i \in T$ and $t_1 < t_2 < ... < t_n$; n = 1, 2, ...

2.4.1 Gaussian(Normal) Processes

Def. 1 Gaussian process based on a single sample wave

Precondition: the stochastic process satisfies the ergodic property.

A stochastic process $\{x(t), t \in T\}$ is a Gaussian process if for any given time t the random variable x(t) is normally distributed.

Gaussian process is a second-order moment process, as the existence of first-order moment and second-order moments.

2.1.3 Distribution and Density Functions

e.g.1.

Given: The stochastic process X(t) is given by $X(t)=Y_1+Y_2t$, t>0, whereas Y_1 and Y_2 are independent Gaussian random variables, with zero mean and variance σ^2

Obtain: one-dimensional distribution and two-dimensional distribution of X(t).

Sln:

$$\operatorname{Var}\{Y_1\} + \operatorname{Var}\{tY_2\} = \sigma^2 + t^2\sigma^2 = \sigma^2(1+t^2)$$

$$f_{X,1}(x;t) = \left[2\pi\sigma^2(1+t^2)\right]^{-1/2} \exp\{-x^2/[2\sigma^2(1+t^2)]\}$$

$$f_{X,Y}(u_{\downarrow}v) =$$

$$\underbrace{\exp\left\{\frac{-1}{2(1-\rho^2)}\left[\left(\frac{u-\mu_1}{\sigma_1}\right)^2-2\rho\left(\frac{u-\mu_1}{\sigma_1}\right)\left(\frac{v-\mu_2}{\sigma_2}\right)+\left(\frac{v-\mu_2}{\sigma_2}\right)^2\right]\right\}}$$

 $2\pi\sigma_1\sigma_2\sqrt{(1-\rho^2)}$

2.1.3 Distribution and Density Functions

$$\operatorname{Var}\{X(t_{k})\} = \sigma^{2}(1 + t_{k}^{2})$$

$$\operatorname{Cov}\{X(t_{1}), X(t_{2})\} = E\{X(t_{1})X(t_{2})\}$$

$$= E\{(Y_{1} + t_{1}Y_{2})(Y_{1} + t_{2}Y_{2})\}$$

$$= \sigma^{2} + t_{1}t_{2}\sigma^{2} = \sigma^{2}(1 + t_{1}t_{2})$$

$$\rho(t_{1}, t_{2}) = \frac{\operatorname{Cov}\{X(t_{1}), X(t_{2})\}}{\sqrt{\operatorname{Var}\{X(t_{1})\}\operatorname{Var}\{X(t_{2})\}}} = \frac{1 + t_{1}t_{2}}{[(1 + t_{1}^{2})(1 + t_{2}^{2})]^{1/2}}$$

$$f_{X,2}(x_{1}, x_{2}; t_{1}, t_{2}) =$$

$$\exp\{-[(1 + t_{2}^{2})x_{1}^{2} - 2(1 + t_{1}t_{2})x_{1}x_{2} + (1 + t_{1}^{2})x_{2}^{2}]/[2\sigma^{2}(t_{1} - t_{2})^{2}]\}$$

 $2\pi\sigma^2|t_1-t_2|$

2.4.1 Gaussian(Normal) Processes

One/two-dimensional distributions:

- The distribution can be decided by mean values $E[X(t_1)]$ and $E[X(t_2)]$ and covariance function $C_{XX}(t_1,t_2)$ or correlation function $R_{XX}(t_1,t_2)$
- n-dimensional distribution:

$$\begin{split} E[X(t_i)], & 1 \leq i \leq n \\ Cov_{XX}(t_i, t_i) & or & R_{XX}(t_i, t_i), & 1 \leq i \leq n, 1 \leq j \leq n \end{split}$$

A Gaussian random process is completely specified by its mean and correlation functions.

2.4.1 Gaussian(Normal) Processes

- If a Gaussian process is weakly stationary, it is also strictly stationary.
- The significance of Gaussian process

 The Gaussian process plays a significant role in stochastic analysis of random phenomena observed in natural sciences, since many random phenomena can be approximately represented by a normal process.

2.4 Some Important Stochastic Processes

- 2.4.1 Gaussian(Normal) Processes
- 2.4.2 Independent Increment Processes
- 2.4.3 Wiener(-Levy) Processes
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Increments

the increment of a stochastic process $\{X(t), t \in T\}$ with respect to the interval $[t_1, t_2]$ is the difference $X(t_2) - X(t_1)$.

Def. 1 Independent Increment Process

A stochastic process X(t) is said to be an independent increment process if $X(t_{i+1}) - X(t_i)$, where i=0,1,2,..., is statistically independent . (and thereby statistically uncorrelated).

Def.2 Stationary Increment Process

A stochastic process X(t) is said to be a stationary increment process if its increments $X(t_2 + \tau) - X(t_1 + \tau)$ have the same probability distribution for all τ with $t_1 + \tau \in T$, $t_2 + \tau \in T$; t_1, t_2 fixed, but arbitrary.

Def.2 Stationary Increment Process

an equivalent definition:

A stochastic process X(t) is said to be a stationary increment process if the probability distribution of $X(t+\tau)-X(t)$ does not depend on t for any fixed τ ; $t,t+\tau\in T$

A stochastic process with stationary increments need not be stationary in any sense.(strictly or weakly)

Def.3

Stationary Independent Increment Process

A stochastic process X(t) which possess both stationary as well as independent increments properties is called a stationary independent increment process.

e.g.1.

Given: X(t) is an independent increment process, $X(t_0)=0$.

Prove: Its autocovariance function is equal to variance function.

SIn:

$$C_{XX}(t_1, t_2) = Var(X(t_1))$$

$$C_{XX}(t_1, t_2) = Var(X(t_2))$$
 ?

2.4 Some Important Stochastic Processes

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2.4.3 Wiener(-Levy) Processes

(Brownian motion process)

A special Gaussian process.

Def.1 Wiener-Levy process a stochastic process X(t) is said to be a Wiener-Levy process if

- (i) X(t) has stationary independent increment.
- (ii) Every independent increment is normally distributed.
- (iii) E[X(t)]=0 for all time.
- (iv) X(0)=0.

2.4.3 Wiener(-Levy) Processes

◆Increments distribution of a Wiener process

$$X(t_2) - X(t_1) \sim N(0, \sigma^2 | t_2 - t_1 |)$$

The distribution of a Wiener process

$$X(t) \sim N(0, \sigma^2 |t|)$$

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2.4.4 Markov Processes

Def.1 Markov Process

A stochastic process X(t) is said to be a Markov process if it satisfies the following conditional probability:

$$Pr\{x(t_n) \le x_n | x(t_1) = x_1, x(t_2) = x_2, \dots, x(t_{n-1}) = x_{n-1}\}\$$

$$= Pr\{x(t_n) = x_n | x(t_{n-1}) = x_{n-1}\}, \quad \text{where } t_1 < t_2 < \dots < t_{n-1} < t_n$$

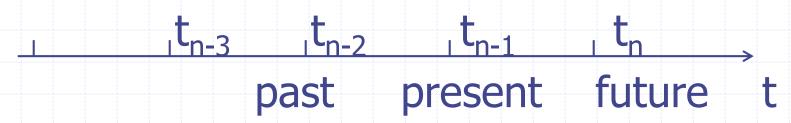
(Markovian property)

2.4.4 Markov Processes

The Markovian property has the following implication:

If t_n is a time point in the future, t_{n-1} the present time, and correspondingly t_1 , t_2 ,..., t_{n-2} , time points in the past,

the future development of a process does not depend on its evolvement in the past, but only on its present state.



2.4.4 Markov Processes

Independent increment process V.S.

Markov process

Every independent increment process is a Markov process, although there are many Markov processes that do not have independent increments.

2.4 Some Important Stochastic Processes

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2.4.5 Counting Processes

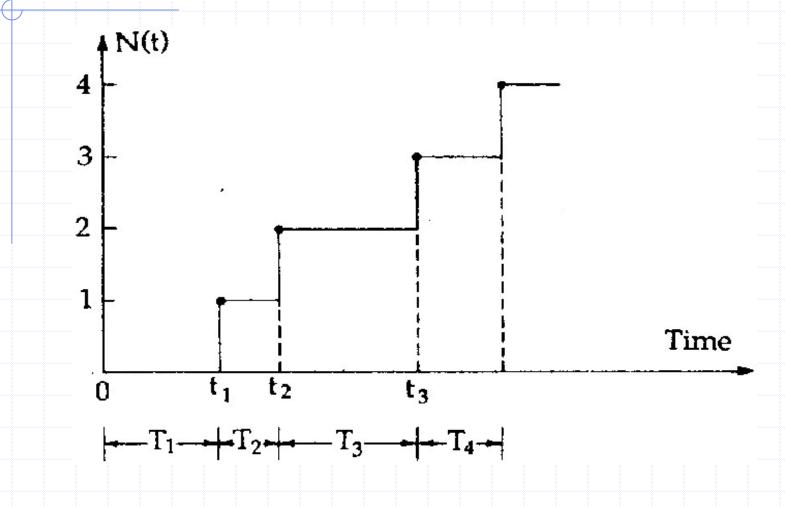
Counting processes deal with the frequency of occurrence of random events.

Def. 1 Counting Process

An integer-valued continuous-time stochastic process N(t) is called a counting process of the series of events if N(t) represents the total number of occurrences of the event in the time interval t=0 to t.

2.4.5 Counting Processes

A sample wave of a counting process N(t)



 $T_1=t_1, T_2=t_2-t_1, T_3=t_3-t_2, \dots$ Interarrival times

2.4.5 Counting Processes

If the interarrival times are independent, identically distributed random variables, then the process is called a renewal process.

If the interarrival times (are independent, identically distributed random variables) obey an exponential distribution, the process is called a Poisson process.

2.4 Some Important Stochastic Processes

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1.2 An Example of Random Processes

1.2.1 Poisson Distribution

"Occurrence of events"

 λ = average rate of occurrence per second;

N = the number of occurrences of an event in an arbitrary period.

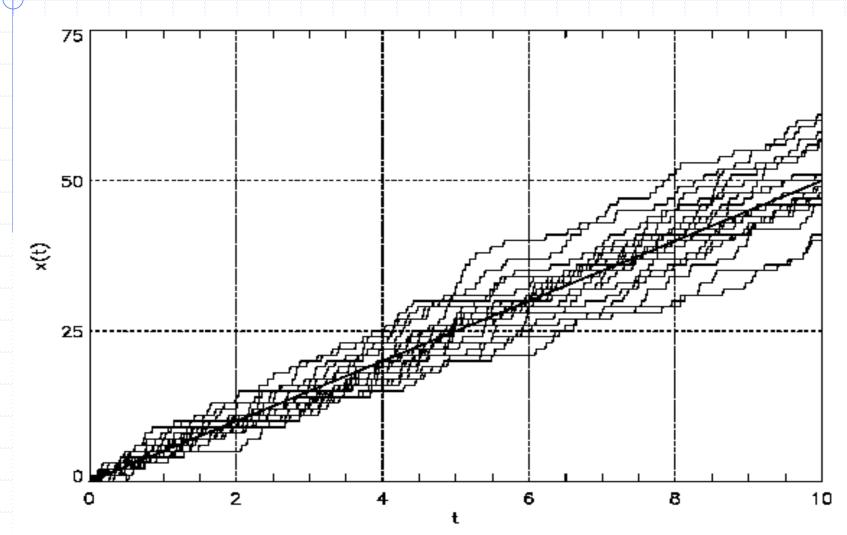
$$\Pr(N=k) = \frac{\lambda^k e^{-\lambda}}{k!}, k = 0, 1, 2, ...$$

$$E(N) = \lambda$$

$$\operatorname{Var}(N) = \lambda$$

$$Cv_N^2 = 1/\lambda$$

Sample waves of a Poisson process



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Def.1 Poisson process

A counting process N(t) is said to be a Poisson process with mean rate (or intensity) λ if

- (i) N(0)=0.
- (ii) N(t) has stationary independent increment.
- (iii) The number in any time interval of length τ is Poisson distributed with mean $\lambda \tau$, That is,

$$P\{N(t+\tau)-N(t)=k\}=\frac{(\lambda\tau)^k}{k!}e^{-\lambda\tau}$$

Both Wiener process and Poisson process have stationary independent increment.

- $N(t+\tau)-N(t)$ is called a Poisson increment process.
 - ightharpoonup Let $X(t) = N(t+\tau) N(t)$

$$E[X(t)] = E[N(t+\tau)] - E[N(t)] = \lambda(t+\tau) - \lambda t = \lambda \tau$$

$$C_{XX}(t_1, t_2) = \begin{cases} Var_X(t_1 + \tau - t_2) & for \ 0 < t_2 - t_1 < \tau \\ 0 & otherwise \end{cases}$$

$$= \begin{cases} Var_X(\tau - u) & for \ 0 < t_2 - t_1 < \tau \\ 0 & otherwise \end{cases}$$

where $u = t_2 - t_1$

The Poisson increment process is covariance stationary.

Another definition of Poisson process

A counting process N(t) is said to be a Poisson process with mean rate λ if

- (i) N(0)=0.
- (ii) N(t) has stationary independent increment.
- (iii) N(t) satisfies

$$P{X(t+h)-X(t)=1} = \lambda h + o(h)$$

$$P{X(t+h)-X(t) \ge 2} = o(h)$$

A function f() is said to be o(h) if $\lim_{h\to 0} \frac{f(h)}{h} = 0$

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2.4.7 Bernoulli Processes

Def.1 Bernoulli process

consider a series of independent repeated trials with two outcomes: success and failure, rain and no rain, and so on.

A counting process X_n is called a Bernoulli process if X_n represents the number of successes in n trials.

2.4.7 Bernoulli Processes

$$\begin{bmatrix} outcomes \\ probability \end{bmatrix} = \begin{bmatrix} success & failure \\ p & q \end{bmatrix}$$

the probability of *k* successes in *n* trials is given by the following binomial distribution:

$$P(X_n = k) = \binom{n}{k} p^k q^{n-k}$$

$$p + q = 1 \quad k = 1, 2, ..., n; \quad n = 1, 2, ...$$

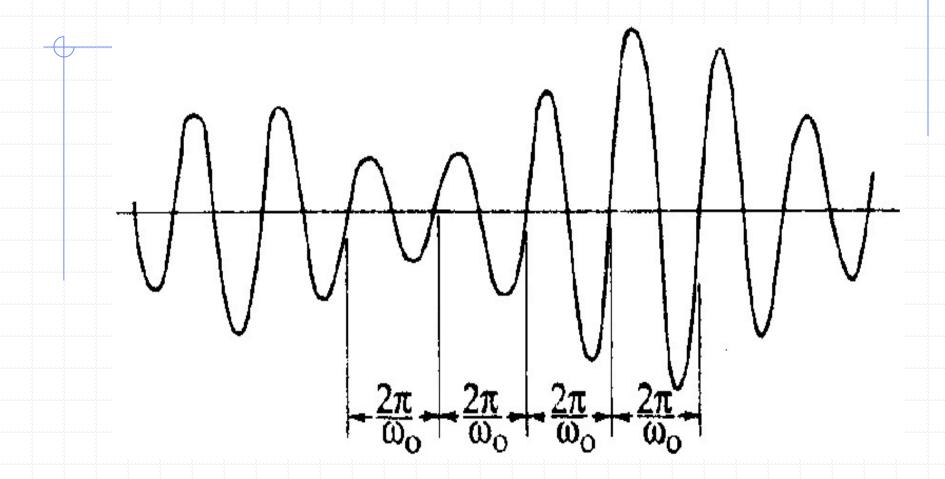
2.4.7 Bernoulli Processes

Poisson process and Bernoulli process are counting process.

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2.4.8 Narrow-Band Processes



Example of narrow-band process

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2.4.8 Narrow-Band Processes

Def.1 Narrow-Band Process

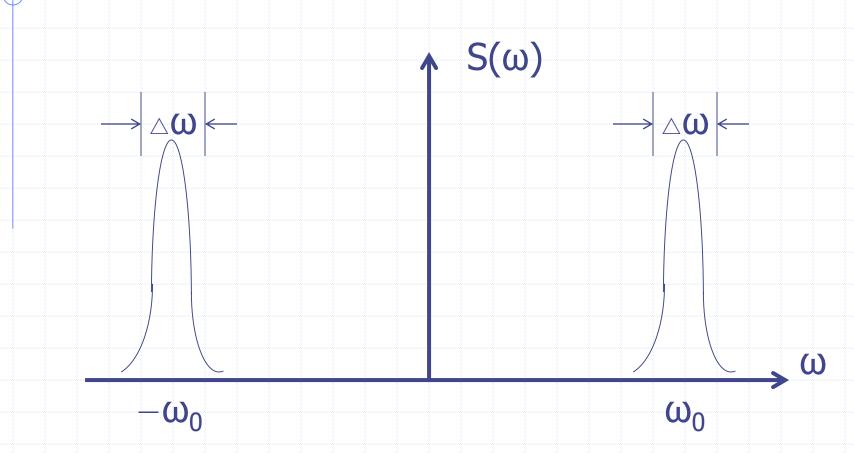
A continuous-state and continuous-time stationary stochastic process X(t) is called a narrow-band process if X(t) can be expressed by

$$X(t) = A(t)\cos\{\omega_0 t + \varepsilon(t)\}\$$

Where ω_0 =constant. The amplitude A(t) and the phase $\varepsilon(t)$ are random variables whose sample spaces are $0 \le A(t) < \infty$ and $0 \le \varepsilon(t) \le 2\pi$ respectively.

2.4.8 Narrow Band Processes

Typical spectrum of a narrow band signal

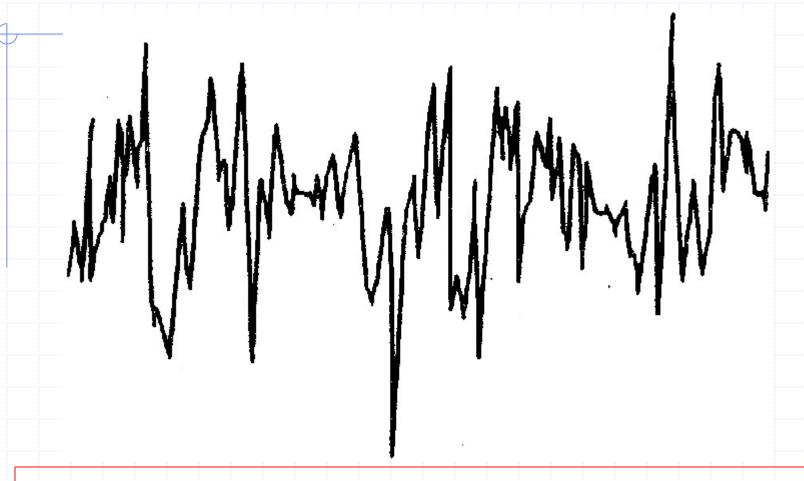


2.4.8 Narrow Band Processes

Wide-Band Processes

A stochastic process that does not satisfy the condition of narrow-band process is called a non-narrow-band or wide-band process.

2.4.8 Narrow Band Processes



Example of a wide-band process

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Homework

Self learning: Complex stochastic processes

Find

- 1. what is complex stochastic process?
- 2. What are it's moments?
- 3. What are the covariance function's properties of a complex stochastic process?

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