

# Lecture 15

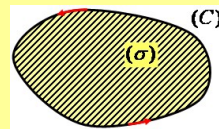
## Gauss' Formula and Stokes' Formula

## Green's Theorem

**Theorem** Suppose there is a **closed** bounded domain  $(\sigma) \subset \mathbb{R}^2$  bounded by a piecewise smooth simple curve  $(C)$ , and functions  $P(x, y), Q(x, y) \in C^{(1)}((\sigma))$ . Then the following relation holds:

$$\iint_{(\sigma)} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) d\sigma = \oint_{(+C)} [P(x, y) dx + Q(x, y) dy],$$

where  $(+C)$  indicates that the integration is in the positive direction of  $(C)$ .



## Gauss' Formula

### Theorem Gauss' Theorem

Suppose that a region  $(V)$  in space is bounded by a piecewise smooth **closed** simple surface  $(S)$ , and  $P(x, y, z), Q(x, y, z), R(x, y, z) \in C^{(1)}((V))$ .

$$\text{Then } \iiint_{(V)} \left( \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) dV = \iint_{(+S)} P dy dz + Q dz dx + R dx dy,$$

where  $(+S)$  denote the normal vector of  $(S)$  pointing to the outside of  $(V)$ .

The Gauss' Theorem gives the relationship between a triple integral over a region  $(V)$  in space and a surface integral of the second type over the boundary surface  $(S)$  of the region  $(V)$ .

## Gauss' Formula

**Proof.** We only prove that

$$\iiint_{(V)} \frac{\partial R}{\partial z} dV = \iint_{(+S)} R dx dy$$

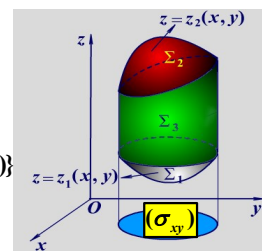
(1) Suppose that the region is

$$V = \{(x, y, z) \mid z_1(x, y) \leq z \leq z_2(x, y), (x, y) \in (\sigma_{xy})\}$$

$$\begin{aligned} \iiint_{(V)} \frac{\partial R}{\partial z} dV &= \iint_{(\sigma_{xy})} d\sigma \int_{z_1(x, y)}^{z_2(x, y)} \frac{\partial R}{\partial z} dz \\ &= \iint_{(\sigma_{xy})} \{R(x, y, z_2(x, y)) - R(x, y, z_1(x, y))\} d\sigma \end{aligned}$$

(2) For the surface integral  $\iint_{(+S)} R dx dy = \iint_{\Sigma_2} R dx dy + \iint_{\Sigma_3} R dx dy + \iint_{\Sigma_1} R dx dy$

$$\iint_{(+S)} R dx dy = \iint_{(\sigma_{xy})} R(x, y, z_2(x, y)) d\sigma + 0 + \iint_{(\sigma_{xy})} -R(x, y, z_1(x, y)) d\sigma$$



## Gauss' Formula

**Note:**

$$\iint_{(+S)} \vec{F} \cdot d\vec{S} = \iint_{(+S)} \vec{F} \cdot \vec{e}_n dS = \iint_{(S)} (P, Q, R) \cdot \vec{e}_n dS$$

$$= \iint_{(S)} (P \cos \alpha + Q \cos \beta + R \cos \gamma) dS$$

$$= \iint_{(S)} P dy dz + Q dz dx + R dx dy$$

$$= \iiint_{(V)} \left( \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) dV = \iiint_{(V)} \nabla \cdot \vec{F} dV, \quad \nabla = \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right).$$

where the normal vector of  $(S)$  points the outside of  $(V)$ .  $\alpha, \beta, \gamma$  are the angles between the outward normal vector at  $(x, y, z)$  on the surface and the three axes.

## Gauss' Theorem

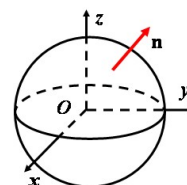
**Example 1** Evaluate the surface integral  $I = \iint_{(S)} x^3 dy dz + y^3 dz dx + z^3 dx dy$  where  $(S)$  is: (1) the outside of the sphere  $x^2 + y^2 + z^2 = R^2$ .

(2) the upper side of the upper hemisphere  $z = \sqrt{R^2 - x^2 - y^2}$ .

**Solution (1)** Suppose that the region bounded by  $(S)$  is  $(V)$ .

According to the Gauss' theorem

$$\begin{aligned} I &= \iiint_{(V)} 3(x^2 + y^2 + z^2) dV \\ &= 3 \int_0^{2\pi} d\theta \int_0^\pi \sin \varphi d\varphi \int_0^R r^4 dr = \frac{12}{5} \pi R^5 \end{aligned}$$



## Gauss' Theorem

**Example 1** Evaluate the surface integral  $I = \iint_{(S)} x^3 dydz + y^3 dzdx + z^3 dxdy$  where  $(S)$  is: (1) the outside of the sphere  $x^2 + y^2 + z^2 = R^2$ .

(2) the upper side of the upper hemisphere  $z = \sqrt{R^2 - x^2 - y^2}$ .

**Solution (II)** The surface  $(S)$  is not closed. We adjoin the circular surface  $(S_1): z = 0, x^2 + y^2 \leq R^2$  with downward normal.

According to the Gauss' theorem

$$\begin{aligned} & \iint_{(S)} x^3 dydz + y^3 dzdx + z^3 dxdy + \iint_{(S_1)} x^3 dydz + y^3 dzdx + z^3 dxdy \\ &= \iiint_{(V)} 3(x^2 + y^2 + z^2) dV = \frac{6}{5} \pi R^5 \\ & \iint_{(S_1)} x^3 dydz + y^3 dzdx + z^3 dxdy = 0 + 0 - \iint_{(S_1)} 0^3 dxdy = 0 \end{aligned}$$

$$\text{Therefore } I = \frac{6}{5} \pi R^5 - 0 = \frac{6}{5} \pi R^5$$

## Gauss' Theorem

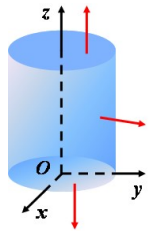
**Example 2** Evaluate  $I = \oint_{\Sigma} (x-y) dxdy + (y-z) xdydz$ , where  $\Sigma$  is the outside of the surface of the cylinder  $x^2 + y^2 = 1$  and  $z = 0, z = 3$ .

**Solution** Since  $P = (y-z)x, Q = 0, R = x-y$ , we have

$$\frac{\partial P}{\partial x} = y-z, \quad \frac{\partial Q}{\partial y} = 0, \quad \frac{\partial R}{\partial z} = 0.$$

Therefore, by the Gauss' Theorem, we obtain

$$\begin{aligned} I &= \iiint_{(V)} (y-z) dxdydz \\ &= \int_0^{2\pi} d\theta \int_0^1 d\rho \int_0^3 (\rho \sin \theta - z) \rho dz = -\frac{9\pi}{2}. \end{aligned}$$

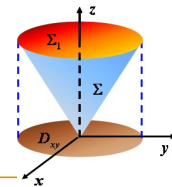


## Gauss' Theorem

**Example 3.** Evaluate  $I = \iint_{\Sigma} (x^2 \cos \alpha + y^2 \cos \beta + z^2 \cos \gamma) dS$ , where  $\Sigma$  is the surface of the cone  $x^2 + y^2 = z^2$  between  $z = 0$  and  $z = h (h > 0)$ , and  $\alpha, \beta, \gamma$  are the angles between the normal vector oriented downward at  $(x, y, z)$  on the surface and the three axes.

**Solution** By adding an additional plane  $\Sigma_1: z = h, (x, y) \in D_{xy}: x^2 + y^2 \leq h^2$  with upperward norm, we can use the Gauss' Theorem.

$$\begin{aligned} & \iint_{\Sigma + \Sigma_1} (x^2 \cos \alpha + y^2 \cos \beta + z^2 \cos \gamma) dS \\ &= \iint_{\Sigma + \Sigma_1} x^2 dy \wedge dz + y^2 dz \wedge dx + z^2 dx \wedge dy \\ &= 2 \iiint_{(V)} (x + y + z) dV, \end{aligned}$$



## Gauss' Theorem

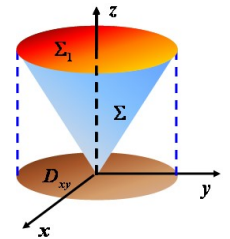
**Solution (continued)** By the symmetry, we know that  $\iiint_{(V)} (x + y) dV = 0$ ,

then  $\iint_{\Sigma + \Sigma_1} (x^2 \cos \alpha + y^2 \cos \beta + z^2 \cos \gamma) dS = 2 \iiint_{(V)} (x + y + z) dV$

$$= 2 \iiint_{(V)} z dV = 2 \int_0^{2\pi} d\theta \int_0^h \rho d\rho \int_0^h z dz = \frac{1}{2} \pi h^4.$$

Moreover, since

$$\begin{aligned} & \iint_{\Sigma} (x^2 \cos \alpha + y^2 \cos \beta + z^2 \cos \gamma) dS \\ &= \iint_{\Sigma} z^2 dx \wedge dy = \iint_{D_{xy}} h^2 d\sigma = \pi h^4, \\ & \text{we have } I = \frac{1}{2} \pi h^4 - \pi h^4 = -\frac{1}{2} \pi h^4. \end{aligned}$$



## Flux and Flux Density

Suppose that  $\vec{F}$  be a vector field on  $(G) \subseteq \mathbb{R}^3$  and  $(S)$  be a directed surface in  $(G)$ . Then the **flux** of the fluid passing through the surface  $(S)$  to the given side is

$$\Phi = \iint_{(S)} \vec{F} \cdot d\vec{S} = \iint_{(S)} P dydz + Q dzdx + R dxdy$$

**Flux density** is defined as  $\lim_{(\Delta V) \rightarrow M} \frac{\Delta \Phi}{\Delta V} = \lim_{(\Delta V) \rightarrow M} \frac{1}{\Delta V} \iint_{(\Delta S)} \vec{F} \cdot d\vec{S}$

## Divergence

**Definition (Divergence)**

Consider a continuous vector field  $\vec{F}$  defined on  $(V) \subseteq \mathbb{R}^3$  and construct an arbitrary closed surface  $(\Delta S) \subseteq (V)$  in the neighborhood of  $M$  which contains the point  $M$  with normal vector of  $(\Delta S)$  pointing outwards. The region bounded by  $(\Delta S)$  is denoted by  $(\Delta V)$  with volume  $\Delta V$ . If the limit of the ratio  $\frac{\Delta \Phi}{\Delta V} = \frac{1}{\Delta V} \iint_{(\Delta S)} \vec{F} \cdot d\vec{S}$  exists when  $(\Delta V)$  shrinks to the points  $M$  in any way, then this limiting value is said to be the **divergence** of  $\vec{F}$  at the point  $M$ , denoted by  $\text{div} \vec{F}(M) = \lim_{(\Delta V) \rightarrow M} \frac{1}{\Delta V} \iint_{(\Delta S)} \vec{F} \cdot d\vec{S}$ .

## Computation of Divergence

Construct a rectangular coordinate system and let

$$\vec{F} = (P(x, y, z), Q(x, y, z), R(x, y, z)) \quad \text{div} \vec{F}(M) = \lim_{(\Delta V) \rightarrow M} \frac{\Delta \Phi}{\Delta V}$$

where  $P, Q, R \in C^{(1)}$ . Then according to the definition of the flux, Gauss' formula and the mean value theorem for the integral, we have

$$\begin{aligned} \Delta \Phi &= \iint_{(\Delta S)} \vec{F} \cdot d\vec{S} = \iint_{(\Delta S)} P dydz + Q dzdx + R dx dy \\ &= \iiint_{(\Delta V)} \left( \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) dV = \left( \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right)_{M^*} \Delta V \end{aligned}$$

$$\text{Therefore, } \text{div} \vec{F}(M) = \lim_{(\Delta V) \rightarrow M} \frac{1}{\Delta V} \iint_{(\Delta S)} \vec{F} \cdot d\vec{S} = \left( \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right)_{M^*}$$

## Computation of Divergence

The divergence of a vector field

$$\vec{F}(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$$

is the scalar function

$$\text{div} \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = \nabla \cdot \vec{F}$$

Flux of a vector field  $\vec{F}$  across a closed oriented surface  $(S)$

$$\iint_{(+S)} \vec{F} \cdot d\vec{S} = \iint_{(+S)} \vec{F} \cdot \vec{e}_n dS = \iiint_{(V)} \nabla \cdot \vec{F} dV = \iiint_{(V)} \text{div} \vec{F} dV, \quad \vec{F} = (P, Q, R)$$

**Example 4** Find the divergence of  $\vec{F}(x, y, z) = 2xz\mathbf{i} - xy\mathbf{j} - zk$ .

**Solution** The divergence of  $\vec{F}$  is

$$\nabla \cdot \vec{F} = \frac{\partial}{\partial x}(2xz) + \frac{\partial}{\partial y}(-xy) + \frac{\partial}{\partial z}(-z) = 2z - x - 1.$$

## Stokes' Theorem

**Theorem Stokes' Theorem**

Suppose  $P, Q, R \in C^{(1)}(G)$  and  $(C)$  is a piecewise smooth directed simply closed curve, and  $(S)$  is a piecewise smooth oriented surface in  $G$  whose boundary is  $(C)$ , and the direction of  $(C)$  and the normal vector of the surface  $(S)$  accord with the right-hand rule. Then

$$\begin{aligned} \oint_{(C)} P dx + Q dy + R dz &= \iint_{(S)} \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) dydz + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) dzdx + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy \\ &= \iint_{(S)} \begin{vmatrix} dydz & dzdx & dx dy \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \end{aligned}$$

## Stokes' Theorem

**Theorem Stokes' Theorem**

The circulation of a vector field  $\vec{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$  around the boundary  $(C)$  of an oriented surface  $(S)$  in the direction counterclockwise with respect to the surface's unit normal vector  $\vec{e}_n$  equals the integral of  $\nabla \times \vec{F} \cdot \vec{e}_n$  over surface  $(S)$ .

Counterclockwise  
circulation

$$\oint_{(C)} \vec{F} \cdot d\vec{s} = \iint_{(S)} \nabla \times \vec{F} \cdot \vec{e}_n dS \quad \text{Curl Integral}$$

circulation density

**Note** If two different oriented surface  $(S_1)$  and  $(S_2)$  have the same boundary  $(C)$ , their curl integral are same.

## Green's Theorem versus Stokes' Theorem

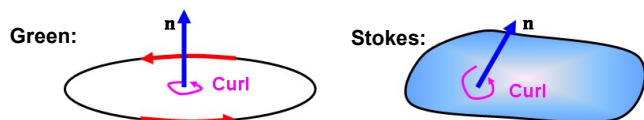
If  $(C)$  is a curve in the  $xy$ -plane, oriented counterclockwise, and  $(\sigma)$  is the region in the  $xy$ -plane bounded by  $(C)$ , then  $dS = d\sigma = dx dy$  and

$$(\nabla \times \vec{F}) \cdot \vec{e}_n = (\nabla \times \vec{F}) \cdot \vec{k} = \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right).$$

Under these conditions, Stokes' equation becomes

$$\oint_{(C)} P dx + Q dy = \oint_{(C)} \vec{F} \cdot d\vec{s} = \iint_{(S)} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dS = \iint_{(\sigma)} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy.$$

**Green's Theorem**



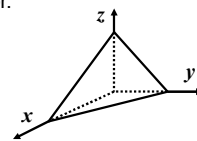
## Find Line Integral by Stokes' Theorem

**Example 5** Find  $\oint_{\Gamma} z dx + x dy + y dz$  where  $\Gamma$  cuts from the plane  $x + y + z = 1$  by the three coordinates plane and its positive direction has right-hand relation with the normal up vector.

**Solution** By Stokes' Theorem, we have

$$\begin{aligned} \oint_{\Gamma} z dx + x dy + y dz &= \iint_{\Sigma} \begin{vmatrix} dydz & dzdx & dx dy \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ z & x & y \end{vmatrix} \\ &= \iint_{\Sigma} dydz + dzdx + dx dy \end{aligned}$$

**Method I** By the symmetry, we have  $\iint_{\Sigma} dydz + dzdx + dx dy = 3 \iint_{(\sigma_{xy})} d\sigma = \frac{3}{2}.$



## Find Line Integral by Stokes' Theorem

**Solution(Cont.) Method II**  $\vec{e}_n = \frac{1}{\sqrt{3}}(1, 1, 1), z = 1 - x - y, z_x = z_y = -1,$

$$\iint_{\Sigma} dydz + dzdx + dx dy = \iint_{\Sigma} \sqrt{3} dS = 3 \iint_{(\sigma_{xy})} d\sigma = \frac{3}{2}$$

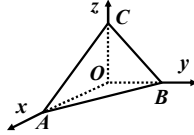
**Method III**  $\iint_{\Sigma} dydz + dzdx + dx dy = \iint_{(\sigma_{yz})} d\sigma + \iint_{(\sigma_{xz})} d\sigma + \iint_{(\sigma_{xy})} d\sigma = \frac{3}{2}$

**Method IV**

$\overline{AB}: y = 1 - x, x: 1 \rightarrow 0; \overline{BC}: z = 1 - y, y: 1 \rightarrow 0; \overline{CA}: x = 1 - z, z: 1 \rightarrow 0;$

$$\oint_{\Gamma} z dx + x dy + y dz = \left( \int_{\overline{AB}} + \int_{\overline{BC}} + \int_{\overline{CA}} \right) z dx + x dy + y dz$$

$$= \int_1^0 x(-1)dx + \int_1^0 y(-1)dy + \int_1^0 z(-1)dz = \frac{3}{2}.$$



## Curl (Rotation)

If the velocity field is  $\vec{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$

Define  $\text{curl } \vec{F} = \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}.$

If we let  $\nabla = \mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z},$

the  $\text{curl } \vec{F}$  is  $\nabla \times \vec{F}:$

$$\nabla \times \vec{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} = \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k} = \text{curl } \vec{F}.$$

$$\oint_{(C)} \vec{F} \cdot d\vec{s} = \iint_{(S)} \nabla \times \vec{F} \cdot \vec{e}_n dS = \iint_{(S)} \nabla \times \vec{F} \cdot d\vec{S} = \iint_{(S)} \text{curl } \vec{F} \cdot d\vec{S}$$

## Curl ( Rotation )

**Example 6** Find the curl of  $\vec{F} = (x^2 - y)\mathbf{i} + 4z\mathbf{j} + x^2\mathbf{k}.$

**Solution**

$$\begin{aligned} \text{curl } \vec{F} = \nabla \times \vec{F} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \\ &= \left( \frac{\partial}{\partial y}(x^2) - \frac{\partial}{\partial z}(4z) \right) \mathbf{i} + \left( \frac{\partial}{\partial z}(x^2 - y) - \frac{\partial}{\partial x}(x^2) \right) \mathbf{j} \\ &\quad + \left( \frac{\partial}{\partial x}(4z) - \frac{\partial}{\partial y}(x^2 - y) \right) \mathbf{k} \\ &= -4\mathbf{i} - 2x\mathbf{j} + \mathbf{k}. \end{aligned}$$