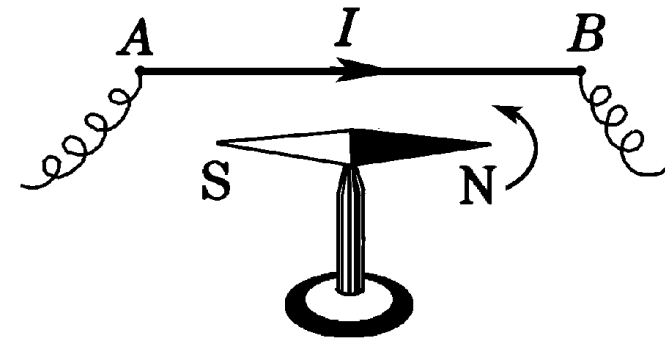
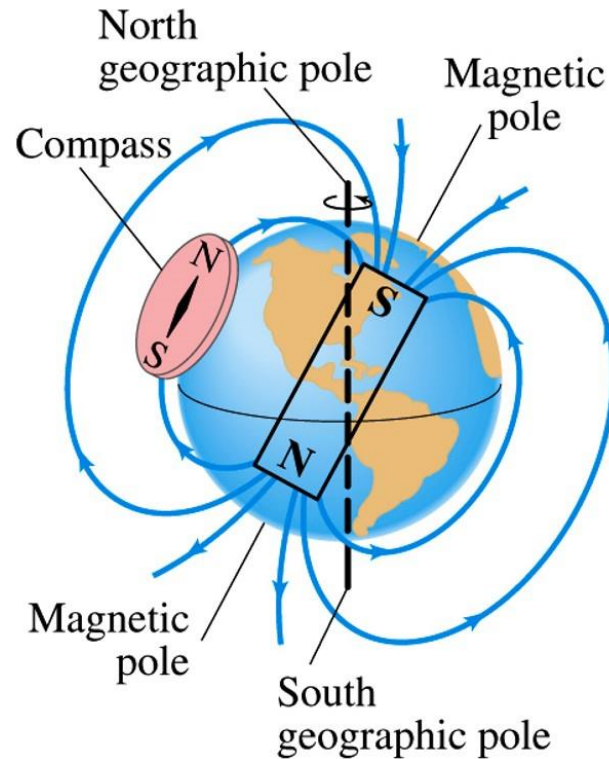
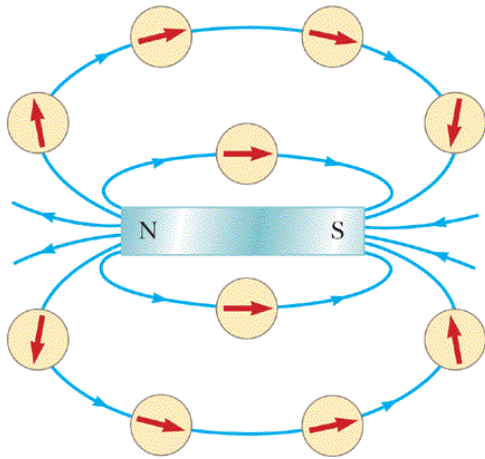


Chapter 25, 26 Magnetic Forces and Magnetic fields



§ 1 Magnetic Fields and Magnetic Forces

Magnetic phenomena



The Comparison between Electronic and Magnetic Interaction Models

Electric interaction model

$$d\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2} \hat{r}$$

$$\vec{F}_e = q\vec{E}$$



Magnetic interaction model



- How does a moving charge or a current **create** the magnetic field throughout the space?
- How does the magnetic field **exert a force** on any other moving charge or current that presents in the field?

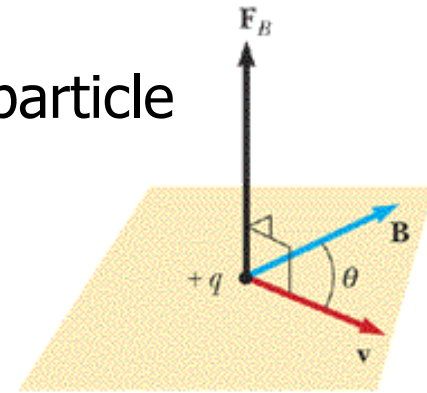
The magnetic force on a moving charged particle



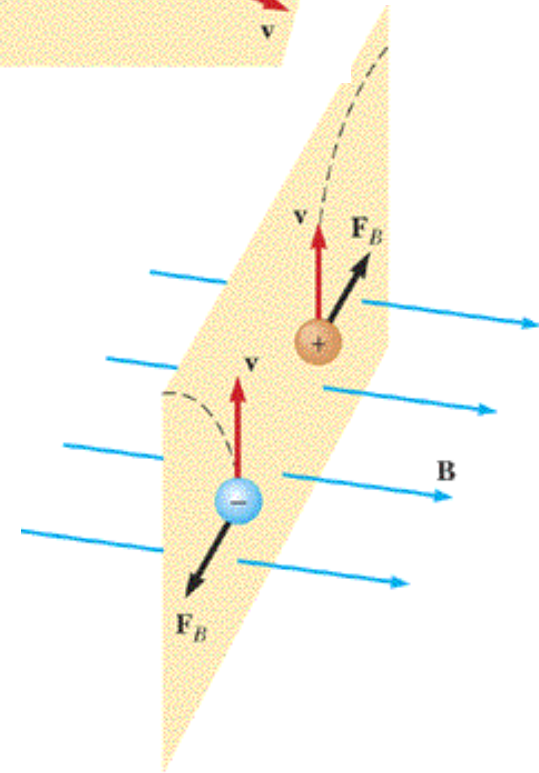
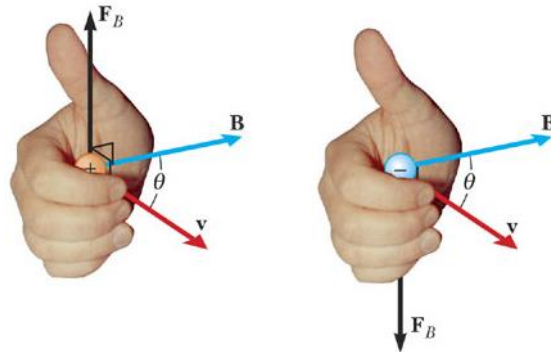
- The magnetic force on a **moving** charged particle

Lorentz force: $\vec{F}_B = q\vec{v} \times \vec{B}$

$$F_B = |q| v B \sin \theta$$



- Right hand rule for the magnetic force:



- The unit of magnetic field
 - SI unit: **tesla** or T. $1 \text{ T} = 1 \text{ N} \cdot \text{s} / \text{C} \cdot \text{m}$
 - cgs unit: gauss or G. $1 \text{ G} = 10^{-4} \text{ T}$

The magnetic field of the earth is of the order of 1G or 10^{-4} T .

The Differences Between Electric Force and Magnetic Forces



- The important differences between electric force and magnetic forces
 - ➡ The electric force is always **parallel** or anti-parallel to the direction of the electric field ($\vec{F}_e = q\vec{E}$), whereas the magnetic force is **perpendicular** to the magnetic field ($\vec{F}_B = q\vec{v} \times \vec{B}$).
 - ➡ The electric force acts on a charged particle is **independent** of the particle's velocity, whereas the magnetic force acts on a charged particle only when the particle is **in motion**.
 - ➡ The electric force **does work** in displacing a charge particle, whereas the magnetic force **does no work** when a charged particle is displaced (because the magnetic force is always perpendicular to its velocity $\vec{F}_B \perp \vec{v}$).

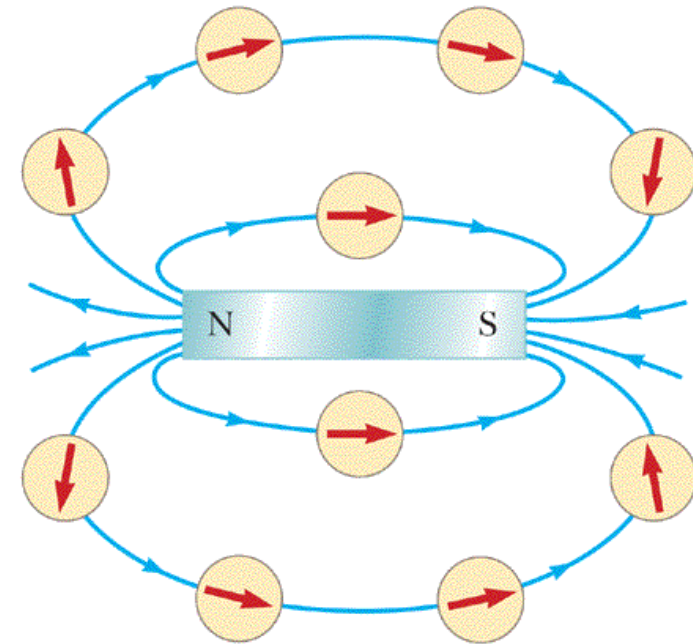
§ 2 Magnetic Field Lines and Magnetic Flux



- Magnetic field lines, a **graphical** way, are related to the magnetic field in the following manner:

Magnetic field in space:

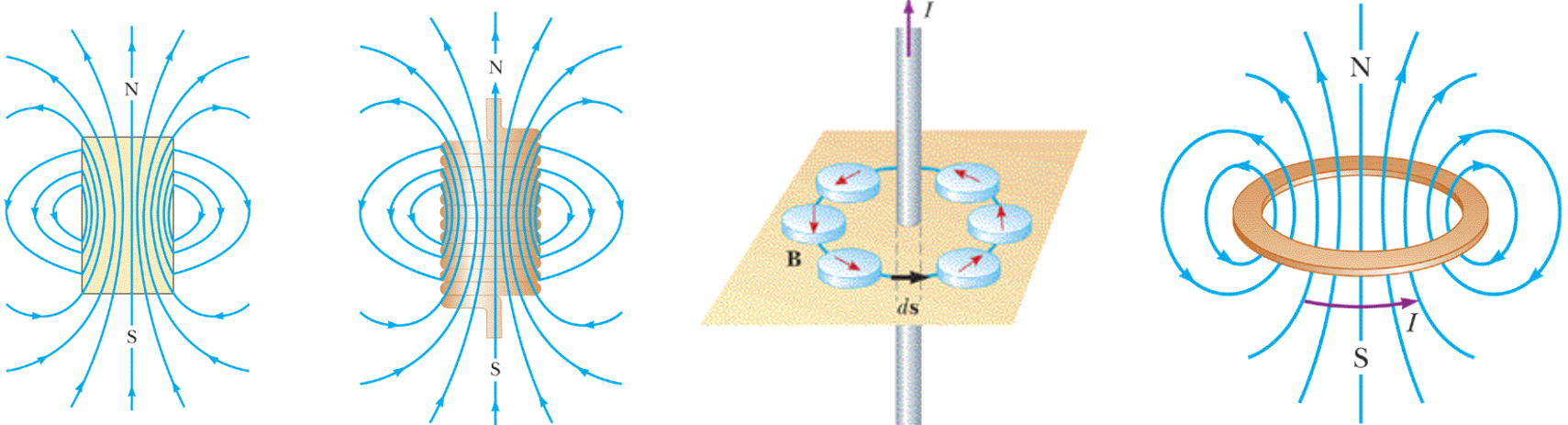
- ➡ Direction — is **tangent** to the magnetic field line at that point.
- ➡ Magnitude — is **proportional** to the number of magnetic field lines per unit area through the cross-sectional surface in that region. The magnitude of B is **larger** where the adjacent field lines are **close together** and **small** where they are **far apart**.



The Fundamental Properties for Magnetic Field Lines



- The fundamental properties for magnetic field lines
 - ➔ Because the direction of magnetic field at each point is unique, field lines **never intersect**.
 - ➔ Unlike electric field lines that begin and end on electric charges, magnetic field lines never have end point, and always form **closed loops**; (If a magnetic field line had end point, such a point would indicate the existence of a magnetic **monopole** (磁单极)).

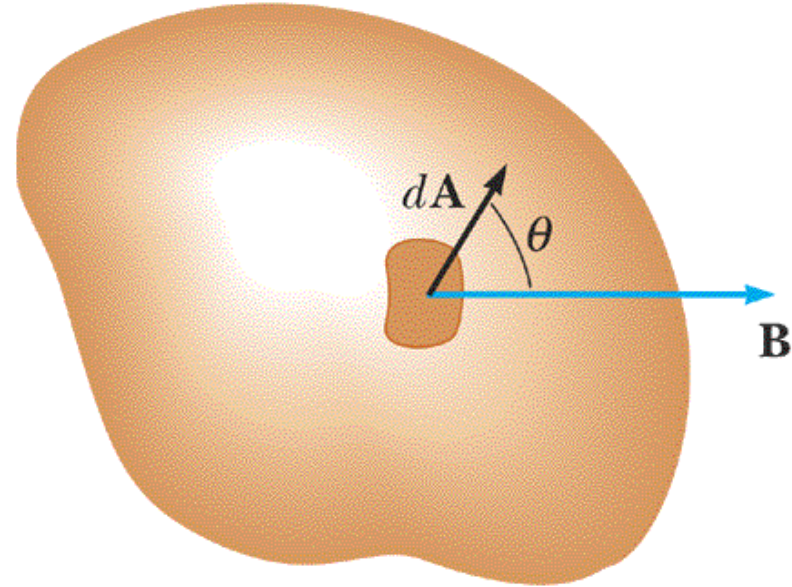


- Magnetic flux:

- ➔ Magnetic flux through a surface:

$$\Phi_B = \iint_{\text{surface}} \vec{B} \cdot d\vec{A}$$

- ➔ SI unit: Weber (Wb)



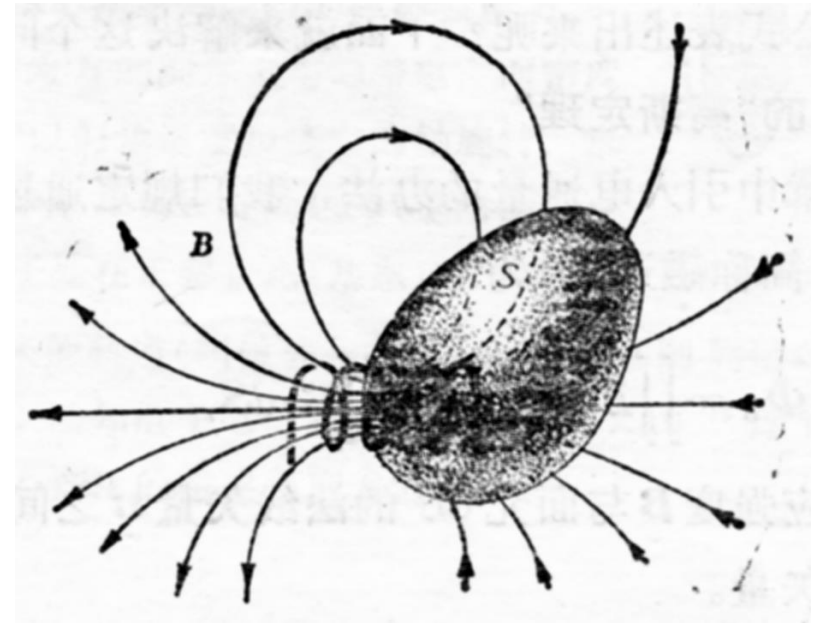
Gauss's law for magnetism



Gauss's law for magnetism

No magnetic monopole has ever been observed.

$$\oiint_S \vec{B} \cdot d\vec{A} = 0$$



§ 3 Motion of a Charged Particle in a Magnetic Field



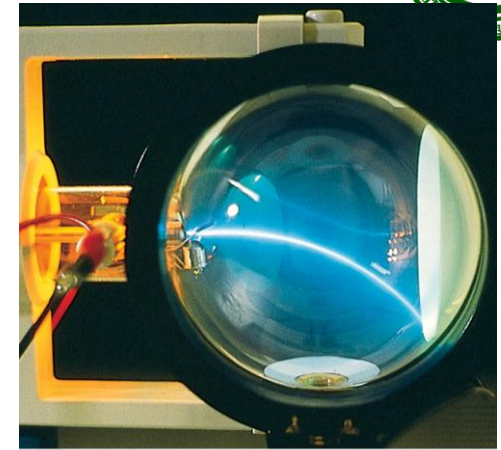
Magnetic force: $\vec{F}_B = q\vec{v} \times \vec{B}$

■ For the case that the initial velocity of the particle is **perpendicular** to the magnetic field:

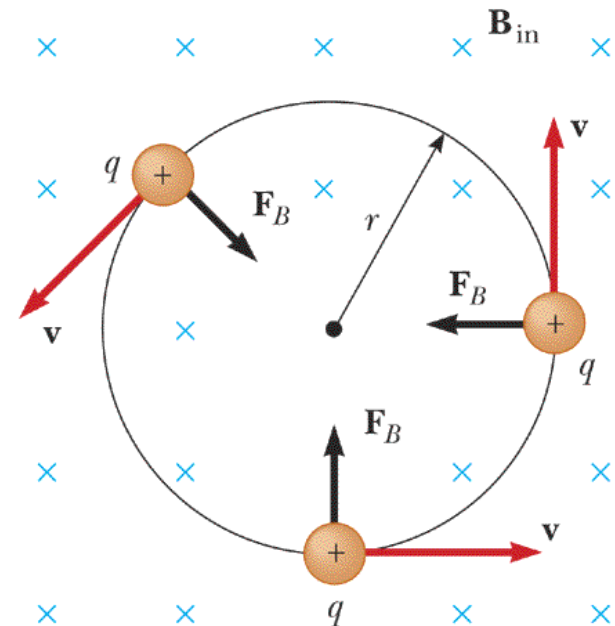
- $\vec{v}_0 \perp \vec{F}_B$, the magnetic force provides the centripetal force. The particle is in uniform circular motion:

$$F_B = qvB = ma_n = m \frac{v^2}{r},$$

$$r = \frac{mv}{qB}, \quad T = \frac{2\pi r}{v} = \frac{2\pi m}{qB}$$



The **bending** of an electron beam in a magnetic field



Magnetic force

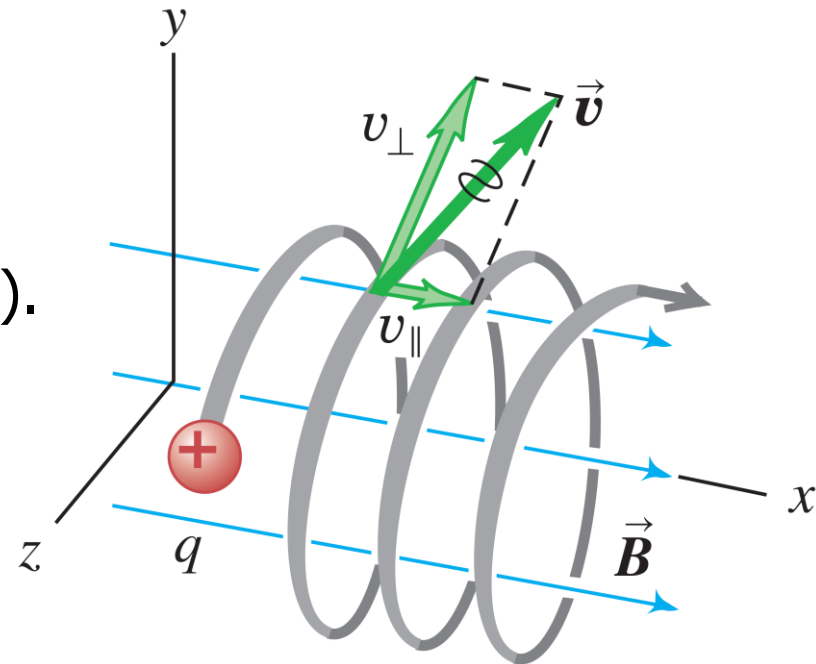


- For the case the initial velocity of the particle is **not perpendicular** to the magnetic field:

- ➡ The parallel component of acceleration $a_{\parallel} = 0$.
- ➡ The perpendicular component of acceleration

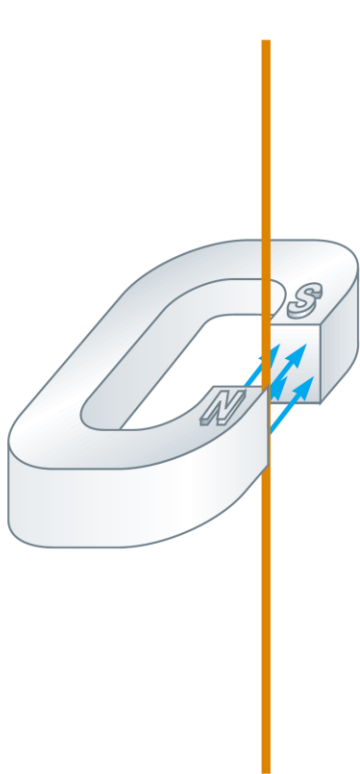
$$a_{\perp} = \frac{v_{\perp}^2}{r}, \quad r = \frac{mv_{\perp}}{qB}$$

- ➡ The particle moves in a helix (回旋).

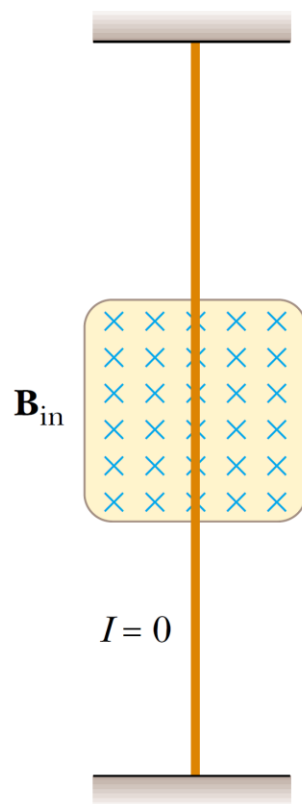


§ 4 Magnetic Force on a Current-Carrying Conductor

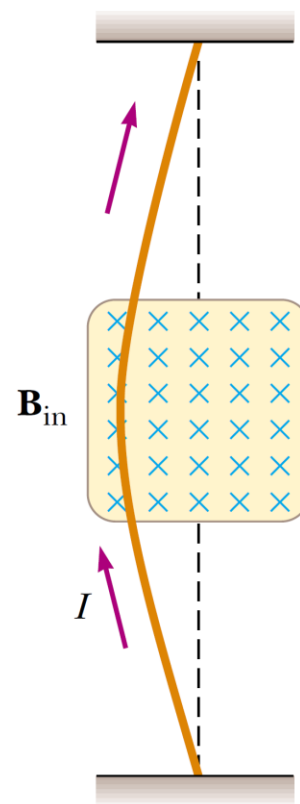
The phenomena of the magnetic force on the current-carrying conductor acted by an external magnetic field.



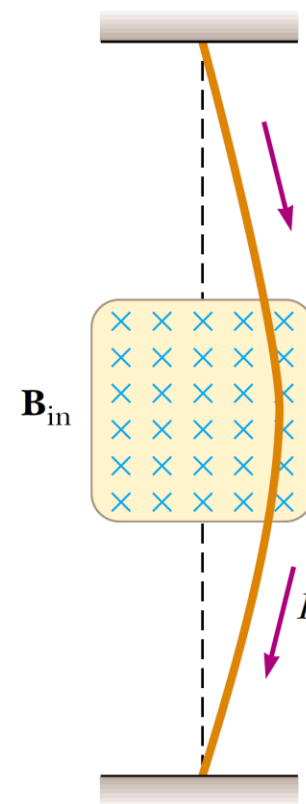
(a)



(b)



(c)

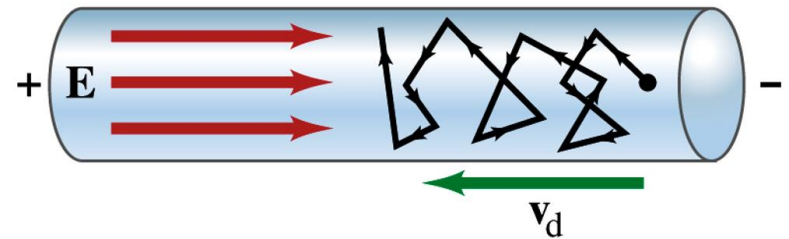


(d)

■ Current density

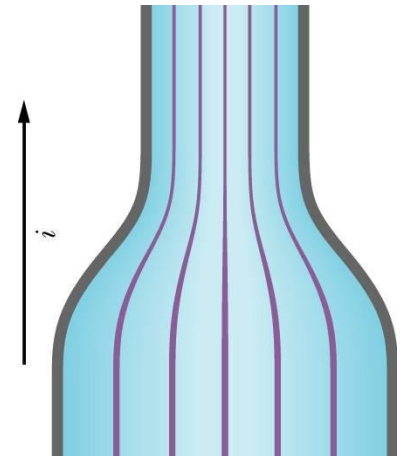
- ➡ Electric current per unit cross-sectional area at any point in space

$$j = \frac{I}{A} \quad (\text{uniform})$$



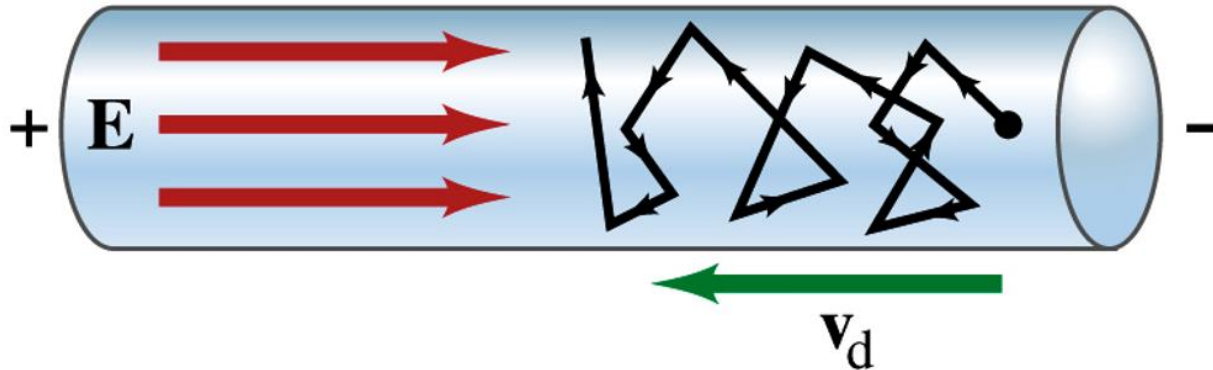
- ➡ The current density is a **vector**. The direction of \vec{j} is defined to be the direction of the flow of positive charge.
- ➡ The relationship between \vec{j} and I :

$$I = \iint_S \vec{j} \cdot d\vec{A}$$



■ Drift velocity

- ➡ The electrons collide with the ions of the lattice. On the average, electrons can be described as moving with a constant **drift speed** v_d in a direction opposite to the electric field.



The relationship between j and v_d

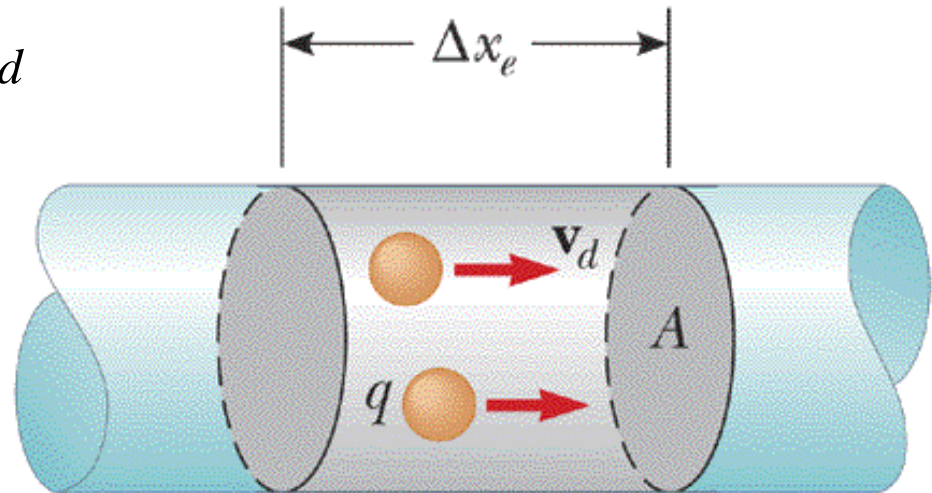


- ➔ In the interval Δt , the magnitude of net charge passing through the surface A is

$$\Delta Q = n(Av_d\Delta t)q \quad n : \text{the number of carrier per unit volume.}$$

$$j = \frac{\Delta Q}{A\Delta t} = nqv_d = -nev_d$$

$$\vec{j} = (-e)n\vec{v}_d$$



The magnetic force on a straight current-carrying wire



■ The magnetic force on a straight current-carrying wire with segment of length l :

- ➔ The magnetic force on a charge q in the wire moving with drift velocity v_d is: $q\vec{v}_d \times \vec{B}$
- ➔ The total magnetic force on the wire segment:

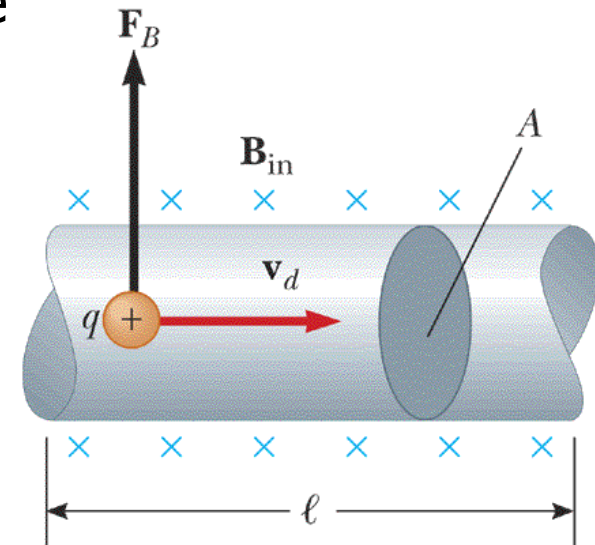
the number of charges in the segment is $n(Al)$, where n is the number of charges per unit volume, A and l are the cross-sectional area and length of the wire.

$$\vec{F}_B = (q\vec{v}_d \times \vec{B})(nAl)$$

- ➔ The current in the wire is $I = (nqv_d)A$. So the \vec{F}_B can be expressed as

$$\vec{F}_B = I\vec{l} \times \vec{B}$$

\vec{l} is the length vector in the direction of the current I .



The magnetic force on a non-straight current-carrying wire



■ If the wire is **not** straight or the magnetic field is **not** uniform

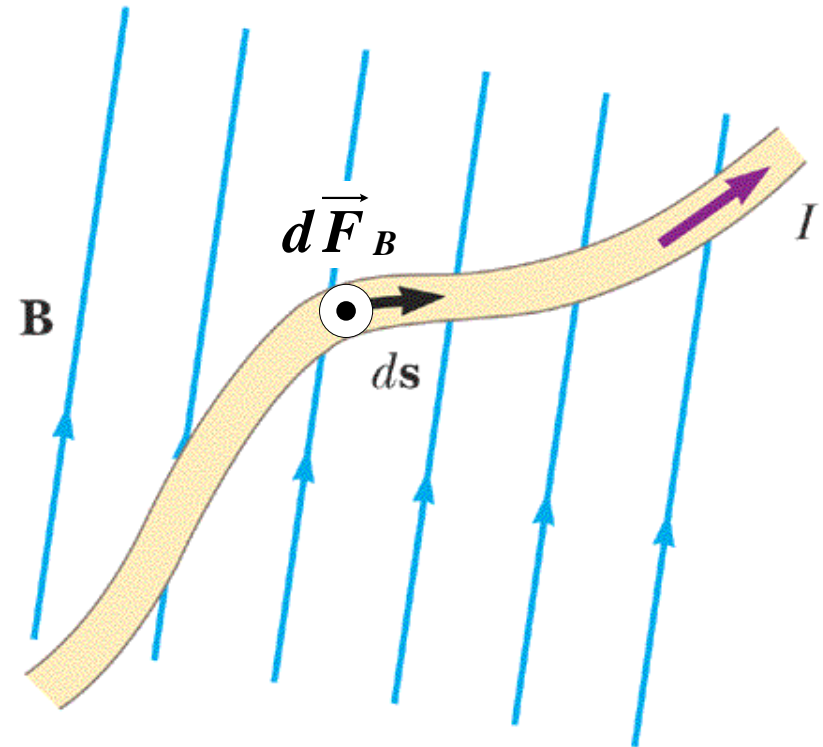
- ➡ Imaging the wire to be broken into small segments of length $d\vec{s}$.

For each small segment:

$$d\vec{F}_B = I d\vec{s} \times \vec{B}$$

- ➡ The total magnetic force on a length of the wire between arbitrary point a and b :

$$\vec{F}_B = I \int_a^b d\vec{s} \times \vec{B}$$

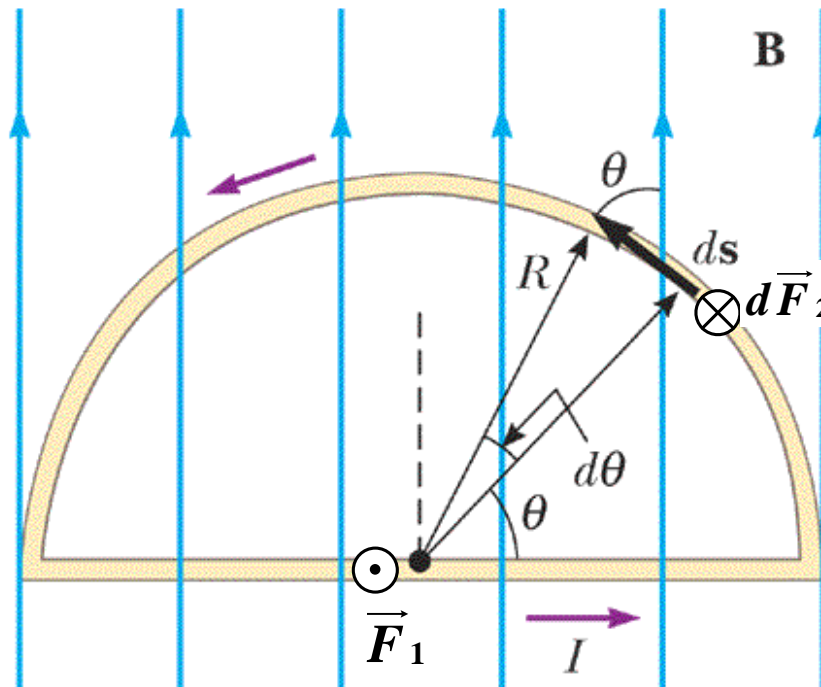


Example



Magnetic force on a semicircular conductor

A wire bent the shape of a semicircle of radius R forms a closed circuit and carries a current I . The circuit lies in the xy plane, and a uniform magnetic field is present along the positive y axis as in the figure. Find the **magnetic force** on the straight portion of wire and on the curved portion.



Example

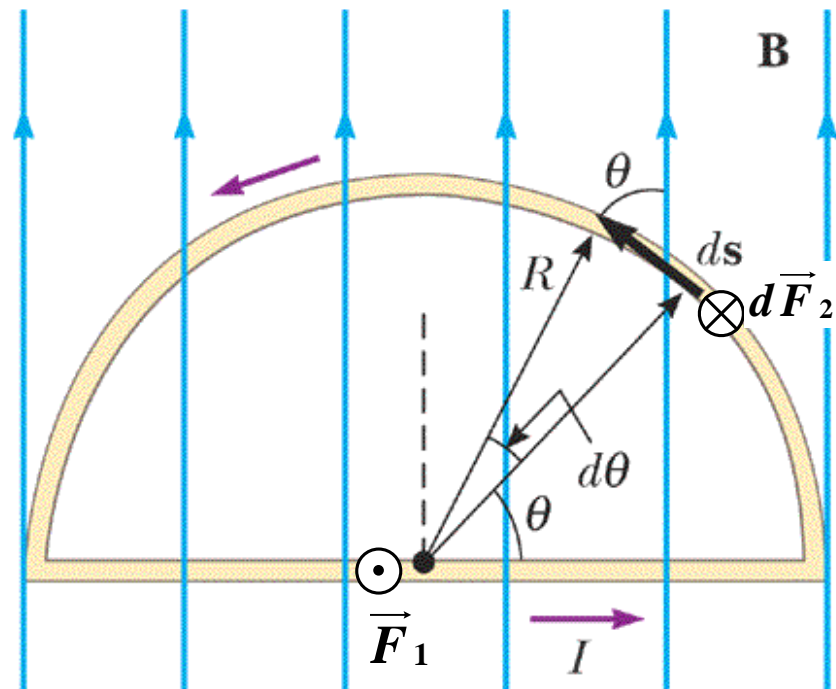


Solution: (1) The force on the straight portion.

$$\vec{F}_B = I\vec{l} \times \vec{B}$$

$$F_1 = IlB = 2IRB$$

The direction of \vec{F}_1 is **outward**.



Example



(2) The magnetic force $d\vec{F}_2$ on the element $d\vec{s}$

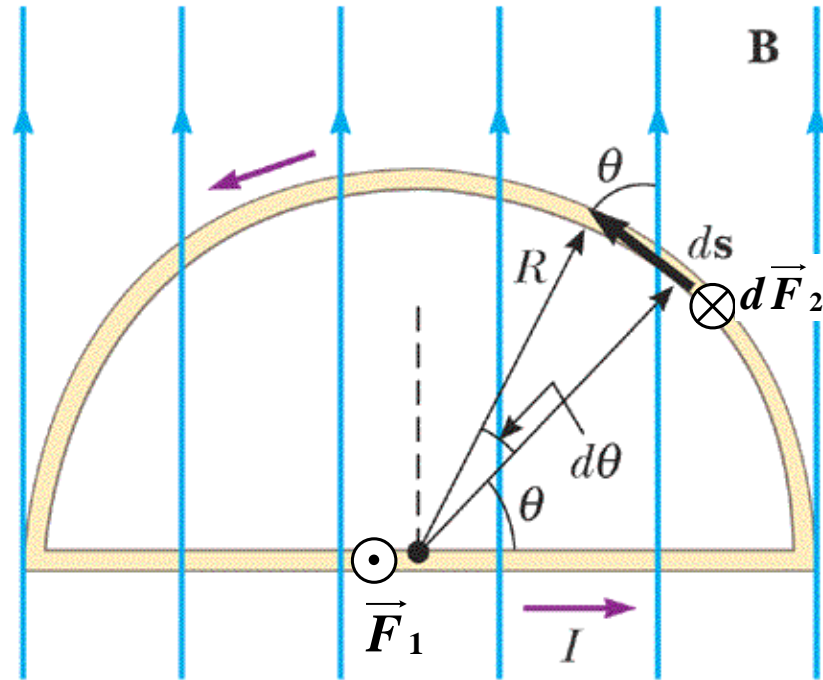
$$dF_2 = I |d\vec{s} \times \vec{B}| = IB \sin \theta ds, \quad ds = R d\theta$$

$$dF_2 = IRB \sin \theta d\theta$$

$$\begin{aligned} F_2 &= IRB \int_0^\pi \sin \theta d\theta \\ &= -IRB(\cos \pi - \cos 0) = 2IRB \end{aligned}$$

The magnetic force \vec{F}_2 is **inward**.

$$\vec{F}_1 + \vec{F}_2 = \mathbf{0}$$



We see that the net magnetic force on the **closed loop** is **zero** when the magnetic field is **uniform**.

$$\vec{F}_m = \oint (I d\vec{s} \times \vec{B}) = I \left(\oint d\vec{s} \right) \times \vec{B} = \mathbf{0}$$

§ 5 Torque on a Current Loop



- The net **force** on a current loop in a uniform magnetic field is **zero**.
- However, the net **torque** is generally **not zero**.

- Example: a rectangular current loop of wire, with side length a and b .
- When the loop is oriented so that the magnetic field is in the plane of the loop, according to

$$\vec{F}_B = I\vec{l} \times \vec{B}$$

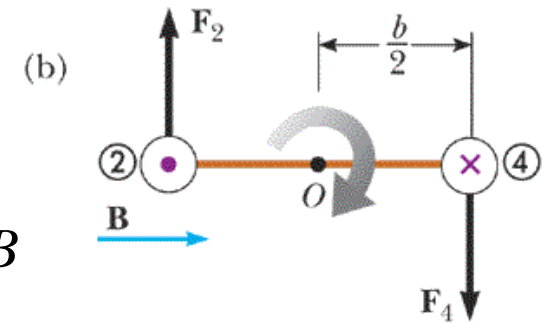
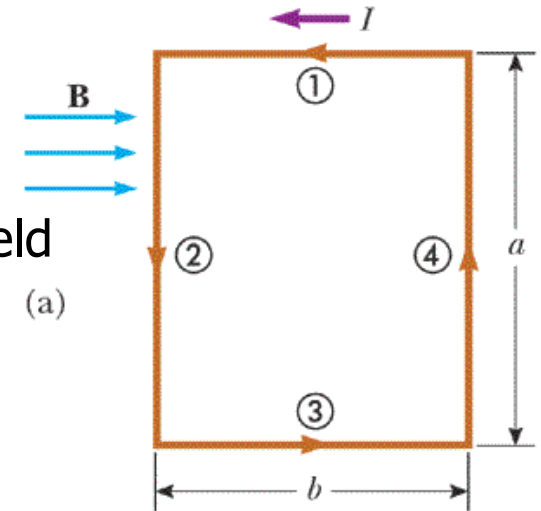
the magnetic forces on the **short** ends are zero.

On the **long** ends, the force are equal but in opposite directions. $|\vec{F}_2| = |\vec{F}_4| = IaB$

The net force on the loop is zero.

- The net torque: tend to rotate the loop clockwise.

$$|\vec{\tau}| = \left(\frac{b}{2}\right)F_2 + \left(\frac{b}{2}\right)F_4 = 2\left(\frac{b}{2}\right)IaB = I(ab)B = (IA)B$$



Torque on a Current Loop



- When the loop is oriented so that the loop plane makes an angle θ with the direction of magnetic field, F_1 is **inward** and has a magnitude of

$$F_1 = IbB \sin(90^\circ + \theta) = IbB \cos \theta$$

- F_3 is **outward** and has a magnitude of

$$F_3 = IbB \sin(90^\circ - \theta) = IbB \cos \theta$$

The forces of F_1 and F_3 have the same line of action, not only they create a total **zero** force, but also do **not** contribute to the net torque.

- The forces F_2 and F_4 :

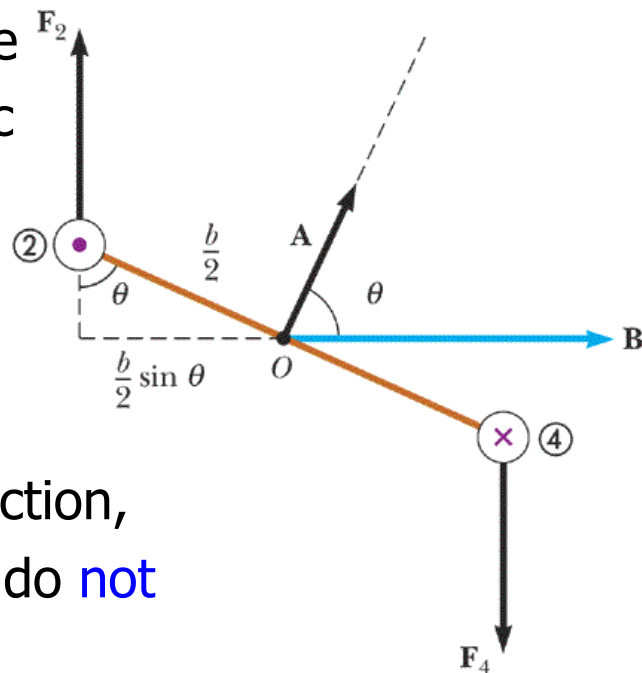
They also create a total zero force, but they create a torque:

$$|\vec{\tau}| = F_2 \left(\frac{b}{2} \right) \sin \theta + F_4 \left(\frac{b}{2} \right) \sin \theta$$

$$= 2(IaB) \left(\frac{b}{2} \right) \sin \theta = (IA)B \sin \theta$$

$$\vec{\tau} = (I \vec{A}) \times \vec{B}$$

If we define the A as a vector \vec{A} perpendicular to the plane of the loop



Magnetic Dipole



Introducing the magnetic dipole and magnetic dipole moment.

- For any current loop with **any shape**, we can define a vector **magnetic moment** $\vec{\mu}$ with magnitude IA . The direction of $\vec{\mu}$ is determined by right-hand rule.

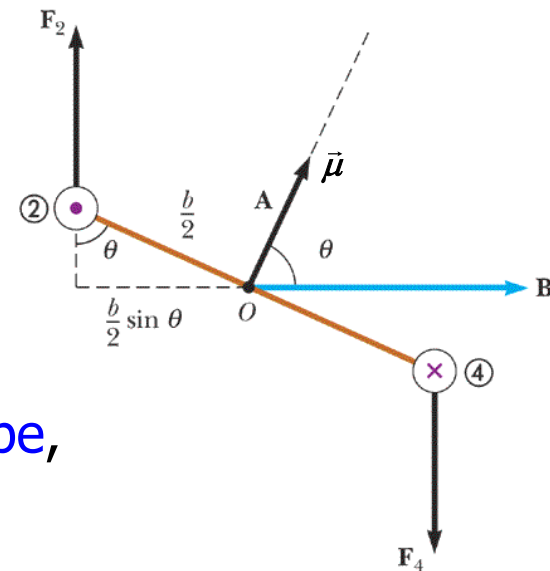
$$\vec{\mu} \equiv I \vec{A}$$

- If a coil consists of N turns of wire, the total magnetic moment of the coil is: $\vec{\mu} = NI \vec{A}$

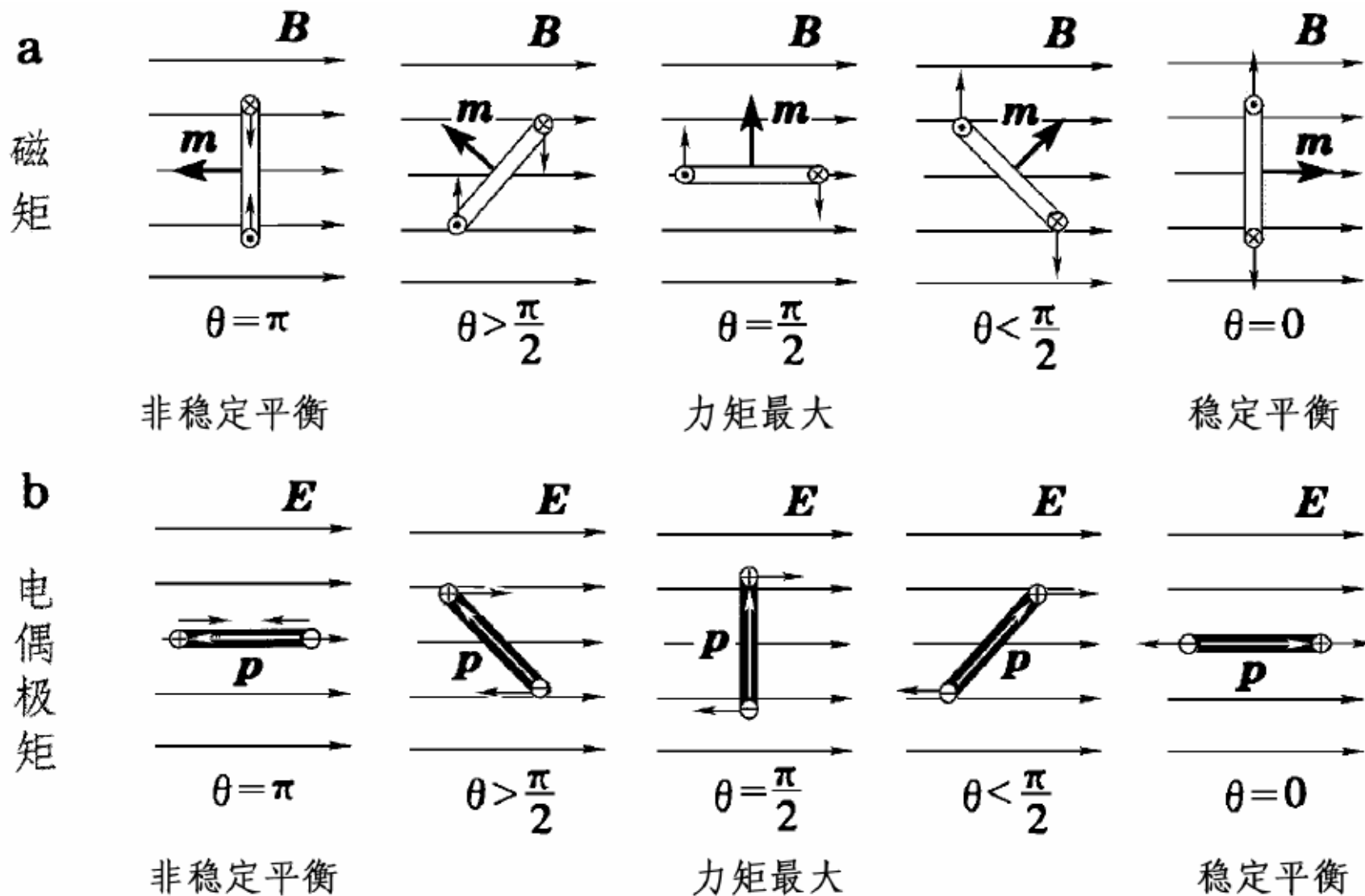
Torque on the current loop in a magnetic field

$$\vec{\tau} = I \vec{A} \times \vec{B} = \vec{\mu} \times \vec{B}$$

- The torque tries to rotate the loop so that $\vec{\mu}$ is brought into **alignment with** \vec{B} .
- The torque expression is valid for loop of **any shape**, although it was derived for a rectangular loop.



$$\vec{\tau} = \vec{\mu} \times \vec{B} \quad \text{vs.} \quad \vec{\tau} = \vec{p} \times \vec{E}$$



Ch25 Prob. 27, 29 (P600)

Ch25 Prob. 12, 37 (P599)

§ 6 The Biot-Savart Law



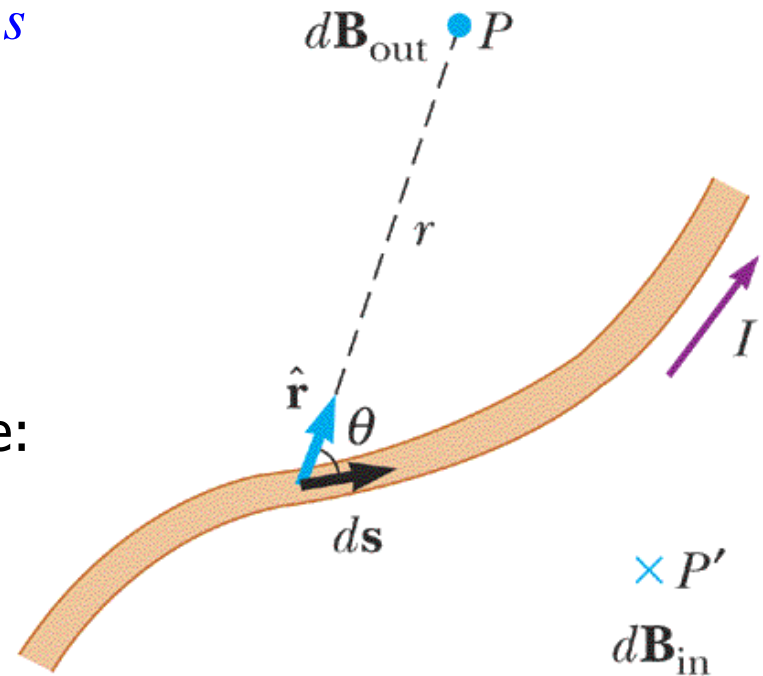
- The magnetic field produced by a **current element**
- ➡ Definition of vector of current element $I d\vec{s}$

➡ Biot-Savart law:

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{s} \times \hat{r}}{r^2}$$

- ➡ The total magnetic field due to entire wire:

$$\vec{B} = \int d\vec{B} = \frac{\mu_0}{4\pi} \int \frac{I d\vec{s} \times \hat{r}}{r^2}$$



μ_0 is called the permeability of free space. $\frac{\mu_0}{4\pi} = 10^{-7} \text{ T} \cdot \text{m/A}$

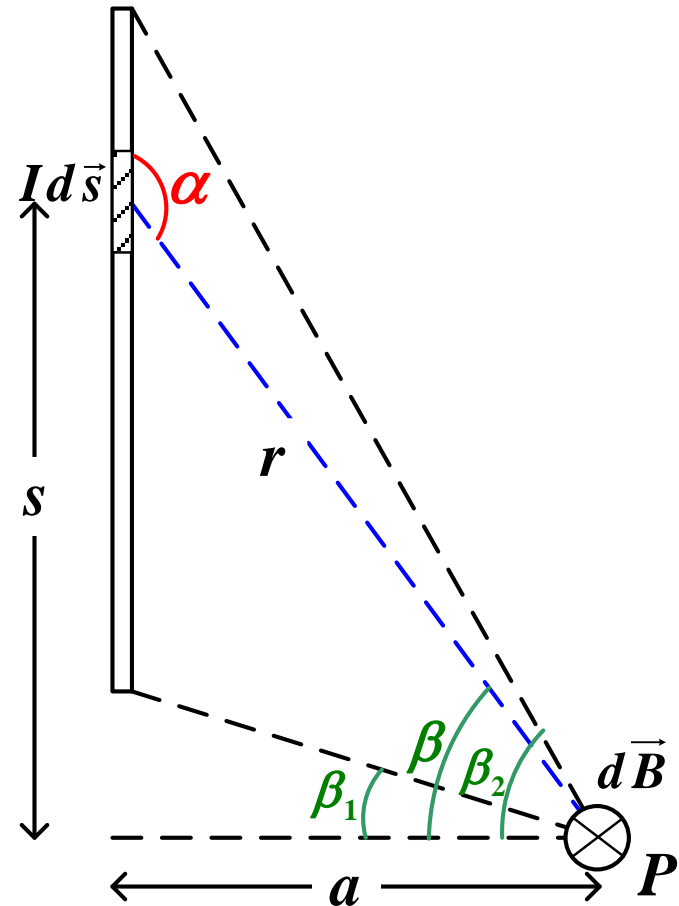
Example



Magnetic field of

a **straight current** wire segment

Find the **magnetic field** at the point P , located a distance a from the wire. The straight wire carries a constant current I . Assume the lines connecting two ends of wire and point P make the angles β_1 and β_2 with the horizontal line.



Magnetic field of a straight current wire segment



Solution: $d\vec{B}$ produced by the current element $I d\vec{s}$ is always inward.

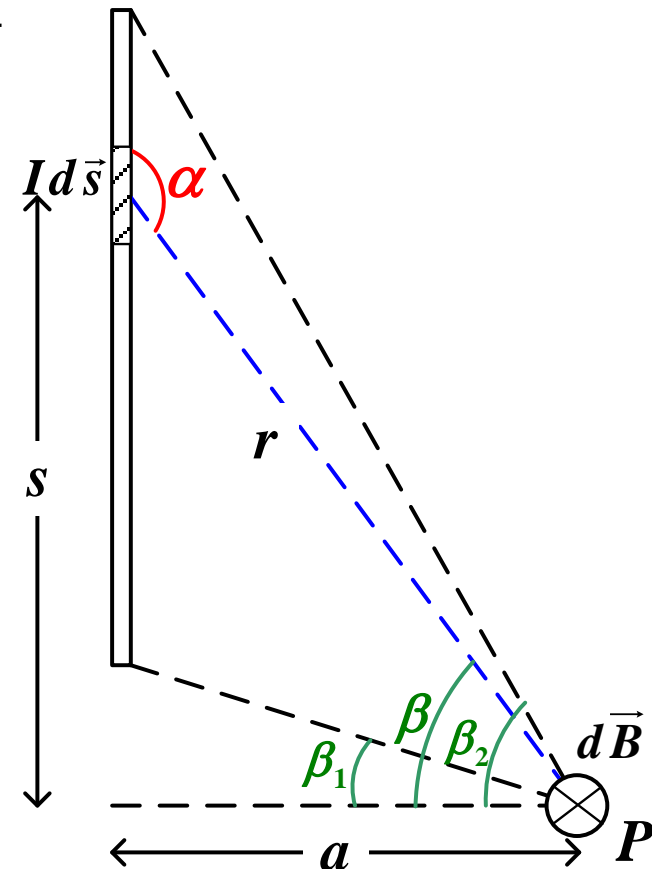
$$dB = \frac{\mu_0}{4\pi} \frac{Id s \sin \alpha}{r^2}, \quad B = \frac{\mu_0}{4\pi} \int \frac{Id s \sin \alpha}{r^2}$$

Find r , s , α in terms of β

$$\alpha = 90^\circ + \beta, \quad \sin \alpha = \cos \beta$$

$$r = \frac{a}{\cos \beta} = a \sec \beta, \quad s = a \tan \beta, \quad ds = a \sec^2 \beta d\beta$$

$$\begin{aligned} B &= \frac{\mu_0 I}{4\pi} \int_{\beta_1}^{\beta_2} \frac{(\cos \beta)(a \sec^2 \beta d\beta)}{a^2 \sec^2 \beta} \\ &= \frac{\mu_0 I}{4\pi a} \int_{\beta_1}^{\beta_2} \cos \beta d\beta = \frac{\mu_0 I}{4\pi a} (\sin \beta_2 - \sin \beta_1) \end{aligned}$$



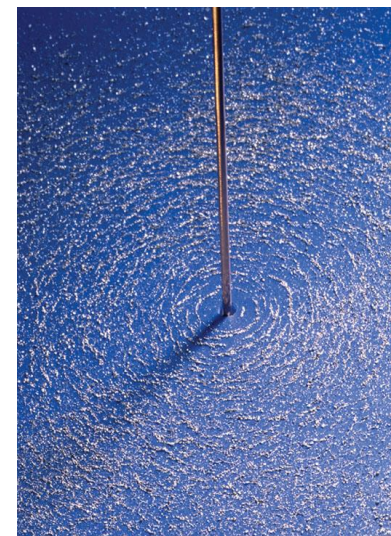
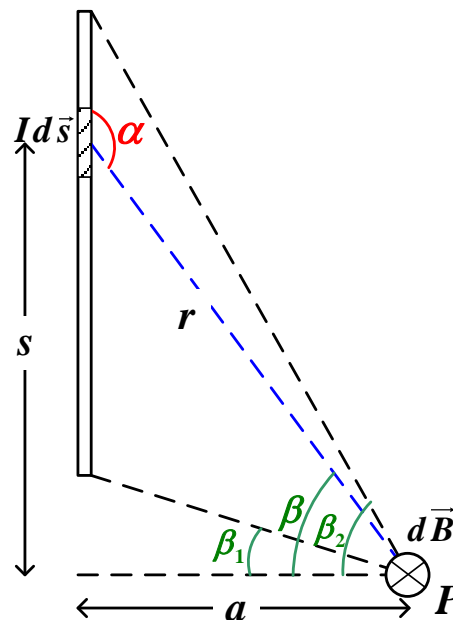
Example Cont'd

$$B = \frac{\mu_0 I}{4\pi a} (\sin \beta_2 - \sin \beta_1)$$

For a very **long** wire, $s \gg a$

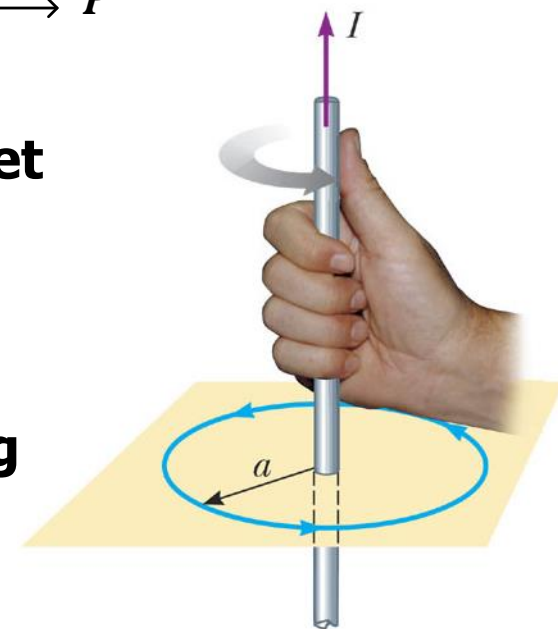
$$\beta_1 \rightarrow -\frac{\pi}{2}, \quad \beta_2 \rightarrow \frac{\pi}{2}$$

$$B \rightarrow \frac{\mu_0 I}{2\pi a} \propto \frac{1}{a}$$



For a long, straight, current-carrying wire, a set of magnetic lines form **concentric circles** around the wire.

We can use the **right-hand rule** to determine the direction of the magnetic field surrounding a long, straight wire carrying a current.

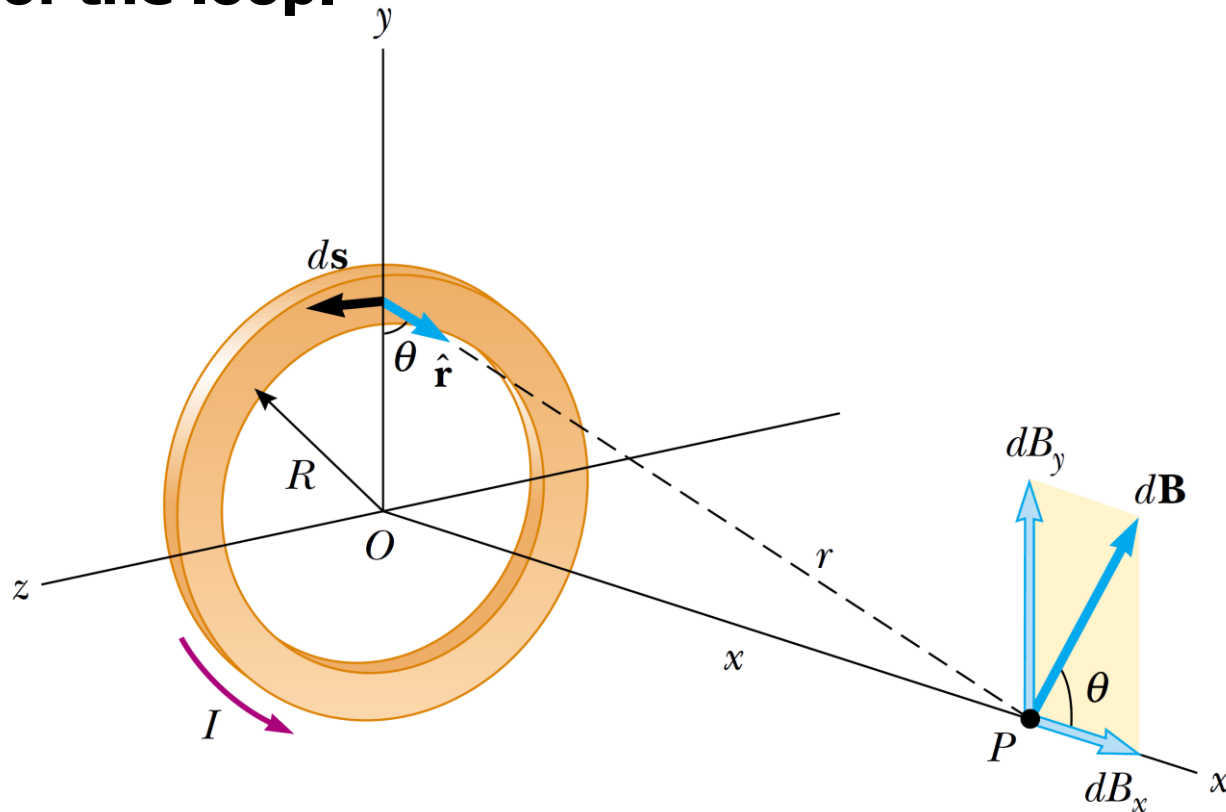


Example



Magnetic field on the axis of a **circular current** loop

Consider a circular loop of wire of radius R located in the y - z plane and carrying a steady current I . Calculate the **magnetic field** at an axial point P a distance x from the center of the loop.

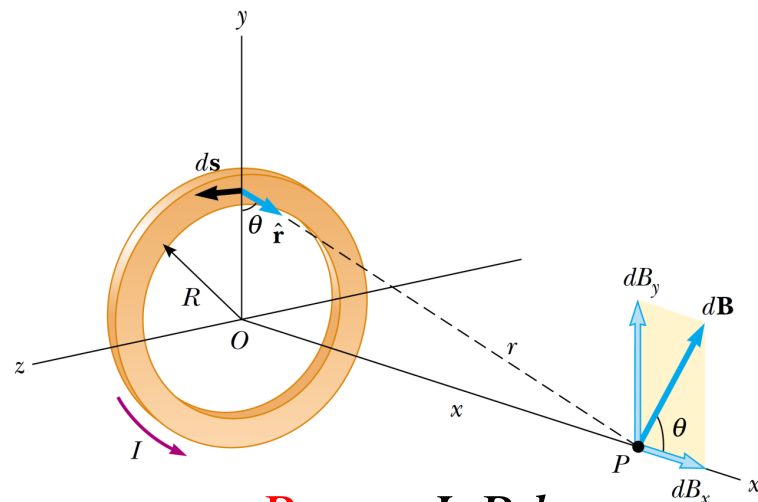


Magnetic field on the axis of a circular current loop



Solution: The $d\vec{B}$ due to the element $d\vec{s}$ can be resolved into a component dB_x , along the x axis, and a component dB_\perp , which perpendicular to the x axis.

By **symmetry**, any element on one side of the loop sets up a component dB_\perp that cancels the component set up by an element diametrically opposite it.



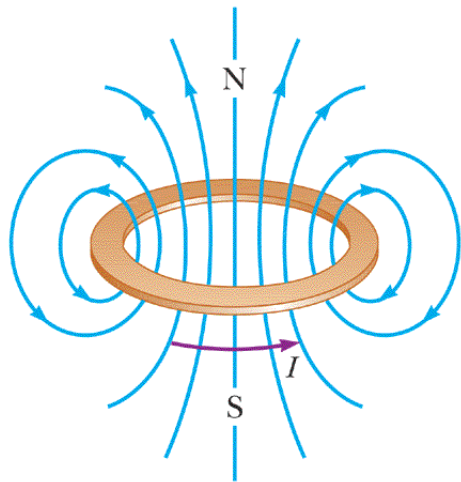
$$dB = \frac{\mu_0 I}{4\pi} \frac{|d\vec{s} \times \hat{r}|}{r^2} = \frac{\mu_0 I}{4\pi} \frac{ds}{r^2}, \quad dB_x = dB \cos \theta = dB \frac{R}{r} = \frac{\mu_0 I}{4\pi} \frac{R ds}{r^3}$$

$$B = \int dB_x = \frac{\mu_0 I}{4\pi} \frac{R}{r^3} \oint ds = \frac{\mu_0 I}{4\pi} \frac{R}{(x^2 + R^2)^{3/2}} (2\pi R) = \frac{\mu_0 I R^2}{2(x^2 + R^2)^{3/2}}$$

At the **center** of the loop: $B = \frac{\mu_0 I}{2R}$ (at $x = 0$)

The direction is determined by the right-hand rule.

Example Cont'd



It is interesting to determine the behavior of the magnetic field far from the loop, $x \gg R$

$$B = \frac{\mu_0 I R^2}{2(x^2 + R^2)^{3/2}} \xrightarrow{x \gg R} \frac{\mu_0 I R^2}{2x^3}$$

Consider the **magnetic dipole moment** of the loop $\mu = I(\pi R^2)$

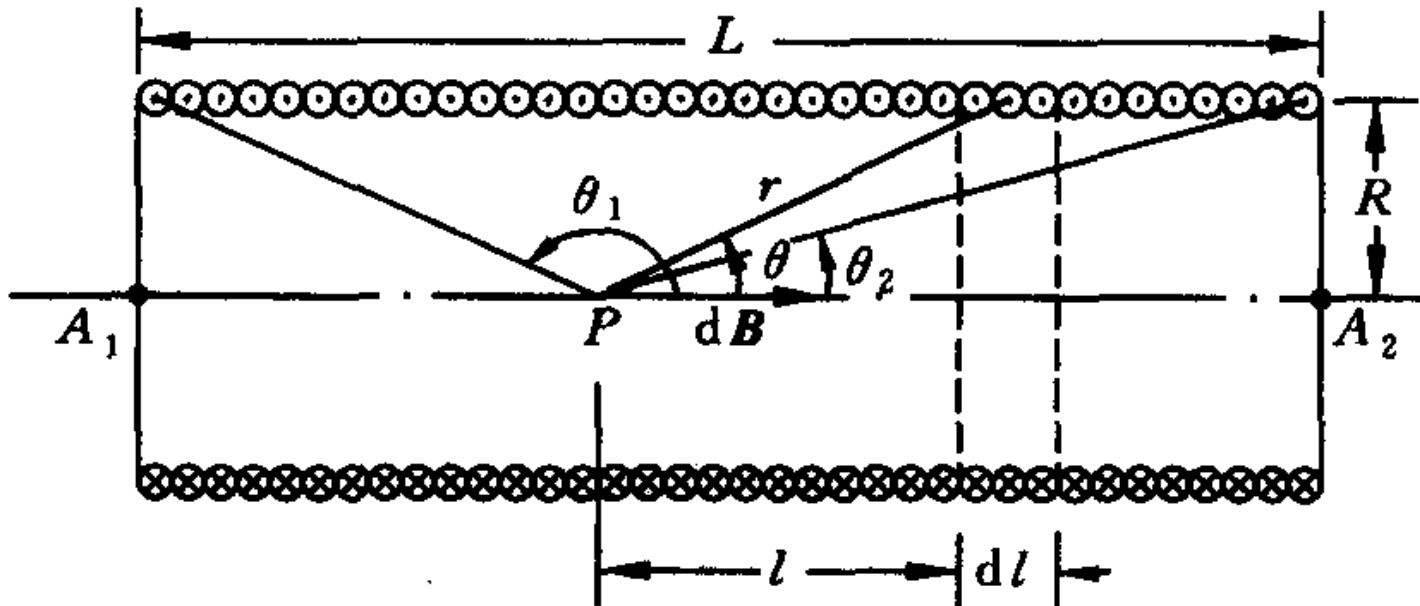
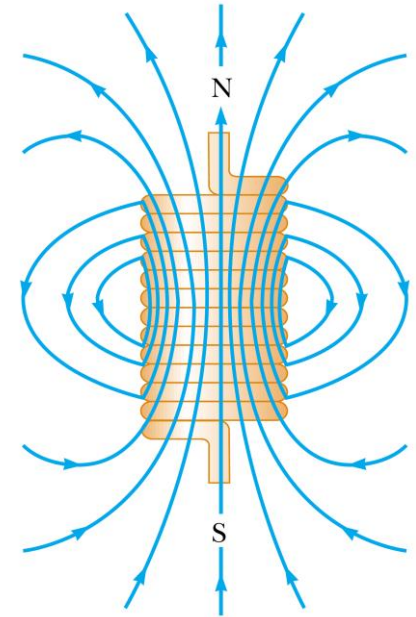
$$B = \frac{\mu_0}{2\pi} \frac{\mu}{x^3} \propto \frac{\mu}{x^3}$$

Compare the electric field due to a **electric dipole**: $E = \frac{1}{2\pi\epsilon_0} \frac{p}{x^3} \propto \frac{p}{x^3}$

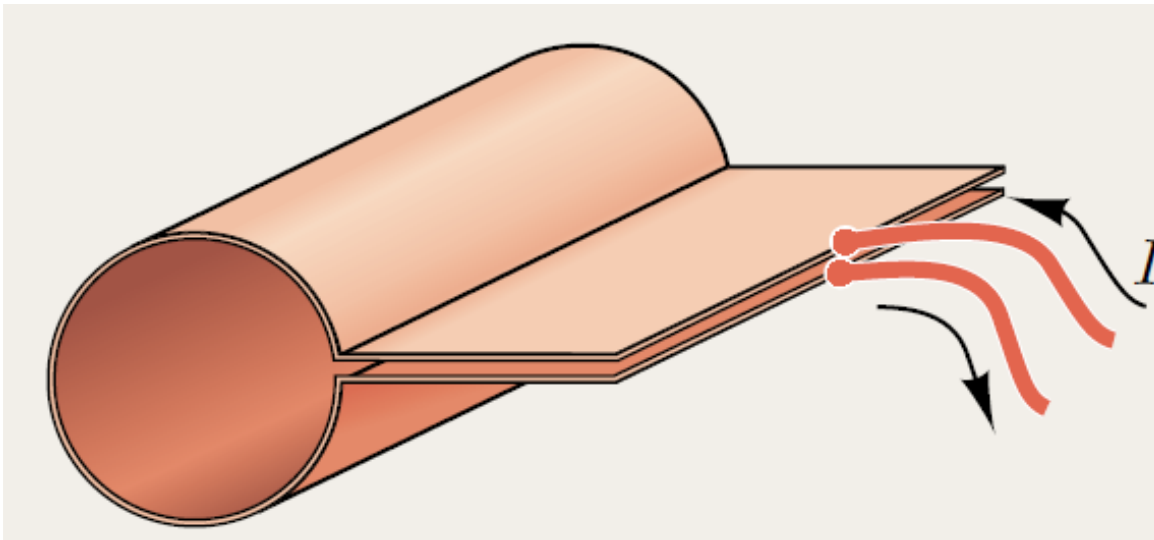
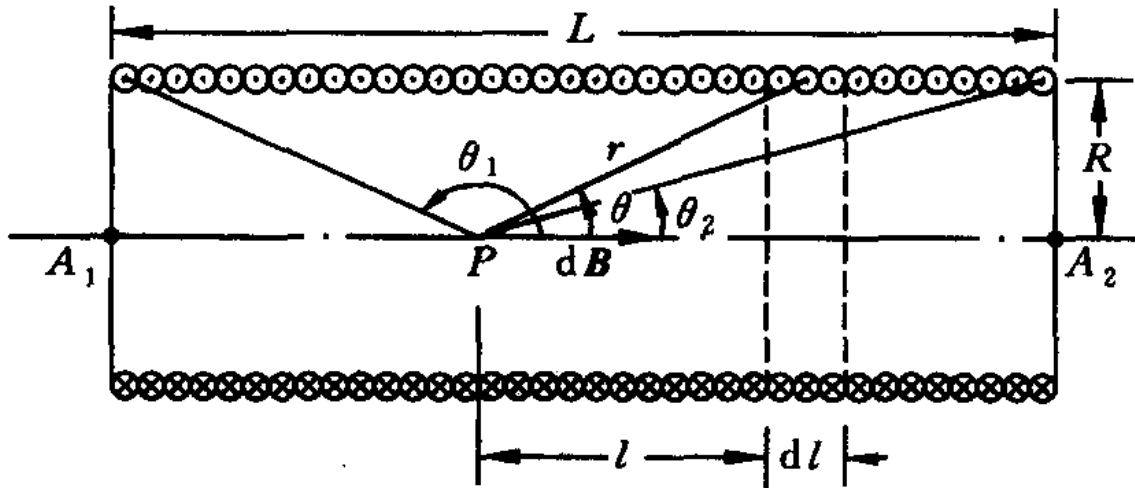
Example

Magnetic field on the axis of a solenoid

A solenoid is a helical winding of wire on a cylindrical core of radius R . The wire carries a current I . The number of the turns per unit length is $n = N/L$. Consider a point P on the central axis of the solenoid make the angles of θ_1 and θ_2 from axis up to the edges of two ends.



Magnetic field on the axis of a solenoid



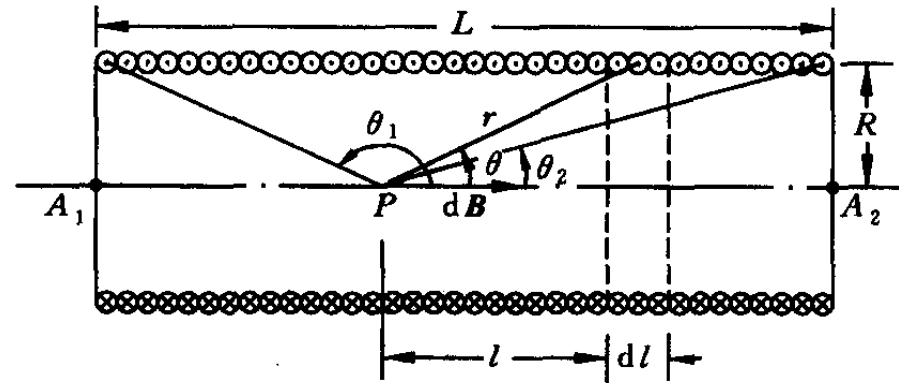
Assume that the current is uniformly distributed over the **sheet** of copper, and treat the solenoid as very long.

Magnetic field on the axis of a solenoid



Solution: Consider a thin ring of width dl . The number of turns in that ring is ndl , and so the total current carried by the **ring** is $nIdl$. The field at P due to this ring is:

$$dB = \frac{\mu_0 R^2 dI'}{2(l^2 + R^2)^{3/2}} = \frac{\mu_0 R^2 (nIdl)}{2(l^2 + R^2)^{3/2}}$$



Express the l in terms of θ :

$$l = R \cot \theta, \quad dl = -R \csc^2 \theta d\theta, \quad l^2 + R^2 = R^2 \csc^2 \theta$$

$$B = \frac{\mu_0 n I}{2} \int_{\theta_1}^{\theta_2} \frac{R^2 (-R \csc^2 \theta) d\theta}{R^3 \csc^3 \theta} = -\frac{\mu_0 n I}{2} \int_{\theta_1}^{\theta_2} \sin \theta d\theta = \frac{\mu_0 n I}{2} (\cos \theta_2 - \cos \theta_1)$$

The direction of the field is determined using right-hand rule.

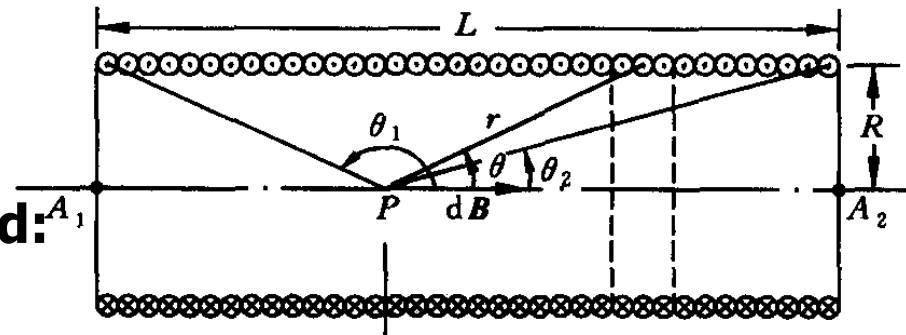
Example Cont'd



$$B = \frac{\mu_0 n I}{2} (\cos \theta_2 - \cos \theta_1)$$

For an ideal solenoid, whose length is very long, $L \gg R$

$$\theta_1 \rightarrow \pi, \theta_2 \rightarrow 0, B \xrightarrow{L \gg R} \mu_0 n I$$

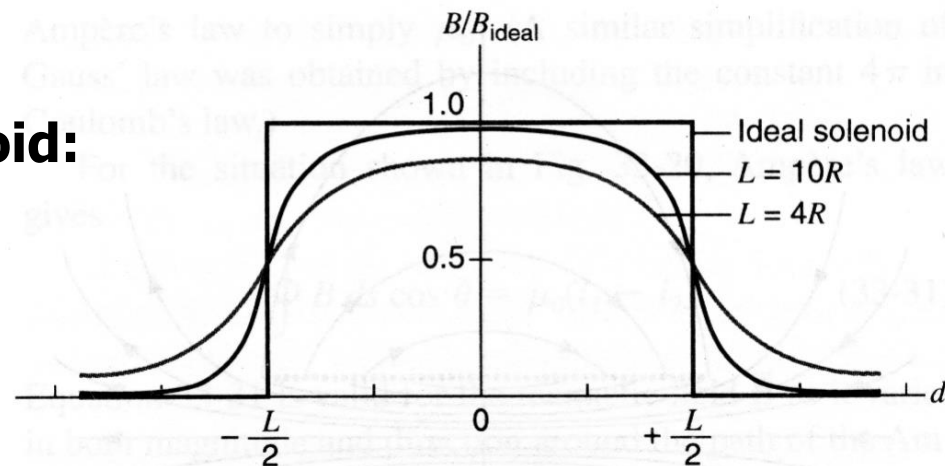


At the end at point A_1 of the solenoid:

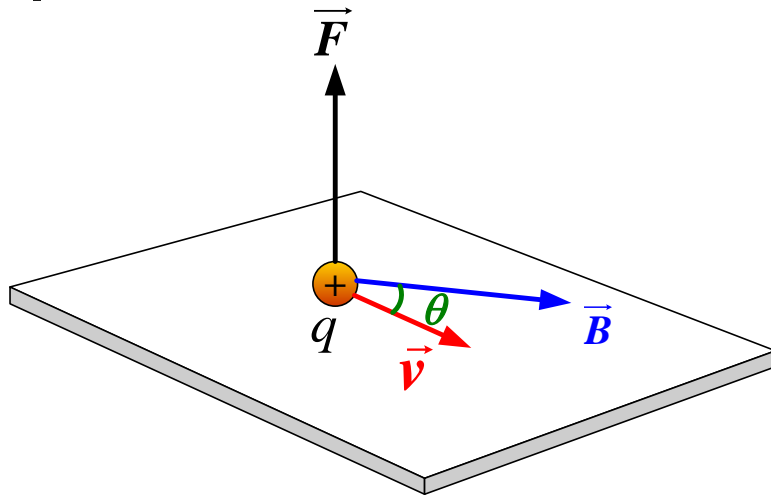
$$\theta_1 \rightarrow \frac{\pi}{2}, \theta_2 \rightarrow 0, B = \frac{1}{2} \mu_0 n I$$

At the end at point A_2 of the solenoid:

$$\theta_1 \rightarrow \pi, \theta_2 \rightarrow \frac{\pi}{2}, B = \frac{1}{2} \mu_0 n I$$

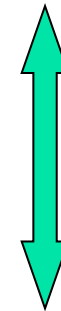


§ 7 Magnetic Field of a Moving Charge



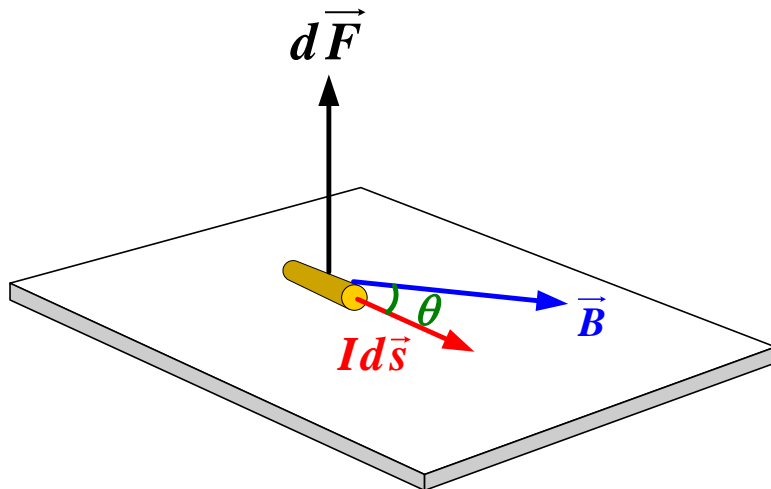
Magnetic force on a moving charge

$$\vec{F} = q\vec{v} \times \vec{B}$$



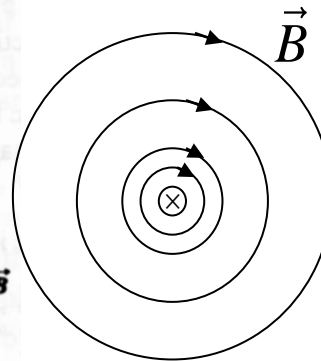
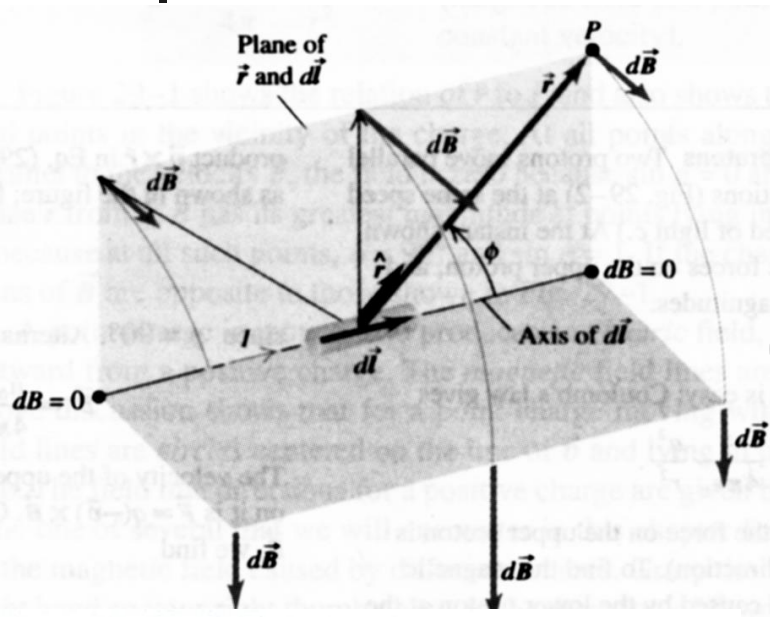
$$q\vec{v} \rightarrow Id\vec{s}$$

Magnetic force on a current element



$$d\vec{F} = Id\vec{s} \times \vec{B}$$

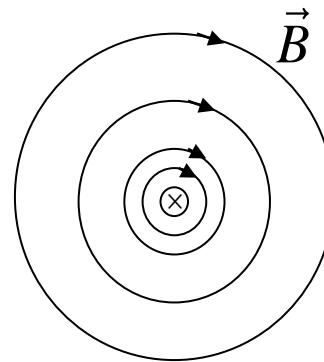
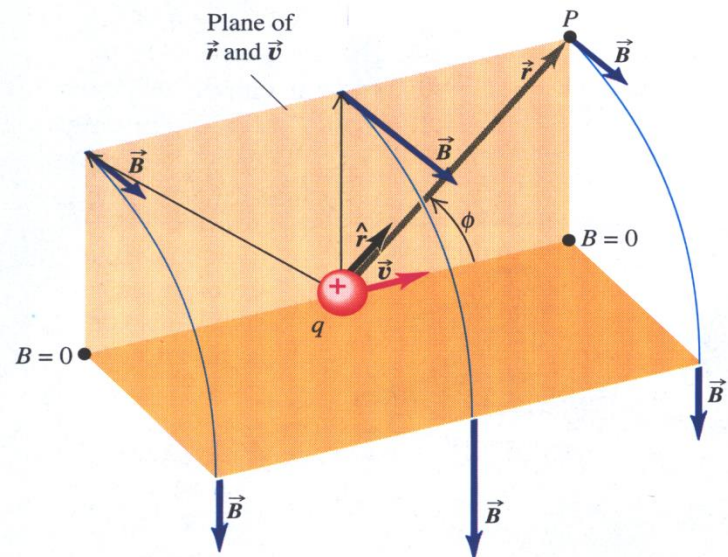
Magnetic field of a moving charge



Magnetic field of a current element

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{Id\vec{s} \times \hat{r}}{r^2}$$

$$Id\vec{s} \rightarrow q\vec{v}$$



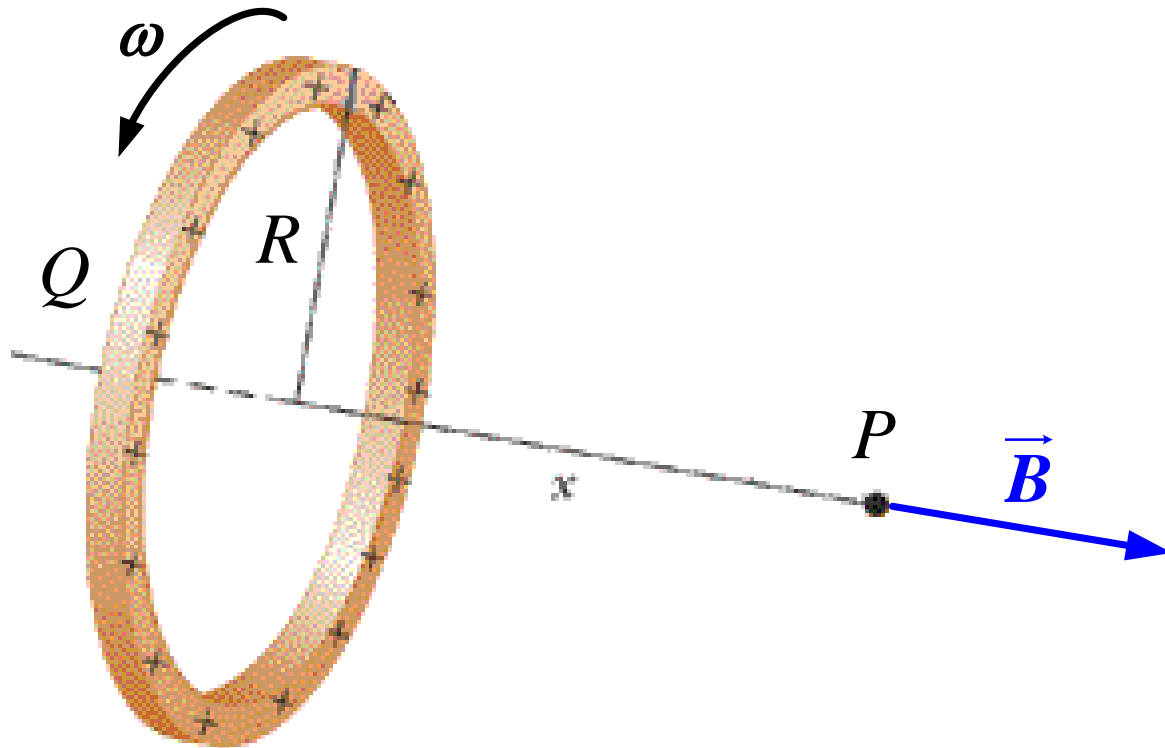
Magnetic field of a moving charge

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \hat{r}}{r^2}$$

Example



A ring of radius R has a uniform positive charge distribution, with a total charge Q . Now the ring rotates anti-clockwise with ω about its central axis. Calculate the **magnetic field** at the point P located on the axis a distance x from the center of the ring.



Example

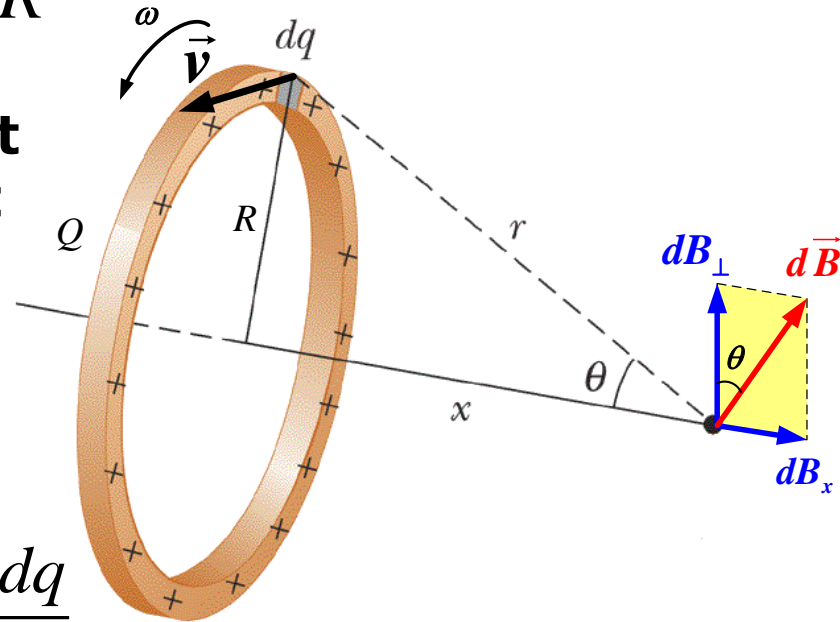


Solution I: Dividing the ring into small segment of charge dq .

$d\vec{B}$ is the field due to the charge dq ,

$$dB = \frac{\mu_0 dq}{4\pi} \frac{|\vec{v} \times \hat{r}|}{r^2} = \frac{\mu_0 v}{4\pi} \frac{dq}{r^2}, \quad v = \omega R$$

which can be resolved into a component dB_x , along the x axis, and a component dB_\perp , which is perpendicular to the x axis. By symmetry, the vector sum of all dB_\perp vanishes. The total field is only contributed by the sum of dB_x .



$$dB_x = dB \sin \theta = \frac{\mu_0 \omega R}{4\pi} \frac{R}{r} \frac{dq}{r^2} = \frac{\mu_0 \omega}{4\pi} \frac{R^2 dq}{r^3}$$

$$B = \int dB_x = \frac{\mu_0 \omega}{4\pi} \frac{R^2}{r^3} \int dq = \frac{\mu_0 \omega Q}{4\pi} \frac{R^2}{(x^2 + R^2)^{3/2}}$$

Example



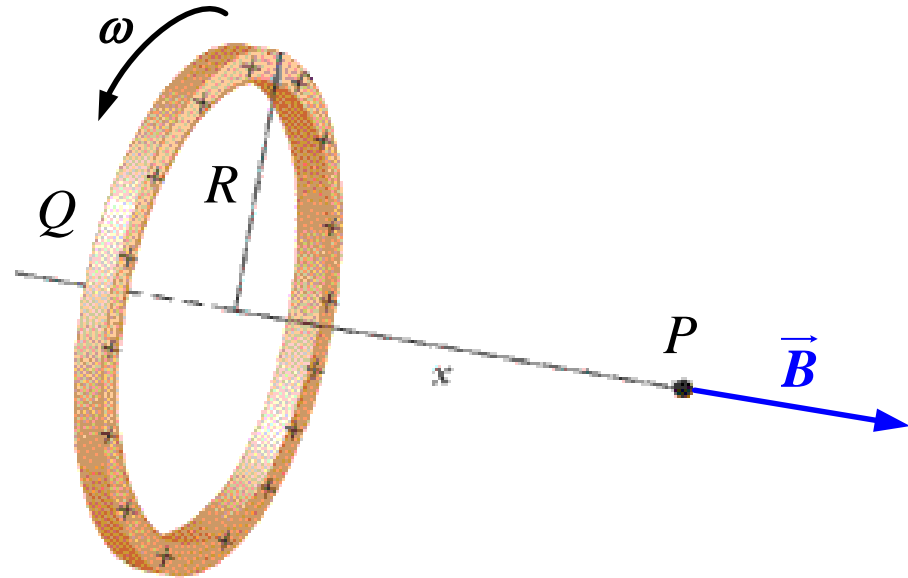
Solution II: The a rotating charge ring is equivalent to a **circular current** loop. For a circular current loop:

$$B = \frac{\mu_0 I R^2}{2(x^2 + R^2)^{3/2}}$$

where $I = \frac{Q}{T} = \frac{Q\omega}{2\pi}$

So $B = \frac{\mu_0 Q \omega R^2}{4\pi(x^2 + R^2)^{3/2}}$

$$\mu = IA = \frac{Q\omega}{2\pi} \pi R^2 = \frac{Q\omega R^2}{2}, \quad B = \frac{\mu_0}{2\pi} \frac{\mu}{(x^2 + R^2)^{3/2}}$$



Ch26 Prob. 31, 33, 36, 42 (P624)

§ 8 Ampère's Law



For electrostatic field

➡ Gauss' Law

$$\oiint_S \vec{E} \cdot d\vec{A} = \frac{q_{inside}}{\epsilon_0},$$

For magnetic field

$$\oiint_S \vec{B} \cdot d\vec{A} = 0$$

➡ Circulation Law

$$\oint_L \vec{E} \cdot d\vec{s} = 0,$$

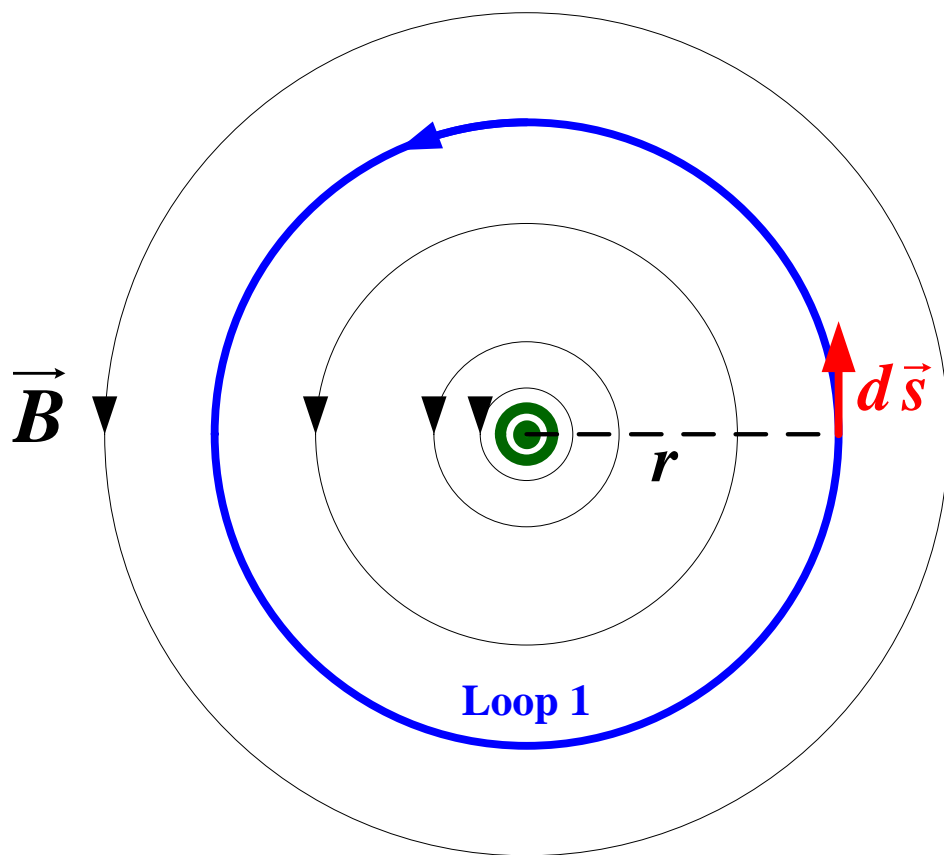
$$\oint_L \vec{B} \cdot d\vec{s} = ?$$

Ampère's Law



■ The line integral around a **loop** near a long, straight current-carrying wire.

➡ The circle loop is centered on the wire, the direction of loop is **right-hand** related to the direction of the current.

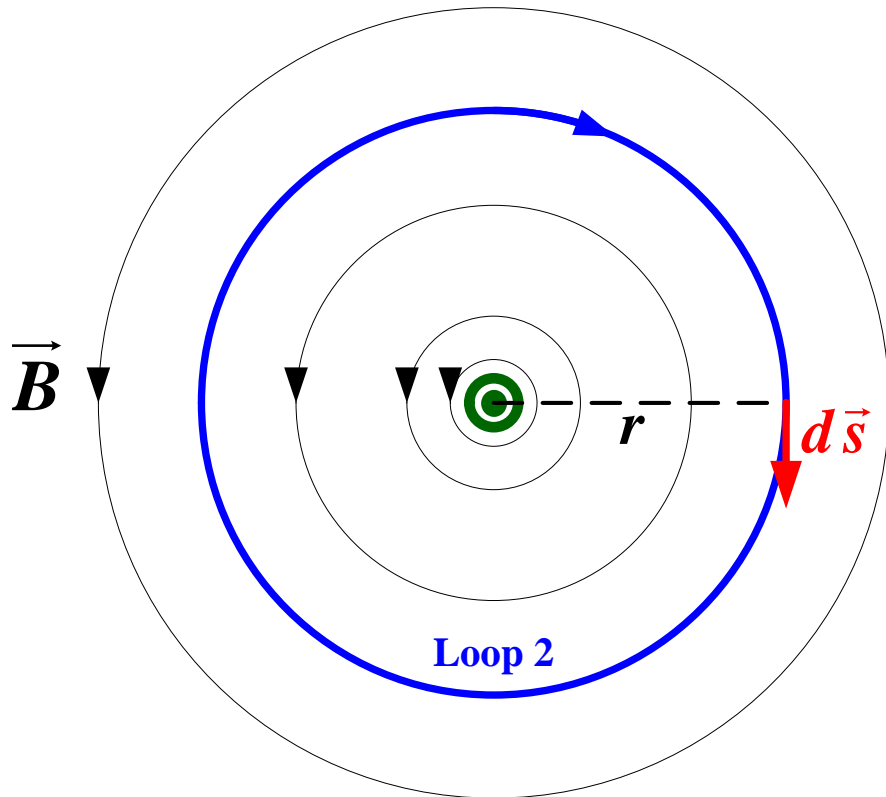


$$\begin{aligned}\oint_{L_1} \vec{B} \cdot d\vec{s} &= \oint_{L_1} B ds \\ &= B \oint_{L_1} ds \\ &= \frac{\mu_0 I}{2\pi r_1} (2\pi r_1) \\ &= \mu_0 I\end{aligned}$$

Ampère's Law



- ➡ The same circle loop but in **opposite** direction.



$$\oint_{L_2} \vec{B} \cdot d\vec{s} = -B \oint_{L_2} ds$$

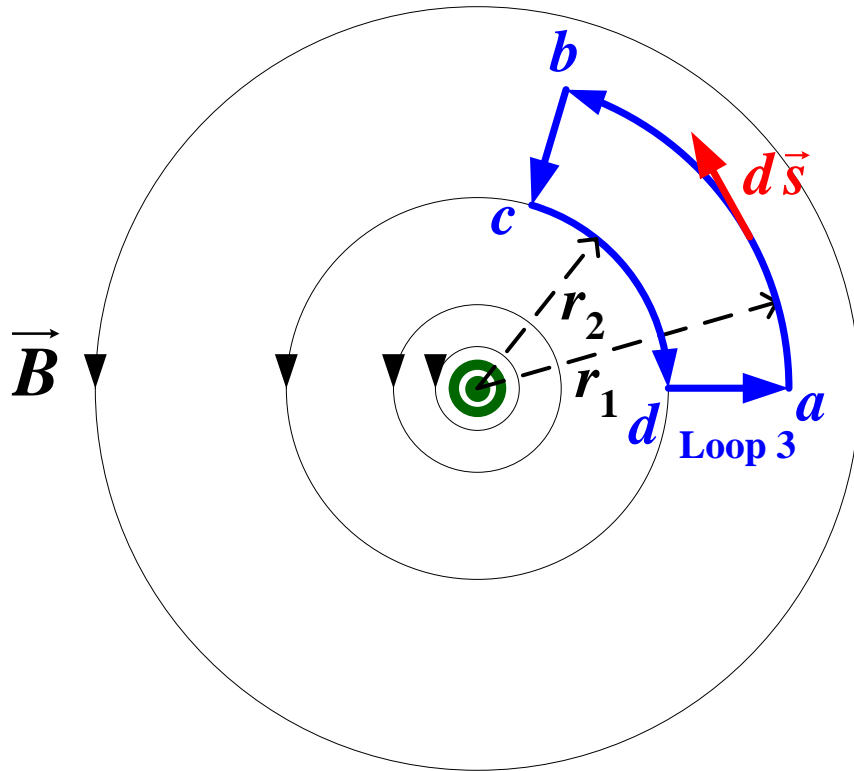
$$= -\frac{\mu_0 I}{2\pi r_1} (2\pi r_1)$$

$$= -\mu_0 I$$

Ampère's Law



➡ An integration loop does **not** enclose the wire.



$$\vec{B}_1 \cdot d\vec{s}_1 = \frac{\mu_0 I}{2\pi r_1} (r_1 d\theta) = \frac{\mu_0 I}{2\pi} d\theta$$

$$\vec{B}_2 \cdot d\vec{s}_2 = -\frac{\mu_0 I}{2\pi r_2} (r_2 d\theta) = -\frac{\mu_0 I}{2\pi} d\theta$$

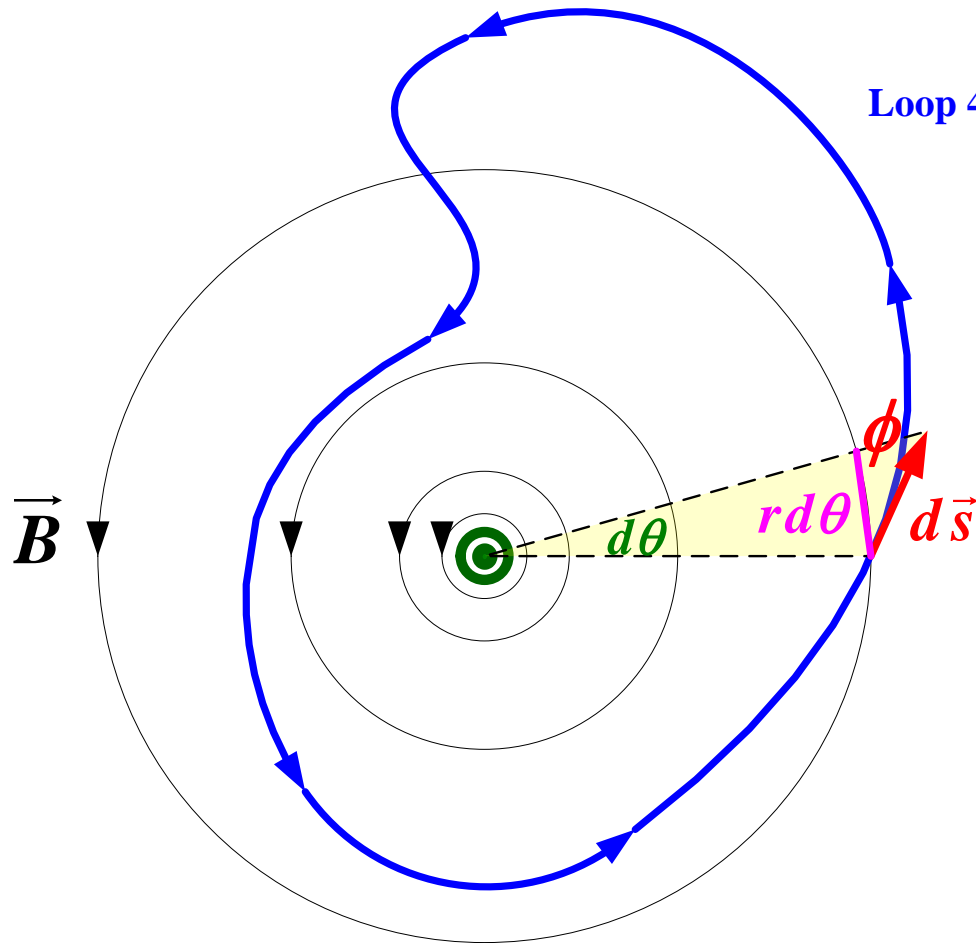
$$\oint_{L_3} \vec{B} \cdot d\vec{s} = \int_a^b B_1 ds + \int_b^c B ds \cos \frac{\pi}{2} + \int_c^d (-B_2) ds + \int_d^a B ds \cos \frac{\pi}{2}$$

$$= 0$$

Ampère's Law



- ➡ A more general loop that **encloses** the wire.



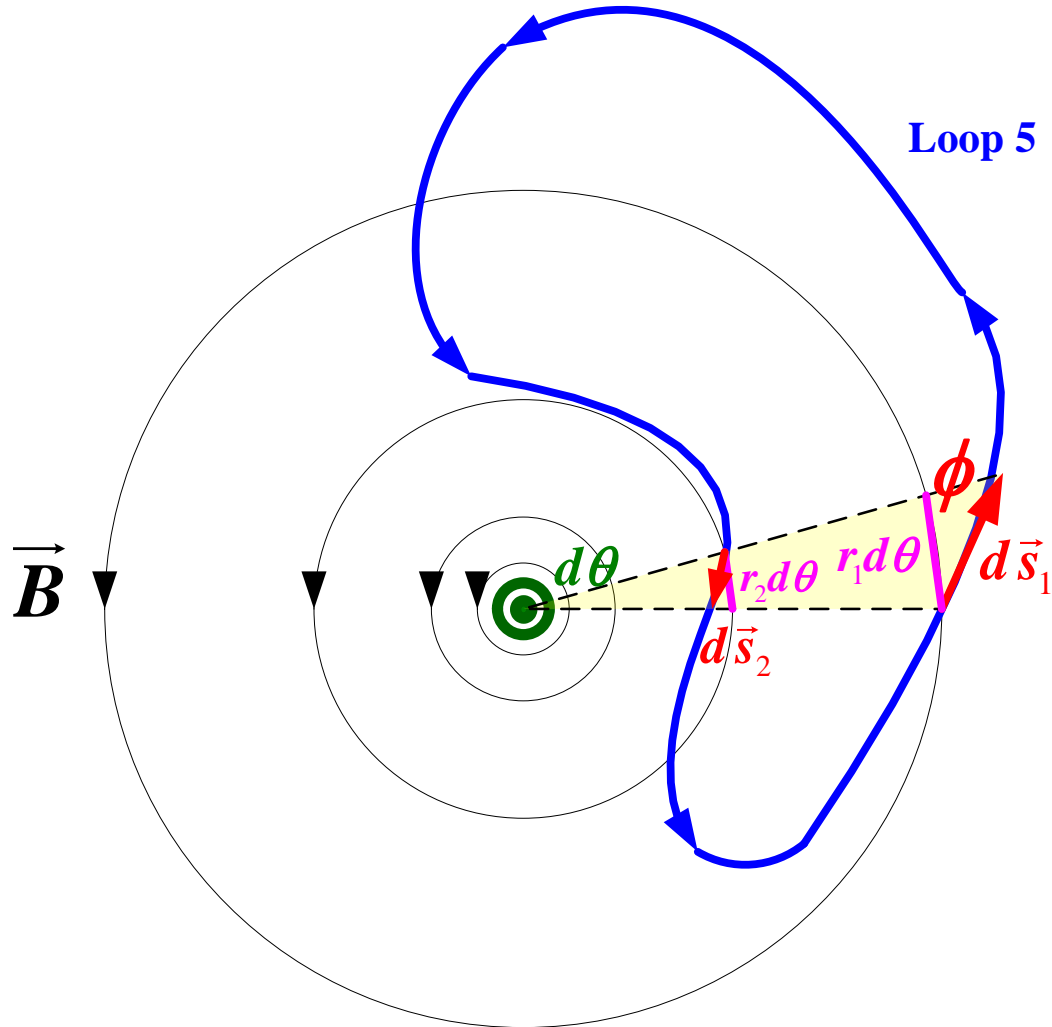
$$ds \cos \phi = r d\theta$$

$$\begin{aligned}\oint_{L_4} \vec{B} \cdot d\vec{s} &= \oint_{L_4} B ds \cos \phi \\ &= \oint_{L_4} \frac{\mu_0 I}{2\pi r} (r d\theta) \\ &= \frac{\mu_0 I}{2\pi} \oint_{L_4} d\theta \\ &= \mu_0 I\end{aligned}$$

Ampère's Law



➡ A more general loop that does **not** enclose the wire.



$$\begin{aligned}
 \vec{B}_1 \cdot d\vec{s}_1 &= B_1 ds_1 \cos \phi_1 \\
 &= \frac{\mu_0 I}{2\pi r_1} (r_1 d\theta) \\
 &= \frac{\mu_0 I}{2\pi r_2} (r_2 d\theta) \\
 &= -\vec{B}_2 \cdot d\vec{s}_2
 \end{aligned}$$

$$\oint_{L_5} \vec{B} \cdot d\vec{s} = 0$$

Ampère's Law

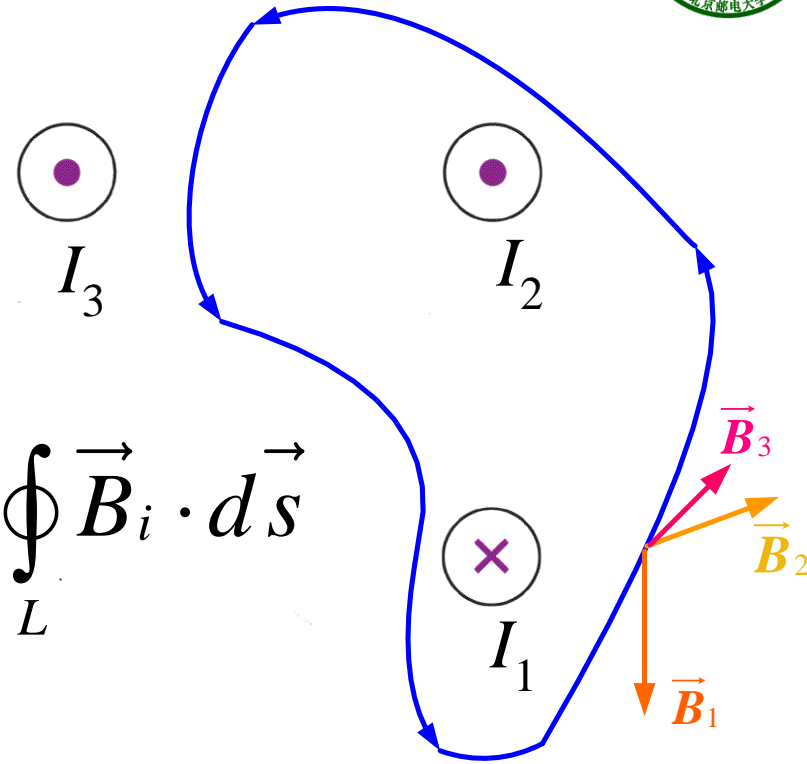


■ Ampère's Law

➡ For **any** loop with **any** shape

$$\vec{B} = \sum_i \vec{B}_i$$

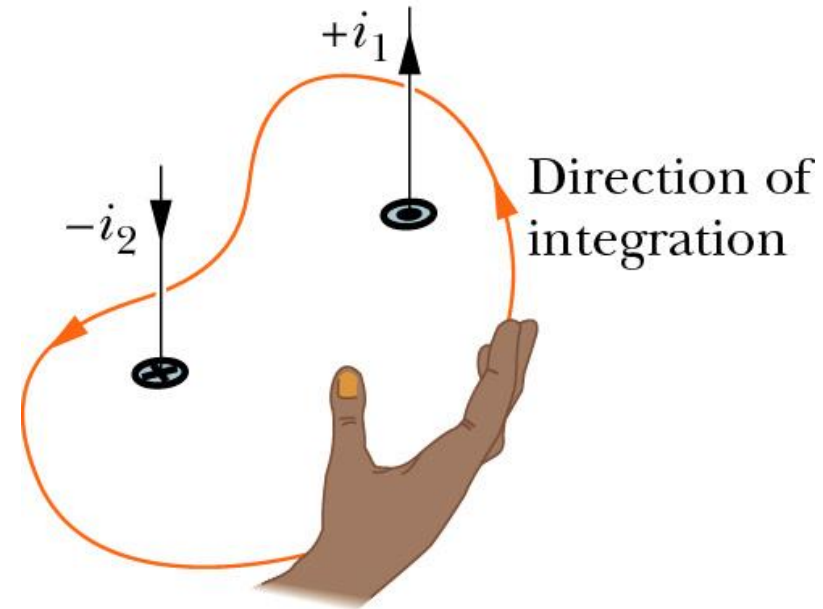
$$\oint_L \vec{B} \cdot d\vec{s} = \oint_L \sum_i \vec{B}_i \cdot d\vec{s} = \sum_i \oint_L \vec{B}_i \cdot d\vec{s}$$



$$\oint_L \vec{B}_i \cdot d\vec{s} = \begin{cases} \mu_0 I & I \text{ within the loop, right-hand rule direction} \\ -\mu_0 I & I \text{ within the loop, left-hand rule direction} \\ 0 & I \text{ not within the loop} \end{cases}$$

➡ Ampère's Law:

$$\oint_L \vec{B} \cdot d\vec{s} = \mu_0 I_{\text{encl}}$$



The line integral of magnetic field along a loop equals μ_0 times the **algebra sum** of the currents **enclosed** or linked by the loop.

■ Calculation of **electric field**:

- ➔ Find the total electric field by summing all the $d\vec{E}$
- ➔ For a symmetric charge distribution, it is often easier to use Gauss's law to find E.

$$d\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2} \hat{r}$$

$$\oiint_S \vec{E} \cdot d\vec{A} = \frac{q_{\text{encl}}}{\epsilon_0}$$

■ Calculation of **magnetic field**:

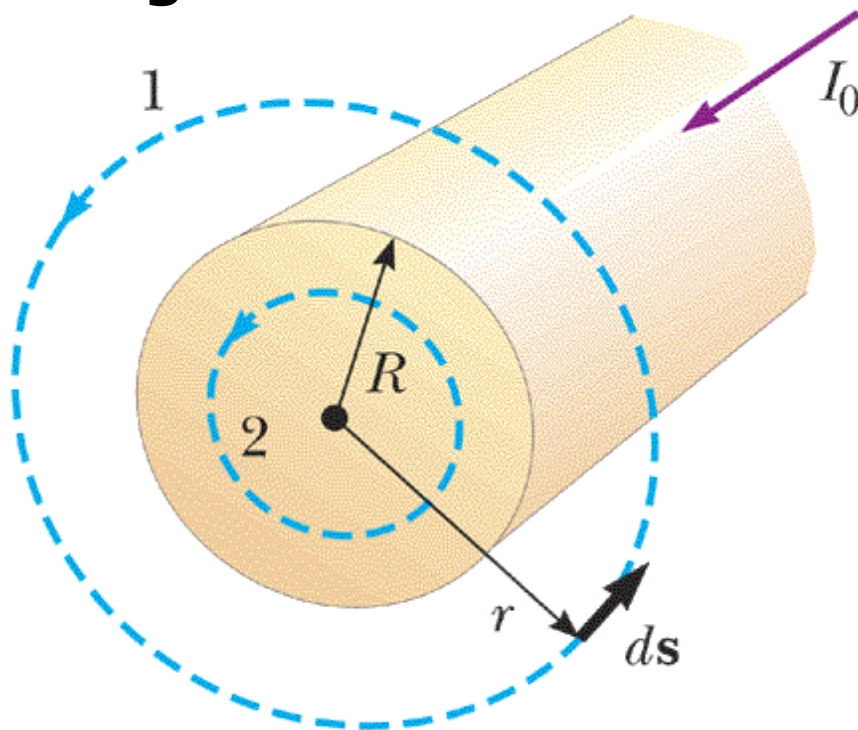
- ➔ Find the total magnetic field by summing all the $d\vec{B}$
- ➔ Gauss' law for magnetism can't be used to determine the magnetic field produced by a particular current distribution. Is there a law which plays the similar role in magnetism as Gauss's law in electrics?

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{Id\vec{s} \times \hat{r}}{r^2}$$

$$\oint_L \vec{B} \cdot d\vec{s} = \mu_0 I_{\text{encl}}$$

Example: The magnetic field created by a long, straight cylindrical wire

A **long**, straight **cylindrical** wire of radius R carries a steady current I_0 that is uniformly distributed through the cross-section of the wire. Calculate the **magnetic field** a distance r from the center of the wire in the regions $r \geq R$ and $r < R$.



The magnetic field created by a long, straight cylindrical wire



Solution: For $r \geq R$, we choose loop 1, a circle of radius r centered at wire.

$$\oint_1 \vec{B} \cdot d\vec{s} = \oint_1 B ds = B \oint_1 ds = B(2\pi r) = \mu_0 I_0$$

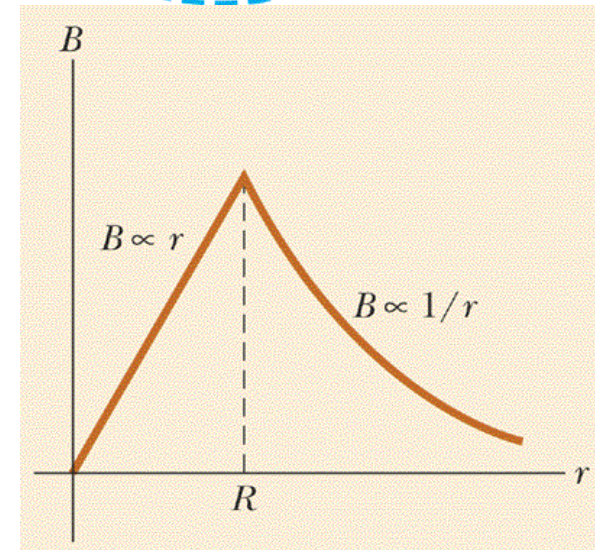
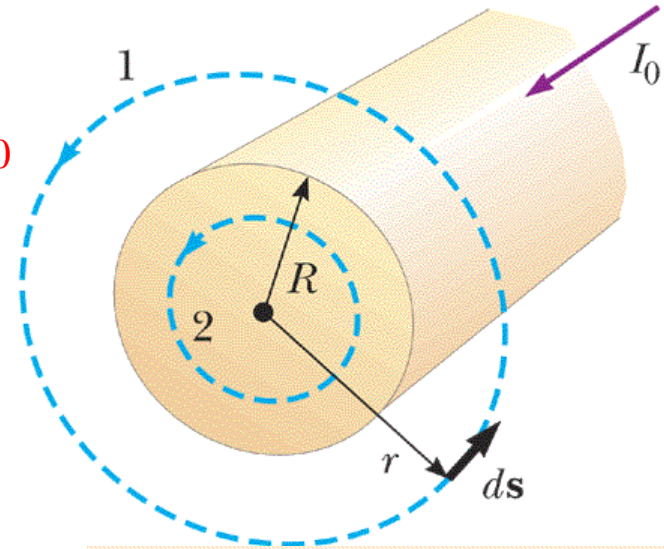
$$B = \frac{\mu_0 I_0}{2\pi r} \quad (\text{for } r \geq R)$$

For $r < R$, we choose circular loop 2.

$$I_{encl} = \frac{I_0}{\pi R^2} (\pi r^2) = \frac{r^2}{R^2} I_0$$

$$\oint_2 \vec{B} \cdot d\vec{s} = B(2\pi r) = \mu_0 I_{encl} = \mu_0 \left(\frac{r^2}{R^2} I_0 \right)$$

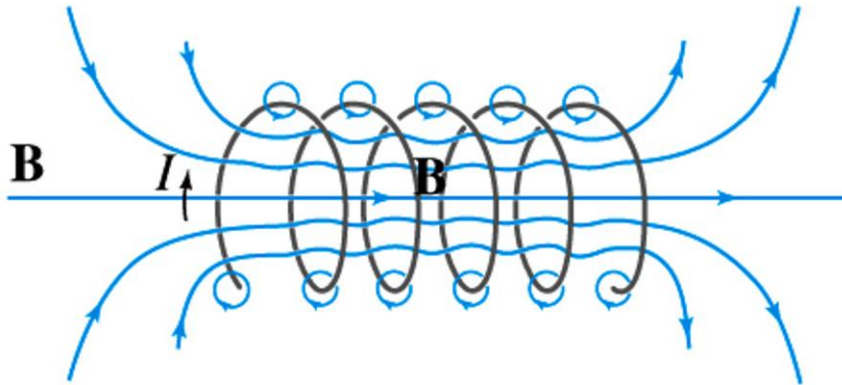
$$B = \frac{\mu_0 I_0}{2\pi R^2} r \quad (\text{for } r < R)$$



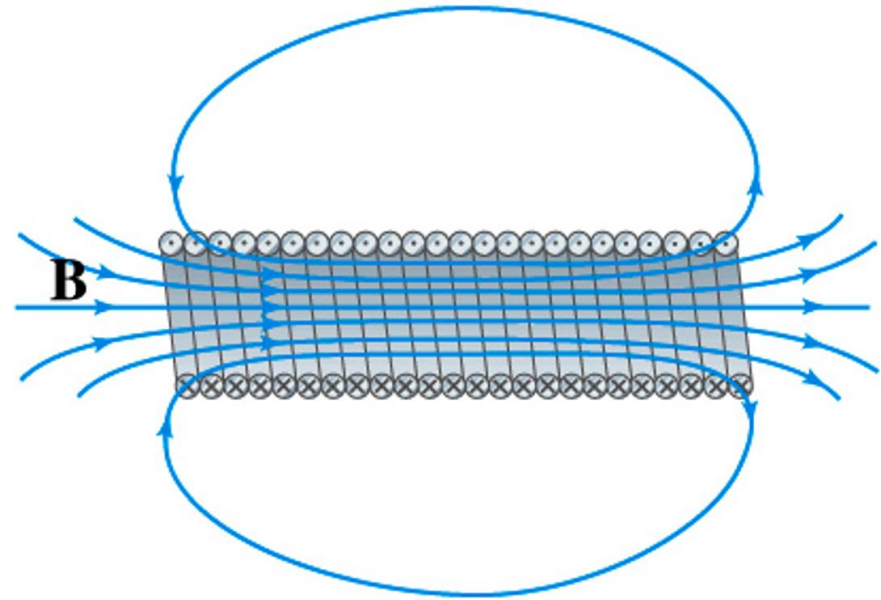
Example: a **solenoid** (螺线管)



A **ideal** solenoid: its turns are **closely** spaced and its length is **large** compared with its radius. For an ideal solenoid, the field outside the solenoid is **zero**, and the field inside is **uniform**. Calculate the **magnetic field** inside an ideal solenoid carrying a current I . The number of turns per unit length is n .



Loosely spaced turns



Closely spaced turns

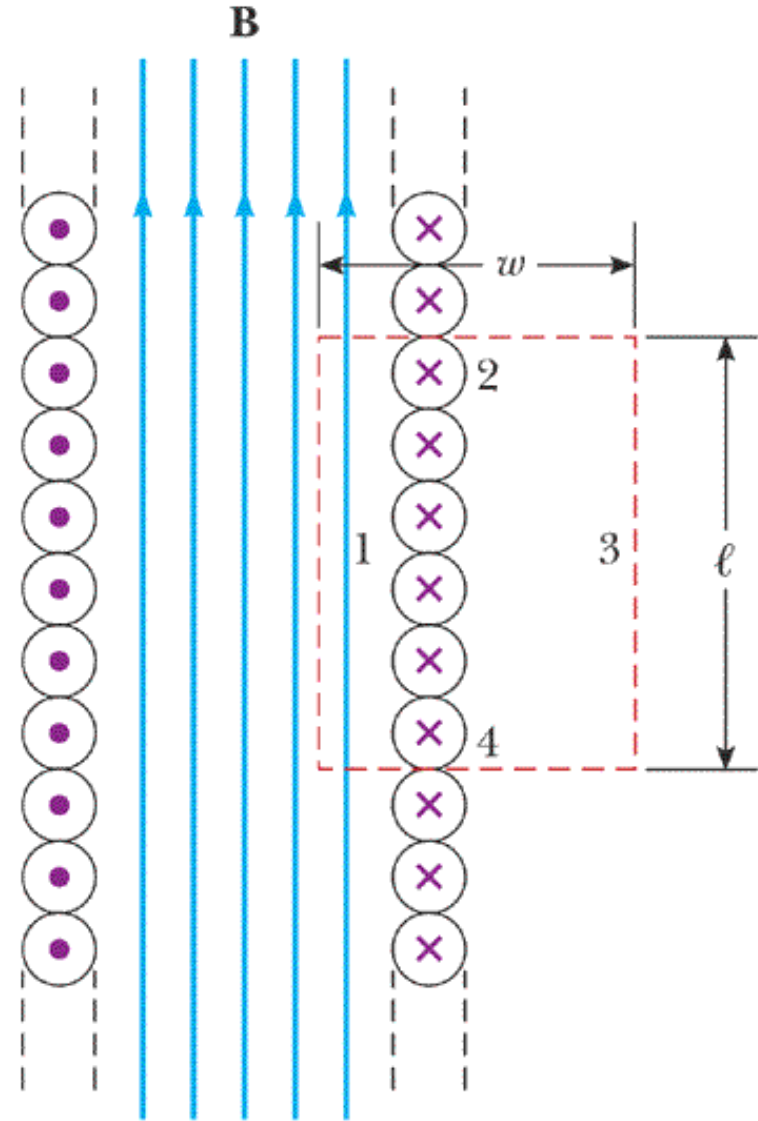
The magnetic field created by a solenoid



Solution: Choose a rectangular loop of length l and width w .

$$\begin{aligned}\oint_L \vec{B} \cdot d\vec{s} &= \int_1 \vec{B} \cdot d\vec{s} + \int_2 \vec{B} \cdot d\vec{s} \\ &+ \int_3 \vec{B} \cdot d\vec{s} + \int_4 \vec{B} \cdot d\vec{s} \\ &= \int_1 \vec{B} \cdot d\vec{s} = B \int_1 ds = Bl \\ &= \mu_0 (NI)\end{aligned}$$

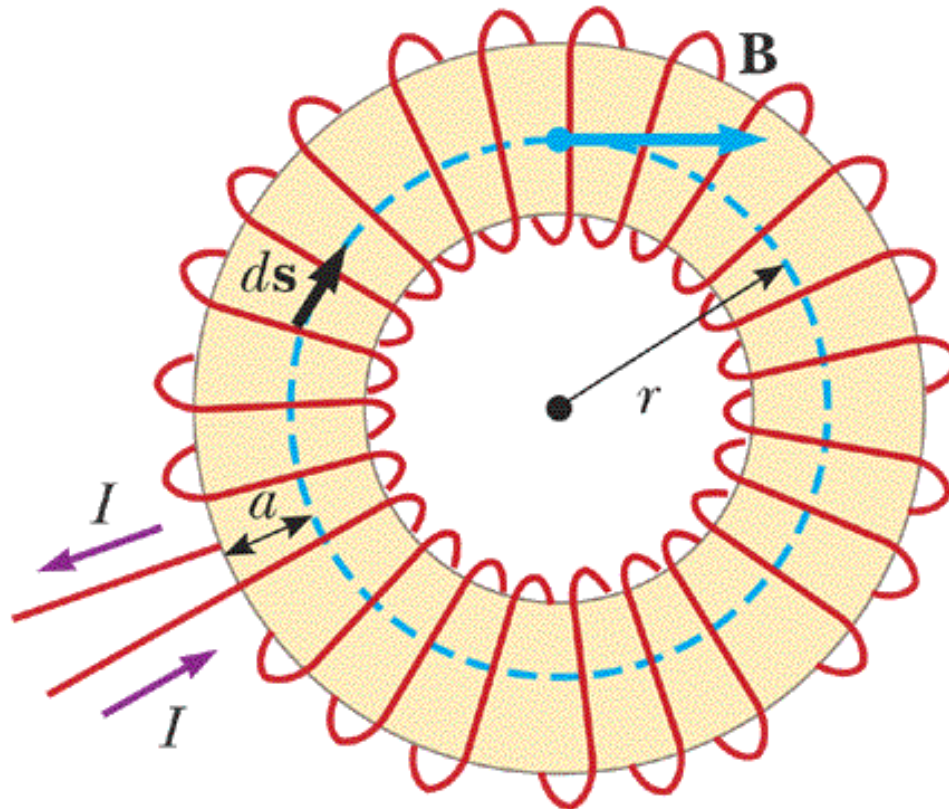
$$B = \mu_0 \frac{N}{l} I = \mu_0 n I$$



Example: a **toroid** (螺绕环)



A toroid has N closely spaced turns of wire carrying a current I . Calculate the **magnetic field** in the region occupied by the torus (圆环体), a distance r from the center.



The magnetic field created by a toroid solenoid (螺绕环)



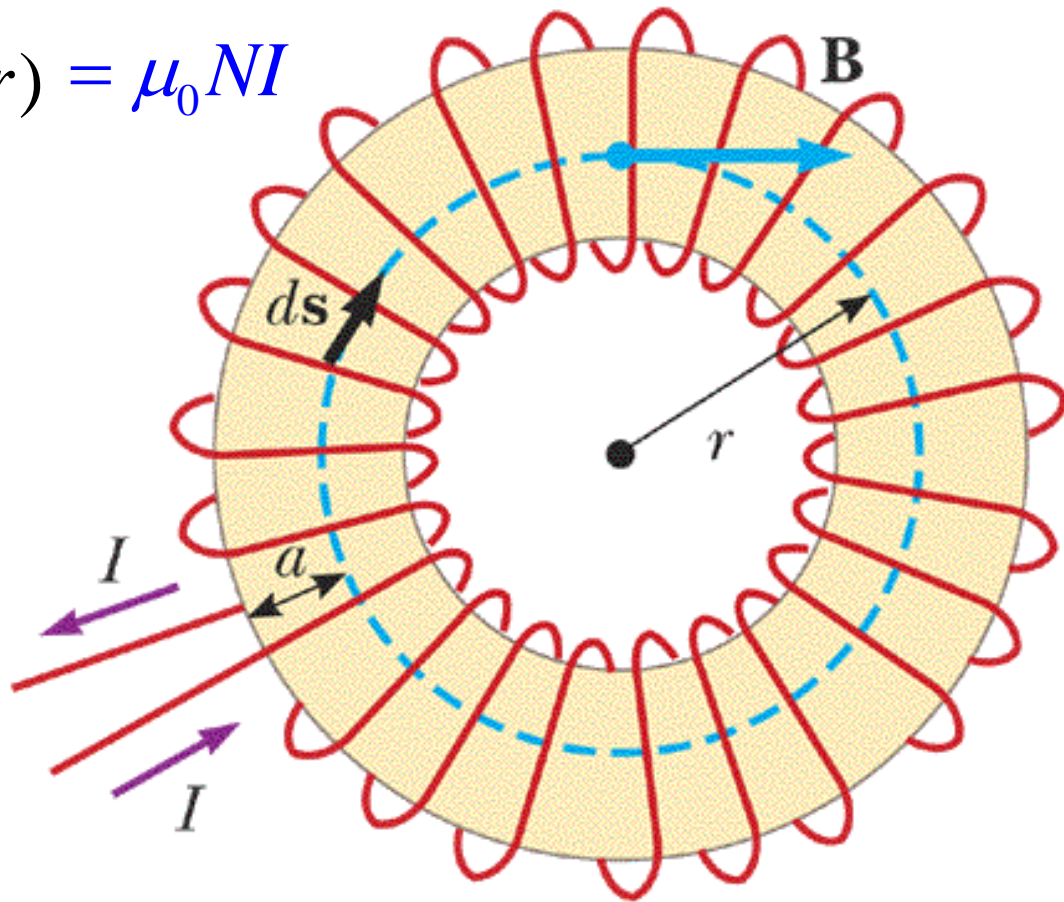
Solution: Choose a circular loop of radius of r .

$$\oint_L \vec{B} \cdot d\vec{s} = B \oint_L ds = B(2\pi r) = \mu_0 NI$$

$$B = \frac{\mu_0 NI}{2\pi r}$$

$$\xrightarrow{a \ll r}$$

$$\frac{\mu_0 NI}{2\pi r_{mid}} = \mu_0 nI$$



Ch26 Prob. 27, 28 (P624)