Ch 3.1 Introduction

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Outline

- Introduction to Fourier Representations of Signals & LTI Systems
 - Clue of this chapter
 - Complex sinusoids and Frequency Response of LTI System
 - Fourier Representations for Four Classes of Signals

Clue of this chapter

- In chapter 2, by representing signals as linear combinations of shifted impulses, we analyzed LTI systems through the convolution sum (integral).
- In this chapter, we explore an alternative representation for signals and LTI systems.
- We will represent signals as linear combinations of a set of basic signals---complex exponentials. The resulting representations are known as the continuous-time and discrete-time Fourier series and transform
 - which convert time-domain signals into frequencydomain (or spectral) representations.

A discrete-time LTI system with impulse response h[n]

Output:
$$y[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k] = \sum_{k=-\infty}^{\infty} h[k]e^{j\Omega(n-k)}$$

$$= e^{j\Omega n} \sum_{k=-\infty}^{\infty} h[k]e^{-j\Omega k} = H(e^{j\Omega})e^{j\Omega n}$$
Complex scaling factor

$$H(e^{j\Omega}) = \sum_{k=-\infty}^{\infty} h[k]e^{-j\Omega k}$$
 ~ a function of frequency Ω .

$$e^{j\Omega n} \longrightarrow h[n] \longrightarrow H(e^{j\Omega})e^{j\Omega n}$$

□ Frequency response $H(e^{j\Omega})$: the response of an *LTI* system to a sinusoidal input

- A continuous-time LTI system with impulse response h(t)

• Output:
$$y(t) = \int_{-\infty}^{\infty} h(\tau)e^{j\omega(t-\tau)}d\tau = e^{j\omega t}\int_{-\infty}^{\infty} h(\tau)e^{-j\omega\tau}d\tau = \underline{H(j\omega)}e^{j\omega t}$$

Frequency response :

$$H(j\omega) = \int_{-\infty}^{\infty} h(\tau)e^{-j\omega\tau}d\tau \quad \text{~~a function of frequency ω.}$$

★ Polar form for
$$H(j\omega)$$
: $H(j\omega) = A(\omega) + jB(\omega) = |H(j\omega)|e^{j\arg\{H(j\omega)\}}$

$$|H(j\omega)| = \sqrt{A^2(\omega) + B^2(\omega)}$$
 ~ Magnitude response

$$\arg\{H(j\omega)\} = \arctan\frac{B(\omega)}{A(\omega)}$$
 ~ Phase response

$$y(t) = |H(j\omega)| e^{j(\omega t + \arg\{H(j\omega)\})}$$

Example 3.1 RC Circuit: Frequency response

The impulse response of the system relating to the input voltage to the voltage across the capacitor in Fig. 3.2 is derived in Example 1.21 as

$$h(t) = \frac{1}{RC}e^{-t/RC}u(t)$$

 $h(t) = \frac{1}{RC} e^{-t/RC} u(t)$ Find an expression for the frequency response, and plot the magnitude and phase response.

<Sol.> Frequency response:

$$H(j\omega) = \frac{1}{RC} \int_{-\infty}^{\infty} e^{-\frac{\tau}{RC}} u(\tau) e^{-j\omega\tau} d\tau$$
$$= \frac{1}{RC} \int_{0}^{\infty} e^{-\left(j\omega + \frac{1}{RC}\right)\tau} d\tau$$

$$= \frac{1}{RC} \frac{-1}{\left(j\omega + \frac{1}{RC}\right)^{\tau}} e^{-\left(j\omega + \frac{1}{RC}\right)^{\tau}} = \frac{\frac{1}{RC}}{j\omega + \frac{1}{RC}}$$

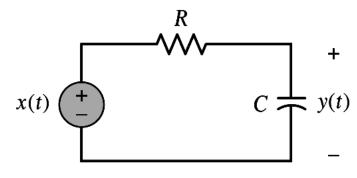


Figure 3.2 (p. 197) RC circuit for Example 3.1.

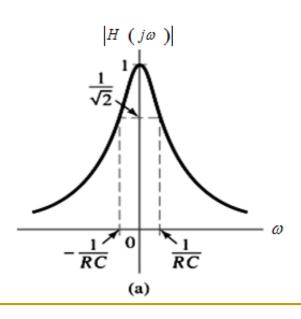
Magnitude response :

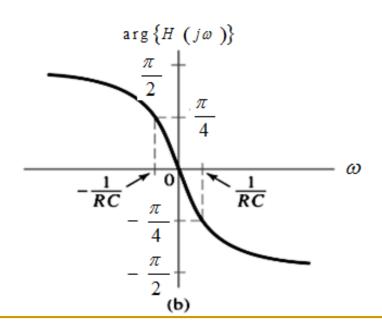
$$H(j\omega) = \frac{\frac{1}{RC}}{j\omega + \frac{1}{RC}}$$

$$|H(j\omega)| = \frac{1}{RC} / \sqrt{\omega^2 + \left(\frac{1}{RC}\right)^2}$$

Phase response:

$$arg\{H(j\omega)\} = -arctan(\omega RC)$$





Eigenvalue and eigenfunction of LTI system

■ Matrix eigenproblem: If e_k is an eigenvector of a matrix A with eigenvalue λ_k , then

$$\mathbf{A}\mathbf{e}_{k}=\lambda_{k}\mathbf{e}_{k}$$

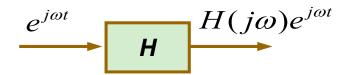
Eigenrepresentation for LTI system:

Eigenfunction: $\psi(t)$

Eigenvalue: λ

Eigenvalue and eigenfunction of LTI system

Continuous-time case:



Eigenfunction: $\psi(t) = e^{j\omega t}$

Eigenvalue: $\lambda = H(j\omega)$

For Arbitrary input = weighted superpositions of eigenfunctions

Ex. Input:
$$x(t) = \sum_{k=1}^{M} a_k e^{j\omega_k t}$$

Output:
$$y(t) = x(t) * h(t) = \sum_{k=1}^{M} a_k e^{j\omega_k t} * h(t) = \sum_{k=1}^{M} a_k H(j\omega_k) e^{j\omega_k t}$$

where
$$H(j\omega) = \int_{-\infty}^{\infty} h(\tau)e^{-j\omega\tau}d\tau$$
.

By representing arbitrary signals as weighted superpositions of eigenfunctions, we transform the operation of convolution to multiplication.

Eigenvalue and eigenfunction of LTI system

Discrete-time case:

$$e^{j\Omega n}$$
 $H(e^{j\Omega})e^{j\Omega n}$

Eigenfunction:
$$\psi[n] = e^{j\Omega n}$$

Eigenvalue: $\lambda = H(e^{j\Omega})$

Ex. Input:
$$x[n] = \sum_{k=1}^{M} a_k e^{j\Omega_k n}$$
 Output: $y[n] = \sum_{k=1}^{M} a_k H(e^{j\Omega_k}) e^{j\Omega_k n}$

Summary

- The response of an LTI system to a complex sinusoidal input lead to a characterization of system behavior that is termed the frequency response of the LTI system.
- Rather than describing system's behavior as a function of time, frequency response describe it as a function of frequency.

How to represent signals as weighted superpositions of complex sinusoidals?

Fourier Representations for Four classes of Signals

Table 3.1 Relationship between Time Properties of a Signal and the Approximate Fourier Representation

Time Property	Periodic	Nonperiodic
Continuous (t)	Fourier Series (FS)	Fourier Transform (FT)
Discrete [n]	Discrete-Time Fourier	Discrete-Time Fourier
	Series (DTFS)	Transform (DTFT)

• FS for x(t) = continuous-time signal with fundamental period T.

$$\hat{x}(t) = \sum A[k]e^{jk\omega_0 t},$$

k

where "^" denotes approximate value.

 $\omega_0 = 2\pi/T$: Fundamental frequency of x(t)

 $e^{jk\omega_0t}$: the k-th harmonic of $e^{j\omega_0t}$.

A[k]: the weight applied to the kth harmonic.



Sinusoidal Signals

Prob 1.18 Find the smallest angular frequencies for which discrete-time sinusoidal signals with the following periods would be periodic:

a)
$$N = 8$$
 $\Omega = \frac{2\pi m}{N} = \frac{2\pi m}{8} = \frac{\pi}{4} m = \frac{\pi}{4}$ when $m = 1$.

b)
$$N = 32$$
 $\Omega = \frac{2\pi m}{32} = \frac{\pi}{16} m = \frac{\pi}{16}$ when $m = 1$.

c)
$$N = 64$$
 $\Omega = \frac{2\pi m}{64} = \frac{\pi}{32} m = \frac{\pi}{32}$ when $m = 1$.

d)
$$N = 128$$
 $\Omega = \frac{2\pi m}{128} = \frac{\pi}{64} m = \frac{\pi}{64}$ when $m = 1$.

Periodic Signals: Fourier Series Representations

■ DTFS for x[n] = discrete-time signal with fundamental period N.

$$\hat{x}[n] = \sum_{k} A[k]e^{jk\Omega_0 n}$$
, $\Omega_0 = 2\pi/N$: Fundamental frequency of $x[n]$

 $= \exp(jk\Omega_o n)$ are N-periodics in the frequency index k.

$$e^{j(N+k)\Omega_0 n} = e^{jN\Omega_0 n} e^{jk\Omega_0 n} = e^{j2\pi n} e^{jk\Omega_0 n} = e^{jk\Omega_0 n}$$

There are only N distinct complex sinusoids of the form $\exp(jk\Omega_0 n)$ should be used in above equation.

$$\hat{x}[n] = \sum_{k} A[k]e^{jk\Omega_0 n} = \sum_{k=0}^{N-1} A[k]e^{jk\Omega_0 n}$$

while
$$\hat{x}(t) = \sum_k A[k]e^{jk\omega_0 t} = \sum_{k=-\infty}^{\infty} A[k]e^{jk\omega_0 t}$$

Periodic Signals: Fourier Series Representations

- Mean-square error (MSE) between the signal and its series representation
 - Continuous-time case:

$$MSE = \frac{1}{T} \int_0^T \left| x(t) - \hat{x}(t) \right|^2 dt$$

Discrete-time case:

$$MSE = \frac{1}{N} \sum_{n=0}^{N-1} |x[n] - \hat{x}[n]|^2 dt$$

The optimum weights or coefficients A[k] are obtained by minimizing the MSE between the signal and its series representation.

Nonperiodic Signals: Fourier-Transform Representations

FT of continuous-time signal:

$$\hat{x}(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

 $X(j\omega)d\omega/(2\pi)$: the weight applied to the sinusoid $e^{j\omega t}$

DTFT of discrete-time signal:

$$\hat{x}[n] = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(e^{j\Omega}) e^{j\Omega n} d\Omega = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\Omega}) e^{j\Omega n} d\Omega$$

 $X(e^{j\Omega})d\Omega/(2\pi)$: the weight applied to the sinusoid $e^{j\Omega n}$

 \square exp($j\Omega n$) are periodical with period 2π .

$$e^{j(\Omega+2\pi)n} = e^{j\Omega n}e^{j2\pi n} = e^{j\Omega n}$$

Nonperiodic Signals: Fourier-Transform Representations

▶ **Problem 3.1** Identify the appropriate Fourier representation for each of the following signals:

- (a) $x[n] = (1/2)^n u[n]$
- (b) $x(t) = 1 \cos(2\pi t) + \sin(3\pi t)$
- (c) $x(t) = e^{-t}\cos(2\pi t)u(t)$
- (d) $x[n] = \sum_{m=-\infty}^{\infty} \delta[n-20m] 2\delta[n-2-20m]$

Answers:

- (a) DTFT
- (b) FS
- (c) FT
- (d) DTFS