

Exercise 5.3.

1. (a)  $A = (1, 0)$ , (b)  $A = (1, 1)$ . (e)  $A = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$

(f)  $A = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$ . (h)  $A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \\ 1 & 1 \end{pmatrix}$ .

2.  $E = \{v_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}, v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}\}$  is a basis of  $\mathbb{R}^2$ : since  $\begin{vmatrix} 1 & 1 \\ -1 & 1 \end{vmatrix} = 2 \neq 0$ .

consider the linear transformation  $L(x) = 2x_1 e_1 + (x_1 + x_2) e_2$

we have  $L(v_1) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} = v_1 + v_2 = (v_1, v_2) \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow [L(v_1)]_E = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$   
 $L(v_2) = \begin{pmatrix} 2 \\ 2 \end{pmatrix} = 2v_2 = (v_1, v_2) \begin{pmatrix} 0 \\ 2 \end{pmatrix} \Rightarrow [L(v_2)]_E = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$

the matrix representing  $L$  relative to basis  $E$  is

$$A = ([L(v_1)]_E, [L(v_2)]_E) = \begin{pmatrix} 1 & 0 \\ 1 & 2 \end{pmatrix}.$$

Exercise 5.4.

6. Consider the linear transformation  $L: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$L(x) = (x_1 \cos \alpha + x_2 \sin \alpha) e_1 + (x_2 \cos \alpha - x_1 \sin \alpha) e_2$$

(a).  $E = \{e_1, e_2\}$  standard basis of  $\mathbb{R}^2$ .

$$L(e_1) = \begin{pmatrix} \cos \alpha \\ -\sin \alpha \end{pmatrix}, \quad L(e_2) = \begin{pmatrix} \sin \alpha \\ \cos \alpha \end{pmatrix}.$$

$\Rightarrow$  the matrix representing  $L$  relative to basis  $E$  is

$$A = (L(e_1), L(e_2)) = \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix}.$$





(b)  $F = \left\{ v_1 = \begin{pmatrix} \cos\beta \\ -\sin\beta \end{pmatrix}, v_2 = \begin{pmatrix} \sin\beta \\ \cos\beta \end{pmatrix} \right\}$  is a basis of  $\mathbb{R}^2$ :  $\begin{vmatrix} \cos\beta & \sin\beta \\ -\sin\beta & \cos\beta \end{vmatrix} = 1 \neq 0$

we have  $L(v_1) = \begin{pmatrix} \cos\beta \cos\alpha - \sin\beta \sin\alpha \\ -\sin\beta \cos\alpha - \cos\beta \sin\alpha \end{pmatrix} = \cos\alpha \begin{pmatrix} \cos\beta \\ -\sin\beta \end{pmatrix} - \sin\alpha \begin{pmatrix} \sin\beta \\ \cos\beta \end{pmatrix}$

$$= (v_1, v_2) \begin{pmatrix} \cos\alpha \\ -\sin\alpha \end{pmatrix} \Rightarrow [L(v_1)]_F = \begin{pmatrix} \cos\alpha \\ -\sin\alpha \end{pmatrix}$$

$$L(v_2) = \begin{pmatrix} \sin\beta \cos\alpha + \cos\beta \sin\alpha \\ \cos\beta \cos\alpha - \sin\beta \sin\alpha \end{pmatrix} = \sin\alpha \begin{pmatrix} \cos\beta \\ -\sin\beta \end{pmatrix} + \cos\alpha \begin{pmatrix} \sin\beta \\ \cos\beta \end{pmatrix}$$

$$= (v_1, v_2) \begin{pmatrix} \sin\alpha \\ \cos\alpha \end{pmatrix} \Rightarrow [L(v_2)]_F = \begin{pmatrix} \sin\alpha \\ \cos\alpha \end{pmatrix}$$

$\Rightarrow$  matrix representing  $L$  relative to basis  $F$  is

$$B = ([L(v_1)]_F, [L(v_2)]_F) = \begin{pmatrix} \cos\alpha & \sin\alpha \\ -\sin\alpha & \cos\alpha \end{pmatrix}.$$

Remark. We can also compute  $B$  using the transition matrix  $S$  from basis  $F$  to standard basis  $E$ .

$$S = (v_1, v_2) = \begin{pmatrix} \cos\beta & \sin\beta \\ -\sin\beta & \cos\beta \end{pmatrix}, \quad S^{-1} = S^T = \begin{pmatrix} \cos\beta & -\sin\beta \\ \sin\beta & \cos\beta \end{pmatrix}$$

then  $B = S^{-1}AS = \begin{pmatrix} \cos\beta & -\sin\beta \\ \sin\beta & \cos\beta \end{pmatrix} \begin{pmatrix} \cos\alpha & \sin\alpha \\ -\sin\alpha & \cos\alpha \end{pmatrix} \begin{pmatrix} \cos\beta & \sin\beta \\ -\sin\beta & \cos\beta \end{pmatrix}$

$$= \begin{pmatrix} \cos\alpha & \sin\alpha \\ -\sin\alpha & \cos\alpha \end{pmatrix}.$$

(c). The invertible matrix  $S$  can be taken as the transition matrix from  $F$  to  $E$ ; or simply taken  $S = I$ . (since  $A = B$  in this example.)



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8.  $B \sim A \Rightarrow \exists S$  invertible,  $B = S^{-1}AS$ .

$A$  is invertible  $\Rightarrow |A| \neq 0$ .  $A^{-1} = \frac{1}{|A|} \text{adj } A$ ,  $\text{adj } A = |A| \cdot A^{-1}$ .

$|B| = |S^{-1}AS| = |S^{-1}| \cdot |A| \cdot |S| = |A| \neq 0$ . so  $B$  is also invertible.

$$\text{adj } B = |B| \cdot B^{-1} = |A| \cdot (S^{-1}AS)^{-1}$$

$$= |A| \cdot S^{-1}A^{-1}S$$

$$= S^{-1}(|A|A^{-1})S = S^{-1}(\text{adj } A)S$$

$\Rightarrow \text{adj } B \sim \text{adj } A$ .

### Exercise 6.1.

6. (a). Indeed, we have checked the positivity of  $\langle \cdot, \cdot \rangle$  in class.

$$\bullet \langle f, g \rangle = \int_{-\pi}^{\pi} f(x)g(x)dx = \int_{-\pi}^{\pi} g(x)f(x)dx = \langle g, f \rangle.$$

$$\begin{aligned} \bullet \langle \alpha f + \beta g, h \rangle &= \int_{-\pi}^{\pi} (\alpha f + \beta g)(x) h(x) dx \\ &= \alpha \int_{-\pi}^{\pi} f(x) h(x) dx + \beta \int_{-\pi}^{\pi} g(x) h(x) dx \\ &= \alpha \langle f, h \rangle + \beta \langle g, h \rangle. \end{aligned}$$

$\Rightarrow \langle \cdot, \cdot \rangle$  is an inner product on  $C[-\pi, \pi]$ .

$$\begin{aligned} \text{(b). } \langle v_m, u_n \rangle &= \int_{-\pi}^{\pi} \cos(mx) \sin(nx) dx \\ &= \int_{-\pi}^{\pi} \frac{1}{2} (\sin(n+m)x - \sin(n-m)x) dx. \end{aligned}$$

$$= 0.$$

$\forall n, m \in \mathbb{N}_0$ ,



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Remark. One can show that in  $C[a, b]$ ,

$$\bullet \quad N_m = \cos(mx) \perp N_n = \cos(nx), \quad \forall m \neq n.$$

$$\bullet \quad U_m = \sin(mx) \perp U_n = \sin(nx), \quad \forall m \neq n, m, n \geq 1.$$

