DRIVECORE

VER 1.2

Enter an ip address to connect

Connect to a recent ip address
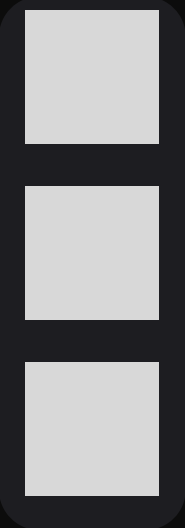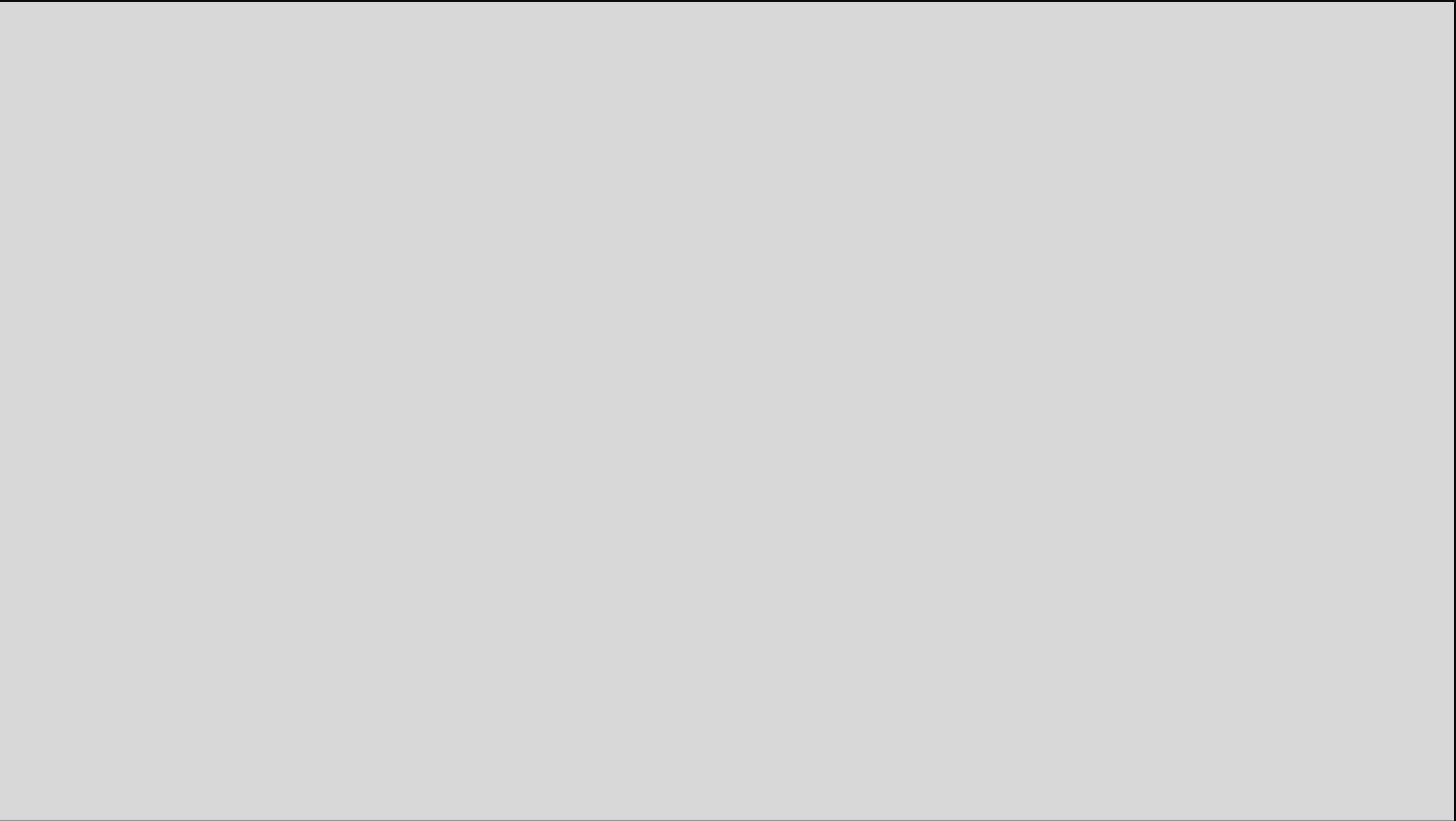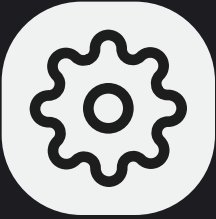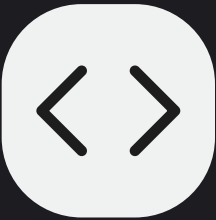
Connection Status

No Connection

Follow the project on GitHub
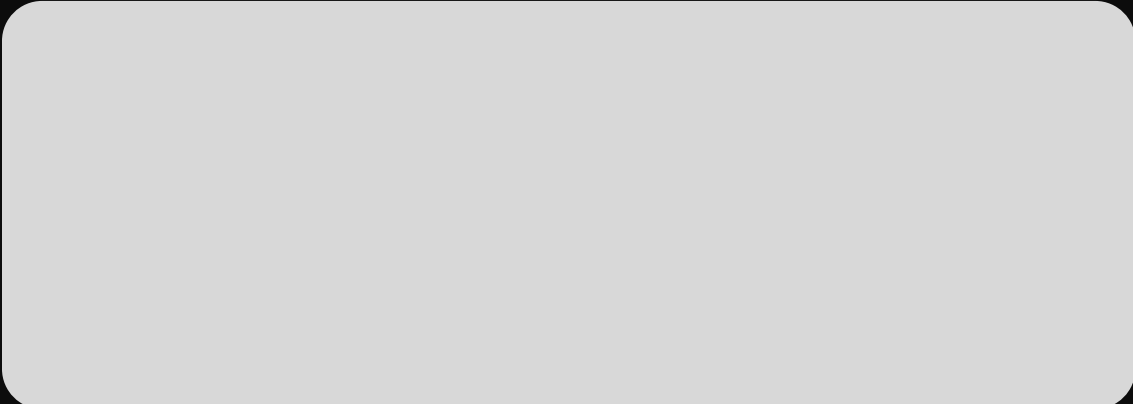
https://github.com/HalfasleepDev/DriveCore

About

DriveCore is a modular and scalable platform designed for controlling RC vehicles with the potential for AI-powered autonomy. Built using Python, OpenCV, and a Raspberry Pi, DriveCore serves as the foundation for both manual and automated vehicle operation, integrating computer vision, sensor fusion, and remote control capabilities.

Current vehicle connected to: Unknown

Accelerate : [W]   Turn Left : [A]   Reverse : [S]   Turn Right : [D]   Brake : [SPACE]