DRIVECORE

VER 1.0

Enter an ip address to connect

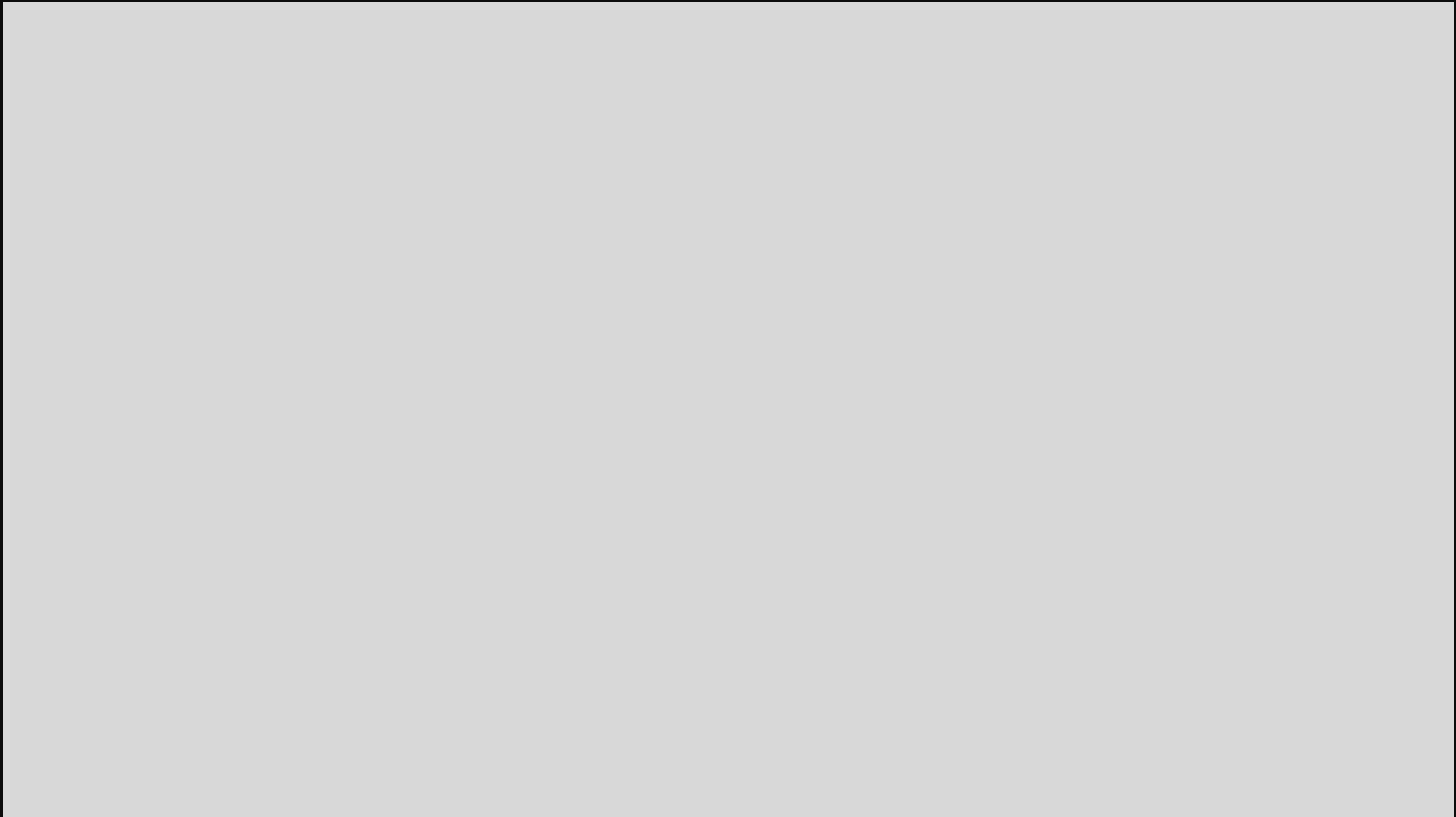**Connect to a recent ip address**

Follow the project on GitHub

https://github.com/HalfasleepDev/DriveCore

About

DriveCore is a modular and scalable platform designed for controlling RC vehicles with the potential for AI-powered autonomy. Built using Python, OpenCV, and a Raspberry Pi, DriveCore serves as the foundation for both manual and automated vehicle operation, integrating computer vision, sensor fusion, and remote control capabilities.

Key bindings

[W] : Accelerate
[A] : Turn Left
[S] : Reverse/Break
[D] : Turn Right

Current vehicle connected to: Unknown