

Boundary conditions for molecular dynamics

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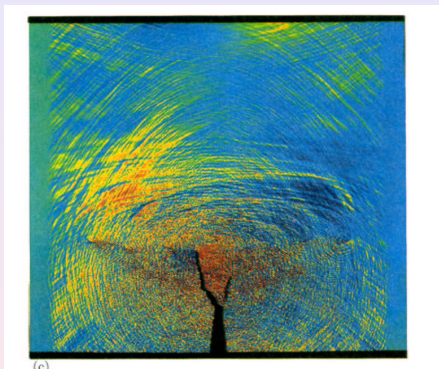
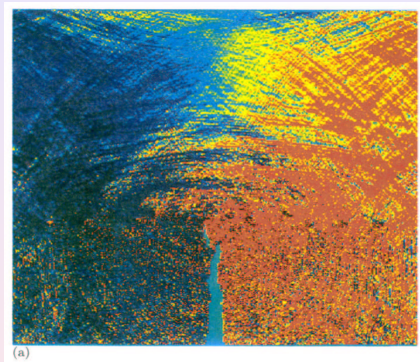
Institute for Math and its Applications

joint work with

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Princeton University

Motivation

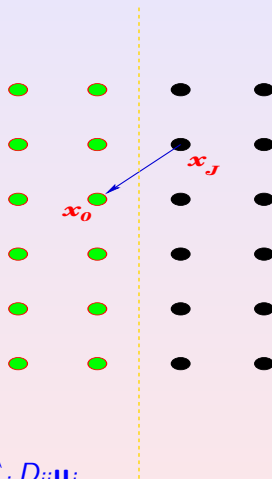


Holian and Ravelo PRB 1994

Outline

- ▶ Exact boundary conditions
- ▶ Phonon reflection
- ▶ Variational formulation
- ▶ Examples
- ▶ Application to fracture simulation

Problem setup



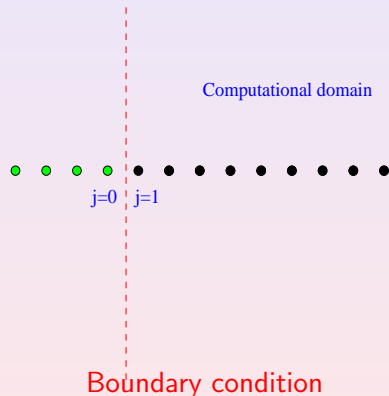
$$m\ddot{\mathbf{u}}_i = -\sum_j D_{ij}\mathbf{u}_j$$

$$m\ddot{\mathbf{u}}_i = -\frac{\partial V}{\partial \mathbf{x}_i}.$$

MD boundary condition: a 1D example

Exact boundary condition can be obtained by solving the **half space problem**:

$$\begin{cases} \ddot{u}_j &= u_{j+1} - 2u_j + u_{j-1}, & j \leq 0 \\ u_j(0) &= 0, \quad v_j(0) = 0, & j \leq 0 \\ u_b(t) &= u_1(t). \end{cases}$$



1D example: exact boundary condition

Exact boundary condition (Adelman et. al. 1974, 1976) :

$$u_0(t) = \int_0^t \beta(t-s)u_1(s)ds, j \leq 0$$

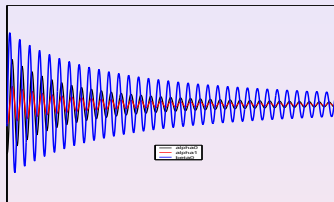
$$\beta(t) = \frac{J_2(2t)}{t}.$$

Faster decay by using more atoms

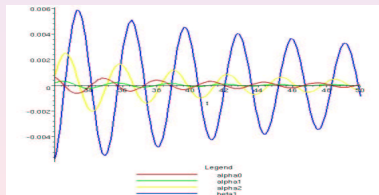
$$u_0 = \sum_{j=1}^J \int_0^t \alpha_j(t-s) u_j(s) ds$$

$$\alpha(t) \sim \frac{C}{t^J}, t \rightarrow +\infty.$$

J=2



J=3



General lattice

Linearized equation of motion,

$$M\ddot{\mathbf{u}}_{i,j,k} = \sum_{l,m,n} D_{i-l,j-m,k-n} \mathbf{u}_{l,m,n},$$

Fourier transform in the j and k direction,

$$M\ddot{\mathbf{U}}_i(\eta, \zeta) = \sum_l \mathcal{D}_{i-l}(\eta, \zeta) \mathbf{U}_l(\eta, \zeta).$$

$$\mathbf{U} = \mathcal{F}_{j \rightarrow \eta, k \rightarrow \zeta}[\mathbf{u}], \mathcal{D} = \mathcal{F}_{j \rightarrow \eta, k \rightarrow \zeta}[\mathcal{D}].$$

Exact boundary condition:

$$\mathbf{u}_{0,j,k}(t) = \sum_m \sum_n \int_0^t \theta_{l,j-m,k-n}(t-\tau) \mathbf{u}_{l,m,n}(\tau) d\tau.$$

Existing work

- ▶ W. Cai, M. de Koning, V. V. Bulatov and S. Yip 2000,
- ▶ G.J. Wagner, G.K. Eduard and W.K. Liu 2004,
- ▶ H.S. Park, E.G.Karpov, W.K. Liu and P.A. Klein 2004.

Practical issue

Exact boundary conditions:

- ▶ **nonlocal** in both space and time
- ▶ premature truncation leads to large reflection
- ▶ not feasible in a multiscale method

Objectives:

- ▶ **local** boundary conditions
- ▶ given stencil, find the BC with minimal phonon reflection
- ▶ take into account of external loading

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An analogy: boundary condition for the wave equation: ABC (Engquist and Majda 1979), and many other methods.

Phonon spectrum

Harmonic approximation:

$$m_i \ddot{\mathbf{u}}_i = - \sum_j D_{i-j} \mathbf{u}_j.$$

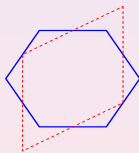
Dynamic matrix:

$$M\mathcal{D}(\mathbf{k}) = \sum_j D_j e^{-i\mathbf{r}_j \cdot \mathbf{k}},$$

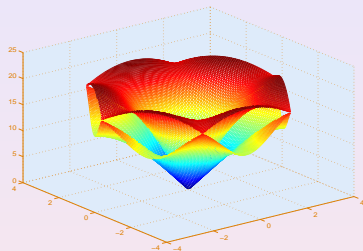
Phonon spectrum

$$\mathcal{D}(\mathbf{k}) \boldsymbol{\varepsilon}_s(\mathbf{k}) = \lambda_s \boldsymbol{\varepsilon}_s(\mathbf{k}).$$

Brillouin zone: triangular lattice

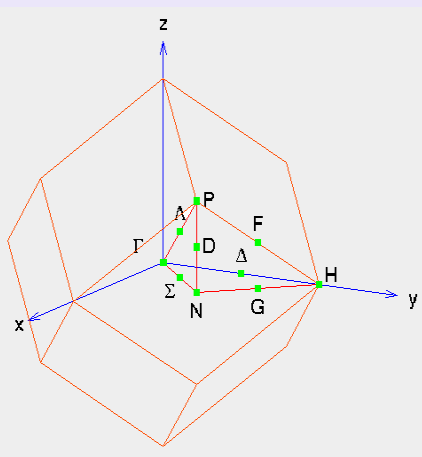


the first Brillouin zone



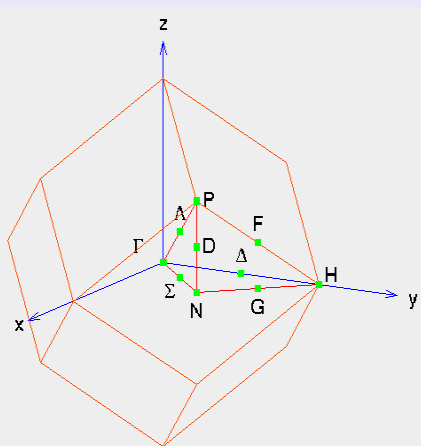
Phonon spectrum

Brillouin zone



BZ for BCC lattice

Brillouin zone

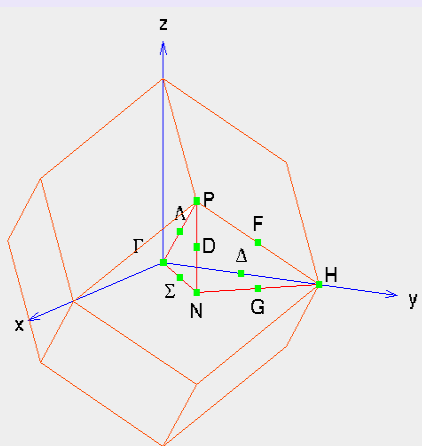


BZ for BCC lattice

Symmetry of the spectrum:

$$\omega(\mathbf{k}) = \omega(P\mathbf{k}), \quad \varepsilon(P\mathbf{k}) = P\varepsilon(\mathbf{k}).$$

Brillouin zone



BZ for BCC lattice

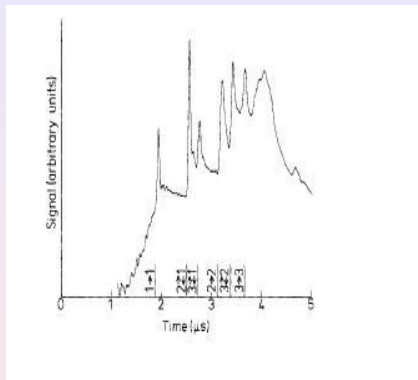
Integration over the BZ: K point method (Monkhorst and Pack 1976).

$$u_i = (2i - nq - 1)/(2nq)$$

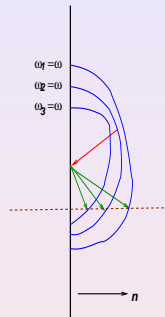
$$\mathbf{k}_{ijl} = u_i \mathbf{b}_i + u_j \mathbf{b}_j + u_l \mathbf{b}_l.$$

The symmetry of the grid points substantially reduces the computation.

Phonon reflection



Taborek and Goodstein 1979



Incident and reflected waves

Phonon reflection:

$$\begin{aligned} \mathbf{k}^I - (\mathbf{k}^I \cdot \mathbf{n}) \mathbf{n} &= \mathbf{k}^R - (\mathbf{k}^R \cdot \mathbf{n}) \mathbf{n} \\ \omega_s(\mathbf{k}^I) &= \omega_{s'}(\mathbf{k}^R). \end{aligned}$$

Let $\lambda = e^{i(\mathbf{k}^R \cdot \mathbf{n})a_n}$

$$\det\left(\mathcal{D}(\mathbf{k}^R) - \omega(\mathbf{k}^I)I\right) = 0,$$

leads to a polynomial for λ . The roots of the polynomial come in pairs $(\lambda, 1/\lambda^*)$. The degree of the polynomial: $Nd \times Ne \times Na$.

The wavenumber:

$$\mathbf{k}_{s,s'}^R \cdot \mathbf{n} = k_r + ik_i.$$

Phonon reflection: *reflection coefficients*

Boundary condition:

$$\mathbf{u}_0(t) = \sum_j \int_0^{t_0} \alpha_j(\tau) \mathbf{u}_j(t - \tau) d\tau.$$

Phonon reflection: *reflection coefficients*

Boundary condition:

$$\mathbf{u}_0(t) = \sum_j \int_0^{t_0} \alpha_j(\tau) \mathbf{u}_j(t - \tau) d\tau.$$

Incident and reflected waves:

$$\mathbf{u}_j(t) = c_s^I e^{i(\mathbf{r}_j \cdot \mathbf{k} - \omega_s t)} \boldsymbol{\epsilon}_s(\mathbf{k})$$

Phonon reflection: *reflection coefficients*

Boundary condition:

$$\mathbf{u}_0(t) = \sum_j \int_0^{t_0} \alpha_j(\tau) \mathbf{u}_j(t - \tau) d\tau.$$

Incident and reflected waves:

$$\begin{aligned} \mathbf{u}_j(t) = & c_s^I e^{i(\mathbf{r}_j \cdot \mathbf{k} - \omega_s t)} \boldsymbol{\epsilon}_s(\mathbf{k}) \\ & + c_{ss'}^R e^{i(\mathbf{r}_j \cdot \mathbf{k}_{ss'}^R - \omega_{s'} t)} \boldsymbol{\epsilon}_{s'}(\mathbf{k}_{ss'}^R) \end{aligned}$$

Phonon reflection: *reflection coefficients*

Boundary condition:

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$$\mathbf{c}^R = R \mathbf{c}^I,$$

Linear system:

$$(I - \mathcal{A}(\mathbf{k})) \boldsymbol{\varepsilon}_s(\mathbf{k}) + \sum_{s'} R_{ss'} (I - \mathcal{A}(\mathbf{k}_{ss'}^R)) \boldsymbol{\varepsilon}_{s'}(\mathbf{k}).$$

Thermal flux

Energy flux at the atomic scale:

$$J = \frac{1}{2} \sum (\dot{\mathbf{u}}_i + \dot{\mathbf{u}}_j) D_{i-j} (\mathbf{u}_i - \mathbf{u}_j) \mathbf{r}_{ij}.$$

Convert to Fourier space:

$$J = J^I + J^R.$$

$$J^R = \int |c_{ss'}^R|^2 \omega_{s'} \nabla \lambda_{s'}(\mathbf{k}) d\mathbf{k},$$

$$J_n^R = 2 \sum_s \int_{\mathbf{k} \in BZ, \mathbf{k} \cdot \mathbf{n} \leq 0} \left| \sum_{s'} c_{s'}^I R_{ss'} \right|^2 \omega_s^2 (\nabla \omega_s \cdot \mathbf{n}) d\mathbf{k}.$$

This is the thermal flux due to the applied boundary condition.

Variational boundary conditions

Discrete boundary condition:

$$\mathbf{u}_0^{n+1} = \sum_{j=1}^J \sum_{m=1}^M \alpha_j^m \mathbf{u}_j^{n-m} \Delta t,$$

Variational formulation:

$$\min_{\{\alpha_j^m\}} \sum_s \int_{\mathbf{k} \in BZ, \mathbf{k} \cdot \mathbf{n} \leq 0} \sum_{s'} |R_{ss'}|^2 |(\nabla \omega_s \cdot \mathbf{n})| d\mathbf{k}$$

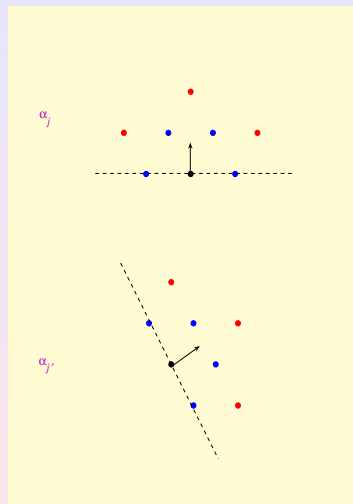
subject to certain constraints.

Symmetry properties

$$\tilde{\alpha}_{j'} = P\alpha_j P^T,$$

Reflection matrices:

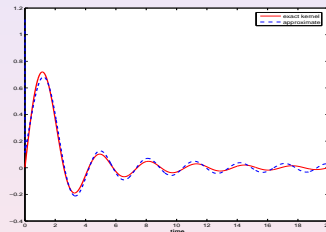
$$R(\mathbf{k}; \{\alpha_{j'}\}) = R(P^T \mathbf{k}; \{\alpha_j\}).$$



Example: 1D chain

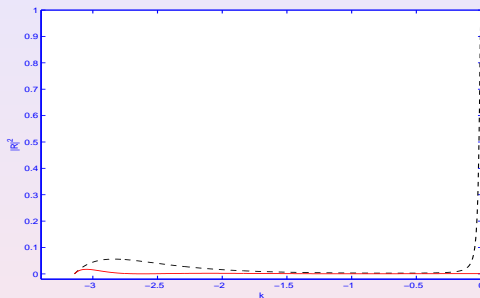
Reflection (E and Huang 2001, 2002)

$$R(k) = \frac{1 - \sum_j e^{ijk} \int_0^{t_0} \alpha_j(\tau) e^{i\omega\tau} d\tau}{1 - \sum_j e^{-ijk} \int_0^{t_0} \alpha_j(\tau) e^{i\omega\tau} d\tau}.$$



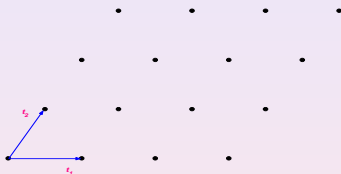
exact kernel

Example: 1D chain

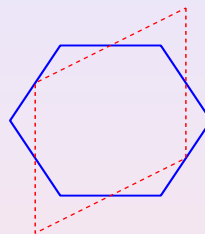


Premature truncation vs variational BC

Example: 2D triangular lattice

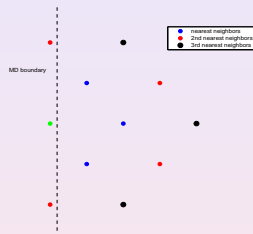


the triangular lattice

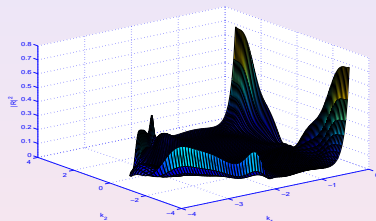


the first Brillouin zone

Example: 2D triangular lattice

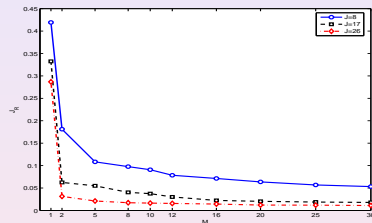


neighbor atoms

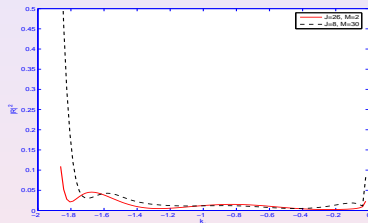


phonon reflection for $J = 26, M = 2$

Example: 2D triangular lattice

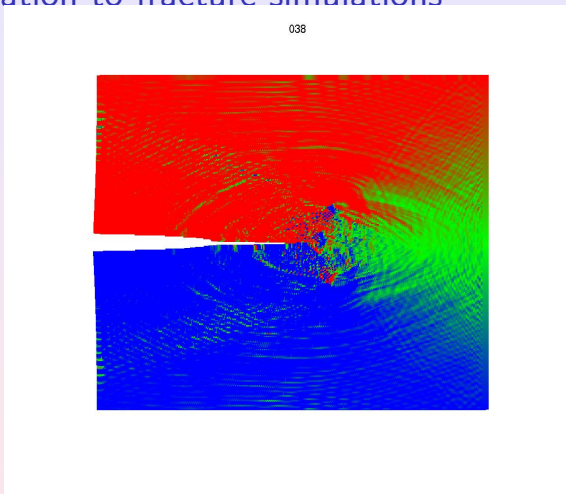


size of the stencil



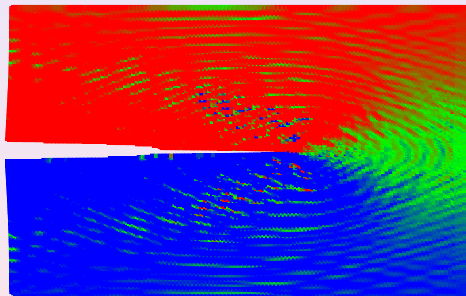
phonon reflection along $\theta = 2\pi/3$

Application to fracture simulations



Fixed BC

Application to fracture simulations



Local BC

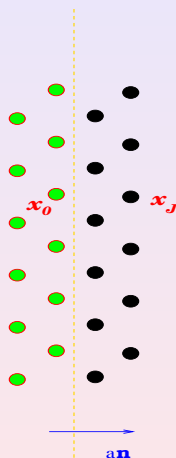
More practical issues: external loading



stress free?

The reflection coefficient $|R(k)| \equiv 1$!

More practical issues: external loading



External loading

Applied deformation:

$$\mathbf{W} = \mathbf{F}\mathbf{n} - \mathbf{n} = \frac{\partial \mathbf{u}}{\partial \mathbf{n}},$$

Boundary condition:

$$\mathbf{w}_0 = \sum_j \int_0^{t_0} \alpha_j(s) \mathbf{w}_j(t-s) ds.$$

In Fourier space:

$$\hat{\mathbf{w}}(k) = \hat{\mathbf{u}}(k)(1 - e^{i\mathbf{a}\mathbf{k} \cdot \mathbf{n}}).$$

Summary

1. analysis of phonon reflection
2. variational formulation to minimize phonon reflection
3. **local** boundary condition
4. implementation issues
5. application to fracture simulations