

GRADIENT DESCENT



Halotech Academy



Training Linear Regression

Cost Function

Merupakan Fungsi yang digunakan untuk menghitung tingkat error pada suatu algoritma machine learning linear

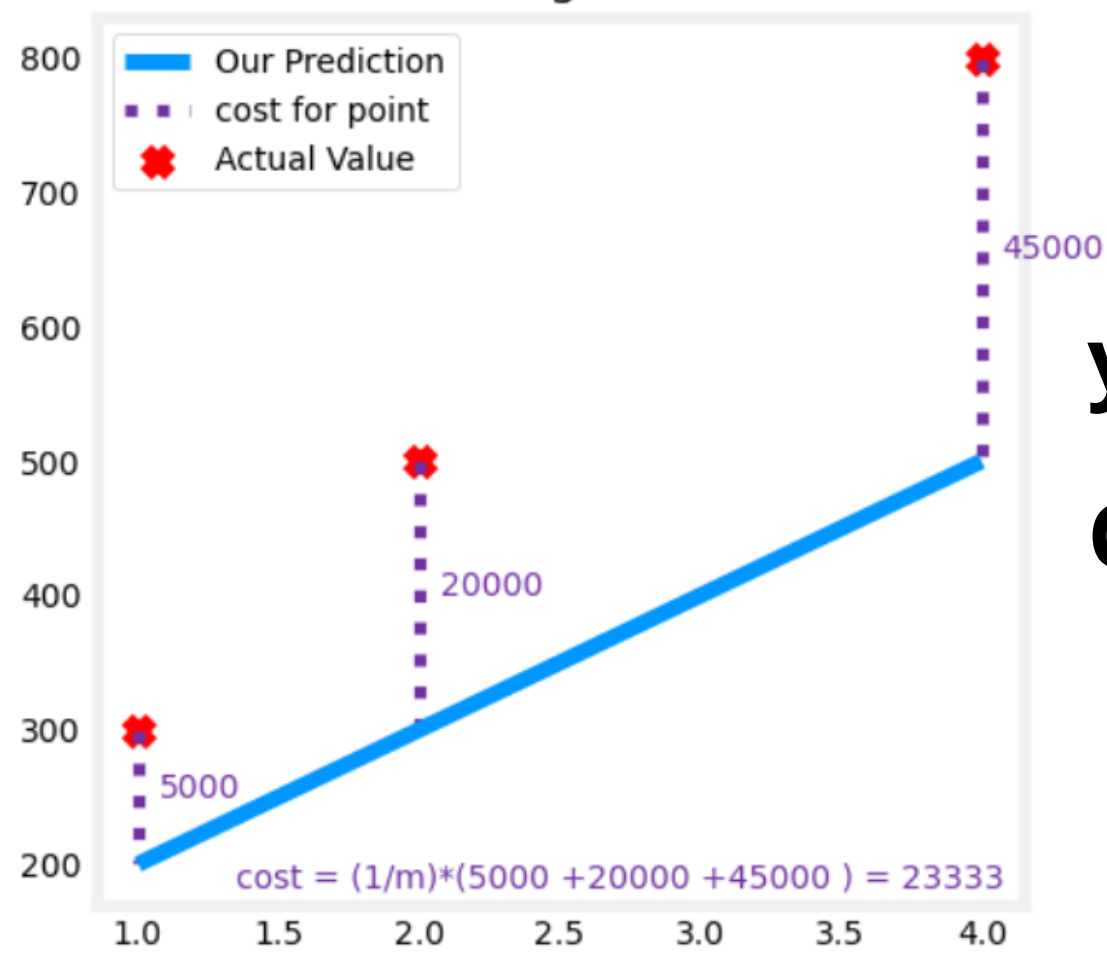
Linear
Regression

W dan **b**

Gradient Descent

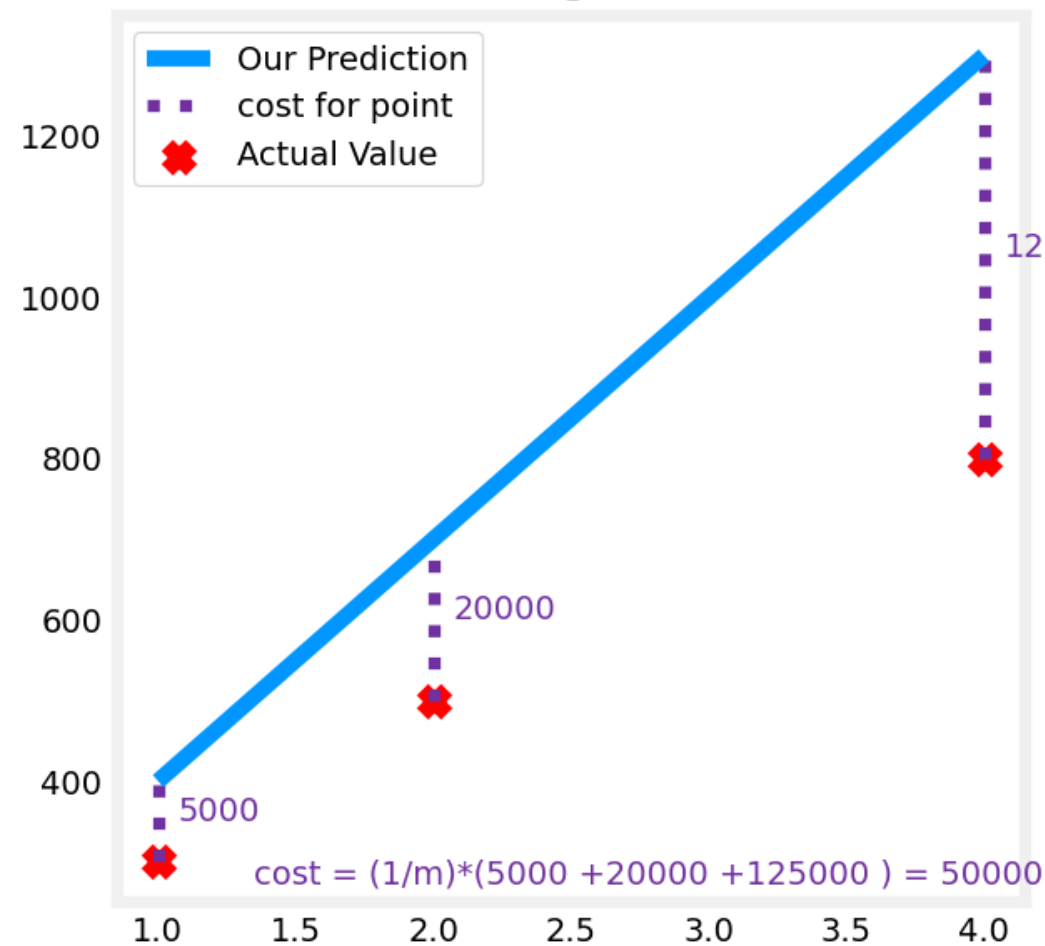
Algoritma optimasi yang digunakan untuk menemukan nilai-nilai parameter (koefisien) dari suatu fungsi (f) yang **meminimalkan** fungsi cost.

Merupakan algoritma yang digunakan untuk memperkecil nilai Cost Function



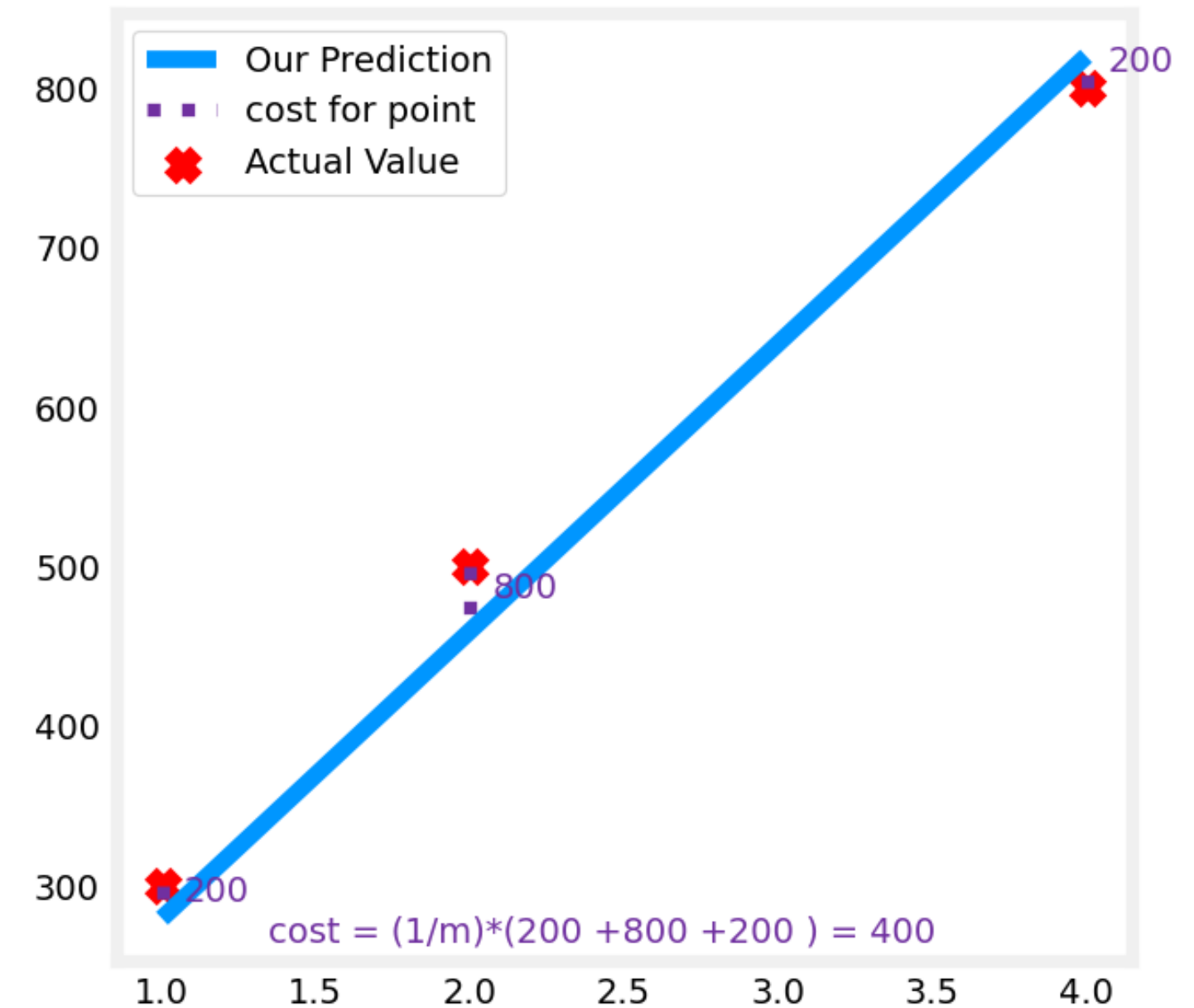
$$y = 100x + 100$$

$$\text{Cost} = 23.333$$



$$y = 300x + 100$$

$$\text{Cost} = 50.000$$



$$y = 180x + 100$$

$$\text{Cost} = 400$$

GRADIENT DESCENT

Repeat Until Convergent {

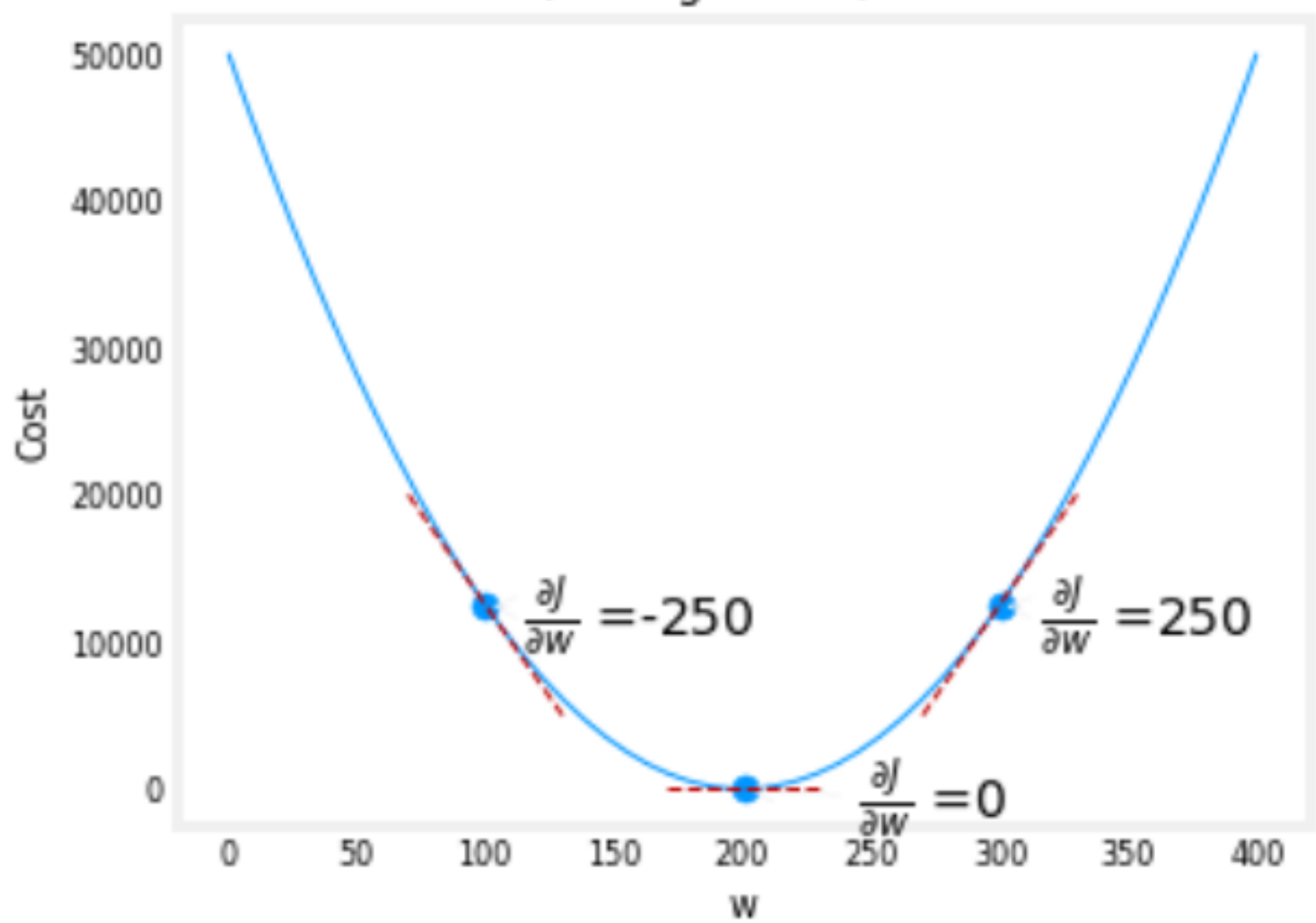
$$\theta_j := \theta_j + \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \qquad (for\ j = 0\ and\ j = 1)$$

}

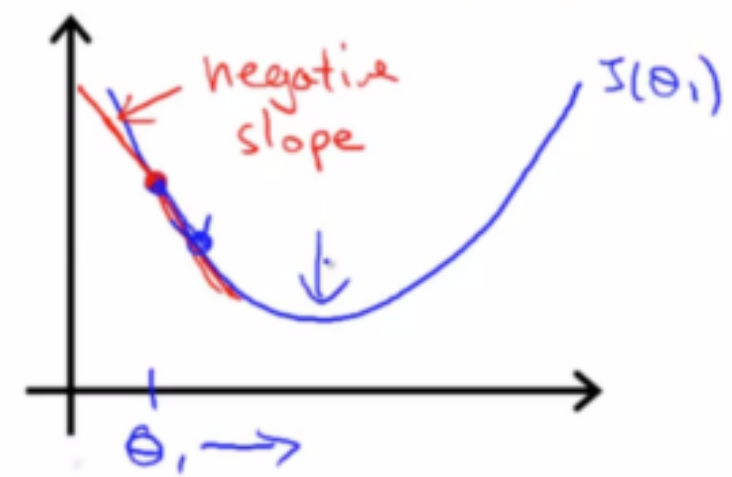
θ_j	Parameter ,Nilai yang di optimasi)
$:=$	Assigment Operator, Operator menggantikan value , ($a:=b$, ini bermasud b menggantikan value a)
α	Learning Rate ,Mengkontrol seberapa besar step yang dilakukan.
$\frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$	Nilai Turunan / Derivative Term , yang memberi arah menuju minimum/optimal

NILAI TURUNAN / DERIVATIVE TERM

$$w := w - \alpha \frac{\partial J(w, b)}{\partial w}$$



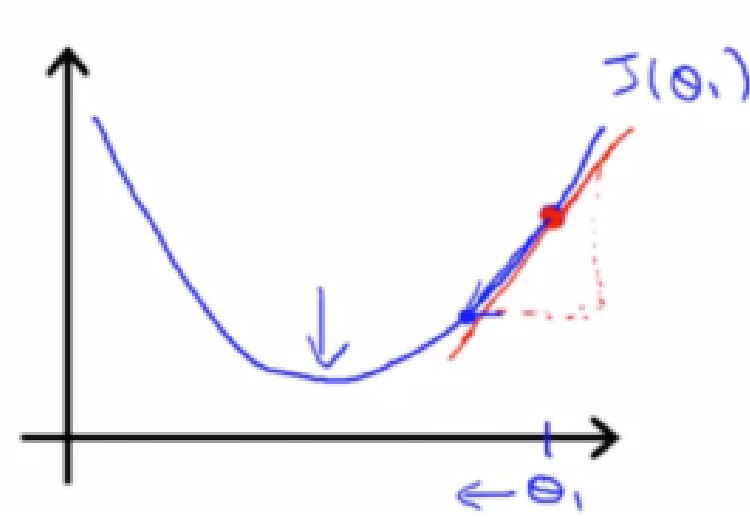
Negative Slope



$$\frac{\partial J(\theta_1)}{\partial \theta_1} \leq 0$$
$$\theta_1 := \theta_1 - \alpha \text{ (negative number)}$$

Andre

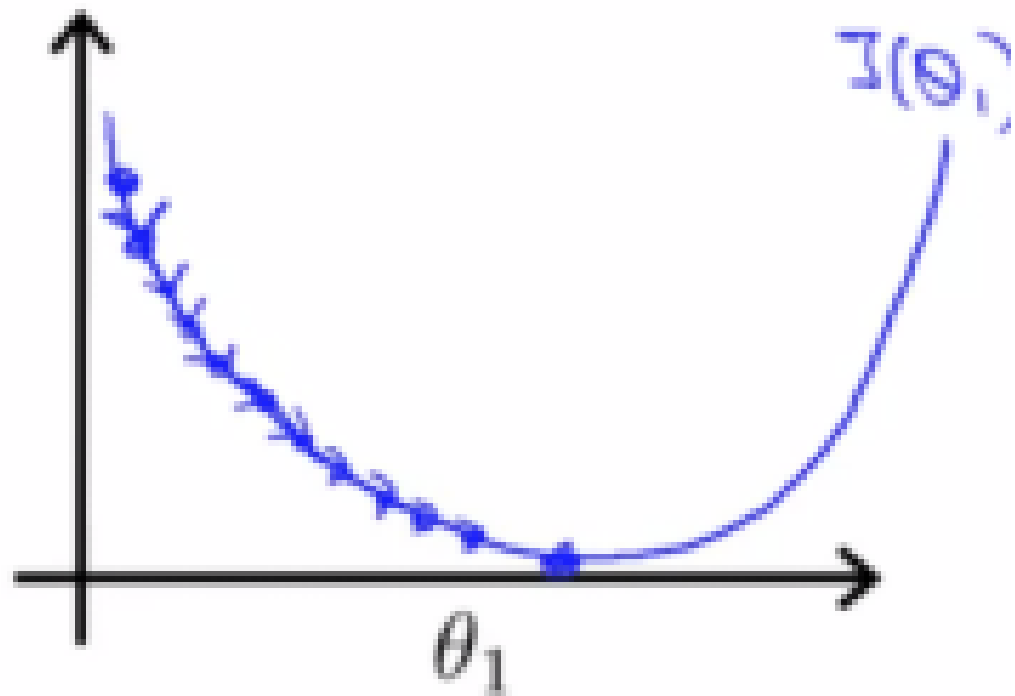
Positive Slope



$$\frac{\partial J(\theta_1)}{\partial \theta_1} \geq 0$$
$$\theta_1 := \theta_1 - \alpha \text{ (positive number)}$$

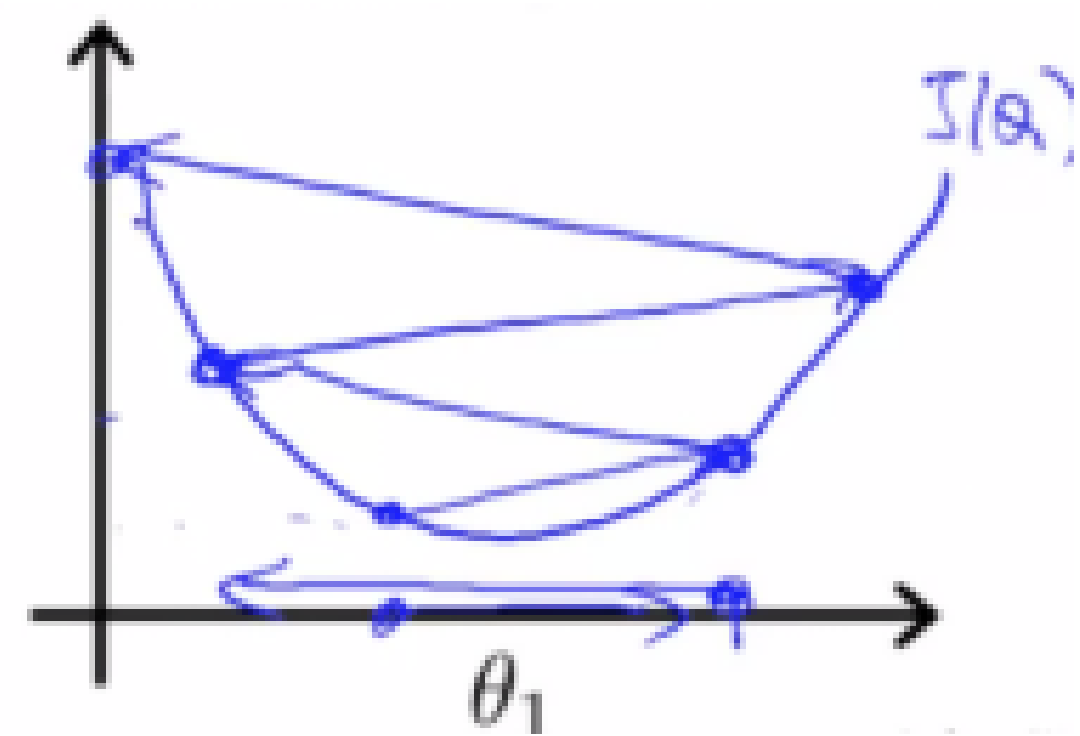
LEARNING RATE

$$w := w - \alpha \frac{\partial J(w, b)}{\partial w}$$



Very Small

$$\alpha \ll$$



Very Big

$$\alpha \gg$$

HOW TO UPDATE

Correct: Simultaneous update

```
temp0 :=  $\theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$   
temp1 :=  $\theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$   
 $\theta_0$  := temp0  
 $\theta_1$  := temp1
```



Incorrect:

```
→ temp0 :=  $\theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$   
→  $\theta_0$  := temp0  
→ temp1 :=  $\theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$  ←  
→  $\theta_1$  := temp1
```



Am

GRADIENT DESCENT

Fungsi --> $f_{w,b}(x^{(i)}) = wx^{(i)} + b$

Cost Function --> $J(\mathbf{w}, \mathbf{b}) = \frac{1}{2m} \sum_{i=0}^{m-1} (f_{w,b}(x^{(i)}) - y^{(i)})^2$

Gradient Descent will be

$$w := w - \alpha \frac{\partial J(w, b)}{\partial w}$$

$$b := b - \alpha \frac{\partial J(w, b)}{\partial b}$$

Then

$$w := w - \alpha \frac{1}{m} \sum_{i=0}^{m-1} (f_{w,b}(x^{(i)}) - y^{(i)}) x^{(i)}$$

$$b := b - \alpha \frac{1}{m} \sum_{i=0}^{m-1} (f_{w,b}(x^{(i)}) - y^{(i)})$$

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$$w := w - \alpha \frac{\partial J(w, b)}{\partial w}$$

$$\frac{\partial J(w, b)}{\partial w} = \frac{\partial}{\partial w} \left(\frac{1}{2m} \sum_{i=0}^{m-1} (f_{w,b}(x^{(i)}) - y^{(i)})^2 \right)$$

$$\frac{\partial J(w, b)}{\partial w} = \frac{1}{2m} \sum_{i=0}^{m-1} \frac{\partial}{\partial w} (f_{w,b}(x^{(i)}) - y^{(i)})^2$$

$$\frac{\partial J(w, b)}{\partial w} = \frac{1}{2m} \sum_{i=0}^{m-1} \frac{\partial}{\partial w} (wx^{(i)} + b - y^{(i)})^2$$

$$\frac{\partial J(w, b)}{\partial w} = \frac{1}{2m} \sum_{i=0}^{m-1} (2(wx^{(i)} + b - y^{(i)}) x^{(i)})$$

$$\frac{\partial J(w, b)}{\partial w} = \frac{1}{m} \sum_{i=0}^{m-1} (wx^{(i)} + b - y^{(i)}) x^{(i)}$$

$$\frac{\partial J(w, b)}{\partial w} = \frac{1}{m} \sum_{i=0}^{m-1} (f_{w,b}(x^{(i)}) - y^{(i)}) x^{(i)}$$

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$$\frac{\partial J(w, b)}{\partial b} = \frac{\partial}{\partial b} \left(\frac{1}{2m} \sum_{i=0}^{m-1} (f_{w,b}(x^{(i)}) - y^{(i)})^2 \right)$$

$$\frac{\partial J(w, b)}{\partial b} = \frac{1}{2m} \sum_{i=0}^{m-1} \frac{\partial}{\partial b} (w x^{(i)} + b - y^{(i)})^2$$

$$\frac{\partial J(w, b)}{\partial b} = \frac{1}{m} \sum_{i=0}^{m-1} (w x^{(i)} + b - y^{(i)})$$

$$\frac{\partial J(w, b)}{\partial b} = \frac{1}{m} \sum_{i=0}^{m-1} (f_{w,b}(x^{(i)}) - y^{(i)})$$

$$b := b - \alpha \frac{\partial J(w, b)}{\partial b}$$



THANKS FOR WATCHING



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