Divide and Congner Example Finding the closest poin of points - on example where the "conquer" step is more complicated. Problem Given n points in the plane, find the pain that is closest together. d(p,q) = distance between p and 9 0 = V(R-qx)2+ (Py-qy)2 Note: we can compare d(p,q) to d(r,s) without r. Brute force: try all pairs O(n2) In 1D (points on & line): sort and compare consecutive pairs. O(nlogn) Note that this does not work in 2D. 1. 3 Divide and Conquer Caffer sorting by accoord.) - divide points into left half, Q, right holf, R, dividing line L - recursively find closest poir in Q, closest poir in R -combine To combine, we need to find close pairs crossing This is the tricky port.

Let  $\delta = \min_{\alpha} distance of <math>\frac{1}{2} closest poir in R$ Must check poirs QEQ, rER with d(q,r) < & Claim Such points satisfy d(q, L) < 8, d(r, L) < 8 Pf. Otherwise hovizontal distance ≥ 8 so distance ≥ S. Let S = points in this vertical strip of width 20 We can restrict our search to S (might be all n points) This problem seems more 1-dimensional Sort S by 4-coordinate Note: do not do this in each recursive cell. Do it once for all points O(nlogn) and extract the needed for Prog. Assign sorted sublist for any 5 in linear time. This is like "unmerging" points sorted by y P1 (P2) (P3) · 0.0 P; (Pi) · 0 Pn points of Scircled P2 P3 ... Pi found by scanning list Note: each recursive call needs to know its points Sorted by y-coordinate.

Overall structure of the algorithm:
X < sort points by >c-coord.
Y < sort points by y-coord
Closest (X,Y) - returns distance between
Closest (X,Y) - returns distance between closest pair of points
Closest (X, Y)
L <- dividing line (middle of X)
"unmerge" to get XQ, XR, YQ, YR
sorted lists for left side (Q), right side (R)
$\delta_Q \leftarrow Closest (X_Q, Y_Q)$
SR < closest (XR, YR)
δ < min 3 δQ, δR ξ
find sel 5 as above
Ys < S sorted by y-coord (extract from Y)
Finally, what do we do with S, Ys?
Our hope: if q,rES, qEQ, rER and d(q,r)<8
then gand rare near each other in the sorted S
not many points  here
worst case 8
18 8
<u>Claim</u> At most 8 points here.

why? We have 8 squares $\frac{5}{2} \times \frac{5}{2}$ and each square
$\int_{2}^{\infty} \int_{1/2}^{\infty} \int_{2}^{\infty} \int_{3/2}^{\infty} \int_{2}^{\infty} \int_{3/2}^{\infty} \int_{2}^{\infty} \int_{3/2}^{\infty} $
Thus If $q, r \in S$ $q \notin Q, r \notin R$ $d(q, r) < \delta$ then $q$ and $r$ are of most $8$ positions apart in sorted $S$
then a and r are of most 8 positions apart in sorted S
Si Si Si Si Si Si Si T
just need to look here for r
So 7n comparisons
Whopping up: preliminary sort by x and by y then $T(n) = 2T(\frac{n}{2}) + c \cdot n$
Then $T(n) = 2T(\frac{1}{2}I + c_1N)$ So $T(n) \in \Theta(n \log n)$
This alg. was due to Preparata & Shamos in the
This ag. was due to Preparata & Shamos in the early days of computational geometry (70's and 80's)
Infact, one can do much more in o(nlogn) -
Infact, one can do much more in O(nlogn) - find closest neighbours of all points
EX. This graph has no cycles, no crossing edges, max degree 6

	Multiplying Large Numbers
School method  981  × 1234  3924 two ndig	SO(n²) time to multiply git numbers
1962 981	
Divide and conquer	
easiest when both numbers	hove come no. digits so pad 981 to 0981
09 81 × 12 34	09 × 12 4 108
	09 × 34 2 306
	81 × 12 2 972
	81 × 34 0 27 5 4
	1210554
Compute each of these 4 pro	oducts recursively
$ e.q.  0  q \times 1  \geq 0 \times$	shift 1 2 0
Compute each of these 4pro e.g. 0 9 × 1/2 0 × 9 × 9 × 9 ×	2 1 0
9×	2 0 18
	208
ナ(n)=4十(型)+0(	
time	e for shiffs, addition

Apply Moster Method

$$T(n) = \partial T(\frac{\pi}{b}) + c \cdot n^k$$
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Now we get T(n)=3T(生)+0(n) a = 3b = 2k = 1  $a = 3 > b^{k} = 2$ T(n) = 0 (n logba) = 0 (n logz3) log\_3 ~ 1.585 This alg. is due to Karatsuba and Ofman 1962 Practical issues 1. What about numbers of odd length? Stad? numbers of different length? 2. What base should we use? Above we used bose 10. Use largest bose s.t. two "digits" can be multiplied directly Actually, can be better to stop recursion before this and revert to school method (4 mult., fewer additions) 3. When is this alg. useful? · for small n the overhead is too high · this alg. beats the basic O(n2) one for numbers of 1000 digits and up [Brassad & Brotley] · for large n there are asymptotically better methods Ceven worse overhead) O(nlogn log lgn) Schönhage & Strassen

Multiplying motrices (similar idea) multiply two nxn matrices standard method is O(n3) Divide and conquer divide into submotices of size 2  $\begin{bmatrix} C_{11} & C_{1,2} \\ C_{2,1} & C_{2,2} \end{bmatrix} = \begin{bmatrix} A_{1,1} & A_{1,2} \\ A_{2,1} & A_{2,2} \end{bmatrix} \times \begin{bmatrix} B_{1,1} & B_{1,2} \\ B_{2,1} & B_{2,2} \end{bmatrix}$ Ci, = A, 1 × B, 1 + A, 2 × B2, 1 - two mult, of 2 size submotices etc. - one addition O(n2) T(n)=8T(=)+0(n2) a=8 b=2 k=2 a=8 > bk=4 T(n) E O (nlogba) = O(N3) So far, no progress, Strassen's alg. . like idez for integer multiplication · get by with 7 subproblems instead of 8 (Hricky!) T(n) = 7T(4) + 0(n2) a=7 b=2 k=1 a=7> b=4 T(n) E O (n log10) = O(n log27) log7~2.808 Again, there are more sophisticated methods

that do better, but with greater overhead.

Here is Strassen's tricky way of using 7 subproblems. Suppose C = A × B, all n×n matrices  $\begin{bmatrix} C_{1,1} & C_{1,2} \\ C_{2,1} & C_{2,2} \end{bmatrix} = \begin{bmatrix} A_{1,1} & A_{1,2} \\ A_{2,1} & A_{2,2} \end{bmatrix} \begin{bmatrix} B_{1,1} & B_{1,2} \\ B_{2,1} & B_{2,2} \end{bmatrix}$ each block is n/2 × n/2 Define: M1 = (A1,1+A2,2) (B1,1+B2,2)  $M_2 = (A_{2,1} + A_{2,2}) B_{1,1}$ M3 = A1,1 (B1,2-B1,2)  $M_4 = A_{2,2} (B_{2,1} - B_{1,1})$ M5 = (A1,1+A1,2) B2,2  $M_6 = (A_{2,1} - A_{1,1})(B_{1,1} + B_{1,2})$  $M_7 = (A_{1,2} - A_{2,2})(B_{2,1} + B_{2,2})$ Then check that  $C_{1,1} = M_1 + M_4 - M_5 + M_7$ C1,2 = M3+ M5  $C_{21} = M_2 + M_4$  $C_{2,2} = M_1 - M_2 + M_3 + M_6$