Overview of Operating System Concepts

1. Introduction

- Modern Computer Hardware Organization
 - ♦ Processor(s)
 - ♦ Main memory
 - ♦ Mass storage
 - ♦ Various input/output devices
- What is Operating Systems
 - An Operating System is a program that acts as an intermediary or interface between a user of a computer and the computer hardware.
 - Convenient abstraction of complex hardware devices
 - Protection of access to shared resources
 - · Security and Authentication
 - Communication amongst logical entities
 - ♦ An Operating System goals
 - Control/execute user or application programs
 - Make the computer system convenient to use
 - Ease the solving of user problems
 - Use the computer hardware in an efficient manner
- Computer System Components
 - ♦ Hardware
 - ♦ Operating system
 - ♦ Application programs (Application systems)
 - ♦ Users
- Classical views of Operating Systems
 - ♦ Resource manager
 - ♦ Control program
 - ♦ Command executer

2. Computer System Organization and Architecture

- Computer Hardware Architecture

 - ♦ Harvard Architecture
 - ♦ Data representation
 - ♦ Addressing mode
 - ♦ Registers
 - ♦ Instruction system
 - ♦ Memory system
 - ♦ Interrupt controller
 - ♦ Input/output controller

- ♦ Information protecting mechanism
- Computer System Organizations
 - ♦ CPU
 - ♦ Main memory
 - ♦ Bus
 - ♦ Device controller
 - ♦ Device driver
 - ♦ Device

■ Interrupt

- ♦ The basic interrupt mechanism
- ♦ Asynchronous processing
- ♦ Interrupt request line
- ♦ Interrupt handler routine
- ♦ Interrupt vector
- ♦ Interrupt controller
- Maskable and non-maskable interrupts
- ♦ Interrupt chaining
- ♦ Interrupt priority
- ♦ Interrupt types
 - Traps (Exceptions)
 - External interrupts
 - System calls
- ♦ Various interrupt attributes.
 - Asynchronous vs. Synchronous.
 - External/Hardware vs. Internal/Software.
 - Implicit vs. Explicit.
- Storage Structures
 - ♦ Registers
 - ♦ Cache
 - ♦ Main memory
 - ♦ Secondary storage (NVM)
 - ♦ Hard disks
- Main Memory Management
 - ♦ Memory management dynamics
 - ♦ Dual-mode operation
 - ♦ Memory Protection
- I/O Structure
- Multiprogrammed batch systems
- Time-Sharing Systems
- Real-Time Systems
- Personal/Desktop Computers
- Multiprocessor Systems
 - ♦ SMP
 - ♦ Multicore

- Clustered Systems
- Networked Systems
- Distributed Systems
- Web-based Systems
- Handheld & Mobile Systems

3. Functional Views of Operating Systems

- Computer Dynamics
 - ♦ Instruction cycle with interrupts
 - ♦ External interrupt
 - ♦ Interrupt handler
 - ♦ Interrupt-driven I/O
 - ♦ Interrupt timeline of CPU and I/O device
 - ♦ Synchronous and asynchronous I/O methods
 - ♦ Direct memory access (DMA)
 - ♦ System calls
- Hardware Protection
 - ♦ Dual-mode operation
 - Monitor mode/Kernel mode
 - User mode
 - Privileged instructions
 - User mode to kernel mode transfer
 - System call
 - ⊙ Interrupt
 - ⊙ Trap
 - ♦ I/O protection
 - System calls for I/O protection
 - ♦ Memory protection
 - Base register (relocation)
 - Limit register (bounded)
 - ♦ CPU protection
 - Timer
- Fundamental OS Concepts
 - ♦ Thread
 - ♦ Address space
 - ♦ Process
 - ♦ Dual-mode operation
- Resource Management
 - ♦ Process management
 - Memory management
 - ♦ File management
 - Mass-storage management
 - ♦ Cache management
 - ♦ I/O management

- Free and Open Source Operating Systems
 - ♦ GNU project
 - ♦ GNU/Linux
 - ♦ BSD UNIX

4. Structures of Operating Systems (1)

- Operating System Services
 - A user oriented view
 - ♦ User interface
 - ♦ Program execution
 - ♦ I/O operations
 - ♦ File systems
 - ♦ Communication
 - ♦ Error detection
 - ♦ Resource allocation
 - ♦ Accounting
 - ♦ Protection and security
- Common Operating System Components
 - ♦ A system oriented view
 - ♦ Process management
 - ♦ Main memory management
 - ♦ File management
 - ♦ Mass-storage management
 - ♦ I/O management
 - ♦ Networking
 - ♦ Command interpreter

 - ♦ Protection and security
 - ♦ Error detection and response
 - ♦ Accounting
- System Calls and APIs
 - ♦ Relationship of API, system call and OS
 - ♦ Standard C library and POSIX
- System Programs
- Operating System Design and Implementation

5. Structures of Operating Systems (2)

- Structure/Organization/Layout of OS
 - ♦ Monolithic (one unstructured program)
 - Traditional UNIX system structure
 - Linux system structure
 - Google's Android
 - ♦ Layered
 - Win3.1

- OS/2
- ♦ Microkernel
 - Architecture of a typical microkernel
 - Mach 3.0
 - MAC OS
 - MINIX
 - Windows NT, XP, 7.0
 - QNX Neutrino RTOS
- ♦ LKMS
- ♦ Virtual Machines

6. Introduction to Process (1)

- Basic Concepts
 - ♦ Segments in a process
 - Text, Data, Heap and Stack
 - ♦ Context of a process
 - ♦ Process virtual memory (PVM) in IA-32
 - Attributes of process
 - Process ID
 - Parent process ID
 - User ID
 - · Process state
 - · Process priority
 - Program counter
 - CPU registers
 - Memory management information
 - I/O status information
 - Access control
 - Accounting information
- Process Table and Process Control Block
 - Process table and its contents
 - ♦ PCB and its contents
- Process States and Transitions
 - ♦ Running, ready and waiting/blocked states
 - Process states transitions
 - ♦ Five-states process model
- Operations on Process
 - ♦ Process creation
 - Details in creating a process
 - Programming: forking a separate process
 - Programming: vforking a sharing space process
 - ♦ Process termination
 - Why terminating a process
 - Details in terminating a process

- Zombie process
- Orphan process
- Programming: forking without waiting child termination
- Programming: forking with waiting child termination
- Programming: vfork, execv and wait
- Programming: vfork, execv without wait

7. Introduction to Process (2)

- Unix and Linux Examples
 - ♦ UNIX SVR4 process states model
 - ♦ Linux process representation
 - ♦ Linux process state
- Process Scheduling
 - ♦ What is process scheduling
 - ♦ Scheduling queues
 - Job queue
 - Ready queue
 - Device/Waiting queues
 - ♦ Types of process schedulers
 - · Long-term scheduler
 - Medium-term scheduler
 - · Short-term scheduler
 - ♦ Process swapping
 - ♦ Process scheduling activities
 - ♦ Process scheduling queues
- Process Switching
 - ♦ Context switching (steps)
 - ♦ Mode switching

8. Inter-process Communication (1)

- Overview
 - ♦ Independent process and cooperating process
 - ♦ Why cooperating
 - Information sharing
 - Computation speedup
 - Modularity
 - Convenience
 - Two fundamental models of IPC
 - Shared memory and message passing
- Shared-memory Systems
 - ♦ Producer-consumer problem with shared-memory
 - A producer and a consumer
 - Concurrency
 - Unbounded and bounded buffer

- ♦ Linux IPCs Limits
- ♦ Linux shared memory
 - System calls
 - Programming: Single-writer-single-reader problem
- ♦ POSIX shared memory
 - POSIX APIs for memory sharing
 - Programming: Producer-consumer problem

9. Inter-process Communication (2)

- Message-passing Systems
 - Primitives for message-passing
 - ♦ Variable and fixed message size
 - ♦ Message format
 - Linux message structure
 - ♦ Logical communication link
 - Direct or indirect communication
 - Synchronous or asynchronous communication
 - Automatic or explicit buffering
 - ♦ Synchronization in Message-passing Systems
 - Blocking and unblocking
 - ♦ Buffering
 - ♦ Linux message passing
 - System calls
 - Programming: Sending & receiving process demo
 - ♦ POSIX message passing
 - POSIX APIs for memory sharing
 - Lab work: Sending & receiving process demo

10. Inter-process Communication (3)

- Pipes
 - ♦ Ordinary pipes
 - ♦ Naked pipes
 - ♦ Linux ordinary pipes
 - System calls
 - ♦ Linux named pipes
 - System calls
 - Programming: single pipe buffer
 - Programming: total pipes capacity
 - Programming: ordinary pipe
 - Programming: named pipe between parent and children
 - Programming: named pipe between two arbitrary Processes

11. Inter-process Communication (4)

Communications in Client-Server Systems

- ♦ Sockets
- ♦ Linux socket programming
 - Socket APIs
 - Programming: socket-server-BBS
- ♦ Remote Procedure Calls

12. Threads (1)

- Overview
 - ♦ Tasks/Processes vs. Threads
 - ♦ Benefits of multithreaded programming
 - Responsiveness
 - · Resource sharing
 - Economy
 - Scalability
 - ♦ Thread states
 - Running
 - Ready
 - Blocked
 - No suspend state
 - ♦ Terminating a thread
- Multicore Programming
 - ♦ Parallelism and concurrency
 - ♦ Multithreading
 - ♦ Programming challengs
 - Balance
 - Data splitting
 - Data dependency
 - Testing and debugging
 - Identifying tasks
 - ♦ Data parallelism and task parallelism
- User and Kernel Level Threads
 - ♦ Thread libraries
 - POSIX Pthreads
 - ♦ User level threads (ULT)
 - Kernel activity for ULTs
 - Advantages and inconveniences of ULTs
 - ♦ Kernel level threads (KLT)
 - Linux threads
 - Advantages and inconveniences of KLTs
 - ♦ Hybrid ULT/KLT Approaches
- Multithreading Models
 - ♦ Many-to-one model,
 - ♦ One-to-one model, and
 - ♦ Many-to-many model.

- ♦ Two-level model
- ♦ Light-weight process (LWP)

13. Threads (2)

- Threads Libraries
 - ♦ POSIX Pthreads
 - POSIX Pthreads APIs
 - Programming: pthread creating
 - Programming: pthread memory sharing
 - Programming: pthread setting stack
- Implicit Threading
 - ♦ Threads pools
 - Lab work: Implementation of a threads pool
 - ♦ OpenMP
 - Programming: OpenMp demo
 - Programming: OpenMP matrix adding
- Threading Issues
 - fork() and execv()
 - Programming: pthread forking demo
 - ♦ Signal handling
 - Linux system calls
 - Programming: sigaction-demo
 - ♦ Thread cancelation
 - Asynchronous cancellation
 - Deferred cancellation

14. Threads (3)

- ♦ Thread local storage (TLS)
 - Programming: TLS implemented by __thread in language level
 - Programming: TLS implemented by pthread_key_create
 - Programming: tls_key and bounding data structure
- Linux clone()
 - Constants with flags in clone()
 - Programming: Linux clone() demo
 - Lab work: Programming with Linux clone()
 - ♦ Windows Threads

15. Cooperating Processes

- Introduction
 - ♦ Process cooperation
 - ♦ Data consistency
- Race Condition
 - ♦ Race condition

- ♦ Critical section
- ♦ Atomic operations
- The Critical-Section Problem
 - ♦ The critical-section problem
 - Three essential criteria to solve the critical-section problem
 - Mutual exclusion
 - Progress
 - Bounded waiting
 - Preemptive and Non-preemptive Kernels
 - Types of solutions to critical-section problem
 - Software-based solutions
 - Hardware-based solutions
 - Operating system solutions
 - Programming language solutions
 - ♦ Software solutions to critical-section problem
 - Algorithm 1-5
 - Peterson's algorithm
 - Peterson's solution for n processes
 - Lamport's Bakery algorithm for n processes
 - Eisenberg-McGuire's algorithm for n processes
 - Lab work: Peterson's algorithm

16. Process Synchronization (1)

- Synchronization Hardware
 - ♦ Atomic (non-interruptible) hardware instructions
 - test_and_set()
 - compare_and_swap()
 - ♦ Mutual exclusion with hardware instructions
- Mutex Lock
 - ♦ Concept of mutex lock
- Semaphores
 - ♦ Concepts
 - Semaphore
 - · Semaphore operations
 - wait(S) and signal(S)
 - P and V operations
 - Solution to critical-section problem with semaphores
 - ♦ Implementation of semaphore
 - Binary Semaphore Implementation
 - Counting Semaphore Implementing
 - ♦ Deadlock and starvation with semaphore
 - ♦ Incorrect use of semaphores
- Solution to Classical Problems with Semaphores
 - ♦ Classical Problems

- Bounded-buffer problem
- Readers-writers problem
- Dining-philosophers problem

17. Process Synchronization (2)

Monitors

- ♦ The monitor type
- ♦ Monitor usage
- ♦ Monitor condition type
- Monitor condition variables
- Monitor condition operations
 - cwait(x) and csignal(x)
- ♦ Solution to the dining-philosophers problem with monitor
- ♦ Monitor implementation using semaphores

■ Deadlock

- ♦ What is deadlock (system model)
- ♦ Four necessary conditions of deadlock
- ♦ Resource allocation graph
- ♦ Methods for handling deadlock
 - · Preventing and Avoiding
 - Detecting and Recovering
 - Ignoring
- ♦ The Banker's algorithm
 - Safety algorithm
 - Resource-request algorithm
 - Limitations of Deadlock Avoidance
 - Programming: the Banker's algorithm

18. Process Synchronization (3)

- Synchronization Examples
 - → Linux gcc __sync atomic family
 - Programming: demo for Linux __sync_** type
 - ♦ POSIX mutex locks
 - Programming: demo for POSIX mutex lock
 - ♦ POSIX unnamed semaphore
 - Programming: demo for POSIX unnamed semaphores
 - ♦ POSIX named semaphore
 - Programming: demo for POSIX named semaphores
 - ♦ POSIX Synchronization
 - Programming: Solution to multi-producer-multi-consumer problem with POSIX semaphores and shared memory

19. CPU Scheduling (1)

Basic Concepts

- ♦ CPU-I/O burst cycle
- ♦ CPU burst time
- ♦ When to make CPU scheduling
- ♦ preemptive scheduling
 - during system call
 - during interruption
- Dispatcher and dispatcher latency
- CPU Scheduling Criteria
 - ♦ Scheduling goals of different systems
 - All systems
 - Batch systems
 - Interactive systems
 - Real-time systems
 - ♦ Scheduling criteria
 - CPU utilization
 - Throughput
 - Turnaround time
 - Waiting time
 - Response time
- Simple Scheduling Algorithms
 - ♦ First-come, first-served scheduling
 - ♦ Shortest-job-first scheduling
 - ♦ Priority scheduling
- Advanced Scheduling Algorithms
 - ♦ Round-robin scheduling
 - ♦ Multiple-priority queues scheduling
 - ♦ Multilevel feedback queue scheduling
 - ♦ Thread scheduling

20. CPU Scheduling (2)

- Multiple-Processor Scheduling
 - ♦ Processor affinity
 - Soft affinity
 - Hard affinity
 - ♦ Load balancing
 - Push migration
 - Pull migration
 - Load balancing vs. processor affinity
 - ♦ Multicore processors
 - Memory stall
- Real-Time CPU Scheduling
 - ♦ Soft real-time and hard real-time systems
 - ♦ Minimizing Latency
 - Event Latency

- Interrupt latency
- Dispatch latency
- ♦ Priority-based scheduling
- ♦ Rate-monotonic scheduling
- ♦ Earliest-deadline-first scheduling
- ♦ Least Laxity First algorithm
- Proportional share scheduling
- ♦ POSIX real-time scheduling
 - Programming: demo for POSIX real-time scheduling
- Linux Scheduling
 - ♦ Completely Fair Scheduler
 - ♦ RTLinux
- Algorithms Evaluation
 - ♦ Deterministic modeling
 - ♦ Queuing models
 - ♦ Simulations
 - ♦ Lab work: CPU scheduling simulations

21. Introduction to Memory Management

- Basic Concepts
 - ♦ Hardware address protection
 - ♦ Address binding
 - ♦ Logical address space and physical address space
 - ♦ Memory-mapped unit (MMU)
 - ♦ Relocation register
 - ♦ Hardware support for relocation and limit registers
 - ♦ Hardware translation of address
 - ♦ Dynamic linking
 - ♦ Swapping
 - ♦ Program size vs. memory size
- Memory Management Requirements
 - ♦ Relocation
 - ♦ Protection
 - ♦ Sharing
 - ♦ Logical organization
 - ♦ Physical organization
- Memory Partitioning
 - ♦ Contiguous allocation
 - ♦ Real memory management techniques
 - ♦ Fixed partitioning
 - Dynamics of fixed partitioning
 - Fragmentation
 - Variable partitioning
 - Internal fragmentation

- External fragmentation
- Compaction
- Basic placement algorithms: First-fit, Next-fit, Best-fit and Worst-fit
- ♦ Buddy system

22. Memory Segmentation and Paging

- Simple Segmentation
 - ♦ User view of a program
 - Dynamics of simple segmentation
 - Segment table
 - Base & limit
 - Segment-table base register (STBR)
 - Segment-table length register (STLR)
 - ♦ Address translation
 - ♦ Protection
 - ♦ Sharing
- Simple Paging
 - ♦ Non-contiguous to avoid external fragmentation
 - ♦ Page and page frame
 - ♦ Free-frame list
 - ♦ Logical address structure
 - ♦ Page table
 - ♦ Page-table base register (PTBR)
 - ♦ Page-table length register (PTLR)
 - ♦ Translation Look-aside Buffer (TLB)
 - ♦ Address translation
 - ♦ Paging hardware with TLB
 - ♦ Protection
 - ♦ Sharing
 - ♦ Structure of page tables
 - Hierarchical page tables
 - Hashed page tables
 - Inverted page tables
- Examples

23. Virtual Memory and Demand Paging (1)

- Virtual Memory
 - ♦ Concept of virtual memory
 - ♦ Virtual memory addressing
 - ♦ Virtual address space
 - ♦ Shared libraries with virtual memory
 - ♦ Process execution with virtual memory
- Demand Paging

- ♦ Concepts of demand paging
- ♦ Page table
- ♦ Present-bit and modified-bit
- ♦ Page fault
 - Steps in handling a page fault
- ♦ Page replacement
 - Steps in handling a page replacement
- ♦ Demand paging with TLB
- ♦ Stages in demand paging (worse case)
- ♦ Performance of demand paging
- Demand Paging Considerations
 - ♦ Locality
 - ♦ Thrashing
 - ♦ Memory-mapped files
 - ♦ Buddy system
 - ♦ Slab system
 - ♦ Copy-on-write
 - ♦ Other issues

24. Virtual Memory and Demand Paging (2)

- Page Replacement Algorithms
 - ♦ Basic page replacement
 - ♦ FIFO algorithm
 - ♦ Optimal page replacement
 - ♦ Least recently used (LRU) algorithm
 - Counter implementation
 - Stack implementation
 - Hardware matrix LRU implementation
 - ♦ LRU approximation algorithms
 - Reference bit and reference byte
 - Second-chance algorithm (CLOCK algorithm)
 - Enhanced second-chance algorithm
 - ♦ Cleaning policy
 - ♦ Lab work: page replacement algorithms
- Combined Segmentation and Paging
- Virtual Memory Policies

25. Mass Storage Systems

- Introduction
 - ♦ Hard disk Structure
 - · Disk Head and head crash
 - Track, section and cylinder
 - Host controller and Hard disk controller
 - Transfer rate and positioning time

- Hard disk performance
- Logical block
- ♦ Hard disk attachment
- Disk Scheduling
 - ♦ Data access time
 - ♦ I/O request queues
 - ♦ First-come first-serve (FCFS)
 - Zigzag effects
 - ♦ Shortest seek time first (SSTF)
 - ♦ Elevator algorithms
 - SCAN scheduling and C-SCAN scheduling
 - LOOK scheduling and C-LOOK scheduling
- Disk Management
 - ♦ Swap-space Management
 - ♦ RAID structure
- Stable-Storage Implementation

26. File System Interface

- Basic Concepts
 - ♦ Files
 - ♦ File attributes
 - ♦ File type extensions
 - ♦ File operations
 - ♦ Access methods
 - Sequential access
 - Direct access
 - ♦ Types of file systems
- File Directories
 - ♦ Elements
 - ♦ Operations
 - ♦ Single-level directory
 - ♦ Two-level directory
 - ♦ Tree-structure directories
 - ♦ DAG directories
 - ♦ General graph directory
 - ♦ File system mounting
- File Sharing and Protection

27. File System Implementation

- File-System Structure
 - → File control block (FCB)
 - ♦ File system layers
 - I/O control level

- Basic file system
- · File organization module
- Logical file system
- ♦ On-storage structures
 - Boot control block, volume control block, directory structure, FCB
- ♦ In-memory structures
 - Mount table, directory-structure cache, system-wide open-file table, open-file table, buffers
- ♦ Directory Implementation
 - Linear list
 - Hash table
- Allocation Methods
 - ♦ Contiguous allocation
 - ♦ Linked allocation/Chained allocation
 - File allocation table (FAT)
 - ♦ Indexed allocation
 - One block scheme
 - Linked scheme
 - Two-level index scheme
 - ♦ Combined schemes
 - ♦ Performance analysis
- Free-Space Management
 - ♦ Bitmap with n blocks
 - ♦ Free-block list (Linked list)
 - ♦ Grouping and counting
 - ♦ Space maps
- Efficiency and Performance
- Recovery
- NFS
- Example: WAFL File System

28. I/O Systems

- Overview
- I/O Hardware
 - ♦ Port, Bus, PCI, PCIe, Expansion bus, Controller (host adapter)
 - ♦ Typical PC bus structure
 - ♦ Memory mapped I/O (MMIO)
 - ♦ I/O device-control registers
 - ♦ Polling (steps)
 - ♦ Interrupt
 - Interrupt-request line
 - Interrupt handler routine
 - Maskable and non-maskable interrupts

- Interrupt vector
- Difference among interrupt, fault, trap and exception
- ♦ Direct memory access (DMA)
 - Cycle stealing
 - DMA steps
- Application I/O Interface
 - ♦ Kernel I/O structure
 - ♦ I/O devices vary in many dimensions
 - Data transfer mode
 - Access mode
 - Transfer schedule
 - Sharing
 - Speed of operation
 - I/O direction
- Kernel I/O Subsystem
 - ♦ Services provided by kernel's I/O subsystem
 - Scheduling
 - Buffering
 - Caching
 - Spooling
 - Device reservation
 - Error handling.
 - ♦ I/O protection
 - ♦ I/O kernel structures
- Power management
- Transforming I/O Requests to Hardware Operations
 - ♦ 10 Steps
- **STREAMS
- Performance Analysis

== The End