Pattern Recognition Project Presentation

The Blue Guys

Group Members



KWS - Implementation Details

Implemented in Python

Used external libraries

KWS

Things we did:

- 1 Find a way to cut the segmentations (used PIL)
- 2 Find appropriate features for describing images
- 3 Using a library for doing DTW
- 4 Getting it all together

KWS - Feature Vector

Used Features:

- Fraction of black pixels
- Upper contour
- Lower contour
- Number of transitions
- Fraction of black pixels between lower half and upper half

KWS - Features

```
WINDSTITUMITUMS NEEDED STORY
                                                        distance 204:
                                                        distance 213 : 9.91416633908
       f = [el/float(norm) for el in f]
                                                       distance 214: 12.2240241938
                                                        distance 216: 7.55893478175
   feat.append(f)
                                                       distance 218: 18.3655027147
                                                       distance 219 : 10.6431651916
                                                       distance 220 : 27.7378438699
eturn feat
                                                       hamed@a-n56jr:~/Git Repositories/KWS$
```

KWS - DTW Library

- Learnt the theories behind DTW first
- Used fastdtw 0.3.0 for the DTW part

Signature Verification

Collect biometric data as the users are signing at certain time intervals

Data: coordinates, pressure, pen-up/down, angles

Signature Verification

Problem: Even the same person can take variable amounts of time to make a signature.

Difficult to compare uneven sets of data.

Dynamic Time Warping

Solution: Dynamic Time Warping is a technique to measure the distance between two uneven temporal sequences.

Data Preparation

- Read data from file save them in an nx7 matrix.
- N is variable depending how much time the signatory need to sign
- 7 is the number of the original features.
- Data
 - o Time
 - X, Y coordinates
 - Pressure
 - o Pen-up
 - Azimuth
 - Inclination

Feature extraction

- Calculate speeds for each coordinate on every time-stamp
- Features used:
 - o X, Y
 - Speed X and Y
 - Pressure
- Final matrix n x 5

Preprocessing

Rescaling:

$$RescaledX = \frac{x - \min(x)}{\max(x) - \min(x)}$$

Distances

- For each signature to be verified we calculate its distance from each of the original signatures of the particular signatory.
- Calculate the mean.