Hamed Alimohammadzadeh

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EDUCATION

University of Southern California

August 2022 - Expected May 2027

Ph.D. Candidate in Computer Science (Passed Qualifying Exam- December 2024)

• Advised by Prof. Shahram Ghandeharizadeh

University of Southern California

August 2022 - May 2024

Master of Science (MS) - Computer Science

Sharif University of Technology

September 2017 - July 2022

Bachelor of Science (BS) - Computer Engineering

• Thesis: Multi-Modal Object Detection by Improving Neural Network Learning. Advised by Prof. Shohreh Kasaei.

RESEARCH INTERESTS

Machine Learning: Utilizing machine learning techniques for visual rendering with swarm robotics.

Swarm Robotics: Decentralized localization of swarms of flying robots to render 3D point clouds.

Human-Computer Interaction: immersive multimedia displays using swarms of UAVs with haptic feedback.

SKILLS

Programming Languages: Python, C/C++, JavaScript, Matlab

Software & Tools: OpenCV, Unity, Blender (Python API), OpenGL/WebGL, ROS, Fusion 360, MAVLink, Docker, Vue.js

PUBLICATIONS

- [1] Reproducibility Companion Paper: Swarical: An Integrated Hierarchical Approach to Localizing Flying Light Specks
 - H. Alimohammadzadeh, S. Ghandeharizadeh, F. Cunico, J. Springer.

In Proceedings of the 33rd ACM International Conference on Multimedia, October 27–31, 2025.

- [2] Illuminating English Letters Using a Flying Light Specks
 - H. Alimohammadzadeh, S. Ghandeharizadeh.

In Proceedings of the 3rd International Workshop on UAVs in Multimedia: Capturing the World from a New Perspective (UAVM '25), October 27–28, 2025, March 14, 2025.

- [3] Techniques to Conceal Dark Standby Flying Light Specks
 - H. Alimohammadzadeh, S. Zhu, S. Ghandeharizadeh.

In ACM Transactions on Multimedia Computing, Communications and Applications, March 14, 2025.

- [4] Swazure: Swarm Measurement of Pose for Flying Light Specks
 - H. Alimohammadzadeh, S. Ghandeharizadeh.

In International Conference on Holodecks, Los Angeles, USA, December 19, 2024.

- [5] Swarical: An Integrated Hierarchical Approach to Localizing Flying Light Specks
 - H. Alimohammadzadeh, S. Ghandeharizadeh.

In ACM Multimedia, Melbourne, Australia, 28 October - 1 November 2024.

[6] Reliability Groups with Standby Flying Light Specks

H. Alimohammadzadeh, S. Zhu, S. Ghandeharizadeh In ACM SIGMM Conference on Multimedia Systems, Bari, Italy, April 15-18, 2024.

[7] Force-Feedback Through Touch-based Interactions With A Nanocopter

Y. Chen, **H. Alimohammadzadeh**, S. Ghandeharizadeh, H. Culbertson In 2024 IEEE Haptics Symposium (HAPTICS), Long Beach, USA, April 7-10, 2024.

[8] SwarMer: A Decentralized Localization Framework for Flying Light Specks

H. Alimohammadzadeh, S. Ghandeharizadeh

In the First International Conference on Holodecks, Los Angeles, USA, December 15, 2023.

[9] A Conceptual Model of Intelligent Multimedia Data Rendered using Flying Light Specks

N. Yazdani, **H. Alimohammadzadeh**, S. Ghandeharizadeh

In the First International Conference on Holodecks Los Angeles, USA, December 15, 2023.

[10] Towards a Stable 3D Physical Human-Drone Interaction

Y. Chen, **H. Alimohammadzadeh**, S. Ghandeharizadeh, H. Culbertson In First International Conference on Holodecks, Los Angeles, USA, December 15, 2023.

[11] Towards Enabling Complex Touch-based Human-Drone Interaction

Y. Chen, **H. Alimohammadzadeh**, S. Ghandeharizadeh, H. Culbertson In Workshop on Human Multi-Robot Interaction, IROS, Detroit, USA, October 1, 2023.

[12] An Evaluation of Decentralized Group Formation Techniques for Flying Light Specks

H. Alimohammadzadeh, H. Culbertson, and S. Ghandeharizadeh In ACM Multimedia Asia, Taipei, Taiwan, December 6-8, 2023.

[13] An Evaluation of Three Distance Measurement Technologies for Flying Light Specks

T. Phan, **H. Alimohammadzadeh**, H. Culbertson, and S. Ghandeharizadeh In International Conference on Intelligent Metaverse Technologies and Applications, Tartu, Estonia, September 18-20, 2023.

[14] Dronevision: An Experimental 3D Testbed for Flying Light Specks

H. Alimohammadzadeh, R. Bernard, Y. Chen, T. Phan, P. Singh, S. Zhu, H. Culbertson, and S. Ghandeharizadeh In the First International Conference on Holodecks, October 1, 2023.

[15] Modeling Illumination Data with Flying Light Specks

H. Alimohammadzadeh, D. Mehraban, and S. Ghandeharizadeh

In Proceedings of the 14th Conference on ACM Multimedia Systems, Vancouver, Canada, June 7-10, 2023.

EXPERIENCE

Flying Light Specks Lab (FLS Lab), University of Southern California

August 2022 - Present

Research Assistant - PI: Prof. Shahram Ghandeharizadeh

- Design a novel collaborative localization algorithm enabling drones to autonomously form 3D formations; later optimized the algorithm's performance, achieving a 2x increase in speed for real-time deployment.
- Develop and implement multi-process emulators for decentralized algorithms across 1,000+ nodes, prioritizing high performance and scalability across AWS and Cloudlab environments using Python.
- Hands-on experience with Crazyflies to evaluate downwash effects and haptic interactions with multiple drones.
- Implement computer vision techniques using Raspberry Pi and camera modules for drones using C++ and Python for real-time position estimation.
- Build physical prototypes of a flying light speck as a miniature drone with self-reliant localization.

Image Processing Lab (IPL), Sharif University of Technology

September 2021 - July 2022

Research Assistant - PI: Prof. Shohreh Kasaei

• Enhanced the accuracy of mitosis detection by 7% across varied datasets by implementing a domain generalization algorithm for multi-domain mitosis figure detection using FastAI and RetinaNet in Python.

Sotoon Cloud Services June 2020 - August 2022

Front-End Engineer

- Developed and maintained a web application for voice and image annotation using Vue with 120+ customers, doubling annotation speed.
- Designed and developed 10+ accessible components for a UI framework using Vue 3, TypeScript, and Tailwind enhancing user experience and accessibility standards.
- Mentored two front-end engineers in their onboarding process.

LEADERSHIP

Board Chair, Students' Scientific Chapter (SSC), Sharif University of Technology

July 2020 - July 2021

• Organized 10+ competitions, workshops, and extracurricular events, engaging 2,000+ participants and fostering a collaborative learning environment across the Department of Computer.

Technical Lead, Sharif AI Challenge 2020, Sharif University of Technology

November 2019 - April 2020

• Facilitated cross-team collaboration among four technical teams, including game designers, web developers, and software engineers, for designing and implementing a competition in AI held by SSC where 300+ AI agents compete against each other to win a tournament.

TEACHING

| • | Database Systems (CSCI 585). Teaching Assistant. | Fall 2024 & Fall 2025 |
|---|--|-----------------------|
| • | Web Technologies. Teaching Assistant. | Fall 2020 |
| • | Web Technologies. Teaching Assistant. | Fall 2019 |
| • | Advanced Programming (Java). Teaching Assistant. | Spring 2019 |
| • | Introduction to Programming (C). Teaching Assistant. | Fall 2018 |

SERVICE

| • | Communication chair and program committee member of the 2nd International Conference on Holodecks | 2024 |
|---|---|------|
| • | Reviewed 3 technical papers as an invited reviewer for ACM-Multimedia'24 | 2024 |
| • | Communication chair and program committee member of the First International Conference on Holodecks | 2023 |
| • | Reviewed 3 technical papers as an invited reviewer for ACM-Multimedia'23 | 2023 |

MENTORSHIP

| • | Phong Nguyen & Allen Lam (undergraduate, USC CURVE program) | 2025 |
|---|---|------|
| • | Kariena Panpaliya & Xuanyu Pan (undergraduate, USC CURVE program) | 2024 |
| • | Wallace Browning (undergraduate, USC) | 2024 |

MEDIA

• Our work for the Holodecks conference is featured in the USC Viterbi School of Engineering news article 2024

AWARDS

• USC Graduate School Fellowship for 1 year of the PhD program

2022

| RoboCup Iran Open 2nd rank in Junior Rescue-A League | 2015 |
|---|------|
| RoboCup Iran Open 1st in Junior Rescue-A super-team competition | 2015 |
| PROJECTS | |

Real-Time UAV Teleoperation with Haptic Feedback

2023

• Created a system for bidirectional teleoperation of a UAV with haptic feedback for obstacle avoidance, demonstrating skills in building responsive, real-time systems.

Scalable Social Media Platform

2021

- Designed and developed a scalable social media platform from the ground up using a microservices architecture, demonstrating experience in building the backend for online services.
- Implemented backend services in Express.js, containerized the system with Docker, and managed traffic with an NGINX load balancer to ensure high availability and performance.