# **Curriculum Vitae**

# Hamid Manouchehri





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### **Education:**

Master of Science in Mechatronics Engineering

University of Tehran

Tehran, Iran 2019 - Dec 2022

Thesis title: A Model-Based Control System for Bi-Manual Manipulation (In progress)

**GPA: 3.22 / 4** (15.91 / 20.00)

Bachelor of Science in Electrical Engineering (Control Engineering)

Kashan, Iran 2015 - 2019

University of Kashan **Project title:** Design and Manufacturing of Pneumatics Table of Instrumentation Lab (<u>link</u>)

**GPA: 3.09 / 4** (15.74 / 20.00) - last two years

## **Research Interests:**

Legged locomotion

- Machine Vision
- Robotic Manipulators

- Autonomous Mobile Manipulators
- Underactuated Robotics
- AI, particularly for robotics applications

## **Teaching Experience:**

> Teacher Assistant Spring 2017

Instructor: Dr. Farzan Rezaei

Course: Digital Logic and Computer Design

Responsibilities: Teaching applications of 'Proteus Design Suite' in digital circuit analysis

and design, and mentoring the students.

# **Project and Research Experiences:**

➤ Implementation of Ant Colony Optimization (ACO) in Vehicle Routing Problem and

Genetic Algorithm in a Decision-Making Problem. (link)

Apr 2021

Instructor: <u>Dr. Masoud AsadPour</u>
Course: Bio-inspired Computing

> Implementation of a PID Controller by Fuzzy Logic (Self-organizing Fuzzy PID Controller)

Jan 2021

Instructor: Prof. Aghil Yousefi Koma

Course: Fuzzy Systems: Theory and Control

Simulation of a Wheeled Inverted Pendulum by Partial Feedback Linearization (link)

Feb 2021

**Instructor:** Dr. Khalil Alipour

**Course:** Nonlinear Control Systems Design

Design and Manufacturing of a 3-DOF Robotic Manipulator (MeArm) (link)

Mar 2020

Instructor: Dr. Mohammad Dehghani

**Course:** Advanced Robotics

Design and Simulation of a Pipe-inspection Robot in SolidWorks (link)

Feb 2020

Instructor: Dr. Alireza Hadi Hosseinabadi

Course: Mechatronics 2

Fanavard Competition of Sharif University of Technology

Summer 2017

→ As a team, we were planning to run an E-Commerce **startup** to provide online repairing

services.

## **Skills:**

- Robotic Softwares / Middlewares: Robot Operating System (ROS 1), rbdl toolkit, RViz, MOVEit, OpenCV (familiar), RoboDK (familiar)
- Programming Languages: C (Professional), Python, C++, C#, bash script, XML, Lua
- > Technical Softwares: Matlab (Script, Simulink, GUI), Proteus, Altium Designer, Docker
- Mechanical Softwares: SolidWorks, FreeCad (familiar), MCS Adams
- > Embedded Systems: MPLAB X IDE (PIC MCUs), Keil (ARM MCUs), CodeVision (AVR MCUs), Raspberry Pi Pico MCU, Arduino IDE, Raspberry Pi (Raspbian OS), NodeMCU, SIM800L GSM
- Version Control Tools: Git, GitHub, GitLab
- Linux: LPIC-1 (Linux Professional Institute)

## **Working Experience:**

	Electronics	Engineer,	Part-time	( <u>link</u> )
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**Employer:** Parmis Smart Home **Business:** Design of smart devices for BMS (Building Management System) Responsibilities: Embedded system designer, Firmware developer of PIC MCUs

Electronics Engineer, CAD Designer, Part-time (link)

Tehran, Iran **Employer:** Kanda Idea Company Feb - Nov 2020

Responsibilities: Research and Development, Designing a box for some electrical devices with SolidWorks

Windows Software Developer, C# programmer, Internship

Isfahan, Iran Jun - Aug 2017 Employer: Behyar Sanaat Sepahan Co.

Responsibilities: Development of windows softwares in VisualStudio (WPF), C# programming

### **Certificate:**

Robot Operating System (ROS): Basic, offered by PISHROBOT, approved by ROBOTIS Covered topics: Basic concepts of ROS 1 (melodic), navigation of TurtleBot in RViz as final project.

Sep 2021

Isfahan, Iran

Mar - Dec 2021

# **Language Proficiency:**

Level	Overall Score	Scores	Exam	Date
Advanced	-	-	IELTS (Academic)	November 2022

#### **References:**

Dr. Mohammad Shahbazi	M.Sc. Supervisor	Assistant Professor   School of Mechanical Engineering Iran University of Science and Technology Email: <a href="mailto:shahbazi@iust.ac.ir">shahbazi@iust.ac.ir</a> , <a href="mailto:HomePage">HomePage</a> , <a href="mailto:Google Scholar">Google Scholar</a>
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