# **Curriculum Vitae**

# Hamid Manouchehri



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in



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#### **Education:**

Master of Science in Mechatronics Engineering

University of Tehran

Thesis title: A Model-Based Control System for Bi-Manual Object Manipulation (link)

Tehran, Iran 2019 - Feb 2023

Bachelor of Science in Electrical Engineering (Control Engineering)

University of Kashan

**Project title:** Design and Manufacturing of Pneumatics Table of Instrumentation Lab (link)

Kashan, Iran 2015 - 2019

# **Research Interests:**

**Legged Locomotion** 

**Machine Vision** 

**Robotic Manipulators** 

- **Autonomous Mobile Manipulators**
- **Underactuated Robotics**
- Al, particularly for robotics applications

### **Teaching Experience:**

Teacher Assistant Spring 2017

Instructor: Dr. Farzan Rezaei

Course: Digital Logic and Computer Design

Responsibilities: Teaching applications of 'Proteus Design Suite' in digital circuit analysis

and design, and mentoring the students.

# **Project and Research Experiences:**

> Implementation of Ant Colony Optimization (ACO) in Vehicle Routing Problem and Apr 2021 Genetic Algorithm in a Decision-Making Problem. (link)

Instructor: Dr. Masoud AsadPour **Course:** Bio-inspired Computing

> Implementation of a PID Controller by Fuzzy Logic (Self-organizing Fuzzy PID Controller)

Instructor: Prof. Aghil Yousefi Koma

Course: Fuzzy Systems: Theory and Control

Simulation of a Wheeled Inverted Pendulum by Partial Feedback Linearization (link)

**Instructor:** Dr. Khalil Alipour

**Course:** Nonlinear Control Systems Design

Design and Manufacturing of a 3-DOF Robotic Manipulator (MeArm) (link)

Instructor: Dr. Mohammad Dehghani

Course: Advanced Robotics

Design and Simulation of a Pipe-inspection Robot in SolidWorks (link)

Instructor: Dr. Alireza Hadi Hosseinabadi

Course: Mechatronics 2

Fanavard Competition of Sharif University of Technology

→ As a team, we were planning to run an E-Commerce startup to provide online repairing services.

**Summer 2017** 

Feb 2020

Jan 2021

Feb 2021

Mar 2020

## **Skills:**

- Robotic Softwares / Middlewares: Robot Operating System (ROS 1), RBDL toolkit, RViz, MOVEit, OpenCV (familiar), RoboDK (familiar)
- Programming Languages: C (Professional), Python, C++, C#, bash script, XML, Lua
- > Technical Softwares: MATLAB (Script, Simulink, GUI), Proteus, Altium Designer, Docker
- Mechanical Softwares: SolidWorks, FreeCad (familiar), MCS Adams
- > Embedded Systems: MPLAB X IDE (PIC MCUs), Keil (ARM MCUs), CodeVision (AVR MCUs), Raspberry Pi Pico MCU, Arduino IDE, Raspberry Pi (Raspbian OS), NodeMCU, SIM800L GSM
- Version Control Tools: Git, GitHub, GitLab
- Linux: LPIC-1 (Linux Professional Institute)

### **Working Experience:**

Electronics Engineer, Part-time (<u>link</u>)

Isfahan, Iran **Employer:** Parmis Smart Home Mar - Dec 2021 **Business:** Design of smart devices for BMS (Building Management System)

Electronics Engineer, CAD Designer, Part-time (link)

Tehran, Iran **Employer:** Kanda Idea Company Feb - Nov 2020

Responsibilities: Research and Development, Designing a box for some electrical devices

with SolidWorks

Windows Software Developer, C# programmer, Internship

Employer: Behyar Sanaat Sepahan Co.

Responsibilities: Development of windows softwares in VisualStudio (WPF), C# programming

Responsibilities: Embedded system designer, Firmware developer of PIC MCUs

#### **Certificate:**

Robot Operating System (ROS): Basic, offered by PISHROBOT, approved by ROBOTIS Covered topics: Basic concepts of ROS 1 (melodic), navigation of TurtleBot in RViz as final project.

Sep 2021

Isfahan, Iran Jun - Aug 2017

# **Language Proficiency:**

Exam	Overall Score	Scores	
TOEFL iBT (Mar 12, 2023)	-	-	
GRE General (Apr 17, 2023)	-	-	

#### **References:**

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