

# Quicksort

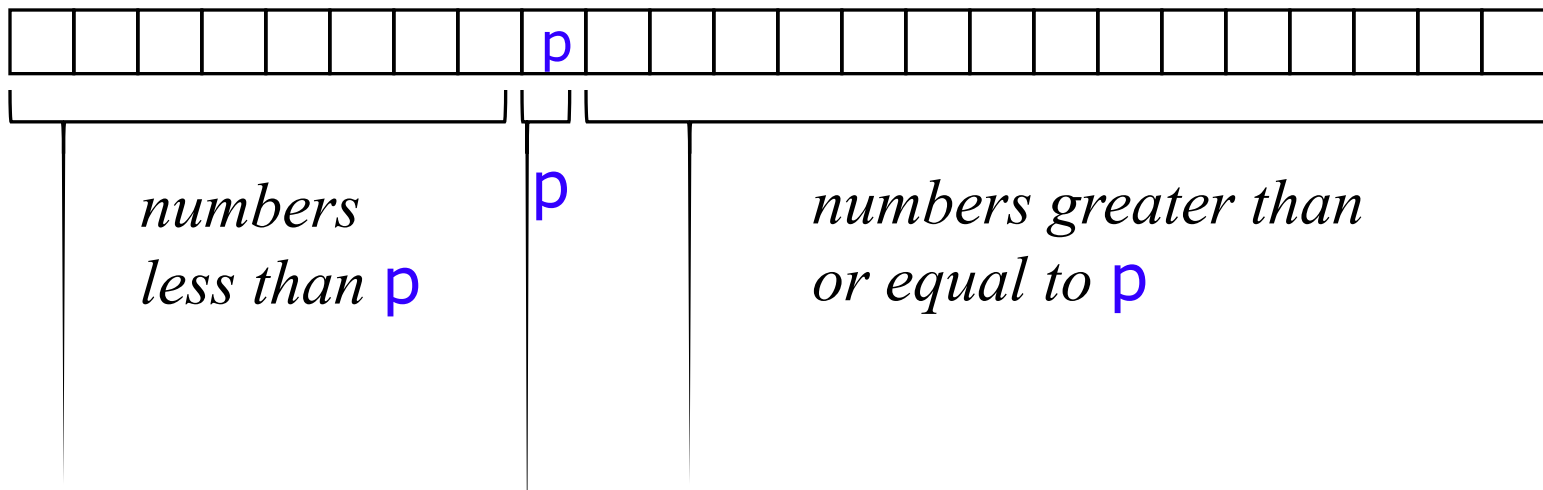
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# Quicksort I: Basic idea

- Pick some number  $p$  from the array
- Move all numbers less than  $p$  to the beginning of the array
- Move all numbers greater than (or equal to)  $p$  to the end of the array
- Quicksort the numbers less than  $p$
- Quicksort the numbers greater than or equal to  $p$





# Quicksort II

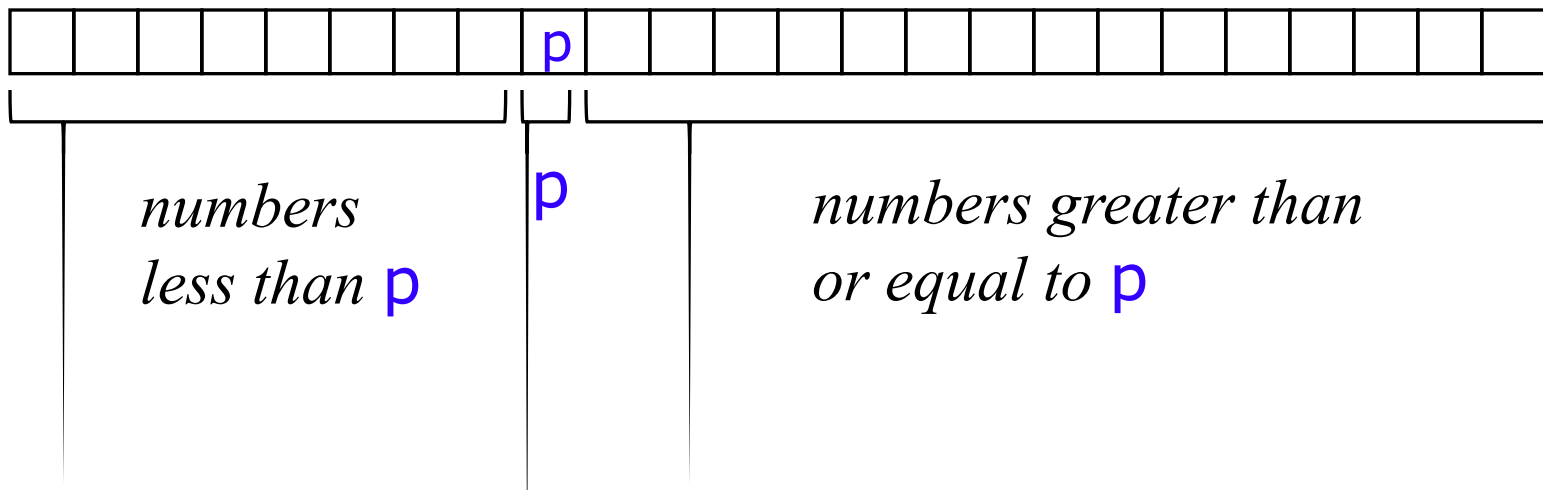
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- To sort  $a[\text{left} \dots \text{right}]$ :
  1. if  $\text{left} < \text{right}$ :
    - 1.1. Partition  $a[\text{left} \dots \text{right}]$  such that:
      - all  $a[\text{left} \dots p-1]$  are less than  $a[p]$ , and
      - all  $a[p+1 \dots \text{right}]$  are  $\geq a[p]$
    - 1.2. Quicksort  $a[\text{left} \dots p-1]$
    - 1.3. Quicksort  $a[p+1 \dots \text{right}]$
  2. Terminate



# Partitioning (Quicksort II)

- A key step in the Quicksort algorithm is **partitioning** the array
  - We choose some (any) number **p** in the array to use as a **pivot**
  - We **partition** the array into three parts:





# Partitioning II

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- Choose an array value (say, the first) to use as the pivot
- Starting from the left end, find the first element that is greater than or equal to the pivot
- Searching backward from the right end, find the first element that is less than the pivot
- Interchange (swap) these two elements
- Repeat, searching from where we left off, until done



# Partitioning

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- To partition  $a[\text{left} \dots \text{right}]$ :
  1. Set  $\text{pivot} = a[\text{left}]$ ,  $l = \text{left} + 1$ ,  $r = \text{right}$ ;
  2. while  $l < r$ , do
    - 2.1. while  $l < \text{right} \ \& \ a[l] < \text{pivot}$  , set  $l = l + 1$
    - 2.2. while  $r > \text{left} \ \& \ a[r] \geq \text{pivot}$  , set  $r = r - 1$
    - 2.3. if  $l < r$ , swap  $a[l]$  and  $a[r]$
  3. Set  $a[\text{left}] = a[r]$ ,  $a[r] = \text{pivot}$
  4. Terminate



# Example of partitioning

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- choose pivot: 4 3 6 9 2 4 3 1 2 1 8 9 3 5 6
- search: 4 3 6 9 2 4 3 1 2 1 8 9 3 5 6
- swap: 4 3 3 9 2 4 3 1 2 1 8 9 6 5 6
- search: 4 3 3 9 2 4 3 1 2 1 8 9 6 5 6
- swap: 4 3 3 1 2 4 3 1 2 9 8 9 6 5 6
- search: 4 3 3 1 2 4 3 1 2 9 8 9 6 5 6
- swap: 4 3 3 1 2 2 3 1 4 9 8 9 6 5 6
- search: 4 3 3 1 2 2 3 1 4 9 8 9 6 5 6 (left > right)
- swap with pivot: 1 3 3 1 2 2 3 4 4 9 8 9 6 5 6



# The partition method (Java)

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```
static int partition(int[] a, int left, int right) {  
    int p = a[left], l = left + 1, r = right;  
    while (l < r) {  
        while (l < right && a[l] < p) l++;  
        while (r > left && a[r] >= p) r--;  
        if (l < r) {  
            int temp = a[l]; a[l] = a[r]; a[r] = temp;  
        }  
    }  
    a[left] = a[r];  
    a[r] = p;  
    return r;  
}
```





# The quicksort method (in Java)

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```
static void quicksort(int[] array, int left, int right) {  
    if (left < right) {  
        int p = partition(array, left, right);  
        quicksort(array, left, p - 1);  
        quicksort(array, p + 1, right);  
    }  
}
```



# Analysis of quicksort—best case

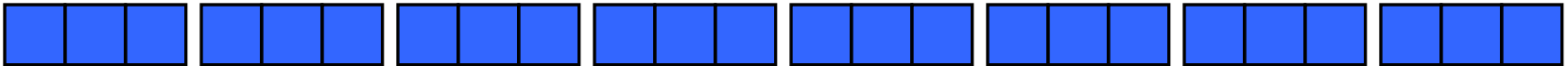
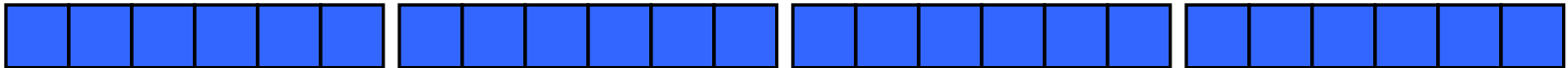
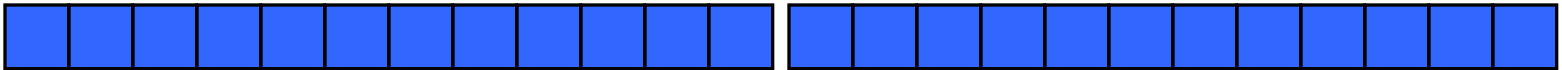
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- Suppose each partition operation divides the array almost exactly in half
- Then the depth of the recursion is  $\log_2 n$ 
  - Because that's how many times we can halve  $n$
- However, there are many recursions!
  - How can we figure this out?
  - We note that
    - Each partition is linear over its subarray
    - All the partitions at one level cover the array



# Partitioning at various levels

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## Best case II

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- We cut the array size in half each time
- So the depth of the recursion in  $\log_2 n$
- At each level of the recursion, all the partitions at that level do work that is linear in  $n$
- $O(\log_2 n) * O(n) = O(n \log_2 n)$
- Hence in the average case, quicksort has time complexity  $O(n \log_2 n)$
- What about the worst case?



# Worst case

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- In the worst case, partitioning always divides the size  $n$  array into these three parts:
  - A length one part, containing the pivot itself
  - A length zero part, and
  - A length  $n-1$  part, containing everything else
- We don't recur on the zero-length part
- Recurring on the length  $n-1$  part requires (in the worst case) recurring to depth  $n-1$



# Worst case partitioning

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# Worst case for quicksort

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- In the worst case, recursion may be  $n$  levels deep (for an array of size  $n$ )
- But the partitioning work done at each level is still  $n$
- $O(n) * O(n) = O(n^2)$
- So worst case for Quicksort is  $O(n^2)$
- When does this happen?
  - There are many arrangements that *could* make this happen
  - Here are two common cases:
    - When the array is already sorted
    - When the array is *inversely* sorted (sorted in the opposite order)



# Typical case for quicksort

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- If the array is sorted to begin with, Quicksort is terrible:  $O(n^2)$
- It is possible to construct other bad cases
- However, Quicksort is *usually*  $O(n \log_2 n)$
- The constants are so good that Quicksort is generally the fastest algorithm known
- Most real-world sorting is done by Quicksort





# Improving the interface

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- We've defined the Quicksort method as  
`static void quicksort(int[] array, int left, int right) { ... }`
- So we would have to call it as  
`quicksort(myArray, 0, myArray.length)`
- That's ugly!
- Solution:  
`static void quicksort(int[] array) {  
 quicksort(array, 0, array.length);  
}`
- Now we can make the original (3-argument) version private



# Tweaking Quicksort

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- Almost anything you can try to “improve” Quicksort will actually slow it down
- One *good* tweak is to switch to a different sorting method when the subarrays get small (say, 10 or 12)
  - Quicksort has too much overhead for small array sizes
- For large arrays, it *might* be a good idea to check beforehand if the array is already sorted
  - But there is a better tweak than this



# Picking a better pivot

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- Before, we picked the *first* element of the subarray to use as a pivot
  - If the array is already sorted, this results in  $O(n^2)$  behavior
  - It's no better if we pick the *last* element
- We could do an *optimal* quicksort (guaranteed  $O(n \log n)$ ) if we always picked a pivot value that exactly cuts the array in half
  - Such a value is called a **median**: half of the values in the array are larger, half are smaller
  - The easiest way to find the median is to *sort* the array and pick the value in the middle (!)



# Median of three

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- Obviously, it doesn't make sense to sort the array in order to find the median to use as a pivot
- Instead, compare just *three* elements of our (sub)array—the first, the last, and the middle
  - Take the *median* (middle value) of these three as pivot
  - It's possible (but not easy) to construct cases which will make this technique  $O(n^2)$
- Suppose we rearrange (sort) these three numbers so that the smallest is in the first position, the largest in the last position, and the other in the middle
  - This lets us simplify and speed up the partition loop



# Final comments

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- Quicksort is the fastest known sorting algorithm
- For optimum efficiency, the pivot must be chosen carefully
- “Median of three” is a good technique for choosing the pivot
- However, no matter what you do, there will be some cases where Quicksort runs in  $O(n^2)$  time



# The End

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