
System Requirements Specification

for

Ingenion Telemetry Web Server

Version 5.0

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Revision History

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1. Introduction

1.1 Purpose & Scope

The Ingenion Telemetry Web Server is purpose-built to serve as an integral tool in the testing and validation of satellite hardware, providing a real-time telemetry data interface that is both robust and user-friendly. Its scope is defined by the imperative to offer engineers a system that not only reliably processes telemetry data but also does so in a manner that facilitates ease of access and interaction. The server is intricately designed to augment the capabilities of existing Total Verification Systems (TVS), used extensively by space agencies, with an enhanced range of features that cater to modern satellite testing requirements.

This includes the strategic integration of a Xilinx MicroBlaze soft-core Central Processing Unit (CPU) within an Artix 7 Field-Programmable Gate Array (FPGA), alongside the deployment of FreeRTOS—an open-source real-time operating system. These integrations ensure that the Ingenion Telemetry Web Server not only hosts an interactive web server but also establishes Transmission Control Protocol (TCP) over Ethernet connections for seamless data management. While the server is adept at handling complex telemetry data, it is crafted with a focus on simplicity and user-centric design, ensuring that even non-specialist users can operate it with minimal training.

It is important to note that while the Ingenion Telemetry Web Server is comprehensive in its functionalities, it is not intended to serve as a development platform for telemetry algorithms. Instead, it is a facilitator, enabling the display and management of telemetry data derived from satellite testing operations. The development of a graphical user interface (GUI) is not within the scope of this project, as the system is designed to complement existing interfaces. The onus of ensuring compatibility of telemetry algorithms with this web server rests with the users, aligning with the project's goal of offering a streamlined and efficient telemetry data management system. The project is focused on individual telemetry streams, providing a specialized solution that does not extend to broader data collection methods or the complexities of managing drone swarms or other such entities.

1.2 Document Conventions

The software requirements document (SRS) adheres to industry-standard conventions for clarity and consistency. No specific fonts or highlighting conventions have been employed. We chose not to assign priorities to requirements as requirements must be completed for us to achieve our end goal for this project. The SRS aims to provide a clear and unambiguous representation of the software requirements without relying on formatting nuances for conveying significance.

1.3 Intended Audience and Reading Suggestions

- i. **Developers:** Start with the "Product Scope" and "Overall Description" sections for a high-level understanding. Dive into "Design and Implementation Constraints" for technical considerations. Explore "External Interface Requirements" for integration details.
- ii. **Scrum Master:** Begin with the "Introduction" and "Product Scope" for project context. Focus on "Assumptions and Dependencies" for potential risks. Review "Other Nonfunctional Requirements" and "Business Rules" for project constraints and standards.
- iii. **External Users:** Begin with the "Introduction" and "Product Scope" to grasp the project's purpose. Explore "User Interfaces" for interactions with the system.

1.4 Product Scope

Our objective for this phase of the Ingenion project is to focus on the software development for enhancing the Total Verification System (TVS), a critical testing tool used by NASA's Goddard Space Flight Center for simulating, testing, and verifying satellite hardware components. With the FPGA hardware already developed, our attention shifts to refining and expanding the system's software capabilities. This project will consist of the integration of FreeRTOS, an open-source real-time operating system, on the Xilinx MicroBlaze soft-core CPU implemented on the Artix 7 FPGA. In addition to the FreeRTOS implementation, we will develop an interactive web server hosted on the FPGA. The web server will facilitate connections to external computers using TCP over Ethernet, enabling the system to read and display telemetry data from peripherals including GPIO, SPI, UART, and I2C.

1.5 References

- i. Xilinx Wiki. (n.d.). ARTY FreeRTOS Web Server. Retrieved from <https://xilinx-wiki.atlassian.net/wiki/spaces/A/pages/18841844/ARTY+FreeRTOS+Web+Server>
- ii. Digilent. (n.d.). Nexys 4 DDR - Getting Started with Microblaze Servers. Retrieved from <https://digilent.com/reference/learn/programmable-logic/tutorials/nexys-4-ddr-getting-started-with-microblaze-servers/start>

2. Overall Description

2.1 Product Perspective

The Ingenion Telemetry Web Server project serves as an augmentation to the existing Total Verification System (TVS). It enhances the TVS by integrating a Xilinx MicroBlaze soft-core CPU on the Artix 7 FPGA and implementing FreeRTOS as an open-source real-time operating system. These enhancements enable the system to host an interactive web server, establish TCP over Ethernet connections with external computers, and manage telemetry data from external,

user-friendly connections. This integration will provide a vital bridge between existing satellite hardware components and the ability to monitor and interact with them remotely.

2.2 Product Functions

The system will host an interactive web server, establish TCP over Ethernet connections, and manage telemetry data. The primary functions of the Ingenion Telemetry Web Server project are as follows:

- Hosting an interactive web server to enable remote monitoring and control of satellite hardware components.
- Establishing TCP over Ethernet connections with external computers to facilitate data exchange and remote management.
- Managing telemetry data from external sources, making it accessible through user-friendly interfaces.

2.3 User Classes and Characteristics

Potential users of the system may include:

- Developers involved in system design and implementation.
- Engineers responsible for hardware and software integration.
- Project managers overseeing the project's progress.
- External users who access the web server for telemetry data and control.

2.4 Operating Environment

The operating environment for the Ingenion Telemetry Web Server project includes:

- Hardware components, such as the Artix 7 FPGA and Digilent Nexys A7 development board.
- Software components, including FreeRTOS as the real-time operating system.
- Network infrastructure to support TCP over Ethernet connections.
- Integration with the existing Total Verification System (TVS) at NASA's Goddard Space Flight Center.

2.5 Design and Implementation Constraints

Constraints for the Ingenion Telemetry Web Server project include:

- **Resource Allocation:** The project must operate within predefined resource constraints, including FPGA resources, memory, and processing power. Trade-offs have been considered to optimize resource utilization without compromising functionality.
- **Compatibility:** Compatibility with existing systems, including the TVS and external computer systems, imposes constraints on the design to ensure seamless integration.
- **Time and Labor:** The project operates within specific time, budget, and labor constraints, in order to complete this project within the given time period (1 semester), and labor (7 team members).

2.6 User Documentation

User Documentation and Helpful Resources

Below are curated resources to assist you with understanding and implementing web server capabilities on Xilinx FPGA platforms using MicroBlaze and FreeRTOS. Each link is accompanied by a brief description to guide you in selecting the resource that best fits your needs.

1. **MicroBlaze Webserver Demo on Xilinx FPGA**

This video tutorial showcases a demonstration of a web server running on a Xilinx FPGA utilizing the MicroBlaze soft processor. The demonstration covers the setup process, configuration, and operation of the web server, providing viewers with a practical example of embedded web server capabilities on FPGA platforms.

[Watch the demo](#)

2. **Implementing a Web Server on Xilinx FPGA with MicroBlaze**

A comprehensive YouTube tutorial that guides users through the process of implementing a web server on a Xilinx FPGA using the MicroBlaze soft processor. This video covers the necessary steps from initial setup to the final implementation, making it a valuable resource for both beginners and experienced users looking to explore web server applications on FPGA.

[View the tutorial on YouTube](#)

3. **ARTY FreeRTOS Web Server Tutorial**

This detailed guide on the Xilinx Wiki provides step-by-step instructions for setting up a FreeRTOS-based web server on the ARTY development board. The tutorial includes information on software and hardware requirements, configuration details, and troubleshooting tips, offering a comprehensive resource for developers looking to leverage FreeRTOS for web server applications on the ARTY platform.

[Read the guide on Xilinx Wiki](#)

These resources are designed to help you navigate the complexities of web server implementation on FPGA platforms, offering practical advice, tutorials, and demonstrations tailored to a variety of learning preferences and project requirements.

2.7 Assumptions and Dependencies

To ensure the success of the Ingenion Telemetry Web Server project, certain assumptions regarding the project environment, resources, and user capabilities must be acknowledged. These assumptions not only help in planning and executing the project but also in setting realistic expectations and preparing for potential adjustments. Below are our assumptions and dependencies:

Assumptions

1. User's Internet Connectivity

We assume that users have a stable and reliable internet connection. This is essential for accessing the telemetry web server, performing remote updates, and utilizing cloud-based services for data analytics and storage. Should users encounter connectivity issues, alternative methods for local data logging and analysis will be considered.

2. Availability of the Artix-7 FPGA Board

The project depends on users having access to the Artix-7 FPGA board, as the development and deployment of the telemetry web server are specifically tailored to this hardware platform. In cases where users do not have this board, guidance will be provided on sourcing the board or on adapting the project to compatible alternatives.

3. Familiarity with FPGA Development Tools

It is assumed that users possess a basic understanding of FPGA development tools and practices. This includes the ability to use Xilinx Vivado for hardware design and synthesis. For users with limited experience, the project will offer resources or recommend educational materials to help bridge the knowledge gap.

4. Access to Required Software and Licenses

The project assumes that users have access to all necessary software and any required licenses, such as development environments, compilers, and debugging tools. Should there be issues with software availability or licensing, the project may suggest open-source alternatives or provide assistance in acquiring the necessary resources.

3. External Interface Requirements

3.1 User Interfaces

REQ-3.1.1: The system shall host a web server via the FPGA's ethernet connection

REQ-3.1.2: The system's web server shall allow the user to read telemetry from the FPGA's onboard components

REQ-3.1.3: The system's web server shall allow the user to interact with the FPGA's onboard components

3.2 Hardware Interfaces

REQ-3.2.1: The system shall have ethernet capabilities with the user's computer through an ethernet interface at 100 Mbps

REQ-3.2.2: The software product shall interface with the memory in the FPGA

REQ-3.2.3: The system interface with the memory shall support read operations for data storage

REQ-3.2.5: The system interface with the memory shall support write operations for data storage

REQ-3.2.6: The software product shall interface with the GPIO soft cores within the FPGA

REQ-3.2.7: The system interface with the GPIO cores shall enable monitoring of the list of incoming signals

REQ-3.2.8: The system interface with the GPIO cores shall enable monitoring of the list of outgoing signals

3.3 Software Interfaces

REQ-3.3.1: The system must run FreeRTOS on the MicroBlaze CPU, with performance metrics meeting customer defined benchmarks.

REQ-3.3.2: The system must utilize FreeRTOS for task scheduling, with task delays of less than 1ms.

REQ-3.3.3: The system shall have a web server software component

REQ-3.3.4: The system's web server software component shall be compatible with FreeRTOS

REQ-3.3.5: The web server software must interface with FreeRTOS to retrieve telemetry data, demonstrating less than 1ms response times

REQ-3.3.6: The system must handle TCP/IP communication over Ethernet, with Cat 5 cable standards of 100Mbps

REQ-3.3.7: The system must gather the telemetry data from the AXI bus, sampling at the standard 400MHz

REQ-3.3.8: The system must process the telemetry data from the AXI bus, processing at a rate of 2s per address request

REQ-3.3.9: The system must gather telemetry data from peripherals, updating within 1s of change

REQ-3.3.9: The system must process telemetry data from peripherals, processing within 1s of data being gathered

REQ-3.3.10: The system must display telemetry data in real-time, with a defined maximum latency of 3s (1 for gathering, 1 for processing)

3.4 Communications Interfaces

REQ-3.4.1: The system must use HTTP for web interactions, meeting at least HTTP/2 standards

REQ-3.4.2: The system must implement WebSockets for real-time communication, with a standard delay maximum of 10ms

REQ-3.4.3: The system's Ethernet communication shall comply with IEEE 802.3 standards.

REQ-3.4.4: The system must accept user commands via HTTP POST requests, with standard 10ms over network latency delays

4. System Features

4.1 Communication Link Establishment

4.1.1 Description and Priority: This feature involves establishing and maintaining a reliable communication link over Ethernet.

4.1.2 Stimulus/Response Sequences:

Step Number	User Action	System Response
1	User connects to webserver	System establishes an ethernet connection with the user
2	User disconnects from webserver	System disconnects ethernet connection with the user

4.2 User Web Interface

4.2.1 Description and Priority: This feature focuses on providing a user web interface, allowing users to initiate telemetry data capture, request specific data, and configure system settings.

4.2.2 Stimulus/Response Sequences:

Step Number	User Action	System Response
1	User opens website	System displays requested site
2	User requests pattern of LEDs	System changes FPGA LEDs to requested pattern
3	User initiates telemetry data capture	System starts capturing telemetry data
4	User requests data at a specific AXI address	System retrieves and displays requested telemetry data at that AXI address
5	User changes system settings	System updates according to new settings

4.3 Telemetry Data Parsing and Display

4.3.1 Description and Priority: This feature involves parsing telemetry data upon request and presenting it in a structured format for clarity.

4.3.2 Stimulus/Response Sequences:

Step Number	User Action	System Response
1	User requests telemetry data	System parses and displays telemetry data in structured format
2	User filters telemetry data	System displays only the filtered data according to user query

3	User selects telemetry data set	System presents detailed view of selected telemetry data set
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5. Other Nonfunctional Requirements

5.1 Performance Requirements

REQ-5.1.1: Conduct functionality verification of the Xilinx MicroBlaze CPU via peripheral testing

REQ-5.1.2: The system shall ensure real-time data processing by FreeRTOS, with latency maximums of 10ms for a task

REQ-5.1.4: The system shall host an interactive web server for equipment monitoring, with non-noticeable delay of real time updates

REQ-5.1.5: The system's web server shall allow for control of test equipment, with 2s maximum latency over network delays for command response times

REQ-5.1.6: The system shall acquire telemetry data from the AXI bus with a maximum allowable delay of 40ns (defined by AXI speed/bitrate)

REQ-5.1.7: The system shall support command transmission to the CPU, with a maximum allowable delay of 5ms to transmission

5.2 Safety Requirements

REQ-5.2.1: The system shall continuously monitor for hardware malfunctions

REQ-5.2.2: The system's malfunction monitoring shall alert the user of identified issues

REQ-5.2.3: The system shall implement self-diagnostic routines for fault detection, specifying the frequency and scope of these diagnostics.

REQ-5.2.4: The system shall export detected abnormalities to the user, based on IEEE 829 error reporting standards

REQ-5.2.5: The system shall monitor for other abnormal behavior, based on IEEE 829 error reporting standards

5.3 Security Requirements

REQ-5.3.1: The system shall incorporate measures for data integrity during telemetry data acquisition, based on IEEE 802.1A (Ethernet Security)

REQ-5.3.2: The system shall maintain data integrity during telemetry transmission, based on IEEE 802.1A

REQ-5.3.3: The system shall implement encrypted storage, based on IEEE 1619 (Cryptographic standards for data)

REQ-5.3.4: The system shall establish redundant backup systems, with backup frequency, storage locations, and restoration procedures based on ISO 22301:2019 (Societal Security Standards)

5.4 Software Quality Attributes

REQ-5.4.1: The system shall achieve a defined MTBF that aligns ISO 9001:2015 (Quality management standards)

REQ-5.4.2: The system shall maintain a low MTTR with effective error logging that aligns with ISO 9001:2015

REQ-5.4.3: The system shall recover gracefully from unexpected failures or errors, detailing recovery processes and maximum allowable downtime based on IEEE 1633 (Software reliability standards)

REQ-5.4.4: The system shall ensure optimal performance for processing telemetry data, based on 50ms response times of processing general data

5.5 Business Rules

REQ-5.5.1: The system and all subsystems shall adhere to industry safety standards, specifying the relevant standards and compliance verification processes.

REQ-5.5.2: The system shall ensure compatibility with existing systems, particularly with TVS, detailing integration and testing processes.

6. Other Requirements

REQ-5.6.1: The system shall adhere to licensing terms allowing modification or distribution, detailing the specific terms.

REQ-5.6.2: The system shall come with comprehensive documentation on intellectual property rights, licensing, and usage permissions.

Appendix A: Glossary

Ingenion Telemetry Web Server	The software component responsible for facilitating communication and interaction between the Digilent Nexys A7 development board, Xilinx Artix 7 FPGA, MicroBlaze soft-core CPU running FreeRTOS, and external client devices via Ethernet. It is a critical part of the Total Verification System (TVS) project
Total Verification System (TVS) Project	A project aimed at enhancing satellite hardware testing by integrating advanced features and improving telemetry data management
Digilent Nexys A7	A development board used in the project for interfacing with satellite hardware components. Xilinx Artix 7 FPGA: A Field-Programmable Gate Array (FPGA) from Xilinx used to host the MicroBlaze soft-core CPU and execute the software
MicroBlaze	A soft-core microprocessor designed by Xilinx for implementation on FPGAs. FreeRTOS: An open-source real-time operating system used for running tasks on the MicroBlaze CPU
Ethernet	A network communication protocol used for connecting the Nexys A7 board to external client devices

TCP/IP	Transmission Control Protocol/Internet Protocol, the suite of communication protocols used for transmitting data over networks, including the internet
User Interface (UI)	The graphical interface that allows end-users to interact with and control the telemetry system. Telemetry Data: Data collected from satellite hardware components, used for monitoring and control
External Computer	A device connected to the telemetry system via Ethernet for data exchange and management. Real-Time Web Server: A web server that provides immediate and interactive access to telemetry data and system controls
Communication Protocols	Standards like Ethernet, TCP/IP, UART, I2C that are used for reliable data exchange within the system
MicroBlaze	The soft-core CPU integrated into the Artix 7 FPGA for processing task
HTTP Protocol	Hypertext Transfer Protocol, used for communication between web browsers and the web server.
Websockets	A communication protocol that enables real-time, bidirectional communication between the web server and connected clients
IEEE 802.3	A standard for Ethernet communication
HTTP POST Requests	A method for sending data from a user to a web server

System Features	Key functionalities or capabilities of the telemetry web server, such as communication link establishment, user web interface, and telemetry data parsing and display
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Appendix B: Analysis Models

Figure 1

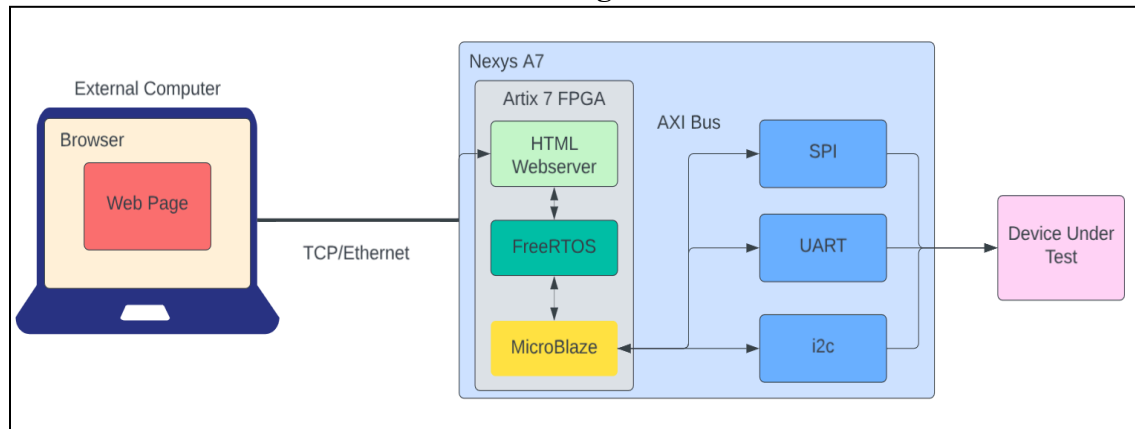


Figure 1 shows a graphical representation of a general component diagram for the system

Appendix C: To Be Determined List