view_frames Result Recorded at time: 110.040 odom nav Broadcaster: /gazebo Broadcaster: /ground_truth_to_tf Average rate: 100.186 Hz Average rate: 100.207 Hz Most recent transform: 110.032 (0.008 sec old) Most recent transform: 110.000 (0.040 sec old) Buffer length: 4.851 sec Buffer length: 4.840 sec base_footprint chassis Broadcaster: /ground_truth_to_tf Average rate: 100.207 Hz Most recent transform: 110.000 (0.040 sec old) Buffer length: 4.840 sec base_stabilized Broadcaster: /ground_truth_to_tf Average rate: 100.207 Hz Most recent transform: 110.000 (0.040 sec old) Buffer length: 4.840 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (110.040 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec dummy_link front_link sonar_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (110.040 sec old) Most recent transform: 0.000 (110.040 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec

ardrone_base_frontcam

bottom_link

ardrone_base_bottomcam